Embedded Virtualization for Mobile Devices

Jim Huang (黄敬群) <jserv@0xlab.org>

Developer, Oxlab

March 29, 2012 / 中國科學技術大學軟件學院(蘇州)

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contact@0xlab.org

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Goals of This Presentation

- Give you an overview about
 - virtualization in general
 - device virtualization on ARM
 - doing virtualization in several approaches
- We will not discuss
 - language runtimes
 - how to use VMware/Xen/KVM/...



Agenda

- (1) Motivations
- (2) Hypervisor Design
- (3) Embedded Hypervisors for ARM



Motivations of enabling virtualization for embedded devices

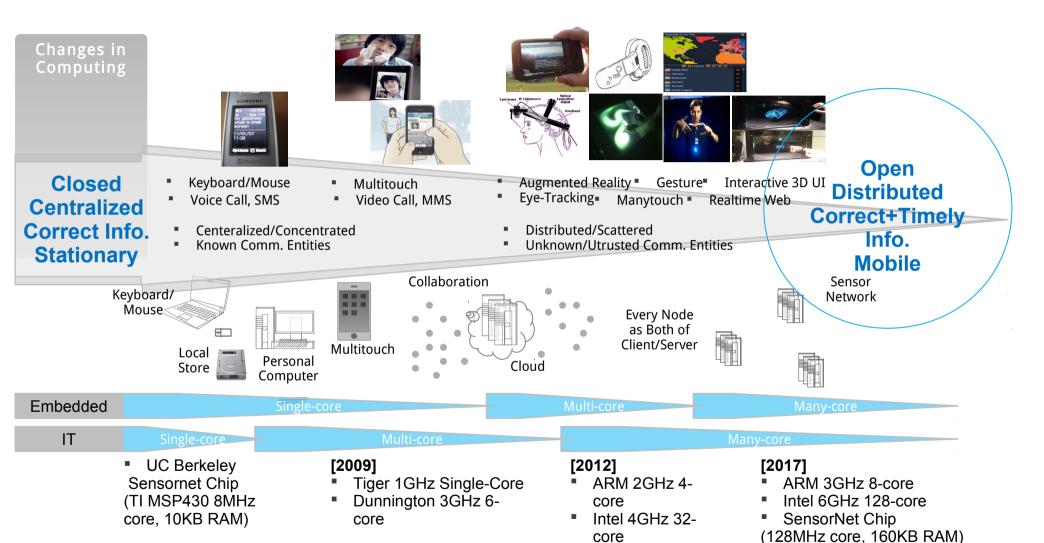


Definition

"virtualization is "a technique for hiding the physical characteristics of computing resources from the way in which other systems, applications, or end users interact with those resources."

- Wikipedia

Future Computing Trends



Privacy

Realtime



Source: **Xen ARM Virtualization**, Xen Summit Asia 2011 by Dr. Sang-bum Suh, Samsung

Server Virtualization::Benefits

- Workload consolidation
 - Increase server utilization
 - Reduce capital, hardware, power, space, heat costs
- Legacy OS support
 - Especially with large 3rd-party software products
- Instant provisioning
 - Easily create new virtual machines
 - Easily reallocate resources (memory, processor, IO) between running virtual machines
- Migration
 - Predicted hardware downtime
 - Workload balancing



Embedded Virtualization::Benefits

- Workload consolidation
- Flexible resource provisioning
- License barrier
- Legacy software support
 - Especially important with dozens or hundreds of embedded operating systems, commercial and even home-brew
- Reliability
- Security



(1) Hardware Consolidation

 Application Processor and Baseband Processor can share multicore ARM CPU SoC to run both Linux and RTOS efficiently.

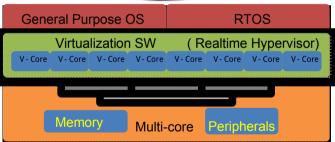


(2) OS Isolation

 important call services can be effectively separated from downloaded third party applications by virtualized ARM combined with access control.

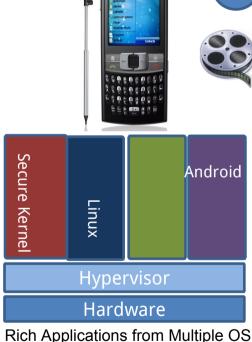






AP SoC + BP SoC → Consolidated Multicore SoC





Rich Applications from Multi

(3) Rich User Experience

 multiple OS domains can run concurrently on a single smartphone.

Source: **Xen ARM Virtualization**, Xen Summit Asia 2011 by Dr. Sang-bum Suh, Samsung

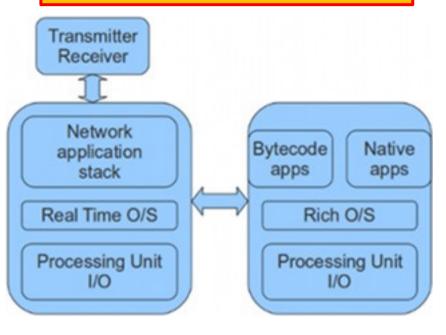
Use Case: Low-cost 3G Handset

- Mobile Handsets
 - Major applications runs on Linux
 - 3G Modem software stack runs on RTOS domain
- Virtualization in multimedia Devices
 - Reduces BOM (bill of materials)
 - Enables the Reusability of legacy code/applications
 - Reduces the system development time
- Instrumentation, Automation
 - Run RTOS for Measurement and analysis
 - Run a GPOS for Graphical Interface
- Real cases: Motorola Evoke QA4

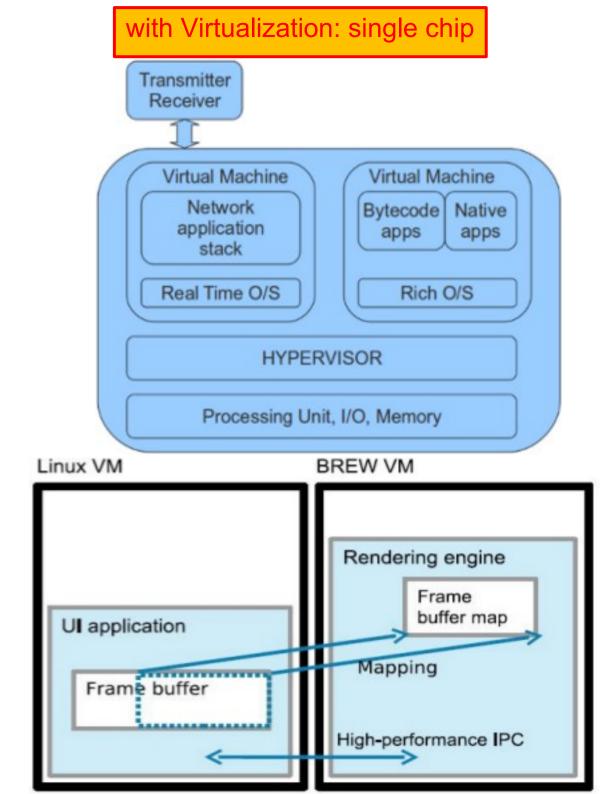
Hypervisor



original mobile phone: two CPUs required



- Evoke's UI functionalities including the touch screen is owned by the Linux apps while video rendering uses a rendering engine running on BREW.
- When a user requests a BREW app, Linux communciates with BREW in the other VM to start up the app. The BREW obtains access to the screen by using a frame buffer from a sharedmemory mapping.



Example: Ubuntu for Android

Mobile and Desktop Virtualization in One Device by VMware and Canonical

http://www.ubuntu.com/devices/android



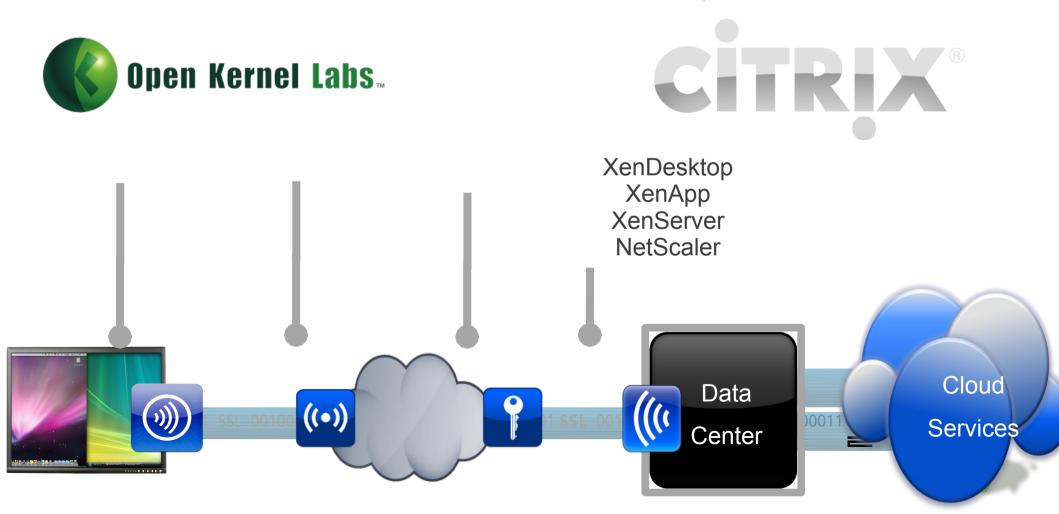


Use Case: Nirvana:

The Convergence of Mobile and Desktop

Virtualization in One Device

by OKLabs + Citrix

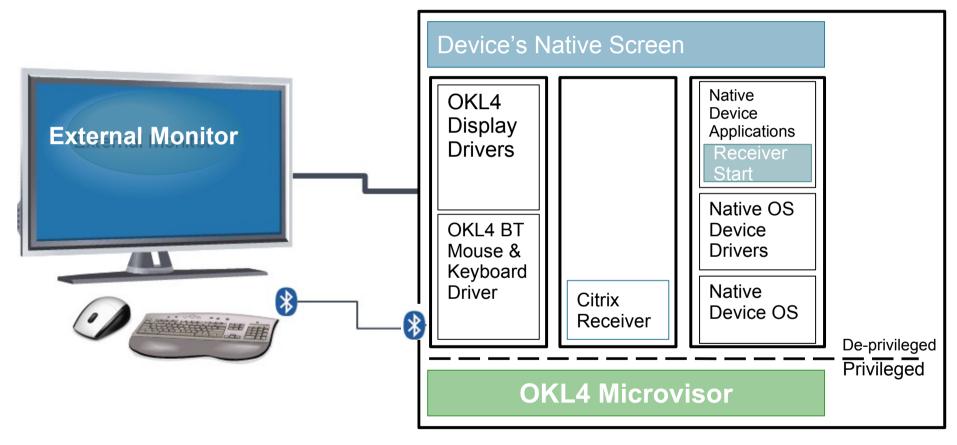


Nirvana phone = Smartphone

- + Full-sized display
- + Keyboard & mouse
- + Virtual desktop
- + OKL4 mobile virtualization

Nirvana Phone

Mobile Device



Demo video:

http://www.youtube.com/user/OpenKernelLabs



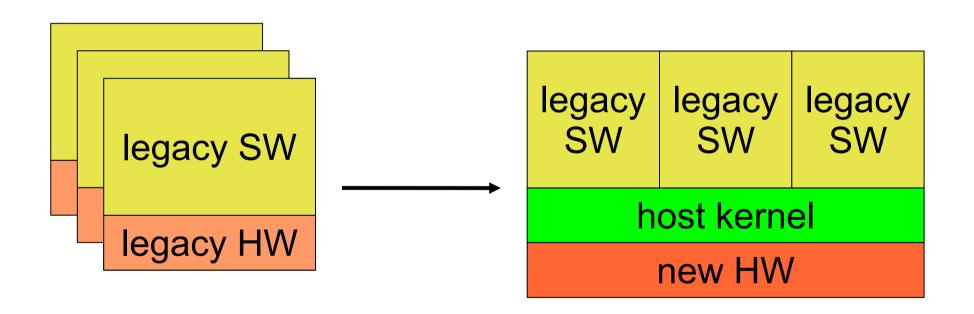
Embedded Virtualization Use Case

- Workload consolidation
- Legacy software
- Multicore enablement
- Improve reliability
- Secure monitoring



Use Case: Workload Consolidation

Consolidate legacy systems

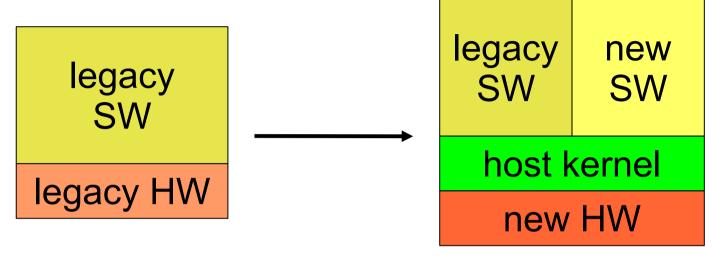




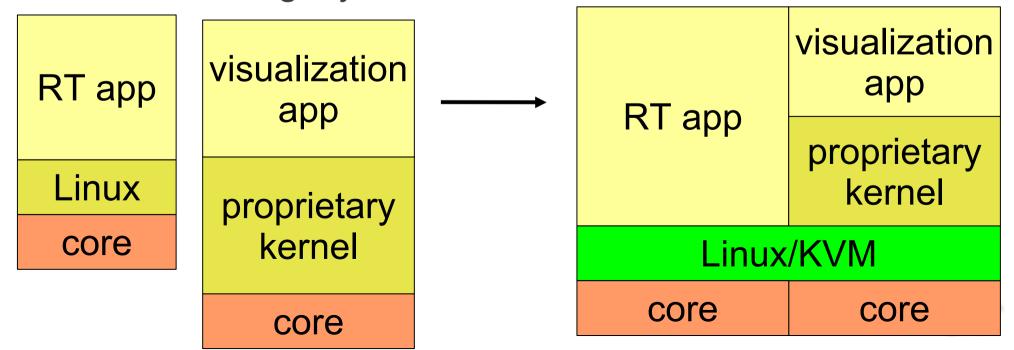
Use Case: Legacy Software

Run legacy software on new core/chip/board with full

virtualization

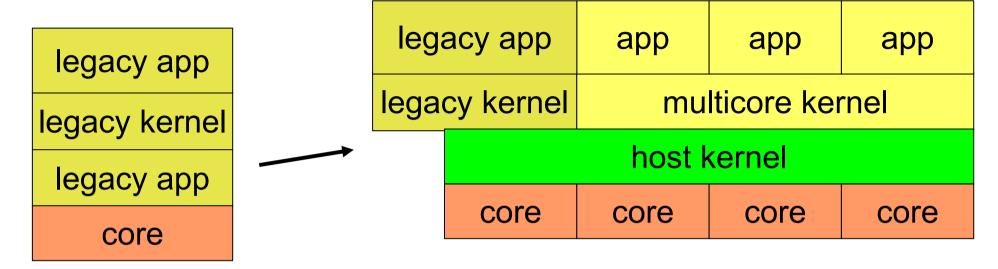


Consolidate legacy software



Use Case: Multicore Enablement

Legacy uniprocessor applications



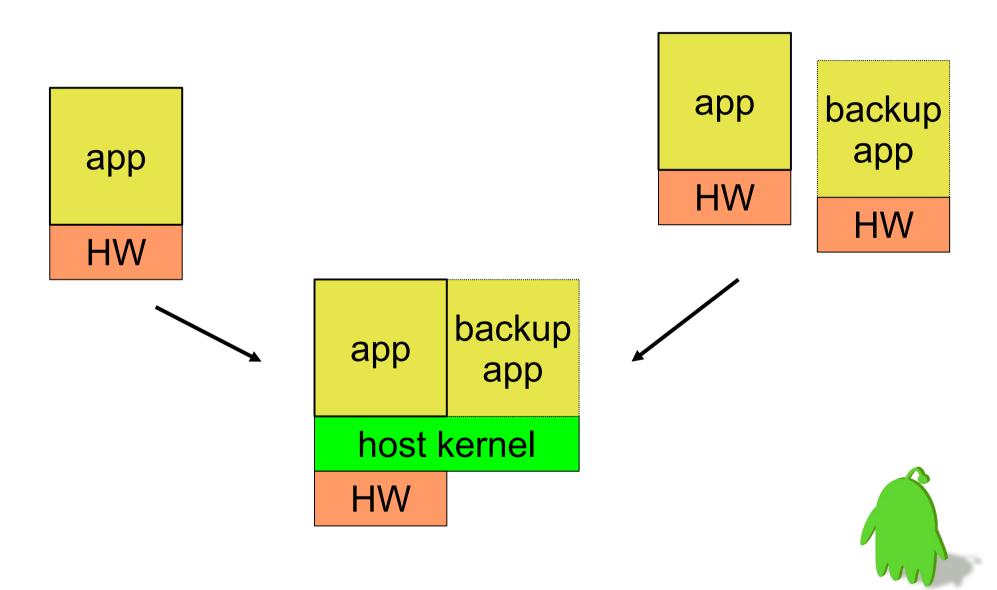
Flexible resource management

control plane	rata	data plane	data plane
	control		
host kernel			
core	core	core	core



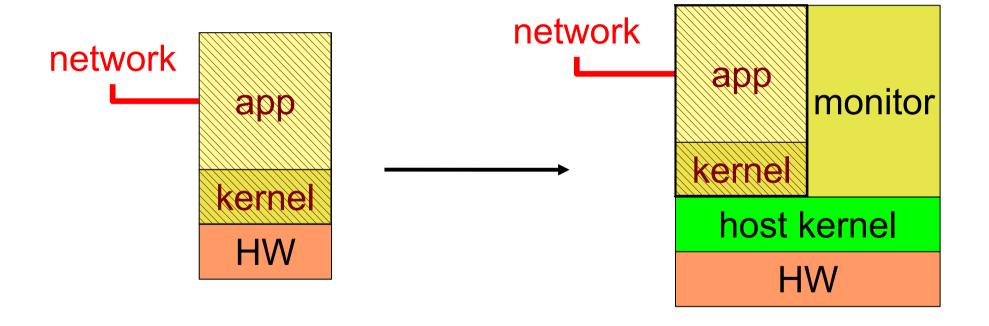
Use Case: Improved Reliability

Hot standby without additional hardware



Use Case: Secure Monitoring

Protect monitoring software





Hypervisor Design



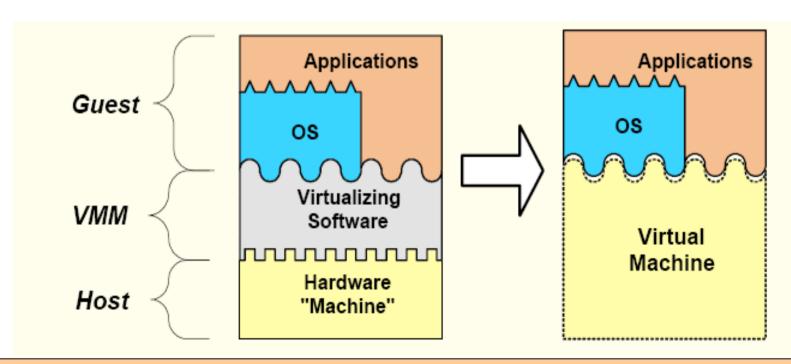
"All problems in computer science can be solved by another level of indirection."

-- David Wheeler --



Virtual Machine

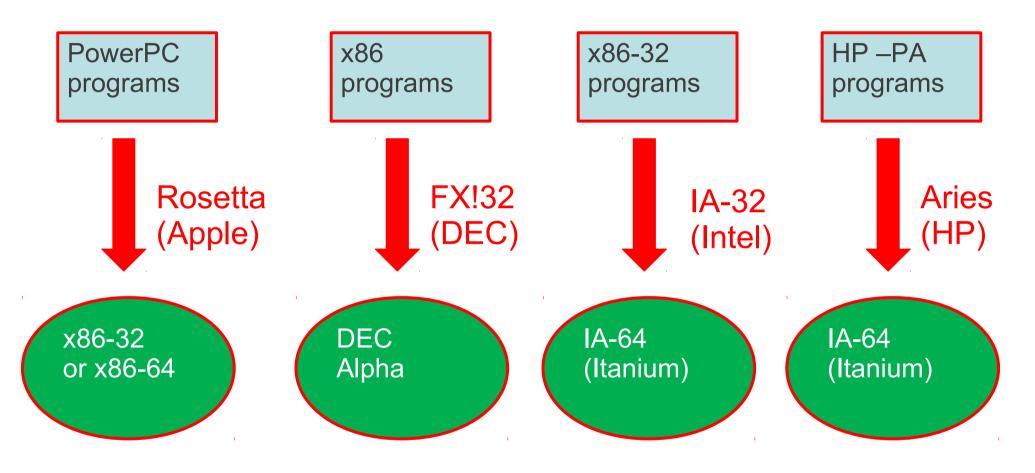
- Gerald Popek and Robert Goldberg defined it as "efficient, isolated duplicate of a real machine"
 - Add Virtualizing Software to a Host platform and support Guest process or system on a Virtual Machine (VM)





The software that provides this illusion is the Virtual Machine Monitor (VMM, mostly used synonymous with Hypervisor)

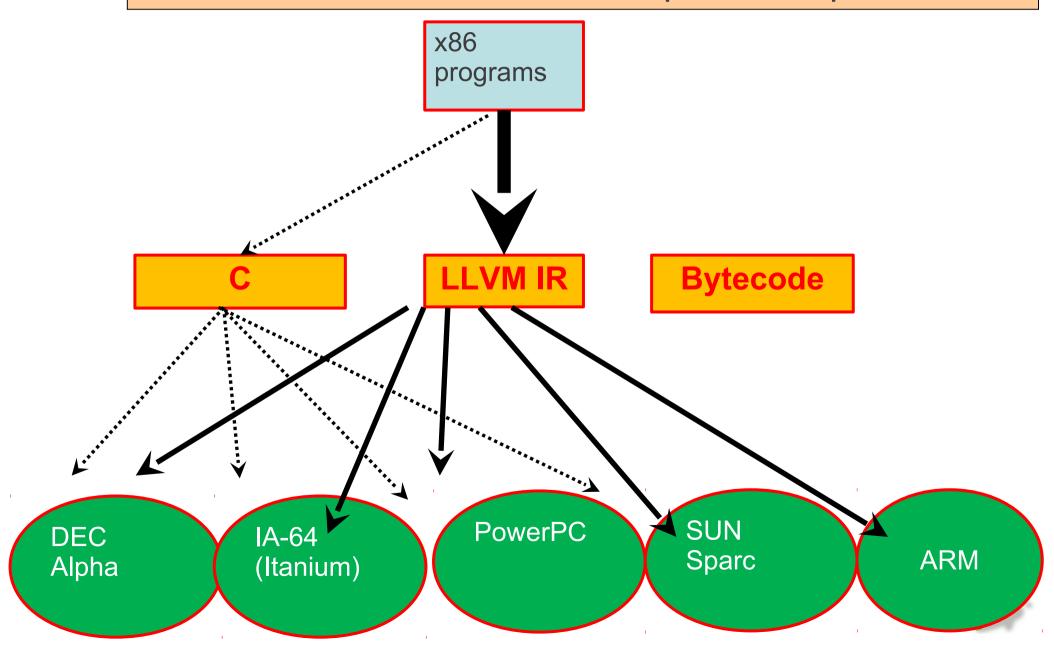
Virtual Machine for Portability (in the past)





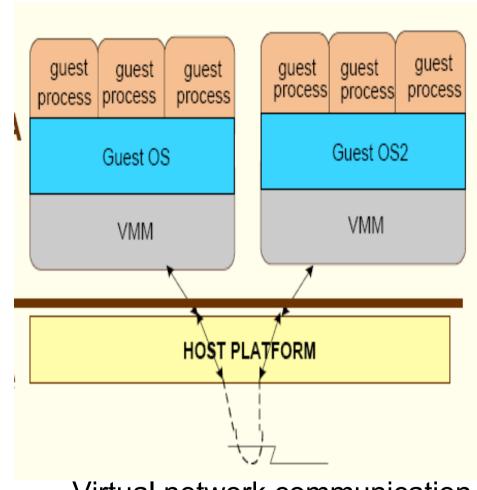
Virtual Machine for Portability

NOTE: we won't discuss such topic in this presentation



System Virtual Machine

- Provide a system environment
- Constructed at ISA level
- Allow multiple OS environments, or support time sharing.
- virtualizing software that implements system VM is called as VMM (virtual machine monitor)
- Examples:
 - IBM VM/360, VMware, VLX, WindRiver Hypervisor, ENEA Hypervisor
 - Xtratum, Lguest, BhyVe (BSD Hypervisor)
 - Xen, KVM, OKL4, Xvisor, Codezero



Virtual network communication

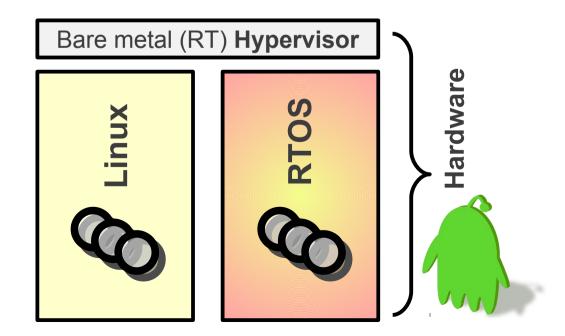


NOTE: We only focus on system virtual machine here.

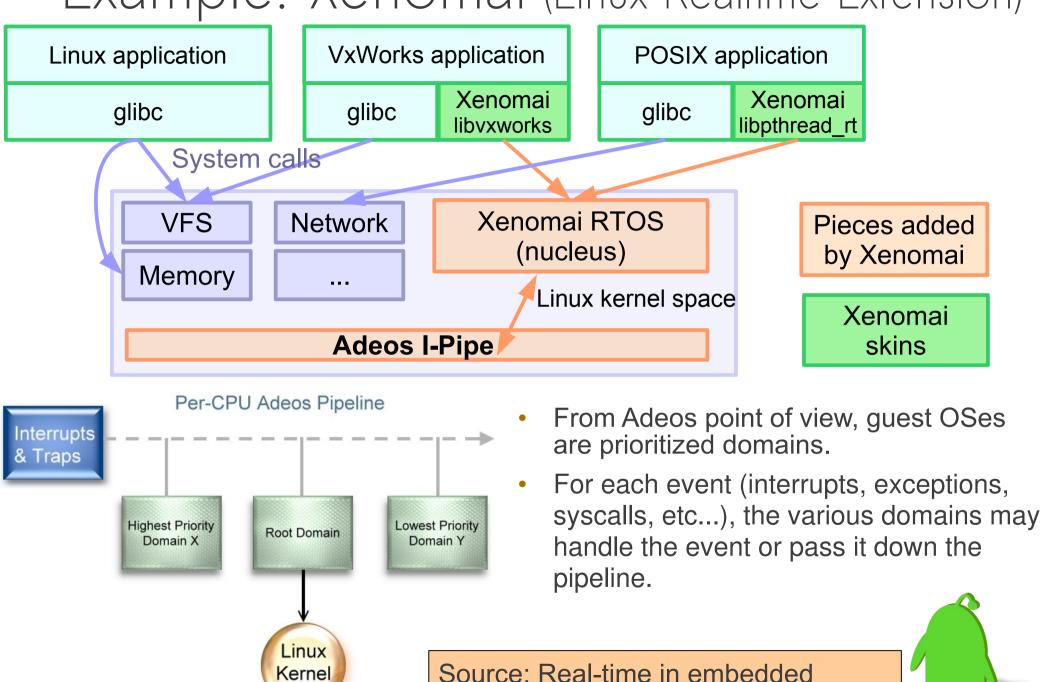
Therefore, this presentation ignores Linux vserver, FreeBSD jail, etc.

Virtualization is Common Technique

- Example: In the past, Linux is far from being realtime, but RTLinux/RTAI/Xenomai/Xtratum attempted to "improve" Linux by introducing new virtualization layer.
- real-time capable virtualization
- Dual kernel approach



Example: Xenomai (Linux Realtime Extension)

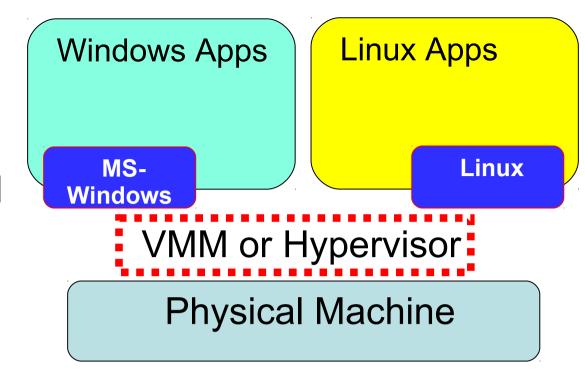


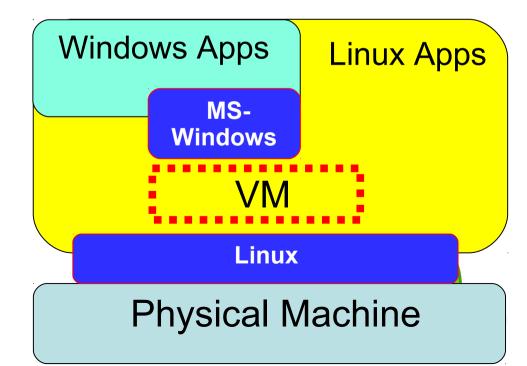
Linux systems, Free Electrons (2011)

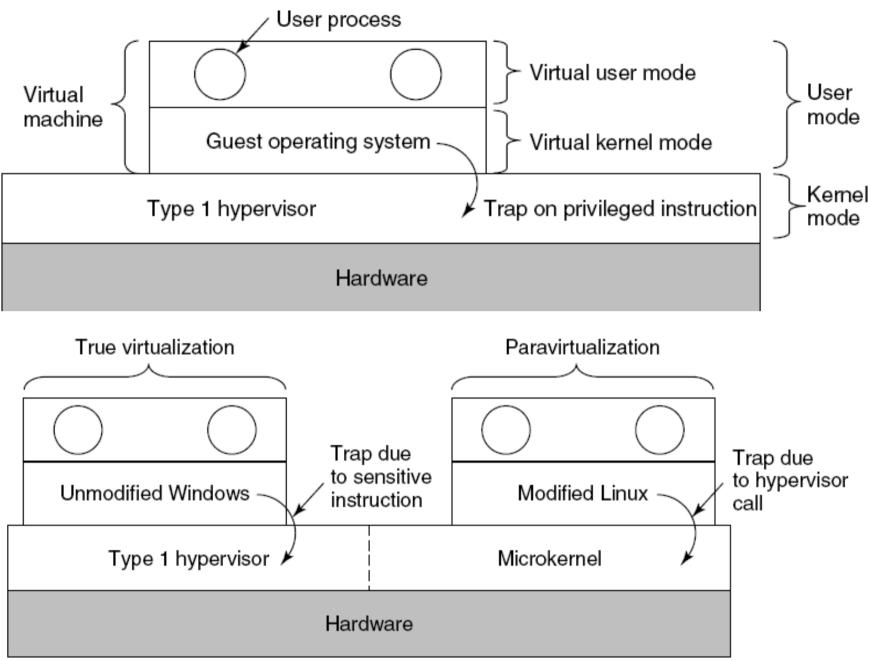
- Type I
- Bare metal system VM

General Classification of Virtualization technologies

- Type 2
- Hosted System VM









Myth of Type I and Type II Hypervisor

source: http://gala4th.blogspot.com/2011/10/myth-of-type-i-and-type-ii-hypervisors.html

- Myth: Type-2 is "lesser" than a true "type-1" hypervisor.
- Virtualization theory really started with a paper from Gerald Popek and Robert Goldberg called Formal Requirements for Virtualizable Third Generation Architectures. (1974)
 - Sensitive Instructions
 - Privileged Instructions
- The terms "type-1" and "type-2" originate from a paper by John Robin called Analyzing the Intel Pentium's Capability to Support a Secure Virtual Machine Monitor. (USENIX 2000)
 - Popek/Goldberg proof does not eliminate the possibility of using dynamic translation

Virtualizable

is a property of the Instruction Set Architecture (ISA)

- A sensitive instruction
 - changes the configuration or mode of the processor,

or

 depends in its behavior on the processor's state

- A privileged instruction
 - must be executed with sufficient privilege
 - causes a trap in user mode

If all sensitive instructions are privileged, a VMM can be written.

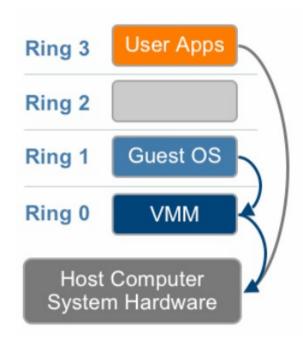


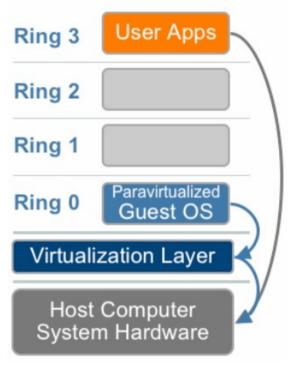
System Virtualization Implementations

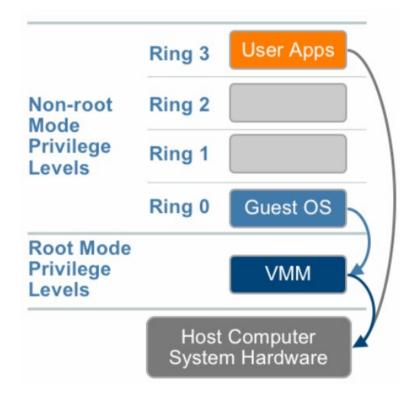
Full Virtualization

Para Virtualization

Hardware Assisted Virtualization







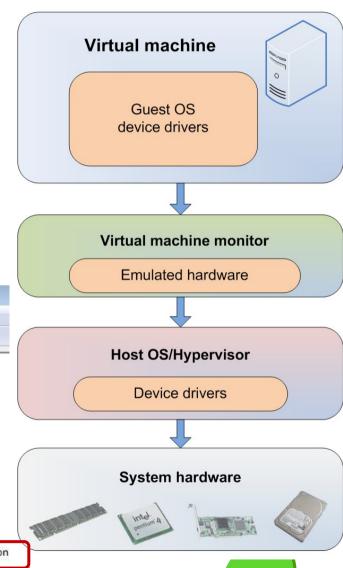


Full Virtualization

- Everything is virtualized
- Full hardware emulation
- Emulation = latency



System Hardware



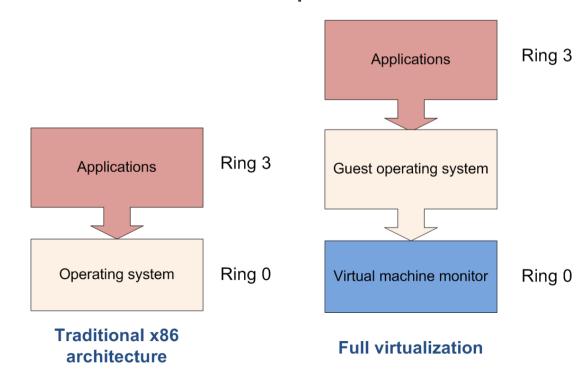
Recall the definitions

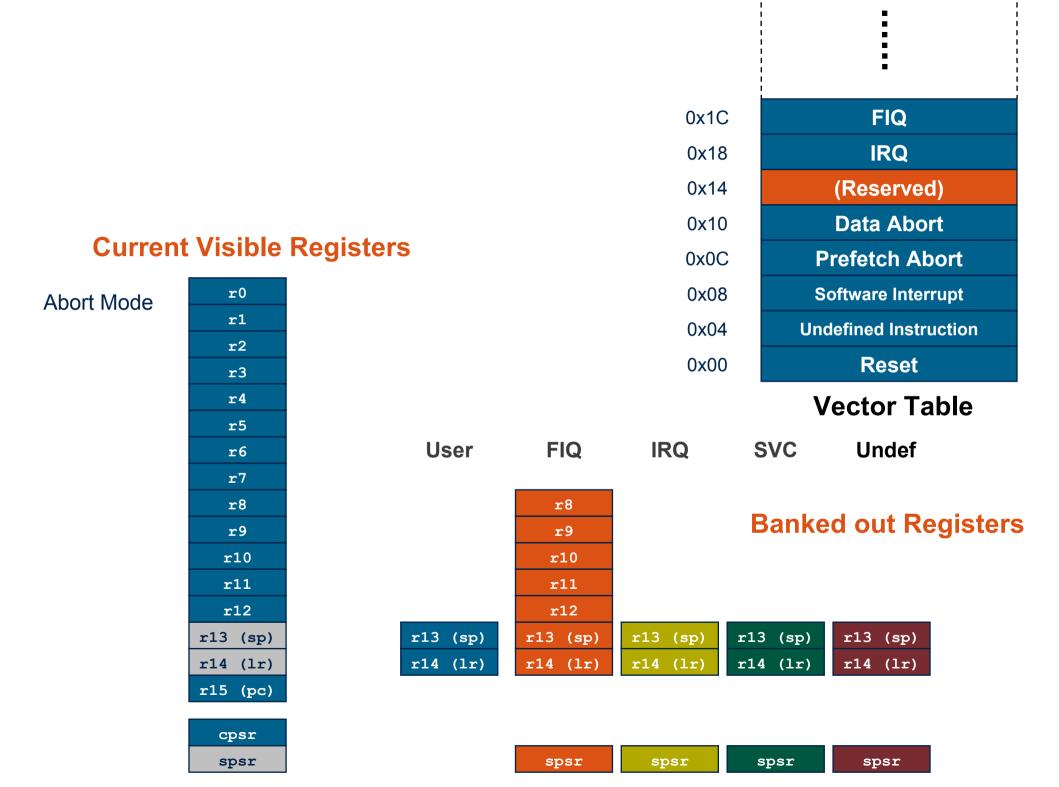
- Sensitive Instructions as defined by "Formal Requirements for Virtualizable Third Generation Architectures" (1974):
 - Mode Referencing Instructions
 - Sensitive Register/Memory Access Instructions
 - -Storage Protection System Referencing Instructions
 - -All I/O Instructions
- Theorem about strict virtualizability by "Analyzing the Intel Pentium's Capability to Support a Secure Virtual Machine Monitor" (2000):
 - -For any conventional third generation computer, a virtual machine monitor may be constructed if the set of sensitive instructions for that computer is a subset of the set of privileged instructions.

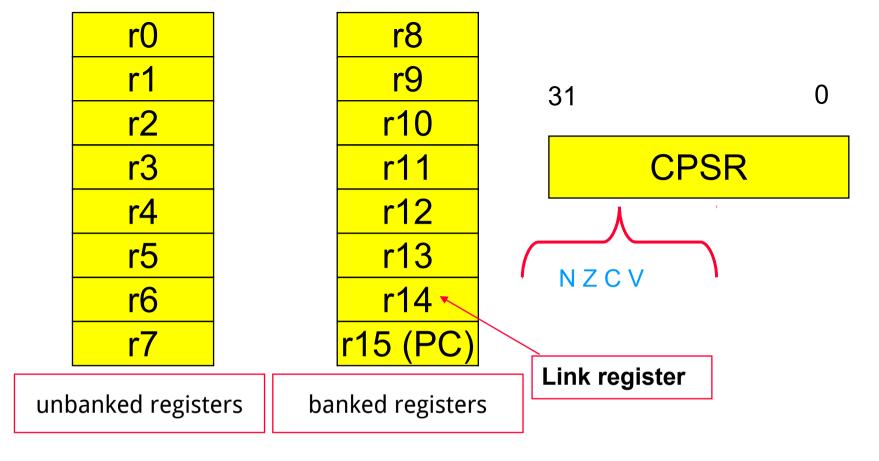


Privileged Instructions

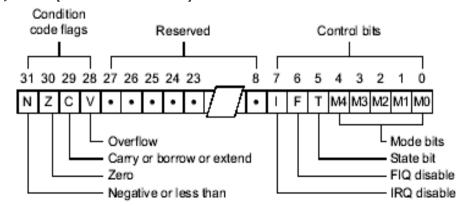
- Privileged instructions: OS kernel and device driver access to system hardware
- Trapped and Emulated by VMM
 - execute guest in separate address space in unprivileged mode
 - emulate all instructions that cause traps







- Every arithmetic, logical, or shifting operation may set CPSR (current program statues register) bits:
 - N (negative), Z (zero), C (carry), V (overflow).
- Examples:
 - -1 + 1 = 0: NZCV = 0110.
 - $2^{31}-1+1 = -2^{31}$: NZCV = 0101.



ARM Architecture (armv4)

- 6 basic operating modes (1 user, 5 privileged)
- 37 registers, all 32 bits wide
 - 1 program counter
 - 5 dedicated saved program status registers
 - 1 Current program status register (PSR)
 - 30 general purpose registers
- Special usage
 - r13 (stack pointer)
 - r14 (link register)
 - r15 (program counter, PC)



Typical ARM instructions (armv4)

- branch and branch with Link (B, BL)
- data processing instructions (AND, TST, MOV, ...)
- shifts: logical (LSR), arithmetic (ASR), rotate (ROR)
- test (TEQ, TST, CMP, CMN)
- processor status register transfer (MSR, MRS)
- memory load/store words (LDR, STR)
- push/pop Stack Operations (STM, LDM)
- software Interrupt (SWI; operating mode switch)
- co-processor (CDP, LDC, STC, MRC, MCR)



Problematic Instructions (1)

- Type 1
 Instructions which executed in user mode will cause undefined instruction exception
- Example

```
MCR p15, 0, r0, c2, c0, 0
```

Move r0 to c2 and c0 in coprocessor specified by p15 (co-processor) for operation according to option 0 and 0

- MRC: from coproc to register
- MCR: from register to coproc
- Problem:
 - Operand-dependent operation

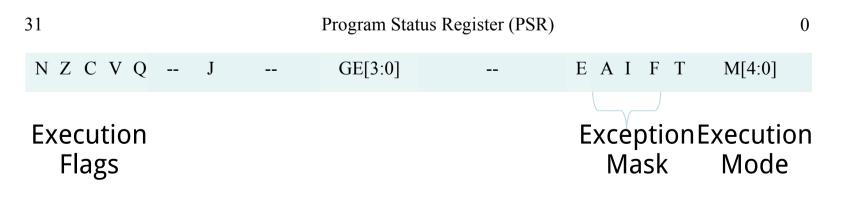


Problematic Instructions (2)

- Type 2
 Instructions which executed in user mode will have no effect
- Example

```
MSR cpsr c, #0xD3
```

Switch to privileged mode and disable interrupt





Problematic Instructions (3)

- Type 3
 Instructions which executed in user mode will cause unpredictable behaviors.
- Example

MOVS PC, LR

The return instruction

changes the **program counter** and switches to **user mode**.

 This instruction causes unpredictable behavior when executed in user mode.



ARM Sensitive Instructions

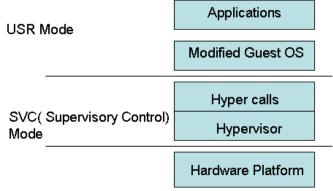
- Coprocessor Access Instructions
 MRC / MCR / CDP / LDC / STC
- SIMD/VFP System Register Access Instructions VMRS / VMSR
- TrustZone Secure State Entry Instructions
 SMC
- Memory-Mapped I/O Access Instructions Load/Store instructions from/into memory-mapped I/O locations
- Direct (Explicit/Implicit) CPSR Access Instructions
 MRS / MSR / CPS / SRS / RFE / LDM (conditional execution) / DPSPC
- Indirect CPSR Access Instructions
 LDRT / STRT Load/Store Unprivileged ("As User")
- Banked Register Access Instructions
 LDM/STM (User mode registers)



Solutions to Problematic Instructions

[Hardware Techniques]

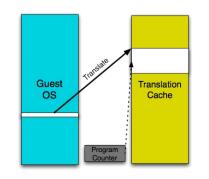
- Privileged Instruction Semantics dictated/translated by instruction set architecture
- MMU-enforced traps
 - Example: page fault
- Tracing/debug support
 - Example: bkpt (breakpoint)
- Hardware-assisted Virtualization
 - Example: extra privileged mode, HYP, in ARM Cortex-A15





Solutions to Problematic Instructions [Software Techniques]

Complexity	Binary translation	Hypercall
Design	High	Low
Implementation	Medium	High
Runtime	High	Medium
Mapped to programming languages	Virtual function	Normal function





Method: trap and emulate

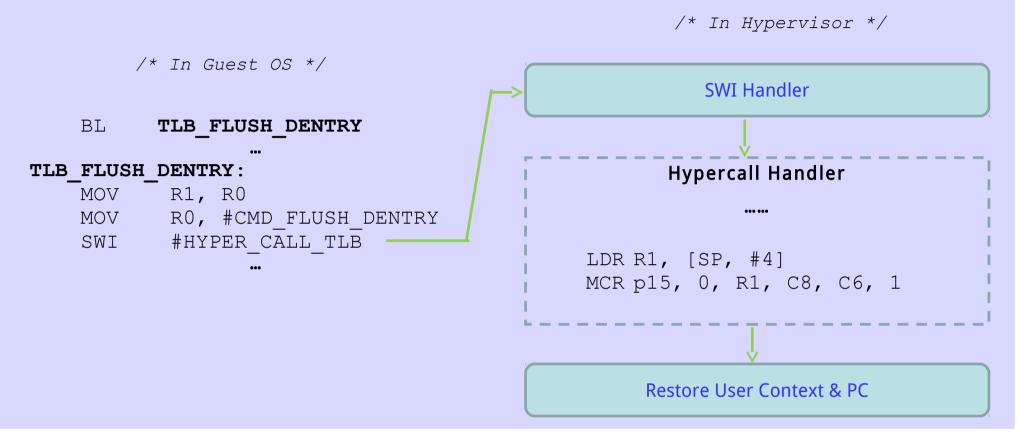
Dynamic Binary Translation

Translation Basic Block BΤι TLB FLUSH DENTRY NEW TLB FLUSH DENTRY: p15, 0, R0, C8, C6, 1 MCR BLTLB FLUSH DENTRY PC, LR MOV TLB FLUSH DENTRY: TLB FLUSH DENTRY NEW: MCR p15, 0, R0, C8, C6, 1 MOV R1, R0 PC, LR VOM RO, #CMD FLUSH DENTRY MOV SWI #HYPER CALL TLB

- ARM has a fixed instruction size
 - 32-bit in ARM mode and 16-bit in Thumb mode
- Perform binary translation
 - Follow control-flow
 - Translate basic block (if not already translated) at the current PC
 - Ensure interposition at end of translated sequence
 - All writes (but not reads) to PC now become problematic instructions
 - Replace problematic instructions 1-1 with hypercalls to trap and emulate → self-modifying code



Virtualization APIs – hypercalls

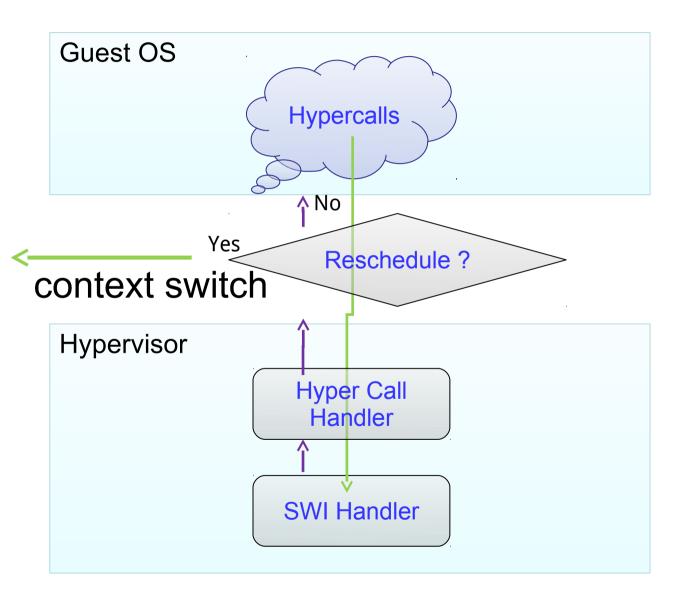


- Use trap instruction to issue hypercall
- Encode hypercall type and original instruction bits in hypercall hint
- Upon trapping into the VMM, decode the hypercall type and the original instruction bits, and emulate instruction semantics





Hypercall



Software Interrupt



Hypercall in xen-i386

System Call int 0x80

```
01 // linux/include/asm/unistd.h
                                                              02
                                                              03 #define
                                                                               NR restart syscall
                                                                                                                 0
                                     Hypervisor
                                                              04 #define
                                                                               NR exit
          Guest OS
                                                              05 #define
                                                                               NR fork
                                       Kernel-space
            User-space
                                                              06 #define
                                                                              NR read
                                                              07 ...
User application
                 C-Library
                                                   System call
        HYPERVOSIR sched op
                        Load arguments
        getpid(void)
                        eax=_NR_getpid,
                     transition to kernel (int 80)
                                         system call
                                           hypercall
                          int 82h
                                        system_call_table[eax]
                                        Hypercall table
                                                       do_sched_op
                                                                                                     int 0x82
                                             return
                              syscall exit
                                                                                 Hyper Call
                       resume_userspace
                                                                 // xen/include/public/xen.h
                       resume Guest OS
                                                              02
          Return
                                                                  #define
                                                                               HYPERVISOR set trap table 0
                                                                  #define
                                                                               HYPERVISOR mmu update
                                                                  #define
                                                                               HYPERVISOR set gdt
                                                                               HYPERVISOR stack switch
                                                                  #define
                                                              07
```

Case study: Xvisor-ARM

https://github.com/xvisor

- File: arch/arm/cpu/arm32/elf2cpatch.py
 - Script to generate cpatch script from guest OS ELF
- Functionality before generating the final ELF image
 - Each sensitive non-priviledged ARM instruction is converted to a hypercall.
 - Hypercall in ARM instruction set is svc <imm24> instruction.
 - Encode sensitive non-priviledged instructions in <imm24> operand of SVC instruction. (software interrupt)
 - Each encoded instruction will have its own unique inst_id.
 - The inst_field for each encoded sensitive non-priviledged instruction will be diffrent.

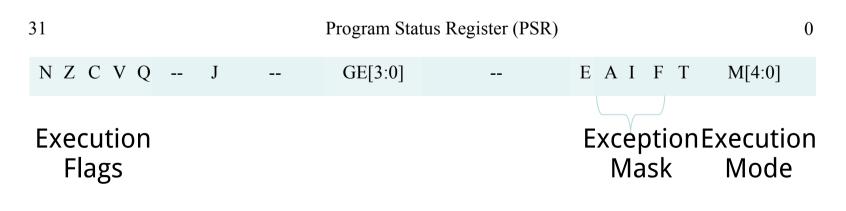
How does Xvisor handle problematic instructions like MSR?

Type 2
 Instructions which executed in user mode will have no effect

Example

MSR cpsr_c, #0xD3

Switch to privileged mode and disable interrupt





First, cpatch (ELF patching tool) looks up the instructions...

```
MSR cpsr_c, #0xD3
```

Switch to privileged mode and disable interrupt

```
MSR (immediate)
      Syntax:
              msr<c> <spec reg>, #<const>
      Fields:
              cond = bits[31:28]
              R = bits[22:22]
              mask = bits[19:16]
              imm12 = bits[11:0]
      Hypercall Fields:
              inst cond[31:28] = cond
              inst op[27:24] = 0xf
              inst id[23:20] = 0
              inst subid[19:17] = 2
              inst fields[16:13] = mask
              inst fields[12:1] = imm12
              inst fields[0:0] = R
```



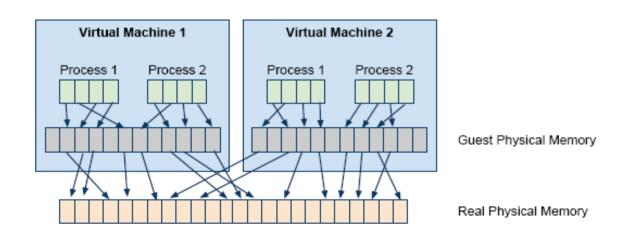
```
MSR (immediate)
                                                 Syntax:
                                                        msr<c> <spec reg>, #<const>
                                                 Fields:
                                                        cond = bits[31:28]
                                                        R = bits[22:22]
                                                        mask = bits[19:16]
                                                        imm12 = bits[11:0]
                                                 Hypercall Fields:
                                                        inst cond[31:28] = cond
                                                        inst op[27:24] = 0xf
                                                        inst id[23:20] = 0
                                                        inst subid[19:17] = 2
def convert msr i inst(hxstr):
                                                        inst fields[16:13] = mask
         hx = int(hxstr, 16)
                                                        inst fields[12:1] = imm12
         inst id = 0
                                                        inst fields[0:0] = R
         inst subid = 2
         cond = (hx >> 28) \& 0xF
                                            Xvisor utilizes cpatch to convert
         R = (hx >> 22) \& 0x1
                                            all problematic instructions for OS
         mask = (hx >> 16) \& 0xF
                                            image files (ELF format).
         imm12 = (hx >> 0) & 0xFFF
         rethx = 0x0F000000
         rethx = rethx \mid (cond << 28)
         rethx = rethx \mid (inst id << 20)
         rethx = rethx | (inst subid << 17)</pre>
         rethx = rethx \mid (mask << 13)
         rethx = rethx \mid (imm12 << 1)
         rethx = rethx
                              (R << 0)
         return rethx
```

Requirements of real Hypervisor

- VMM at higher privilege level than VMs
 - CPU Virtualization
 - Memory Virtualization
 - Device & I/O Virtualization
- User and System modes
- Privileged instructions only available in system mode
 - Trap to system if executed in user mode
- All physical resources only accessible using privileged instructions
 - Including page tables, interrupt controls, I/O registers

Memory Virtualization

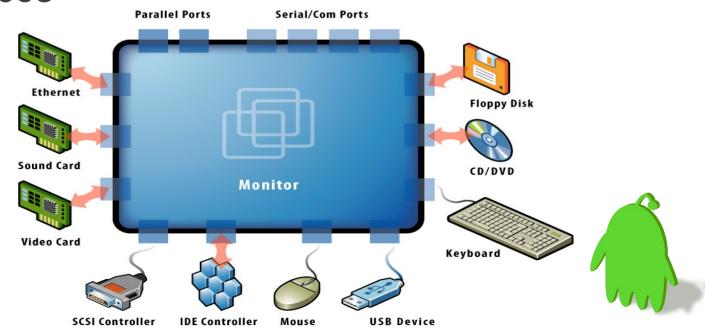
- Deal with allocation of Physical memory among Guest OS
- RAM space shares among Guest OS
- Processors with memory virtualization support is expecting in 2nd generation processors (Intel VT and ARM Cortex-A15)





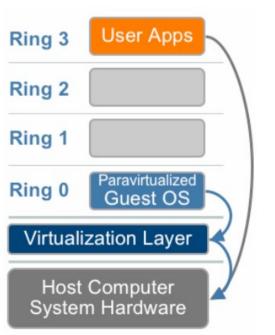
Device and I/O Virtualization

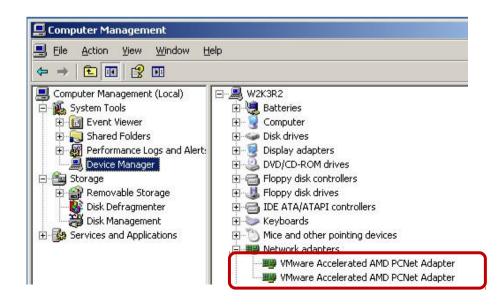
- Deal with routing of I/O requests between virtual devices and the shared physical hardware
- Similar to the single I/O device shared concurrently among different applications.
- Hypervisor virtualizes the physical hardware and present each virtual machine with a standard set of virtual devices



Paravirtualization

- OS or system devices are virtualization aware
- Requirements:
 - OS level translated/modified kernel
 - Device level paravirtualized or "enlightened" device drivers







Paravirtualization

- Why all the trouble? Just "port" a guest operating system to the interface of your choice.
- Paravirtualization can
 - provide better performance
 - simplify VMM
- but at a maintainance cost and you need the source code
 - Compromise: Use paravirtualized drivers for I/O performance (KVM virtio, VMware).
- Examples: MkLinux, L4Linux, Xen, . . .



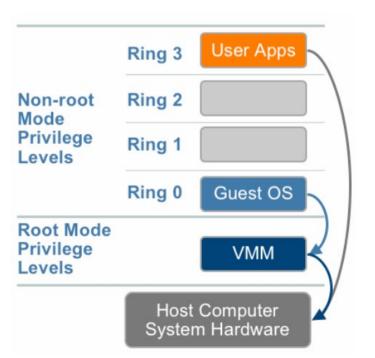
Paravirtualization

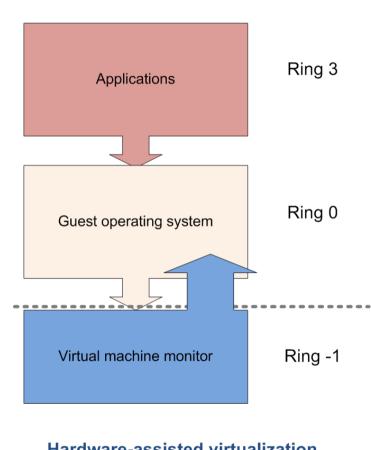
- Paravirtualization can also be semi-automated:
 - Sensitive instructions are automatically identified (in compiler output).
 - Sensitive memory access needs to manually identified.
 - Leave markers in binary.
 - On VM load-time, VMM replaces instructions with emulation code.
 - In-Place VMM translates to hypervisor calls.
- Benefits:
 - less effort than plain paravirtualization
 - comparable speed



Hardware-assisted Virtualization

- Hardware is virtualization aware
- Hypervisor and VMM load at Ring -1
- Remove CPU emulation bottleneck
- Provides address bus isolation



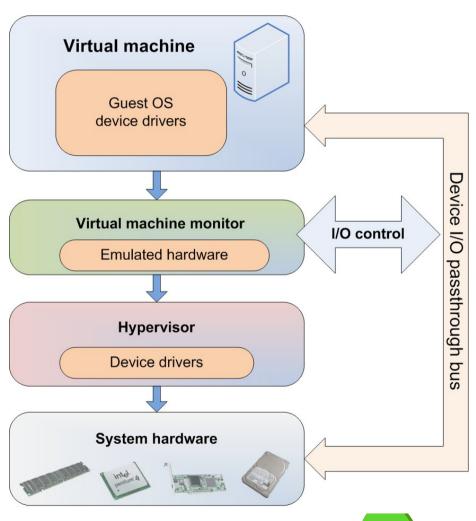


Hardware-assisted virtualization



Hardware-assisted Virtualization

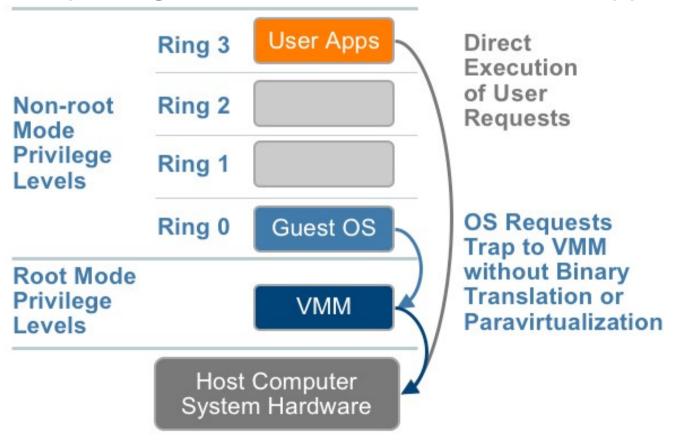
- VMM coordinates direct hardware access
- Memory virtualization solved in 2nd generation hardware assisted platforms
- Passthrough I/O has limited use cases without IOV (I/O Virtualization) http://www.pcisig.com/specifications/iov/





Hardware-assisted Virtualization in x86

- VT technology enables new execution mode (VMX-Root Mode in x86 by Intel) in the processors to support virtualization
- Hypervisor runs in a root mode below Ring0
- OS requests trap VMM without binary translation or PV
- Specialized Hardware support is required
- A special CPU privileged mode is to be selected to support





Hardware-assisted Virtualization in ARM

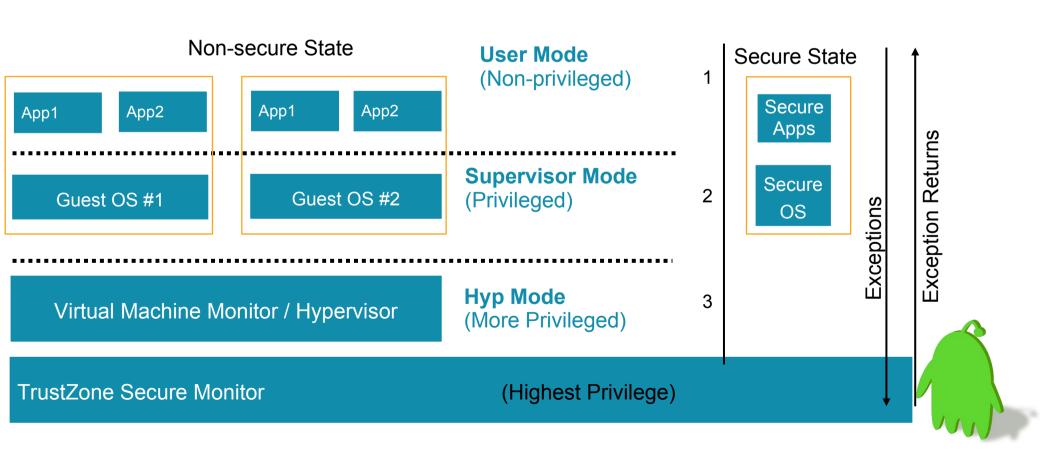
- Enable new execution mode Hypervisor (HYP)
- Hypervisor runs in a Hypervisor (HYP) mode
- Guest OS Runs in Supervisory Control (SVC) mode
- Applications runs in User (USR) mode

USR Mode	Applications	
SVC(Supervisory Control) Mode	Guest OS	
HYP Mode	Hypervisor	
	Hardware Platform	



Virtualization: Third Privilege

- Guest OS same kernel/user privilege structure
- HYP mode higher privilege than OS kernel level
- VMM controls wide range of OS accesses
- Hardware maintains TZ security (4th privilege)



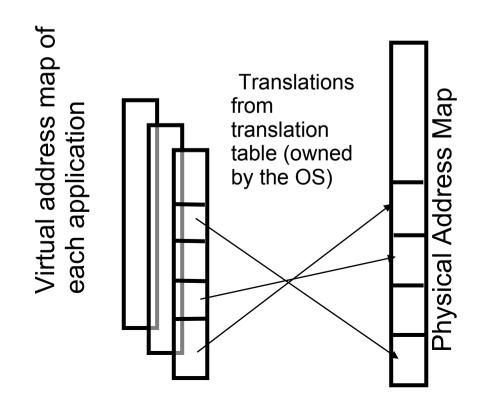
Virtualization Extensions: The Basics

- New Non-secure level of privilege to hold Hypervisor
 - Hyp mode
- New mechanisms avoid the need Hypervisor intervention for:
 - Guest OS Interrupt masking bits
 - Guest OS page table management
 - Guest OS Device Drivers due to Hypervisor memory relocation
 - Guest OS communication with the interrupt controller (GIC)
- New traps into Hyp mode for:
 - ID register accesses and idling (WFI/WFE)
 - Miscellaneous "difficult" System Control Register cases
- New mechanisms to improve:
 - Guest OS Load/Store emulation by the Hypervisor
 - Emulation of trapped instructions through syndromes



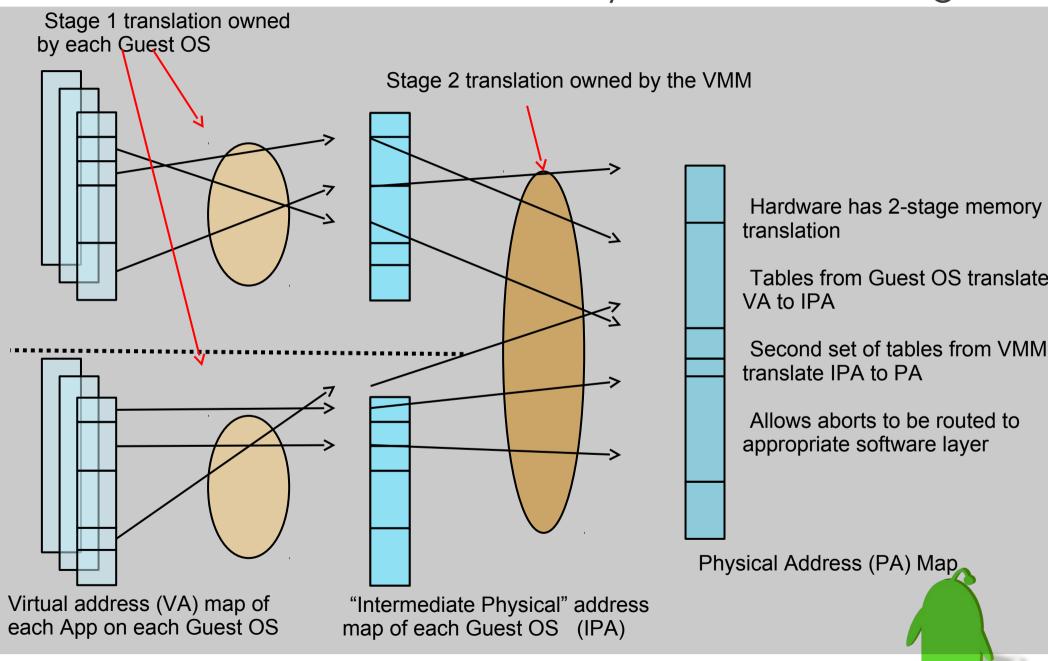
Memory - the Classic Resource

- Before virtualization: the OS owns the memory
 - Allocates areas of memory to the different applications
 - Virtual Memory commonly used in "rich" operating systems



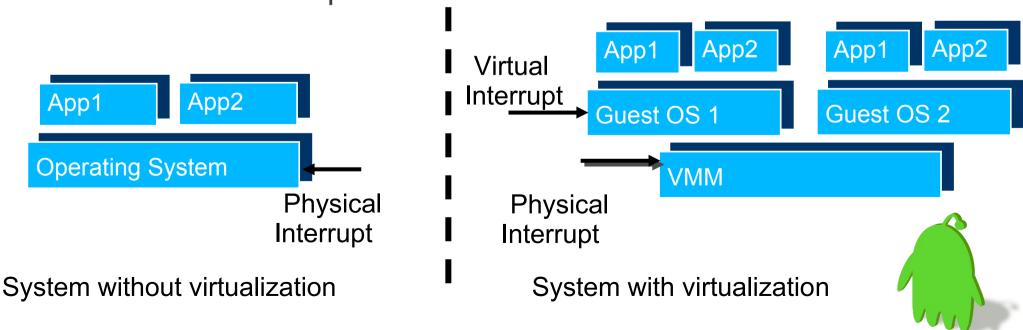


Virtual Memory in Two Stages



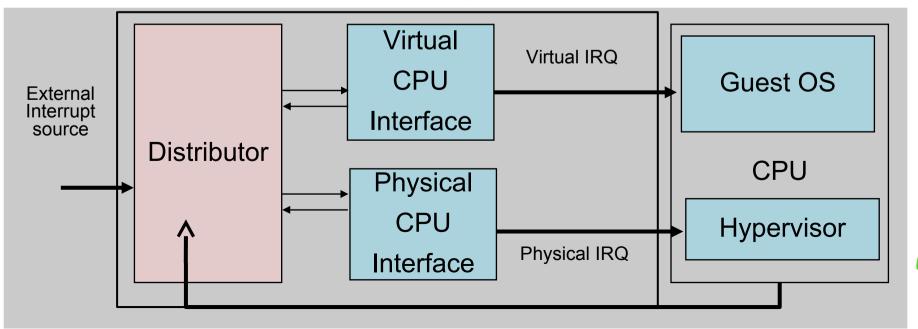
Classic Issue: Interrupts

- An Interrupt might need to be routed to one of
 - Current or different Guest OS
 - Hypervisor
 - OS/RTOS running in the secure TrustZone environment
- Basic model of the ARM virtualization extensions
 - Physical interrupts are taken initially in the Hypervisor
 - If the Interrupt should go to a Guest OS, Hypervisor maps a "virtual" interrupt for that Guest OS



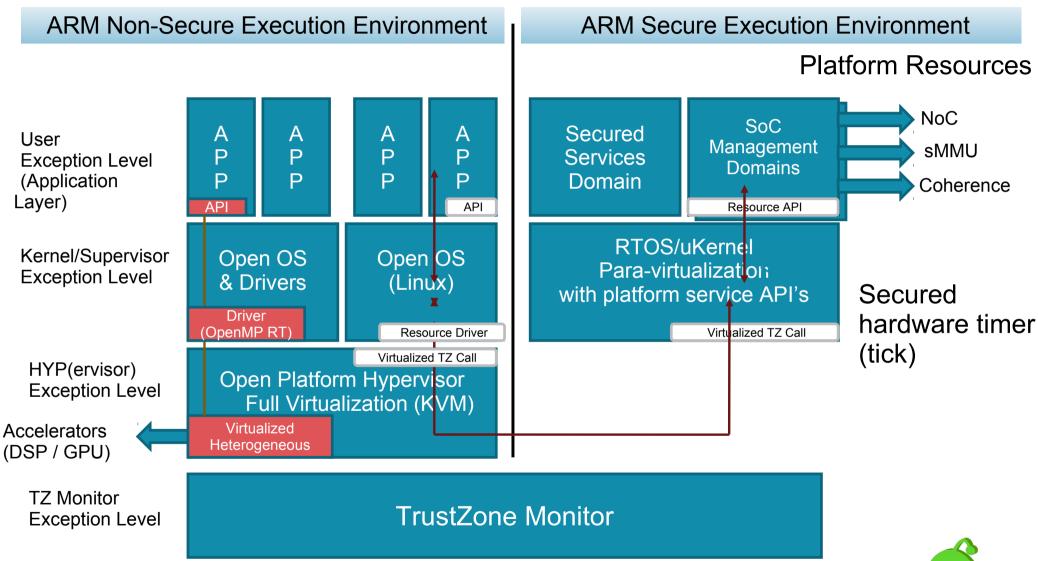
Virtual interrupt example

- External IRQ (configured as virtual by the hypervisor) arrives at the GIC
- GIC Distributor signals a Physical IRQ to the CPU
- CPU takes HYP trap, and Hypervisor reads the interrupt status from the Physical CPU Interface
- Hypervisor makes an entry in register list in the GIC
- GIC Distributor signals a Virtual IRQ to the CPU
- CPU takes an IRQ exception, and Guest OS running on the virtual machine reads the interrupt status from the Virtual CPU Interface





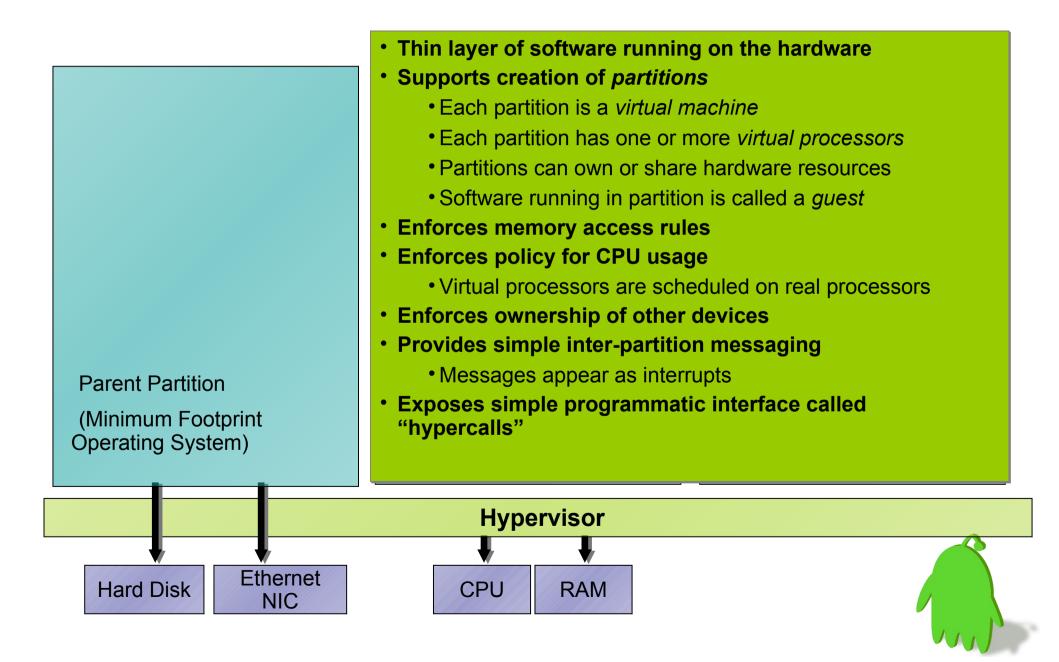
Spanning Hypervisor Framework



Source: Hardware accelerated Virtualization in the ARM Cortex™ Processors, John Goodacre, ARM Ltd. (2011)

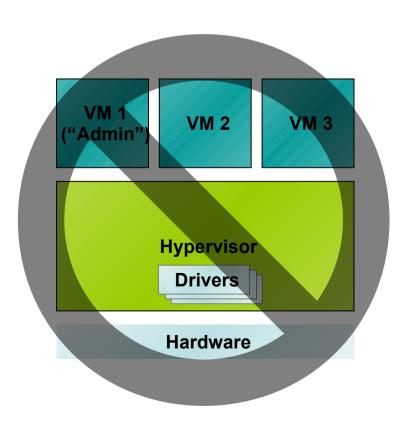


What does Hypervisor looks like

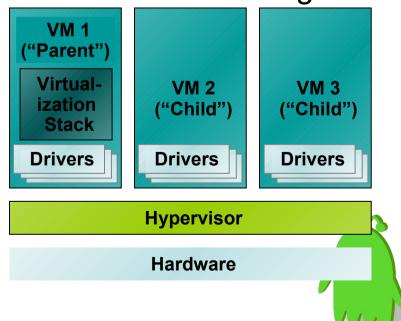


Monolithic vs. Microkernel

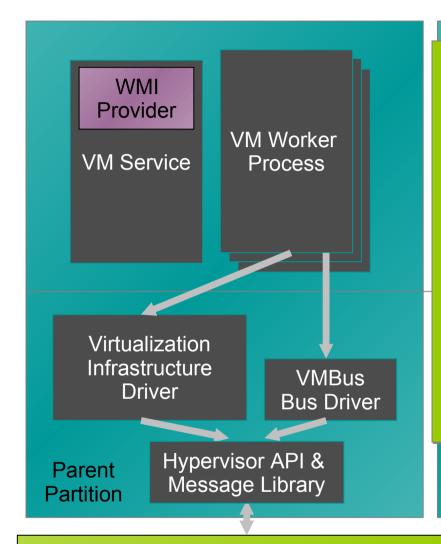
- Monolithic hypervisor
 - Simpler than a modern kernel, but still complex
 - Contains its own drivers model



- Microkernel based hypervisor
 - Simple partitioning functionality
 - Increase reliability and minimize TCB
 - No third-party code
 - Drivers run within guests



Virtualization Stack



- Collection of user-mode and kernel-mode components
 - Runs within a partition on top of a (minimal) OS
 - Contains all VM support not in the hypervisor
- Interacts with hypervisor
 - Calls the hypervisor to perform certain actions
 - Responds to messages from the hypervisor or from other partitions
- Creates and manages a group of "child partitions"
 - Manages memory for child partitions
 - Virtualizes devices for child partitions
- Exposes a management interface

Child Partition 1

Child Partition 2

Hypervisor

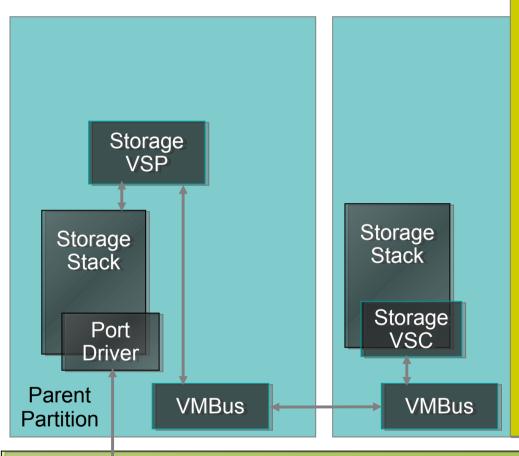


Device Virtualization

- Standard VSP (Virtualization service providers)
 - Storage: support difference drive chains
 - Network: provide virtualized network mechanism
 - Video: 2D/3D graphics w/ or w/o HW acceleration
 - USB: allow a USB device to be assigned to a partition
 - Input: keyboard, mouse, touchscreen
 - Time: virtualization for RTC hardware



Device Virtualization



- Physical devices
 - Managed by traditional driver stacks
- Virtualization service providers
 - Virtualize a specific class of device
 - Expose an abstract device interface
 - Run within the partition that owns the corresponding physical device
- Virtualization service clients
 - Consume virtualized hardware service
- VMBus
 - Software "bus" (enumeration, hot plug, etc.)
 - Enables VSPs and VSCs to communicate efficiently
 - Uses memory sharing and hypervisor IPC messages

Hypervisor





Embedded Virtualization Issues

- Memory footprint
- Security
 - Increases size of Trusted Computing Base
- Direct IO Access
- Emulate IO
- Virtual IO
- Real-time support



Direct I/O Access

- Guest can directly access physical IO without host involvement
 - Native speed
- IOMMU provides isolation and physical address translation (DMA)
 - Translation could be done with guest modifications
- Issues:
 - IOMMU required for DMA isolation
 - Limited by number of physical IO devices
 - Guests must have device drivers
 - What about legacy guests on new hardware?
 - Breaks migration
 - IRQ delivery and routing



Emulated I/O

- Host software emulates guest IO accesses
- Issues:
 - Must write software to (perfectly?) emulate hardware
 - Dramatic increase in IO latency
 - Host OS must have physical device drivers
 - · Device driver availability, licensing concerns



Virtual I/O

- No hardware at all, just inter-guest data transfer
- New guest device drivers co-operate with host
- Issues:
 - Requires guest modification (at least new device drivers)
 - Host OS still needs physical IO drivers



Embedded Hypervisors for ARM



Embedded Hypervisors for ARM

(open source part)

- Xen
 - Xen-arm, contributed by Samsung
 ARM9, ARM11, ARM Cortex-A9 MP
 - Xen-arm-cortext-a15, contributed by Citrix https://lkml.org/lkml/2011/11/29/265

ARM Cortex-A15

- OKL4 (from open to close source), OKLabs
- L4Linux, TU Desden
- KVM ARM porting
 - Columbia University
 - NTHU, Taiwan
- Xvisor: supports ARMv5, ARMv7, ARMv7+VE
- Codezero

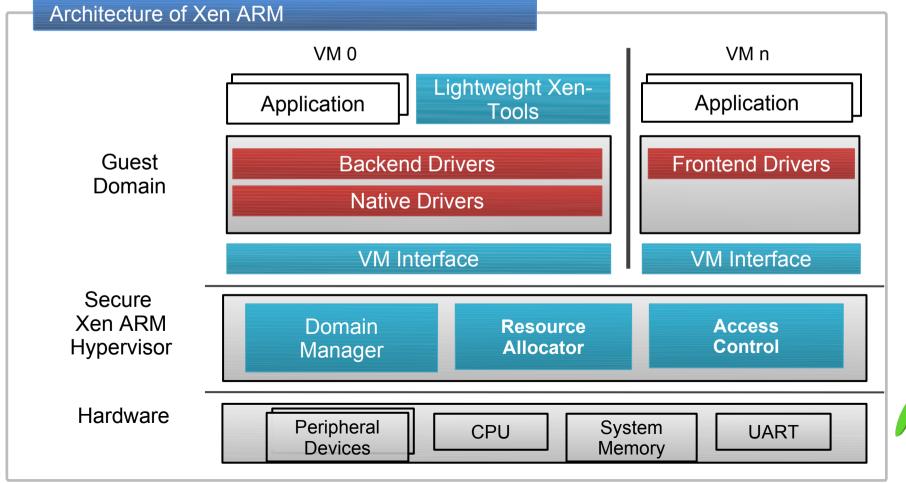


Xen-ARM (Samsung)

Goals

Lightweight virtualization for secure 3G/4G mobile devices

- High performance hypervisor based on ARM processor
- Fine-grained access control fitted to mobile devices





Xen-ARM (Samsung)

Logical

split

Xen ARM mode

virtual kernel mode

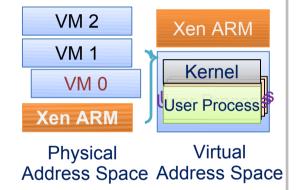
virtual user mode

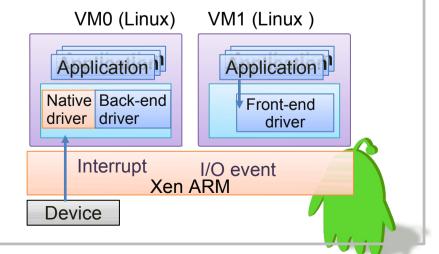
Overview

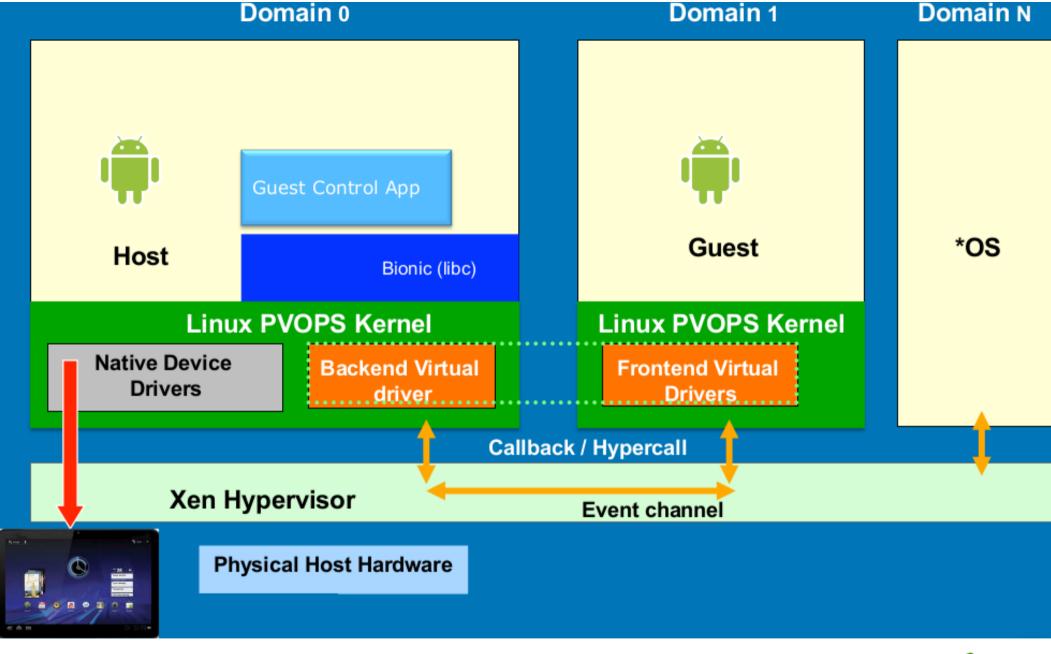
- CPU virtualization
- Virtualization requires 3 privilege CPU levels, but ARM supports 2 levels
 - Xen ARM mode: supervisor mode (most privileged level)
 - Virtual kernel mode: User mode (least privileged level)
 - Virtual user mode: User mode (least privileged level)
- Memory virtualization
- VM's local memory should be
- protected from other VMs
- Xen ARM switches VM's virtual address space
 - using MMU
 - VM is not allowed to manipulate MMU directly
- I/O virtualization
- Split driver model of Xen ARM
 - Client & Server architecture for shared I/O devices
 - Client: frontend driver
 - Server: native/backend driver





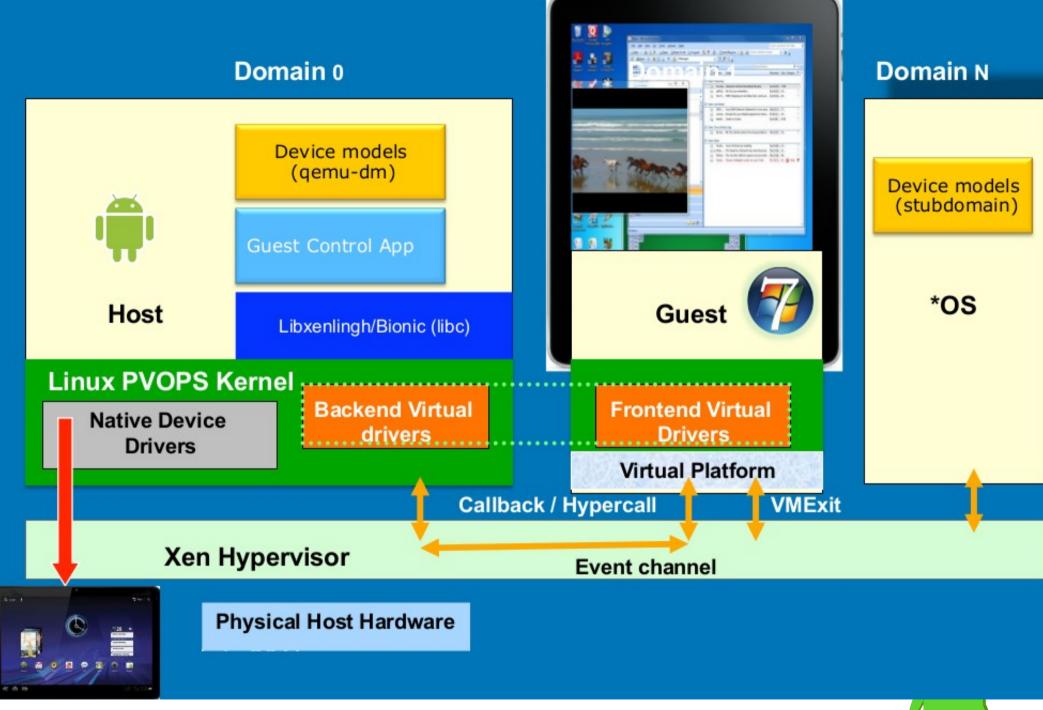






Xen without assisted hardware VM





Xen with assisted hardware VM

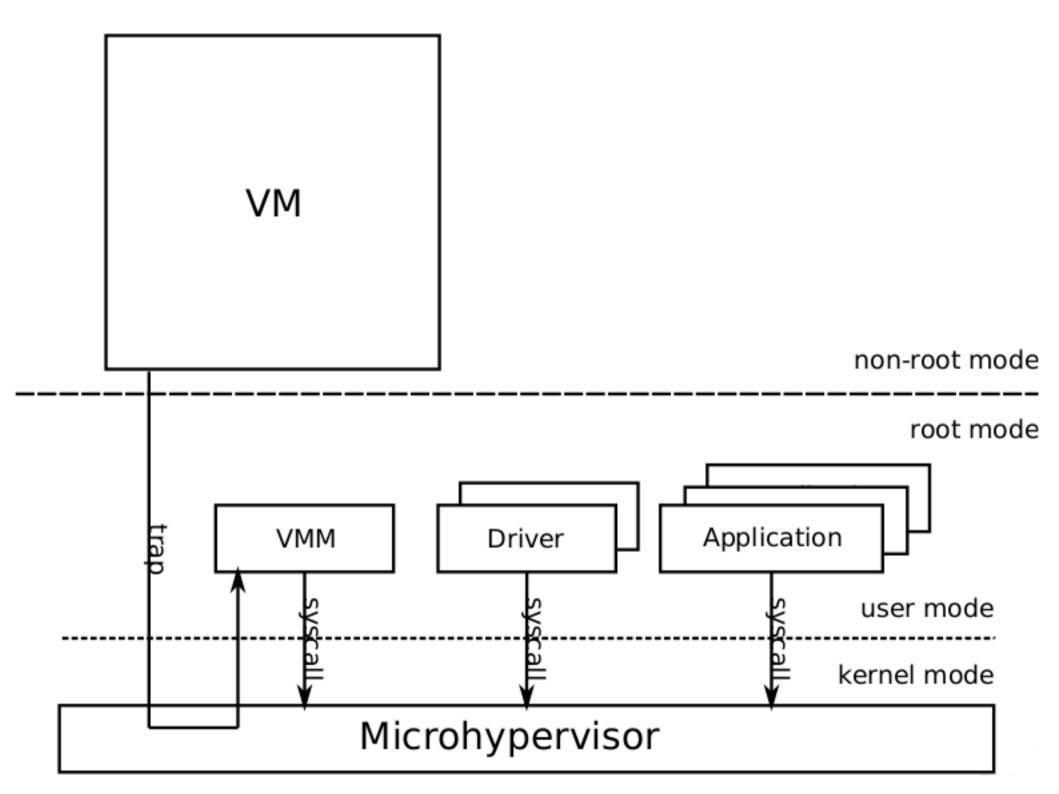


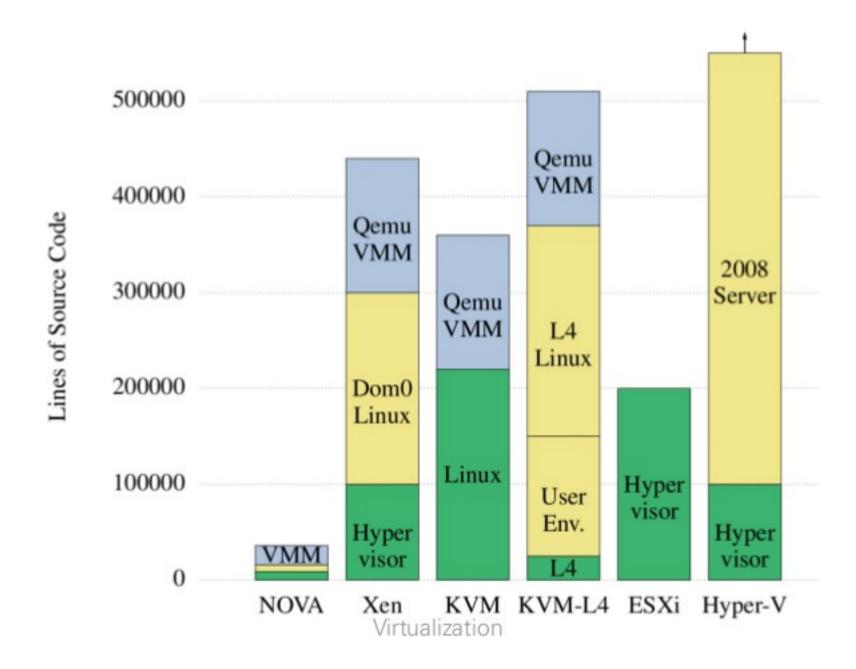
Micro-hypervisor

- Microvisor OKL4 4.0
- Research projects such as NOVA, Coyotos, and seL4
- Microhypervisor
 - "the kernel part"
 - provides isolation
 - mechanisms, no policies
 - enables safe access to
 - virtualization features to userspace

- VMM
 - "the userland part"
 - CPU emulation
 - device emulation









Source: VIRTUALIZATION, Julian Stecklina, TU Dresden

Advantage of NOA architecture: Reduce TCB of each VM

- Micro-hypervisor provides low-level protection domains
 - address spaces
 - virtual machines
- VM exits are relayed to VMM as IPC with selective guest state
- one VMM per guest in (root mode) userspace:
 - possibly specialized VMMs to reduce attack surface
 - only one generic VMM implemented



Reference

- 前瞻資訊科技一虛擬化, 薛智文, 台大資訊所 (2011)
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- Hardware accelerated Virtualization in the ARM Cortex™ Processors, John Goodacre, ARM Ltd. (2011)
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