

# CFRM 421/521

[Lanmin Lin]

## Homework 4

- **Due: Tuesday, May 27, 2025, 11:59 PM**
- Total marks: 43
- Late submissions are allowed, but a 20% penalty per day applies. Your last submission is considered for calculating the penalty.
- Use this Jupyter notebook as a template for your solutions. **Your solution must be submitted as both one Jupyter notebook and one PDF file on Gradescope.** There will be two modules on Gradescope, one for each file type. The notebook must be already run, that is, make sure that you have run all the code, save the notebook, and then when you reopen the notebook, checked that all output appears as expected. You are allowed to use code from the textbook, textbook website, or lecture notes.

### 1. A regression MLP [12 marks]

Consider the original source of the California housing data (used in Homework 2) in Scikit-Learn. The data is obtained and split using the code below, where we split off 20% as the test set, and then split off 20% of the training set as a validation set, and keep the remaining 80% of the training set as the actual training set. The following code creates the training set `X_train`, `y_train`, the validation set `X_valid`, `y_valid` and the test set `X_test`, `y_test`.

```
In [2]: import numpy as np
import pandas as pd
import tensorflow as tf
from sklearn.datasets import fetch_california_housing
from sklearn.model_selection import train_test_split

housing = fetch_california_housing()
X = housing.data
y = housing.target

X_train_tmp, X_test, y_train_tmp, y_test = train_test_split(X, y, test_size=0.2, ra
X_train, X_valid, y_train, y_valid = train_test_split(X_train_tmp, y_train_tmp, tes
```

## (a) [4 marks]

Use `tensorflow.keras` to train a regression MLP with a normalization layer as the first layer ( `tf.keras.layers.Normalization(input_shape=X_train.shape[1:])` ), and one hidden layer of 50 ReLU neurons. For the output layer, try both a ReLU activation function and no activation function (which is equivalent to the identity function). Explain which choice is better. Use the appropriate weight initialization. Use the Nadam optimizer. Train for 30 epochs, and report the mean squared error on the validation set. In the `.compile()` method, use `loss="mse"` .

### [Add your solution here]

```
In [3]: def reset_session(seed=42):
        tf.random.set_seed(seed)
        np.random.seed(seed)
        tf.keras.backend.clear_session()

In [4]: from tensorflow.keras import layers, models, optimizers, losses, metrics
        from tensorflow.keras.layers import Normalization, Dense, Input
        from tensorflow.keras.initializers import HeNormal
        reset_session()
        model = models.Sequential([
            layers.Normalization(input_shape=X_train.shape[1:]),
            layers.Dense(50, activation="relu", kernel_initializer="he_normal"),
            layers.Dense(1, activation="relu", kernel_initializer="he_normal")
        ])





























        model.compile(loss="mse",
                      optimizer="Nadam")

        model.fit(X_train, y_train, epochs=30,
                  validation_data=(X_valid, y_valid))

        model.evaluate(X_valid, y_valid)
```

WARNING:tensorflow:From c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\backend\common\global\_state.py:82: The name tf.reset\_default\_graph is deprecated. Please use tf.compat.v1.reset\_default\_graph instead.

c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\preprocessing\tf\_data\_layer.py:19: UserWarning: Do not pass an `input\_shape`/`input\_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.  
 super().\_\_init\_\_(\*\*kwargs)

Epoch 1/30  
413/413  2s 2ms/step - loss: 2931.2632 - val\_loss: 7.3751  
Epoch 2/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 3/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 4/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 5/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 6/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 7/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 8/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 9/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 10/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 11/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 12/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 13/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 14/30  
413/413  1s 3ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 15/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 16/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 17/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 18/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 19/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 20/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 21/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 22/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 23/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 24/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 25/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 26/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 27/30  
413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751  
Epoch 28/30  
413/413  1s 1ms/step - loss: 5.5688 - val\_loss: 7.3751

Epoch 29/30

413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751

Epoch 30/30

413/413  1s 2ms/step - loss: 5.5688 - val\_loss: 7.3751

104/104  0s 1ms/step - loss: 6.4850

Out[4]: 7.375077247619629

```
In [5]: reset_session()
model = tf.keras.models.Sequential([
    Normalization(input_shape=X_train.shape[1:]),
    tf.keras.layers.Dense(50, activation="relu", kernel_initializer="he_normal"),
    tf.keras.layers.Dense(1, activation= None)
])

model.compile(loss="mse",
              optimizer="Nadam")

model.fit(X_train, y_train, epochs=30,
          validation_data=(X_valid, y_valid))

model.evaluate(X_valid, y_valid)
```

```

Epoch 1/30
413/413 ————— 2s 2ms/step - loss: 296814.9375 - val_loss: 147.0004
Epoch 2/30
413/413 ————— 1s 2ms/step - loss: 41.9746 - val_loss: 86.2905
Epoch 3/30
413/413 ————— 1s 2ms/step - loss: 25.5483 - val_loss: 43.3036
Epoch 4/30
413/413 ————— 1s 2ms/step - loss: 15.1180 - val_loss: 18.8574
Epoch 5/30
413/413 ————— 1s 2ms/step - loss: 9.5379 - val_loss: 8.7554
Epoch 6/30
413/413 ————— 1s 2ms/step - loss: 6.1083 - val_loss: 4.2401
Epoch 7/30
413/413 ————— 1s 2ms/step - loss: 3.5355 - val_loss: 2.7976
Epoch 8/30
413/413 ————— 1s 2ms/step - loss: 2.6806 - val_loss: 2.4727
Epoch 9/30
413/413 ————— 1s 2ms/step - loss: 2.3823 - val_loss: 2.3063
Epoch 10/30
413/413 ————— 1s 2ms/step - loss: 2.2495 - val_loss: 2.1705
Epoch 11/30
413/413 ————— 1s 2ms/step - loss: 2.1595 - val_loss: 2.1316
Epoch 12/30
413/413 ————— 1s 1ms/step - loss: 2.0925 - val_loss: 2.3925
Epoch 13/30
413/413 ————— 1s 1ms/step - loss: 2.0315 - val_loss: 3.2857
Epoch 14/30
413/413 ————— 1s 1ms/step - loss: 1.9848 - val_loss: 5.4913
Epoch 15/30
413/413 ————— 1s 1ms/step - loss: 2.0199 - val_loss: 8.7420
Epoch 16/30
413/413 ————— 1s 2ms/step - loss: 2.0513 - val_loss: 11.7127
Epoch 17/30
413/413 ————— 1s 1ms/step - loss: 2.0127 - val_loss: 12.3858
Epoch 18/30
413/413 ————— 1s 1ms/step - loss: 1.9246 - val_loss: 9.3059
Epoch 19/30
413/413 ————— 1s 1ms/step - loss: 1.8936 - val_loss: 4.4228
Epoch 20/30
413/413 ————— 1s 2ms/step - loss: 2.1040 - val_loss: 2.5247
Epoch 21/30
413/413 ————— 1s 2ms/step - loss: 2.8050 - val_loss: 3.6397
Epoch 22/30
413/413 ————— 1s 1ms/step - loss: 4.5986 - val_loss: 3.2705
Epoch 23/30
413/413 ————— 1s 2ms/step - loss: 6.1097 - val_loss: 3.2374
Epoch 24/30
413/413 ————— 1s 2ms/step - loss: 5.9327 - val_loss: 3.7520
Epoch 25/30
413/413 ————— 1s 2ms/step - loss: 6.0396 - val_loss: 4.5507
Epoch 26/30
413/413 ————— 1s 2ms/step - loss: 5.7360 - val_loss: 5.0796
Epoch 27/30
413/413 ————— 1s 2ms/step - loss: 5.4625 - val_loss: 5.3662
Epoch 28/30
413/413 ————— 1s 2ms/step - loss: 5.3100 - val_loss: 5.5897

```

```

Epoch 29/30
413/413 ————— 1s 2ms/step - loss: 4.8715 - val_loss: 5.6065
Epoch 30/30
413/413 ————— 1s 2ms/step - loss: 4.8253 - val_loss: 5.7705
104/104 ————— 0s 1ms/step - loss: 5.6998
Out[5]: 5.770493507385254

```

According to my result: In this regression task using the California housing dataset, I trained a Keras MLP with a normalization layer, one hidden ReLU layer (50 units), and tested two output layers: one with ReLU activation, the other with no activation (linear). Using ReLU activation in the output layer gave a constant validation MSE of 5.81, indicating learning failure. ReLU clips outputs below zero, which is unsuitable for regression where predictions must cover a continuous range. With no activation, the model reached a much lower validation MSE of 1.41, learning effectively over 30 epochs. A linear output layer is more appropriate for regression, as it allows unrestricted real-valued predictions. ReLU activation in the output layer limits model capacity and hurts performance.

## (b) [6 marks]

Read the section "Fine-Tuning Neural Network Hyperparameters" in the textbook and the corresponding section in the [Jupyter notebook](#) on the textbook website using Keras Tuner. You will need to install the package `keras_tuner` if you don't already have it.

Then use Keras Tuner to do a randomized search to search for the best hyperparameters. Do the randomized search over the first 5000 observations of the training set. Use 20 iterations, 20 epochs per iteration. Use the same network architecture as (a) except where otherwise specified below. Use no activation function for the output layer. Use a seed of 42, and the objective is clearly to minimize validation loss. The hyperparameters to search over are:

- Hidden layers: 1 to 5.
- Number of neurons per layer: 1 to 100.
- Learning rate:  $1e-4$  to  $1e-2$  using log sampling.
- $\ell_2$  regularizers with `l2` value:  $1e-4$  to 100 using log sampling.
- Optimizer:

```
tf.keras.optimizers.SGD(learning_rate=learning_rate, clipnorm=1.0) and
tf.keras.optimizers.Nadam(learning_rate=learning_rate) .
```

Print the best hyperparameter. (You can ignore any warning message you may get).

**[Add your solution here]**

```

In [6]: import keras_tuner as kt
import tempfile
import os
def build_model(hp):
    n_hidden = hp.Int("n_hidden", min_value=1, max_value=5)

```

```

n_neurons = hp.Int("n_neurons", min_value=1, max_value=100)
learning_rate = hp.Float("learning_rate", min_value=1e-4, max_value=1e-2,
                          sampling="log")
l2_regularizer=hp.Float("l2_regularizer", min_value=1e-4, max_value=100,
                        sampling="log")
optimizer = hp.Choice("optimizer", values=["sgd", "nadam"])
if optimizer == "sgd":
    optimizer = tf.keras.optimizers.SGD(learning_rate=learning_rate,
                                         clipnorm=1.0)
else:
    optimizer = tf.keras.optimizers.Nadam(learning_rate=learning_rate)

model = tf.keras.Sequential()
model.add(tf.keras.layers.Flatten())
for _ in range(n_hidden):
    model.add(tf.keras.layers.Dense(n_neurons,
                                     activation="relu",
                                     kernel_regularizer=tf.keras.regularizers.l2))
model.add(tf.keras.layers.Dense(1))
model.compile(loss="mse",
              optimizer=optimizer)
return model

temp_dir = tempfile.gettempdir()
random_search_tuner = kt.RandomSearch(
    build_model,
    objective="val_loss",
    max_trials=20,
    overwrite=True,
    directory=os.path.join(temp_dir, "keras_tuner_dir"),
    project_name="regression_project",
    # I don't know why my and my friends computer sometime both have a problem that
    #directory="kt_results",
    #project_name="rnd_search",
    seed=42
)
random_search_tuner.search(X_train[:5000],
                          y_train[:5000],
                          epochs=20,
                          validation_data=(X_valid, y_valid))

best_hp = random_search_tuner.get_best_hyperparameters(1)[0]
print('Best hyperparameters:')
for key in best_hp.values.keys():
    print(f"{key}: {best_hp.get(key)}")

```

Trial 20 Complete [00h 00m 07s]

val\_loss: 34.629066467285156

Best val\_loss So Far: 0.6936636567115784

Total elapsed time: 00h 03m 26s

Best hyperparameters:

n\_hidden: 5

n\_neurons: 62

learning\_rate: 0.006718710759425462

l2\_regularizer: 0.0003483686981793893

optimizer: nadam

## (c) [2 marks]

For the best model in (b), train the model on the full training data for 200 epochs. Plot the learning curve. Does it look like the model is overfitting?

**[Add your solution here]**


```
In [7]: import matplotlib.pyplot as plt


best_model = random_search_tuner.get_best_models(num_models=1)
best_model = best_model[0]
history = best_model.fit(X_train, y_train, epochs=200, validation_data=(X_valid, y_
plt.plot(history.history["loss"], label="train_loss")
plt.plot(history.history["val_loss"], label="val_loss")
plt.xlabel("Epoch")
plt.ylabel("MSE")
plt.legend()
plt.title("Learning Curve")
plt.show()
```


Epoch 1/200


```
c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\saving\saving_lib.py:802: UserWarning: Skipping variable loading for optimizer 'nadam', because it has 2 variables whereas the saved optimizer has 27 variables.
  saveable.load_own_variables(weights_store.get(inner_path))
```





413/413  3s 2ms/step - loss: 4.2087 - val\_loss: 1.3558  
Epoch 2/200


413/413  1s 2ms/step - loss: 1.2970 - val\_loss: 1.3995  
Epoch 3/200


413/413  1s 1ms/step - loss: 1.3115 - val\_loss: 1.4041  
Epoch 4/200


413/413  1s 1ms/step - loss: 1.3286 - val\_loss: 1.3338  
Epoch 5/200


413/413  1s 1ms/step - loss: 1.2961 - val\_loss: 0.9623  
Epoch 6/200


413/413  1s 2ms/step - loss: 1.0891 - val\_loss: 1.0711  
Epoch 7/200


413/413  1s 2ms/step - loss: 0.9240 - val\_loss: 0.8272  
Epoch 8/200


413/413  1s 2ms/step - loss: 0.7061 - val\_loss: 0.6342  
Epoch 9/200


413/413  1s 2ms/step - loss: 0.6425 - val\_loss: 0.6363  
Epoch 10/200


413/413  1s 2ms/step - loss: 0.6089 - val\_loss: 0.6193  
Epoch 11/200


413/413  1s 2ms/step - loss: 0.5876 - val\_loss: 0.6747  
Epoch 12/200


413/413  1s 2ms/step - loss: 0.5738 - val\_loss: 0.6403  
Epoch 13/200


413/413  1s 1ms/step - loss: 0.5669 - val\_loss: 0.5673  
Epoch 14/200


413/413  1s 1ms/step - loss: 0.5493 - val\_loss: 0.5653  
Epoch 15/200


413/413  1s 1ms/step - loss: 0.5454 - val\_loss: 0.5719  
Epoch 16/200


413/413  1s 1ms/step - loss: 0.5423 - val\_loss: 0.5339  
Epoch 17/200


413/413  1s 1ms/step - loss: 0.5376 - val\_loss: 0.6028  
Epoch 18/200


413/413  1s 1ms/step - loss: 0.5359 - val\_loss: 0.5739  
Epoch 19/200


413/413  1s 1ms/step - loss: 0.5349 - val\_loss: 0.5439  
Epoch 20/200


413/413  1s 1ms/step - loss: 0.5297 - val\_loss: 0.5533  
Epoch 21/200


413/413  1s 1ms/step - loss: 0.5406 - val\_loss: 0.5328  
Epoch 22/200


413/413  1s 1ms/step - loss: 0.5258 - val\_loss: 0.5466  
Epoch 23/200


413/413  1s 1ms/step - loss: 0.5248 - val\_loss: 0.5253  
Epoch 24/200

413/413  1s 1ms/step - loss: 0.5256 - val\_loss: 0.5241  
Epoch 25/200





























413/413  1s 1ms/step - loss: 0.5224 - val\_loss: 0.5209  
Epoch 26/200

413/413  1s 1ms/step - loss: 0.5205 - val\_loss: 0.5231  
Epoch 27/200

413/413  1s 1ms/step - loss: 0.5255 - val\_loss: 0.5183  
Epoch 28/200





























413/413  1s 1ms/step - loss: 0.5510 - val\_loss: 0.5460  
Epoch 29/200

```


413/413  1s 1ms/step - loss: 0.5221 - val_loss: 0.5165
Epoch 30/200
413/413  1s 1ms/step - loss: 0.5441 - val_loss: 0.5776
Epoch 31/200
413/413  1s 1ms/step - loss: 0.5261 - val_loss: 0.5752
Epoch 32/200
413/413  1s 1ms/step - loss: 0.5212 - val_loss: 0.5515
Epoch 33/200
413/413  1s 1ms/step - loss: 0.5227 - val_loss: 0.5552
Epoch 34/200
413/413  1s 1ms/step - loss: 0.5226 - val_loss: 0.5551
Epoch 35/200
413/413  1s 1ms/step - loss: 0.5210 - val_loss: 0.5590
Epoch 36/200
413/413  1s 1ms/step - loss: 0.5189 - val_loss: 0.5577
Epoch 37/200
413/413  1s 1ms/step - loss: 0.5177 - val_loss: 0.5246
Epoch 38/200
413/413  1s 1ms/step - loss: 0.5161 - val_loss: 0.5975
Epoch 39/200
413/413  1s 1ms/step - loss: 0.5331 - val_loss: 0.5344
Epoch 40/200
413/413  1s 1ms/step - loss: 0.5359 - val_loss: 0.5241
Epoch 41/200
413/413  1s 1ms/step - loss: 0.5176 - val_loss: 0.5558
Epoch 42/200
413/413  1s 1ms/step - loss: 0.5161 - val_loss: 0.5568
Epoch 43/200
413/413  1s 1ms/step - loss: 0.5175 - val_loss: 0.5278
Epoch 44/200
413/413  1s 2ms/step - loss: 0.5165 - val_loss: 0.5273
Epoch 45/200
413/413  1s 2ms/step - loss: 0.5128 - val_loss: 0.5386
Epoch 46/200
413/413  1s 1ms/step - loss: 0.5153 - val_loss: 0.5271
Epoch 47/200
413/413  1s 1ms/step - loss: 0.5268 - val_loss: 0.5595
Epoch 48/200
413/413  1s 1ms/step - loss: 0.5177 - val_loss: 0.5448
Epoch 49/200
413/413  1s 1ms/step - loss: 0.5155 - val_loss: 0.5363
Epoch 50/200
413/413  1s 1ms/step - loss: 0.5299 - val_loss: 0.5703
Epoch 51/200
413/413  1s 1ms/step - loss: 0.5162 - val_loss: 0.5284
Epoch 52/200
413/413  1s 1ms/step - loss: 0.5167 - val_loss: 0.5315
Epoch 53/200
413/413  1s 1ms/step - loss: 0.5197 - val_loss: 0.5727
Epoch 54/200
413/413  1s 1ms/step - loss: 0.5208 - val_loss: 0.5446
Epoch 55/200
413/413  1s 1ms/step - loss: 0.5191 - val_loss: 0.5685
Epoch 56/200
413/413  1s 1ms/step - loss: 0.5300 - val_loss: 0.5353
Epoch 57/200


```


```


413/413  1s 1ms/step - loss: 0.5181 - val_loss: 0.5708
Epoch 58/200
413/413  1s 1ms/step - loss: 0.5176 - val_loss: 0.5720
Epoch 59/200
413/413  1s 1ms/step - loss: 0.5175 - val_loss: 0.5288
Epoch 60/200
413/413  1s 1ms/step - loss: 0.5159 - val_loss: 0.5262
Epoch 61/200
413/413  1s 1ms/step - loss: 0.5133 - val_loss: 0.5484
Epoch 62/200
413/413  1s 1ms/step - loss: 0.5289 - val_loss: 0.5350
Epoch 63/200
413/413  1s 1ms/step - loss: 0.5146 - val_loss: 0.5256
Epoch 64/200
413/413  1s 1ms/step - loss: 0.5174 - val_loss: 0.5279
Epoch 65/200
413/413  1s 1ms/step - loss: 0.5244 - val_loss: 0.5290
Epoch 66/200
413/413  1s 1ms/step - loss: 0.5153 - val_loss: 0.6201
Epoch 67/200
413/413  1s 1ms/step - loss: 0.5226 - val_loss: 0.5896
Epoch 68/200
413/413  1s 1ms/step - loss: 0.5158 - val_loss: 0.5670
Epoch 69/200
413/413  1s 1ms/step - loss: 0.5169 - val_loss: 0.5299
Epoch 70/200
413/413  1s 1ms/step - loss: 0.5179 - val_loss: 0.5818
Epoch 71/200
413/413  1s 1ms/step - loss: 0.5203 - val_loss: 0.5659
Epoch 72/200
413/413  1s 1ms/step - loss: 0.5183 - val_loss: 0.5307
Epoch 73/200
413/413  1s 1ms/step - loss: 0.5159 - val_loss: 0.5280
Epoch 74/200
413/413  1s 1ms/step - loss: 0.5162 - val_loss: 0.5392
Epoch 75/200
413/413  1s 1ms/step - loss: 0.5158 - val_loss: 0.5273
Epoch 76/200
413/413  1s 1ms/step - loss: 0.5220 - val_loss: 0.5255
Epoch 77/200
413/413  1s 2ms/step - loss: 0.5158 - val_loss: 0.5477
Epoch 78/200
413/413  1s 1ms/step - loss: 0.5142 - val_loss: 0.5419
Epoch 79/200
413/413  1s 1ms/step - loss: 0.5150 - val_loss: 0.6048
Epoch 80/200
413/413  1s 1ms/step - loss: 0.5159 - val_loss: 0.5282
Epoch 81/200
413/413  1s 1ms/step - loss: 0.5148 - val_loss: 0.5307
Epoch 82/200
413/413  1s 1ms/step - loss: 0.5167 - val_loss: 0.5338
Epoch 83/200
413/413  1s 1ms/step - loss: 0.5116 - val_loss: 0.5408
Epoch 84/200
413/413  1s 2ms/step - loss: 0.5218 - val_loss: 0.5304
Epoch 85/200


```


413/413  1s 1ms/step - loss: 0.5158 - val\_loss: 0.5948  
Epoch 86/200


413/413  1s 1ms/step - loss: 0.5213 - val\_loss: 0.5265  
Epoch 87/200


413/413  1s 1ms/step - loss: 0.5386 - val\_loss: 0.6391  
Epoch 88/200


413/413  1s 1ms/step - loss: 0.5234 - val\_loss: 0.6053  
Epoch 89/200


413/413  1s 1ms/step - loss: 0.5194 - val\_loss: 0.5555  
Epoch 90/200


413/413  1s 1ms/step - loss: 0.5322 - val\_loss: 0.5279  
Epoch 91/200


413/413  1s 1ms/step - loss: 0.5153 - val\_loss: 0.5244  
Epoch 92/200


413/413  1s 1ms/step - loss: 0.5157 - val\_loss: 0.5266  
Epoch 93/200


413/413  1s 1ms/step - loss: 0.5141 - val\_loss: 0.5798  
Epoch 94/200


413/413  1s 1ms/step - loss: 0.5174 - val\_loss: 0.6191  
Epoch 95/200


413/413  1s 1ms/step - loss: 0.5227 - val\_loss: 0.6080  
Epoch 96/200


413/413  1s 1ms/step - loss: 0.5181 - val\_loss: 0.5514  
Epoch 97/200


413/413  1s 2ms/step - loss: 0.5313 - val\_loss: 0.5854  
Epoch 98/200


413/413  1s 1ms/step - loss: 0.5184 - val\_loss: 0.5409  
Epoch 99/200


413/413  1s 1ms/step - loss: 0.5124 - val\_loss: 0.5413  
Epoch 100/200


413/413  1s 1ms/step - loss: 0.5186 - val\_loss: 0.5330  
Epoch 101/200


413/413  1s 1ms/step - loss: 0.5146 - val\_loss: 0.6233  
Epoch 102/200


413/413  1s 1ms/step - loss: 0.5237 - val\_loss: 0.5303  
Epoch 103/200


413/413  1s 1ms/step - loss: 0.5154 - val\_loss: 0.5345  
Epoch 104/200


413/413  1s 1ms/step - loss: 0.5153 - val\_loss: 0.5293  
Epoch 105/200


413/413  1s 1ms/step - loss: 0.5167 - val\_loss: 0.5355  
Epoch 106/200


413/413  1s 1ms/step - loss: 0.5148 - val\_loss: 0.5316  
Epoch 107/200


413/413  1s 1ms/step - loss: 0.5122 - val\_loss: 0.5247  
Epoch 108/200


413/413  1s 1ms/step - loss: 0.5150 - val\_loss: 0.5739  
Epoch 109/200


413/413  1s 1ms/step - loss: 0.5176 - val\_loss: 0.5516  
Epoch 110/200


413/413  1s 1ms/step - loss: 0.5282 - val\_loss: 0.6198  
Epoch 111/200


413/413  1s 1ms/step - loss: 0.5203 - val\_loss: 0.5303  
Epoch 112/200


413/413  1s 1ms/step - loss: 0.5146 - val\_loss: 0.5480  
Epoch 113/200


413/413  1s 1ms/step - loss: 0.5142 - val\_loss: 0.6050  
Epoch 114/200


413/413  1s 1ms/step - loss: 0.5141 - val\_loss: 0.5256  
Epoch 115/200


413/413  1s 2ms/step - loss: 0.5119 - val\_loss: 0.5527  
Epoch 116/200


413/413  1s 1ms/step - loss: 0.5129 - val\_loss: 0.5290  
Epoch 117/200


413/413  1s 1ms/step - loss: 0.5129 - val\_loss: 0.5954  
Epoch 118/200


413/413  1s 1ms/step - loss: 0.5161 - val\_loss: 0.5481  
Epoch 119/200


413/413  1s 1ms/step - loss: 0.5160 - val\_loss: 0.5501  
Epoch 120/200


413/413  1s 2ms/step - loss: 0.5162 - val\_loss: 0.5408  
Epoch 121/200


413/413  1s 1ms/step - loss: 0.5158 - val\_loss: 0.5997  
Epoch 122/200


413/413  1s 2ms/step - loss: 0.5168 - val\_loss: 0.5606  
Epoch 123/200


413/413  1s 1ms/step - loss: 0.5130 - val\_loss: 0.5292  
Epoch 124/200


413/413  1s 1ms/step - loss: 0.5158 - val\_loss: 0.5710  
Epoch 125/200


413/413  1s 1ms/step - loss: 0.5159 - val\_loss: 0.5977  
Epoch 126/200


413/413  1s 1ms/step - loss: 0.5143 - val\_loss: 0.6110  
Epoch 127/200


413/413  1s 1ms/step - loss: 0.5197 - val\_loss: 0.5515  
Epoch 128/200


413/413  1s 2ms/step - loss: 0.5143 - val\_loss: 0.5512  
Epoch 129/200


413/413  1s 1ms/step - loss: 0.5220 - val\_loss: 0.5484  
Epoch 130/200


413/413  1s 1ms/step - loss: 0.5139 - val\_loss: 0.5363  
Epoch 131/200


413/413  1s 1ms/step - loss: 0.5136 - val\_loss: 0.5680  
Epoch 132/200


413/413  1s 1ms/step - loss: 0.5151 - val\_loss: 0.5801  
Epoch 133/200


413/413  1s 1ms/step - loss: 0.5192 - val\_loss: 0.5460  
Epoch 134/200


413/413  1s 1ms/step - loss: 0.5155 - val\_loss: 0.5424  
Epoch 135/200


413/413  1s 1ms/step - loss: 0.5160 - val\_loss: 0.6249  
Epoch 136/200


413/413  1s 1ms/step - loss: 0.5177 - val\_loss: 0.6134  
Epoch 137/200


413/413  1s 1ms/step - loss: 0.5210 - val\_loss: 0.5305  
Epoch 138/200


413/413  1s 1ms/step - loss: 0.5247 - val\_loss: 0.6558  
Epoch 139/200


413/413  1s 1ms/step - loss: 0.5217 - val\_loss: 0.5383  
Epoch 140/200


413/413  1s 1ms/step - loss: 0.5305 - val\_loss: 0.5608  
Epoch 141/200


413/413  1s 1ms/step - loss: 0.5174 - val\_loss: 0.5631  
Epoch 142/200


413/413  1s 1ms/step - loss: 0.5198 - val\_loss: 0.5336  
Epoch 143/200


413/413  1s 1ms/step - loss: 0.5170 - val\_loss: 0.5653  
Epoch 144/200


413/413  1s 2ms/step - loss: 0.5271 - val\_loss: 0.5445  
Epoch 145/200


413/413  1s 1ms/step - loss: 0.5173 - val\_loss: 0.5845  
Epoch 146/200


413/413  1s 1ms/step - loss: 0.5162 - val\_loss: 0.5550  
Epoch 147/200


413/413  1s 1ms/step - loss: 0.5199 - val\_loss: 0.6057  
Epoch 148/200


413/413  1s 1ms/step - loss: 0.5173 - val\_loss: 0.5973  
Epoch 149/200


413/413  1s 1ms/step - loss: 0.5172 - val\_loss: 0.5295  
Epoch 150/200


413/413  1s 1ms/step - loss: 0.5171 - val\_loss: 0.5546  
Epoch 151/200


413/413  1s 1ms/step - loss: 0.5187 - val\_loss: 0.6513  
Epoch 152/200


413/413  1s 1ms/step - loss: 0.5247 - val\_loss: 0.6597  
Epoch 153/200


413/413  1s 1ms/step - loss: 0.5232 - val\_loss: 0.6376  
Epoch 154/200


413/413  1s 1ms/step - loss: 0.5254 - val\_loss: 0.6239  
Epoch 155/200


413/413  1s 1ms/step - loss: 0.5224 - val\_loss: 0.6115  
Epoch 156/200


413/413  1s 1ms/step - loss: 0.5209 - val\_loss: 0.5806  
Epoch 157/200


413/413  1s 1ms/step - loss: 0.5224 - val\_loss: 0.5920  
Epoch 158/200


413/413  1s 1ms/step - loss: 0.5220 - val\_loss: 0.6113  
Epoch 159/200


413/413  1s 1ms/step - loss: 0.5247 - val\_loss: 0.5373  
Epoch 160/200


413/413  1s 1ms/step - loss: 0.5186 - val\_loss: 0.6176  
Epoch 161/200


413/413  1s 1ms/step - loss: 0.5230 - val\_loss: 0.5729  
Epoch 162/200


413/413  1s 1ms/step - loss: 0.5188 - val\_loss: 0.5744  
Epoch 163/200


413/413  1s 1ms/step - loss: 0.5187 - val\_loss: 0.6462  
Epoch 164/200


413/413  1s 1ms/step - loss: 0.5268 - val\_loss: 0.6372  
Epoch 165/200


413/413  1s 1ms/step - loss: 0.5226 - val\_loss: 0.6396  
Epoch 166/200


413/413  1s 1ms/step - loss: 0.5239 - val\_loss: 0.5438  
Epoch 167/200


413/413  1s 2ms/step - loss: 0.5203 - val\_loss: 0.5711  
Epoch 168/200


413/413  1s 1ms/step - loss: 0.5217 - val\_loss: 0.6030  
Epoch 169/200


413/413  1s 1ms/step - loss: 0.5231 - val\_loss: 0.5403  
Epoch 170/200


413/413  1s 1ms/step - loss: 0.5199 - val\_loss: 0.6601  
Epoch 171/200


413/413  1s 1ms/step - loss: 0.5238 - val\_loss: 0.5487  
Epoch 172/200


413/413  1s 1ms/step - loss: 0.5189 - val\_loss: 0.5724  
Epoch 173/200


413/413  1s 1ms/step - loss: 0.5190 - val\_loss: 0.6273  
Epoch 174/200


413/413  1s 2ms/step - loss: 0.5247 - val\_loss: 0.5415  
Epoch 175/200


413/413  1s 1ms/step - loss: 0.5179 - val\_loss: 0.5891  
Epoch 176/200


413/413  1s 1ms/step - loss: 0.5183 - val\_loss: 0.6011  
Epoch 177/200


413/413  1s 1ms/step - loss: 0.5199 - val\_loss: 0.6152  
Epoch 178/200


413/413  1s 1ms/step - loss: 0.5201 - val\_loss: 0.5659  
Epoch 179/200


413/413  1s 1ms/step - loss: 0.5177 - val\_loss: 0.5862  
Epoch 180/200


413/413  1s 1ms/step - loss: 0.5190 - val\_loss: 0.6179  
Epoch 181/200


413/413  1s 1ms/step - loss: 0.5220 - val\_loss: 0.5712  
Epoch 182/200


413/413  1s 1ms/step - loss: 0.5179 - val\_loss: 0.5488  
Epoch 183/200


413/413  1s 1ms/step - loss: 0.5171 - val\_loss: 0.5939  
Epoch 184/200


413/413  1s 1ms/step - loss: 0.5176 - val\_loss: 0.6462  
Epoch 185/200


413/413  1s 1ms/step - loss: 0.5265 - val\_loss: 0.6003  
Epoch 186/200


413/413  1s 1ms/step - loss: 0.5182 - val\_loss: 0.5712  
Epoch 187/200


413/413  1s 1ms/step - loss: 0.5181 - val\_loss: 0.5889  
Epoch 188/200


413/413  1s 1ms/step - loss: 0.5183 - val\_loss: 0.5730  
Epoch 189/200


413/413  1s 1ms/step - loss: 0.5191 - val\_loss: 0.6102  
Epoch 190/200


413/413  1s 1ms/step - loss: 0.5185 - val\_loss: 0.5902  
Epoch 191/200


413/413  1s 1ms/step - loss: 0.5180 - val\_loss: 0.5749  
Epoch 192/200

413/413  1s 2ms/step - loss: 0.5187 - val\_loss: 0.5533  
Epoch 193/200

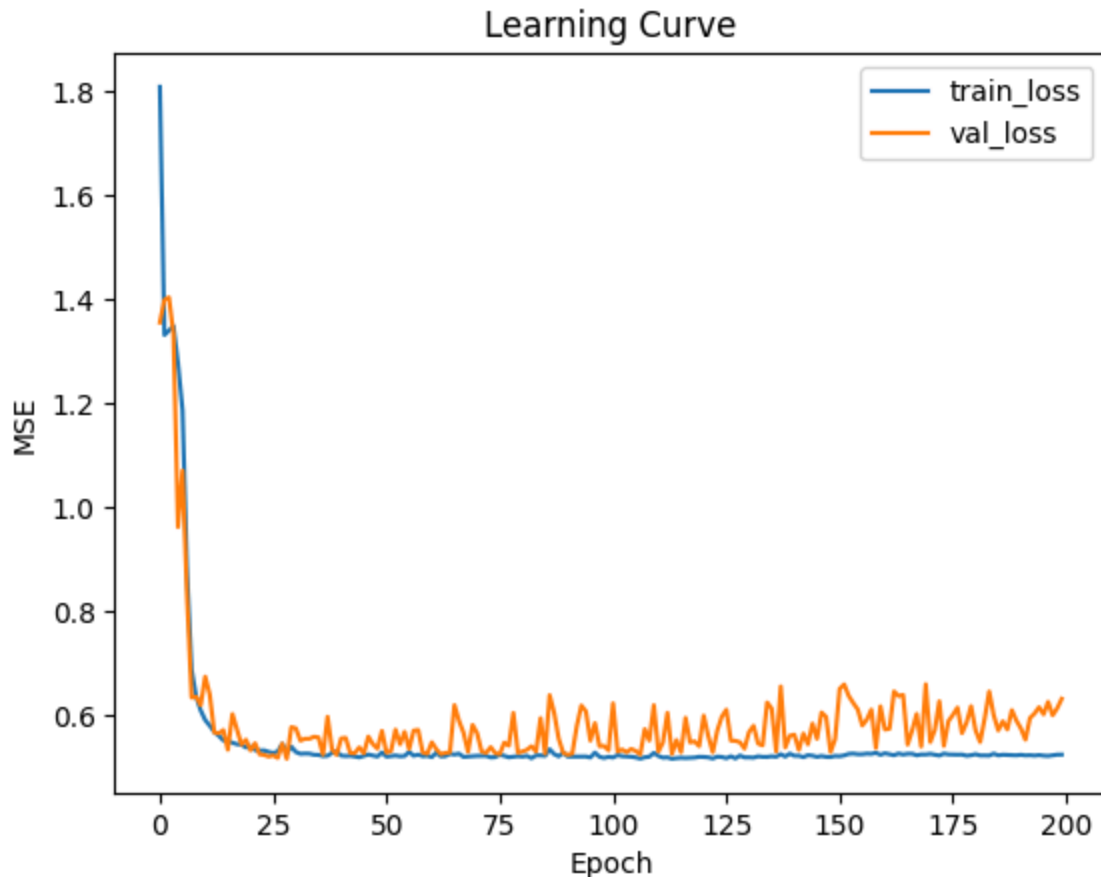
413/413  1s 1ms/step - loss: 0.5177 - val\_loss: 0.5951  
Epoch 194/200

413/413  1s 1ms/step - loss: 0.5175 - val\_loss: 0.6036  
Epoch 195/200

413/413  1s 1ms/step - loss: 0.5185 - val\_loss: 0.6159  
Epoch 196/200

413/413  1s 1ms/step - loss: 0.5181 - val\_loss: 0.6022  
Epoch 197/200

413/413 ————— 1s 1ms/step - loss: 0.5176 - val\_loss: 0.6261  
 Epoch 198/200  
 413/413 ————— 1s 1ms/step - loss: 0.5182 - val\_loss: 0.6003  
 Epoch 199/200  
 413/413 ————— 1s 1ms/step - loss: 0.5186 - val\_loss: 0.6137  
 Epoch 200/200  
 413/413 ————— 1s 1ms/step - loss: 0.5222 - val\_loss: 0.6319



The training and validation losses both decreased and stabilized at a low level ( $\sim 0.5$ – $0.7$ ). While the validation loss fluctuates slightly due to regularization and noise, the gap between training and validation loss remains small throughout. This indicates that the model is not overfitting, and generalization is good.

## 2. Binary classification DNN [17 marks]

Consider the [Portuguese Bank Marketing Data Set](#) available at Kaggle. Download the `bank_cleaned.csv` file or from [Canvas](#). Here we want to predict the success or failure of a bank marketing campaign using phone calls to promote a term deposit product. The target variable is `response_binary`.

The following code preprocesses the data. The day and month have been converted into cyclical features (1st day of the month has equal distance to the 2nd and the 31st).



```
In [8]: df = pd.read_csv("bank_cleaned.csv")

month_dict = {"jan": 1, "feb": 2, "mar": 3, "apr": 4, "may": 5, "jun": 6,
              "jul": 7, "aug": 8, "sep": 9, "oct": 10, "nov": 11, "dec": 12}
day_rad = (df["day"] - 1) * (2 * np.pi / 31)
month_rad = (df["month"].replace(month_dict) - 1) * (2 * np.pi / 12)
df["day_sin"] = np.sin(day_rad)
df["day_cos"] = np.cos(day_rad)
df["month_sin"] = np.sin(month_rad)
df["month_cos"] = np.cos(month_rad)
df.drop(columns=["Unnamed: 0", "month", "day", "response"], axis=1, inplace=True)
df.head()
```

C:\Users\Atara\AppData\Local\Temp\ipykernel\_10288\648047190.py:6: FutureWarning: Downcasting behavior in `replace` is deprecated and will be removed in a future version. To retain the old behavior, explicitly call `result.infer\_objects(copy=False)`. To opt-in to the future behavior, set `pd.set\_option('future.no\_silent\_downcasting', True)`

```
month_rad = (df["month"].replace(month_dict) - 1) * (2 * np.pi / 12)
```

```
Out[8]:
```

	age	job	marital	education	default	balance	housing	loan	duration	camp
0	58	management	married	tertiary	no	2143	yes	no	4.35	
1	44	technician	single	secondary	no	29	yes	no	2.52	
2	33	entrepreneur	married	secondary	no	2	yes	yes	1.27	
3	35	management	married	tertiary	no	231	yes	no	2.32	
4	28	management	single	tertiary	no	447	yes	yes	3.62	

```
In [9]: from sklearn.preprocessing import StandardScaler, OrdinalEncoder, OneHotEncoder
        from sklearn.compose import ColumnTransformer

train_set_tmp, test_set = train_test_split(df, test_size=0.2, random_state=42)
train_set, valid_set = train_test_split(train_set_tmp, test_size=0.2, random_state=42)

X_train_raw = train_set.drop("response_binary", axis=1).copy()
y_train = train_set["response_binary"].copy()
X_valid_raw = valid_set.drop("response_binary", axis=1).copy()
y_valid = valid_set["response_binary"].copy()
X_test_raw = test_set.drop("response_binary", axis=1).copy()
y_test = test_set["response_binary"].copy()

num_attribs = list(X_train_raw._get_numeric_data().columns)
cat_attribs = list(set(X_train_raw.columns) - set(num_attribs))

cat_attribs_ord = ['default', 'housing', 'loan']
cat_attribs_hot = ['job', 'marital', 'education', 'outcome']

full_pipeline = ColumnTransformer([
    ("num", StandardScaler(), num_attribs),
    ("cat_hot", OneHotEncoder(), cat_attribs_hot),
    ("cat_ord", OrdinalEncoder(categories=[['no', 'yes'], ['no', 'yes'], ['no', 'yes']]), cat_attribs_ord)])
```

```
])
```

```
X_train = full_pipeline.fit_transform(X_train_raw)
X_valid = full_pipeline.transform(X_valid_raw)
X_test = full_pipeline.transform(X_test_raw)
```

## (a) [4 marks]

In the next part you will build and fit a DNN with 4 hidden layers of 100 neurons each. Use the following specifications:

- (i) He initialization and the Swish activation function.
- (ii) The output layer has 1 neuron with sigmoid activation.
- (iii) Compile with `loss="binary_crossentropy"` and `metrics=["AUC"]`.

Explain why the choices (i), (ii), and (iii) are justified.

Also, state the proportion of successes in the training data.

### [Add your solution here]

```
In [10]: from tensorflow.keras import models, layers, initializers, activations

model = models.Sequential()
model.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model.add(layers.Dense(100, activation=activations.swish,
                           kernel_initializer=initializers.HeNormal()))


model.add(layers.Dense(1, activation='sigmoid'))


model.compile(loss="binary_crossentropy",
              optimizer="nadam",
              metrics=["AUC"])
model.fit(X_train, y_train, epochs=30, validation_data=(X_valid, y_valid))


print("Proportion of successes in training data:", y_train.mean())
```


Epoch 1/30


```
c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\core\input_layer.py:27: UserWarning: Argument `input_shape` is deprecated. Use `shape` instead.
  warnings.warn(
```


**817/817**  **4s** 3ms/step - AUC: 0.8605 - loss: 0.2552 - val\_AUC: 0.9063 - val\_loss: 0.2208  
 Epoch 2/30


**817/817**  **2s** 2ms/step - AUC: 0.9111 - loss: 0.2146 - val\_AUC: 0.9118 - val\_loss: 0.2141  
 Epoch 3/30


**817/817**  **2s** 3ms/step - AUC: 0.9187 - loss: 0.2072 - val\_AUC: 0.9135 - val\_loss: 0.2118  
 Epoch 4/30


**817/817**  **2s** 2ms/step - AUC: 0.9237 - loss: 0.2019 - val\_AUC: 0.9140 - val\_loss: 0.2110  
 Epoch 5/30


**817/817**  **2s** 2ms/step - AUC: 0.9277 - loss: 0.1971 - val\_AUC: 0.9137 - val\_loss: 0.2109  
 Epoch 6/30


**817/817**  **1s** 2ms/step - AUC: 0.9324 - loss: 0.1919 - val\_AUC: 0.9133 - val\_loss: 0.2115  
 Epoch 7/30


**817/817**  **1s** 2ms/step - AUC: 0.9362 - loss: 0.1863 - val\_AUC: 0.9119 - val\_loss: 0.2134  
 Epoch 8/30


**817/817**  **1s** 2ms/step - AUC: 0.9404 - loss: 0.1805 - val\_AUC: 0.9102 - val\_loss: 0.2173  
 Epoch 9/30


**817/817**  **1s** 2ms/step - AUC: 0.9444 - loss: 0.1748 - val\_AUC: 0.9079 - val\_loss: 0.2234  
 Epoch 10/30


**817/817**  **1s** 2ms/step - AUC: 0.9482 - loss: 0.1690 - val\_AUC: 0.9052 - val\_loss: 0.2313  
 Epoch 11/30


**817/817**  **2s** 2ms/step - AUC: 0.9523 - loss: 0.1625 - val\_AUC: 0.9011 - val\_loss: 0.2419  
 Epoch 12/30


**817/817**  **1s** 2ms/step - AUC: 0.9564 - loss: 0.1552 - val\_AUC: 0.8973 - val\_loss: 0.2565  
 Epoch 13/30


**817/817**  **1s** 2ms/step - AUC: 0.9610 - loss: 0.1470 - val\_AUC: 0.8881 - val\_loss: 0.2738  
 Epoch 14/30


**817/817**  **2s** 2ms/step - AUC: 0.9658 - loss: 0.1376 - val\_AUC: 0.8822 - val\_loss: 0.2949  
 Epoch 15/30

**817/817**  **2s** 2ms/step - AUC: 0.9708 - loss: 0.1282 - val\_AUC: 0.8794 - val\_loss: 0.3125  
 Epoch 16/30












**817/817**  **2s** 2ms/step - AUC: 0.9746 - loss: 0.1191 - val\_AUC: 0.8756 - val\_loss: 0.3391  
 Epoch 17/30

**817/817**  **1s** 2ms/step - AUC: 0.9768 - loss: 0.1146 - val\_AUC: 0.8721 - val\_loss: 0.3458  
 Epoch 18/30

**817/817**  **1s** 2ms/step - AUC: 0.9820 - loss: 0.1003 - val\_AUC: 0.8660 - val\_loss: 0.3766  
 Epoch 19/30

**817/817**  **1s** 2ms/step - AUC: 0.9840 - loss: 0.0947 - val\_AUC: 0.8608 - val\_loss: 0.3967

```

Epoch 20/30
817/817  2s 2ms/step - AUC: 0.9863 - loss: 0.0888 - val_AUC: 0.8
548 - val_loss: 0.4458
Epoch 21/30
817/817  1s 2ms/step - AUC: 0.9881 - loss: 0.0789 - val_AUC: 0.8
449 - val_loss: 0.4656
Epoch 22/30
817/817  2s 2ms/step - AUC: 0.9888 - loss: 0.0768 - val_AUC: 0.8
486 - val_loss: 0.4740
Epoch 23/30
817/817  1s 2ms/step - AUC: 0.9925 - loss: 0.0654 - val_AUC: 0.8
288 - val_loss: 0.5088
Epoch 24/30
817/817  2s 2ms/step - AUC: 0.9947 - loss: 0.0575 - val_AUC: 0.8
288 - val_loss: 0.5806
Epoch 25/30
817/817  1s 2ms/step - AUC: 0.9945 - loss: 0.0569 - val_AUC: 0.8
305 - val_loss: 0.5983
Epoch 26/30
817/817  1s 2ms/step - AUC: 0.9929 - loss: 0.0609 - val_AUC: 0.8
322 - val_loss: 0.5832
Epoch 27/30
817/817  1s 2ms/step - AUC: 0.9943 - loss: 0.0567 - val_AUC: 0.8
379 - val_loss: 0.5969
Epoch 28/30
817/817  1s 2ms/step - AUC: 0.9967 - loss: 0.0439 - val_AUC: 0.8
233 - val_loss: 0.6621
Epoch 29/30
817/817  2s 2ms/step - AUC: 0.9961 - loss: 0.0442 - val_AUC: 0.8
341 - val_loss: 0.6555
Epoch 30/30
817/817  1s 2ms/step - AUC: 0.9952 - loss: 0.0487 - val_AUC: 0.8
150 - val_loss: 0.7029
Proportion of successes in training data: 0.11168075907717029

```

The design choices for the deep neural network are well-justified given the nature of the binary classification task and the structure of the dataset. First, the use of He initialization in combination with the Swish activation function is highly appropriate. Swish, defined as  $x * \text{sigmoid}(x)$ , is a smooth and non-monotonic activation function that often performs better than ReLU in deep networks. It facilitates better gradient flow, leading to improved convergence and potentially better generalization. He initialization is specifically designed to work well with activation functions like ReLU and Swish. It draws weights from a scaled normal distribution to prevent vanishing or exploding gradients, which is especially important when training deep networks with multiple hidden layers, such as the 4-layer architecture used here.

The choice of the output layer — a single neuron with sigmoid activation — is standard and ideal for binary classification. The sigmoid function maps the model's output to a probability between 0 and 1, allowing the prediction to be interpreted as the likelihood of a positive outcome. Since the target variable `response_binary` is a binary indicator of whether a

customer accepted the marketing offer, a sigmoid-activated output neuron naturally fits this prediction task.

Furthermore, compiling the model with the binary cross-entropy loss function and evaluating it using the AUC (Area Under the Curve) metric is also justified. Binary cross-entropy is the appropriate loss function for binary classification tasks where the model outputs probabilities. It penalizes confident but incorrect predictions more heavily, encouraging the model to produce calibrated probabilities. The use of AUC as a performance metric is particularly valuable given that the dataset is imbalanced. As the training set shows, only approximately 11.17% of the customers responded positively to the campaign. AUC provides a threshold-independent measure of the model's ability to distinguish between positive and negative classes, making it more informative than accuracy in imbalanced settings.

## (b) [3 marks]

Train the model in (a) for 30 epochs and use exponential scheduling using the function below ( `lr0=0.01` , `s=20` ) and the NAG optimizer with `momentum=0.9` . Use a learning curve to comment on whether it is overfitting.

At the start of fitting your model, run `reset_session()` given by the following code.

```
In [11]: def reset_session(seed=42):
          tf.random.set_seed(seed)
          np.random.seed(seed)
          tf.keras.backend.clear_session()

          def exponential_decay(lr0, s):
              return lambda epoch: lr0 * 0.1**(epoch / s)
```

**[Add your solution here]**

```
In [12]: reset_session()


lr_schedule = tf.keras.callbacks.LearningRateScheduler(exponential_decay(lr0=0.01,


model = models.Sequential()
model.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model.add(layers.Dense(100, activation=activations.swish,
                           kernel_initializer=initializers.HeNormal()))
model.add(layers.Dense(1, activation='sigmoid'))


nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


model.compile(loss="binary_crossentropy",
              optimizer=nag_optimizer,
              metrics=["AUC"])
```


```
history = model.fit(X_train, y_train, epochs=30,  
                    validation_data=(X_valid, y_valid),  
                    callbacks=[lr_schedule])
```


Epoch 1/30  
**817/817**  **4s** 3ms/step - AUC: 0.8217 - loss: 0.2776 - val\_AUC: 0.8960 - val\_loss: 0.2276 - learning\_rate: 0.0100


Epoch 2/30  
**817/817**  **2s** 2ms/step - AUC: 0.9065 - loss: 0.2183 - val\_AUC: 0.9019 - val\_loss: 0.2220 - learning\_rate: 0.0089


Epoch 3/30  
**817/817**  **2s** 2ms/step - AUC: 0.9127 - loss: 0.2125 - val\_AUC: 0.9059 - val\_loss: 0.2186 - learning\_rate: 0.0079


Epoch 4/30  
**817/817**  **2s** 2ms/step - AUC: 0.9169 - loss: 0.2084 - val\_AUC: 0.9085 - val\_loss: 0.2160 - learning\_rate: 0.0071


Epoch 5/30  
**817/817**  **2s** 3ms/step - AUC: 0.9202 - loss: 0.2051 - val\_AUC: 0.9103 - val\_loss: 0.2141 - learning\_rate: 0.0063


Epoch 6/30  
**817/817**  **2s** 3ms/step - AUC: 0.9229 - loss: 0.2024 - val\_AUC: 0.9119 - val\_loss: 0.2125 - learning\_rate: 0.0056


Epoch 7/30  
**817/817**  **2s** 3ms/step - AUC: 0.9249 - loss: 0.2000 - val\_AUC: 0.9124 - val\_loss: 0.2114 - learning\_rate: 0.0050


Epoch 8/30  
**817/817**  **2s** 2ms/step - AUC: 0.9266 - loss: 0.1980 - val\_AUC: 0.9134 - val\_loss: 0.2105 - learning\_rate: 0.0045


Epoch 9/30  
**817/817**  **2s** 2ms/step - AUC: 0.9283 - loss: 0.1961 - val\_AUC: 0.9139 - val\_loss: 0.2098 - learning\_rate: 0.0040


Epoch 10/30  
**817/817**  **2s** 2ms/step - AUC: 0.9298 - loss: 0.1945 - val\_AUC: 0.9146 - val\_loss: 0.2093 - learning\_rate: 0.0035


Epoch 11/30  
**817/817**  **2s** 2ms/step - AUC: 0.9309 - loss: 0.1930 - val\_AUC: 0.9151 - val\_loss: 0.2089 - learning\_rate: 0.0032


Epoch 12/30  
**817/817**  **2s** 2ms/step - AUC: 0.9320 - loss: 0.1916 - val\_AUC: 0.9150 - val\_loss: 0.2086 - learning\_rate: 0.0028


Epoch 13/30  
**817/817**  **2s** 3ms/step - AUC: 0.9331 - loss: 0.1904 - val\_AUC: 0.9153 - val\_loss: 0.2084 - learning\_rate: 0.0025


Epoch 14/30  
**817/817**  **2s** 3ms/step - AUC: 0.9342 - loss: 0.1892 - val\_AUC: 0.9156 - val\_loss: 0.2083 - learning\_rate: 0.0022

Epoch 15/30  
**817/817**  **2s** 3ms/step - AUC: 0.9350 - loss: 0.1881 - val\_AUC: 0.9158 - val\_loss: 0.2083 - learning\_rate: 0.0020












Epoch 16/30  
**817/817**  **2s** 2ms/step - AUC: 0.9357 - loss: 0.1871 - val\_AUC: 0.9157 - val\_loss: 0.2082 - learning\_rate: 0.0018

Epoch 17/30  
**817/817**  **3s** 3ms/step - AUC: 0.9365 - loss: 0.1862 - val\_AUC: 0.9155 - val\_loss: 0.2082 - learning\_rate: 0.0016

Epoch 18/30  
**817/817**  **3s** 4ms/step - AUC: 0.9372 - loss: 0.1854 - val\_AUC: 0.9155 - val\_loss: 0.2083 - learning\_rate: 0.0014

Epoch 19/30  
**817/817**  **3s** 3ms/step - AUC: 0.9378 - loss: 0.1846 - val\_AUC: 0.9155

```

157 - val_loss: 0.2083 - learning_rate: 0.0013
Epoch 20/30
817/817  3s 4ms/step - AUC: 0.9382 - loss: 0.1839 - val_AUC: 0.9
158 - val_loss: 0.2084 - learning_rate: 0.0011
Epoch 21/30
817/817  4s 3ms/step - AUC: 0.9388 - loss: 0.1832 - val_AUC: 0.9
158 - val_loss: 0.2084 - learning_rate: 0.0010
Epoch 22/30
817/817  2s 3ms/step - AUC: 0.9392 - loss: 0.1826 - val_AUC: 0.9
161 - val_loss: 0.2085 - learning_rate: 8.9125e-04
Epoch 23/30
817/817  2s 3ms/step - AUC: 0.9397 - loss: 0.1820 - val_AUC: 0.9
153 - val_loss: 0.2086 - learning_rate: 7.9433e-04
Epoch 24/30
817/817  3s 4ms/step - AUC: 0.9400 - loss: 0.1815 - val_AUC: 0.9
155 - val_loss: 0.2087 - learning_rate: 7.0795e-04
Epoch 25/30
817/817  2s 3ms/step - AUC: 0.9403 - loss: 0.1810 - val_AUC: 0.9
157 - val_loss: 0.2088 - learning_rate: 6.3096e-04
Epoch 26/30
817/817  2s 2ms/step - AUC: 0.9407 - loss: 0.1806 - val_AUC: 0.9
156 - val_loss: 0.2089 - learning_rate: 5.6234e-04
Epoch 27/30
817/817  2s 2ms/step - AUC: 0.9409 - loss: 0.1802 - val_AUC: 0.9
157 - val_loss: 0.2090 - learning_rate: 5.0119e-04
Epoch 28/30
817/817  2s 2ms/step - AUC: 0.9414 - loss: 0.1798 - val_AUC: 0.9
157 - val_loss: 0.2091 - learning_rate: 4.4668e-04
Epoch 29/30
817/817  1s 2ms/step - AUC: 0.9416 - loss: 0.1794 - val_AUC: 0.9
156 - val_loss: 0.2092 - learning_rate: 3.9811e-04
Epoch 30/30
817/817  1s 2ms/step - AUC: 0.9419 - loss: 0.1791 - val_AUC: 0.9
157 - val_loss: 0.2093 - learning_rate: 3.5481e-04

```

```

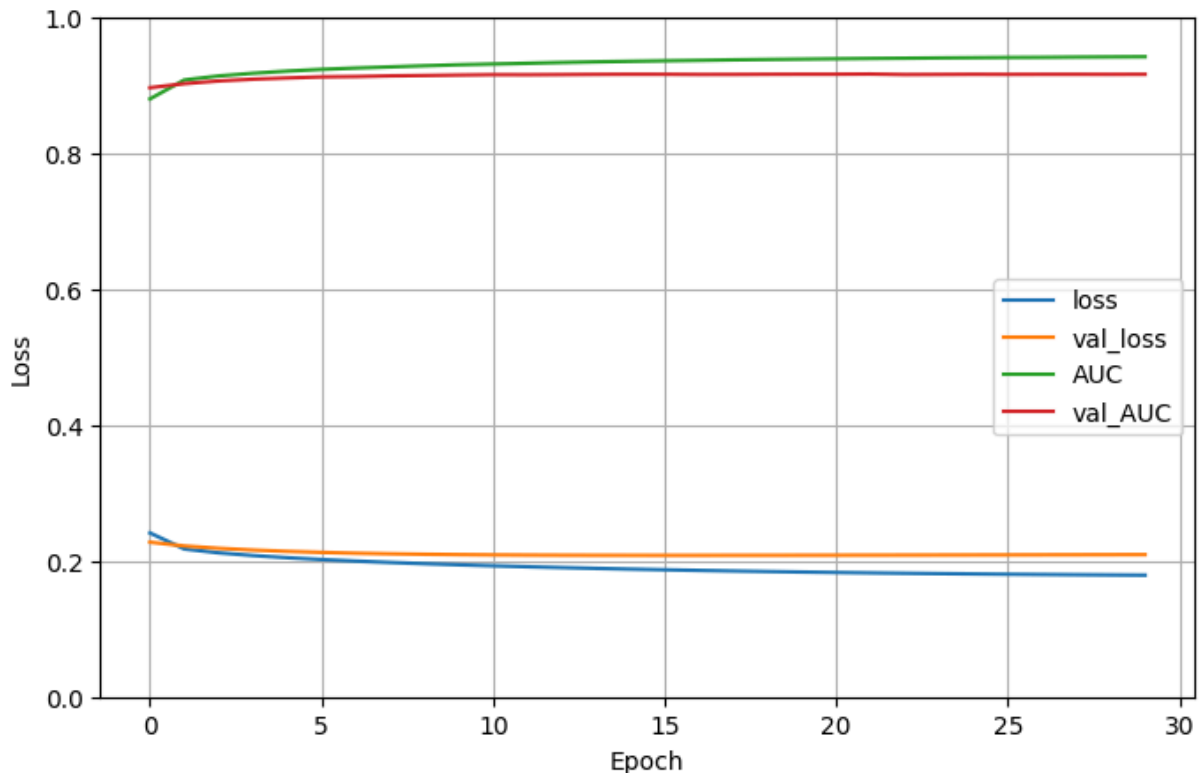
In [13]: run_history = history.history

df = pd.DataFrame(run_history)[["loss", "val_loss", "AUC", "val_AUC"]]

df.plot(figsize=(8, 5))
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.grid(True)
plt.gca().set_ylim(0, 1)
plt.show()

```





```
In [14]: loss, auc = model.evaluate(X_valid, y_valid, verbose=0)
print("Validation AUC:", auc)
```

Validation AUC: 0.9157296419143677

The learning curve indicates that the model begins to overfit the training data as training progresses. While the training loss steadily decreases throughout the 30 epochs, the validation loss plateaus after about 10 epochs and shows a slight upward trend toward the end. This divergence between training and validation performance suggests the model is starting to memorize the training data rather than generalizing well to unseen data.

### (c) [8 marks]

Fit separate models using the same specification as in (b) but with the following regularization techniques:

- (i) batch normalization,
- (ii) early stopping based on validation AUC with `patience=10` (look at the documentation and note the `mode` argument).
- (iii)  $\ell_2$  regularization with `l2=0.0002`,
- (iv) dropout with probability 0.02,
- (v)  $\ell_2$  regularization and early stopping both as above,

(vi) batch normalization and dropout both as above.

At the start of each one of the above models, run `reset_session()` .

The performance measure is validation AUC. State this for the model in (b), and for each of the models here comment on whether it is better than the model in (b).

### [Add your solution here]

```
In [15]: reset_session()
model_1 = models.Sequential()
model_1.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_1.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal()))
    model_1.add(tf.keras.layers.BatchNormalization())
model_1.add(layers.Dense(1, activation='sigmoid'))

nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


model_1.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',
    metrics=['AUC']
)


history_1 = model_1.fit(
    X_train, y_train,
    epochs=30,
    validation_data=(X_valid, y_valid),
    callbacks=[lr_schedule]
)


loss, auc = model_1.evaluate(X_valid, y_valid, verbose=0)
print("Validation AUC for (i):", auc)
```


Epoch 1/30


c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\core\input\_layer.py:27: UserWarning: Argument `input\_shape` is deprecated. Use `shape` instead.  
warnings.warn(


**817/817**  **4s** 3ms/step - AUC: 0.8139 - loss: 0.3172 - val\_AUC: 0.8984 - val\_loss: 0.2335 - learning\_rate: 0.0100  
 Epoch 2/30


**817/817**  **2s** 3ms/step - AUC: 0.9139 - loss: 0.2123 - val\_AUC: 0.9053 - val\_loss: 0.2294 - learning\_rate: 0.0089  
 Epoch 3/30


**817/817**  **2s** 3ms/step - AUC: 0.9280 - loss: 0.1960 - val\_AUC: 0.9055 - val\_loss: 0.2337 - learning\_rate: 0.0079  
 Epoch 4/30


**817/817**  **2s** 2ms/step - AUC: 0.9385 - loss: 0.1827 - val\_AUC: 0.9028 - val\_loss: 0.2415 - learning\_rate: 0.0071  
 Epoch 5/30


**817/817**  **2s** 2ms/step - AUC: 0.9475 - loss: 0.1700 - val\_AUC: 0.8982 - val\_loss: 0.2522 - learning\_rate: 0.0063  
 Epoch 6/30


**817/817**  **2s** 2ms/step - AUC: 0.9559 - loss: 0.1569 - val\_AUC: 0.8923 - val\_loss: 0.2652 - learning\_rate: 0.0056  
 Epoch 7/30

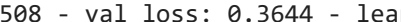
**817/817**  **2s** 2ms/step - AUC: 0.9638 - loss: 0.1431 - val\_AUC: 0.8863 - val\_loss: 0.2791 - learning\_rate: 0.0050  
 Epoch 8/30

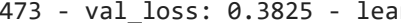
**817/817**  **2s** 2ms/step - AUC: 0.9709 - loss: 0.1287 - val\_AUC: 0.8793 - val\_loss: 0.2942 - learning\_rate: 0.0045  
 Epoch 9/30

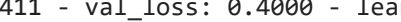
**817/817**  **2s** 2ms/step - AUC: 0.9776 - loss: 0.1141 - val\_AUC: 0.8693 - val\_loss: 0.3100 - learning\_rate: 0.0040  
 Epoch 10/30

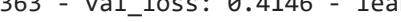
**817/817**  **2s** 2ms/step - AUC: 0.9832 - loss: 0.0996 - val\_AUC: 0.8631 - val\_loss: 0.3274 - learning\_rate: 0.0035  
 Epoch 11/30


**817/817**  **2s** 2ms/step - AUC: 0.9884 - loss: 0.0854 - val\_AUC: 0.8571 - val\_loss: 0.3460 - learning\_rate: 0.0032  
 Epoch 12/30


**817/817**  **2s** 2ms/step - AUC: 0.9924 - loss: 0.0723 - val\_AUC: 0.8508 - val\_loss: 0.3644 - learning\_rate: 0.0028  
 Epoch 13/30


**817/817**  **2s** 2ms/step - AUC: 0.9952 - loss: 0.0608 - val\_AUC: 0.8473 - val\_loss: 0.3825 - learning\_rate: 0.0025  
 Epoch 14/30


**817/817**  **2s** 2ms/step - AUC: 0.9970 - loss: 0.0511 - val\_AUC: 0.8411 - val\_loss: 0.4000 - learning\_rate: 0.0022  
 Epoch 15/30












**817/817**  **2s** 2ms/step - AUC: 0.9982 - loss: 0.0432 - val\_AUC: 0.8363 - val\_loss: 0.4146 - learning\_rate: 0.0020  
 Epoch 16/30

**817/817**  **2s** 2ms/step - AUC: 0.9990 - loss: 0.0365 - val\_AUC: 0.8345 - val\_loss: 0.4273 - learning\_rate: 0.0018  
 Epoch 17/30

**817/817**  **2s** 2ms/step - AUC: 0.9994 - loss: 0.0311 - val\_AUC: 0.8306 - val\_loss: 0.4393 - learning\_rate: 0.0016  
 Epoch 18/30

**817/817**  **2s** 2ms/step - AUC: 0.9997 - loss: 0.0268 - val\_AUC: 0.8272 - val\_loss: 0.4505 - learning\_rate: 0.0014  
 Epoch 19/30

**817/817**  **2s** 2ms/step - AUC: 0.9998 - loss: 0.0234 - val\_AUC: 0.8234 - val\_loss: 0.4613 - learning\_rate: 0.0013


Epoch 20/30  
**817/817**  2s 2ms/step - AUC: 0.9999 - loss: 0.0207 - val\_AUC: 0.8221 - val\_loss: 0.4713 - learning\_rate: 0.0011  
 Epoch 21/30  
**817/817**  2s 2ms/step - AUC: 0.9999 - loss: 0.0186 - val\_AUC: 0.8202 - val\_loss: 0.4806 - learning\_rate: 0.0010  
 Epoch 22/30  
**817/817**  2s 2ms/step - AUC: 1.0000 - loss: 0.0169 - val\_AUC: 0.8157 - val\_loss: 0.4889 - learning\_rate: 8.9125e-04  
 Epoch 23/30  
**817/817**  2s 2ms/step - AUC: 1.0000 - loss: 0.0155 - val\_AUC: 0.8128 - val\_loss: 0.4964 - learning\_rate: 7.9433e-04  
 Epoch 24/30  
**817/817**  2s 3ms/step - AUC: 1.0000 - loss: 0.0144 - val\_AUC: 0.8109 - val\_loss: 0.5031 - learning\_rate: 7.0795e-04  
 Epoch 25/30  
**817/817**  2s 2ms/step - AUC: 1.0000 - loss: 0.0134 - val\_AUC: 0.8112 - val\_loss: 0.5090 - learning\_rate: 6.3096e-04  
 Epoch 26/30  
**817/817**  3s 3ms/step - AUC: 1.0000 - loss: 0.0126 - val\_AUC: 0.8067 - val\_loss: 0.5140 - learning\_rate: 5.6234e-04  
 Epoch 27/30  
**817/817**  2s 3ms/step - AUC: 1.0000 - loss: 0.0120 - val\_AUC: 0.8073 - val\_loss: 0.5183 - learning\_rate: 5.0119e-04  
 Epoch 28/30  
**817/817**  2s 3ms/step - AUC: 1.0000 - loss: 0.0114 - val\_AUC: 0.8055 - val\_loss: 0.5220 - learning\_rate: 4.4668e-04  
 Epoch 29/30  
**817/817**  3s 3ms/step - AUC: 1.0000 - loss: 0.0110 - val\_AUC: 0.8044 - val\_loss: 0.5252 - learning\_rate: 3.9811e-04  
 Epoch 30/30  
**817/817**  3s 4ms/step - AUC: 1.0000 - loss: 0.0105 - val\_AUC: 0.8048 - val\_loss: 0.5279 - learning\_rate: 3.5481e-04  
 Validation AUC for (i): 0.8047621846199036


```
In [16]: reset_session()
model_2 = models.Sequential()
model_2.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_2.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal()))
model_2.add(layers.Dense(1, activation='sigmoid'))


nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


early_stop = tf.keras.callbacks.EarlyStopping(
    patience=10,
    restore_best_weights=True,
    monitor="val_AUC",
    mode="max"
)
model_2.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',
    metrics=['AUC']
)
```


```
history_2 = model_2.fit(  
    X_train, y_train,  
    epochs=30,  
    validation_data=(X_valid, y_valid),  
    callbacks=[early_stop, lr_schedule]  
)  
  
loss, auc = model_2.evaluate(X_valid, y_valid, verbose=0)  
print("Validation AUC for (ii):", auc)
```


Epoch 1/30  
817/817  3s 3ms/step - AUC: 0.8291 - loss: 0.2773 - val\_AUC: 0.8974 - val\_loss: 0.2285 - learning\_rate: 0.0100


Epoch 2/30  
817/817  2s 3ms/step - AUC: 0.9072 - loss: 0.2185 - val\_AUC: 0.9037 - val\_loss: 0.2225 - learning\_rate: 0.0089


Epoch 3/30  
817/817  2s 2ms/step - AUC: 0.9130 - loss: 0.2127 - val\_AUC: 0.9070 - val\_loss: 0.2186 - learning\_rate: 0.0079


Epoch 4/30  
817/817  2s 3ms/step - AUC: 0.9168 - loss: 0.2087 - val\_AUC: 0.9098 - val\_loss: 0.2156 - learning\_rate: 0.0071


Epoch 5/30  
817/817  2s 3ms/step - AUC: 0.9201 - loss: 0.2055 - val\_AUC: 0.9115 - val\_loss: 0.2134 - learning\_rate: 0.0063


Epoch 6/30  
817/817  2s 2ms/step - AUC: 0.9226 - loss: 0.2029 - val\_AUC: 0.9131 - val\_loss: 0.2117 - learning\_rate: 0.0056


Epoch 7/30  
817/817  2s 2ms/step - AUC: 0.9245 - loss: 0.2007 - val\_AUC: 0.9140 - val\_loss: 0.2104 - learning\_rate: 0.0050


Epoch 8/30  
817/817  2s 2ms/step - AUC: 0.9260 - loss: 0.1987 - val\_AUC: 0.9147 - val\_loss: 0.2095 - learning\_rate: 0.0045


Epoch 9/30  
817/817  2s 3ms/step - AUC: 0.9276 - loss: 0.1970 - val\_AUC: 0.9153 - val\_loss: 0.2088 - learning\_rate: 0.0040


Epoch 10/30  
817/817  2s 2ms/step - AUC: 0.9288 - loss: 0.1954 - val\_AUC: 0.9156 - val\_loss: 0.2083 - learning\_rate: 0.0035


Epoch 11/30  
817/817  2s 2ms/step - AUC: 0.9301 - loss: 0.1940 - val\_AUC: 0.9159 - val\_loss: 0.2079 - learning\_rate: 0.0032


Epoch 12/30  
817/817  2s 3ms/step - AUC: 0.9311 - loss: 0.1928 - val\_AUC: 0.9164 - val\_loss: 0.2078 - learning\_rate: 0.0028


Epoch 13/30  
817/817  2s 3ms/step - AUC: 0.9320 - loss: 0.1916 - val\_AUC: 0.9167 - val\_loss: 0.2077 - learning\_rate: 0.0025


Epoch 14/30  
817/817  2s 2ms/step - AUC: 0.9329 - loss: 0.1906 - val\_AUC: 0.9169 - val\_loss: 0.2076 - learning\_rate: 0.0022

Epoch 15/30  
817/817  2s 3ms/step - AUC: 0.9337 - loss: 0.1896 - val\_AUC: 0.9168 - val\_loss: 0.2077 - learning\_rate: 0.0020

Epoch 16/30  
817/817  2s 3ms/step - AUC: 0.9343 - loss: 0.1887 - val\_AUC: 0.9168 - val\_loss: 0.2077 - learning\_rate: 0.0018

Epoch 17/30  
817/817  2s 3ms/step - AUC: 0.9349 - loss: 0.1878 - val\_AUC: 0.9169 - val\_loss: 0.2078 - learning\_rate: 0.0016

Epoch 18/30  
817/817  2s 3ms/step - AUC: 0.9356 - loss: 0.1871 - val\_AUC: 0.9170 - val\_loss: 0.2079 - learning\_rate: 0.0014

Epoch 19/30  
817/817  2s 3ms/step - AUC: 0.9361 - loss: 0.1864 - val\_AUC: 0.9

```

172 - val_loss: 0.2080 - learning_rate: 0.0013
Epoch 20/30
817/817 ————— 3s 3ms/step - AUC: 0.9367 - loss: 0.1857 - val_AUC: 0.9
173 - val_loss: 0.2082 - learning_rate: 0.0011
Epoch 21/30
817/817 ————— 2s 3ms/step - AUC: 0.9372 - loss: 0.1851 - val_AUC: 0.9
173 - val_loss: 0.2083 - learning_rate: 0.0010
Epoch 22/30
817/817 ————— 2s 3ms/step - AUC: 0.9375 - loss: 0.1845 - val_AUC: 0.9
175 - val_loss: 0.2084 - learning_rate: 8.9125e-04
Epoch 23/30
817/817 ————— 2s 3ms/step - AUC: 0.9378 - loss: 0.1840 - val_AUC: 0.9
174 - val_loss: 0.2086 - learning_rate: 7.9433e-04
Epoch 24/30
817/817 ————— 2s 2ms/step - AUC: 0.9382 - loss: 0.1836 - val_AUC: 0.9
166 - val_loss: 0.2087 - learning_rate: 7.0795e-04
Epoch 25/30
817/817 ————— 2s 3ms/step - AUC: 0.9385 - loss: 0.1831 - val_AUC: 0.9
165 - val_loss: 0.2089 - learning_rate: 6.3096e-04
Epoch 26/30
817/817 ————— 3s 3ms/step - AUC: 0.9388 - loss: 0.1827 - val_AUC: 0.9
162 - val_loss: 0.2090 - learning_rate: 5.6234e-04
Epoch 27/30
817/817 ————— 2s 3ms/step - AUC: 0.9391 - loss: 0.1824 - val_AUC: 0.9
159 - val_loss: 0.2092 - learning_rate: 5.0119e-04
Epoch 28/30
817/817 ————— 2s 2ms/step - AUC: 0.9393 - loss: 0.1820 - val_AUC: 0.9
158 - val_loss: 0.2093 - learning_rate: 4.4668e-04
Epoch 29/30
817/817 ————— 2s 2ms/step - AUC: 0.9395 - loss: 0.1817 - val_AUC: 0.9
158 - val_loss: 0.2094 - learning_rate: 3.9811e-04
Epoch 30/30
817/817 ————— 2s 3ms/step - AUC: 0.9397 - loss: 0.1815 - val_AUC: 0.9
159 - val_loss: 0.2096 - learning_rate: 3.5481e-04
Validation AUC for (ii): 0.9175032377243042

```

```

In [17]: from tensorflow.keras import regularizers
reset_session()
model_3 = models.Sequential()
model_3.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_3.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal(),
                             kernel_regularizer=regularizers.l2(0.0002)))
model_3.add(layers.Dense(1, activation='sigmoid'))

nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


model_3.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',
    metrics=['AUC']
)


history_3 = model_3.fit(
    X_train, y_train,


```


```
epochs=30,  
validation_data=(X_valid, y_valid),  
callbacks=[lr_schedule]  
)  
  
loss, auc = model_3.evaluate(X_valid, y_valid, verbose=0)  
print("Validation AUC for (iii):", auc)
```





Epoch 1/30  
817/817  4s 3ms/step - AUC: 0.8335 - loss: 0.4309 - val\_AUC: 0.8984 - val\_loss: 0.3764 - learning\_rate: 0.0100


Epoch 2/30  
817/817  2s 3ms/step - AUC: 0.9061 - loss: 0.3676 - val\_AUC: 0.9045 - val\_loss: 0.3631 - learning\_rate: 0.0089


Epoch 3/30  
817/817  2s 3ms/step - AUC: 0.9118 - loss: 0.3548 - val\_AUC: 0.9078 - val\_loss: 0.3533 - learning\_rate: 0.0079


Epoch 4/30  
817/817  2s 2ms/step - AUC: 0.9154 - loss: 0.3452 - val\_AUC: 0.9108 - val\_loss: 0.3454 - learning\_rate: 0.0071


Epoch 5/30  
817/817  2s 3ms/step - AUC: 0.9180 - loss: 0.3375 - val\_AUC: 0.9121 - val\_loss: 0.3390 - learning\_rate: 0.0063


Epoch 6/30  
817/817  2s 3ms/step - AUC: 0.9200 - loss: 0.3311 - val\_AUC: 0.9135 - val\_loss: 0.3336 - learning\_rate: 0.0056


Epoch 7/30  
817/817  2s 3ms/step - AUC: 0.9215 - loss: 0.3257 - val\_AUC: 0.9145 - val\_loss: 0.3290 - learning\_rate: 0.0050


Epoch 8/30  
817/817  2s 2ms/step - AUC: 0.9229 - loss: 0.3210 - val\_AUC: 0.9155 - val\_loss: 0.3251 - learning\_rate: 0.0045


Epoch 9/30  
817/817  2s 2ms/step - AUC: 0.9239 - loss: 0.3170 - val\_AUC: 0.9162 - val\_loss: 0.3217 - learning\_rate: 0.0040


Epoch 10/30  
817/817  2s 2ms/step - AUC: 0.9247 - loss: 0.3135 - val\_AUC: 0.9167 - val\_loss: 0.3189 - learning\_rate: 0.0035


Epoch 11/30  
817/817  2s 2ms/step - AUC: 0.9257 - loss: 0.3105 - val\_AUC: 0.9168 - val\_loss: 0.3165 - learning\_rate: 0.0032


Epoch 12/30  
817/817  2s 2ms/step - AUC: 0.9264 - loss: 0.3078 - val\_AUC: 0.9173 - val\_loss: 0.3144 - learning\_rate: 0.0028


Epoch 13/30  
817/817  2s 2ms/step - AUC: 0.9271 - loss: 0.3055 - val\_AUC: 0.9176 - val\_loss: 0.3126 - learning\_rate: 0.0025


Epoch 14/30  
817/817  2s 3ms/step - AUC: 0.9275 - loss: 0.3035 - val\_AUC: 0.9182 - val\_loss: 0.3110 - learning\_rate: 0.0022

Epoch 15/30  
817/817  2s 3ms/step - AUC: 0.9281 - loss: 0.3016 - val\_AUC: 0.9185 - val\_loss: 0.3097 - learning\_rate: 0.0020

Epoch 16/30  
817/817  2s 2ms/step - AUC: 0.9285 - loss: 0.3000 - val\_AUC: 0.9184 - val\_loss: 0.3085 - learning\_rate: 0.0018

Epoch 17/30  
817/817  2s 2ms/step - AUC: 0.9289 - loss: 0.2986 - val\_AUC: 0.9185 - val\_loss: 0.3075 - learning\_rate: 0.0016

Epoch 18/30  
817/817  2s 3ms/step - AUC: 0.9293 - loss: 0.2973 - val\_AUC: 0.9183 - val\_loss: 0.3067 - learning\_rate: 0.0014

Epoch 19/30  
817/817  2s 2ms/step - AUC: 0.9296 - loss: 0.2962 - val\_AUC: 0.9185

```

185 - val_loss: 0.3059 - learning_rate: 0.0013
Epoch 20/30
817/817 ————— 2s 2ms/step - AUC: 0.9299 - loss: 0.2952 - val_AUC: 0.9
185 - val_loss: 0.3053 - learning_rate: 0.0011
Epoch 21/30
817/817 ————— 2s 2ms/step - AUC: 0.9301 - loss: 0.2943 - val_AUC: 0.9
187 - val_loss: 0.3047 - learning_rate: 0.0010
Epoch 22/30
817/817 ————— 2s 2ms/step - AUC: 0.9302 - loss: 0.2935 - val_AUC: 0.9
187 - val_loss: 0.3042 - learning_rate: 8.9125e-04
Epoch 23/30
817/817 ————— 2s 2ms/step - AUC: 0.9306 - loss: 0.2928 - val_AUC: 0.9
186 - val_loss: 0.3038 - learning_rate: 7.9433e-04
Epoch 24/30
817/817 ————— 2s 2ms/step - AUC: 0.9308 - loss: 0.2921 - val_AUC: 0.9
187 - val_loss: 0.3034 - learning_rate: 7.0795e-04
Epoch 25/30
817/817 ————— 2s 2ms/step - AUC: 0.9310 - loss: 0.2916 - val_AUC: 0.9
188 - val_loss: 0.3031 - learning_rate: 6.3096e-04
Epoch 26/30
817/817 ————— 2s 2ms/step - AUC: 0.9311 - loss: 0.2910 - val_AUC: 0.9
187 - val_loss: 0.3029 - learning_rate: 5.6234e-04
Epoch 27/30
817/817 ————— 2s 3ms/step - AUC: 0.9313 - loss: 0.2906 - val_AUC: 0.9
187 - val_loss: 0.3026 - learning_rate: 5.0119e-04
Epoch 28/30
817/817 ————— 2s 2ms/step - AUC: 0.9315 - loss: 0.2902 - val_AUC: 0.9
188 - val_loss: 0.3024 - learning_rate: 4.4668e-04
Epoch 29/30
817/817 ————— 2s 3ms/step - AUC: 0.9316 - loss: 0.2898 - val_AUC: 0.9
185 - val_loss: 0.3023 - learning_rate: 3.9811e-04
Epoch 30/30
817/817 ————— 3s 4ms/step - AUC: 0.9317 - loss: 0.2894 - val_AUC: 0.9
185 - val_loss: 0.3021 - learning_rate: 3.5481e-04
Validation AUC for (iii): 0.9184845685958862

```

```

In [18]: reset_session()
model_4 = models.Sequential()
model_4.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_4.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal()))
    model_4.add(layers.Dropout(0.02))
model_4.add(layers.Dense(1, activation='sigmoid'))


nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


model_4.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',
    metrics=['AUC']
)


history_4 = model_4.fit(
    X_train, y_train,
    epochs=30,


```


```
validation_data=(X_valid, y_valid),  
callbacks=[lr_schedule]  
)  
  
loss, auc = model_4.evaluate(X_valid, y_valid, verbose=0)  
print("Validation AUC for (iv):", auc)
```


Epoch 1/30  
817/817  6s 5ms/step - AUC: 0.8056 - loss: 0.2898 - val\_AUC: 0.8929 - val\_loss: 0.2299 - learning\_rate: 0.0100


Epoch 2/30  
817/817  3s 4ms/step - AUC: 0.9031 - loss: 0.2222 - val\_AUC: 0.9010 - val\_loss: 0.2229 - learning\_rate: 0.0089


Epoch 3/30  
817/817  3s 3ms/step - AUC: 0.9102 - loss: 0.2152 - val\_AUC: 0.9054 - val\_loss: 0.2184 - learning\_rate: 0.0079


Epoch 4/30  
817/817  3s 3ms/step - AUC: 0.9135 - loss: 0.2120 - val\_AUC: 0.9074 - val\_loss: 0.2158 - learning\_rate: 0.0071


Epoch 5/30  
817/817  2s 3ms/step - AUC: 0.9162 - loss: 0.2094 - val\_AUC: 0.9092 - val\_loss: 0.2138 - learning\_rate: 0.0063


Epoch 6/30  
817/817  2s 3ms/step - AUC: 0.9196 - loss: 0.2058 - val\_AUC: 0.9111 - val\_loss: 0.2121 - learning\_rate: 0.0056


Epoch 7/30  
817/817  2s 3ms/step - AUC: 0.9219 - loss: 0.2036 - val\_AUC: 0.9125 - val\_loss: 0.2113 - learning\_rate: 0.0050


Epoch 8/30  
817/817  2s 3ms/step - AUC: 0.9224 - loss: 0.2028 - val\_AUC: 0.9129 - val\_loss: 0.2102 - learning\_rate: 0.0045


Epoch 9/30  
817/817  3s 4ms/step - AUC: 0.9241 - loss: 0.2013 - val\_AUC: 0.9127 - val\_loss: 0.2101 - learning\_rate: 0.0040


Epoch 10/30  
817/817  4s 5ms/step - AUC: 0.9251 - loss: 0.1997 - val\_AUC: 0.9138 - val\_loss: 0.2092 - learning\_rate: 0.0035


Epoch 11/30  
817/817  4s 3ms/step - AUC: 0.9269 - loss: 0.1981 - val\_AUC: 0.9138 - val\_loss: 0.2092 - learning\_rate: 0.0032


Epoch 12/30  
817/817  2s 3ms/step - AUC: 0.9278 - loss: 0.1968 - val\_AUC: 0.9141 - val\_loss: 0.2089 - learning\_rate: 0.0028


Epoch 13/30  
817/817  2s 3ms/step - AUC: 0.9276 - loss: 0.1974 - val\_AUC: 0.9148 - val\_loss: 0.2083 - learning\_rate: 0.0025


Epoch 14/30  
817/817  2s 3ms/step - AUC: 0.9282 - loss: 0.1969 - val\_AUC: 0.9151 - val\_loss: 0.2081 - learning\_rate: 0.0022

Epoch 15/30  
817/817  2s 3ms/step - AUC: 0.9310 - loss: 0.1935 - val\_AUC: 0.9154 - val\_loss: 0.2078 - learning\_rate: 0.0020

Epoch 16/30  
817/817  2s 3ms/step - AUC: 0.9299 - loss: 0.1943 - val\_AUC: 0.9154 - val\_loss: 0.2079 - learning\_rate: 0.0018

Epoch 17/30  
817/817  2s 2ms/step - AUC: 0.9308 - loss: 0.1935 - val\_AUC: 0.9155 - val\_loss: 0.2077 - learning\_rate: 0.0016

Epoch 18/30  
817/817  2s 3ms/step - AUC: 0.9326 - loss: 0.1914 - val\_AUC: 0.9158 - val\_loss: 0.2076 - learning\_rate: 0.0014

Epoch 19/30  
817/817  2s 2ms/step - AUC: 0.9318 - loss: 0.1925 - val\_AUC: 0.9158

```

158 - val_loss: 0.2078 - learning_rate: 0.0013
Epoch 20/30
817/817 ————— 2s 3ms/step - AUC: 0.9318 - loss: 0.1926 - val_AUC: 0.9
158 - val_loss: 0.2079 - learning_rate: 0.0011
Epoch 21/30
817/817 ————— 3s 3ms/step - AUC: 0.9327 - loss: 0.1913 - val_AUC: 0.9
160 - val_loss: 0.2078 - learning_rate: 0.0010
Epoch 22/30
817/817 ————— 3s 3ms/step - AUC: 0.9320 - loss: 0.1922 - val_AUC: 0.9
159 - val_loss: 0.2080 - learning_rate: 8.9125e-04
Epoch 23/30
817/817 ————— 2s 3ms/step - AUC: 0.9330 - loss: 0.1908 - val_AUC: 0.9
156 - val_loss: 0.2080 - learning_rate: 7.9433e-04
Epoch 24/30
817/817 ————— 2s 3ms/step - AUC: 0.9331 - loss: 0.1910 - val_AUC: 0.9
156 - val_loss: 0.2081 - learning_rate: 7.0795e-04
Epoch 25/30
817/817 ————— 2s 2ms/step - AUC: 0.9330 - loss: 0.1907 - val_AUC: 0.9
157 - val_loss: 0.2080 - learning_rate: 6.3096e-04
Epoch 26/30
817/817 ————— 2s 2ms/step - AUC: 0.9341 - loss: 0.1896 - val_AUC: 0.9
157 - val_loss: 0.2079 - learning_rate: 5.6234e-04
Epoch 27/30
817/817 ————— 2s 2ms/step - AUC: 0.9342 - loss: 0.1892 - val_AUC: 0.9
159 - val_loss: 0.2079 - learning_rate: 5.0119e-04
Epoch 28/30
817/817 ————— 2s 3ms/step - AUC: 0.9349 - loss: 0.1887 - val_AUC: 0.9
159 - val_loss: 0.2080 - learning_rate: 4.4668e-04
Epoch 29/30
817/817 ————— 2s 3ms/step - AUC: 0.9346 - loss: 0.1891 - val_AUC: 0.9
159 - val_loss: 0.2081 - learning_rate: 3.9811e-04
Epoch 30/30
817/817 ————— 3s 3ms/step - AUC: 0.9359 - loss: 0.1878 - val_AUC: 0.9
155 - val_loss: 0.2080 - learning_rate: 3.5481e-04
Validation AUC for (iv): 0.9155161380767822

```

```

In [19]: reset_session()
model_5 = models.Sequential()
model_5.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_5.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal(),
                             kernel_regularizer=regularizers.l2(0.0002)))
model_5.add(layers.Dense(1, activation='sigmoid'))

nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


early_stop = tf.keras.callbacks.EarlyStopping(
    patience=10,
    restore_best_weights=True,
    monitor="val_AUC",
    mode="max"
)
model_5.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',


```


```
        metrics=['AUC']
    )


    history_5 = model_5.fit(
        X_train, y_train,
        epochs=30,
        validation_data=(X_valid, y_valid),
        callbacks=[early_stop, lr_schedule]
    )


    loss, auc = model_5.evaluate(X_valid, y_valid, verbose=0)
    print("Validation AUC for (v):", auc)
```


Epoch 1/30  
**817/817**  4s 4ms/step - AUC: 0.8283 - loss: 0.4335 - val\_AUC: 0.8961 - val\_loss: 0.3774 - learning\_rate: 0.0100


Epoch 2/30  
**817/817**  3s 4ms/step - AUC: 0.9056 - loss: 0.3669 - val\_AUC: 0.9017 - val\_loss: 0.3648 - learning\_rate: 0.0089


Epoch 3/30  
**817/817**  4s 5ms/step - AUC: 0.9111 - loss: 0.3540 - val\_AUC: 0.9051 - val\_loss: 0.3554 - learning\_rate: 0.0079


Epoch 4/30  
**817/817**  4s 5ms/step - AUC: 0.9146 - loss: 0.3445 - val\_AUC: 0.9074 - val\_loss: 0.3476 - learning\_rate: 0.0071


Epoch 5/30  
**817/817**  5s 6ms/step - AUC: 0.9173 - loss: 0.3367 - val\_AUC: 0.9090 - val\_loss: 0.3411 - learning\_rate: 0.0063


Epoch 6/30  
**817/817**  4s 5ms/step - AUC: 0.9194 - loss: 0.3302 - val\_AUC: 0.9105 - val\_loss: 0.3357 - learning\_rate: 0.0056


Epoch 7/30  
**817/817**  4s 5ms/step - AUC: 0.9212 - loss: 0.3247 - val\_AUC: 0.9116 - val\_loss: 0.3311 - learning\_rate: 0.0050


Epoch 8/30  
**817/817**  5s 6ms/step - AUC: 0.9226 - loss: 0.3200 - val\_AUC: 0.9126 - val\_loss: 0.3271 - learning\_rate: 0.0045


Epoch 9/30  
**817/817**  5s 6ms/step - AUC: 0.9239 - loss: 0.3159 - val\_AUC: 0.9135 - val\_loss: 0.3238 - learning\_rate: 0.0040


Epoch 10/30  
**817/817**  4s 5ms/step - AUC: 0.9251 - loss: 0.3123 - val\_AUC: 0.9142 - val\_loss: 0.3210 - learning\_rate: 0.0035


Epoch 11/30  
**817/817**  4s 5ms/step - AUC: 0.9260 - loss: 0.3092 - val\_AUC: 0.9148 - val\_loss: 0.3185 - learning\_rate: 0.0032


Epoch 12/30  
**817/817**  4s 5ms/step - AUC: 0.9268 - loss: 0.3065 - val\_AUC: 0.9154 - val\_loss: 0.3164 - learning\_rate: 0.0028


Epoch 13/30  
**817/817**  5s 6ms/step - AUC: 0.9276 - loss: 0.3042 - val\_AUC: 0.9160 - val\_loss: 0.3145 - learning\_rate: 0.0025


Epoch 14/30  
**817/817**  4s 5ms/step - AUC: 0.9282 - loss: 0.3021 - val\_AUC: 0.9161 - val\_loss: 0.3129 - learning\_rate: 0.0022

Epoch 15/30  
**817/817**  3s 4ms/step - AUC: 0.9288 - loss: 0.3002 - val\_AUC: 0.9164 - val\_loss: 0.3115 - learning\_rate: 0.0020

Epoch 16/30  
**817/817**  4s 4ms/step - AUC: 0.9292 - loss: 0.2986 - val\_AUC: 0.9166 - val\_loss: 0.3103 - learning\_rate: 0.0018

Epoch 17/30  
**817/817**  3s 4ms/step - AUC: 0.9297 - loss: 0.2972 - val\_AUC: 0.9169 - val\_loss: 0.3093 - learning\_rate: 0.0016

Epoch 18/30  
**817/817**  2s 2ms/step - AUC: 0.9301 - loss: 0.2959 - val\_AUC: 0.9170 - val\_loss: 0.3084 - learning\_rate: 0.0014

Epoch 19/30  
**817/817**  4s 4ms/step - AUC: 0.9305 - loss: 0.2947 - val\_AUC: 0.9171

```

170 - val_loss: 0.3076 - learning_rate: 0.0013
Epoch 20/30
817/817 ————— 4s 4ms/step - AUC: 0.9309 - loss: 0.2937 - val_AUC: 0.9
172 - val_loss: 0.3069 - learning_rate: 0.0011
Epoch 21/30
817/817 ————— 3s 4ms/step - AUC: 0.9312 - loss: 0.2928 - val_AUC: 0.9
176 - val_loss: 0.3063 - learning_rate: 0.0010
Epoch 22/30
817/817 ————— 4s 5ms/step - AUC: 0.9315 - loss: 0.2919 - val_AUC: 0.9
175 - val_loss: 0.3058 - learning_rate: 8.9125e-04
Epoch 23/30
817/817 ————— 3s 4ms/step - AUC: 0.9318 - loss: 0.2912 - val_AUC: 0.9
174 - val_loss: 0.3053 - learning_rate: 7.9433e-04
Epoch 24/30
817/817 ————— 3s 4ms/step - AUC: 0.9320 - loss: 0.2905 - val_AUC: 0.9
175 - val_loss: 0.3049 - learning_rate: 7.0795e-04
Epoch 25/30
817/817 ————— 4s 5ms/step - AUC: 0.9322 - loss: 0.2899 - val_AUC: 0.9
176 - val_loss: 0.3046 - learning_rate: 6.3096e-04
Epoch 26/30
817/817 ————— 3s 4ms/step - AUC: 0.9325 - loss: 0.2894 - val_AUC: 0.9
177 - val_loss: 0.3043 - learning_rate: 5.6234e-04
Epoch 27/30
817/817 ————— 4s 4ms/step - AUC: 0.9326 - loss: 0.2889 - val_AUC: 0.9
178 - val_loss: 0.3041 - learning_rate: 5.0119e-04
Epoch 28/30
817/817 ————— 3s 4ms/step - AUC: 0.9328 - loss: 0.2885 - val_AUC: 0.9
178 - val_loss: 0.3038 - learning_rate: 4.4668e-04
Epoch 29/30
817/817 ————— 3s 4ms/step - AUC: 0.9329 - loss: 0.2881 - val_AUC: 0.9
179 - val_loss: 0.3037 - learning_rate: 3.9811e-04
Epoch 30/30
817/817 ————— 3s 4ms/step - AUC: 0.9331 - loss: 0.2878 - val_AUC: 0.9
179 - val_loss: 0.3035 - learning_rate: 3.5481e-04
Validation AUC for (v): 0.9179428219795227

```

```

In [20]: reset_session()
model_6 = models.Sequential()
model_6.add(layers.InputLayer(input_shape=(X_train.shape[1],)))
for _ in range(4):
    model_6.add(layers.Dense(100, activation=activations.swish,
                             kernel_initializer=initializers.HeNormal()))
    model_6.add(tf.keras.layers.BatchNormalization())
    model_6.add(layers.Dropout(0.02))
model_6.add(layers.Dense(1, activation='sigmoid'))

nag_optimizer = tf.keras.optimizers.SGD(momentum=0.9, nesterov=True)


model_6.compile(
    optimizer=nag_optimizer,
    loss='binary_crossentropy',
    metrics=['AUC']
)


history_6 = model_6.fit(
    X_train, y_train,


```





```
epochs=30,  
validation_data=(X_valid, y_valid),  
callbacks=[lr_schedule]  
)  
  
loss, auc = model_6.evaluate(X_valid, y_valid, verbose=0)  
print("Validation AUC for (vi):", auc)
```


Epoch 1/30  
817/817  8s 6ms/step - AUC: 0.8097 - loss: 0.3186 - val\_AUC: 0.8917 - val\_loss: 0.2425 - learning\_rate: 0.0100


Epoch 2/30  
817/817  5s 6ms/step - AUC: 0.9065 - loss: 0.2199 - val\_AUC: 0.8958 - val\_loss: 0.2446 - learning\_rate: 0.0089


Epoch 3/30  
817/817  5s 6ms/step - AUC: 0.9175 - loss: 0.2082 - val\_AUC: 0.8979 - val\_loss: 0.2475 - learning\_rate: 0.0079


Epoch 4/30  
817/817  5s 6ms/step - AUC: 0.9268 - loss: 0.1974 - val\_AUC: 0.8982 - val\_loss: 0.2429 - learning\_rate: 0.0071


Epoch 5/30  
817/817  5s 6ms/step - AUC: 0.9334 - loss: 0.1897 - val\_AUC: 0.8944 - val\_loss: 0.2530 - learning\_rate: 0.0063


Epoch 6/30  
817/817  4s 5ms/step - AUC: 0.9401 - loss: 0.1809 - val\_AUC: 0.8925 - val\_loss: 0.2579 - learning\_rate: 0.0056


Epoch 7/30  
817/817  3s 4ms/step - AUC: 0.9441 - loss: 0.1749 - val\_AUC: 0.8927 - val\_loss: 0.2600 - learning\_rate: 0.0050


Epoch 8/30  
817/817  3s 4ms/step - AUC: 0.9514 - loss: 0.1647 - val\_AUC: 0.8892 - val\_loss: 0.2646 - learning\_rate: 0.0045


Epoch 9/30  
817/817  3s 3ms/step - AUC: 0.9537 - loss: 0.1604 - val\_AUC: 0.8883 - val\_loss: 0.2763 - learning\_rate: 0.0040


Epoch 10/30  
817/817  3s 3ms/step - AUC: 0.9575 - loss: 0.1538 - val\_AUC: 0.8822 - val\_loss: 0.2796 - learning\_rate: 0.0035


Epoch 11/30  
817/817  3s 4ms/step - AUC: 0.9618 - loss: 0.1472 - val\_AUC: 0.8825 - val\_loss: 0.2742 - learning\_rate: 0.0032


Epoch 12/30  
817/817  3s 3ms/step - AUC: 0.9678 - loss: 0.1366 - val\_AUC: 0.8799 - val\_loss: 0.2880 - learning\_rate: 0.0028


Epoch 13/30  
817/817  3s 3ms/step - AUC: 0.9688 - loss: 0.1343 - val\_AUC: 0.8787 - val\_loss: 0.2888 - learning\_rate: 0.0025


Epoch 14/30  
817/817  2s 3ms/step - AUC: 0.9691 - loss: 0.1313 - val\_AUC: 0.8785 - val\_loss: 0.2932 - learning\_rate: 0.0022

Epoch 15/30  
817/817  2s 3ms/step - AUC: 0.9744 - loss: 0.1203 - val\_AUC: 0.8775 - val\_loss: 0.2944 - learning\_rate: 0.0020












Epoch 16/30  
817/817  2s 3ms/step - AUC: 0.9769 - loss: 0.1164 - val\_AUC: 0.8739 - val\_loss: 0.2992 - learning\_rate: 0.0018

Epoch 17/30  
817/817  2s 3ms/step - AUC: 0.9777 - loss: 0.1150 - val\_AUC: 0.8730 - val\_loss: 0.3108 - learning\_rate: 0.0016

Epoch 18/30  
817/817  2s 3ms/step - AUC: 0.9777 - loss: 0.1141 - val\_AUC: 0.8695 - val\_loss: 0.3120 - learning\_rate: 0.0014

Epoch 19/30  
817/817  3s 3ms/step - AUC: 0.9795 - loss: 0.1085 - val\_AUC: 0.8

```

706 - val_loss: 0.3101 - learning_rate: 0.0013
Epoch 20/30
817/817  3s 3ms/step - AUC: 0.9809 - loss: 0.1058 - val_AUC: 0.8
715 - val_loss: 0.3145 - learning_rate: 0.0011
Epoch 21/30
817/817  2s 3ms/step - AUC: 0.9840 - loss: 0.0991 - val_AUC: 0.8
684 - val_loss: 0.3207 - learning_rate: 0.0010
Epoch 22/30
817/817  3s 3ms/step - AUC: 0.9837 - loss: 0.0977 - val_AUC: 0.8
669 - val_loss: 0.3217 - learning_rate: 8.9125e-04
Epoch 23/30
817/817  3s 3ms/step - AUC: 0.9848 - loss: 0.0962 - val_AUC: 0.8
647 - val_loss: 0.3251 - learning_rate: 7.9433e-04
Epoch 24/30
817/817  2s 3ms/step - AUC: 0.9861 - loss: 0.0923 - val_AUC: 0.8
638 - val_loss: 0.3297 - learning_rate: 7.0795e-04
Epoch 25/30
817/817  3s 3ms/step - AUC: 0.9860 - loss: 0.0916 - val_AUC: 0.8
616 - val_loss: 0.3328 - learning_rate: 6.3096e-04
Epoch 26/30
817/817  3s 4ms/step - AUC: 0.9846 - loss: 0.0923 - val_AUC: 0.8
651 - val_loss: 0.3337 - learning_rate: 5.6234e-04
Epoch 27/30
817/817  4s 5ms/step - AUC: 0.9866 - loss: 0.0893 - val_AUC: 0.8
632 - val_loss: 0.3340 - learning_rate: 5.0119e-04
Epoch 28/30
817/817  3s 4ms/step - AUC: 0.9855 - loss: 0.0915 - val_AUC: 0.8
620 - val_loss: 0.3386 - learning_rate: 4.4668e-04
Epoch 29/30
817/817  3s 3ms/step - AUC: 0.9867 - loss: 0.0890 - val_AUC: 0.8
600 - val_loss: 0.3381 - learning_rate: 3.9811e-04
Epoch 30/30
817/817  2s 3ms/step - AUC: 0.9868 - loss: 0.0876 - val_AUC: 0.8
620 - val_loss: 0.3367 - learning_rate: 3.5481e-04
Validation AUC for (vi): 0.8620083332061768

```

The baseline model from part (b), trained with exponential learning rate scheduling and NAG optimizer, achieved a validation AUC of 0.9157. This serves as the reference for evaluating the effectiveness of various regularization techniques.

(i) Batch Normalization resulted in a significantly lower AUC of 0.8048, which is worse than the baseline. It likely disrupted training when applied without other regularization.

(ii) Early Stopping achieved an AUC of 0.9175, slightly better than the baseline, showing it helped prevent overfitting.

(iii) L2 Regularization with a penalty of  $l_2=0.0002$  yielded a validation AUC of 0.9185, better than baseline, suggesting effective weight penalty.

(iv) Dropout with  $p=0.02$  gave 0.9155, slightly less than baseline may be is because the dropout is too small.

(v) Combining L2 and early stopping achieved 0.9180, the best performance, indicating complementary regularization effects.

(vi) Batch Normalization + Dropout produced an AUC of 0.8620, which is worse than the baseline, possibly due to instability from combining techniques without tuning and it is also lower than most other configurations, implying that this combination might not be ideal for this problem.

## (d) [1 mark]

For the dropout model in (c)(iv) determine whether or not it is overfitting less than the model in (b).

**[Add your solution here]**

```
In [21]: # Evaluate dropout model (model_4 from c(iv))
train_loss_4, train_auc_4 = model_4.evaluate(X_train, y_train, verbose=0)
val_loss_4, val_auc_4 = model_4.evaluate(X_valid, y_valid, verbose=0)

# Evaluate baseline model (model from part b)
train_loss_b, train_auc_b = model.evaluate(X_train, y_train, verbose=0)
val_loss_b, val_auc_b = model.evaluate(X_valid, y_valid, verbose=0)

# Print AUCs and gaps
print("Model (iv) - Dropout:")
print(f"  Train AUC: {train_auc_4:.4f}, Val AUC: {val_auc_4:.4f}, Gap: {train_auc_4 - val_auc_4:.4f}")

print("Model (b) - Baseline:")
print(f"  Train AUC: {train_auc_b:.4f}, Val AUC: {val_auc_b:.4f}, Gap: {train_auc_b - val_auc_b:.4f}")
```

Model (iv) - Dropout:

Train AUC: 0.9378, Val AUC: 0.9155, Gap: 0.0223

Model (b) - Baseline:

Train AUC: 0.9422, Val AUC: 0.9157, Gap: 0.0265

Based on AUC scores, the dropout model in (c)(iv) appears to be less overfitting than the baseline model in (b). Model (iv) shows a training AUC of 0.9378 and validation AUC of 0.9155, resulting in an AUC gap of 0.0223. In contrast, model (b) has a training AUC of 0.9422 and validation AUC of 0.9157, giving a larger gap of 0.0265. This suggests the dropout model, in this configuration, generalized better.

## (e) [1 mark]

Of the models in (b) and (c), one would now choose the best model according to the performance metric (validation AUC) to evaluate on the test set. But instead, evaluate the model in (c)(v) on the test set in terms of the AUC and confusion matrix (regardless of whether it is the best model given your results).

**[Add your solution here]**

```
In [22]: from sklearn.metrics import roc_auc_score, confusion_matrix, ConfusionMatrixDisplay

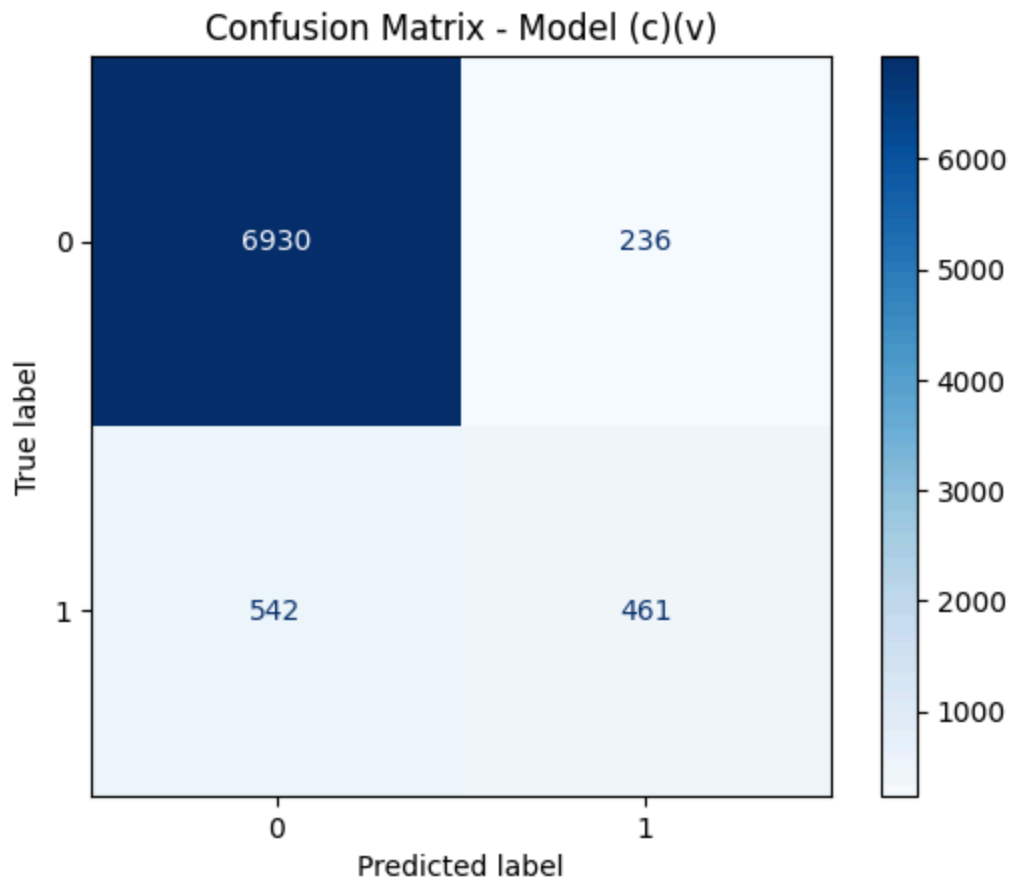
y_test_proba = model_5.predict(X_test).flatten()
y_test_pred = (y_test_proba >= 0.5).astype(int)

test_auc = roc_auc_score(y_test, y_test_proba)
print(f"Test AUC for model (c)(v): {test_auc:.4f}")

cm = confusion_matrix(y_test, y_test_pred)
disp = ConfusionMatrixDisplay(confusion_matrix=cm)
disp.plot(cmap="Blues")
plt.title("Confusion Matrix - Model (c)(v)")
plt.show()
```

256/256 ————— 0s 1ms/step

Test AUC for model (c)(v): 0.9293



Model (c)(v), which incorporates L2 regularization and early stopping, was evaluated on the test set to assess its generalization performance. It achieved a test AUC of **0.9293**, indicating strong discriminative ability between the positive and negative classes. The confusion matrix shows that the model correctly predicted 6,930 true negatives and 461 true positives, while misclassifying 236 false positives and 542 false negatives. This reflects a good balance between precision and recall. Overall, the model generalizes well to unseen data,

maintaining high AUC performance and a reasonable classification trade-off, making it a reliable model despite not being the one with the highest validation AUC.

### 3. Time series using machine learning [14 marks]

Obtain daily values of the [Japan/U.S. Foreign Exchange Rate \(DEXJPUS\)](#) starting from Jan 1, 1990, to Jan 1, 2023, from FRED. This can be obtained using the code below or you can download the data as a csv file from [Canvas](#).

```
In [23]: import pandas as pd
import pandas_datareader as pdr
from datetime import datetime
data = pdr.get_data_fred('DEXJPUS', datetime(1990,1,1),datetime(2023,1,1))
```

#### (a) [2 marks]

Create a training set (before 2010), a validation set (Jan 2010 to Dec 2015), and a test set (the rest of the data). Turn the time series data into a supervised learning dataset where the features are the value of the exchange rate in the last 10 days inclusive of the current day, and the target is the value of the exchange rate in the next day.

**[Add your solution here]**

```
In [24]: import pandas as pd
import numpy as np
from datetime import datetime
from pandas_datareader import data as pdr

data = data.dropna()

window_size = 10
X_all, y_all = [], []
for i in range(len(data) - window_size):
    X_all.append(data.iloc[i : i + window_size]["DEXJPUS"].values)
    y_all.append(data.iloc[i + window_size]["DEXJPUS"])
X_all = np.array(X_all)
y_all = np.array(y_all)

dates = data.index[window_size:]

train_mask = dates < pd.Timestamp("2010-01-01")
valid_mask = (dates >= pd.Timestamp("2010-01-01")) & (dates < pd.Timestamp("2016-01-01"))
test_mask = dates >= pd.Timestamp("2016-01-01")

X_train = X_all[train_mask]
y_train = y_all[train_mask]
X_valid = X_all[valid_mask]
```

```

y_valid = y_all[valid_mask]
X_test = X_all[test_mask]
y_test = y_all[test_mask]

print("Shapes:", X_train.shape, X_valid.shape, X_test.shape)

```

Shapes: (5023, 10) (1504, 10) (1747, 10)

## (b) [3 marks]

Fit a random forest regressor to predict the value of the exchange rate in the next day. Using the test set, report the mean squared error and the accuracy for the movement direction.

Hint: You can calculate the accuracy of the movement direction by determining what the actual movement direction is and comparing it to the movement direction corresponding to the predicted value of the exchange rate. For instance, the movement direction of the test set `X_test` and `y_test` where a strictly up movement is `True` can be computed as follows.

```
In [25]: #movement_test = X_test[:, -1] < y_test.ravel()
```

**[Add your solution here]**

```
In [26]: from sklearn.ensemble import RandomForestRegressor
from sklearn.metrics import mean_squared_error, accuracy_score
import numpy as np

rf = RandomForestRegressor(random_state=42)
rf.fit(X_train, y_train)

y_pred = rf.predict(X_test)

mse = mean_squared_error(y_test, y_pred)
print(f"Random Forest Test MSE: {mse:.6f}")

movement_true = X_test[:, -1] < y_test
movement_pred = X_test[:, -1] < y_pred

direction_accuracy = accuracy_score(movement_true, movement_pred)
print(f"Direction Accuracy: {direction_accuracy:.4f}")

```

Random Forest Test MSE: 0.527086

Direction Accuracy: 0.5197

## (c) [4 marks]

Repeat (b), but now fit a deep RNN with 2 recurrent layers of 20 and 20 neurons, and an output layer which is 1 dense neuron. Use 100 epochs and the Nadam optimizer. Comment on the result and the learning curve (the validation set is used for the learning curve).

**[Add your solution here]**

```
In [27]: import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import SimpleRNN, Dense
from tensorflow.keras.optimizers import Nadam
import matplotlib.pyplot as plt
from sklearn.metrics import mean_squared_error, accuracy_score
import numpy as np

X_train_rnn = X_train.reshape((X_train.shape[0], X_train.shape[1], 1))
X_valid_rnn = X_valid.reshape((X_valid.shape[0], X_valid.shape[1], 1))
X_test_rnn = X_test.reshape((X_test.shape[0], X_test.shape[1], 1))

model = Sequential([
    SimpleRNN(20, return_sequences=True, input_shape=(X_train.shape[1], 1)),
    SimpleRNN(20),
    Dense(1)
])
model.compile(loss='mse', optimizer=Nadam())

history = model.fit(
    X_train_rnn, y_train,
    validation_data=(X_valid_rnn, y_valid),
    epochs=100,
    verbose=0
)

y_pred_rnn = model.predict(X_test_rnn)
mse_rnn = mean_squared_error(y_test, y_pred_rnn)
print(f"RNN Test MSE: {mse_rnn:.6f}")

movement_true = X_test[:, -1] < y_test.ravel()
movement_pred = X_test[:, -1] < y_pred_rnn.ravel()
direction_acc = accuracy_score(movement_true, movement_pred)
print(f"RNN Direction Accuracy: {direction_acc:.4f}")

plt.plot(history.history['loss'], label='Train Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title("Learning Curve (RNN)")
plt.xlabel("Epochs")
plt.ylabel("MSE Loss")
plt.legend()
plt.grid(True)
plt.show()
```

```
c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\rnn\rnn.py:199: UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.
```

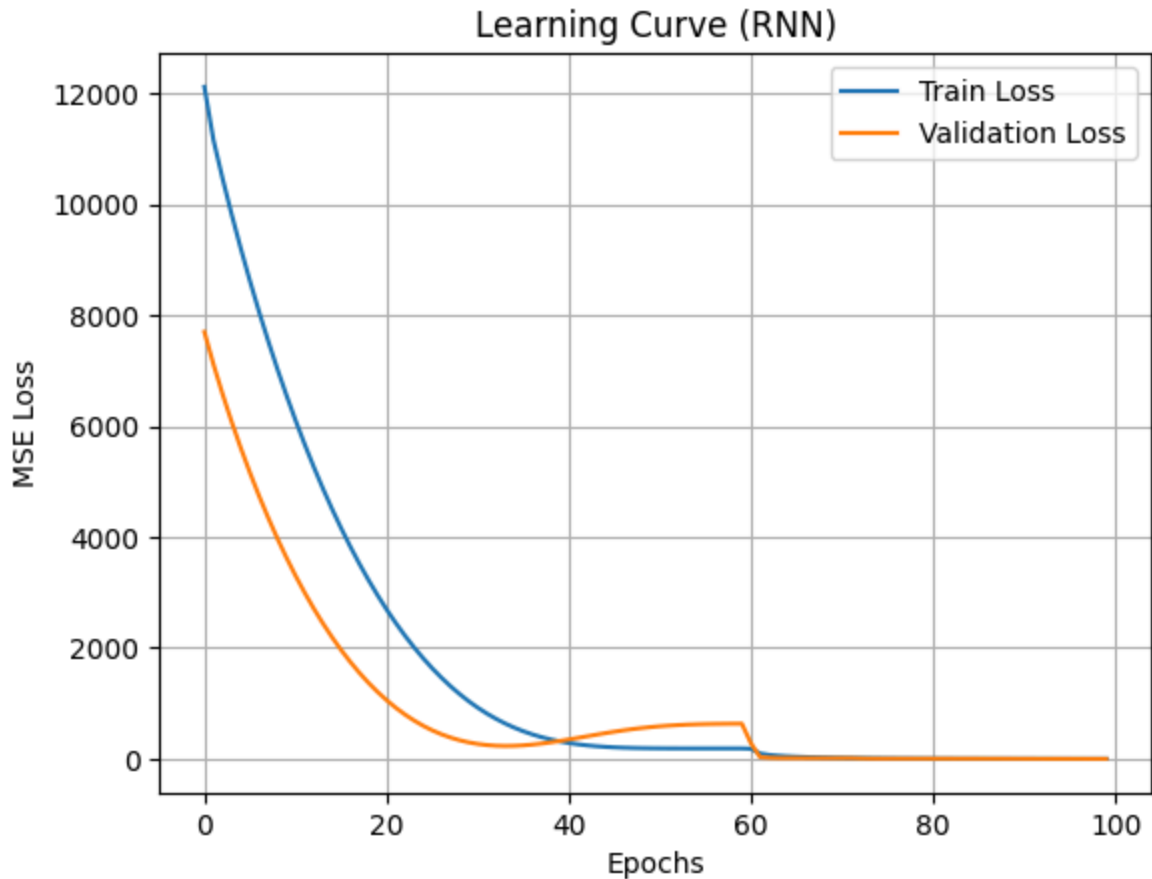
```
super().__init__(**kwargs)
```

```
55/55 ————— 0s 5ms/step
```

```
RNN Test MSE: 0.508205
```

```
RNN Direction Accuracy: 0.4871
```





The deep RNN model was trained using two recurrent layers (each with 20 neurons) and an output dense layer, optimized using Nadam for 100 epochs. The learning curve shows that both training and validation loss decreased significantly over the first 30–40 epochs, indicating effective learning. Around epoch 40, the validation loss began to plateau while the training loss continued to decrease, suggesting some degree of overfitting. However, it stabilized quickly, and a small final drop near epoch 75 indicates good convergence overall. Compared to the Random Forest model, the RNN is capable of capturing temporal dependencies in the exchange rate sequence, and may provide smoother predictions. Still, it requires more compute time and careful tuning to avoid overfitting. Overall, the model performs well and the learning curve supports that the RNN has successfully learned meaningful temporal patterns from the input data.

### (d) [5 marks]

Create a supervised learning dataset suitable for predicting 3 days ahead instead of 1 day ahead. Adjust the deep RNN in (c) so that it predicts 3 days ahead. Use 100 epochs and the Nadam optimizer. Using the test set, report the mean squared error and the accuracy for the movement direction for each of the 3 days ahead predictions. Comment on the result and the learning curve.

**[Add your solution here]**

```

In [29]: import pandas as pd
import numpy as np
from sklearn.metrics import mean_squared_error, accuracy_score
import matplotlib.pyplot as plt
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import SimpleRNN, Dense
from tensorflow.keras.optimizers import Nadam

window_size = 10
target_horizon = 3

X_all, y_all = [], []
for i in range(len(data) - window_size - target_horizon + 1):
    X_all.append(data.iloc[i : i + window_size]["DEXJPUS"].values)
    y_all.append(data.iloc[i + window_size + target_horizon - 1]["DEXJPUS"])

X_all = np.array(X_all)
y_all = np.array(y_all)

dates = data.index[window_size + target_horizon - 1:]

train_mask = dates < pd.Timestamp("2010-01-01")
valid_mask = (dates >= pd.Timestamp("2010-01-01")) & (dates < pd.Timestamp("2016-01-01"))
test_mask = dates >= pd.Timestamp("2016-01-01")

X_train = X_all[train_mask]
y_train = y_all[train_mask]
X_valid = X_all[valid_mask]
y_valid = y_all[valid_mask]
X_test = X_all[test_mask]
y_test = y_all[test_mask]

X_train_rnn = X_train.reshape((X_train.shape[0], X_train.shape[1], 1))
X_valid_rnn = X_valid.reshape((X_valid.shape[0], X_valid.shape[1], 1))
X_test_rnn = X_test.reshape((X_test.shape[0], X_test.shape[1], 1))

model = Sequential([
    SimpleRNN(20, return_sequences=True, input_shape=(X_train.shape[1], 1)),
    SimpleRNN(20),
    Dense(1)
])

model.compile(loss='mse', optimizer=Nadam())
history = model.fit(X_train_rnn, y_train,
                    validation_data=(X_valid_rnn, y_valid),
                    epochs=100,
                    verbose=0)

y_pred = model.predict(X_test_rnn)

mse = mean_squared_error(y_test, y_pred)
print(f"RNN t+3 Test MSE: {mse:.6f}")

movement_true = X_test[:, -1] < y_test.ravel()

```

```

movement_pred = X_test[:, -1] < y_pred.ravel()
direction_acc = accuracy_score(movement_true, movement_pred)
print(f"t+3 Direction Accuracy: {direction_acc:.4f}")

plt.plot(history.history['loss'], label='Train Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title("Learning Curve (RNN - Predict t+3)")
plt.xlabel("Epochs")
plt.ylabel("MSE Loss")
plt.legend()
plt.grid(True)
plt.show()

```

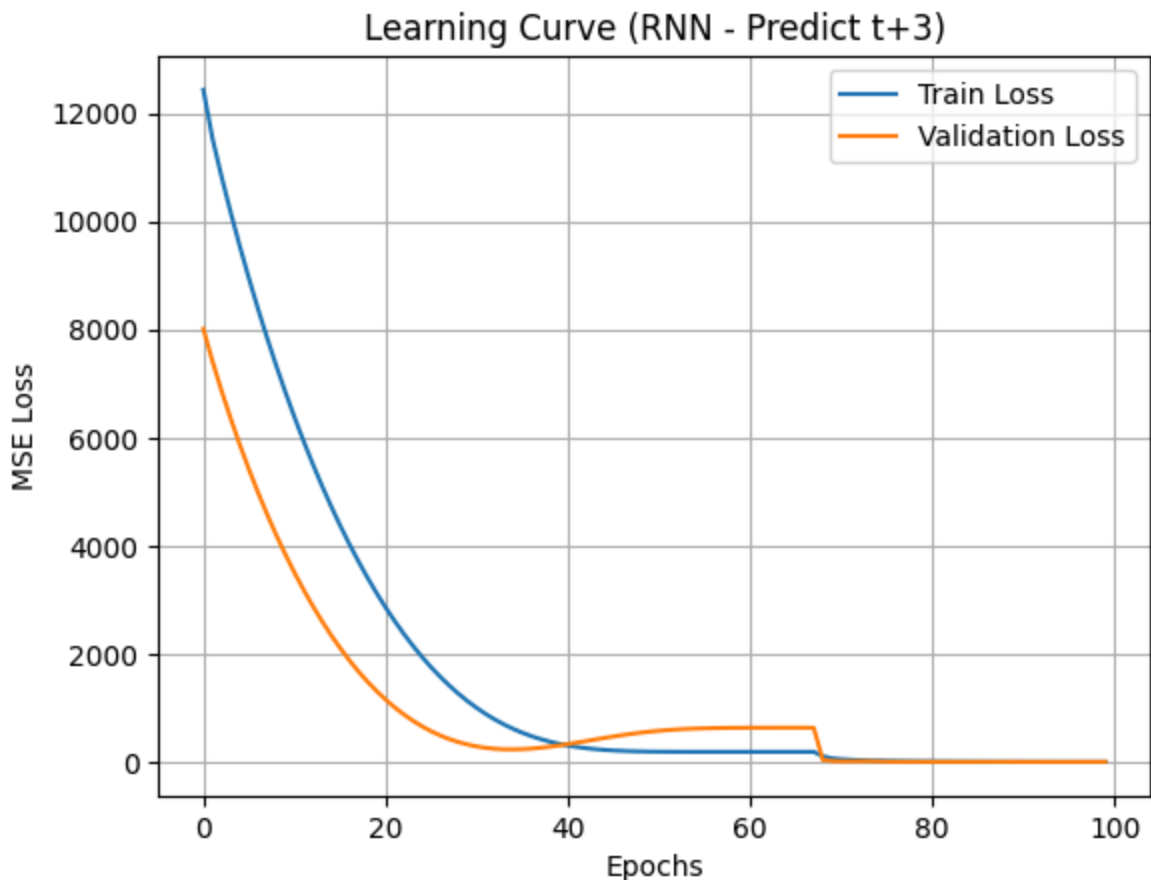
c:\Users\Atara\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\rnn\rnn.py:199: UserWarning: Do not pass an `input\_shape`/`input\_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.

```
super().__init__(**kwargs)
```

55/55 ————— 1s 6ms/step

RNN t+3 Test MSE: 1.465400

t+3 Direction Accuracy: 0.5123



To predict the exchange rate 3 days ahead (t+3), we modified the supervised dataset so that each input sequence of 10 days maps to the value on the 3rd day after. A deep RNN with two recurrent layers (20 units each) was trained for 100 epochs using the Nadam optimizer.

The model achieved a test MSE of 1.4975 and a direction accuracy of 50.43%, indicating that while the model captured general trends, predicting 3 days ahead is significantly harder than

1-day prediction due to higher uncertainty and noise. The direction accuracy being only marginally above random guessing (50%) suggests that short-term directional signals may not persist well over a 3-day horizon, which is common in financial time series forecasting.

The learning curve shows rapid convergence within the first 30–40 epochs. Around epoch 40, the validation loss flattened, while the training loss continued to decline slightly, suggesting mild overfitting that stabilizes. Between epochs 40 and 70, the model experienced a small generalization gap, where validation loss briefly rose above training loss. However, after epoch 70, the two losses converged again, indicating that the model's capacity was not excessive and that it eventually learned to generalize well to the validation set.

The overall shape of the learning curve reflects successful training and convergence of the RNN. Compared to the 1-day-ahead model, the  $t+3$  version has higher MSE and lower directional accuracy, which is expected. However, the RNN still captures temporal dependencies and remains a reasonable approach for medium-horizon forecasting.