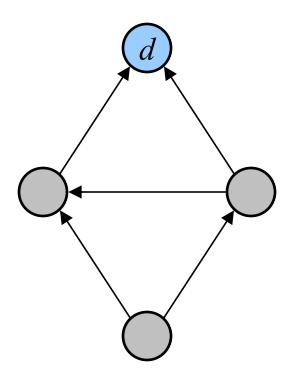
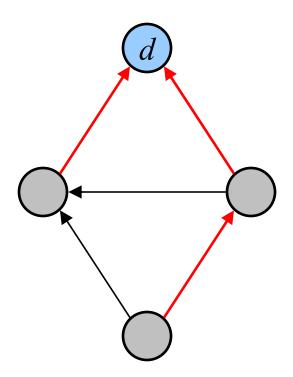
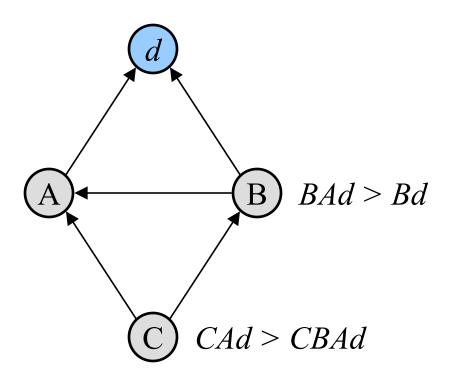
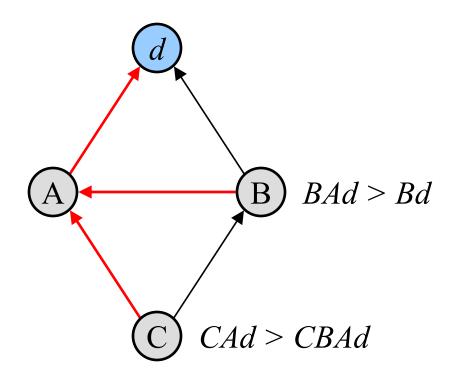
The complexity of a restricted variant of the stable paths problem

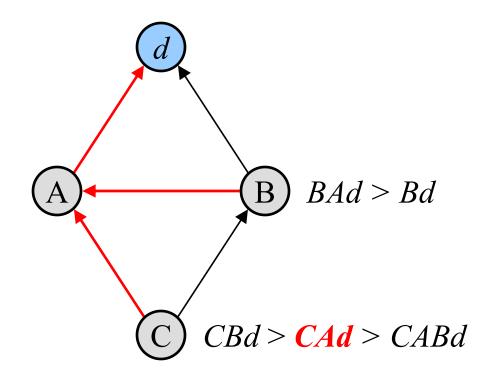
Andrei Lapets
Based on joint work with Kevin Donnelly and Assaf Kfoury
April 23, 2010

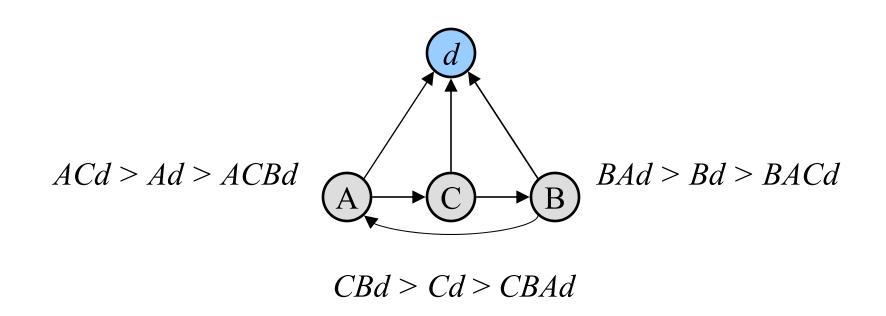


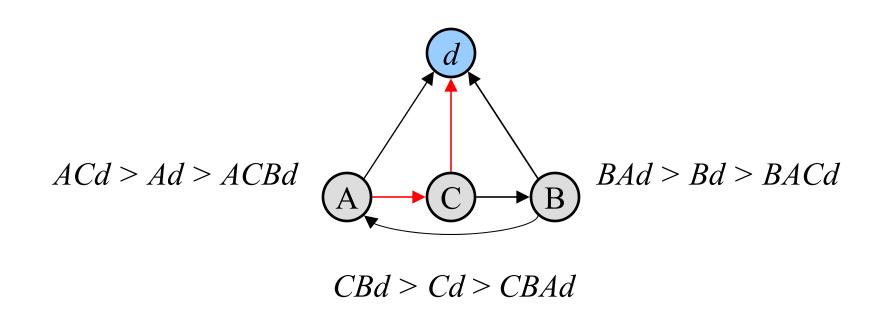


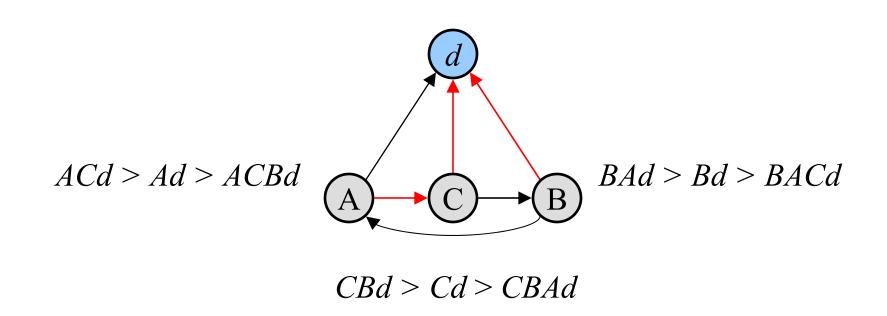


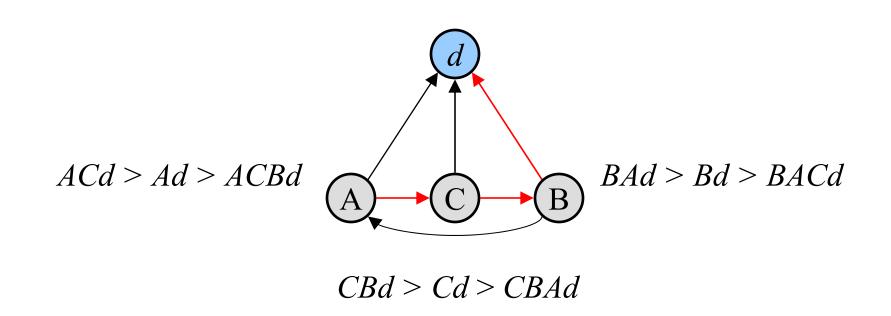


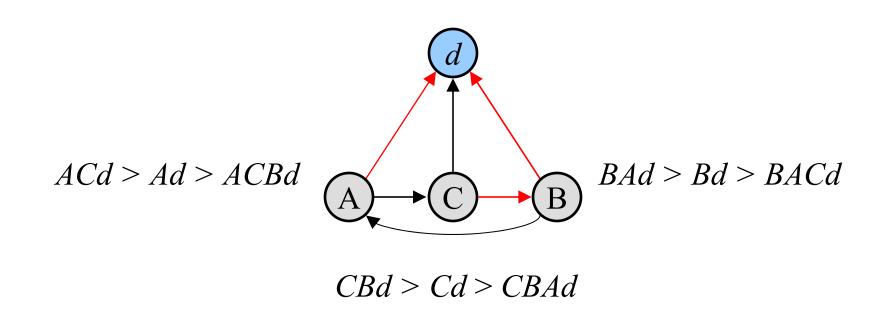


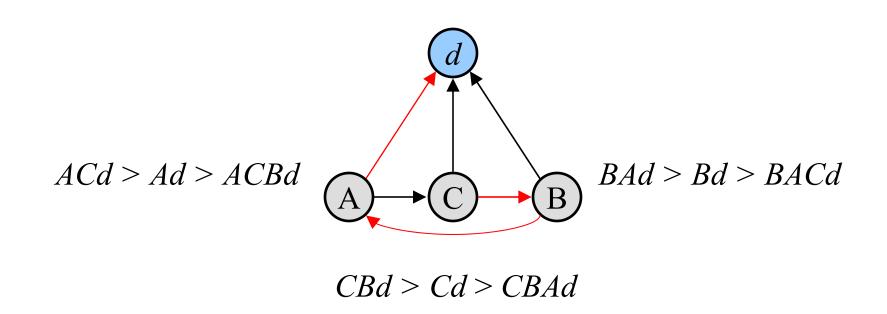


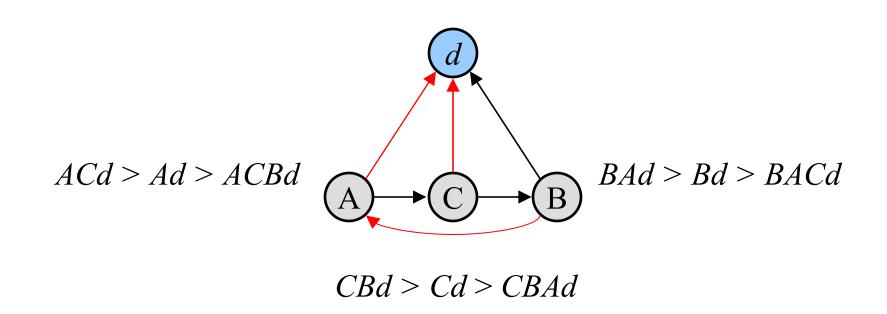


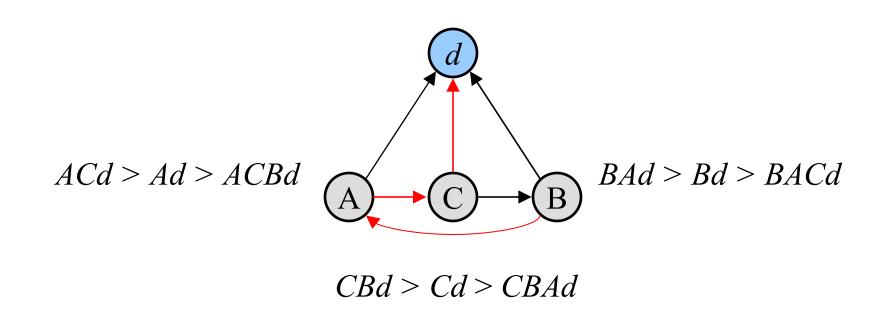


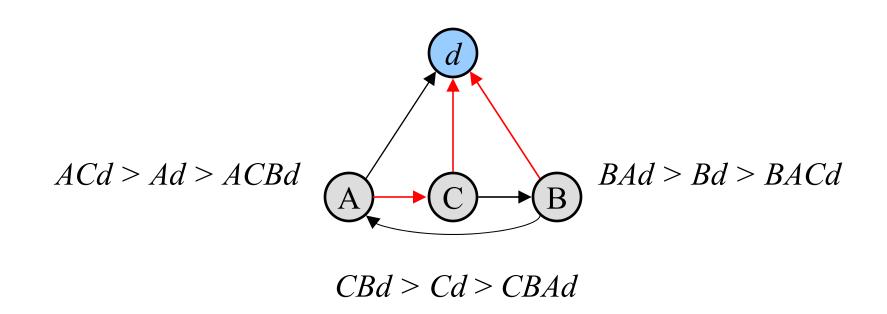


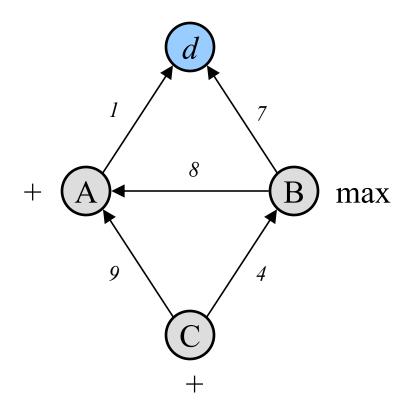




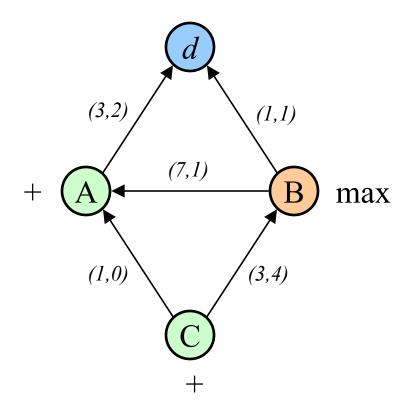






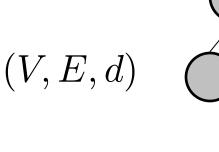


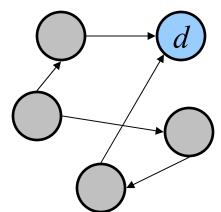
path rankings using aggregates prefix preservation



path rankings using aggregates prefix preservation

f-SPP problem instance

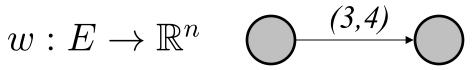




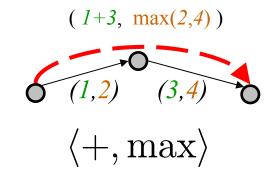
$$\pi: V \to n$$



$$w: E \to \mathbb{R}^n$$



$$\overline{f} = \langle f_1, \dots, f_n \rangle$$



Given an \overline{f} -SPP instance

$$(V, E, d), \pi, w, \langle f_1, \ldots, f_n \rangle,$$

does there exist a stable solution?

Given an \overline{f} -SPP instance

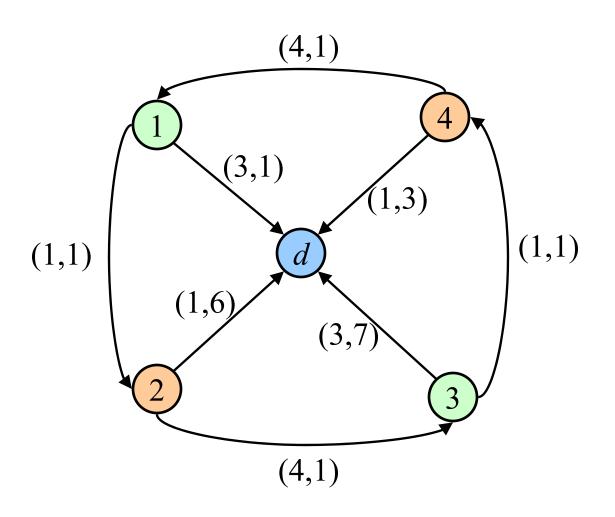
 $(V, E, d), w, \langle f_1, \ldots, f_n \rangle,$

does there exist a solution that is stable under all possible π ?

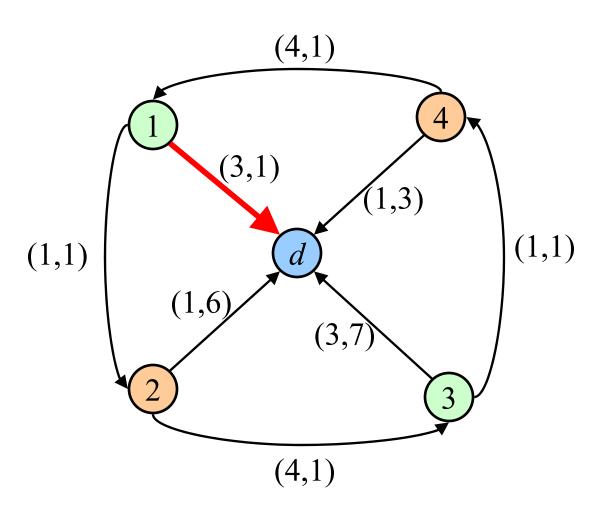
Given an \overline{f} -SPP instance

$$(V, E, d), \pi, w, \langle f_1, \ldots, f_n \rangle,$$

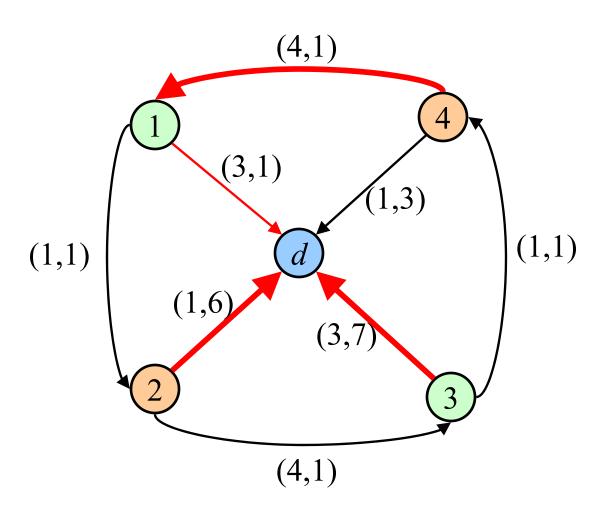
does there exist a stable solution?



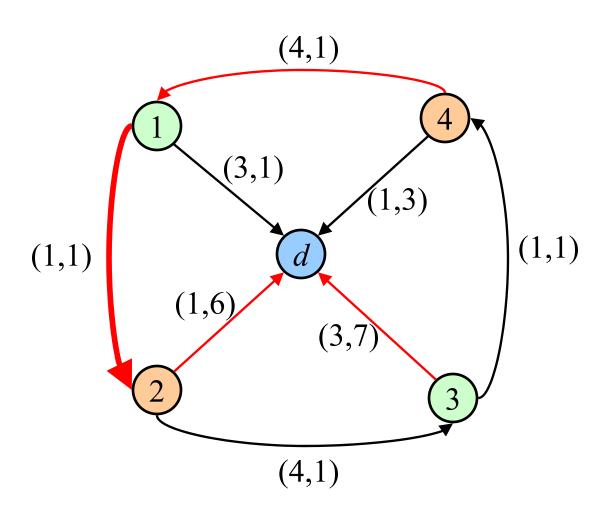
$$\overline{f} = \langle \max, \max \rangle$$



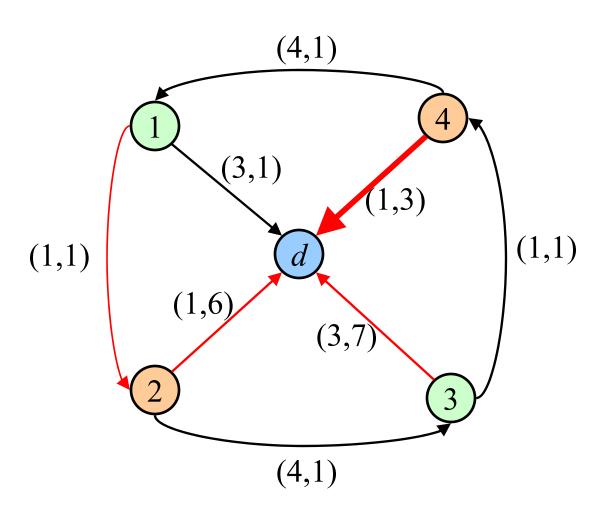
$$\overline{f} = \langle \max, \max \rangle$$



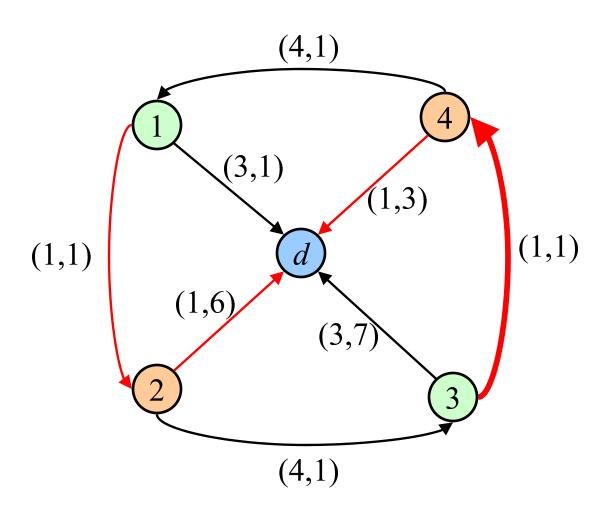
$$\overline{f} = \langle \max, \max \rangle$$



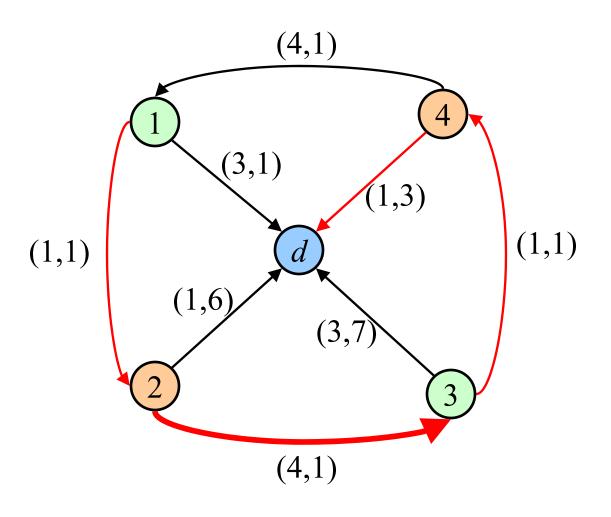
 $\overline{f} = \langle \max, \max \rangle$



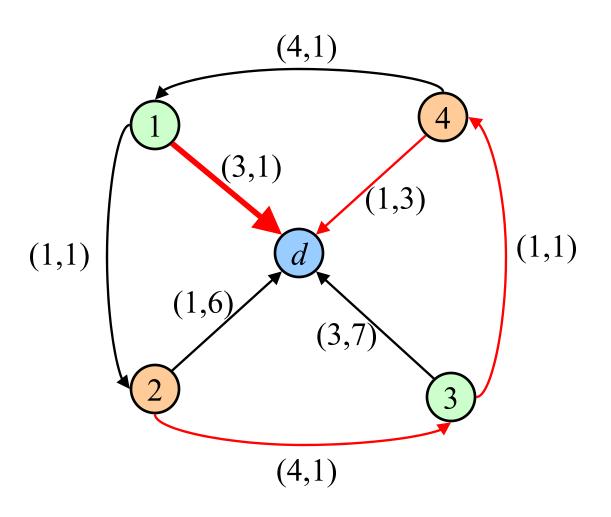
$$\overline{f} = \langle \max, \max \rangle$$



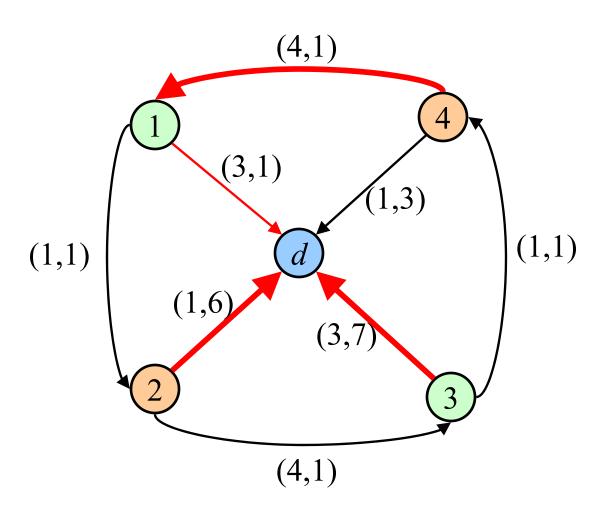
$$\overline{f} = \langle \max, \max \rangle$$



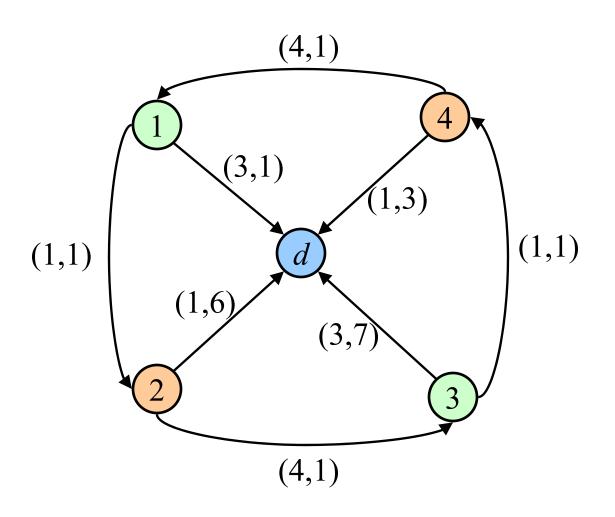
$$\overline{f} = \langle \max, \max \rangle$$



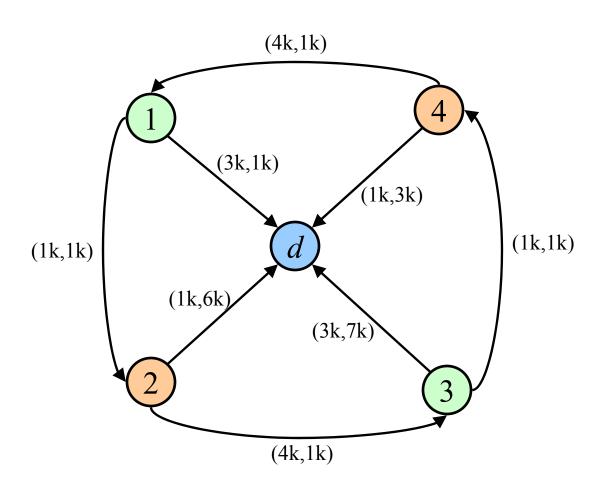
$$\overline{f} = \langle \max, \max \rangle$$



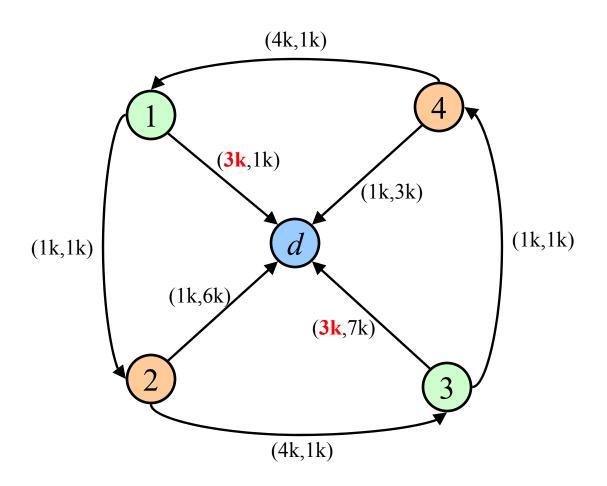
$$\overline{f} = \langle \max, \max \rangle$$



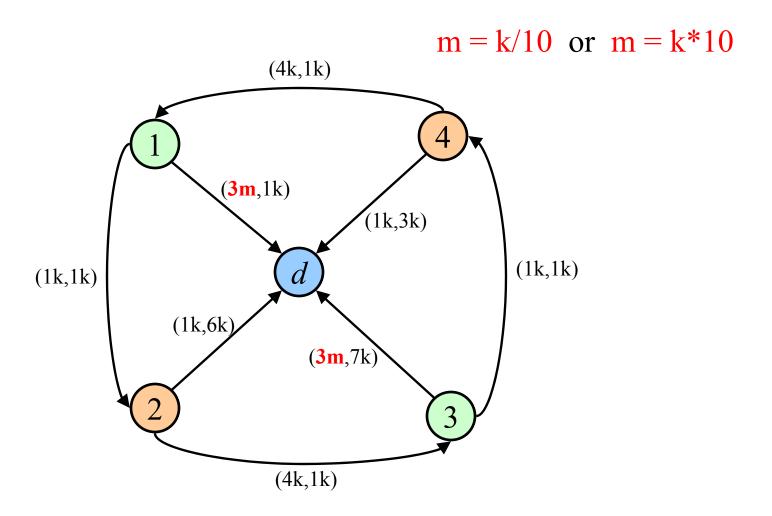
$$\overline{f} = \langle \max, \max \rangle$$



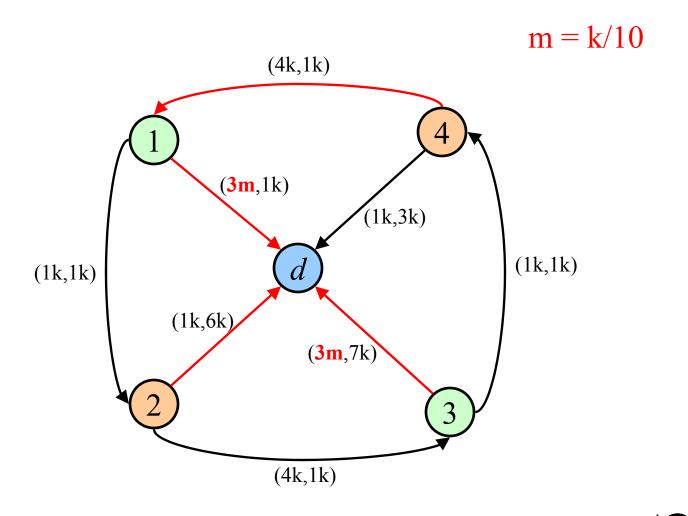
$$\overline{f} = \langle \text{max}, \text{max} \rangle$$



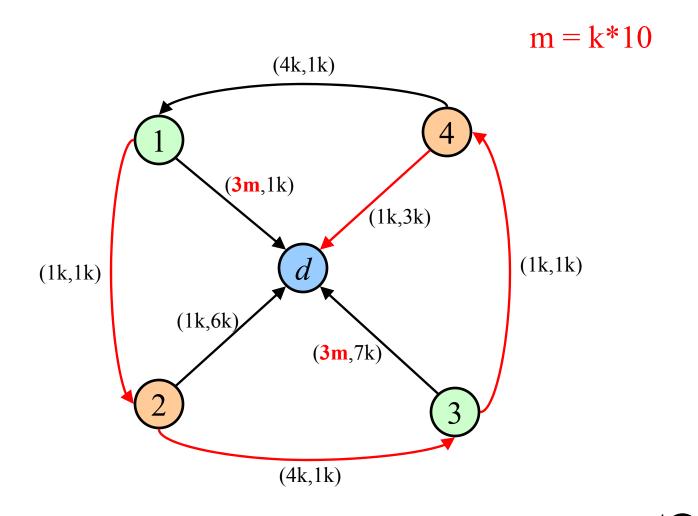
$$\overline{f} = \langle \max, \max \rangle$$



$$\overline{f} = \langle \mathbf{max}, \mathbf{max} \rangle$$



$$\overline{f} = \langle \mathbf{max}, \mathbf{max} \rangle$$



$$\overline{f} = \langle \max, \max \rangle$$

Given an \overline{f} -SPP instance

$$(V, E, d), \pi, w, \langle f_1, \ldots, f_n \rangle,$$

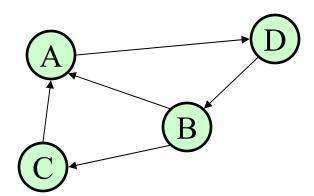
does there exist a stable solution?

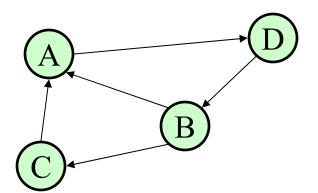
instance of the Hamiltonian circuit problem



instance of $\langle \max, \max \rangle$ -SPP

s.t. a circuit exists iff a stable solution exists





A

A

A

(A)

B

B

B

 $\left(\mathbf{B}\right)$

 \bigcirc

 \bigcirc

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 \bigcirc

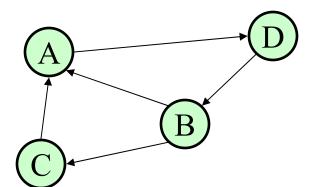
(D)

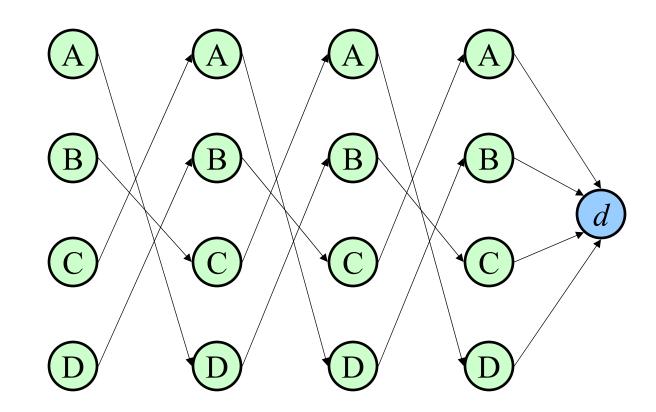
(D)

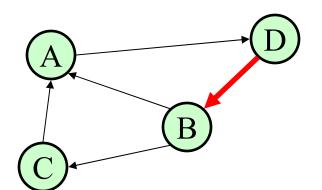
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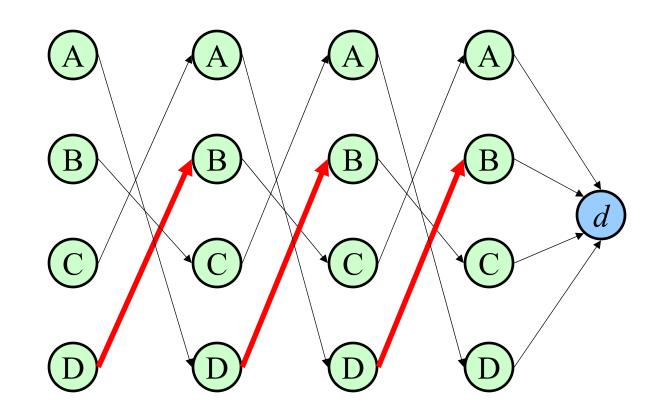
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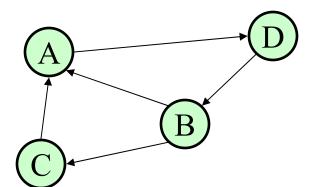
d

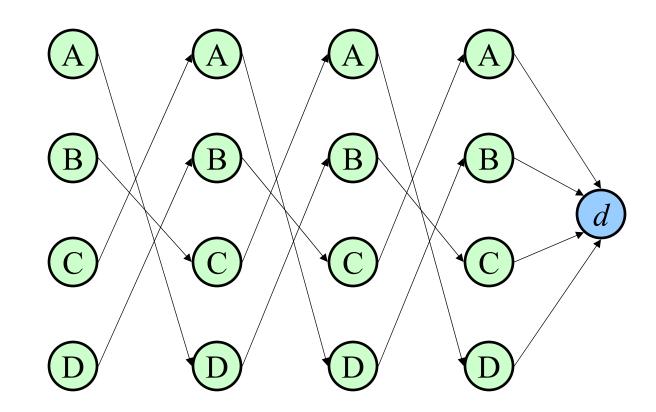


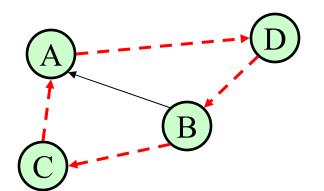


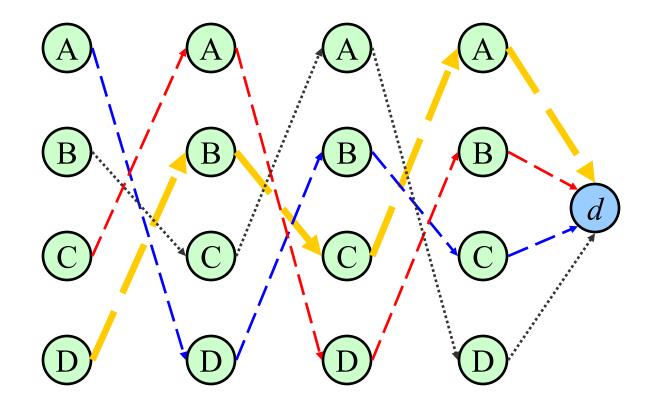


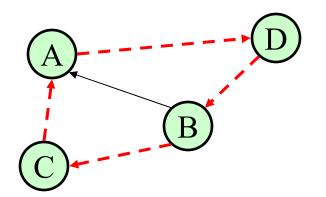


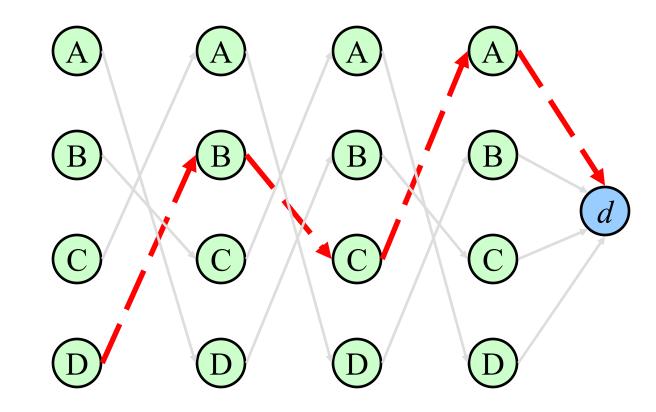


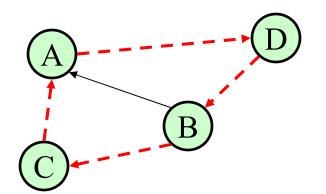


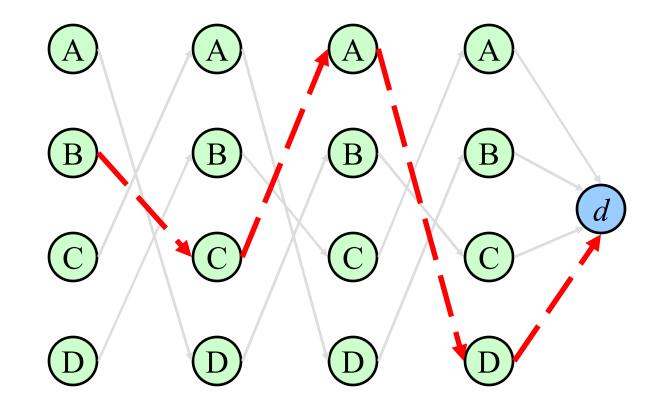


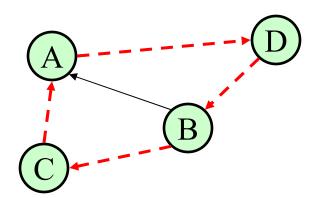


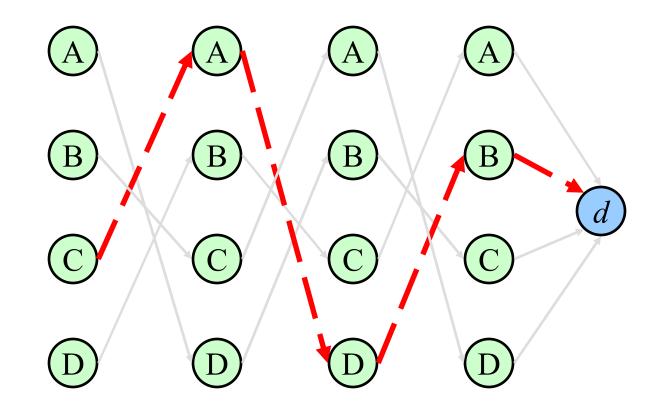


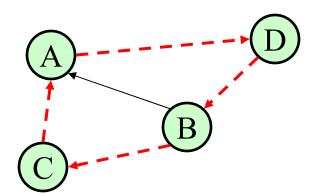


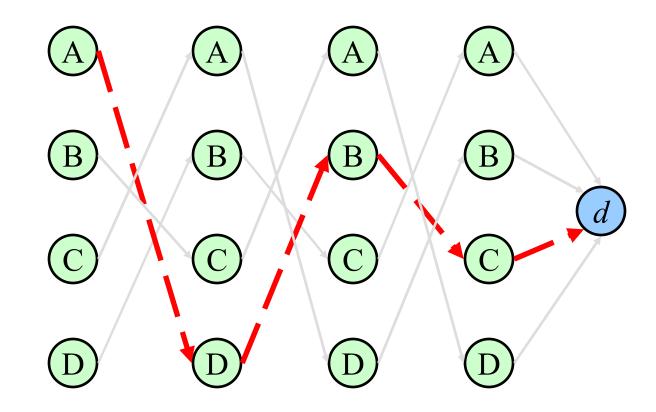


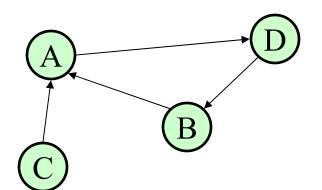


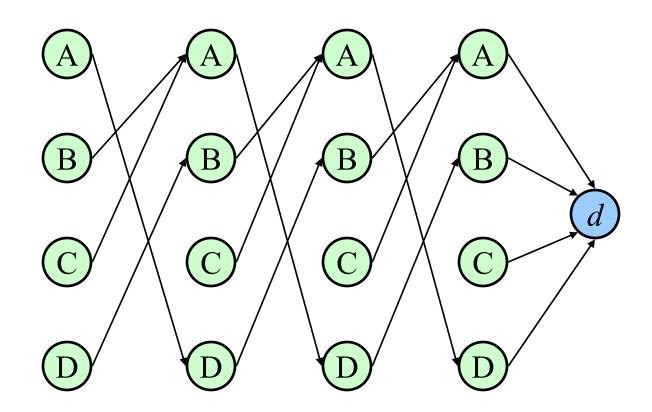


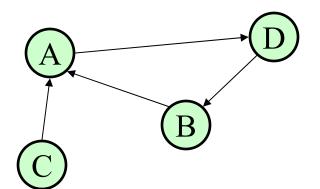


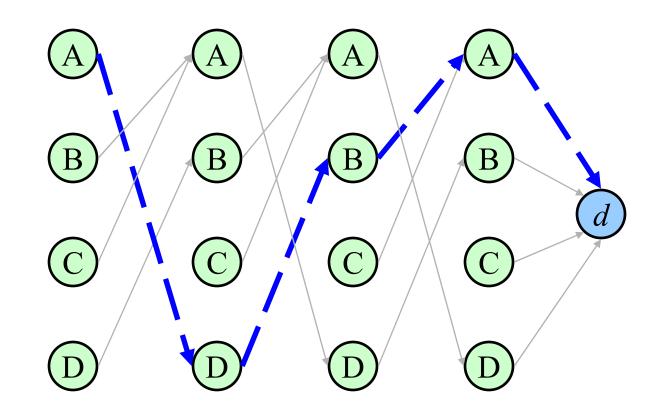


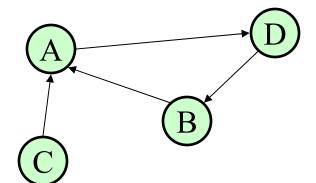








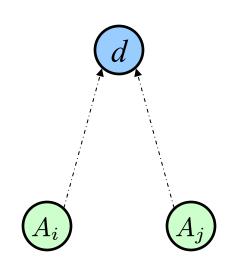


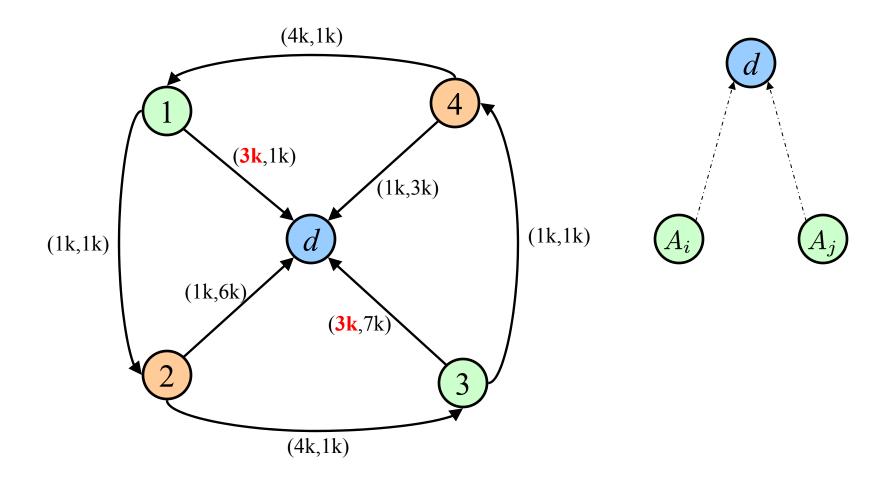


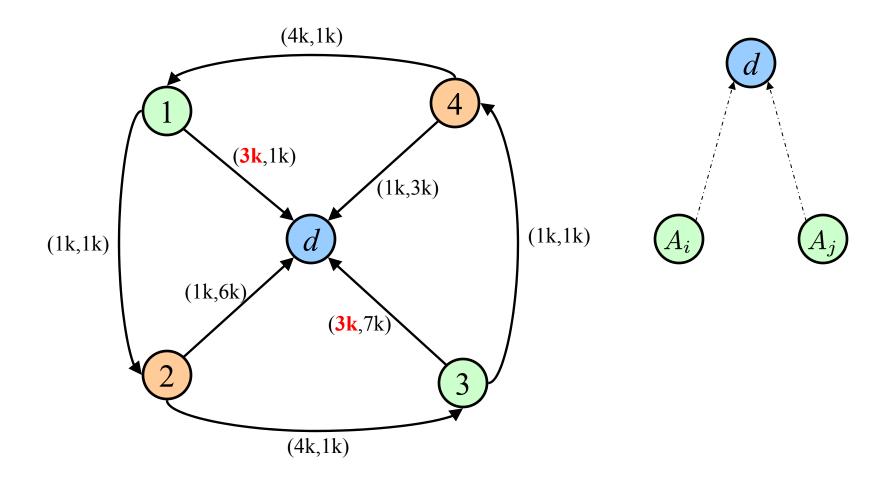


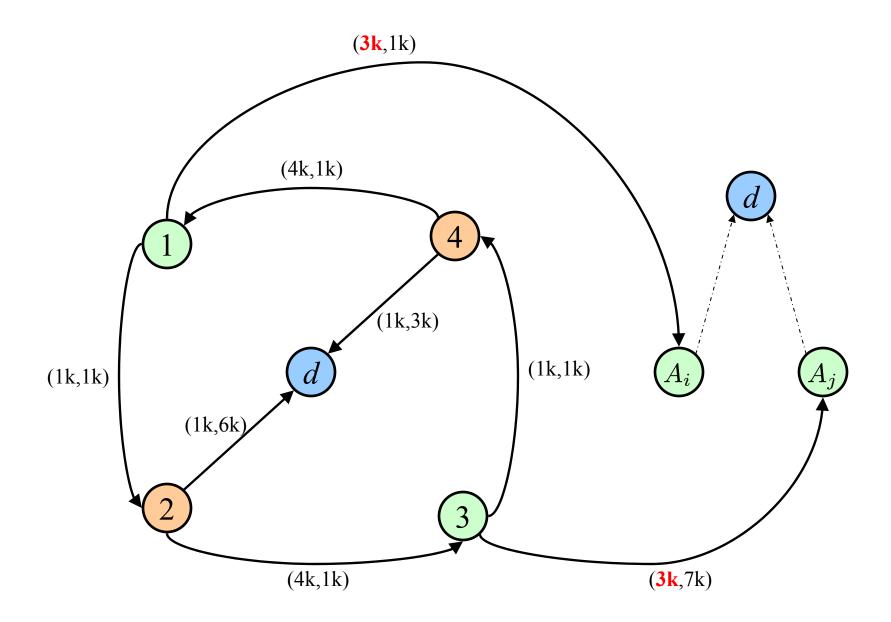


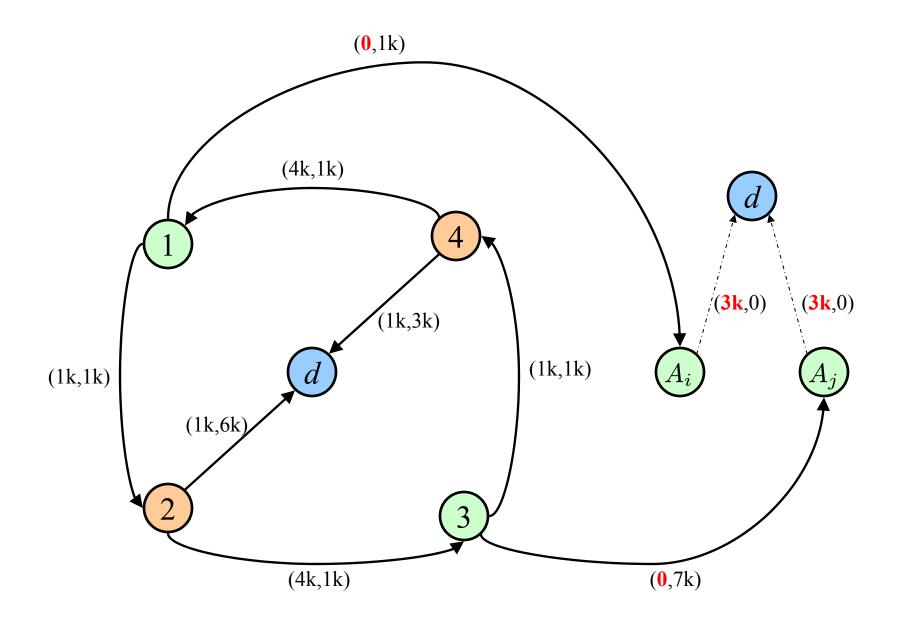


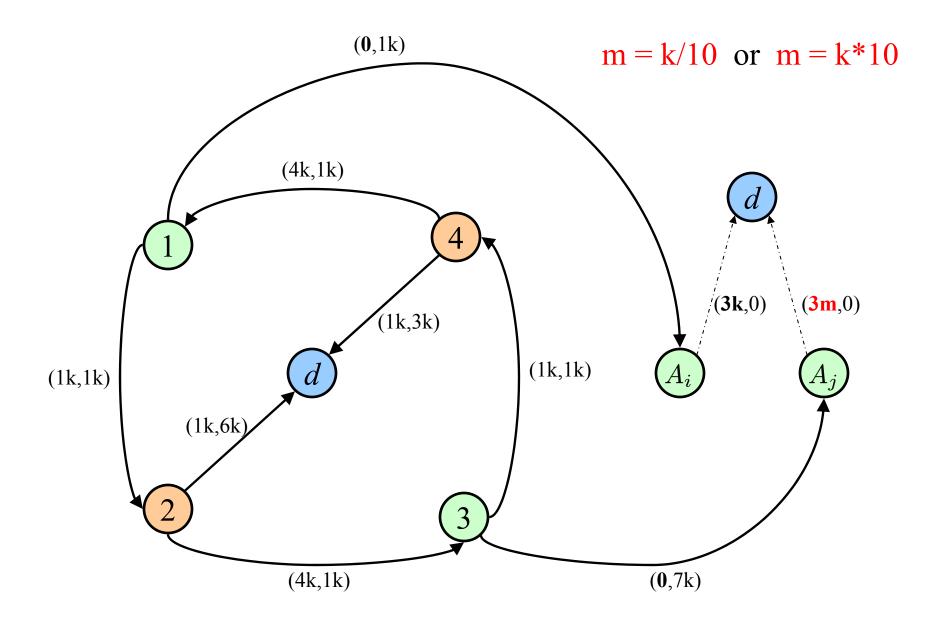


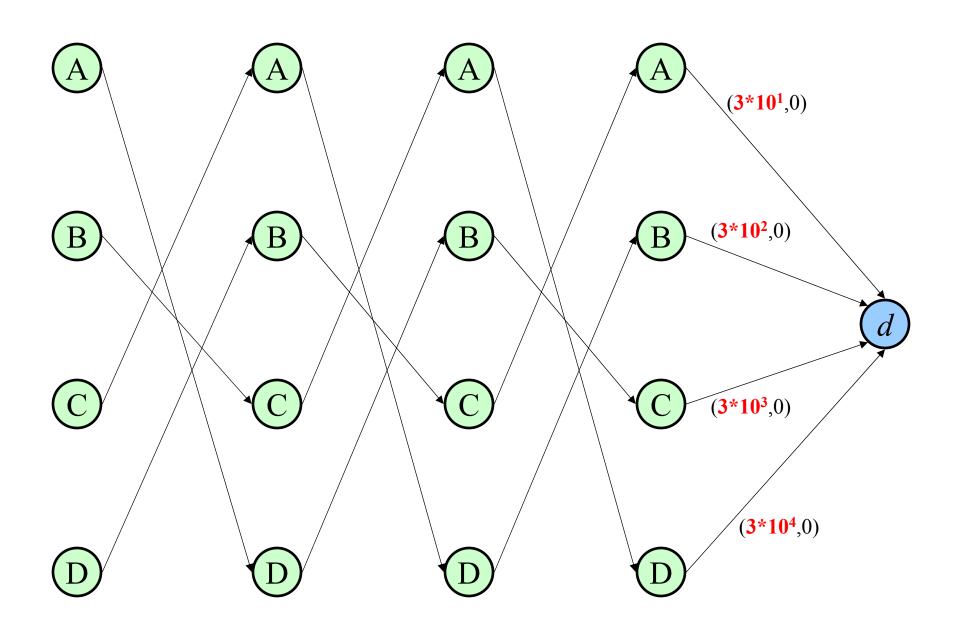


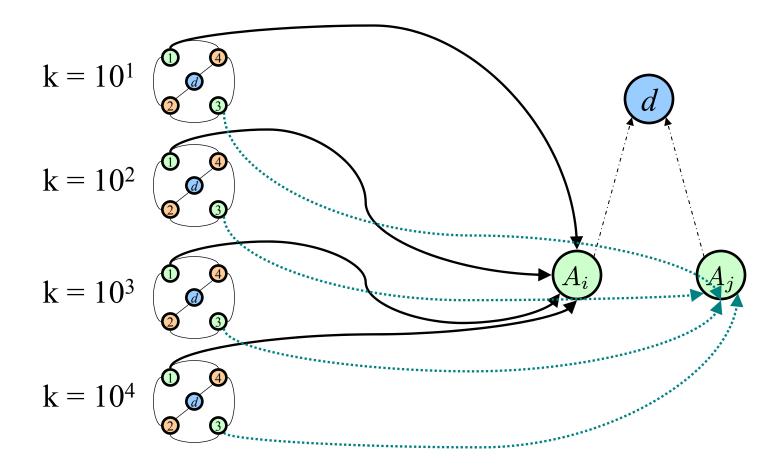


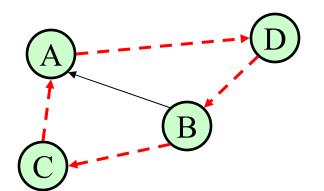


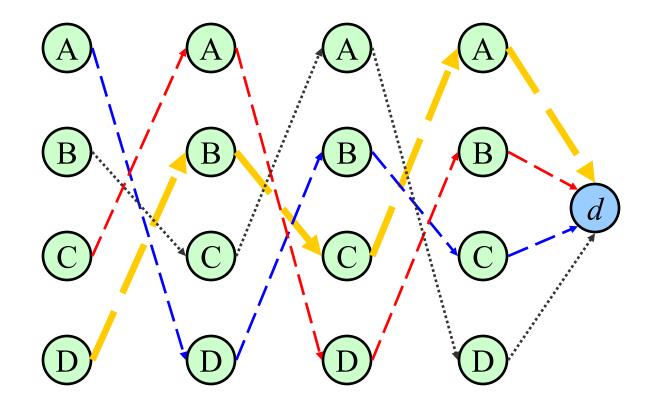












stable solution

- no subgraph is unstable
- no path from any A_i crossing another A_i
- Hamiltonian circuit must exist

no stable solutions

- some subgraph is unstable
- path through an A_i always crosses an A_j
- no Hamiltonian circuit exists

Given an \overline{f} -SPP instance

 $(V, E, d), w, \langle f_1, \ldots, f_n \rangle,$

does there exist a solution that is stable under all possible π ?

