

Nuclear-norm Regularized Model Let $D \in \mathbb{R}^{n \times t}$ be the reshaped video with n pixels and t frames. Assume that $\Phi_s \in \mathbb{R}^{n \times n}$ and $\Phi_t \in \mathbb{R}^{t \times t}$ are graph Laplacians in the spatial and temporal domains, respectively. Now we consider a foreground-background separation model of the form

$$\min_{L, S \in \mathbb{R}^{n \times t}} \frac{1}{2} \|D - L - S\|_F^2 + \lambda_1 \|L\|_* + \lambda_2 \|S\|_1 + \frac{\gamma_1}{2} \text{tr}(L^T \Phi_s L) + \frac{\gamma_2}{2} \text{tr}(L \Phi_t L^T).$$

By introducing an auxiliary variable U , we rewrite the above problem

$$\min_{L, S, U} \frac{1}{2} \|D - L - S\|_F^2 + \lambda_1 \|U\|_* + \lambda_2 \|S\|_1 + \frac{\gamma_1}{2} \text{tr}(L^T \Phi_s L) + \frac{\gamma_2}{2} \text{tr}(L \Phi_t L^T), \quad \text{s.t.} \quad U = L.$$

Define the augmented Lagrangian

$$\mathcal{L}(L, S, U) = \frac{1}{2} \|D - L - S\|_F^2 + \lambda_1 \|U\|_* + \lambda_2 \|S\|_1 + \frac{\gamma_1}{2} \text{tr}(L^T \Phi_s L) + \frac{\gamma_2}{2} \text{tr}(L \Phi_t L^T) + \frac{\rho}{2} \|U - L + \tilde{L}\|_F^2.$$

Based on the alternating direction method of multipliers (ADMM), we derive the algorithm

$$\begin{cases} L \leftarrow \underset{L}{\text{argmin}} \frac{1}{2} \|D - L - S\|_F^2 + \frac{\gamma_1}{2} \text{tr}(L^T \Phi_s L) + \frac{\gamma_2}{2} \text{tr}(L \Phi_t L^T) + \frac{\rho}{2} \|U - L + \tilde{L}\|_F^2 \\ S \leftarrow \underset{S}{\text{argmin}} \lambda_2 \|S\|_1 + \frac{1}{2} \|D - L - S\|_F^2 \\ U \leftarrow \underset{U}{\text{argmin}} \lambda_1 \|U\|_* + \frac{\rho}{2} \|U - L + \tilde{L}\|_F^2 = \underset{U}{\text{argmin}} \frac{\lambda_1}{\rho} \|U\|_* + \frac{1}{2} \|U - L + \tilde{L}\|_F^2 \\ \tilde{L} \leftarrow \tilde{L} + (U - L) \end{cases}$$

The first L -subproblem is a least-square problem with the normal equation

$$L + S - D + \gamma_1 \Phi_s L + \gamma_2 L \Phi_t + \rho(L - U - \tilde{L}) = 0$$

Note that $\frac{d}{dX} \text{tr}(X^T A X) = (A + A^T)X$, $\frac{d}{dX} \text{tr}(X A X^T) = X(A + A^T)$ and both Φ_t and Φ_s are symmetric. The above equation can be rewritten in the Sylvester equation form

$$(I + \gamma_1 \Phi_s + \gamma_2 I + \rho I)L + L(\gamma_2 \Phi_t) = D - S + \rho(U + \tilde{L}).$$

This can give us a unique solution under certain condition via `scipy.linalg.solve_sylvester(A, B, Q)` for solving the standard Sylvester equation of the form $AX + XB = Q$

$$L = \text{sylvester_solver}(A, B, Q),$$

where $A = (1 + \gamma_2 + \rho)I + \gamma_1 \Phi_s$, $B = \gamma_2 \Phi_t$, and $Q = D - S + \rho(U + \tilde{L})$. The S -subproblem has the closed-form solution

$$S \leftarrow \text{shrink}(D - L, \lambda_2).$$

Here the shrinkage operator is defined as $(\text{shrink}(A, \mu))_{ij} = \text{sign}(a_{ij}) \cdot \max\{|a_{ij}| - \mu, 0\}$ where a_{ij} is the (i, j) -th entry of A . The U -subproblem has the closed-form solution via the singular value thresholding operator (SVT)

$$U \leftarrow A \tilde{D} B, \quad \tilde{D} = \text{shrink}(D, \lambda_1 / \rho)$$

where ADB is the SVD of the matrix $(L - \tilde{L})$.