# Concurrency

Concurrency and Distributed Systems January 2023

### **Contents**

- Parallel composition
- Deadlock
- Algebra

### Parallel composition

We can describe a concurrent combination of two processes using the parallel operator [ || ].

This operator takes four arguments. The two outer arguments are processes. The two inner arguments are sets of events.

The operator is commutative.

compare: external choice

### **Interpretation: Parallel**

If P and Q are process-valued expressions, and aP and aQ are set-valued expressions, then

is a process that behaves as a combination of P and Q in which

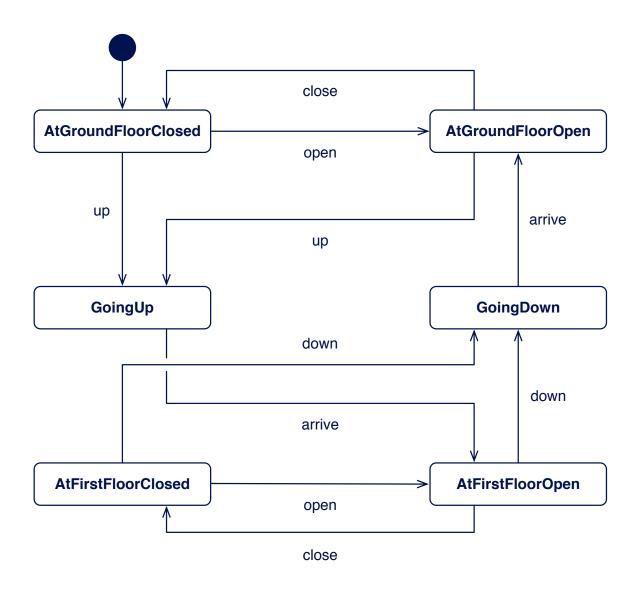
- events from aP are allowed only when P allows them
- events from aQ are allowed only when Q allows them

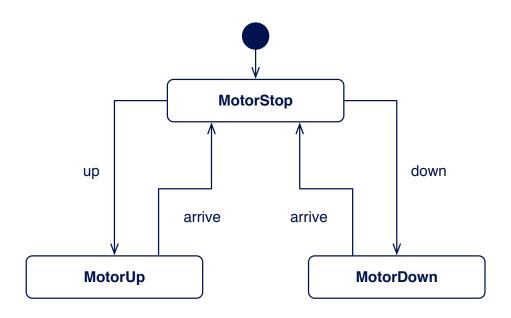
we call aP the alphabet of P

#### Step law: Parallel

```
If
  P = [] e : A @ e -> P(e)
  Q = [] e : B @ e -> Q(e)
with A < aP and B < aQ then
  P [aP || aQ]Q =
    ( [] e : diff(A,aQ) @ e -> P(e) [ aP || aQ ] Q )
    ( [] e : diff(B,aP) @ e -> P [ aP || aQ ] Q(e) )
    Π
    ( [] e : inter(A,B) @ e -> P(e) [ aP || aQ ] Q(e)
```

compare: external choice



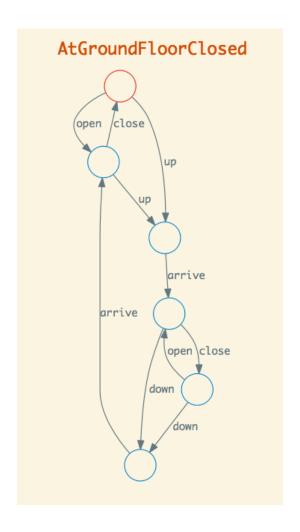


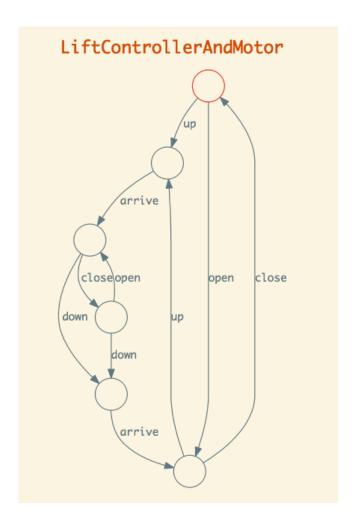
```
aLiftController = { up, down, open, close, arrive }
LiftController =
  AtGroundFloorClosed
AtGroundFloorClosed =
  open -> AtGroundFloorOpen
  up -> GoingUp
AtGroundFloorOpen =
  close -> AtGroundFloorClosed
  up -> GoingUp
```

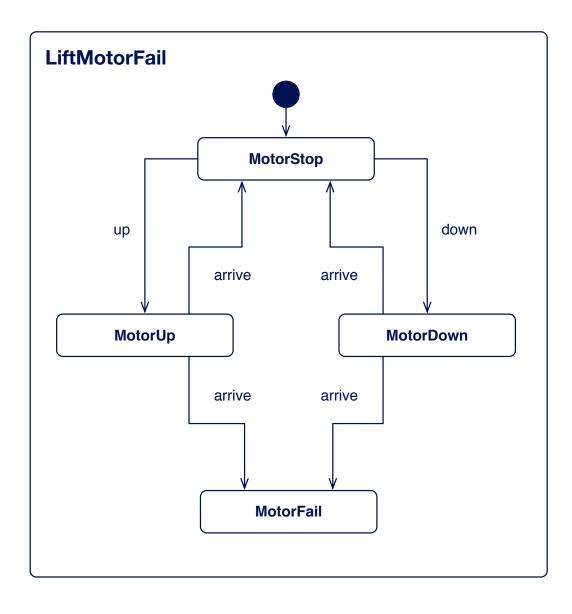
```
AtFirstFloorClosed =
  open -> AtFirstFloorOpen
  down -> GoingDown
AtFirstFloorOpen =
  close -> AtFirstFloorClosed
  down -> GoingDown
GoingUp = arrive -> AtFirstFloorOpen
GoingDown = arrive -> AtGroundFloorOpen
```

```
aLiftMotor = { up, down, arrive }
LiftMotor =
  let
   MotorStop =
      up -> MotorUp
      down -> MotorDown
   MotorUp = arrive -> MotorStop
   MotorDown = arrive -> MotorStop
 within
   MotorStop
```

```
LiftController [aLiftController || aLiftMotor] LiftMotor
= AtGroundFloorClosed
  [aLiftController || aLiftMotor]
  MotorStop
= open ->
   (AtGroundFloorOpen
    [aLiftController || aLiftMotor]
   MotorStop)
  up ->
   (GoingUp
    [aLiftController || aLiftMotor]
    MotorUp)
```



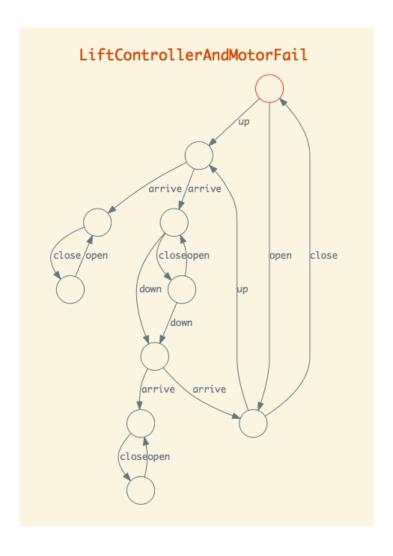


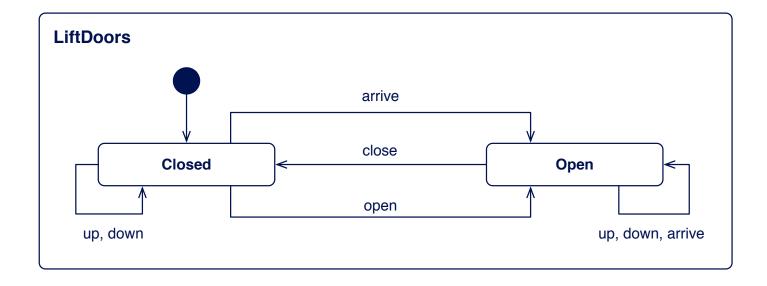


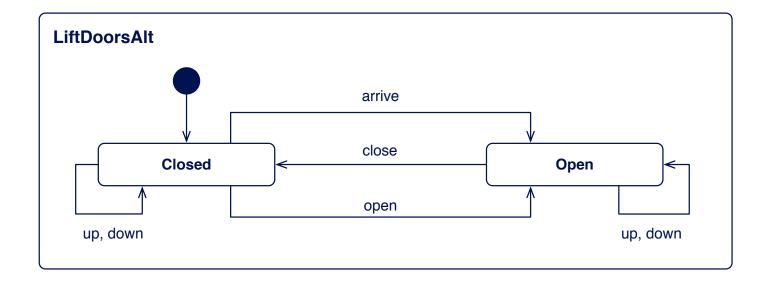
```
LiftMotorFail =
  let
    MotorStop =
      up -> MotorUp [] down -> MotorDown
    MotorUp =
      arrive -> MotorStop [] arrive -> MotorFail
    MotorDown =
      arrive -> MotorStop [] arrive -> MotorFail
   MotorFail = STOP
 within
   MotorStop
```

```
LiftController
[aLiftController || aLiftMotor]
LiftMotorFail

= open -> ...
[]
up ->
    (arrive ->
    ...
)
```







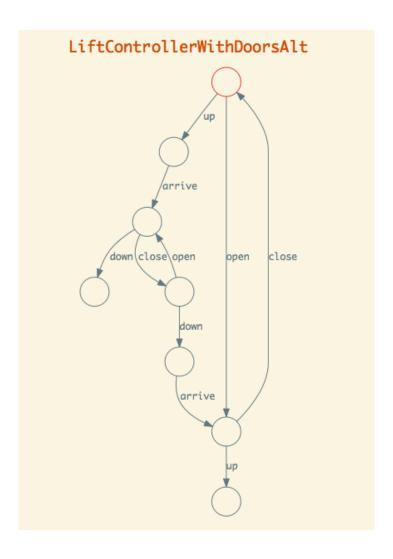
```
aLiftDoors = {open, arrive, up, down, close}
LiftDoors =
  let
    Closed =
      ( [] e : {open,arrive} @ e -> Open )
      ( [] e : {up,down} @ e -> Closed )
    Open =
      ( [] e : {up,down,arrive} @ e -> Open )
      ( close -> Closed )
 within
    Closed
```

```
LiftDoorsAlt =
  let
    Closed =
      ( [] e : {open,arrive} @ e -> Open )
      ( [] e : {up,down} @ e -> Closed )
    Open =
      ( [] e : {up,down} @ e -> Open )
      ( close -> Closed )
 within
    Closed
```

```
LiftController [ aLiftController || aLiftDoors ] LiftDoors
[F=
LiftController
LiftController
[F=
LiftController [ aLiftController || aLiftDoors ] LiftDoors
LiftController [ aLiftController || aLiftDoors ] LiftDoorsAlt
?
```

```
LiftController
[ aLiftController || aLiftDoors ]
LiftDoorsAlt
AtGroundFloorClosed
[ aLiftController || aLiftDoors ]
Open
open -> ... [] up -> ...
[ aLiftController || aLiftDoors ]
close -> ... [] up -> ... [] down -> ...
up ->
 (GoingUp
  [ aLiftController || aLiftDoors ]
  Open)
```

```
up ->
  (arrive -> ...
  [ aLiftController || aLiftDoors ]
  close -> ... [] up -> ... [] down -> ...
  )
=
up -> STOP
```



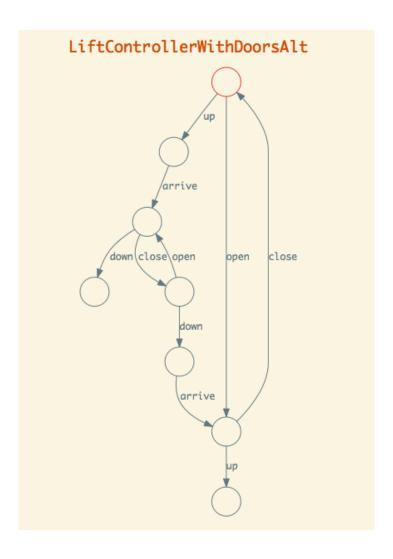
#### **Deadlock**

If P is a process-valued expression, then we may use the following assertion to check whether P can reach a state in which no further events are allowed:

```
assert P :[deadlock free]
```

```
assert LiftControllerAndMotor
  :[deadlock free]
assert LiftControllerAndMotorFail
  :[deadlock free]
assert LiftControllerWithDoors
  :[deadlock free]
assert LiftControllerWithDoorsAlt
  :[deadlock free]
```

LiftControllerAndMotor :[deadlock free] Finished: Passed	?
LiftControllerAndMotorFail :[deadlock free]     Finished: Passed	?
LiftControllerWithDoors :[deadlock free] Finished: Passed	?
LiftControllerWithDoorsAlt :[deadlock free]     Finished: Failed	?
Debug	



### **Algebra**

### **Distributive**

```
P [ aP || aQR ] (Q |~| R)
=
(P [ aP || aQR ] Q) |~| (P [ aP || aQR ] R)
```

```
aHelpful = aAwkward = { goOut, stayIn } = A
Helpful = goOut -> STOP [] stayIn -> STOP

Awkward = goOut -> STOP |~| stayIn -> STOP
```

```
Helpful [ A || A ] Helpful =
  goOut -> STOP
  stayIn -> STOP
Helpful [ A || A ] Awkward =
  goOut -> STOP
  stayIn -> STOP
Awkward [ A || A ] Awkward =
  goOut -> STOP
  stayIn -> STOP
  STOP
```

```
Helpful [ A || A ] Helpful =
   Helpful
Helpful [ A || A ] Awkward =
   Awkward

Awkward [ A || A ] Awkward =
   Awkward
| ~ |
   STOP
```

```
External [ A || A ] External =
   External

External [ A || A ] Internal =
   Internal

Internal [ A || A ] Internal =
   Internal [ A || A ] Internal =
   Internal
   | ~ |
   STOP
```

### **Summary**

- Parallel composition
- Deadlock
- Algebra

#### Index

- 2 Contents
- 3 Parallel composition
- 4 Interpretation: Parallel
- 5 Step law: Parallel
- 6 Example
- 7 Example
- 8 Example
- 9 Example
- 10 Example
- 11 Example
- 12 Example

- 13 Example
- 14 Example
- 15 Example
- 16 Example
- 17 Example
- 18 Example
- 19 Example
- 20 Example
- 21 Example
- 24 Example
- 25 Deadlock
- 26 Example
- 27 Example

- 28 Example
- 29 Algebra
- 30 Distributive
- 31 Example
- 35 Summary
- 36 Index