

$$\frac{\partial \hat{y}}{\partial \hat{y}} = \frac{\partial^2}{\partial \hat{y}} = -\frac{2}{\kappa} y_n \frac{\partial \partial y(\hat{y})}{\partial \hat{y}} = -\frac{2}{\kappa} y_n \frac{\partial \hat{y}_k}{\partial \hat{y}_i}$$

$$= -y_i(1-p_i) + \sum_{h \neq i} p_i + y_n = -y_i + p_i l y_i + \sum_{h \neq i} y_n$$

$$= l y_i(1-p_i) + \sum_{h \neq i} p_i + y_i = -y_i + p_i l y_i + \sum_{h \neq i} y_n$$

$$= l y_i(1-p_i) + \sum_{h \neq i} p_i + y_i = -y_i + p_i l y_i + \sum_{h \neq i} y_n$$

On the right hand -side:
$$\frac{-y_i}{\hat{y}_i} * \hat{y}_i - \frac{1}{2} * \hat{y}_j \hat{y}_j$$

$$=-\mathcal{I}_{i}+\mathcal{I}_{j}\hat{\mathcal{I}}_{i}=\widehat{\mathcal{I}}_{i}-\mathcal{I}_{i}=\mathcal{I}_{j}$$

$$(d) dh_{i} = \frac{1}{2} \frac{\partial (\tilde{y})_{i}}{\partial h_{i}} d(\tilde{y})_{j} = d(\tilde{y}_{i} - \tilde{y}_{i}) W^{2}$$

(e)
$$d(z) = \frac{\partial^2}{\partial h_i} + \frac{\partial h}{\partial z} = \frac{e^{-2i}}{(1+e^{-2i})^2} + (\hat{y}_i - \hat{y}_i) W^2 T$$

$$(f) d(w_i)_{ij} = \frac{\partial^2}{\partial z_i} \frac{\partial^2 v}{\partial w_{ij}} = \chi(\hat{y}_i - \hat{y}_i) w^{2T} + h_i (l - h_i)$$