## Solvers for dense and sparse quadratic problems

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## Definition (Unconstrained optimization problem (P))

$$\min_{x\in\mathbb{R}^n}f(x)$$

• where  $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$  is the **objective function** 

## Quadratic functions

## Definition (Quadratic form)

A quadratic form reads

$$f(x) = \frac{1}{2}x^{\top}Ax - b^{\top}x + c$$

where  $x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{n \times n}$ ,  $b \in \mathbb{R}^n$  and  $c \in \mathbb{R}$ .

- ightarrow what equation verifies a stationary point? the point where the gradient is equal to zero
- $\rightarrow$  what condition on A to have existence and unicity of  $x^*$ ?
- ightarrow show that minimizing f boils down to solving a linear system. se reduire

grad  $f(x)=1/2 (A+A^t)x^*-b$  1/2 (A+A^t)x\*=b

# Taylor at order 2

Motivation

Assuming f is twice differentiable, the Taylor expansion at order 2 of f at x reads:

$$\forall h \in \mathbb{R}^n, \ f(x+h) = f(x) + \nabla f(x)^{\top} h + \frac{1}{2} h^{\top} \nabla^2 f(x) h + o(\|h\|^2)$$

- $\nabla f(x) \in \mathbb{R}^n$  is the gradient.
- $\nabla^2 f(x) \in \mathbb{R}^{n \times n}$  the Hessian matrix.

Remark: It gives a local quadratic approximation

 $\rightarrow$  Show that if  $\nabla^2 f(x) = LI$  then minimizing the quadratic approximation leads to gradient descent. With what step size?

> $x+h^*=x-(1/L)^*gradf(x)$  $h^*=1/L$  grad f(x)



We consider problems with n samples, observations, and p features, variables.

## Definition (Ridge regression)

Let  $y \in \mathbb{R}^n$  the n targets to predict and  $(x^i)_i$  the n samples in  $\mathbb{R}^p$ . Ridge regression consists in solving the following problem

$$\min_{w,b} \frac{1}{2} \|y - Xw - b\|^2 + \frac{\lambda}{2} \|w\|^2, \lambda > 0$$

where  $w \in \mathbb{R}^p$  is called the weights vector,  $b \in \mathbb{R}$  is the intercept (a.k.a. bias) and the *i*th row of X is  $x^i$ .

*Remark:* We have an optimization problem in dimension p+1

*Remark:* Note that the intercept is not penalized with  $\lambda$ .



#### Exercise

Let

Motivation

$$\hat{w}, \hat{b} = \arg\min_{w,b} \frac{1}{2} \|y - Xw - b\|^2 + \frac{\lambda}{2} \|w\|^2, \lambda > 0$$

 $\overline{y} \in \mathbb{R}$  the mean of y and  $\overline{X} \in \mathbb{R}^p$  the mean of each column of X.  $\to$  Show that  $\hat{b} = -\overline{X}^{\top}\hat{w} + \overline{y}$ .

$$f(w,b) = 1/2 \ ||y-Xw-b||^2 + lambda/2 \ ||w||^2$$
 grad  $f(w,b) = (gradw \ f(w,b) \ , \ gradb \ f(w,b))^t$ 

grad 
$$f(w^*,b^*)=0$$

$$grad(w) f(w,b) = -X^t (y-Xw-b) + lambda.w$$

$$grad(b) f(w,b) = -1|^{t} (y-Xw-b) = (-\ddot{y} + "X^{t}. w + b) . n$$

## Exercise

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Motivation

$$\hat{w}, \hat{b} = \underset{w,b}{\operatorname{arg\,min}} \frac{1}{2} \|y - Xw - b\|^2 + \frac{\lambda}{2} \|w\|^2, \lambda > 0$$

 $\overline{y} \in \mathbb{R}$  the mean of y and  $\overline{X} \in \mathbb{R}^p$  the mean of each column of X. o Show that  $\hat{b} = -\overline{X}^{\top}\hat{w} + \overline{v}$ .

Ways to deal with the intercept:

• Option 1 (dense case): Center the target y and each column feature and solve:

if feature of value is bigger than others, the descant'll be slow 
$$\min_{w \in \mathbb{R}^p} \frac{1}{2} \|y - Xw\|^2 + \frac{\lambda}{2} \|w\|^2$$

 Option 2 (sparse case): Add a column of 1 to X and try not to penalize it (too much).

prb is strongly convex because lamda>0 Lipschitz constant = ||X^t.X|| + lamda.ld

We consider:

$$\min_{w \in \mathbb{R}^p} \frac{1}{2} \|y - Xw\|^2 + \frac{\lambda}{2} \|w\|^2$$

#### Exercise

- Show that ridge regression boils down to the minimization of a quadratic form.
- Propose a closed form solution.
- Show that the solution is obtained by solving a linear system.
- Is the objective function strongly convex?
- Assuming n convexity?

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# Singular value decomposition (SVD)

- SVD is a factorization of a matrix (real here)
- $M = U \Sigma V^{\top}$  where  $M \in \mathbb{R}^{n \times p}$ ,  $U \in \mathbb{R}^{n \times n}$ ,  $\Sigma \in \mathbb{R}^{n \times p}$ ,  $V \in \mathbb{R}^{p \times p}$
- $U^{\top}U = UU^{\top} = I_n$  (orthogonal matrix)
- $V^{\top}V = VV^{\top} = I_p$  (orthogonal matrix)
- Σ diagonal matrix
- $\Sigma_{i,i}$  are called the singular values
- U are left-singular vectors
- V are right-singular vectors

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# Singular value decomposition (SVD)

- SVD is a factorization of a matrix (real here)
- U contains the eigenvectors of  $MM^{\top}$  associated to the eigenvalues  $\Sigma_{i,i}^2$  for  $1 \leq i \leq n$ .
- V contains the eigenvectors of  $M^{\top}M$  associated to the eigenvalues  $\Sigma_{i,i}^2$  for  $1 \leq i \leq p$ .
- we assume here  $\Sigma_{i,i} = 0$  for  $\min(n,p) \leq i \leq \max(n,p)$
- SVD is particularly useful to find the rank, null-space, image and pseudo-inverse of a matrix

## atrix inversion lemma

## Proposition (Matrix inversion lemma)

also known as Sherman-Morrison-Woodbury formula states that:

$$(A + UCV)^{-1} = A^{-1} - A^{-1}U(C^{-1} + VA^{-1}U)^{-1}VA^{-1},$$

where  $A \in \mathbb{R}^{n \times n}$ ,  $U \in \mathbb{R}^{n \times k}$ ,  $C \in \mathbb{R}^{k \times k}$ ,  $V \in \mathbb{R}^{k \times n}$ .

## Proposition (Matrix inversion lemma)

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*Proof.* Just check that (A+UCV) times the RHS of the Woodbury identity gives the identity matrix:

$$(A + UCV) \left[ A^{-1} - A^{-1}U \left( C^{-1} + VA^{-1}U \right)^{-1} VA^{-1} \right]$$

$$= I + UCVA^{-1} - (U + UCVA^{-1}U)(C^{-1} + VA^{-1}U)^{-1}VA^{-1}$$

$$= I + UCVA^{-1} - UC(C^{-1} + VA^{-1}U)(C^{-1} + VA^{-1}U)^{-1}VA^{-1}$$

$$= I + UCVA^{-1} - UCVA^{-1} = I$$

We consider:

$$\min_{w \in \mathbb{R}^p} \frac{1}{2} \|y - Xw\|^2 + \frac{\lambda}{2} \|w\|^2$$

The solution is given by:

$$A = lambda . Id$$
  
 $X = U.E.V^t$ 

$$\hat{w} = (X^{\top}X + \lambda I_p)^{-1}X^{\top}y$$

Using matrix inversion lemma show that: utiliser pour calculer une matrice de dimension inférieure

$$\hat{w} = X^{\top} (XX^{\top} + \lambda I_n)^{-1} y$$

This is a dual formulation and the matrix to invert is in  $\mathbb{R}^{n \times n}$ .

- $\rightarrow$  Using the SVD of X propose an implementation.
- ightarrow Can you use the SVD to confirm the primal-dual link?
- $\rightarrow$  What if X is sparse, n is 1e5 and p is 1e6? No, we use conjugate gradient



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## Conjugate gradient method: Solve Ax = b

The conjugate gradient method is an iterative method to solve linear systems with positive definite matrices  $(A \succ 0)$ . It only needs to know how to compute Ax (operation can be implicit).

## Principle:

Motivation

- Iterate:  $x^{k+1} = x^k \beta_k d^k$
- The direction  $d^k$  depends on all the gradients at previous iterates  $(\nabla f(x^1), \ldots, \nabla f(x^k))$ .
- $p^k = \beta_k d^k$  is chosen as the vector in  $\operatorname{span}(\nabla f(x^1), \dots, \nabla f(x^k))$  which minimizes  $f(x^k p^k)$



#### Theorem (Convergence in n iterations)

The conjugate gradient algorithm finds the minimum of positive definite quadratic form f, in at most n iterations.



## Conjugate gradient method: Solve Ax = b

- Property
  - $\forall I < k, Ap^k \perp p^I$
  - i.e., vectors  $p^k$  and  $p^l$  are conjugate w.r.t. A
- Computation of the direction:
  - $d^k = g^k + \alpha_k d^{k-1}$  where  $g^k = \nabla f(x^k)$  (we correct the gradient with a term that depends on previous iterations),

$$\alpha_k = -\frac{\langle g^k, Ad^{k-1} \rangle}{\langle Ad^{k-1}, d^{k-1} \rangle}$$

Computation of optimal step size:

$$\beta_k = \frac{\langle g^k, d^k \rangle}{\langle Ad^k, d^k \rangle}$$

# Conjugate gradient: Solve Ax = b

```
Require: A \in \mathbb{R}^{n \times n} and b \in \mathbb{R}^n
 1: x^0 \in \mathbb{R}^n, g^0 = Ax^0 - b
 2: for k = 0 to n do
 3: if g^k = 0 then
 4: break
 5: end if
 6: if k = 0 then
 7: d^k = g^0
         else
 8:
            \alpha_k = -\frac{\langle g^k, Ad^{k-1} \rangle}{\langle d^{k-1}, Ad^{k-1} \rangle}
        d^k = g^k + \alpha_k d^{k-1}
10:
11:
         end if
12: \beta_k = \frac{\langle g^k, d^k \rangle}{\langle d^k, Ad^k \rangle}
13: x^{k+1} = x^k - \beta_k d^k
14: g^{k+1} = Ax^{k+1} - b
15: end for
16: return x^{k+1}
```

If  $g^k = 0$ , then  $x^k = x^*$  is solution of the linear system Ax = b. For k = 1, we have  $d^0 = g^0$ , so:

$$\langle g^{1}, d^{0} \rangle$$

$$= \langle Ax^{1} - b, d^{0} \rangle$$

$$= \langle Ax^{0} - b, d^{0} \rangle - \beta_{0} \langle Ad^{0}, d^{0} \rangle$$

$$= \langle g^{0}, d^{0} \rangle - \beta_{0} \langle Ad^{0}, d^{0} \rangle$$

$$= 0$$
(1)

by definition of  $\beta_0$ . This leads to

$$\langle g^1,g^0\rangle=\langle g^1,d^0\rangle=0$$

and

$$\langle d^1, Ad^0 \rangle = \langle g^1, Ad^0 \rangle + \alpha_0 \langle d^0, Ad^0 \rangle = 0$$

by definition of  $\alpha_0$ .



One can prove the result by recurrence assuming that:

$$\langle g^k, g^j \rangle = 0 \text{ for } 0 \le j < k$$
$$\langle g^k, d^j \rangle = 0 \text{ for } 0 \le j < k$$
$$\langle d^k, Ad^j \rangle = 0 \text{ for } 0 \le j < k$$

If  $g^k \neq 0$ , the algorithm computes  $x^{k+1}$ ,  $g^{k+1}$  and  $d^{k+1}$ .

- By construction one has  $\langle g^{k+1}, d^k \rangle = 0$  (cf. (1)).
- For j < k:

$$\begin{split} &\langle \boldsymbol{g}^{k+1}, \boldsymbol{d}^{j} \rangle \\ = &\langle \boldsymbol{g}^{k+1}, \boldsymbol{d}^{j} \rangle - \langle \boldsymbol{g}^{k}, \boldsymbol{d}^{j} \rangle \\ = &\langle \boldsymbol{g}^{k+1} - \boldsymbol{g}^{k}, \boldsymbol{d}^{j} \rangle \\ = &- \beta_{k} \langle \boldsymbol{A} \boldsymbol{d}^{k}, \boldsymbol{d}^{j} \rangle \\ = &0 \text{ (recurrence hypothesis)} \end{split}$$

• For  $j \leq k$ :

$$\langle g^{k+1},g^j\rangle=\langle g^{k+1},d^j\rangle-\alpha_j\langle g^{k+1},d^{j-1}\rangle=0\ ,$$
 since  $g^j=d^j-\alpha_jd^{j-1}.$ 

• Now: 
$$d^{k+1} = g^{k+1} + \alpha_{k+1}d^k$$
. For  $j < k$  
$$\langle d^{k+1}, Ad^j \rangle$$
 
$$= \langle g^{k+1}, Ad^j \rangle + \alpha_{k+1} \langle d^k, Ad^j \rangle$$
 
$$= \langle g^{k+1}, Ad^j \rangle \ .$$

As 
$$g^{j+1} = g^j - \beta_j A d^j$$
, one obtains

$$\langle g^{k+1}, Ad^j \rangle = \frac{1}{\beta_j} \langle g^{k+1}, g^j - g^{j+1} \rangle = 0 \text{ if } \beta_j \neq 0.$$

This implies that if  $\beta_i \neq 0$ ,  $\langle d^{k+1}, Ad^j \rangle = 0$  for j < k.

- Furthermore one has  $\langle d^{k+1}, Ad^k \rangle = 0$ .
- So  $\langle d^{k+1}, Ad^j \rangle = 0$  for j < k+1.

- This completes the proof for  $\beta_j \neq 0$  and  $g^j \neq 0$ .
- However one has that

$$\begin{split} \langle \mathbf{g}^k, \mathbf{d}^k \rangle &= \langle \mathbf{g}^k, \mathbf{g}^k \rangle + \alpha_k \langle \mathbf{g}^k, \mathbf{d}^{k-1} \rangle = \| \mathbf{g}^k \|^2 \ , \end{split}$$
 and  $\beta_k = \frac{\langle \mathbf{g}^k, \mathbf{d}^k \rangle}{\langle A \mathbf{d}^k, \mathbf{d}^k \rangle}.$ 

- So  $\beta_k$  can only be 0 if  $g^k = 0$ , which would imply that  $x^k = x^*$ .
- Furthermore

$$\|d^k\|^2 = \|g^k\|^2 + \alpha_k^2 \|d^{k-1}\|^2$$
.

So if  $g^k \neq 0$  then  $d^k \neq 0$ .



- Consequently, if the vectors  $g^0$ ,  $g^1$ , ...,  $g^k$  are all non-zero, the vectors  $d^0$ ,  $d^1$ , ...,  $d^k$  are also non-zero.
- These vectors are an orthogonal basis for the dot product  $\langle \cdot, \cdot \rangle_A$  and the k+1 directions
- $g^0$ ,  $g^1$ , ...,  $g^k$  are an orthogonal basis for the dot product  $\langle \cdot, \cdot \rangle$ .
- These directions are therefore independent. As a consequence, if  $g^0$ ,  $g^1$ , ...,  $g^{n-1}$  are all non-zero, one has that  $d^n = g^n = 0$ .
- So it converges after n iterations at the most.

## Warm starts and paths

Motivation

In machine learning it is common to try to solve a problem that is very similar to a previous one. remplace Id by lambda

- You train a model every day and you need just to "update" the model
- You look for the best hyperparmater and evaluate the parameter on a grid of values. For example on a grid of  $\lambda$  when doing cross-validation.

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## More

Motivation

**Note:** Conjugate gradient for sparse linear systems is implemented in scipy.sparse.linalg.cg and in scipy.optimize.fmin\_cg

**Note:** sklearn.linear\_model.Ridge has many solvers. In v0.18 you have 'svd', 'cholesky', 'lsqr', 'sparse\_cg', 'sag' and and 'auto' mode.

- $\rightarrow$  more in the lecture notes.
- $\rightarrow$  cf. notebook