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CP.2.7.1.a, Sauer3

Implement Newton's Method with appropriate starting points to find all solutions. Check with EX.2.7.3 to make sure your answers are correct.

(a)
$$\begin{cases} u^2 + v^2 = 1\\ (u-1)^2 + v^2 = 1 \end{cases}$$

Hint from Sauer from his solution as in EX.2.7.3:

a. The curves are circles with radius 1 centered at (u, v) = (0, 0) and (1, 0), respectively. Solving the first equation for v^2 and substituting into the second yields $(u - 1)^2 + 1 - u^2 = 1$ or -2u + 1 = 0, so $u = \frac{1}{2}$. The two solutions are

 $\begin{pmatrix} u_1 \\ v_1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{pmatrix}, \text{ and } \begin{pmatrix} u_2 \\ v_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ -\frac{\sqrt{3}}{2} \end{pmatrix}.$

Special Instructions:

- a. Please first compute the two solutions using either Sauer's exact solutions (see Hint above) or scipy.optimize.fsolve or scipy.optimize.root. This will be useful to compute the forward error.
- b. Start Newton's method from a relative distance (as measured by the infinity norm) of at least 0.1 from the solution.
- c. At each iteration of Newton's method, you must print:
 - (a) k, the iteration number
 - (b) the absolute backward error at iteration number k defined by

$$||F(x_k)||_{\infty}$$

where x_k is the current iterate.

(c) the relative forward error at iteration number k defined by

$$||x_k - x||_{\infty}/||x||_{\infty}$$

where x_k is the current iterate and x is the solution as computed by **scipy.optimize.fsolve** or **scipy.optimize.root**.

You can also print the current iterate x_k if you want.

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EX.2.7.2.a, Sauer3, solution, Langou

Colab: https://colab.research.google.com/drive/1PRQ6gpiXodEJBQhQRzifdhheXmzb7ehJ

```
from math import sqrt
import numpy as np
import scipy
```

```
from scipy.optimize import fsolve
from scipy.optimize import root
F = lambda x : np.array([x[0]**2 + x[1]**2 - 1., \]
                         (x[0]-1.)**2+x[1]**2-1.]
# Per EX.2.7.3, we have two exact solution x1 and 2 such that
x1 = np.array([1./2., sqrt(3.)/2.])
x2 = np.array([1./2., - sqrt(3.)/2.])
\# Let us check that || F(x1) || oo and || F(x2) || oo are small
print( "|| F(x1) || oo =", f"{np.linalg.norm(F(x1),np.infty):.2E}")
print("|| F(x2) || _oo =", f"{np.linalg.norm(F(x2),np.infty):.2E}")
| | F(x1) | |_{00} = 1.11E-16
| | F(x2) | |_{-00} = 1.11E-16
\# using scipy.optimize.fsolve to find two approximate solutions
\# x_{-} is the exact solution that we are trying to find, it is either
\# x1 or x2, as per EX.2.7.3. x_{-} is useful to compute the forward error.
\# x is the initial guess, we find that
      starting \ with \ [0, 1], \ scipy.optimize.fsolve \ converge \ to \ x1,
     starting with [0,-1], scipy.optimize.fsolve converge to x2
# so x = [0, 1] and x_{-} = x1 is what we use for the first iteration,
\# and x = \lceil 0, -1 \rceil and x_- = x2 is what we use for the second iteration
for x, x_{-} in zip( [ np.array( [ 0., 1. ] ), np.array( [ 0., -1. ] ) ],
                  [ x1, x2 ] ):
 x = scipy.optimize.fsolve(F, x)
 print( "\nx = [", f"{x[0]:+20.16f}", "]"\
            x* = [", f"{x_{-}[0]:+20.16f}",
           [", f''\{x[1]:+20.16f\}", "]"\
                  [", f''\{x_{-}[1]:+20.16f\}", "]")
 print ("forward error: || x - x* ||_{00} = ",
 f''{np.linalg.norm(x-x<sub>-</sub>,np.infty):7.2e}",\
         "\nbackward error: || F(x) ||_{00} = ", 
f"{np.linalg.norm(F(x),np.infty):7.2e}")
x = [ +0.50000000000000000]
                                 x* = [ +0.500000000000000 ]
    +0.8660254037844409
                                 [ +0.8660254037844386 ]
forward error: || x - x* ||_{-00} = 2.33e-15
backward error: || F(x) ||_{0} = 4.00e-15
x = [ +0.50000000000000000 ] x* = [ +0.5000000000000000 ]
                                [ -0.8660254037844386 ]
    [ -0.8660254037844409 ]
forward error: || x - x* ||_{0} = 2.33e-15
backward error: || F(x) ||_{0} = 4.00e-15
```

```
# using scipy.optimize.root to find two approximate solutions
for x, x_i in zip( [ np.array( [ 0., 1. ] ), np.array( [ 0., -1. ] ) ],
                  [x1, x2]:
 x = scipy.optimize.root(F, x).x
 print( "\nx = [", f"{x[0]:+20.16f}", "]"\
             x* = [", f"{x_{-}[0]:+20.16f}",
             [", f''\{x[1]:+20.16f\}", "]"\
 print( "
                   [", f''\{x_{-}[1]:+20.16f\}", "]")
 print( "forward error: || x - x* ||_{00} = ",
 f''{np.linalg.norm(x-x<sub>-</sub>,np.infty):7.2e}",\
        "\nbackward error: || F(x) || _oo = ",\
 f"{np.linalg.norm(F(x),np.infty):7.2e}")
x = [ +0.500000000000000000]
                                x* = [ +0.500000000000000000]
      +0.8660254037844409
                                      [ +0.8660254037844386 ]
forward error: || x - x* ||_{00} = 2.33e-15
backward error: || F(x) ||_{0} = 4.00e-15
x = [ +0.5000000000000000 ]
                               [ -0.8660254037844386 ]
    [ -0.8660254037844409 ]
forward error: || x - x* ||_{oo} =
                                   2.33e - 15
backward error: || F(x) ||_{00} = 4.00e-15
# this is Jacobian of F
DF = lambda x : np.array([[ 2. * x[0], 2. * x[1] ],
                          [2. * (x[0] - 1.), 2. * x[1]])
for x, x_i in zip( [ np.array( [ 0.1, 1.5 ] ), np.array( [ 0., -1.5 ] ) ],
                 [x1, x2]:
  print( "**", "[", f"{x_{-}[0]:+20.16f}", f"{x_{-}[1]:+20.16f}", "]",\
                  , "******" )
 print( f''\{0:2d\}'', "[", f''\{x[0]:+20.16f\}'', f''\{x[1]:+20.16f\}'',
       "]", f"{np.linalg.norm(x - x_-, np.infty):4.1e}", \
      f"{np.linalg.norm(F(x), np.infty):4.1e}")
\# this is the Newton's method loop, 6 iterations should be enough
 for i in range(1,6):
  this is the Newton's method update
   x = x - np.linalg.solve(DF(x), F(x))
   print( f"{i:2d}", "[", f"{x[0]:+20.16f}", f"{x[1]:+20.16f}",\
           "]", f"{np.linalg.norm(x - x_-, np.infty):4.1e}",\
          f"{np.linalg.norm( F(x), np.infty):4.1e}" )
 print( "\nx = [", f"{x[0]:+20.16f}", "]"\
```

```
x* = [", f"{x_{-}[0]:+20.16f}", "]")
          [", f''\{x[1]:+20.16f\}", "]"\
 print( "
                [", f''\{x_{-}[1]:+20.16f\}", "]")
 print( "forward error: || x - x* ||_{0} = "
       f''{np.linalg.norm(x-x_,np.infty):7.2e}",\
       "\nbackward error: || F(x) || _oo = ",\
       f"{np.linalg.norm(F(x),np.infty):7.2e}")
 print("\n")
** [
     +0.5000000000000000
                        +0.8660254037844386 ] ****** *****
                        +1.5000000000000000 ] 6.3e-01 2.1e+00
0 L
     +0.10000000000000000
                         1 [
     +0.5000000000000001
2 Γ
                        +0.8826793248945148 ] 1.7e-02 2.9e-02
    +0.50000000000000001
3 F +0.5000000000000000
                        +0.8661825124197711 ] 1.6e-04 2.7e-04
4 [ +0.5000000000000000
                        +0.8660254180326618 ] 1.4e-08 2.5e-08
                        +0.8660254037844387 ] 1.1e-16 0.0e+00
5 [ +0.5000000000000000
x = [ +0.5000000000000000 ]
                             x* = [ +0.50000000000000000000]
   +0.8660254037844387
                               [ +0.8660254037844386 ]
forward error: || x - x* ||_{0} = 1.11e-16
backward error: || F(x) ||_{0} = 0.00e+00
** \[ +0.500000000000000
                         -0.8660254037844386 ] ****** ******
                         0 F
     +0.0000000000000000
1 [
     +0.5000000000000000
                         -0.8878205128205128 ] 2.2e-02 3.8e-02
     +0.50000000000000000
3 \Gamma + 0.500000000000000
                         -0.8662929278904008 ] 2.7e-04 4.6e-04
                         -0.8660254450921447 ] 4.1e-08 7.2e-08
4 [
    +0.5000000000000000
5 [ +0.500000000000000
                        -0.8660254037844396 ] 1.0e-15 1.8e-15
                              \mathbf{x} * = \Gamma
                                    +0.5000000000000000000000
[ -0.8660254037844396 ]
                               [ -0.8660254037844386 ]
forward error: || x - x* ||_{00} = 9.99e-16
backward error: || F(x) ||_{00} = 1.78e-15
```