

LANG CHENG

Manchester, UK

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PROFILE

MSc Robotics student at the University of Manchester with a BEng in Computer Science and internship experience building Python data workflows to support product iteration. Strong in structuring messy data (logs + text), running reproducible experiments (config-driven runs, Git), and translating requirements into implementable processing steps with clear documentation.

EDUCATION

University of Manchester MSc Robotics Focus: robotics software development, perception/ML foundations, reproducible experimentation	Sep 2025 – Present
Beijing Institute of Technology, Zhuhai BEng Computer Science and Technology Focus: programming fundamentals, data processing, applied ML concepts	Sep 2021 – Jun 2025

TECHNICAL SKILLS

Programming	Python; C++ (basic); MATLAB
Data & Pipelines	Data cleaning/processing (pandas, NumPy); parsing and normalizing logs/text; data-quality checks; traceable workflows (inputs → transforms → outputs)
Engineering Practices	Git; config-driven runs (YAML/JSON); structured READMEs and runbooks for reproducibility; metric tracking and comparison
ML / CV (supporting)	PyTorch (training/evaluation loops); object detection (YOLOv8); failure-case analysis (occlusion/lighting/viewpoint)

WORK EXPERIENCE

Zhuhai Hengqin Boyi Data Technology Co., Ltd <i>AI Product Intern</i>	Mar 2025 – Jul 2025 <i>Zhuhai, China</i>
· Built Python (pandas/NumPy) data preparation workflows for structured data and text/usage logs; standardized schemas and formats to make analysis and iteration repeatable. · Worked with stakeholders on requirement analysis and feature definition; translated business needs into concrete data collection, processing, and evaluation steps. · Supported prompt iteration with lightweight evaluation and change tracking; documented updates and outcomes to enable consistent team decision-making. · Synthesized user feedback and basic usage metrics into actionable notes that informed prioritization and product improvements.	

PROJECTS & RESEARCH

Robot Vision Study: ResNet-18 vs. SIFT–BoW–SVM on iCubWorld <i>Computer Vision / Engineering Evaluation</i>	Oct 2025 – Dec 2025 <i>University of Manchester</i>
· Built two end-to-end recognition pipelines (classical features + ML vs. transfer learning) and ran controlled training/evaluation under viewpoint and illumination variation. · Designed reproducible experimentation: validation-based model selection, structured hyperparameter sweeps (e.g., BoW vocab size; SVM C; KNN k; CNN lr/weight decay/batch size), and consistent metric tracking. · ResNet-18 achieved ~98–99% test accuracy; best SIFT–BoW–SVM achieved ~56%. Produced confusion-matrix analysis and documented failure modes/trade-offs for engineering decisions.	

Autonomous Object Retrieval Robot (YOLOv8 + Color Sorting)*Software Development / Robotics*

Course Project

University of Manchester

- Delivered a perception-to-action system enabling a mobile robot to detect colored objects, navigate for pickup, and sort into matching bins.
- Integrated real-time YOLOv8 detection with task logic; added practical robustness checks for missed detections, occlusions, and lighting changes.
- Improved system reliability through iterative testing, parameter tuning, and structured run notes to accelerate debugging and team collaboration.

Topic Modelling + Social Network Analysis on Reddit Corpora*A research led by Dr. Han C.W. HSIAO*

Final Year

Undergraduate Thesis

- Developed an end-to-end Python pipeline for large text corpora: preprocessing, LSA topic modelling, topic interpretation, and reporting-ready outputs.
- Performed social network analysis (centrality measures) and created visualizations with concise written summaries for non-technical communication.
- Organized experiments and outputs with a reproducible folder structure and clear documentation for re-runs and review.

Python Data Processing for Product Usage Logs*Data Engineering (Foundations)*

Internship Project

- Implemented scripts to parse, clean, and normalize usage logs and text data for analysis and reporting.
- Added practical data-quality checks and traceability (inputs → transformations → outputs) to support reliable iteration.