$$f(\theta) = \left[(L_2(\cos\theta\sin\gamma + \sin\theta\cos\gamma) - y_2) \left(p_2^2 - p_1^2 - (L_3\cos\theta - x_1)^2 - L_3^2\sin^2\theta \right) - (L_3\sin\theta) \left(p_3^2 - p_1^2 - (L_2(\cos\theta\cos\gamma - \sin\theta\sin\gamma) - x_2)^2 - (L_2(\cos\theta\sin\gamma + \sin\theta\cos\gamma) - y_2)^2 \right) \right]^2 \\ + \left[-(L_2(\cos\theta\cos\gamma - \sin\theta\sin\gamma) - x_2) (p_2^2 - p_1^2 - (L_3\cos\theta - x_1)^2 - L_3^2\sin^2\theta) + (L_3\cos\theta - x_1) (p_3^2 - p_1^2 - ((L_2(\cos\theta\cos\gamma - \sin\theta\sin\gamma) - x_2)^2) - ((L_2(\cos\theta\sin\gamma + \sin\theta\cos\gamma) - y_2)^2) \right]^2 \\ - 4p_1^2 \left[(L_3\cos\theta - x_1) (L_2(\cos\theta\sin\gamma + \sin\theta\cos\gamma) - y_2) - (L_3\sin\theta) (L_2(\cos\theta\cos\gamma - \sin\theta\sin\gamma) - x_2) \right]^2$$