Communication

Concurrency and Distributed Systems November 2023

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- Input and output
- Indexed parallel

Channels

Parameters in event names can serve two purposes:

- to represent data being passed;
- to indicate an event performed by a process instance.

They are written after a dot: c.v

Parameter expressions can take values from built-in or user-defined datatypes.

Built-in datatypes include sets and sequences.

compare: process parameters

Declarations

If c is a name and T is a type-valued expression, then

```
channel c : T
```

introduces the set of all events of the form c.t, where t is a value of type T.

We may introduce more than one channel in the same declaration: for example,

```
channel c, d : T
```

would introduce two channels c and d, both of type T.

Built-in datatypes

The built-in type Int represents the set of positive and negative integers: $-2^{31} + 1 ... 2^{31} - 1$.

The built-in type Bool represents the set of Boolean values: True and False.

Example

The following declaration introduces a channel insert that can carry any integer value

channel insert : Int

User-defined datatypes

The declaration

```
datatype NewType = name1 | name2 | name3
```

introduces

- a new datatype NewType
- three constants, name1, name2, and name3, as values of that datatype

Constructors

The declaration

datatype NewType = name1 | name2 | label.OtherType
introduces

- a new datatype NewType
- two constants, name1 and name2, as values of that datatype
- a set of values of the form label.t, where t is any value of the datatype Type

types may be recursive - Type may be NewType

```
datatype Tree = Leaf.Int | Node.Int.Tree.Tree

Leaf.3 :: Tree

Node.5.(Leaf.3).(Leaf.5) :: Tree
```

More components

An event on a channel may have several components. The definition

```
channel c : T . U
```

introduces a set of events

```
{ c.t.u | t <- T, u <- U }
```

```
Floor = {0..2}
datatype Person = pA | pB | pC
channel call : Floor . Person
```

Productions

If we wish to refer to the set of all events associated with a channel, then we may use the productions operator. If c is a channel, then

```
{| c |}
```

is the set of all events c.x matching the declaration of c.

More generally, if **c** is a channel with multiple components, then

is the set of all events c.t.x matching the declaration.

Input and output

If two or more processes share a channel then, for each component:

- some processes may allow any value
- some processes may insist on exactly one value

Input and output

If the transaction described by the channel occurs, then for each component

- all participating processes agree on the value chosen
- their future behaviour may depend upon that value

Input

If the transaction described by the channel occurs, then a process allowing any value for some component

- now has a value for that component to work with
- a value arising from the behaviour of the other components

Input

We may use an indexed external choice to describe a process that allows any value for a component.

If c is a channel declared as

and P is a process parameterised by values of type V, then

[]
$$v : V @ c.v -> P(v)$$

allows any event of the form c.v, and may be referred to as input on channel c.

Example

```
LiftController = ...
```

call?f?p -> ...

Input

We may use? to indicate an indexed external choice for a particular component of a channel.

If c is a channel declared as

channel c : V

and P is a process parameterised by values of type V, then

$$c?v \rightarrow P(v)$$

allows any event of the form c.v, and may be referred to as input on channel c.

if we want to allow only c.v for some subset W of V, then we can write $c?v:W \rightarrow P(v)$

Output

We may use! to indicate insistence upon a particular value for a particular component:

If c is a channel declared as

channel c : V

and P is a process, and E is an expression with value val of type V

 $c!E \rightarrow P$

will allow only the event c.val, and may be referred to as output on channel c.

```
datatype MotorInstruction = up | down | stop

channel motor : MotorInstruction

LiftController =
    ...
    motor!down -> ...
```

Output

For a single component, ! behaves exactly as (.).

However, for a channel with multiple components, the expression

denotes a process that will allow any value of x and any value of y: that is, an external choice over pairs of values.

If we wish to describe a process that will allow any value of one component but will insist upon a particular value for the next, then we need to use !.

$$c?x!y -> ...$$

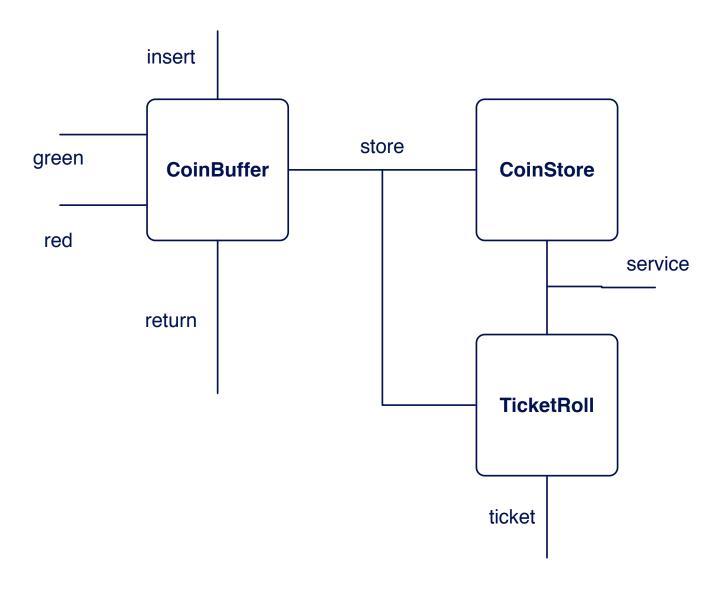
```
Person(pA) = ...
```

Example

```
channel insert : Coin
channel green, red, ticket
channel store, return : {0..400}
channel service

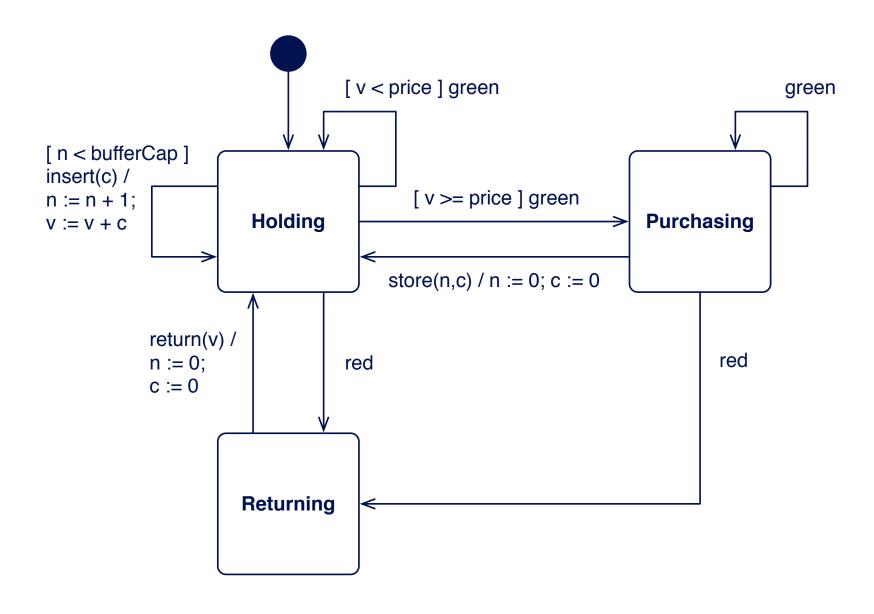
Coin = {10,20,50,100}
price = 100
bufferCap = 4
storeCap = 8
rollSize = 2
```

we write 0..400 rather than Int...



```
aCoinBuffer = {| insert, green, red, store, return |}
CoinBuffer =
  let
    Holding(n,v) =
      n < bufferCap &</pre>
        insert?c -> Holding(n+1,v+c)
      green -> ( if v >= price then
                   Purchasing(n,v)
                 else
           Holding(n,v))
      red -> Returning(v)
```

```
Purchasing(n,v) =
    green -> Purchasing(n,v)
    red -> Returning(v)
    store!n -> Holding(0,0)
  Returning(v) =
    return!v -> Holding(0,0)
within
  Holding(0,0)
```



```
aCoinStore = {| store, service |}

CoinStore = 
let
   Holding(m) = 
     store?n:{1..(storeCap-m)} -> Holding(m+n)
   []
   service -> Holding(0)

within
   Holding(0)
```

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```
aTicketRoll = {| store, service, ticket |}

TicketRoll =
  let
   Holding(t) =
     (t > 0) & store?n -> ticket -> Holding(t-1)
   []
   service -> Holding(rollSize)
  within
   Holding(rollSize)
```

```
TicketMachine =
  CoinBuffer
  [ aCoinBuffer || union(aCoinStore,aTicketRoll) ]
  ( CoinStore [ aCoinStore || aTicketRoll ] TicketRoll )
assert TicketMachine :[deadlock free]
TicketMachineWithoutService =
  TicketMachine [ aTicketMachine || {service} ] STOP
assert TicketMachineWithoutService : [deadlock free]
```

Scope

Our language of processes is declarative.

Each variable gets its value at the point at which it is declared, and retains that value for the scope of that declaration.

Indexed parallel

If P(x) is a process-valued expression with parameter x, and aP(x) is a set-valued expression with the same parameter, then

is a process that behaves as a combination of processes P(x), one for each value of x in X, in which

• events from aP(x) are allowed only when P(x) allows them

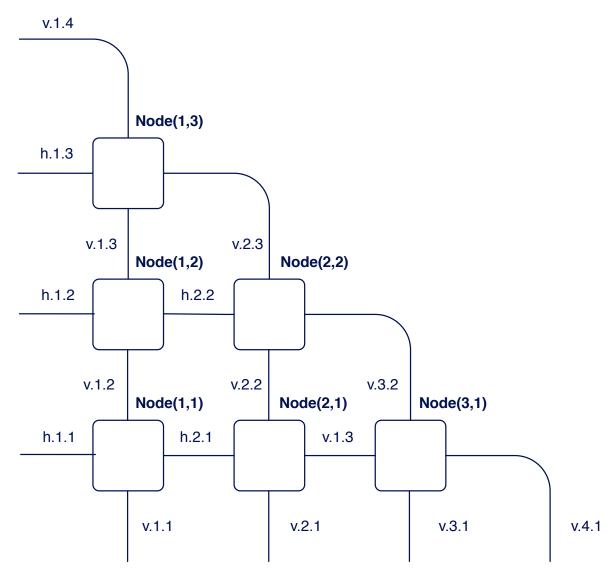
```
channel enterLift, exitLift: Floor . Person
aFloor(i) = {| enterLift.i, exitLift.i, ... |}
Floor(i) =
  let
    Holding(P) =
      enterLift!i?p:P -> ...
Floors = | | i : \{0...10\} @ [aFloor(i)] Floor(i)
```

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```
Node(i,j) =
h.i.j?x -> v.i.(j+1)?y -> v.i.j!min(x,y) ->
    if i + j == N then
       v.(i+1).j!max(x,y) -> Node(i,j)
    else
       h.(i+1).j!max(x,y) -> Node(i,j)
```

```
aNode(i,j) =
    {| h.i.j, v.i.(j+1), v.i.j,
        if i + j == N then v.(i+1).j else h.(i+1).j |}

Array(N) =
    || i : {1..N}, j : {1..N}, i+j <= N @ [aNode(i,j)] Node(i,j)</pre>
```



```
aInput = \{ | h.1.1, h.1.2, h.1.3, v.1.4 | \}
Input = h.1.1!4 \rightarrow h.1.2!3 \rightarrow h.1.3!2 \rightarrow v.1.4!1 \rightarrow Input
aOutput = \{ | v.1.1, v.2.1, v.3.1, v.4.1 | \}
Output = v.1.1!1 \rightarrow v.2.1!2 \rightarrow v.3.1!3 \rightarrow v.4.1!4 \rightarrow Output
aArray = \{ | v.i.j, h.i.j | i < \{1..4\}, j < \{1..4\} | \}
ArrayIO = (Input [ aInput || aArray ] Array(4))
                     [ aArray || aOutput ] Output
assert ArrayIO :[deadlock free]
```

Example

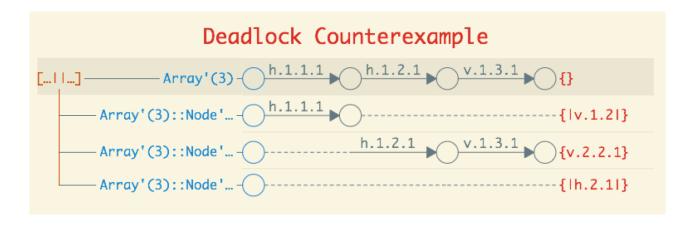
```
Node'(i,j) =
h.i.j?x -> v.i.(j+1)?y ->
if i + j == N then
    v.(i+1).j!max(x,y) -> v.i.j!min(x,y) -> Node'(i,j)
else
    h.(i+1).j!max(x,y) -> v.i.j!min(x,y) -> Node'(i,j)
```

alternative

Example

Deadlock Counterexample

$$[...]_{-+}^{-+}-Array'(3)-\underbrace{\begin{array}{c}h.1.1.1\\}\\h.1.2.1\end{array}}$$



Summary

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- Input and output
- Indexed parallel

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