# hw2

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# 1 HW2

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## 1.1 1

1. **DFT**:

2. **DCT**:

3. Hadamard:

4. Haar (归一化):

```
[14]: import numpy as np
     from scipy.fftpack import dct, idct
     from scipy.linalg import hadamard
     #输入矩阵
     matrix = np.array([
         [0, 1, 1, 0],
         [0, 1, 1, 0],
         [0, 1, 1, 0],
         [0, 1, 1, 0]
     ])
     # DFT
     def compute_dft(image):
         M, N = image.shape
         # 构建行频率矩阵和列频率矩阵
         u = np.arange(M) # 生成一个等差数列, 0 到 M-1
         v = np.arange(N)
         x = np.arange(M)
         y = np.arange(N)
         # 行变换矩阵
         W_x = np.exp(-2j * np.pi * u[:, None] * x / M)
         # 列变换矩阵
         W_y = np.exp(-2j * np.pi * v[:, None] * y / N)
         # 对图像进行离散傅里叶变换
         dft_result = W_x @ image @ W_y.T
         return dft_result
     # DCT
     def compute_dct(matrix):
         return dct(dct(matrix.T, norm='ortho').T, norm='ortho')
```

```
def compute_dct_mine(image):
   M, N = image.shape
   #构建 DCT 变换矩阵
   u = np.arange(M)
   v = np.arange(N)
   x = np.arange(M)
   y = np.arange(N)
   # 计算 DCT 基函数
   W_x = np.sqrt(2/M)*np.cos(np.pi * (2 * x + 1) * u[:,None] / (2 * M))
   W_y = np.sqrt(2/N)*np.cos(np.pi * (2 * y + 1) * v[:, None] / (2 * N))
   #修正第一个系数的归一化因子
   W_x[0, :] /= np.sqrt(2)
   W_y[0, :] /= np.sqrt(2)
   # 对图像进行离散余弦变换
   dct_result = W_x @ image @ W_y.T
   return dct_result
# Hadamard Transform
def compute_hadamard(matrix):
   # Ensure matrix is of size 2 n x 2 n
   H = hadamard(4)
   print(H)
   print(H@H.T) # H*H^T=nI, n is the size of the matrix
   # H2=hadamard(2)
   # print(np.kron(np.kron(H2,H2),H2))
   # return np.dot(np.dot(H, matrix), H)
   return H @ matrix @ H.T
# Haar Transform
# def compute_haar(matrix):
    def haar_step(v):
```

```
result = np.zeros_like(v)
#
          half = v.shape[0] // 2
          for i in range(half):
              result[i] = (v[2 * i] + v[2 * i + 1]) / np.sqrt(2)
#
              result[half + i] = (v[2 * i] - v[2 * i + 1]) / np.sqrt(2)
          return result
      def haar_2d(mat):
#
#
          rows_transformed = np.apply_along_axis(haar_step, 1, mat)
          return np.apply_along_axis(haar_step, 0, rows_transformed)
      return haar_2d(matrix)
#compute Haar matrix
def haarMatrix(n, normalized=False):
    # Allow only size n of power 2
    n = 2**np.ceil(np.log2(n))
    if n > 2:
        h = haarMatrix(n / 2)
    else:
        return np.array([[1, 1], [1, -1]])
    # calculate upper haar part
    h_n = np.kron(h, [1, 1])
    # calculate lower haar part
    if normalized:
        h_i = np.sqrt(n/2)*np.kron(np.eye(len(h)), [1, -1])
        # combine parts
        h = 1/np.sqrt(n)*np.vstack((h_n, h_i))
    else:
        h_i = np.kron(np.eye(len(h)), [1, -1])
        # combine parts
        h = np.vstack((h_n, h_i))
```

```
return h
def compute_haar(matrix):
    d1=matrix.shape[0]
    d2=matrix.shape[1]
    Hn=haarMatrix(d1,normalized=True)
    return Hn@matrix@Hn.T
# 计算变换
dft_result = compute_dft(matrix)
dct_result = compute_dct(matrix)
hadamard_result = compute_hadamard(matrix)
haar_result = compute_haar(matrix)
# 输出结果
print("DFT Result:\n", np.round(dft_result,4))
print("\nDCT Result:\n", dct_result)
print("\nmy DCT Result:\n", compute_dct_mine(matrix))
print("\nHadamard Result:\n", hadamard_result)
print("\nHaar Result:\n", haar_result)
[[1 \ 1 \ 1 \ 1]]
[ 1 -1 1 -1]
 [ 1 1 -1 -1]
 [ 1 -1 -1 1]]
[[4 0 0 0]
 [0 4 0 0]
 [0 0 4 0]
 [0 0 0 4]]
DFT Result:
 [[8.+0.j-4.-4.j-0.+0.j-4.+4.j]
 [-0.-0.j -0.+0.j 0.-0.j 0.+0.j]
 [ 0.-0.j -0.+0.j 0.+0.j 0.+0.j]
 [ 0.-0.j -0.+0.j 0.+0.j 0.+0.j]]
DCT Result:
```

[[ 2. 0. -2. 0.]

[ 0. 0. 0. 0.]

[ 0. 0. 0. 0.]

[ 0. 0. 0. 0.]]

#### my DCT Result:

[[ 2.00000000e+00 1.11022302e-16 -2.00000000e+00 -4.44089210e-16]

[ 0.00000000e+00 0.00000000e+00 0.00000000e+00 0.00000000e+00]

[-1.11022302e-16 -6.16297582e-33 1.11022302e-16 2.46519033e-32]

[-2.77555756e-16 -2.15704154e-32 2.77555756e-16 5.54667824e-32]]

#### Hadamard Result:

[[8 0 0 -8]]

[0 0 0 0]

[0 0 0 0]

[0 0 0 0]]

#### Haar Result:

[[ 2.	0.	-1.41421	356 1.414	21356]
[ 0.	0.	0.	0.	]
[ 0.	0.	0.	0.	]
[ 0.	0.	0.	0.	]]

#### 1.2 2

均方误差为:

$$MSE = \sum_{i=33}^{64} 1 = 32$$

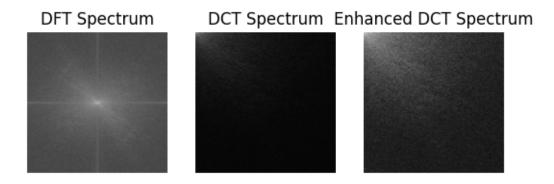
所以,原始图像和重建图像之间的均方误差是32。

## 1.3 3

分别适用库函数和手动实现,其中库函数实现中使用了对数变换增强视觉对比度。1. 使用库函数实现

```
[6]: import cv2
    import numpy as np
    import matplotlib.pyplot as plt
    # 读取灰度图像
    image = cv2.imread('lena.bmp', cv2.IMREAD_GRAYSCALE)
    # 检查图像是否成功加载
    if image is None:
        print("图像加载失败")
    else:
        # 计算离散傅里叶变换 (DFT)
        dft = cv2.dft(np.float32(image), flags=cv2.DFT_COMPLEX_OUTPUT)
        dft_shift = np.fft.fftshift(dft)
        magnitude_spectrum = 20 * np.log(cv2.magnitude(dft_shift[:, :, 0],__

dft_shift[:, :, 1]))
        #显示 DFT 频谱图像
        plt.subplot(131), plt.imshow(magnitude_spectrum, cmap='gray')
        plt.title('DFT Spectrum'), plt.axis('off')
        # 计算离散余弦变换 (DCT)
        dct = cv2.dct(np.float32(image))
        dct_log = np.log(np.abs(dct) + 1)
        # 显示 DCT 频谱图像
        plt.subplot(132), plt.imshow(dct_log, cmap='gray')
        plt.title('DCT Spectrum'), plt.axis('off')
        plt.subplot(133), plt.imshow(np.log(np.abs(dct_log)+1), cmap='gray')
        plt.title('Enhanced DCT Spectrum'), plt.axis('off')
        plt.show()
```



## 手动实现

```
[3]: import numpy as np
    import cv2
    import matplotlib.pyplot as plt
    # 1. 使用矩阵形式实现离散傅里叶变换 (DFT)
    def dft_2d_matrix(image):
       M, N = image.shape
        # 构建行频率矩阵和列频率矩阵
       u = np.arange(M)
       v = np.arange(N)
        x = np.arange(M)
        y = np.arange(N)
        # 行变换矩阵
        W_x = np.exp(-2j * np.pi * u[:, None] * x / M)
        # 列变换矩阵
        W_y = np.exp(-2j * np.pi * v[:, None] * y / N)
        # 对图像进行离散傅里叶变换
        dft_result = W_x @ image @ W_y.T
        return dft_result
    # 2. 使用矩阵形式实现离散余弦变换 (DCT)
```

```
def dct_2d_matrix(image):
   M, N = image.shape
   #构建 DCT 变换矩阵
   u = np.arange(M)
   v = np.arange(N)
   x = np.arange(M)
   y = np.arange(N)
   # 计算 DCT 基函数
   W_x = np.sqrt(2/M)*np.cos(np.pi * (2 * x + 1) * u[:,None] / (2 * M))
   W_y = np.sqrt(2/N)*np.cos(np.pi * (2 * y + 1) * v[:, None] / (2 * N))
   # 对图像进行离散余弦变换
   dct_result = W_x @ image @ W_y.T
   return dct_result
#3. 图像预处理函数
def preprocess_image(image_path):
   # 使用 cv2 加载图像并转换为灰度图像
   img = cv2.imread(image_path, cv2.IMREAD_GRAYSCALE)
   if img is None:
       raise ValueError(f"无法加载图像 {image_path}")
   # 将图像转换为浮动格式并中心化
   img = np.float32(img)
   return img
# 4. 频谱图像显示函数
def display_spectrum(transformed_image,is_dft=True):
   # 计算幅度谱
   magnitude = np.abs(transformed_image)
   if is_dft == True:
       #将频谱图像中心化(使用 fftshift)
```

```
magnitude_shifted = np.fft.fftshift(magnitude)
   else:
       magnitude_shifted =magnitude
   # 对数尺度增强显示效果
   log_magnitude = np.log(1 + magnitude_shifted)
   #显示频谱图像
   plt.figure(figsize=(6, 6))
   plt.imshow(log_magnitude, cmap='gray')
   if is_dft == True:
       plt.title('DFT Magnitude Spectrum')
   else:
       plt.title('DCT Magnitude Spectrum')
   plt.colorbar()
   plt.show()
# 5. 主程序: 加载图像, 进行 DFT 和 DCT 变换, 并显示频谱图像
def main():
   image_path = 'lena.bmp' # 图像路径
   img = preprocess_image(image_path)
   # 1) 计算离散傅里叶变换
   dft_result = dft_2d_matrix(img)
   display_spectrum(dft_result,is_dft=True)
   # 2) 计算离散余弦变换
   dct_result = dct_2d_matrix(img)
   display_spectrum(dct_result,is_dft=False)
if __name__ == '__main__':
   main()
```

