

# Probabilistic Graphical Models

## Lecture 16: Learning: Partial Observability

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June 4, 2020

# Maximum Likelihood Estimation

- We've seen (e.g., Lecture 13) that choosing parameters that maximize the empirical log-likelihood of data is an effective approach to learning

$$\theta^* = \arg \max_{\theta} \frac{1}{|\mathcal{D}|} \sum_{m=1}^{|\mathcal{D}|} \log \hat{P}(\xi; \theta)$$

- Suppose instead that the joint distribution was

$$P(\mathbf{X}, \mathbf{Z}; \theta)$$

where  $\mathcal{D}$  provides samples of  $\mathbf{X}$  but  $\mathbf{Z}$  is never observed, i.e.,

$$\mathcal{D} = \{(0, 1, 0, ?, ?, ?), (1, 1, 1, ?, ?, ?), (0, 1, 1, ?, ?, ?), \dots\}$$

- Assume also that the hidden variables are *missing completely at random* (otherwise, we should model *why* these values are missing)

- In the fully observed, IID case, as  $|\mathcal{D}| \rightarrow \infty$ , the empirical log-likelihood approaches the true expected log-likelihood
- In the partially observed setting, what happens if we have infinite data?
- Is it possible to uniquely identify the true parameters?

# Maximum Likelihood

- We can still use the same maximum likelihood approach
- The objective that we are maximizing becomes

$$\ell(\boldsymbol{\theta}) = \frac{1}{|\mathcal{D}|} \sum_{m=1}^{|\mathcal{D}|} \log \sum_{\mathbf{Z}} P(\mathbf{X}^{(m)}, \mathbf{Z}; \boldsymbol{\theta})$$

- For Bayesian networks, as a result of the marginalization over  $\mathbf{Z}$ :
  - the objective is no longer locally or globally decomposable
  - there is no longer a closed-form solution for  $\boldsymbol{\theta}^*$
- Furthermore, the objective is no longer convex, and may have a different mode for every possible assignment  $\mathbf{Z}$
- One approach is to employ gradient ascent as a general purpose optimization method to reach a local maxima of  $\ell(\boldsymbol{\theta})$

# Expectation Maximization

- The expectation maximization (EM) algorithm provides an alternative approach to finding the local maximum of  $\ell(\boldsymbol{\theta})$
- EM is particularly useful when a closed-form solution for  $\boldsymbol{\theta}^{\text{ML}}$  exists in the fully observed setting
- For example, in Bayesian networks, we have the following

$$\hat{\theta}_{x|u}^{\text{ML}} = \frac{\#[x, u]}{\#[u]}$$

where  $U$  are the parents of  $X$

# Expectation Maximization

The EM algorithm follows as

- 1 Write down the *complete log-likelihood*  $\log P(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta})$  in a way that is linear in  $\mathbf{Z}$
- 2 Initialize  $\boldsymbol{\theta}_0$  at random or using a heuristic
- 3 Repeat until convergence

$$\boldsymbol{\theta}_{t+1} = \arg \max_{\boldsymbol{\theta}} \sum_{m=1}^{|\mathcal{D}|} \mathbb{E}_{P(\mathbf{Z}^{(m)} | \mathbf{X}^{(m)}; \boldsymbol{\theta}_t)} \left[ \log P(\mathbf{X}^{(m)}, \mathbf{Z}; \boldsymbol{\theta}) \right]$$

- Notice that  $\log P(\mathbf{X}^{(m)}, \mathbf{Z}; \boldsymbol{\theta})$  is a random function because  $\mathbf{Z}$  is unknown
- By linearity of expectation, the objective decomposes into expectation terms and data terms
- “E” step corresponds to computing the objective (i.e., the *expectations*)
- “M” step corresponds to *maximizing* the objective