

8-bit Proprietary Microcontrollers

CMOS

F²MC-8FX MB95R203

MB95R203

■ DESCRIPTION

The MB95R203 is general-purpose, single-chip microcontrollers. In addition to a compact instruction set, the microcontrollers contain a variety of peripheral functions.

Note : F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- F²MC-8FX CPU core
 - Instruction set optimized for controllers
 - Multiplication and division instructions
 - 16-bit arithmetic operations
 - Bit test branch instruction
 - Bit manipulation instructions etc.
- Clock
 - Selectable Main clock source
 - Main OSC clock (Up to 10 MHz, Maximum Machine clock frequency is 5 MHz)
 - External clock (Up to 20 MHz, Maximum Machine clock frequency is 10 MHz)
 - Internal main CR clock (Typ 1 MHz, Machine clock frequency is 1 MHz)
 - Selectable Sub clock source
 - Sub OSC clock (32 kHz)
 - Sub internal CR clock (Typ : 100 kHz, Min : 50 kHz, Max : 200 kHz)

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- Timer
 - 8/16-bit composite timer
 - Timebase timer
 - Watch prescaler
- UART/SIO
 - Offers clock asynchronous (UART) or clock synchronous (SIO) serial data transfer
 - Full duplex double buffer
- I²C
 - Built-in wake-up function
- External interrupt
 - Interrupt by the edge detection (Select rising edge/falling edge/both edges)
 - Can be used to recover from low-power consumption modes (also called standby mode)
- 8/10-bit A/D converter
 - 8-bit or 10-bit resolutions can be selected
- Low-power consumption (standby) mode
 - Stop mode
 - Sleep mode
 - Watch mode
 - Timebase timer mode
- I/O port : Max 16
 - General-purpose I/O ports (Max) :
CMOS I/O : 12, N-ch open drain : 4
- On-chip debug
 - 1 wire serial control
 - Support serial writing. (Asynchronous mode)
- Hardware/Software watchdog timer
 - Built-in Hardware watchdog timer
- Low voltage detection circuit (LVD)
 - Low voltage detection reset circuit
 - Circuit to monitor FRAM power supply
- Clock supervisor counter (CSV)
 - Built-in Clock supervise function
- Programmable input voltage levels of port
 - CMOS input level / hysteresis input level
- FRAM
 - Non-volatile memory
 - 8 Kbytes of FRAM integrated on-chip
- FRAM memory security function
 - Protects the content of FRAM memory

■ PRODUCT OVERVIEW

Part number	MB95R203
Parameter	
ROM (FRAM) capacity	8 Kbytes
RAM capacity	496 bytes
Reset output	Yes
Low voltage detection	Yes
CPU function	Number of basic instructions : 136 instructions Instruction bit length : 8 bits Instruction length : 1 to 3 bytes Data bit length : 1, 8, and 16 bits Minimum instruction execution time : 300 ns (at machine clock 10 MHz) Interrupt processing time : 1.7 μ s (at machine clock 10 MHz)
Port	General-purpose I/O ports (Max) : 16 CMOS I/O : 12, N-ch open drain : 4
Timebase timer	Interrupt cycle : 0.256 ms to 8.3 s (at external 4 MHz)
Hardware/software Watchdog timer	Reset generation cycle Main clock at 10 MHz : 105 ms (Min) Subclock CR can be used as the Watchdog source clock.
Wild registers	It can be used to replace three bytes of data.
UART/SIO	Able to transfer data using UART/SIO Variable data length (5/6/7/8-bit) , built-in baud rate generator Transfer rate (2400 bps to 125000 bps at 10 MHz) , full-duplex transfers with built-in double buffers NRZ type transfer format, error detection function LSB-first or MSB-first can be selected Capable of clock synchronous (SIO) or clock asynchronous (UART) serial data transfer
I ² C bus	Transmit and receive master/slave Bus function, arbitration function, transfer direction detection function Start condition repeated generation and detection functions Built-in timeout detection function
8/10-bit A/D converter	6 ch 8-bit or 10-bit resolution can be selected
8/16-bit composite timer	2 ch Can be configured as a 2 ch \times 8-bit timer or 1 ch \times 16-bit timer Built-in timer function, PWC function, PWM function and capture function Count clock : available from internal clocks (7 types) or external clocks With square wave output
External interrupt	6 ch Interrupt by edge detection (Select rising edge/falling edge/both edges) Can be used to recover from standby modes
On-chip debug	1 wire serial control Support serial writing. (Asynchronous mode)

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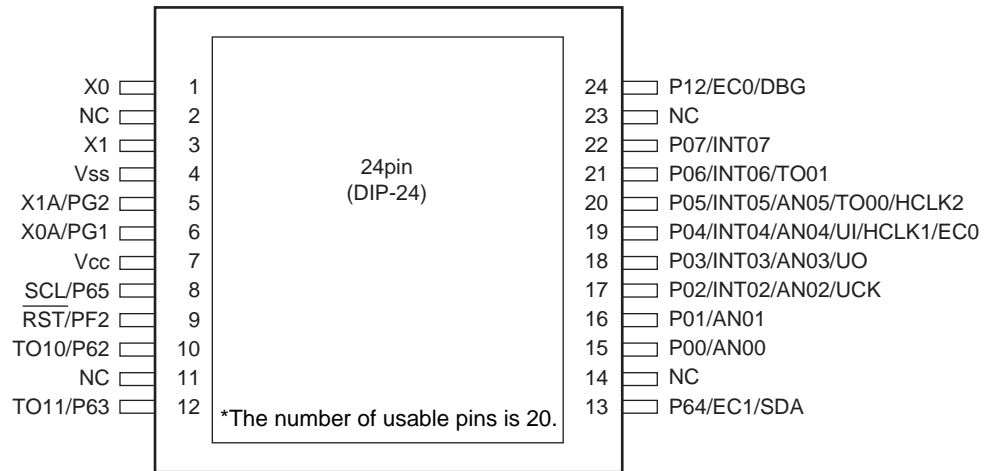
MB95R203

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Parameter \ Part number	MB95R203
Watch prescaler	Eight different time intervals can be selected.
FRAM	Non-volatile memory Number of read/write cycles : (Min)10 ¹⁰ times (Typ)10 ¹¹ times Data retention characteristics : 10 years (+ 55 °C) Read security function Function to monitor FRAM power supply
Standby Mode	Sleep mode, Stop mode, Watch mode, timebase timer mode
Package	SDIP-24, SOP-20

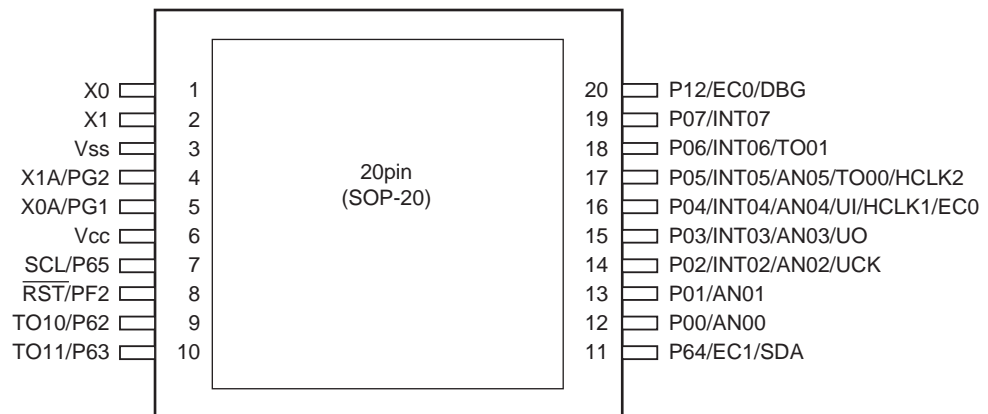
PIN ASSIGNMENT

(TOP VIEW)



(DIP-24P-M07)

(TOP VIEW)



(FPT-20P-M09)

■ PIN DESCRIPTION

Pin no.		Pin name	I/O Circuit type*	Function
SDIP24	SOP20			
1	1	X0	B	Main clock input oscillation pin
3	2	X1	B	Main clock input/output oscillation pin
4	3	Vss	—	Power supply pin (GND)
5	4	PG2/X1A	C	General-purpose I/O port This pin is also used as Sub clock input/output oscillation pin.
6	5	PG1/X0A	C	General-purpose I/O port This pin is also used as Sub clock input oscillation pin.
7	6	Vcc	—	Power supply pin
8	7	P65/SCL	I	General-purpose I/O port This pin is also used as I ² C clock I/O.
9	8	PF2/ $\overline{\text{RST}}$	A	General-purpose I/O port This pin is also used as reset pin
10	9	P62/TO10	D	General-purpose I/O port High current port This pin is also used as 8/16-bit composite timer ch.1 output.
12	10	P63/TO11	D	General-purpose I/O port This pin is also used as 8/16-bit composite timer ch.1 output. High current port
13	11	P64/SDA/EC1	I	General-purpose I/O port This pin is also used as I ² C data I/O. This pin is also used as 8/16-bit composite timer ch.1 clock input.
15	12	P00/AN00	E	General-purpose I/O port This pin is also used as A/D converter analog input.
16	13	P01/AN01	E	General-purpose I/O port This pin is also used as A/D converter analog input.
17	14	P02/INT02/AN02/ UCK	E	General-purpose I/O port This pin is also used as external interrupt input. This pin is also used as A/D converter analog input. This pin is also used as UART/SIO clock I/O.
18	15	P03/INT03/AN03/ UO	E	General-purpose I/O port This pin is also used as external interrupt input. This pin is also used as A/D converter analog input. This pin is also used as UART/SIO data output.
19	16	P04/INT04/AN04/ UI/HCLK1/EC0	F	General-purpose I/O port This pin is also used as external interrupt input. This pin is also used as A/D converter analog input. This pin is also used as UART/SIO data input. This pin is also used as 8/16-bit composite timer ch.0 clock input.

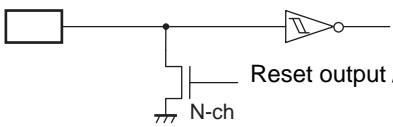
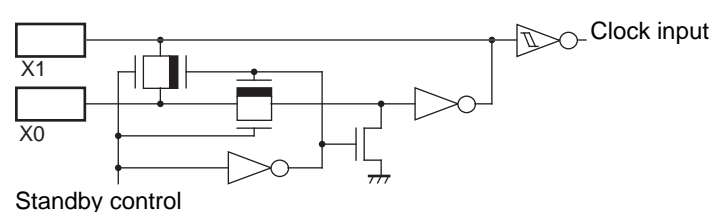
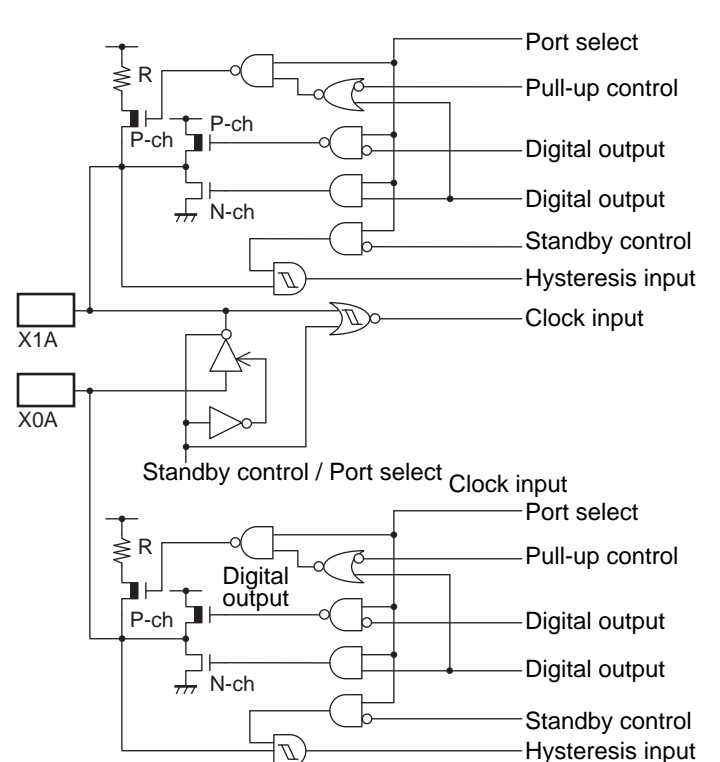
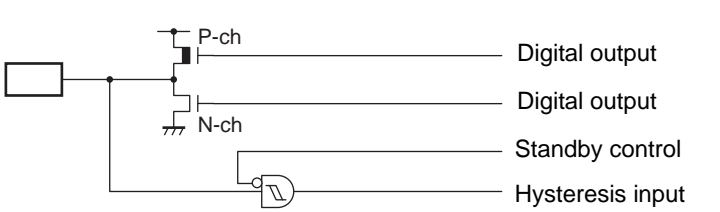
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Pin no.		Pin name	I/O Circuit type*	Function
SDIP24	SOP20			
20	17	P05/INT05/AN05/ TO00/HCLK2	E	General-purpose I/O port This pin is also used as external interrupt input. This pin is also used as A/D converter analog input. The pins are also used as 8/16-bit compound timer ch.0 output. This pin is also used as the external clock input.
21	18	P06/INT06/TO01	G	General-purpose I/O port High current port This pin is also used as external interrupt input. This pin is also used as 8/16-bit compound timer ch.0 output.
22	19	P07/INT07	G	General-purpose I/O port This pin is also used as external interrupt input.
24	20	P12/EC0/DBG	H	General-purpose I/O port This pin is also used as DBG input pin. This pin is also used as 8/16-bit composite timer ch.0 clock input.
2, 11, 14, 23	—	NC	—	Internal connect pin. Be sure this pin is left open.

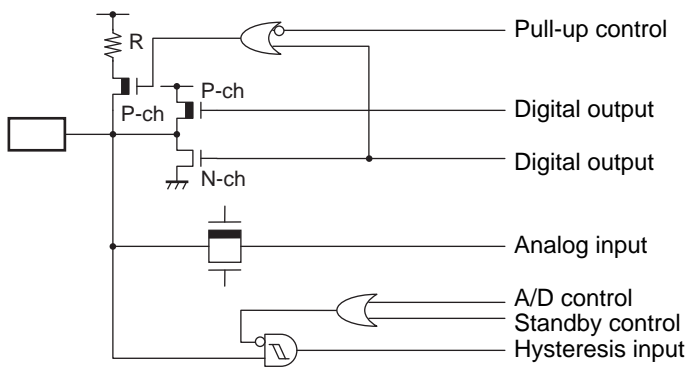
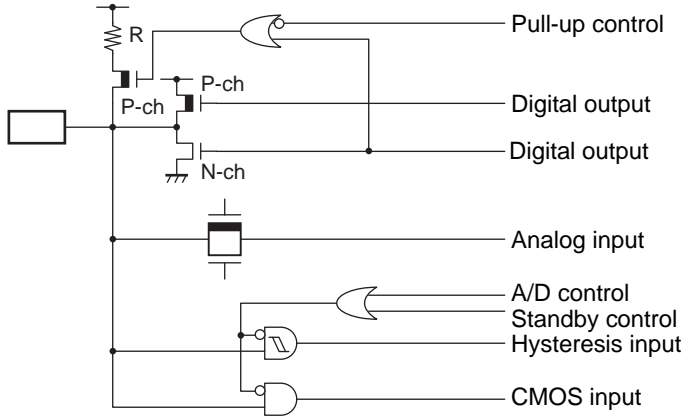
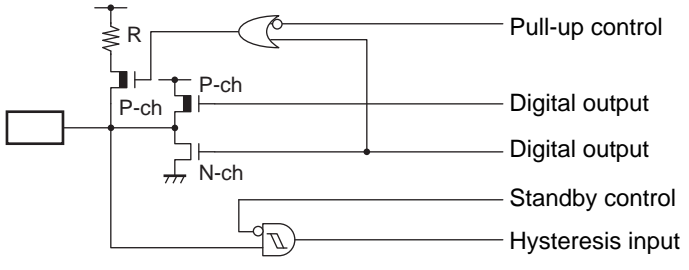
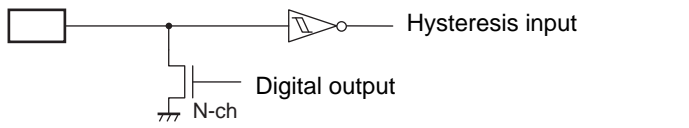
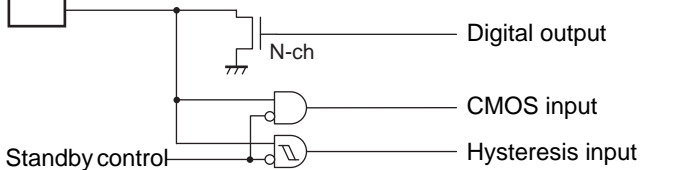
* : For the I/O circuit type, refer to “■ I/O CIRCUIT TYPE”.

■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A		<ul style="list-style-type: none"> • N-ch open drain output • Hysteresis input • Reset output
B		<ul style="list-style-type: none"> • Oscillation circuit • High-speed side Feedback resistance : approx. 1 MΩ • CMOS output • Hysteresis input
C		<ul style="list-style-type: none"> • Oscillation circuit • Low-speed side Feedback resistance : approx. 10 MΩ • CMOS output • Hysteresis input • With pull-up control
D		<ul style="list-style-type: none"> • CMOS output • Hysteresis input

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Type	Circuit	Remarks
E	 <p>Pull-up control</p> <p>Digital output</p> <p>Digital output</p> <p>Analog input</p> <p>A/D control</p> <p>Standby control</p> <p>Hysteresis input</p>	<ul style="list-style-type: none"> • CMOS output • Hysteresis input • With pull-up control
F	 <p>Pull-up control</p> <p>Digital output</p> <p>Digital output</p> <p>Analog input</p> <p>A/D control</p> <p>Standby control</p> <p>Hysteresis input</p> <p>CMOS input</p>	<ul style="list-style-type: none"> • CMOS output • Hysteresis input • CMOS input • With pull-up control
G	 <p>Pull-up control</p> <p>Digital output</p> <p>Digital output</p> <p>Standby control</p> <p>Hysteresis input</p>	<ul style="list-style-type: none"> • Hysteresis input • CMOS output • With pull-up control
H	 <p>Hysteresis input</p> <p>Digital output</p> <p>N-ch</p>	<ul style="list-style-type: none"> • N-ch open drain output • Hysteresis input
I	 <p>Digital output</p> <p>CMOS input</p> <p>Hysteresis input</p> <p>Standby control</p> <p>N-ch</p>	<ul style="list-style-type: none"> • N-ch open drain output • CMOS input • Hysteresis input

■ NOTES ON DEVICE HANDLING

- Preventing Latch-up

Care must be taken to ensure that maximum voltage ratings are not exceeded when they are used.
Latch-up may occur on CMOS ICs if voltage higher than V_{CC} or lower than V_{SS} is applied to input and output pins other than medium- and high-withstand voltage pins or if higher than the rating voltage is applied between V_{CC} pin and V_{SS} pin.
When latch-up occurs, power supply current increases rapidly and might thermally damage elements.
- Stable Supply Voltage

Supply voltage should be stabilized.
A sudden change in power-supply voltage may cause a malfunction even within the guaranteed operating range of the V_{CC} power-supply voltage.
For stabilization, in principle, keep the variation in V_{CC} ripple (p-p value) in a commercial frequency range (50 Hz / 60 Hz) not to exceed 10% of the standard V_{CC} value and suppress the voltage variation so that the transient variation rate does not exceed 0.1 V/ms during a momentary change such as when the power supply is switched.
- Precautions for Use of External Clock

Even when an external clock is used, oscillation stabilization wait time is required for power-on reset, wake-up from sub clock mode or stop mode.
- Do not use a sample used in program development as mass-produced product.

■ PIN CONNECTION

• Treatment of Unused Input Pin

Leaving unused input pins unconnected can cause abnormal operation or latch-up, leaving to permanent damage. Unused input pins should always be pulled up or down through resistance of at least 2 k Ω . Any unused input/output pins may be set to output mode and left open, or set to input mode and treated the same as unused input pins. If there is unused output pin, make it to open.

• Power Supply Pins

In products with multiple V_{CC} or V_{SS} pins, the pins of the same potential are internally connected in the device to avoid abnormal operations including latch-up. However, you must connect the pins to external power supply and a ground line to lower the electro-magnetic emission level, to prevent abnormal operation of strobe signals caused by the rise in the ground level, and to conform to the total output current rating.

Moreover, connect the current supply source with the V_{CC} and V_{SS} pins of this device at the low impedance. It is also advisable to connect a ceramic bypass capacitor of approximately 0.1 μ F between V_{CC} and V_{SS} near this device.

• DBG Pin

Connect the DBG pin directly to external Pull-up.

To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the DBG pins to V_{CC} or V_{SS} pins.

The DBG pin should not stay at "L" level after power-on until the reset output is released.

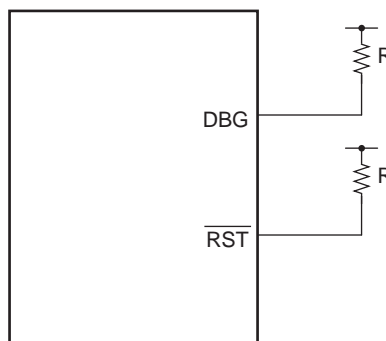
• \overline{RST} Pin

Connect the \overline{RST} pin directly to Pull-up.

To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the \overline{RST} pins to V_{CC} or V_{SS} pins.

The \overline{RST} /PF2 pin functions as the reset input/output pin after power-on. In addition, the reset output can be enabled by the RSTOE bit of the SYSC register, and the reset input function or the general purpose I/O function can be selected by the RSTEN bit of the SYSC register.

• Example of DBG / \overline{RST} connection diagram



Pull-up resistor recommended resistance

For DBG pin : $R = 4.7 \text{ k}\Omega$

For \overline{RST} pin : $R = 10 \text{ k}\Omega$

■ RESTRICTIONS

- Data written to FRAM before IR reflow is not guaranteed to retain after IR reflow.
(Data written to FRAM might be broken by heat processing at IR reflow.)

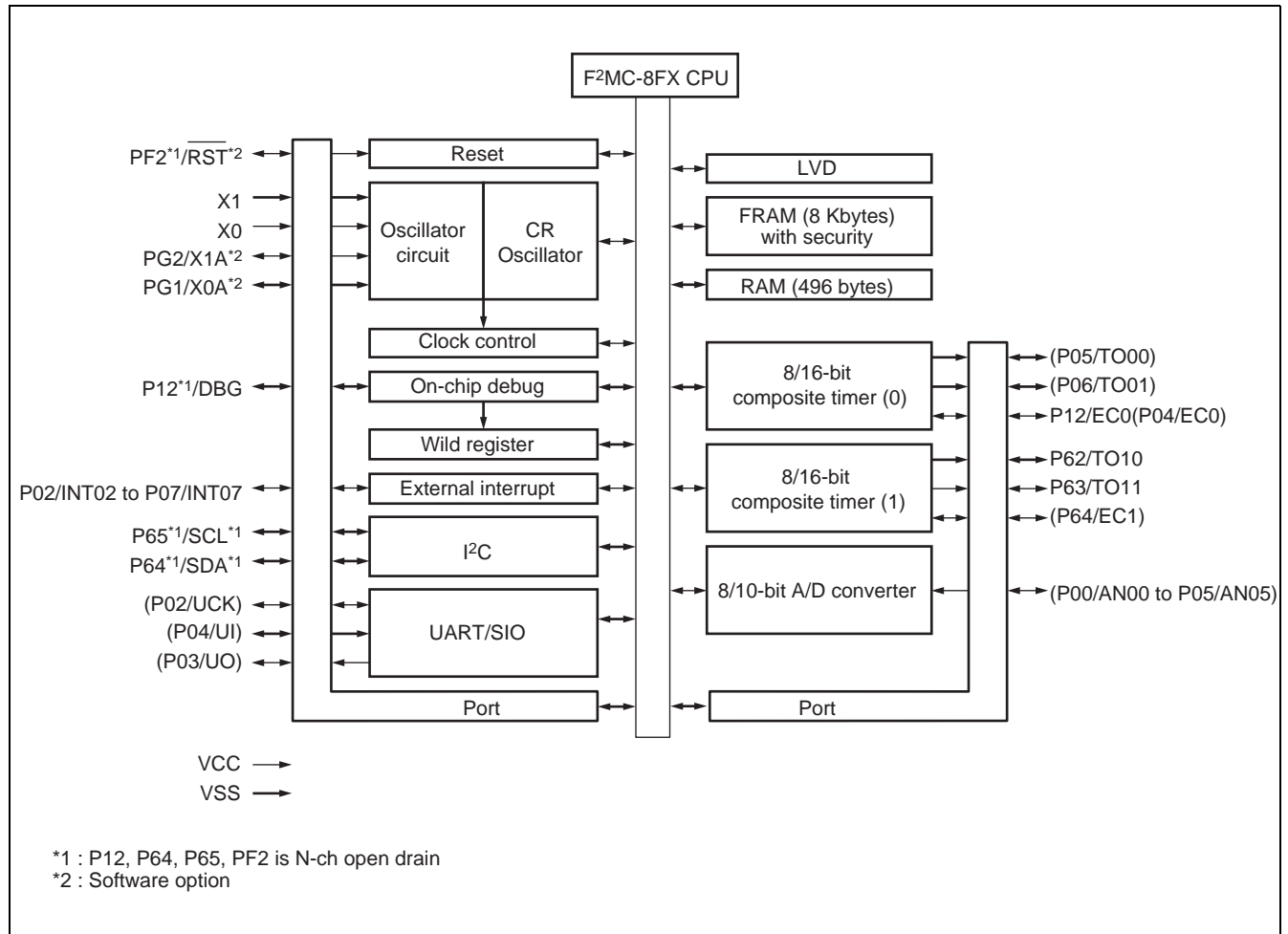
■ NOTES ON DEBUG

- Although the [Upload Flash Memory] button is enabled, clicking it does not start the actual processing.
- When you click on the [Erase Flash Memory] button on SOFTUNE Workbench, data is overwritten into the FRAM area, as shown below.

Address	Data to be overwritten
F554 _H	55 _H
FAAA _H	A0 _H
FFBC _H	Indeterminate
FFBD _H	Indeterminate
Entire FRAM except the above	FF _H

- Be very careful not to apply voltages to the pins PF2/ $\overline{\text{RST}}$ in excess of the absolute maximum ratings. Especially when handling devices in the environment compatible to the package, such as MB95F200H/210H and so on, the voltage may be erroneously applied to the pins PF2/ $\overline{\text{RST}}$ in excess of the maximum rating and it may cause thermal breakdown of the device.

■ BLOCK DIAGRAM



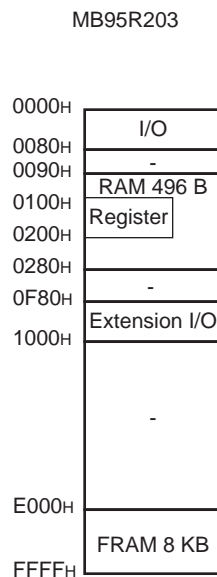
MB95R203

■ CPU CORE

1. Memory space

Memory space of the MB95R203 is 64 Kbytes and consists of I/O area, data area, and program area. The memory space includes special-purpose areas such as the general-purpose registers and vector table. Memory map of the MB95R203 shown below.

- Memory Map



■ I/O MAP

Address	Register abbreviation	Register name	R/W	Initial value
0000 _H	PDR0	Port 0 data register	R/W	00000000 _B
0001 _H	DDR0	Port 0 direction register	R/W	00000000 _B
0002 _H	PDR1	Port 1 data register	R/W	00000000 _B
0003 _H	DDR1	Port 1 direction register	R/W	00000000 _B
0004 _H	—	(disabled)	—	—
0005 _H	WATR	Oscillation stabilization wait time setting register	R/W	11111111 _B
0006 _H	—	(disabled)	—	—
0007 _H	SYCC	System clock control register	R/W	XXXXXX11 _B
0008 _H	STBC	Standby control register	R/W	00000XXX _B
0009 _H	RSRR	Reset source register	R	XXXXXXXX _B
000A _H	TBTC	Timebase timer control register	R/W	00000000 _B
000B _H	WPCR	Watch prescaler control register	R/W	00000000 _B
000C _H	WDTC	Watchdog timer control register	R/W	00000000 _B
000D _H	SYCC2	System clock control register 2	R/W	XX100011 _B
000E _H to 0015 _H	—	(disabled)	—	—
0016 _H	PDR6	Port 6 data register	R/W	00000000 _B
0017 _H	DDR6	Port 6 direction register	R/W	00000000 _B
0018 _H to 0027 _H	—	(disabled)	—	—
0028 _H	PDRF	Port F data register	R/W	00000000 _B
0029 _H	DDRF	Port F direction register	R/W	00000000 _B
002A _H	PDRG	Port G data register	R/W	00000000 _B
002B _H	DDRG	Port G direction register	R/W	00000000 _B
002C _H	PUL0	Port 0 pull-up register	R/W	00000000 _B
002D _H to 0034 _H	—	(disabled)	—	—
0035 _H	PULG	Port G pull-up register	R/W	00000000 _B
0036 _H	T01CR1	8/16-bit compound timer 01 control status register 1 ch.0	R/W	00000000 _B
0037 _H	T00CR1	8/16-bit compound timer 00 control status register 1 ch.0	R/W	00000000 _B
0038 _H	T11CR1	8/16-bit compound timer 11 control status register 1 ch.1	R/W	00000000 _B
0039 _H	T10CR1	8/16-bit compound timer 10 control status register 1 ch.1	R/W	00000000 _B

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Address	Register abbreviation	Register name	R/W	Initial value
003A _H to 0048 _H	—	(disabled)	—	—
0049 _H	EIC10	External interrupt circuit control register ch.2/ch.3	R/W	00000000 _B
004A _H	EIC20	External interrupt circuit control register ch.4/ch.5	R/W	00000000 _B
004B _H	EIC30	External interrupt circuit control register ch.6/ch.7	R/W	00000000 _B
004C _H to 0055 _H	—	(disabled)	—	—
0056 _H	SMC1	UART/SIO serial mode control register 1	R/W	00000000 _B
0057 _H	SMC2	UART/SIO serial mode control register 2	R/W	00100000 _B
0058 _H	SSR	UART/SIO serial status and data register	R/W	00000001 _B
0059 _H	TDR	UART/SIO serial output data register	R/W	00000000 _B
005A _H	RDR	UART/SIO serial input data register	R/W	00000000 _B
005B _H to 005F _H	—	(disabled)	—	—
0060 _H	IBCR00	I ² C bus control register 0	R/W	00000000 _B
0061 _H	IBCR10	I ² C bus control register 1	R/W	00000000 _B
0062 _H	IBSR0	I ² C bus status register	R/W	00000000 _B
0063 _H	IDDR0	I ² C data register	R/W	00000000 _B
0064 _H	IAAR0	I ² C address register	R/W	00000000 _B
0065 _H	ICCR0	I ² C clock control register	R/W	00000000 _B
0066 _H	FSCR	FRAM status/control register	R/W	00000000 _B
0067 _H	FRAC	FRAM register access control register	R/W	00000000 _B
0068 _H	FABH	FRAM write permit start address register (H)	R/W	11111111 _B
0069 _H	FABL	FRAM write permit start address register (L)	R/W	11111111 _B
006A _H	FASH	FRAM write permit area size register (H)	R/W	00000000 _B
006B _H	FASL	FRAM write permit area size register (L)	R/W	00000000 _B
006C _H	ADC1	8/10-bit A/D converter control register 1	R/W	00000000 _B
006D _H	ADC2	8/10-bit A/D converter control register 2	R/W	00000000 _B
006E _H	ADDH	8/10-bit A/D converter data register (upper byte)	R/W	00000000 _B
006F _H	ADDL	8/10-bit A/D converter data register (lower byte)	R/W	00000000 _B
0070 _H	FVAH	FRAM violation address register (H)	R	XXXXXXXX _B
0071 _H	FVAL	FRAM violation address register (L)	R	XXXXXXXX _B

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Address	Register abbreviation	Register name	R/W	Initial value
0072 _H to 0075 _H	—	(disabled)	—	—
0076 _H	WREN	Wild register address compare enable register	R/W	00000000 _B
0077 _H	WROR	Wild register data test setting register	R/W	00000000 _B
0078 _H	—	Register bank pointer (RP) , Mirror of direct bank pointer (DP)	—	—
0079 _H	ILR0	Interrupt level setting register 0	R/W	11111111 _B
007A _H	ILR1	Interrupt level setting register 1	R/W	11111111 _B
007B _H	ILR2	Interrupt level setting register 2	R/W	11111111 _B
007C _H	ILR3	Interrupt level setting register 3	R/W	11111111 _B
007D _H	ILR4	Interrupt level setting register 4	R/W	11111111 _B
007E _H	ILR5	Interrupt level setting register 5	R/W	11111111 _B
007F _H	—	(disabled)	—	—
0F80 _H	WRARH0	Wild register address setting register (upper byte) ch.0	R/W	00000000 _B
0F81 _H	WRARL0	Wild register address setting register (lower byte) ch.0	R/W	00000000 _B
0F82 _H	WRDR0	Wild register data setting register ch.0	R/W	00000000 _B
0F83 _H	WRARH1	Wild register address setting register (upper byte) ch.1	R/W	00000000 _B
0F84 _H	WRARL1	Wild register address setting register (lower byte) ch.1	R/W	00000000 _B
0F85 _H	WRDR1	Wild register data setting register ch.1	R/W	00000000 _B
0F86 _H	WRARH2	Wild register address setting register (upper byte) ch.2	R/W	00000000 _B
0F87 _H	WRARL2	Wild register address setting register (lower byte) ch.2	R/W	00000000 _B
0F88 _H	WRDR2	Wild register data setting register ch.2	R/W	00000000 _B
0F89 _H to 0F91 _H	—	(disabled)	—	—
0F92 _H	T01CR0	8/16-bit compound timer 01 control status register 0 ch.0	R/W	00000000 _B
0F93 _H	T00CR0	8/16-bit compound timer 00 control status register 0 ch.0	R/W	00000000 _B
0F94 _H	T01DR	8/16-bit compound timer 01 data register ch.0	R/W	00000000 _B
0F95 _H	T00DR	8/16-bit compound timer 00 data register ch.0	R/W	00000000 _B
0F96 _H	TMCR0	8/16-bit compound timer 00/01 timer mode control register ch.0	R/W	00000000 _B
0F97 _H	T11CR0	8/16-bit compound timer 11 control status register 0 ch.1	R/W	00000000 _B
0F98 _H	T10CR0	8/16-bit compound timer 10 control status register 0 ch.1	R/W	00000000 _B

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Address	Register abbreviation	Register name	R/W	Initial value
0F99 _H	T11DR	8/16-bit compound timer 11 data register ch.1	R/W	00000000 _B
0F9A _H	T10DR	8/16-bit compound timer 10 data register ch.1	R/W	00000000 _B
0F9B _H	TMCR1	8/16-bit compound timer 10/11 timer mode control register ch.1	R/W	00000000 _B
0F9C _H to 0FBD _H	—	(disabled)	—	—
0FBE _H	PSSR0	UART/SIO prescaler select register	R/W	00000000 _B
0FBF _H	BRSR0	UART/SIO baud rate setting register	R/W	00000000 _B
0FC0 _H to 0FC2 _H	—	(disabled)	—	—
0FC3 _H	AIDRL	A/D input disable register lower	R/W	00000000 _B
0FC4 _H to 0FE3 _H	—	(disabled)	—	—
0FE4 _H	CRT _H	CR-trimming register upper	R/W	1XXXXXXX _B
0FE5 _H	CRT _L	CR-trimming register lower	R/W	000XXXXX _B
0FE6 _H , 0FE7 _H	—	(disabled)	—	—
0FE8 _H	SYSC	System control register	R/W	11000-11 _B
0FE9 _H	CMCR	Clock monitor control register	R/W	--000000 _B
0FEA _H	CMDR	Clock monitor data register	R/W	00000000 _B
0FEB _H	WDTH	Watchdog ID register upper	R/W	XXXXXXXX _B
0FEC _H	WDTL	Watchdog ID register lower	R/W	XXXXXXXX _B
0FED _H	—	(disabled)	—	—
0FEE _H	ILSR	Input level select register	R/W	-----0-- _B
0FEF _H to 0FFF _H	—	(disabled)	—	—

- R/W access symbols

R/W : Readable / Writable

R : Read only

W : Write only

- Initial value symbols

0 : The initial value of this bit is "0".

1 : The initial value of this bit is "1".

X : The initial value of this bit is undefined.

Note : Do not write to the " (Disabled) ". Reading the " (Disabled) " returns an undefined value.

■ INTERRUPT SOURCE TABLE

Interrupt source	Interrupt request number	Vector table address		Bit name of interrupt level setting register	Priority order of interrupt sources of the same level (occurring simultaneously)
		Upper	Lower		
External interrupt ch.4	IRQ00	FFFAH	FFFBH	L00 [1 : 0]	<div>High</div> <div>↑</div> <div>↓</div> <div>Low</div>
External interrupt ch.5	IRQ01	FFF8H	FFF9H	L01 [1 : 0]	
External interrupt ch.2	IRQ02	FFF6H	FFF7H	L02 [1 : 0]	
External interrupt ch.6					
External interrupt ch.3	IRQ03	FFF4H	FFF5H	L03 [1 : 0]	
External interrupt ch.7					
UART/SIO (transmit)	IRQ04	FFF2H	FFF3H	L04 [1 : 0]	
UART/SIO (receive)					
8/16-bit composite timer ch.0 (Lower)	IRQ05	FFF0H	FFF1H	L05 [1 : 0]	
8/16-bit composite timer ch.0 (Upper)	IRQ06	FFEEH	FFEFH	L06 [1 : 0]	
—	IRQ07	FFECH	FFEDH	L07 [1 : 0]	
—	RQ08	FFEAH	FFEBH	L08 [1 : 0]	
FRAM (UDEF, PROT)	IRQ09	FFE8H	FFE9H	L09 [1 : 0]	
—	IRQ10	FFE6H	FFE7H	L10 [1 : 0]	
—	IRQ11	FFE4H	FFE5H	L11 [1 : 0]	
—	IRQ12	FFE2H	FFE3H	L12 [1 : 0]	
—	IRQ13	FFE0H	FFE1H	L13 [1 : 0]	
8/16-bit composite timer ch.1 (Upper)	IRQ14	FFDEH	FFDFH	L14 [1 : 0]	
—	IRQ15	FFDCH	FFDDH	L15 [1 : 0]	
I ² C complete/error	IRQ16	FFDAH	FFDBH	L16 [1 : 0]	
I ² C stop/AL/wakeup					
—	IRQ17	FFD8H	FFD9H	L17 [1 : 0]	
8/10-bit A/D converter	IRQ18	FFD6H	FFD7H	L18 [1 : 0]	
Timebase timer	IRQ19	FFD4H	FFD5H	L19 [1 : 0]	
Watch prescaler	IRQ20	FFD2H	FFD3H	L20 [1 : 0]	
—	IRQ21	FFD0H	FFD1H	L21 [1 : 0]	
8/16-bit composite timer ch.1 (Lower)	IRQ22	FFCEH	FFCFH	L22 [1 : 0]	
FRAM (AREA)	IRQ23	FFCCH	FFCDH	L23 [1 : 0]	

■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V _{CC}	V _{SS} – 0.3	V _{SS} + 4.0	V	
Input voltage*1	V _{I1}	V _{SS} – 0.3	V _{SS} + 4.0	V	Other than P64, P65*2
	V _{I2}	V _{SS} – 0.3	V _{SS} + 6.0	V	P64, P65
Output voltage*1	V _O	V _{SS} – 0.3	V _{SS} + 4.0	V	*2
“L” level maximum output current	I _{OL1}	—	15	mA	Other than P05, P06, P62 and P63
	I _{OL2}		15		P05, P06, P62 and P63
“L” level average current	I _{OLAV1}	—	4	mA	Other than P05, P06, P62 and P63 Average output current = operating current × operating ratio (1pin)
	I _{OLAV2}		12		P05, P06, P62 and P63 Average output current = operating current × operating ratio (1pin)
“L” level total maximum output current	ΣI _{OL}	—	100	mA	
“L” level total average output current	ΣI _{OLAV}	—	50	mA	Total average output current = operating current × operating ratio (Total of pins)
“H” level maximum output current	I _{OH1}	—	–15	mA	Other than P05, P06, P62 and P63
	I _{OH2}		–15		P05, P06, P62 and P63
“H” level average current	I _{OHAV1}	—	–4	mA	Other than P05, P06, P62 and P63 Average output current = operating current × operating ratio (1 pin)
	I _{OHAV2}		–8		P05, P06, P62 and P63 Average output current = operating current × operating ratio (1pin)
“H” level total maximum output current	ΣI _{OH}	—	–100	mA	
“H” level total average output current	ΣI _{OHAV}	—	–50	mA	Total average output current = operating current × operating ratio (Total of pins)
Power consumption	P _d	—	320	mW	
Operating temperature	T _A	–20	+ 70	°C	
Storage temperature	T _{stg}	–20	+ 85	°C	

(Continued)

(Continued)

*1 : The parameter is based on $V_{SS} = 0.0 \text{ V}$.

*2 : V_{I1} and V_o should not exceed $V_{CC} + 0.3 \text{ V}$. V_{I1} must not exceed the rating voltage.

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

2. Recommended Operating Conditions

(V_{SS} = 0.0 V)

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage	V _{CC}	2.7	3.6	V	In normal operating
		3.0	3.6		On-chip debug mode
		2.6	3.6		Hold condition in STOP mode
Operating temperature	T _A	−20	+70	°C	Other than on-chip debug mode
		+5	+35	°C	On-chip debug mode

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges.

Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

3. DC Characteristics

($V_{CC} = 3.3\text{ V}$, $V_{SS} = 0.0\text{ V}$, $T_A = -20\text{ }^{\circ}\text{C}$ to $+70\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
“H” level input voltage	V_{IH1}	P04	*1	$0.7 V_{CC}$	—	$V_{CC} + 0.3$	V	When CMOS input level (Hysteresis input) is selected
	V_{IH2}	P64, P65	*1	$0.7 V_{CC}$	—	$V_{SS} + 5.5$	V	When CMOS input level (Hysteresis input) is selected
	V_{IHS1}	P00 to P07, P12, P62, P63, PG1, PG2	*1	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Hysteresis input
	V_{IHS2}	P64, P65	*1	$0.8 V_{CC}$	—	$V_{SS} + 5.5$	V	Hysteresis input
	V_{IHM}	PF2	—	$0.8 V_{CC}$	—	$V_{CC} + 0.3$	V	Hysteresis input
“L” level input voltage	V_{IL}	P04, P64, P65	*1	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	When CMOS input level (Hysteresis input) is selected
	V_{ILS}	P00 to P07, P12, P62 to P65, PG1, PG2	*1	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	Hysteresis input
	V_{ILM}	PF2	—	$V_{SS} - 0.3$	—	$0.3 V_{CC}$	V	Hysteresis input
Open-drain output application voltage	V_{D1}	P64, P65	—	$V_{SS} - 0.3$	—	$V_{SS} + 5.5$	V	
	V_{D2}	PF2, P12	—	$V_{SS} - 0.3$	—	$0.2 V_{CC}$	V	
“H” level output voltage	V_{OH1}	Output pins other than P05, P06, P62 to P65, PF2, P12	$I_{OH} = -4.0\text{ mA}$	2.4	—	—	V	
	V_{OH2}	P05, P06, P62, P63	$I_{OH} = -8.0\text{ mA}$	2.4	—	—	V	
“L” level output voltage	V_{OL1}	Output pins other than P05, P06, P62, P63	$I_{OL} = 4.0\text{ mA}$	—	—	0.4	V	
	V_{OL2}	P05, P06, P62, P63	$I_{OL} = 12.0\text{ mA}$	—	—	0.4	V	

(Continued)

(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input leak current (Hi-Z output leak current)	I _{LI}	Other than ports P64, P65	0.0 V < V _I < V _{CC}	-5	—	+ 5	μA	When pull-up resistance is disabled
Open-drain output leak current	I _{LIOD}	P64, P65	0.0 V < V _I < V _{SS} + 5.5 V	—	—	+ 5	μA	
Pull-up resistance	R _{PULL}	P00 to P07, PG1, PG2	V _I = 0.0 V	25	50	100	kΩ	When pull-up resistance is enabled
Input capacitance	C _{IN}	Other than V _{CC} , V _{SS}	f = 1 MHz	—	5	15	pF	
Power supply current*2	I _{CC}	V _{CC} (External clock operation)	F _{CH} = 20 MHz, F _{MP} = 10 MHz Main clock mode (divided by 2)	—	6	9	mA	
				—	8	12	mA	At A/D conversion
	I _{CCS}		F _{CH} = 20 MHz, F _{MP} = 10 MHz Main sleep mode (divided by 2)	—	3	5	mA	
	I _{CCCL}		F _{CL} = 32 kHz, F _{MPL} = 16 kHz Sub clock mode (divided by 2) T _A = +25 °C	—	30	70	μA	
	I _{CCCLS}		F _{CL} = 32 kHz, F _{MPL} = 16 kHz Sub sleep mode (divided by 2) T _A = +25 °C	—	5	40	μA	
	I _{CCCT}		F _{CL} = 32 kHz, Watch mode Main stop mode T _A = +25 °C	—	3	18	μA	
	I _{CCMCR}	V _{CC}	F _{CRH} = 1 MHz, F _{MP} = 1 MHz Main CR clock mode	—	2	—	mA	
	I _{CCSCR}		Sub CR clock mode (divided by 2) T _A = +25 °C	—	80	300	μA	

(Continued)

(Continued)

(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current*2	I _{CCTS}	V _{CC} (External clock operation)	F _{CH} = 10 MHz, Timebase timer mode T _A = +25 °C	—	1	3	mA	
	I _{CCCH}		Sub stop mode T _A = +25 °C	—	1	10	μA	
	I _{CRH}	V _{CC}	Current consumption of internal main CR oscillator	—	0.2	0.3	mA	
	I _{CRL}		At oscillating 100 kHz current consumption of internal sub CR oscillator	—	20	72	μA	

*1 : P04, P64, P65 can switch the input level to either the “CMOS input level” or “hysteresis input level”.
The switching of the input level can be set by the input level selection register (ILSR) .

*2 : • The power-supply current is determined by the external clock. when Internal CR are selected, the power-supply current will be a value of adding current consumption of internal CR oscillator (I_{CRL}) to the specified value.

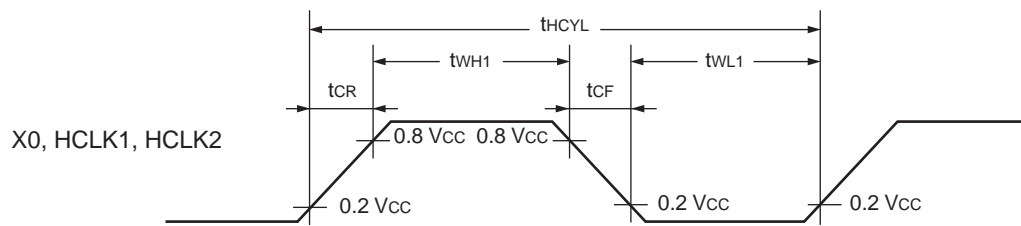
- Refer to “4. AC Characteristics (1) Clock Timing” for F_{CH} and F_{CL}.
- Refer to “4. AC Characteristics (2) Source Clock/Machine Clock” for F_{MP} and F_{MPL}.

4. AC Characteristics

(1) Clock Timing

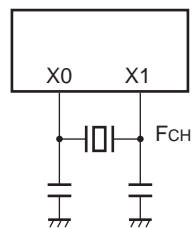
(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Sym- bol	Pin name	Condi- tion	Value			Unit	Remarks		
				Min	Typ	Max				
Clock frequency	F _{CH}	X0, X1	—	1	—	10	MHz	When the main oscillation circuit is used		
		X0, X1, HCLK1, HCLK2		1	—	20	MHz	When the main external clock is used		
	F _{CRH}	—		0.95	1	1.05	MHz	When the main internal CR clock is used (3.0 V ≤ V _{CC} ≤ 3.6 V, + 5 °C ≤ T _A ≤ + 35 °C)		
	F _{CL}	X0A, X1A		—	32.768	—	MHz	When the sub oscillation circuit is used		
				—	32.768	—	kHz	When the sub external clock is used		
	F _{CRL}	—		50	100	200	kHz	When the sub internal CR clock is used		
Clock cycle time	t _{H CYL}	X0, X1		100	—	1000	ns	When the main oscillation circuit is used		
		X0, X1, HCLK1, HCLK2		50	—	1000	ns	When the main external clock is used		
	t _{L CYL}	X0A, X1A		—	30.5	—	μs	When using sub clock		
Input clock pulse width	t _{WH1}	X0, HCLK1, HCLK2		20	—	—	ns	When the external clock is used, the duty ratio should range between 40% and 60%		
	t _{WL1}								μs	
	t _{WH2}	X0A					—			15.2
	t _{WL2}									
Input clock rise time and fall time	t _{CR}	X0, X0A, HCLK1, HCLK2		—	—	5	ns	When the external clock is used		
	t _{CF}									
Internal CR oscillation start time	t _{CRHWK}	—		—	—	10	μs	When the main-internal CR clock is used		
	t _{CRLWK}	—						10	μs	When the sub-internal CR clock is used

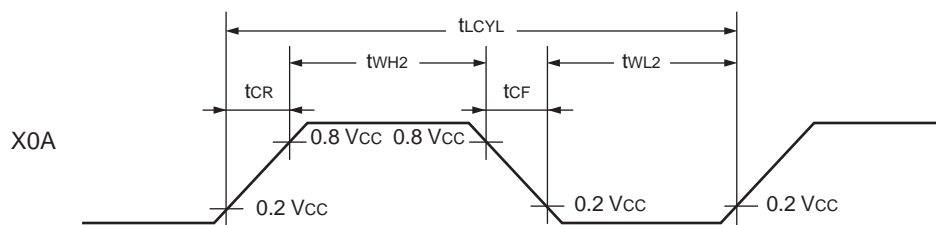
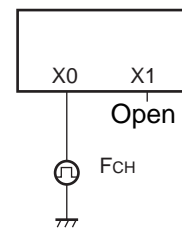


• Figure of main clock input port external connection

When using a crystal or Ceramic oscillator

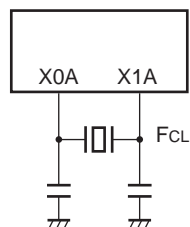


When using external clock

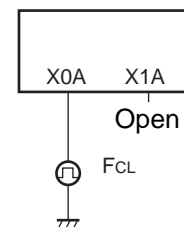


• Figure of sub clock input port external connection

When using a crystal or Ceramic oscillator



When using external clock



(2) Source Clock/Machine Clock

(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Source clock cycle time ^{*1} (Clock before division)	t _{SCLK}	—	100	—	2000	ns	When using main external clock Min : F _{CH} = 20 MHz, divided by 2 Max : F _{CH} = 1 MHz, divided by 2
			—	1	—	μs	When using main CR oscillation clock F _{CRH} = 1 MHz
			—	61	—	μs	When using sub oscillation clock F _{CL} = 32.768 kHz, divided by 2
			—	20	—	μs	When using sub oscillation clock F _{CRL} = 100 kHz, divided by 2
Source clock frequency	F _{SP}	—	0.5	—	10	MHz	When using main oscillation clock
			—	1	—	MHz	When using main CR oscillation clock
	F _{SPL}		—	16.384	—	kHz	When using sub oscillation clock
			—	50	—	kHz	When using sub CR clock
Machine clock cycle time ^{*2} (Minimum instruction execution time)	t _{MCLK}	—	100	—	32000	ns	When using main oscillation clock Min : F _{SP} = 10 MHz, no division Max : F _{SP} = 0.5 MHz, divided by 16
			1	—	16	μs	When using main CR clock Min : F _{SP} = 1 MHz, no division Max : F _{SP} = 1 MHz, divided by 16
			61	—	976.5	μs	When using sub oscillation clock Min : F _{SPL} = 16.384 kHz, no division Max : F _{SPL} = 16.384 kHz, divided by 16
			20	—	320	μs	When using sub CR clock Min : F _{SPL} = 50 kHz, no division Max : F _{SPL} = 50 kHz, divided by 16
Machine clock frequency	F _{MP}	—	0.031	—	10	MHz	When using main oscillation clock
			0.0625	—	1	MHz	When using main CR clock
	F _{MPL}		1.024	—	16.384	kHz	When using sub oscillation clock
			3.125	—	50	kHz	When using sub CR clock
FRAM clock cycle time ^{*3} (Minimum instruction execution time)	t _{FCLK}	—	300	—	96000	ns	When using main oscillation clock Min : F _{SP} = 10 MHz, divided by 3 Max : F _{SP} = 0.5 MHz, divided by 48
			3	—	48	μs	When using main CR clock Min : F _{SP} =1 MHz, divided by 3 Max : F _{SP} =1 MHz, divided by 48
			183	—	2929.7	μs	When using sub oscillation clock Min : F _{SPL} = 16.384 kHz, divided by 3 Max : F _{SPL} = 16.384 kHz, divided by 48
			60	—	960	μs	When using sub CR clock Min : F _{SPL} = 50 kHz, divided by 3 Max : F _{SPL} = 50 kHz, divided by 48

(Continued)

(Continued)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
FRAM clock frequency	F _{FCLK}	—	0.010	—	3.3	MHz	When using main oscillation clock
			0.0208	—	0.3333	MHz	When using main CR clock
	F _{FCLKL}		0.341	—	5.461	kHz	When using sub oscillation clock
			1.042	—	16.667	kHz	When using sub CR clock

*1 : Clock before setting division due to machine clock division ratio selection bit (SYCC : DIV1 and DIV0) . This source clock is divided by the machine clock division ratio selection bit (SYCC : DIV1 and DIV0) , and it becomes the machine clock. Further, the source clock can be selected as follows.

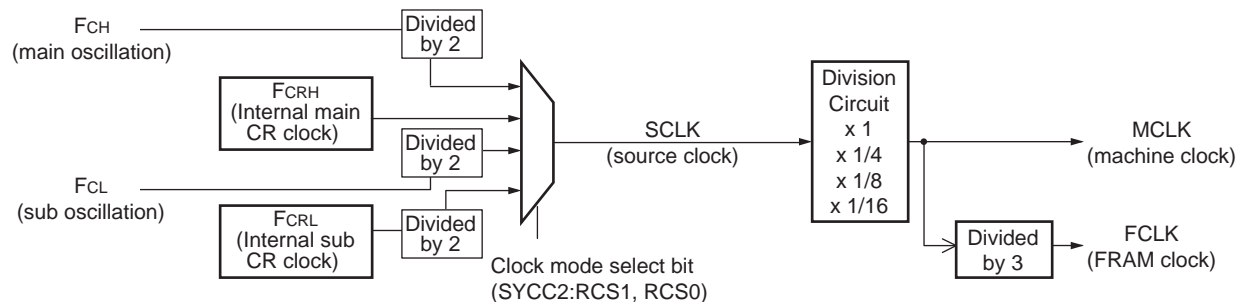
- Main clock divided by 2
- Main CR clock
- Sub clock divided by 2
- Sub CR clock divided by 2

*2 : Operation clock of the microcontroller. Machine clock can be selected as follows.

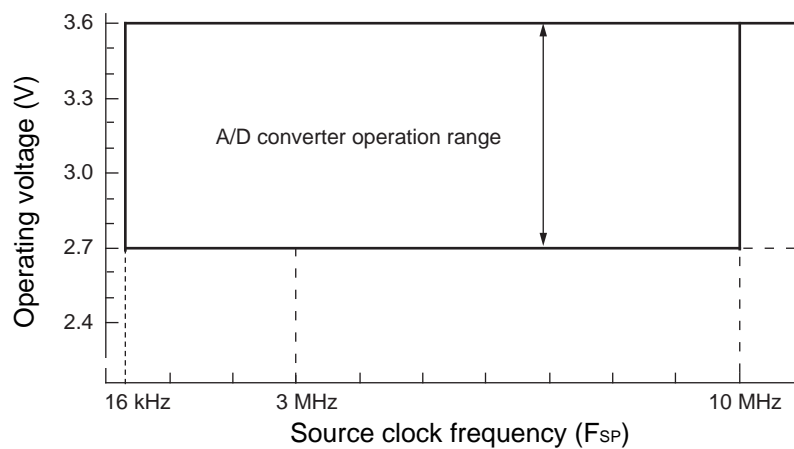
- Source clock (no division)
- Source clock divided by 4
- Source clock divided by 8
- Source clock divided by 16

*3 : The clock in case of operating code on FRAM, or Read/Write access to FRAM. Its value is machine clock divided by 3.

• Outline of clock generation block



- Operating voltage - Operating frequency (When $T_A = -20\text{ }^{\circ}\text{C}$ to $+70\text{ }^{\circ}\text{C}$)



(3) External Reset

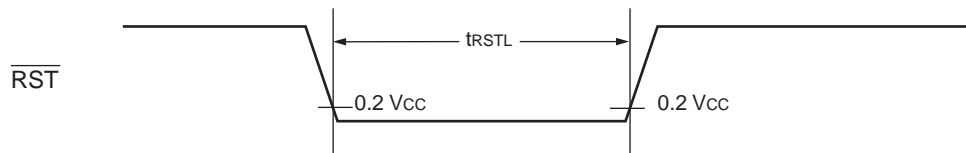
(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Value		Unit	Remarks
		Min	Max		
$\overline{\text{RST}}$ "L" level pulse width	t_{RSTL}	$2 t_{\text{MCLK}}^{*1}$	—	ns	At normal operating
		Oscillation time of oscillator ^{*2} + 100	—	μs	At stop mode, sub clock mode, sub sleep mode, and watch mode
		100	—	μs	At time-base timer mode

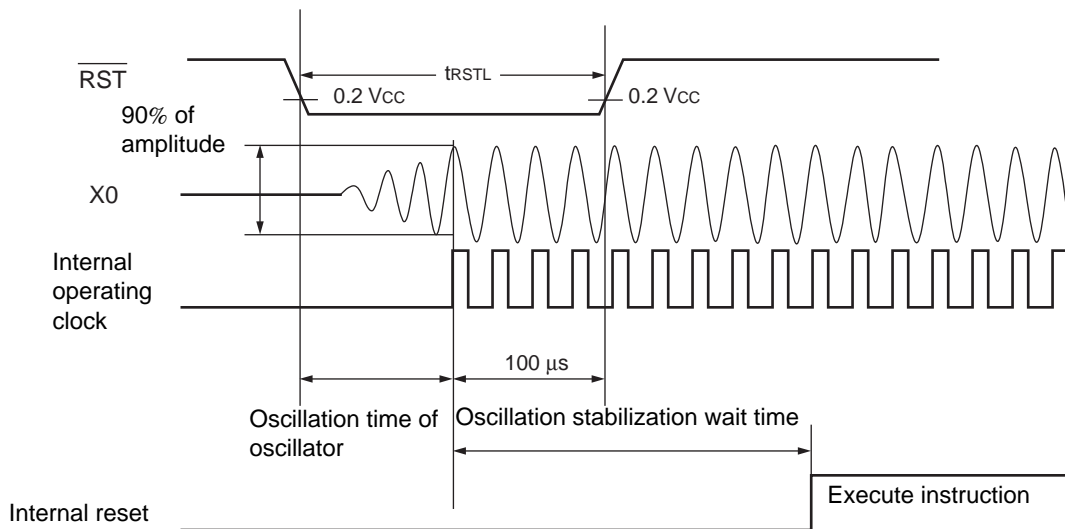
*1 : Refer to "(2) Source Clock/Machine Clock" for t_{MCLK} .

*2 : Oscillation time of oscillator is the time that the amplitude reaches 90%. In the crystal oscillator, the oscillation time is between several ms and tens of ms. In ceramic oscillators, the oscillation time is between hundreds of μs and several ms. In the external clock, the oscillation time is 0 ms.

- At normal operating



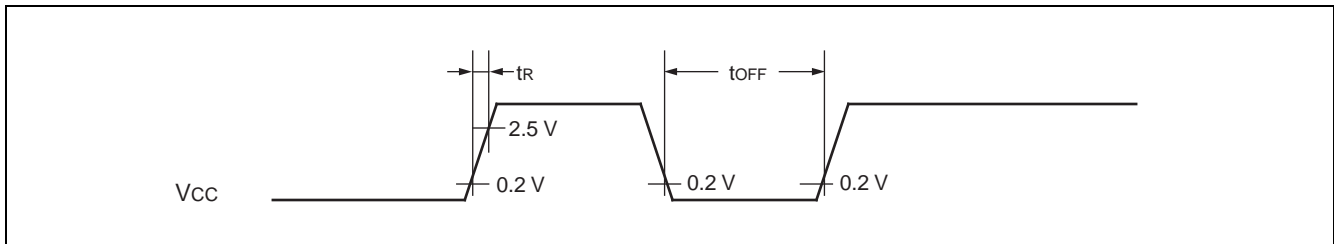
- At stop mode, sub clock mode, sub sleep mode, watch mode, and power-on



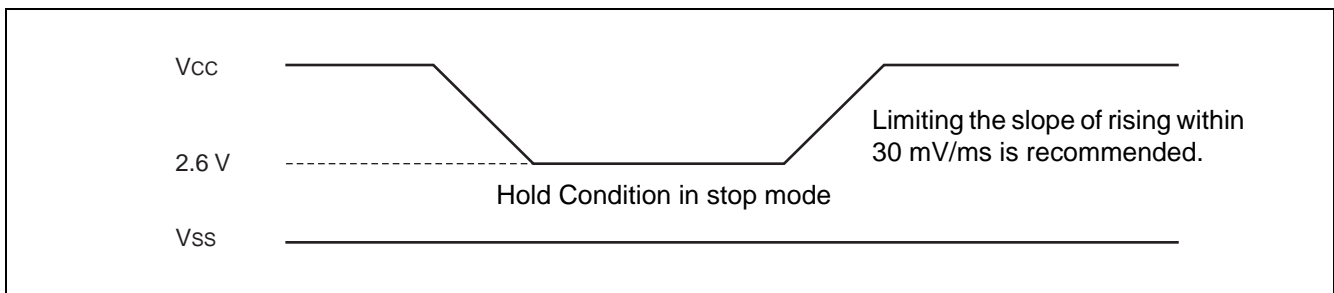
(4) Power-on Reset

(V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Conditions	Value		Unit	Remarks
			Min	Max		
Power supply rising time	t _R	—	—	50	ms	
Power supply cutoff time	t _{OFF}	—	1	—	ms	Waiting time until power-on



Note: Sudden change of power supply voltage may activate the power-on reset function. When changing power supply voltages during operation, set the slope of rising within 30 mV/ms as shown below.

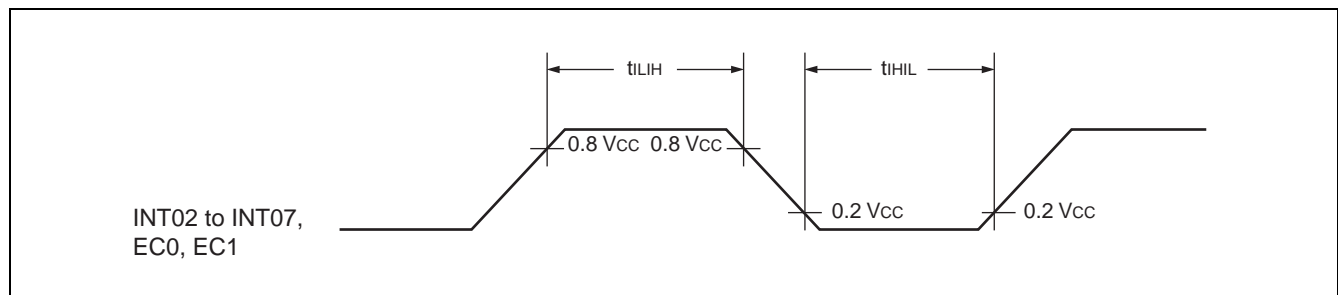


(5) Peripheral Input Timing

($V_{CC} = 3.3\text{ V}$, $V_{SS} = 0.0\text{ V}$, $T_A = -20\text{ }^{\circ}\text{C}$ to $+70\text{ }^{\circ}\text{C}$)

Parameter	Symbol	Pin name	Value		Unit
			Min	Max	
Peripheral input "H" pulse	t_{LIH}	INT02 to INT07, EC0, EC1	$2\ t_{MCLK}^*$	—	ns
Peripheral input "L" pulse	t_{HIL}		$2\ t_{MCLK}^*$	—	ns

* : Refer to “ (2) Source Clock/Machine Clock” for t_{MCLK} .



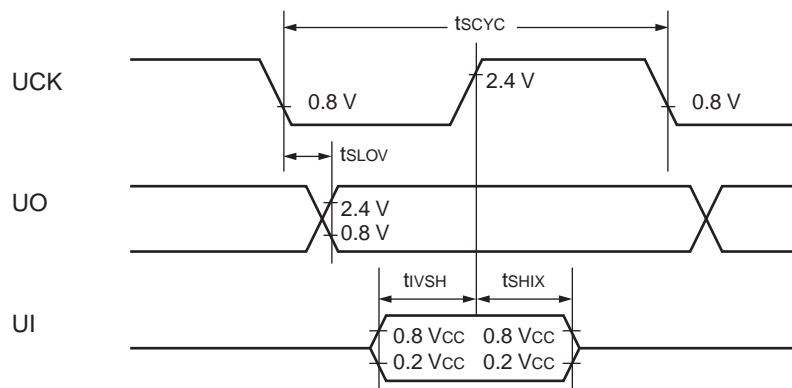
(6) UART/SIO, Serial I/O Timing

(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

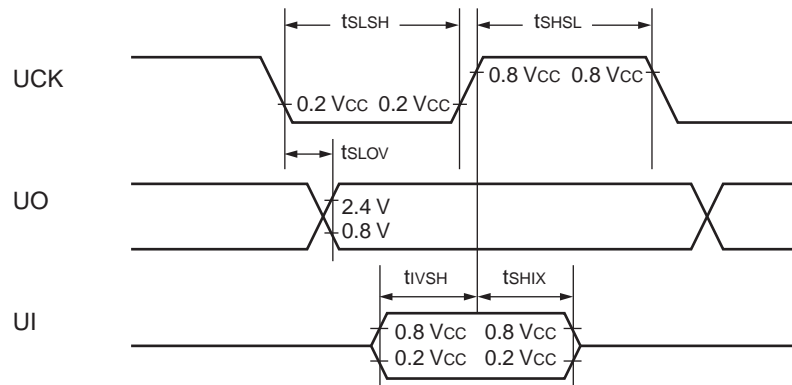
Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t _{SCYC}	UCK	Internal clock operation output pin : C _L = 80 pF + 1 TTL.	4 t _{MCLK} *	—	ns
UCK ↓ → UO time	t _{SLOV}	UCK, UO		-190	+190	ns
Valid UI → UCK ↑	t _{IVSH}	UCK, UI		2 t _{MCLK} *	—	ns
UCK ↑ → valid UI hold time	t _{SHIX}	UCK, UI		2 t _{MCLK} *	—	ns
Serial clock "H" pulse width	t _{SHSL}	UCK	External clock operation output pin : C _L = 80 pF + 1 TTL.	4 t _{MCLK} *	—	ns
Serial clock "L" pulse width	t _{SLSH}	UCK		4 t _{MCLK} *	—	ns
UCK ↓ → UO time	t _{SLOV}	UCK, UO		0	190	ns
Valid UI → UCK ↑	t _{IVSH}	UCK, UI		2 t _{MCLK} *	—	ns
UCK ↑ → valid UI hold time	t _{SHIX}	UCK, UI		2 t _{MCLK} *	—	ns

* : Refer to “ (2) Source Clock/Machine Clock” for details on t_{MCLK}.

• Internal shift clock mode



• External shift clock mode



(7) I²C Timing

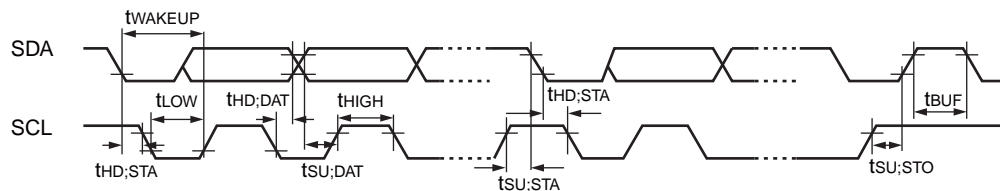
(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Conditions	Value				Unit
				Standard-mode		Fast-mode		
				Min	Max	Min	Max	
SCL clock frequency	t _{SCYC}	SCL	R = 1.7 kΩ, C = 50 pF ^{*1}	0	100	0	400	kHz
(Repeat) Start condition hold time SDA ↓ → SCL ↓	t _{HD;STA}	SCL SDA		4.0	—	0.6	—	μs
SCL clock “L” width	t _{LOW}	SCL		4.7	—	1.3	—	μs
SCL clock “H” width	t _{HIGH}	SCL		4.0	—	0.6	—	μs
(Repeat) Start condition setup time SCL ↑ → SDA ↓	t _{SU;STA}	SCL SDA		4.7	—	0.6	—	μs
Data hold time SCL ↓ → SDA ↓ ↑	t _{HD;DAT}	SCL SDA		0	3.45 ^{*2}	0	0.9 ^{*3}	μs
Data setup time SDA ↓ ↑ → SCL ↑	t _{SU;DAT}	SCL SDA		0.25	—	0.1	—	μs
Stop condition setup time SCL ↑ → SDA ↓	t _{SU;STO}	SCL SDA		4.0	—	0.6	—	μs
Bus free time between stop condition and start condition	t _{BUF}	SCL SDA		4.7	—	1.3	—	μs

*1 : R, C : Pull-up resistance and load capacitance of the SCL and SDA lines.

*2 : The maximum value of t_{HD;DAT} is applicable only if the device does not extend the "L" width (t_{LOW}) of the SCL signal.

*3 : A fast-mode I²C-bus device can be used in a standard-mode I²C-bus system, but the requirement t_{SU;DAT} ≥ 250 ns must then be met.



(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Condi-tions	Value ²		Unit	Remarks
				Min	Max		
SCL clock "L" width	t _{LOW}	SCL	R = 1.7 kΩ, C = 50 pF ⁻¹	$(2 + nm / 2) t_{MCLK} - 20$	—	ns	Master mode
SCL clock "H" width	t _{HIGH}	SCL		$(nm / 2) t_{MCLK} - 20$	$(nm / 2) t_{MCLK} + 20$	ns	Master mode
Start condition hold time	t _{HD,STA}	SCL SDA		$(-1 + nm / 2) t_{MCLK} - 20$	$(-1 + nm / 2) t_{MCLK} + 20$	ns	Master mode maximum value is applied when m, n = 1, 8. Otherwise, the minimum value is applied.
Stop condition setup time	t _{SU,STO}	SCL SDA		$(1 + nm / 2) t_{MCLK} - 20$	$(1 + nm / 2) t_{MCLK} + 20$	ns	Master mode
Start condition setup time	t _{SU,STA}	SCL SDA		$(1 + nm / 2) t_{MCLK} - 20$	$(1 + nm / 2) t_{MCLK} + 20$	ns	Master mode
Bus free time between stop condition and start condition	t _{BUF}	SCL SDA		$(2 nm + 4) t_{MCLK} - 20$	—	ns	
Data hold time	t _{HD,DAT}	SCL SDA		$3 t_{MCLK} - 20$	—	ns	Master mode
Data setup time	t _{SU,DAT}	SCL SDA		$(-2 + nm / 2) t_{MCLK} - 20$	$(-1 + nm / 2) t_{MCLK} + 20$	ns	Master mode When assuming that "L" of SCL is not extended, the minimum value is applied to first bit of continuous data. Otherwise, the maximum value is applied.
Setup time between cleaning interrupt and SCL rising	t _{SU,INT}	SCL		$(nm / 2) t_{MCLK} - 20$	$(1 + nm / 2) t_{MCLK} + 20$	ns	Minimum value is applied to interrupt at 9th SCL↓. Maximum value is applied to interrupt at 8th SCL↓.
SCL clock "L" width	t _{LOW}	SCL		$4 t_{MCLK} - 20$	—	ns	At reception
SCL clock "H" width	t _{HIGH}	SCL		$4 t_{MCLK} - 20$	—	ns	At reception
Start condition detection	t _{HD,STA}	SCL SDA		$4 t_{MCLK} - 20$	—	ns	Undetected when 1 t _{MCLK} is used at reception

(Continued)

(Continued)

(V_{CC} = 3.3 V, V_{SS} = 0.0 V, T_A = -20 °C to +70 °C)

Parameter	Symbol	Pin name	Conditions	Value*2		Unit	Remarks
				Min	Max		
Stop condition detection	t _{SU;STO}	SCL SDA	R = 1.7 kΩ, C = 50 pF*1	4 t _{MCLK} - 20	—	ns	Undetected when 1 t _{MCLK} is used at reception
Restart condition detection condition	t _{SU;STA}	SCL SDA		2 t _{MCLK} - 20	—	ns	Undetected when 1 t _{MCLK} is used at reception
Bus free time	t _{BUF}	SCL SDA		2 t _{MCLK} - 20	—	ns	During reception
Data hold time	t _{HD;DAT}	SCL SDA		2 t _{MCLK} - 20	—	ns	In slave transmission mode
Data setup time	t _{SU;DAT}	SCL SDA		t _{LOW} - 3 t _{MCLK} - 20	—	ns	In slave transmission mode
Data hold time	t _{HD;DAT}	SCL SDA		0	—	ns	During reception
Data setup time	t _{SU;DAT}	SCL SDA		t _{MCLK} - 20	—	ns	During reception
SDA ↓ → SCL ↑ (when using wakeup function)	t _{WAKEUP}	SCL SDA		Oscillation stabilization wait time + 2 t _{MCLK} - 20	—	ns	

*1 : R, C : Pull-up resistance and load capacitance of the SCL and SDA lines.

*2 : • Refer to “(2) Source Clock/Machine Clock” for details on t_{MCLK}.

- m is the CS4 and CS3 bits (bit 4 and bit 3) of the I²C clock control register (ICCR0) .
- n is the CS2 to CS0 bits (bit 2 to bit0) of the I²C clock control register (ICCR0) .
- The actual I²C timing is determined by the machine (t_{MCLK}) and the values of m and n configured in bits CS4 to CS0 of the I²C clock control register (ICCR0) .

• Standard-mode :

m and n can be set in the range : 0.9 MHz < t_{MCLK} (machine clock) < 10 MHz.

The machine clock to be used is determined by the settings of m and n as follows.

(m, n) = (1, 8)	: 0.9 MHz < t _{MCLK} ≤ 1 MHz
(m, n) = (1, 22), (5, 4), (6, 4), (7, 4), (8, 4)	: 0.9 MHz < t _{MCLK} ≤ 2 MHz
(m, n) = (1, 38), (5, 8), (6, 8), (7, 8), (8, 8)	: 0.9 MHz < t _{MCLK} ≤ 4 MHz
(m, n) = (1, 98)	: 0.9 MHz < t _{MCLK} ≤ 1 MHz

• Fast-mode :

m and n can be set in the range : 3.3 MHz < t_{MCLK} (machine clock) < 10 MHz.

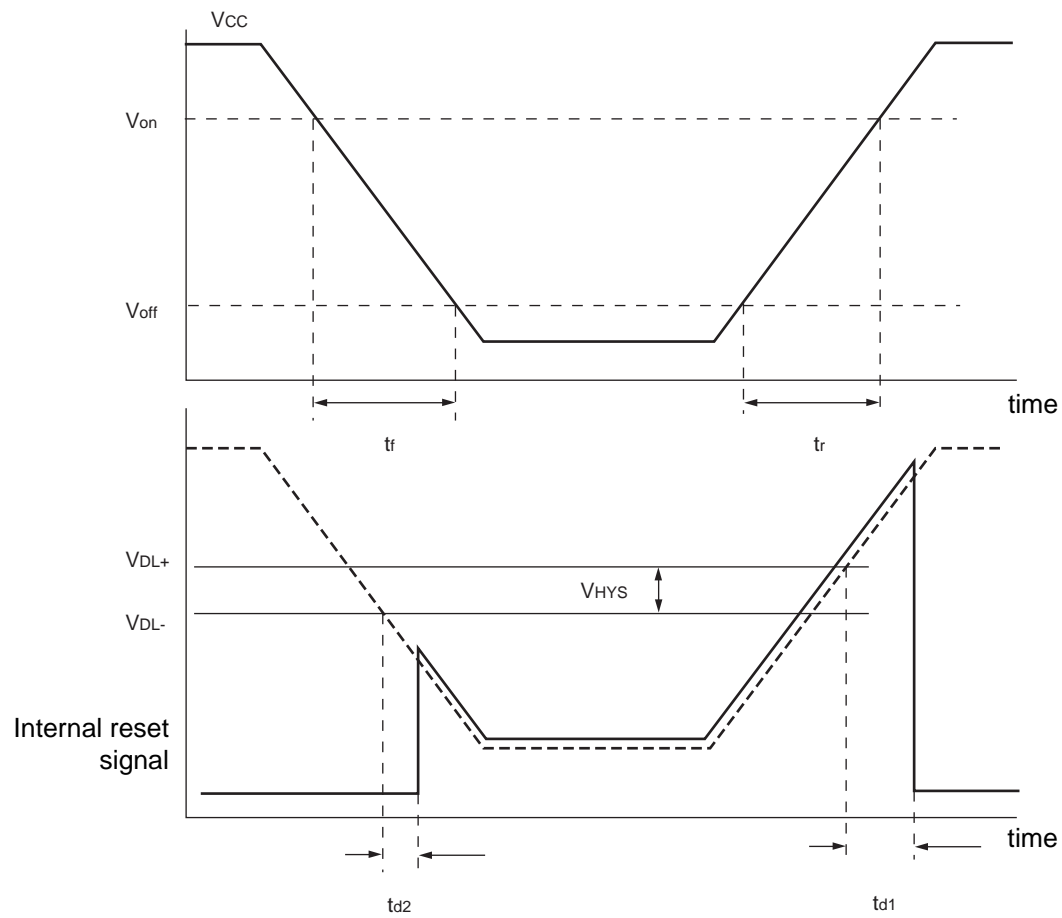
The machine clock to be used is determined by the settings of m and n as follows.

(m, n) = (1, 8)	: 3.3 MHz < t _{MCLK} ≤ 4 MHz
(m, n) = (1, 22), (5, 4)	: 3.3 MHz < t _{MCLK} ≤ 8 MHz
(m, n) = (6, 4)	: 3.3 MHz < t _{MCLK} ≤ 10 MHz

(8) Low Voltage Detection

($V_{SS} = 0.0 \text{ V}$, $T_A = -20 \text{ }^{\circ}\text{C}$ to $+70 \text{ }^{\circ}\text{C}$)

Parameter		Symbol	Value			Unit	Remarks
			Min	Typ	Max		
Low voltage detection reset	Release voltage	$V1_{DL+}$	2.7	2.8	2.9	V	At power-supply rise
	Detection voltage	$V1_{DL-}$	2.6	2.7	2.8	V	At power-supply fall
	Hysteresis width	$V1_{HYS}$	70	100	—	mV	
FRAM power supply monitor	Release voltage	$V2_{DL+}$	2.8	2.9	3.0	V	At power-supply rise
	Detection voltage	$V2_{DL-}$	2.7	2.8	2.9	V	At power-supply fall
	Hysteresis width	$V2_{HYS}$	70	100	—	mV	
Power-supply start voltage		V_{off}	—	—	2.2	V	
Power-supply end voltage		V_{on}	3.3	—	—	V	
Power-supply voltage change time (at power supply rise)		t_r	0.3	—	—	μs	Slope of power supply that reset release signal generates
			—	200	—	μs	Slope of power supply that reset release signal generates within rating ($V1_{DL+}$, $V2_{DL+}$)
Power-supply voltage change time (at power supply fall)		t_f	0.3	—	—	μs	Slope of power supply that reset detection signal generates
			—	200	—	μs	Slope of power supply that reset detection signal generates within rating ($V1_{DL-}$, $V2_{DL-}$)
Reset release delay time		t_{d1}	—	—	300	μs	
Reset detection delay time		t_{d2}	—	—	20	μs	



5. A/D Converter

(1) A/D Converter Electrical Characteristics

($V_{CC} = 2.7 \text{ V to } 3.6 \text{ V}$, $V_{SS} = 0.0 \text{ V}$, $T_A = -20 \text{ }^{\circ}\text{C to } +70 \text{ }^{\circ}\text{C}$)

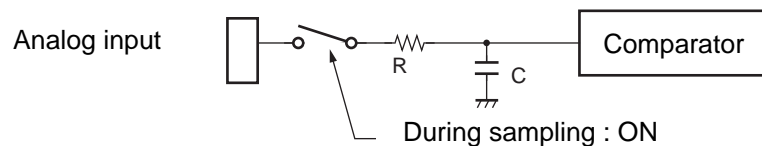
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Resolution	—	—	—	10	bit	
Total error		-3.0	—	+3.0	LSB	
Linearity error		-2.5	—	+2.5	LSB	
Differential linear error		-1.9	—	+1.9	LSB	
Zero transition voltage	V_{OT}	$V_{SS} - 1.5 \text{ LSB}$	$V_{SS} + 0.5 \text{ LSB}$	$V_{SS} + 2.5 \text{ LSB}$	V	
Full-scale transition voltage	V_{FST}	$V_{CC} - 3.5 \text{ LSB}$	$V_{CC} - 1.5 \text{ LSB}$	$V_{CC} + 0.5 \text{ LSB}$	V	
Compare time	—	0.6	—	140	μs	
Sampling time	—	0.4	—	∞	μs	$3.0 \text{ V} \leq V_{CC} \leq 3.6 \text{ V}$ At external impedance < 1.8 k Ω
Analog input current	I_{AIN}	-0.3	—	+0.3	μA	
Analog input voltage	V_{AIN}	V_{SS}	—	V_{CC}	V	

(2) Notes on Using A/D Converter

• About the external impedance of analog input and its sampling time

A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting A/D conversion precision. Therefore, to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. Also, if the sampling time cannot be sufficient, connect a capacitor of about 0.1 μF to the analog input pin.

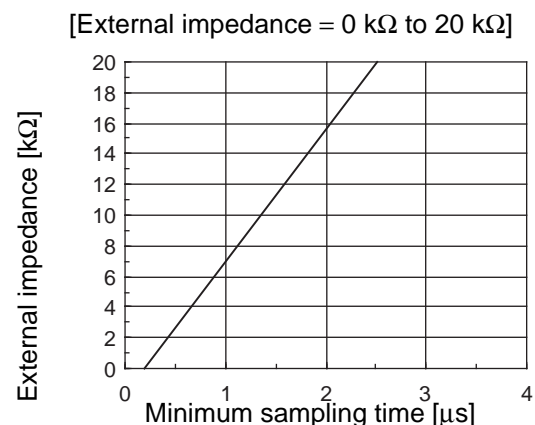
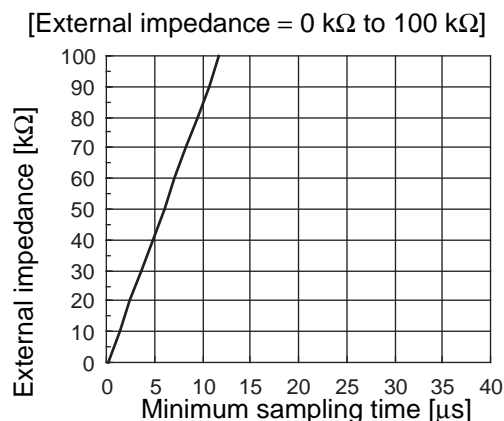
• Analog input equivalent circuit



$$2.7 \text{ V} \leq V_{\text{CC}} \leq 3.6 \text{ V} : R \leq 1.7 \text{ k}\Omega \text{ (Max)}, C \leq 14.5 \text{ pF (Max)}$$

Note : The values are reference values.

• The relationship between external impedance and minimum sampling time.



• About errors

$|V_{\text{CC}} - V_{\text{SS}}|$ becomes smaller, values of relative errors grow larger.

(3) Definition of A/D Converter Terms

- Resolution

The level of analog variation that can be distinguished by the A/D converter.

When the number of bits is 10, analog voltage can be divided into $2^{10} = 1024$.

- Linearity error (unit : LSB)

The deviation between the value along a straight line connecting the zero transition point

("00 0000 0000" \longleftrightarrow "00 0000 0001") of a device and the full-scale transition point

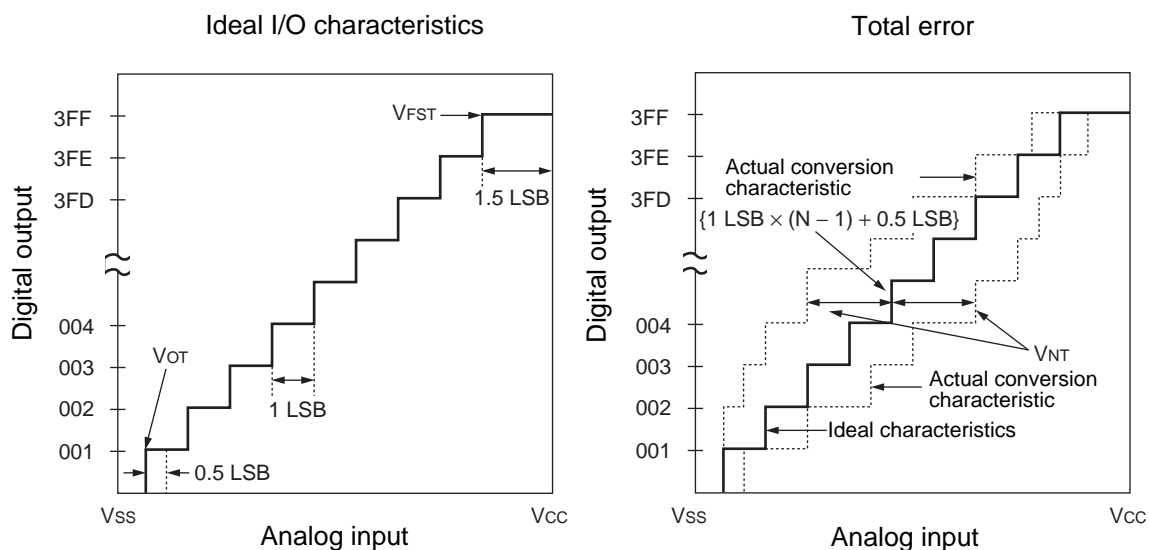
("11 1111 1111" \longleftrightarrow "11 1111 1110") compared with the actual conversion values obtained.

- Differential linear error (Unit : LSB)

Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.

- Total error (unit : LSB)

Difference between actual and theoretical values, caused by a zero transition error, full-scale transition error, linearity error, quantum error, and noise.



$$1 \text{ LSB} = \frac{V_{CC} - V_{SS}}{1024} \text{ (V)}$$

$$\text{Total error of digital output N} = \frac{V_{NT} - \{1 \text{ LSB} \times (N - 1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}} \text{ [LSB]}$$

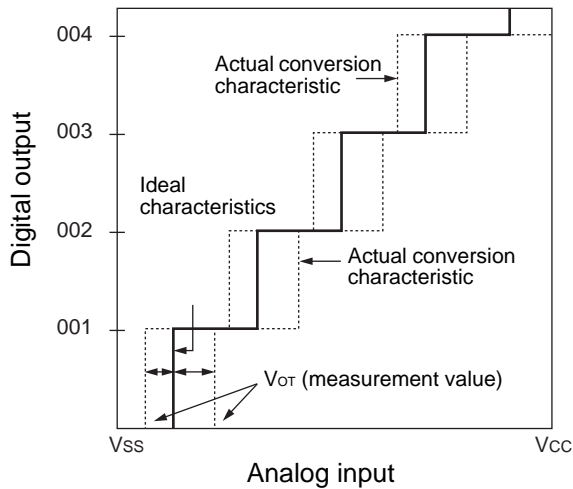
N : A/D converter digital output value

V_{NT} : A voltage at which digital output transits from (N - 1) to N

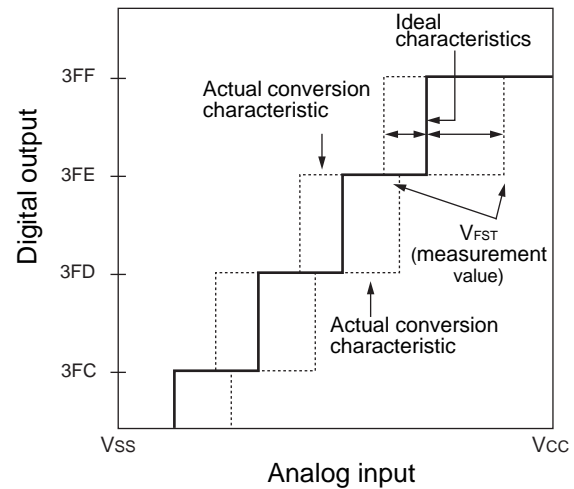
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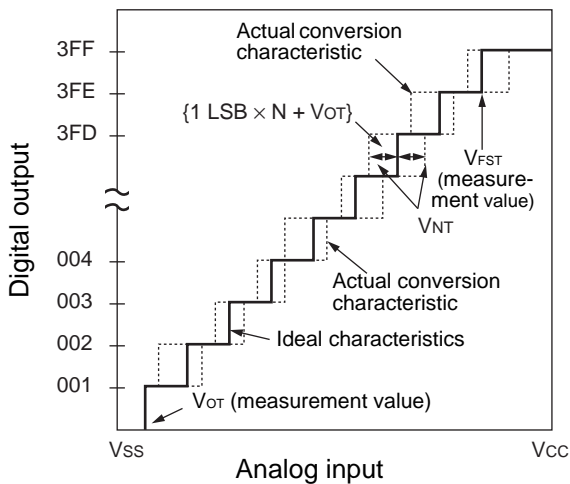
Zero transition error



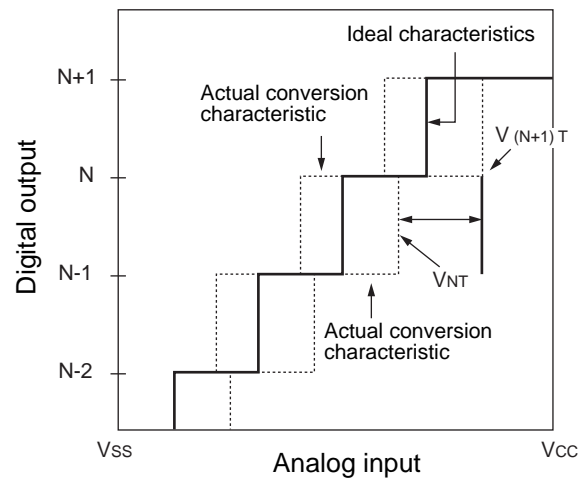
Full-scale transition error



Linearity error



Differential linear error



$$\text{Linearity error in digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times N + V_{OT}\}}{1 \text{ LSB}}$$

$$\text{Differential linear error In digital output } N = \frac{V_{(N+1)T} - V_{NT}}{1 \text{ LSB}} - 1$$

N : A/D converter digital output value

V_{NT} : A voltage at which digital output transits from (N - 1) to N.

V_{OT} (Ideal value) = V_{SS} + 0.5 LSB [V]

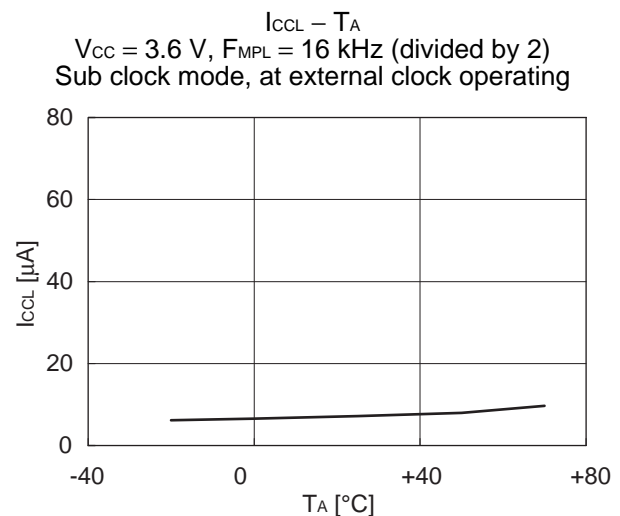
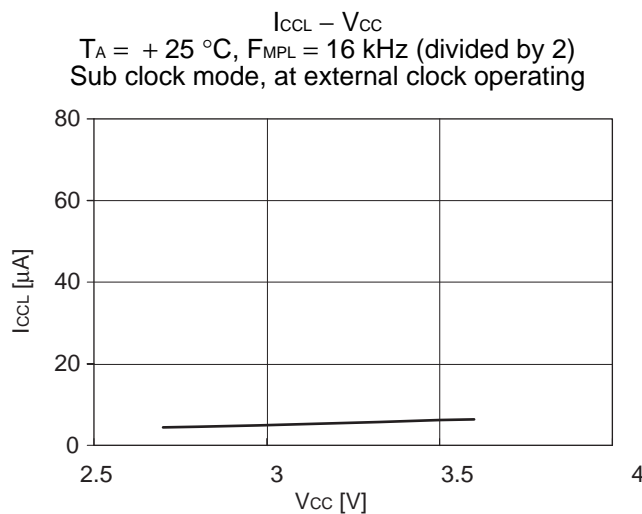
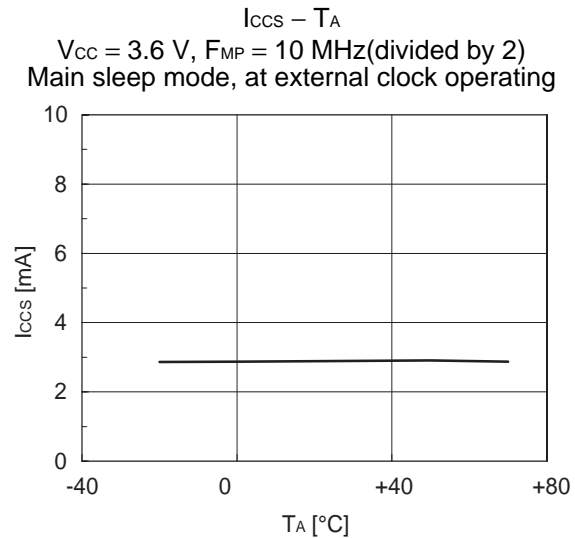
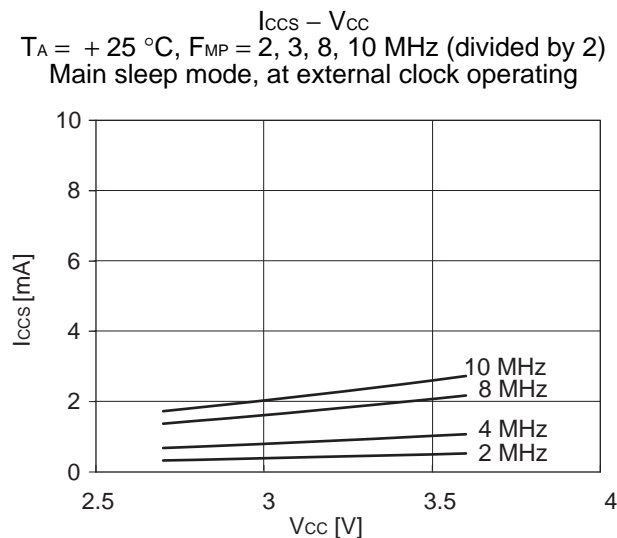
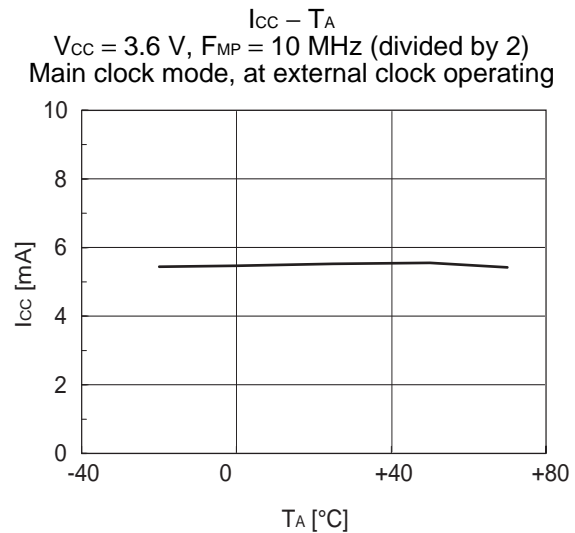
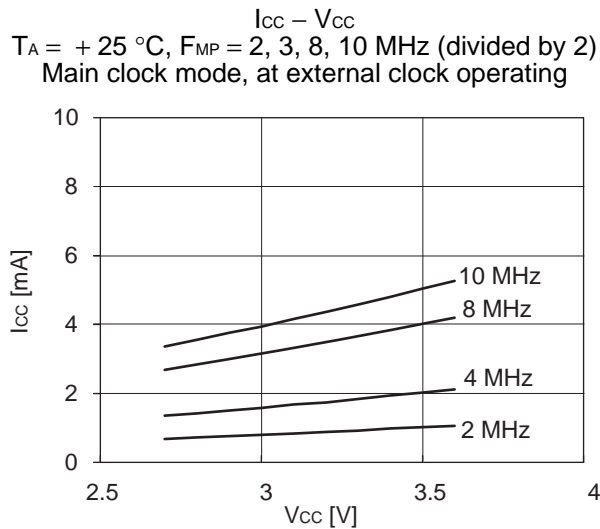
V_{FST} (Ideal value) = V_{CC} - 2.0 LSB [V]

6. FRAM Characteristics

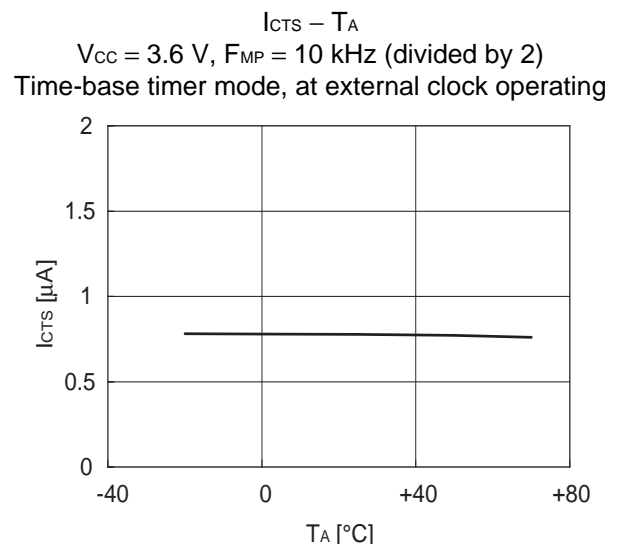
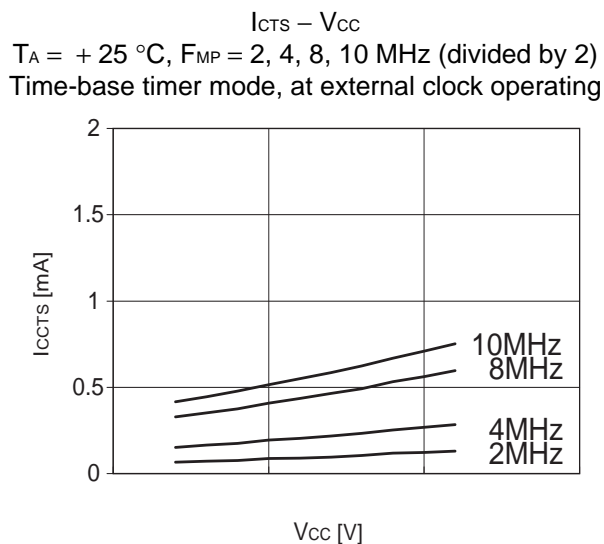
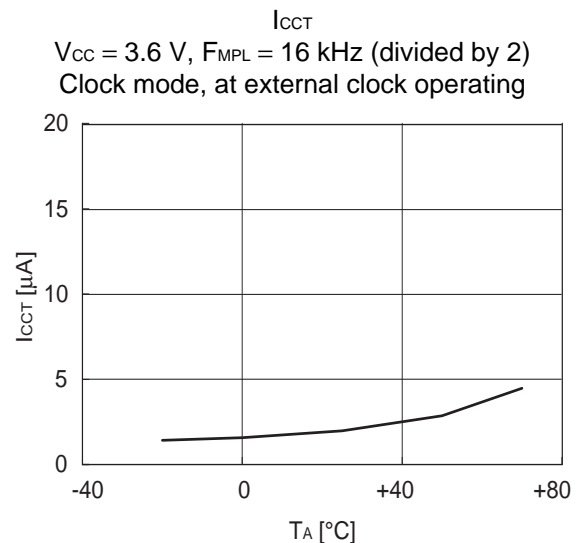
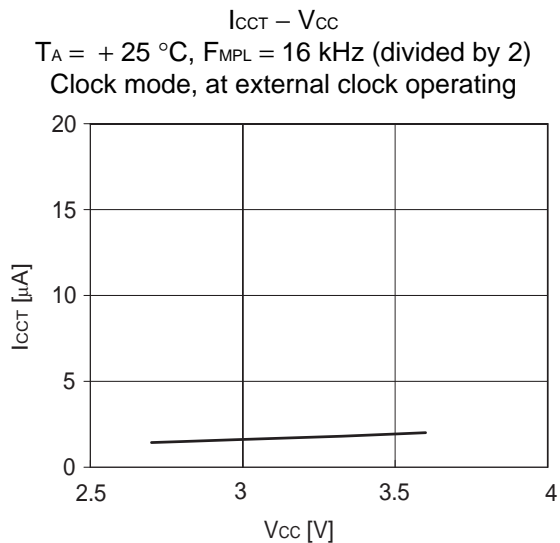
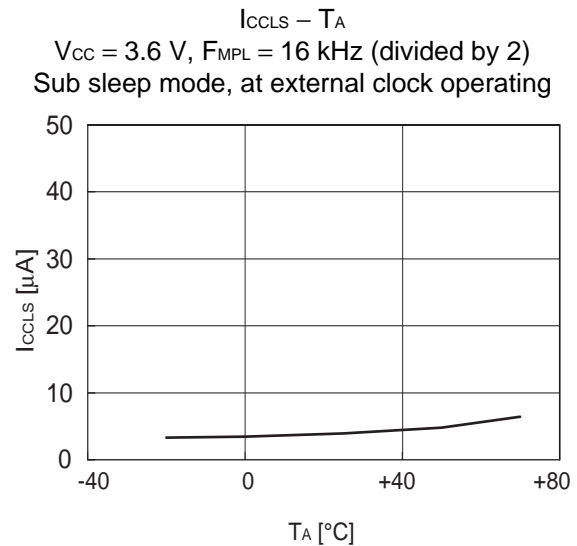
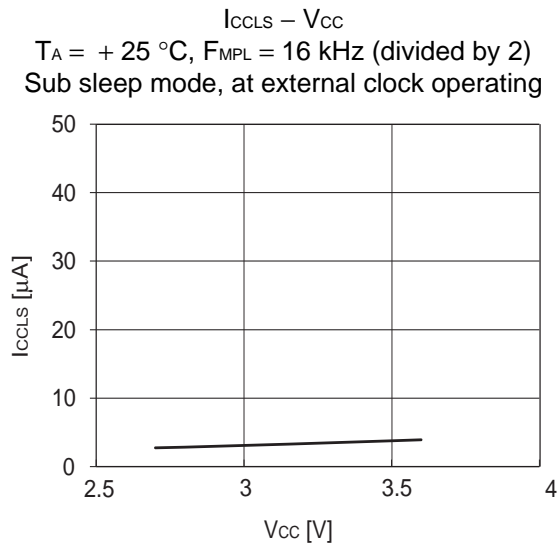
Parameter	Value			Unit	Remarks
	Min	Typ	Max		
Number of read/write cycle	10^{10}	10^{11}	—	cycle	

EXAMPLE CHARACTERISTICS

- Power supply current and temperature



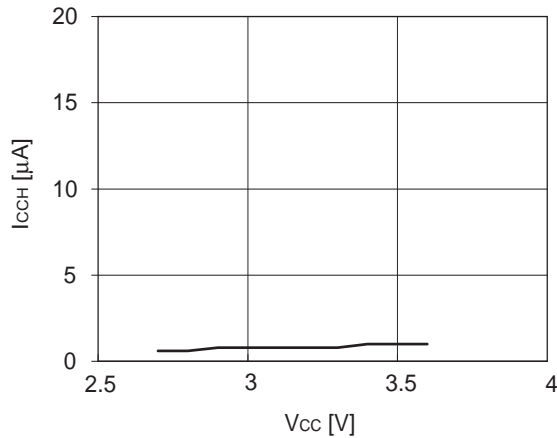
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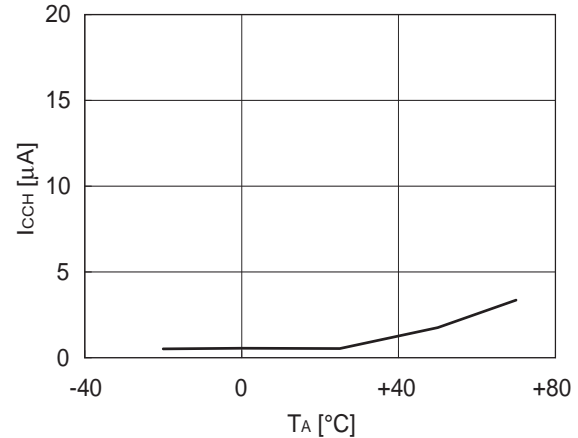
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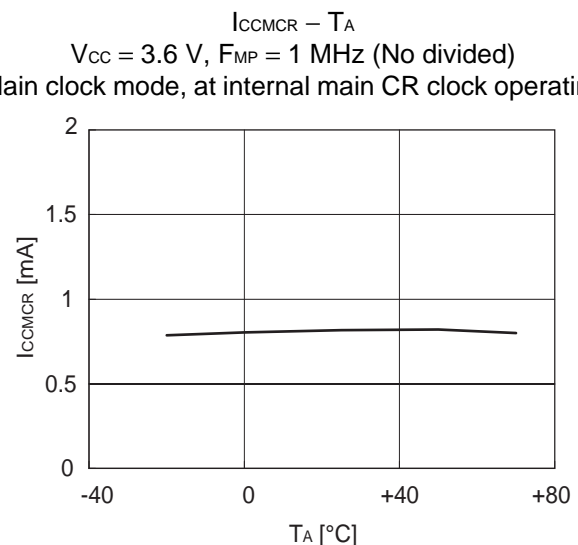
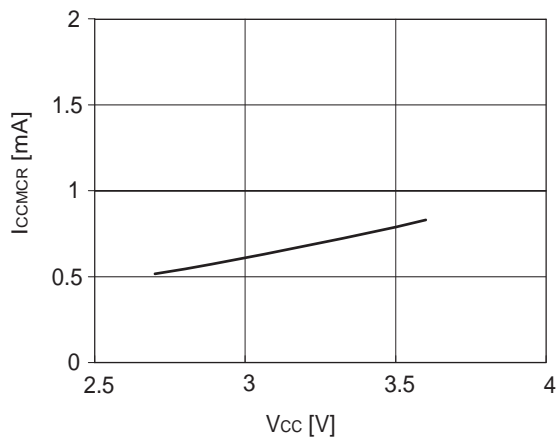
$I_{CCH} - V_{CC}$
 $T_A = +25^\circ\text{C}$, $F_{MPL} = (\text{stop})$
 Sub stop mode, at external clock stopping



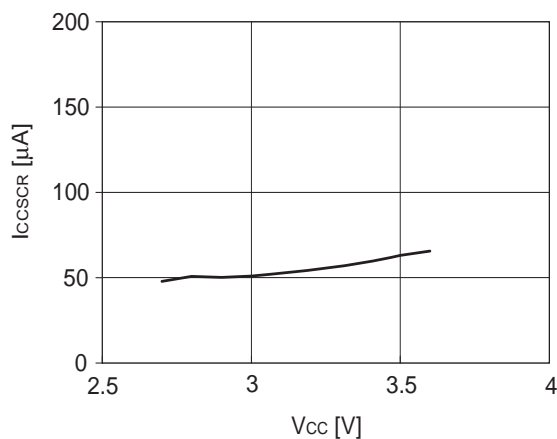
$I_{CCH} - T_A$
 $V_{CC} = 3.6\text{ V}$, $F_{MPL} = (\text{stop})$
 Sub stop mode, at external clock stopping



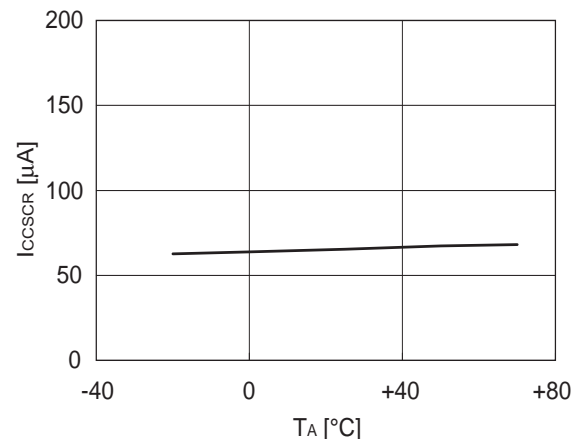
$I_{CCMCR} - V_{CC}$
 $T_A = +25^\circ\text{C}$, $F_{MP} = 1\text{ MHz}$ (No divided)
 Main clock mode, at internal main CR clock operating



$I_{CCSCR} - V_{CC}$
 $T_A = +25^\circ\text{C}$, $F_{MPL} = 50\text{ kHz}$ (divided by 2)
 Sub clock mode, at internal sub CR clock operating

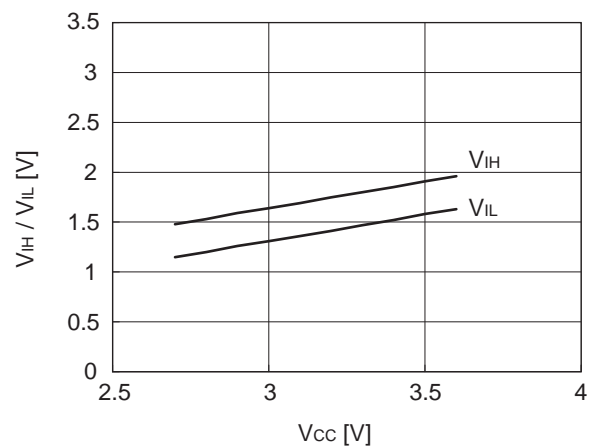


$I_{CCSCR} - T_A$
 $V_{CC} = 3.6\text{ V}$, $F_{MPL} = 50\text{ kHz}$ (divided by 2)
 Sub clock mode, at internal sub CR clock operating

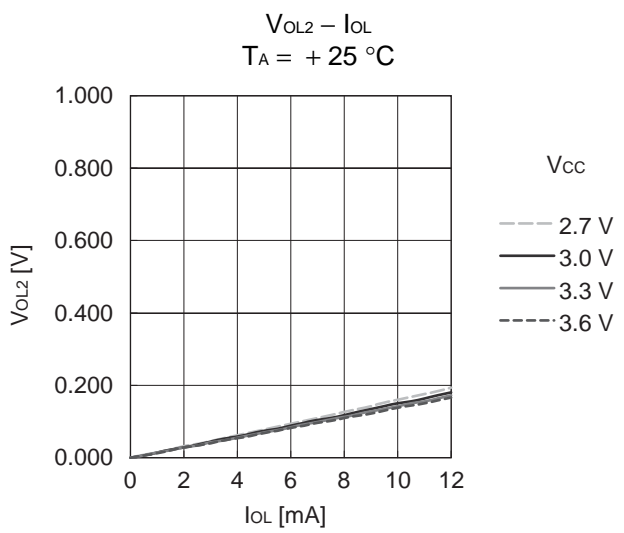
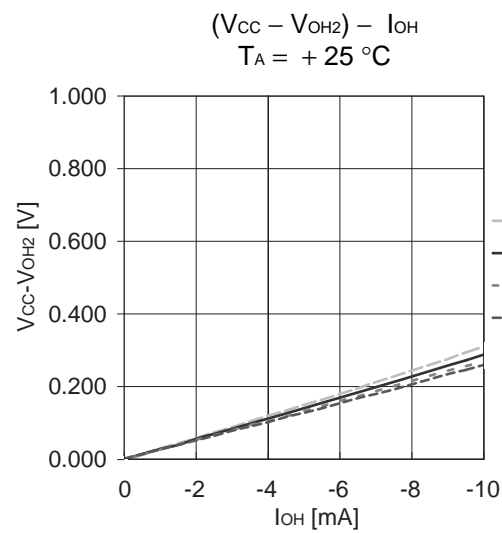
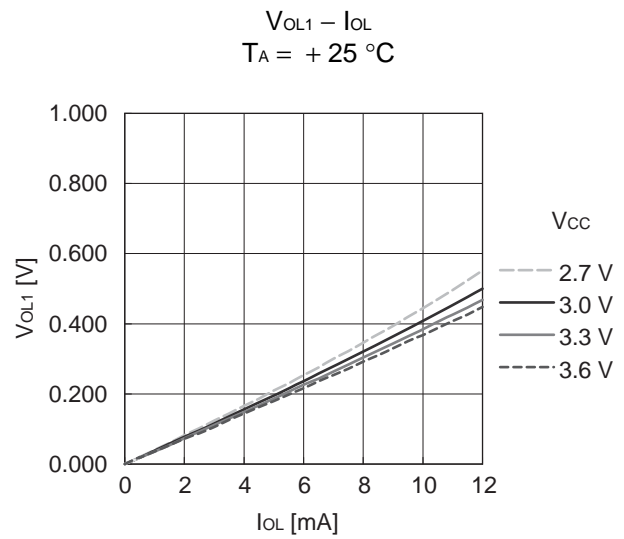
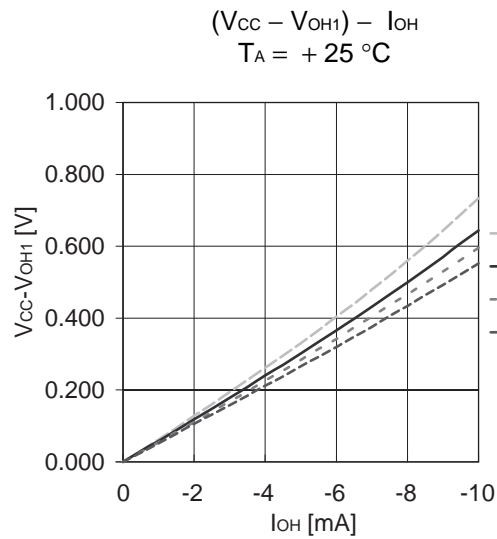


- Input voltage

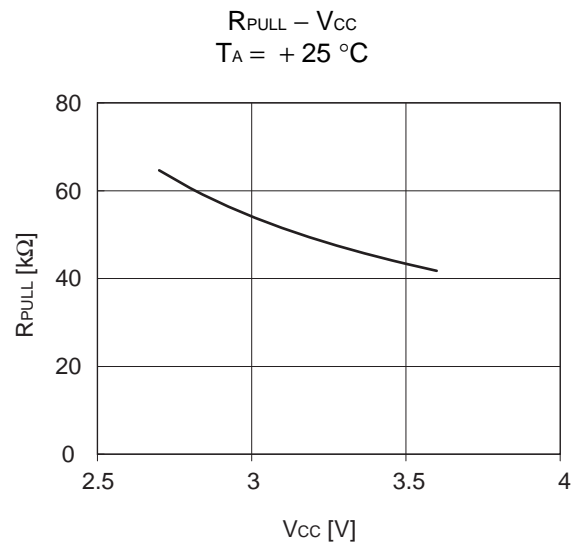
$V_{IH1}, V_{IH2}, V_{IHS1}, V_{IHS2}, V_{IHM} - V_{CC}$ and
 $V_{IL}, V_{ILS}, V_{ILM} - V_{CC}$
 $T_A = +25\text{ }^{\circ}\text{C}$



• Output voltage



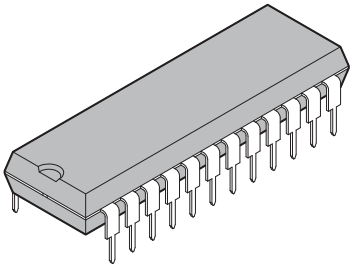
- Pull-up

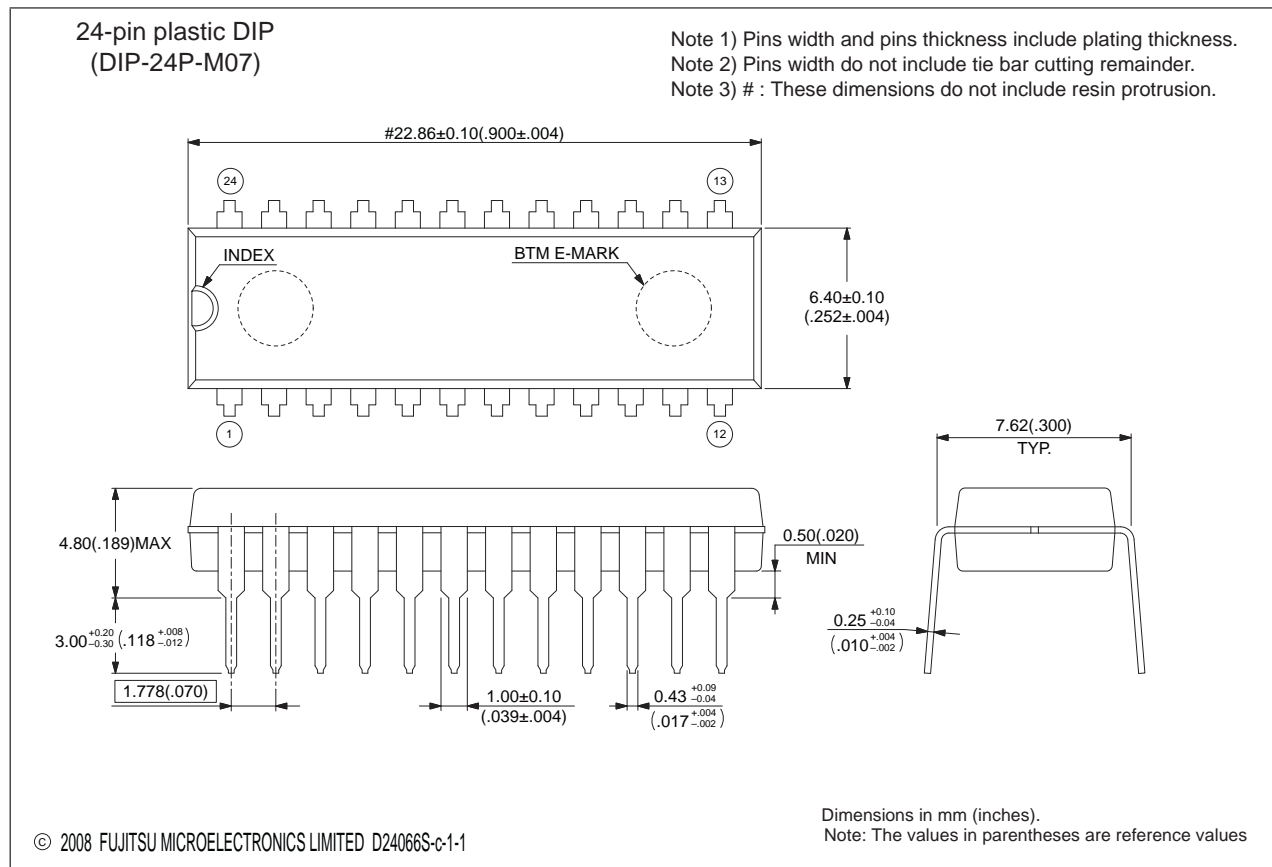


■ ORDERING INFORMATION

Part number	Package	Remarks
MB95R203P-G-SH-JNE2	24-pin plastic SDIP (DIP-24P-M07)	
MB95R203PF-G-JNE2	20-pin plastic SOP (FPT-20P-M09)	

■ PACKAGE DIMENSIONS

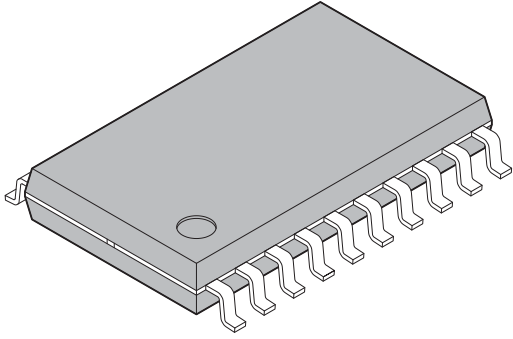
<p>24-pin plastic DIP</p>  <p>(DIP-24P-M07)</p>	Lead pitch	1.778 mm
	Package width × package length	6.40 mm × 22.86 mm
	Sealing method	Plastic mold
	Mounting height	4.80 mm Max

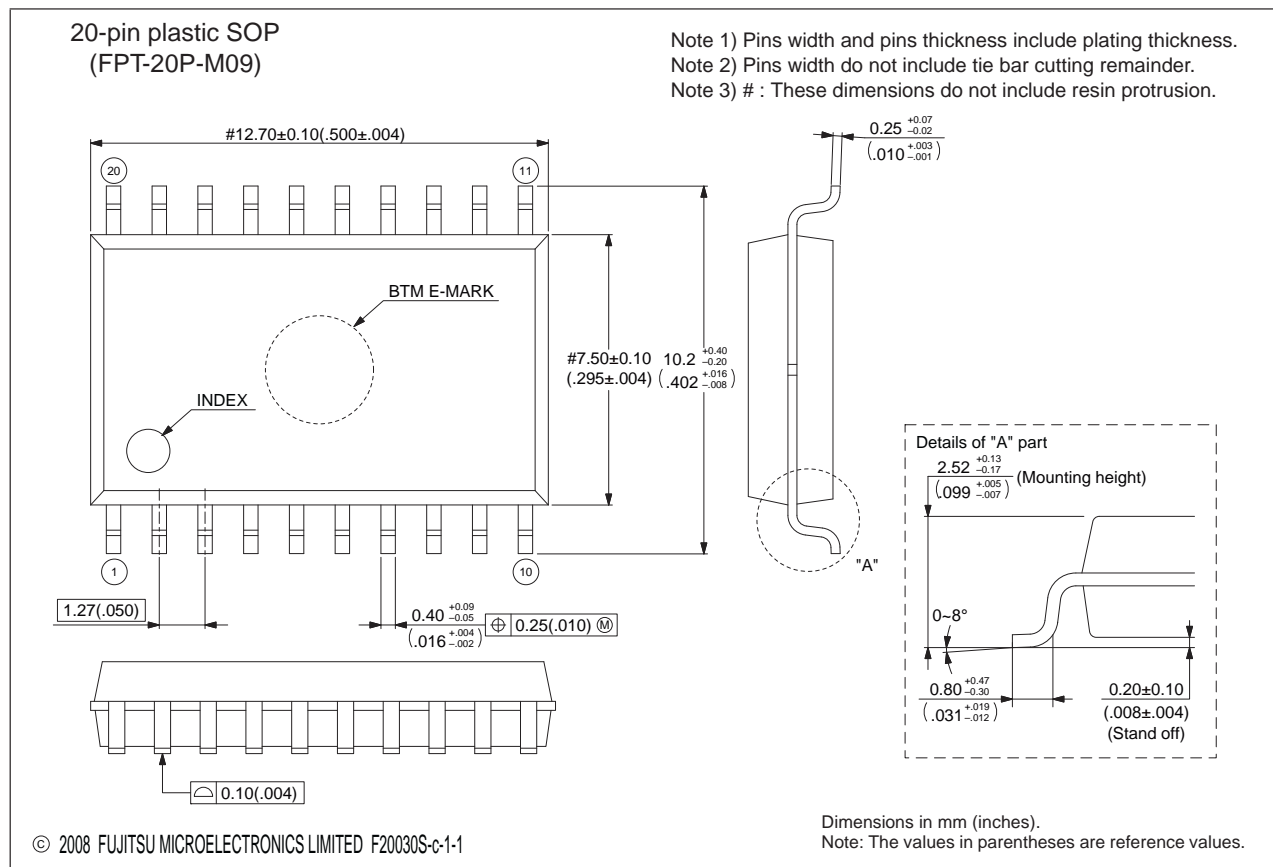


Please confirm the latest Package dimension by following URL.
<http://edevic.fujitsu.com/package/en-search/>

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<p>20-pin plastic SOP</p>  <p>(FPT-20P-M09)</p>	Lead pitch	1.27 mm
	Package width × package length	7.50 mm × 12.70 mm
	Lead shape	Gullwing
	Lead bend direction	Normal bend
	Sealing method	Plastic mold
	Mounting height	2.65 mm Max



Please confirm the latest Package dimension by following URL.
<http://edevic.fujitsu.com/package/en-search/>

■ MAIN CHANGES IN THIS EDITION

Page	Section	Change Results
—	—	Preliminary Data Sheet → Data Sheet
4	■ PRODUCT OVERVIEW	Corrected number of read/write cycles for FRAM. 10 ¹¹ times → (Min)10 ¹⁰ times (Typ)10 ¹¹ times
9	■ I/O CIRCUIT TYPE	Corrected the remarks of Type G. CMOS input → CMOS output
12	■ NOTES ON DEBUG	Corrected the address. F555 _H → F554 _H
15	■ I/O MAP	Corrected the register abbreviation and the register name for address 000B _H . WTCR → WPCR Watch timer control register → Watch prescaler control register
17		Changed the register name for address 0F89 _H , 0F8A _H , and 0F8B _H to (disabled).
24	■ ELECTRICAL CHARACTERISTICS 3. DC Characteristics	Added “T _A = + 25 °C” to the condition for “Power supply current (I _{CCLS})”.
32	4. AC Characteristics (4) Power-on Reset	Corrected the voltage for “Hold Condition in stop mode”. 2.3 V → 2.6 V
45 to 50	■ EXAMPLE CHARACTERISTICS	Added the section.

The vertical lines marked in the left side of the page show the changes.

MEMO

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