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CP.2.3.1, Sauer3

For the *n*-by-*n* matrix with entries $a_{ij} = 5/(i+2j-1)$, set $x = (1, ..., 1)^T$ and b = Ax. Use the Use the python program from CP.2.2.2 or Numpy's **numpy.linalg.solve** command to compute $\mathbf{x}_{-}\mathbf{c}$, the double precision computed solution. Find the infinity norm of the forward error and the error magnification factor of the problem Ax = b, and compare it with the condition number of A: (a) n = 6, (b) n = 10.

<u>Hint:</u> Be careful with Python's indexing that starts at 0, and Sauer's and Matlab's indexing that starts at 1. With zero-based indexing the formula for a_{ij} is $a_{ij} = 5/(i+2j+2)$. Here is a code snippet to generate A with n = 5.

```
n = 5
A = np.zeros([n, n], dtype=float)
for i in range(0,n):
    for j in range(0,n):
        A[i,j] = 5 / (i + 2*j + 2.)
print(A)
```

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CP.2.3.1, Sauer3, solution, Langou

Colab: https://colab.research.google.com/drive/1YjBvnQZNZYyeWpx5IR5p0M9As0esFe4j

We see that both our python code and numpy.linalg.solve are backward stable for this example. That the backward error returned is less than 2×10^{-16} which is excellent. We do expect numpy.linalg.solve to be backward stable. That is, for any input A and b, we expect the backward error to be of the order of machine precision. For our python code, we are using LU without pivoting and, while for this type of matrix, this seems to work, LU without pivoting is not a backward stable algorithm. So good backward error.

Now the condition number is about 10^8 for n = 6 and about 10^{14} for n = 10.

We see that the forward error is about

$forward_error \approx backward_error \times condition_number$

So despite having low backward error, the forward error is quite high. For n = 6, the forward error is of the order 10^{-9} (which is about $(10^8) \cdot (10^{-16})$.) For n = 10, the forward error is of the order 10^{-4} (which is about $(10^{14}) \cdot (10^{-16})$.)

The relation

 $forward_error \approx backward_error \times condition_number$

is related to the fact that

 $error_magnification_factor = forward_error / backward_error \approx condition_number$

error_magnification_factor = forward_error / backward_error < condition_number

```
for n in [ 6, 10 ]:
  A = np.zeros([n, n], dtype=float)
  for i in range(0,n):
    for j in range(0,n):
     A[i,j] = 5 / (i + 2*j + 2.)
  x = np.ones([n, 1], dtype=float)
  b = A @ x
  xc = np.linalg.solve(A, b)
  relative_forward_error = np.linalg.norm( x - xc, np.inf )\
     / np.linalg.norm( x, np.inf )
  relative_backward_error = np.linalq.norm( b - A@xc, np.inf )\
    / np.linalg.norm( b, np.inf )
  error_magnification_factor = relative_forward_error\
    / relative_backward_error
  print( "n = ",f"\{n:4d\}" )
  print( "relative forward error
                                                      = ",\
    f"{relative_forward_error:8.2e}" )
  print( "relative backward error
    f"{relative_backward_error:8.2e}" )
  print( "error magnification factor
                                                      = ",\
   f"{error_magnification_factor:8.2e}" )
  print( "kappa( A ) = || A ||_oo * || A^{-1} ||_oo
   f"{np.linalg.norm(A,np.infty)\
      * np.linalg.norm(np.linalg.inv(A),np.infty):8.2e}")
  print("\n")
        6
n =
relative forward error
                                               6.48e - 10
relative backward error
                                               1.45e - 16
error magnification factor
                                            = 4.47e + 06
kappa(A) = ||A||_{oo} * ||A^{-1}||_{oo}
                                               7.03e+07
n =
       10
relative forward error
                                            = 2.51e-04
relative backward error
                                            = 1.21e-16
error magnification factor
                                            = 2.07e+12
kappa(A) = ||A||_{-00} * ||A^{-1}||_{-00}
                                               1.31e + 14
for n in [ 6, 10 ]:
  A = np.zeros([n, n], dtype=float)
  for i in range(0,n):
    for j in range(0,n):
      A[i,j] = 5 / (i + 2*j + 2.)
  x = np.ones([n, 1], dtype=float)
  b = A @ x
```

```
L, U = lu_no_pivoting(A)
  y = forward__substitution( L, b )
  xc = backward_substitution( U, y )
  relative_forward_error = np.linalg.norm( x - xc, np.inf )\
     / np.linalg.norm( x, np.inf )
  relative_backward_error = np.linalg.norm( b - A@xc, np.inf )\
    / np.linalg.norm( b, np.inf )
  error_magnification_factor = relative_forward_error\
    / relative_backward_error
  print( "n = ",f"{n:4d}" )
  print( "relative forward error
                                                       = ",\
    f"{relative_forward_error:8.2e}" )
  print( "relative backward error
    f"{relative_backward_error:8.2e}" )
  print( "error magnification factor
   f"{error_magnification_factor:8.2e}" )
  print( "kappa( A ) = || A ||_oo * || A^{-1} ||_oo
   f"{np.linalg.norm(A,np.infty)\
    * np.linalg.norm(np.linalg.inv(A),np.infty):8.2e}")
  print("\n")
n =
relative forward error
                                                6.25e - 10
relative backward error
                                                1.45e - 16
error magnification factor
                                                4.31e + 06
kappa( A ) = || A ||_oo * || A^{-1} ||_oo
                                             = 7.03e+07
```

7.17e-04

1.21e-16

5.91e + 12

1.31e + 14

n =

10

relative forward error

relative backward error

error magnification factor

 $kappa(A) = ||A||_{oo} * ||A^{-1}||_{oo}$