

A large-scale comparison of cross-situational word learning models

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Abstract

One problem faced by language learners is how to extract word meanings from situations that often present many possible referents. While a word's meaning may be ambiguous given any one scene, a large body of empirical work has found that people are able to learn cross-situationally across multiple occurrences of a given word. There has been correspondingly much interest in modeling such learning, and yet there is little consensus on the main mechanisms underpinning cross-situational word learning. The lack of consensus is in part due to the large number of disparate studies and models, and lack of systematic model comparisons across a wide range of studies. This study seeks to remedy this, comparing the performance of several extant cross-situational word learning models on a dataset consisting of 1,696 participants spread across 44 experimental conditions. Using cross-validated parameters, we fit multiple models representing theories of both associative learning and hypothesis-testing theories of word learning, find two best-fitting models, and discuss issues of model and mechanism identifiability. Finally, we test the models' best-fitting parameters ability to generalize to a set of additional experiments, including developmental data.

Keywords: cross-situational word learning; model comparison; language learning

Introduction

Learning word meanings is a crucial aspect of the process of language acquisition. If a learner's task is to connect the words they hear to the potential referents and eventually to generalizable meanings, the challenge appears formidable (Quine, 1960): words are heard in rich and cluttered contexts. Yet children learn words very quickly. How do they do this?

An array of social (Yurovsky & Frank, 2017), pragmatic (Clark, 1987; Markman, 1992), and linguistic (Gleitman, 1990) cues are often available to reduce a learner's uncertainty. Yet at its heart, these information sources can be seen as reducing the uncertainty inherent in the task of *cross-situational mapping* (Frank, Goodman, & Tenenbaum, 2009): that is, cross-referencing which referents a word has consistently appeared with across multiple uses (Carey & Bartlett, 1978; Gleitman, 1990). If learners can learn cross-situationally, they might be able to pool information about reference (and hence word meaning) over time and learn even absent perfectly disambiguated input in any particular situation. Can children (or even adults) learn in this way?

The general idea of cross-situational word learning has been adopted into a variety of experimental paradigms for testing the word learning ability of infants (e.g., Smith &

Yu, 2008; Vlach & Johnson, 2013), children (e.g., Akhtar & Montague, 1999; Suanda, Mugwanya, & Namy, 2014; Vlach & Sandhofer, 2012), and adults (e.g., Yu & Smith, 2007; Smith, Smith, & Blythe, 2011). In such experiments, participants are typically presented with a series of training trials comprised of multiple possible referents (e.g., an array of 2–4 novel objects) and one or more spoken nonce words, and (when possible) instructed to learn the meaning(s) of the presented words. These training trials typically present 10–20 distinct word-referent pairs to be learned across 10–50 trials, presenting each word/referent 3–10 times across a total span of < 10 minutes. Learning is then typically assessed by presenting each word and asking learners to make a forced choice of the best referent, either from the entire set or from a small subset of referents.

People of all ages are able to learn word-object mappings in such paradigms at a level significantly above chance, but their performance is typically far from perfect in all but the most trivial versions of the task (Yurovsky & Frank, 2017). Numerous training manipulations have been found to influence performance. How often mappings are presented (Kachergis, Yu, & Shiffrin, 2016; Suanda & Namy, 2012), the interval between appearances of a mapping (Vlach & Johnson, 2013; Vlach & Sandhofer, 2012), and the number of mappings presented per trial (Yu, 2008) all have been shown to affect learning performance. In sum, the evidence is strong that people can learn word cross-situationally: we are somehow able to integrate evidence (co-occurrence of words and objects) across trials and use that evidence to learn and remember new word meanings in cross-situational learning experiments. But what are the psychological mechanisms supporting this process? And critically, do these mechanisms support naturalistic word learning?

Computational models provide one strategy for instantiating proposals about mechanism. Such models can then be applied to naturalistic data to make a first assessment of whether cross-situational learning could be a viable strategy for word learning “in the wild”. Accordingly, there has been great interest in creating and testing computational models of this task. These models often represent distinct intuitions of how learning operates, variously representing the problem as logical inferencing (e.g., Siskind, 1996), proposing and testing hypotheses (e.g., Trueswell, Medina, Hafri, & Gleitman, 2013), or accumulating graded associations (e.g., Fazly, Al-

ishahi, & Stevenson, 2010; Kachergis, Yu, & Shiffrin, 2012; Tilles & Fontanari, 2012).

It is unknown which of these models – or even which broad class of models – best fits the breadth of experimental data. While most models of cross-situational learning have typically been tested against at least a few datasets, to our knowledge there has been no systematic comparison of models across a wide variety of experimental conditions. Identifying the model(s) that best predict human performance is thus an important goal for consolidating this broad literature. More broadly, identifying such models could be an important step in assessing the contribution of cross-situational learning to word learning more generally.

Thus, the goal of our current study is to test the ability of a range of cross-situational word learning models in accounting for a wide range of experimental data. Our goal is to scale up both the number of models evaluated and the number of experiment designs (and participants) being used for evaluation. Different models often contain a range of parameters that must be fit to data, an issue that has hindered previous comparison work, either because the parameters have been allowed to vary freely across multiple conditions, or because models’ performance is compared on different datasets. Thus, we focus on out-of-sample prediction of human data using cross-validated parameter fits. We end by examining results from generalization of models to other experiments not included in the initial evaluation and parameter fitting.

Method

Procedure

Our goal is to fit a set of models to a set of datasets; members of each of these sets are listed below. Each model typically is defined as a function that takes input data and a group of parameter values (often between 2–4) and then can be evaluated on test trials (typically multi-alternative forced choice test). Each model then returns predictions on each test trial, which can be scored against the “correct” (intended by the design) answer and averaged to produce an analogue to human performance. Our primary outcome measure is the correlation between each model’s performance for each item in a specific experimental condition and item-level human performance on that same experimental condition.

Although input data and test trials are features of specific experimental tests, each model has parameters that must be specified. Typically the settings of these parameters are critical to the predictive performance of the model. Hence, to ensure a fair comparison between models, these parameters must be fit to data. In all cases, we optimize parameter values to minimize the sum of squared error (SSE) between model and human performance, weighting the contribution of each condition’s SSE by the number of participants in that condition. We optimize parameters using differential evolution via the DEoptim R package (Mullen, Ardia, Gil, Windover, & Cline, 2011). For the stochastic models, each parameter setting was evaluated using a simulated sample of 200 learners.

We conducted two evaluations of models. First, we opti-

mize each model’s parameters on 80% of data and evaluate on the remaining 20% (5-fold cross-validation). Second, in the *group fit* regime we fit each model to all conditions and datasets and evaluate across all data. Though slightly overfit, this evaluation allows us to make the best test of generalization to other experiments from the literature.

Models

We fit a baseline co-occurrence model along with six associative models, two hypothesis-testing models, and two hybrid models that store multiple, graded hypotheses—but only a subset of all possible associations. These models and their free parameters are briefly described below.

Baseline Co-occurrence Model The baseline model simply tallies the co-occurrences of any words and objects appearing together on each trial, accumulating the counts in a word \times object matrix M . At test, for word w_1 this model selects the correct referent o_1 according to Luce choice from the co-occurrences of w_1 with all referents: $P(o_1|w_1) = M_{w_1,o_1} / \sum M_{w_1,\cdot}$. The model’s probability of correctly choosing each word per condition is what is scored against people’s average probability of choosing the correct item.

Probabilistic Associative Model (PA) The probabilistic associative model (Fazly et al., 2010) represents the meaning of each word w as a probability distribution $p(\cdot|w)$ over the objects appearing across the trials, and incrementally learns these distributions trial-by-trial. The association between a given w and o grows more quickly if $p(w|o)$ is already high (a familiarity bias), unless some other word has a strong association with o ; thus, associations are competitive. A parameter λ is a small smoothing constant added to both the numerator and denominator of each $p(w|o)$, further adjusted in the denominator by a β parameter representing the upper bound on the number of symbol types. At test, the correct referent for each word w is chosen according to Luce choice from the probability distribution over the objects that appeared with that word $p(\cdot|w)$.¹

Familiarity- and Uncertainty-biased Model (FU) The familiarity- and uncertainty-biased associative model (Kachergis et al., 2012) assumes that learners associate all presented words with all visible objects to some extent, but that they selectively attend more to some of the presented word-object pairings. Specifically, greater attention is directed to pairings that have previously co-occurred (a familiarity bias), but is also directed to stimuli that have no strong associates, tracked via the entropy (H) of their association strengths (e.g., novel stimuli, or stimuli that have diffuse associations with several stimuli). Thus, the model grows its association matrix as it experiences each trial, dynamically apportioning a fixed amount of associative weight (learning rate χ) among the possible word-object associations, with the relative weight of the familiarity

¹The original model implemented a θ -thresholded lexicon that discretized the probability matrix, but we found that including this mechanism resulted in a worse fit to the data.

bias and the uncertainty bias determined by parameter λ . Association strengths decay at a rate controlled by parameter α . The update rule for adjusting the association $M_{w,o}$ between a given word w and object o on a given trial is:

$$M_{w,o} = \alpha M_{w,o} + \frac{\chi \cdot e^{\lambda \cdot (H(w) + H(o))} \cdot M_{w,o}}{\sum_{w \in W} \sum_{o \in O} e^{\lambda \cdot (H(w) + H(o))} \cdot M_{w,o}} \quad (1)$$

At test, given word w learners use Luce choice, choosing referent o from the m given alternatives in proportion to associative strength $M_{w,o}$.

We also fit a *stochastic sampling* (FUs) version of this model (see Kachergis & Yu, 2017), which uses the same update equation, but samples only a single presented object for each word on a trial instead of updating all possible associations. This FU sampling model can still build multiple graded associations for each word (or object), but on any given run will accumulate only a sparse, randomized version of what the full associative model would build.

Strength-, Uncertainty-, & Novelty-biased (S,U,N) Models

We also test three variations on the Kachergis et al. model that use only a subset of the mechanisms of the full model in order to understand the contributions of each mechanism. The *strength model* lacks the uncertainty bias term, and thus only implements a bias for familiar (i.e., already-strong) associations, with learning rate (χ) and decay α parameters.

The *uncertainty model* lacks the strength bias term, and thus only implements a bias for stimuli with uncertain (high-entropy) associations. The *novelty model* lacks the strength bias term, and substitutes novelty for the entropy terms (e.g., $1/(\text{frequency}(w)+1)$ instead of $H(w)$). These models still have all three parameters of the original FU model, and at test operate in the same way as the original model.

Bayesian Decay Model (BD) This previously-unpublished model updates the $p(w|o)$ and the joint probability $p(w,o)$ from trial to trial according to a likelihood function that reinforces the association between w and o when they co-occur (scaled by parameter δ), and penalizes all associations that are not occurring on the trial (scaled by parameter α). Thus, in contrast to other incremental associative learning models considered here (e.g., Fazly and the Kachergis class of models), this model globally updates the entire association matrix on each trial – both co-occurring pairs and non-co-occurring pairs, and re-normalizes the tracked probabilities at each time step. At test, this model uses a softmax choice rule with parameter τ to select the best referent for each word from the presented alternatives.

Rescorla-Wagner Model (RW) This associative model is inspired by the prediction-error-based learning model of Rescorla & Wagner (1972). Objects on each trial serve as cues to predict which words will be heard. When a given word is heard, the associations between that word and each object on the trial are scaled at a learning rate β in proportion to the magnitude of the difference between the prediction and the maximum association value (λ). Each trial, the association matrix is subject to decay (parameter α). At test, this

model uses Luce choice to select the best referent for each word from the presented alternatives.

Propose-but-Verify Model (PV) In the propose-but-verify hypothesis testing model (Trueswell et al., 2013), a presented referent is selected at random for any presented word that has no remembered referent. The next time that word occurs, the previously-proposed referent is remembered with probability α , a free parameter. If the remembered referent is verified to be present, the future probability of recalling the word is increased by ε (another free parameter). If the remembered referent is not present, the old hypothesis is assumed to be forgotten and a new proposal is selected from the available referents. This model implements trial-level mutual exclusivity by selecting new proposals only from among the referents that are not yet part of a hypothesis.

Guess-and-Test Model (GT) The guess-and-test hypothesis testing model is based on the description given by Medina, Snedeker, Trueswell, & Gleitman (2011) of a one-shot (i.e. “fast mapping”) learning, which posits that “i) learners hypothesize a single meaning based on their first encounter with a word, ii) learners neither weight nor even store back-up alternative meanings, and iii) on later encounters, learners attempt to retrieve this hypothesis from memory and test it against a new context, updating it only if it is disconfirmed.” We give this model two free parameters: a probability of successful encoding (s , hypothesis formation), and a probability f of forgetting a hypothesis at retrieval. At test, for each word the model chooses the currently hypothesized referent.

Pursuit Model (P) The pursuit model (Stevens, Gleitman, Trueswell, & Yang, 2017) is a hybrid model, potentially storing graded associations involving a given word and multiple referents (or vice-versa), while on any given trial greedily pursuing the strongest association for each presented word. If the strongest associated referent for a given word w is present on the trial, the association is strengthened at a rate determined by γ . If the strongest referent for w is not present, the association is weakened (scaled down by $(1 - \gamma)$) and the association with a random other available referent is strengthened. Novel words are given an initial association of strength γ with the available referent whose strongest association is the smallest, implementing an uncertainty bias in forming associations for novel words. A given word-object association only enters the lexicon if $p(o|w) > \theta$, a threshold parameter. At test, this model chooses the best referent for each word by Luce choice from the lexicon, which is not necessarily 1-to-1.

Data

The modeled data are average accuracies from 726 word-object pairs in 44 experimental conditions, in which a total of 1696 subjects participated. A table containing details of each condition is available on OSF². The number of trials per condition ranged from 18 to 108, with 1-4 words and objects presented per trial, and a total of 12-24 pairs to be learned per condition. The bulk of these data have been previously

²Information about the dataset: <https://osf.io/s2aty/>

published: data from 13 of the conditions were reported in Kachergis & Yu (2013), data from 12 conditions are from Kachergis et al. (2012), and data from another nine conditions are from Kachergis et al. (2016). However, data from several conditions are contributed by Chen Yu’s lab at Indiana University, and have never before been published. Each condition consists of an ordered list of training trials consisting of 1-4 words and 2-4 objects per trial. At test, participants heard each word and were asked to select the best referent from either all m presented objects (m -alternative forced choice; AFC), or from a subset (e.g., 4AFC).

Results

Table 1 shows the sum of squared error (SSE) and correlation (r) for each model’s best-fitting parameters vs. average human performance on the 726 items, both for the CV fits and for the all-condition fits, along with the number of fitted parameters in each model (P). The results of the two fitting procedures yielded fairly similar SSEs and correlations, and a consistent rank-ordering of the models, with the Kachergis sampling model performing best, followed closely by the Fazly et al. model and then the associative Kachergis et al. model. The hypothesis testing models (Propose-but-Verify and Guess-and-Test) and the Pursuit model fit less well than the 0-parameter baseline co-occurrence counting model (not in the table), which had $SSE = 32.0$ and $r = 0.53$. Correlations between data and models are presented in Figure 1.

Model	CV SSE	r	All SSE	r	P
FUs	17.74	0.74	17.76	0.74	3
PA	18.72	0.73	18.77	0.73	2
FU	18.92	0.72	19.07	0.72	3
Nov	22.02	0.67	22.01	0.67	2
Unc	23.06	0.69	23.02	0.69	3
BD	23.95	0.62	23.71	0.63	3
GnT	31.49	0.50	31.57	0.50	2
R-W	31.80	0.62	31.79	0.62	3
Str	39.05	0.46	39.07	0.46	2
Pur	41.68	0.57	40.50	0.59	3
PbV	42.92	0.35	30.82	0.51	2

Table 1: Cross-validated and group model fits.

Table 2 shows the correlations between model predictions made using the group-optimized parameters, with the strongest correlation per row in bold.

Generalization Experiment Results

Using the optimal parameters found for each model in the group fit, we simulate model performance for four other published (two adult, two developmental) for which we only have participants’ average performance. Koehne, Trueswell, & Gleitman (2013) manipulated the temporal order with which words were assigned two meanings of different strengths across four conditions given to adults. Medina et al. (2011) manipulated the informativeness (number of referents per

Table 2: Correlations of models’ predictions.

	FUs	PA	FU	N	U	BD	PV	GT	RW	S	P
FUs	-	.87	.92	.87	.82	.75	.51	.68	.83	.60	.74
PA	.87	-	.84	.79	.81	.79	.58	.70	.84	.59	.68
FU	.92	.84	-	.87	.83	.79	.50	.63	.78	.60	.67
N	.87	.79	.87	-	.74	.82	.50	.67	.79	.74	.70
U	.82	.81	.83	.74	-	.64	.47	.66	.80	.53	.66
BD	.75	.79	.79	.82	.64	-	.56	.60	.70	.67	.53
PV	.51	.58	.50	.50	.47	.56	-	.65	.67	.53	.41
GT	.68	.70	.63	.67	.66	.60	.65	-	.87	.62	.54
RW	.83	.84	.78	.79	.80	.70	.67	.87	-	.65	.68
S	.60	.59	.60	.74	.53	.67	.53	.62	.65	-	.28
P	.74	.68	.67	.70	.66	.53	.41	.54	.68	.28	-

Table 3: Generalization experiment results.

Model	Koehne et al.	Medina et al.	Suanda et al.	Smith & Yu	Total RMSE
R-W	0.09	0.11	0.11	0.17	0.48
PA	0.11	0.15	0.13	0.24	0.63
Unc	0.1	0.19	0.2	0.22	0.71
Nov	0.06	0.17	0.2	0.29	0.72
Str	0.07	0.17	0.18	0.29	0.72
FUs	0.07	0.16	0.25	0.27	0.76
FU	0.09	0.19	0.26	0.29	0.82
PbV	0.24	0.16	0.21	0.27	0.89
GnT	0.25	0.17	0.23	0.28	0.93
Pur	0.15	0.25	0.3	0.24	0.94
BD	0.15	0.45	0.05	0.32	0.96

trial) and order of trials across four conditions, again with adults. Smith & Yu (2008) and Yu & Smith (2011) trained 12- and 14-month-old infants on 6 words repeated across 30 trials, and found that infants learned 4 of the 6 words on average. Suanda et al. (2014) tested 6-year-old children in three conditions with varying contextual diversity. Table 3 shows the root-mean-square error (RMSE) of each model vs. average human performance, as well as the total RMSE across the four experiments. The Rescorla-Wagner model fared the best overall, predicting both the Medina et al. and Smith & Yu data better than other models. The novelty-biased model best predicted the Koehne et al. data, and the Suanda et al. data was best fit by the Bayesian Decay model. All models generally outperformed children in the developmental experiments: it is likely that allowing parameters to vary would allow them to better account for developmental data.

Discussion

We set out to conduct a systematic comparison of several models of cross-situational word learning models across a wide variety of experimental conditions. Using a database of 1696 participants in 44 conditions, we found best-fitting parameters for 11 different models under two different regimes: 1) simultaneously fitting all of the data, and 2) 5-fold cross-validation, testing generalization to the final 20% of conditions after training on 80% of them. The results of both fitting regimes were consistent and clear: shown in Table 1, the associative models generally achieved better fits (lower SSE and higher correlations) than the hypothesis-testing mod-

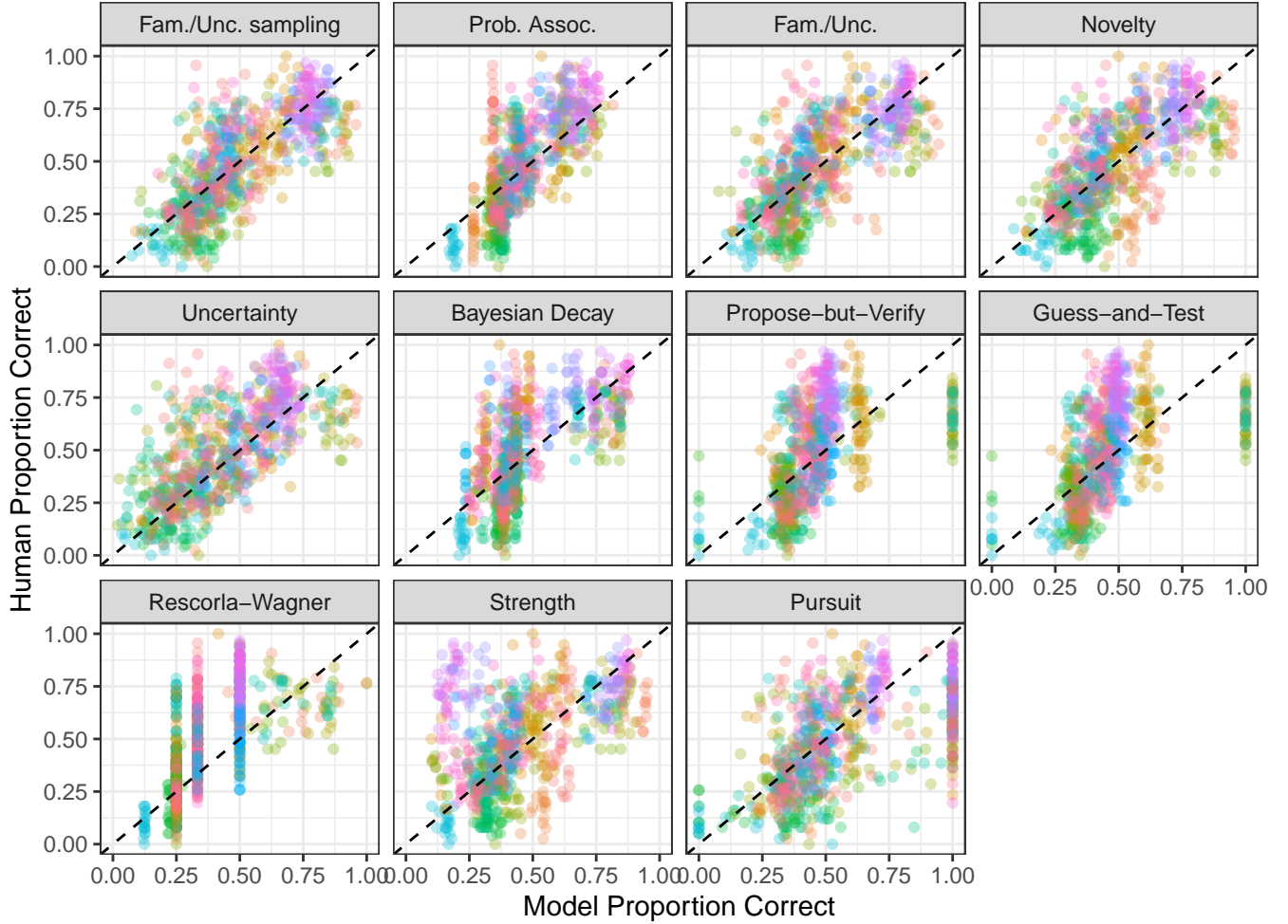


Figure 1: Human vs. model item-level accuracy using best-fitting parameters per model for all conditions (colored by condition). Note that on some items, PbV, GnT, and Pursuit all show more extreme responding (1 or 0) than people ever do.

els (Guess-and-Test; Medina et al. (2011) and Propose-but-Verify; Trueswell et al. (2013)), which made strongly-correlated predictions (see Table 2: .91). The Rescorla-Wagner model, a prediction-error based associative model, performed similarly to these models, and made surprisingly correlated predictions (GnT: .89, PbV: .87). The hybrid Pursuit model (Stevens et al., 2017) fared even more poorly, in part because it often outperformed humans ($M_{mod} = 0.56$, $M_{hum} = 0.48$).

Among the associative models, the PA model (Fazly et al., 2010) and the FU model (Kachergis et al., 2012) both fare quite well, and the sampling version of the FU model (FUs) performs slightly better, albeit with 3 free parameters compared to 2 in the PA model. The predictions of the top three models are more correlated with each other than with the human data (see Table 1): PA vs. FUs: .87, PA vs. FU: .84, FU vs. FUs: .92. But the PA model also showed a .84 correlation with the Rescorla-Wagner model, and both FU and FUs show a .87 correlation with the simpler novelty-biased associative model (N)—stronger than for the uncertainty-bias mechanism

used by the FU models. Future work should aim to further explore when these models make overlapping predictions, but another approach is to find conditions where models make very predictions.

The FUs and PA models make maximally divergent predictions in the conditions with fewer words than objects per trial (esp. 1x3, 1x3 6/18 4AFC, and 1x4), which hints at a difference in mechanism for these models and may guide the design of a new experiment to diagnose which is better able to account for human behavior.

The generalization experiments did not see the continued success of the PA and FUs models: instead, the RW model came out ahead. However, most models far outperformed children in the two developmental experiments, and thus we hesitate to conclude much from the results of these experiments: future work should allow parameters to vary across development (with cross-validation).

Although we have aimed for broad coverage of models and experimental conditions, this study is far from complete in both respects. First, there are many other models that we have

not yet implemented (e.g., Tilles & Fontanari, 2012; McMurray, Horst, & Samuelson, 2012), or that we have not finished fitting to the data (e.g., Yurovsky & Frank, 2015). Moreover, this dataset represents performance from a fairly homogeneous sample: English-speaking US college students, mostly from a single midwestern university. Future work should aim to include not only more models, but a more broadly diverse sample, both in terms of language background and age. We invite other researchers to contribute datasets and model implementations for future, larger-scale comparisons.

In summary, we have shown not only how a large model comparison can help rank models from most to least able to account for human data, but also how such comparisons can identify models that mimic each other, as well as identifying experimental designs that might aid in distinguishing models. Future work should extend this comparison to cross-situational word learning models and extant datasets beyond those tested here, and design novel experiments designed to distinguish these models. Finally, assuming that cross-situational learning is an important tool in the language learner's toolbox, it is important to consider how these models can be extended to incorporate other information sources at the learner's disposal, such as social cues, pragmatics, and syntactic constraints on meaning (Hirsh-Pasek, Golinkoff, & Hollich, 2000; Markman, 1990; Yurovsky & Frank, 2017). While many of these models have mechanisms for preferentially selecting and storing particular associations, most have yet to formally incorporate relevant cues from social partners—linguistic and nonlinguistic (though see Yurovsky & Frank, 2017).

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