

Linear Equations in Linear Algebra

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- 1 Systems of Linear Equations
- 2 Row Reduction and Echelon Forms
- 3 Vector Equations
- 4 The Matrix Equation $Ax = b$
- 5 Solution Sets of Linear Systems
- 6 Applications of Linear Systems
- 7 Linear Independence

Definition

An indexed set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in \mathbb{R}^n is said to be **linearly independent** if the vector equation

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \dots + x_p\mathbf{v}_p = \mathbf{0} , \quad (1)$$

has only the **trivial solution**. The set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is said to be **linearly dependent** if there exist weights c_1, \dots, c_p , **not all zero**, such that

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_p\mathbf{v}_p = \mathbf{0} . \quad (2)$$

Equation (2) is called a linear dependence relation among $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ when the weights are not all zero. An indexed set is linearly dependent if and only if it is not linearly

independent. $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ are linearly dependent when we mean that $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is a linearly dependent set.

7.1 Linear Independence of Matrix Columns

The matrix equation $A\mathbf{x} = \mathbf{0}$ can be written as

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{0} . \quad (3)$$

Each linear dependence relation among the columns of A corresponds to a nontrivial solution of $A\mathbf{x} = \mathbf{0}$.

The columns of a matrix A are linearly independent if and only if the equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.

7.2 Sets of One or Two Vectors

A set of two vectors $\{\mathbf{v}_1, \mathbf{v}_2\}$ is linearly dependent if at least one of the vectors is a multiple of the other. The set is linearly independent if and only if neither of the vectors is a multiple of the other.

7.3 Sets of Two or More Vectors

Characterization of Linearly Dependent Sets

An indexed set $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of two or more vectors is linearly dependent if and only if at least one of the vectors in S is a linear combination of the others. In fact, if S is linearly dependent and $\mathbf{v}_1 \neq \mathbf{0}$, then some \mathbf{v}_j (with $j > 1$) is a linear combination of the preceding vectors, $\mathbf{v}_1, \dots, \mathbf{v}_{j-1}$.

Theorem

If a set contains more vectors than there are entries in each vector, then the set is linearly dependent. That is, any set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in \mathbb{R}^n is linearly dependent if $p > n$.

Theorem

If a set $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in \mathbb{R}^n contains the zero vector, then the set is linearly dependent.

8 Introduction to Linear Transformations

Solving the equation $A\mathbf{x} = \mathbf{b}$ amounts to finding all vectors \mathbf{x} in \mathbb{R}^4 that are transformed into the vector \mathbf{b} in \mathbb{R}^2 under the “action” of multiplication by A .

A **transformation** (or **function** or **mapping**) T from \mathbb{R}^n to \mathbb{R}^m is a rule that assigns to each vector \mathbf{x} in \mathbb{R}^n a vector $T(\mathbf{x})$ in \mathbb{R}^m . The set \mathbb{R}^n is called the **domain** of T , and \mathbb{R}^m is called the **codomain** of T . The notation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ indicates that the domain of T is \mathbb{R}^n and the codomain is \mathbb{R}^m . For \mathbf{x} in \mathbb{R}^n , the vector $T(\mathbf{x})$ in \mathbb{R}^m is called the **image** of \mathbf{x} (under the action of T). The set of all images $T(\mathbf{x})$ is called the **range** of T .

8.1 Matrix Transformations

9 The Matrix of a Linear Transformation

10 Linear Models in Business, Science, and Engineering