

# ACDC DAQ Programers Manual

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# 1 Introduction

This document is intended to document the commands sent to the ACC and ACDC cards.

It includes source listings of the source and destinations for each command as they were when this documentation was written. New implementations may have been written since, but that is outside the scope of this document.

The command protocol for each 32-bit instruction set is shown in [Figure 1](#).

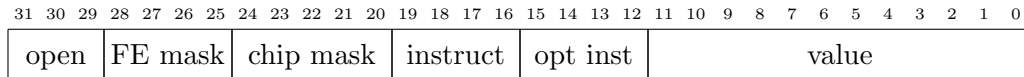


Figure 1: Command protocol

This is parsed on the front-end board like this

|                    |    |                               |
|--------------------|----|-------------------------------|
| INSTRUCT_PSEC_MASK | <= | xINSTRUCT_WORD(24 downto 20); |
| INSTRUCTION        | <= | xINSTRUCT_WORD(19 downto 16); |
| INSTRUCTION_OPT    | <= | xINSTRUCT_WORD(15 downto 12); |
| INSTRUCT_VALUE     | <= | xINSTRUCT_WORD(11 downto 0);  |

[Table 1](#) lists all the instruction flags passed by software.

The instruction for setting self-trigger instructions has many optional instructions, listed in [Table 2](#).

Table 1: List of Instructions

| Bits | Description                               |
|------|---|
| 0x0  | Do nothing                                |
| 0x1  | Set delay-locked loop VDD control voltage |
| 0x2  | Calibration pulse switch enable           |
| 0x3  | Set pedestal                              |
| 0x4  | Reset DLL                                 |
| 0x5  | Reset internal trigger                    |
| 0x6  | Set self trigger mask                     |
| 0x7  | Set self trigger instructions             |
| 0x8  | Set trigger threshold                     |
| 0x9  | Adjust ring oscillation frequency         |
| 0xA  | Enable/disable on-board LEDs              |
| 0xB  | (DC) Central card FIFO toggle             |
| 0xB  | (CC) Central card done                    |
| 0xC  | (CC) Central card read mode               |
| 0xD  | (CC) Align/setup SERDES                   |
| 0xE  | (CC) USB trigger                          |
| 0xF  | (CC) Sync USB                             |

Table 2: Optional instructs for 0x7 - set self-trigger instructions

| Bits | Description             |
|------|-------------------------|
| 0x0  | Enable                  |
| 0x1  | Wait for system trigger |
| 0x2  | Measure rate only       |
| 0x3  | Trigger sign            |

## 2 Instructions

|      |  |    |
|------|--|----|
| 2.1  | 0x1 - Set DLL VDD . . . . .                | 5  |
| 2.2  | 0x2 -Toggle Cal . . . . .                  | 7  |
| 2.3  | 0x3 -Set Pedestal Value . . . . .          | 9  |
| 2.4  | 0x4 - Reset DLL . . . . .                  | 11 |
| 2.5  | 0x4 - Reset Self Trigger . . . . .         | 13 |
| 2.6  | 0x4 - Reset Time Stamp . . . . .           | 14 |
| 2.7  | 0x4 - Reset ACDC . . . . .                 | 15 |
| 2.8  | 0x4 - Hard Reset . . . . .                 | 16 |
| 2.9  | 0x4 - USB Force Wakeup . . . . .           | 17 |
| 2.10 | 0x6 - Set Self-trigger Mask . . . . .      | 18 |
| 2.11 | 0x7 - Set Self-trigger Lo . . . . .        | 20 |
| 2.12 | 0x7 - Set Self-trigger hi . . . . .        | 22 |
| 2.13 | 0x8 - Set Self-trigger Threshold . . . . . | 24 |
| 2.14 | 0x9 - Set RO Target Count . . . . .        | 26 |
| 2.15 | 0xA - Toggle LED . . . . .                 | 28 |
| 2.16 | 0xA - Read ACDC Ram . . . . .              | 30 |
| 2.17 | 0xB - Manage CC FIFO . . . . .             | 32 |
| 2.18 | 0xB - Prep Sync . . . . .                  | 33 |
| 2.19 | 0xB - Make Sync . . . . .                  | 34 |
| 2.20 | 0xB - System Card Trig Valid . . . . .     | 35 |
| 2.21 | 0xC - Set USB Read Mode . . . . .          | 36 |
| 2.22 | 0xD - Align LVDS . . . . .                 | 39 |
| 2.23 | 0xE - Software Trigger . . . . .           | 40 |
| 2.24 | 0xF - Sync Usb . . . . .                   | 42 |

## 2.1 0x1 - Set DLL VDD

This sets the dll vdd

### 2.1.1 Bit Fields

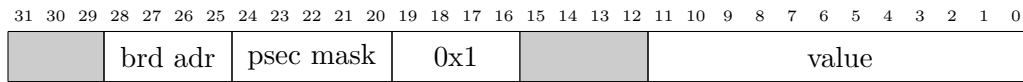


Figure 2: Command 0x1 bit fields

| Bits  | Name          | Description                     |
|-------|---------------|---------------------------------|
| 28-25 | board address | The address of the board        |
| 24-20 | psec mask     | The psec chips to apply this to |
| 19-16 | <b>0x1</b>    | Command marker                  |
| 11-0  | value         | VDD Value                       |

### 2.1.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_dll_vdd(unsigned int VALUE,
    unsigned int boardAdr,
    int device,
    unsigned int psec_mask)
{
    createUSBHandles();
    const unsigned int hi_cmd = 0x00010000;
    unsigned int send_word = hi_cmd | VALUE | boardAdr <<
        ↪ boardAdrOffset
    | psec_mask << psecAdrOffset;

    if(device == 0)                usb.sendData(send_word);
    if(device == 1 && mode==USB2x) usb2.sendData(send_word);

    closeUSBHandles();
}
```

### 2.1.3 Destination

`project:path/to/filename.vhd`

---

## 2.2 0x2 -Toggle Cal

### 2.2.1 Bit Fields

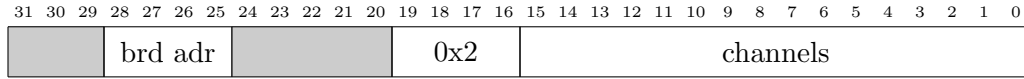


Figure 3: 0x2 - Cal enabled

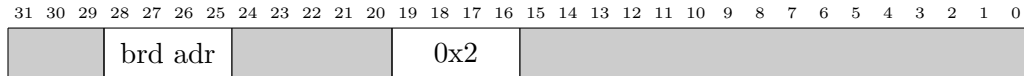


Figure 4: 0x2 - Cal disabled

| Bits  | Name          | Description                             |
|-------|---------------|---|
| 28-25 | board address | The address of the board (default = 15) |
| 19-16 | <b>0x2</b>    | Command marker                          |
| 15-0  | channels      | Channels (default = 0x7FFF)             |
|       |               | Not used if cal is disabled             |

### 2.2.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::toggle_CAL( bool EN,  int device)
{
    createUSBHandles();

    unsigned int send_word = 0x00020000;
    unsigned int channels  = 0x7FFF;
    unsigned int boardAdr  = 15;

    if(EN){
        send_word = send_word | boardAdr <<
            ↪ boardAdrOffset | channels;
        if(device == 0)                usb.sendData(
            ↪ send_word);
        if(device == 1 && mode==USB2x)  usb2.sendData(
            ↪ send_word);
    }
}

```

```

    } else{
        send_word = send_word | boardAdr <<
            ↪ boardAdrOffset;
        if(device == 0)                usb.sendData(
            ↪ send_word);
        if(device == 1 && mode==USB2x) usb2.sendData(
            ↪ send_word);
    }
closeUSBHandles();
}

```

### 2.2.3 Destination

project:path/to/filename.vhd

---



## 2.3 0x3 -Set Pedestal Value

### 2.3.1 Bit Fields

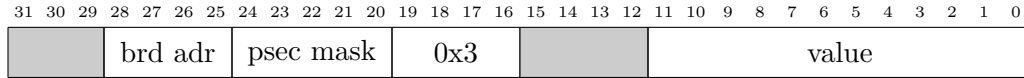


Figure 5: Command 0x3 bit fields

| Bits  | Name          | Description                             |
|-------|---------------|---|
| 28-25 | board address | The address of the board (default = 15) |
| 24-20 | psec mask     | Mask for chip addresses                 |
| 19-16 | <b>0x2</b>    | Command marker                          |
| 12-0  | value         | Pedestal value (default = 0x800)        |

### 2.3.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::set_pedestal_value( unsigned int PED_VALUE,
unsigned int boardAdr,
int device,
unsigned int psec_mask)
{
    createUSBHandles();
    const unsigned int hi_cmd = 0x00030000;
    unsigned int send_word = hi_cmd | PED_VALUE
    | boardAdr << boardAdrOffset
    | psec_mask << psecAdrOffset;

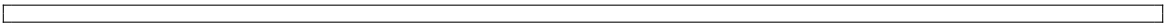
    if(device == 0)                usb.sendData(send_word);
    if(device == 1 && mode==USB2x)  usb2.sendData(send_word);

    closeUSBHandles();
}

```

### 2.3.3 Destination

project:path/to/filename.vhd



## 2.4 0x4 - Reset DLL

This command resets the DLL

### 2.4.1 Bit Fields

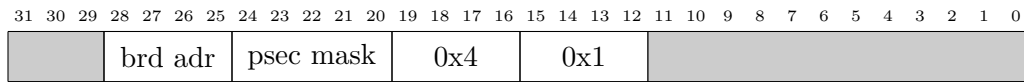


Figure 6: 0x4 Instruct Bit Fields

| Bits  | Name          | Description                       |
|-------|---------------|-----------------------------------|
| 28-25 | board address | The address of the board.         |
| 24-20 | psec mask     | Which psec chips to apply this to |
| 19-16 | <b>0x4</b>    | Command marker                    |
| 15-12 | <b>0x1</b>    | Optional command marker           |

### 2.4.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::reset_dll(bool sync)
{
    createUSBHandles();
    const unsigned int hi_cmd = 0x00041000;
    const unsigned int mask = 31; //chip mask
    unsigned int send_word = hi_cmd | mask << 20 | 15 <<
        ↪ boardAdrOffset;

    if(sync) prep_sync();
    usb.sendData(send_word); //dll reset pulse
    if(mode == USB2x) usb2.sendData(send_word);
    if(sync) make_sync();

    closeUSBHandles();
}

```

### 2.4.3 Destination

## 2.5 0x4 - Reset Self Trigger

This command resets the self trigger

### 2.5.1 Bit Fields

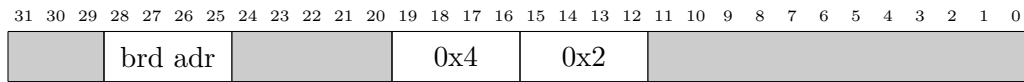


Figure 7: 0x4 Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0x4</b>    | Command marker            |
| 15-12 | <b>0x2</b>    | Optional command marker   |

### 2.5.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::reset_self_trigger(unsigned int boardAdr, int device)
{
    createUSBHandles();
    unsigned int send_word = 0x00042000 | boardAdr <<
        ↪ boardAdrOffset;

    if(device == 0) usb.sendData(send_word);
    if(device == 1 && mode == USB2x) usb2.sendData(send_word)
        ↪ ;

    closeUSBHandles();
}

```

### 2.5.3 Destination

|  |
|--|
|  |
|--|

## 2.6 0x4 - Reset Time Stamp

This command resets the time stamp

### 2.6.1 Bit Fields

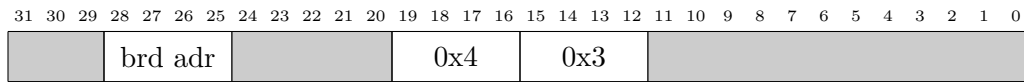


Figure 8: 0x4 Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0x4</b>    | Command marker            |
| 15-12 | <b>0x3</b>    | Optional command marker   |

### 2.6.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::reset_time_stamp(bool sync)
{
    createUSBHandles();
    unsigned int send_word = 0x00043000 | 15 <<
        ↪ boardAdrOffset;

    if(sync) prep_sync();
    usb.sendData(send_word);
    if(mode == USB2x) usb2.sendData(send_word);
    if(sync) make_sync();

    closeUSBHandles();
}

```

### 2.6.3 Destination

## 2.7 0x4 - Reset ACDC

This command resets the acdc

### 2.7.1 Bit Fields

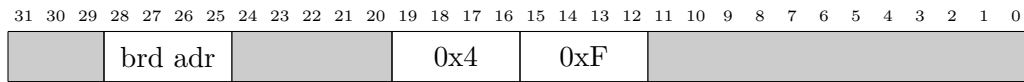


Figure 9: 0x4 Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0x4</b>    | Command marker            |
| 15-12 | <b>0xF</b>    | Optional command marker   |

### 2.7.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::reset_acdc()
{
    usb.createHandles();
    unsigned int send_word = 0x0004F000 | 15 <<
        ↪ boardAdrOffset;

    usb.sendData(send_word);
    if(mode == USB2x) usb2.sendData(send_word);

    closeUSBHandles();
}

```

### 2.7.3 Destination

## 2.8 0x4 - Hard Reset

This command resets the acdc

### 2.8.1 Bit Fields

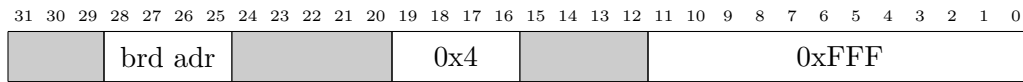


Figure 10: 0x4 Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0x4</b>    | Command marker            |
| 11-0  | <b>0xFFF</b>  | Hard reset value          |

### 2.8.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::hard_reset( bool DEVICE)
{
    usb.createHandles();
    unsigned int send_word = 0x00040FFF | 15 <<
        ↪ boardAdrOffset;
    usb.sendData(send_word);
    if(mode == USB2x && DEVICE==true) usb2.sendData(send_word
        ↪ );
    closeUSBHandles();
}
```

### 2.8.3 Destination



## 2.9 0x4 - USB Force Wakeup

This command resets the acdc

### 2.9.1 Bit Fields

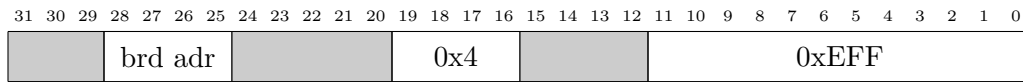


Figure 11: 0x4 Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0x4</b>    | Command marker            |
| 11-0  | <b>0xEFF</b>  | USB wakeup value          |

### 2.9.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::usb_force_wakeup()
{
    usb.createHandles();
    unsigned int send_word = 0x00040EFF;
    usb.sendData(send_word);
    if(mode == USB2x) usb2.sendData(send_word);

    closeUSBHandles();
}
```

### 2.9.3 Destination

|  |
|--|
|  |
|--|

## 2.10 0x6 - Set Self-trigger Mask

This command sends certain trigger mask

### 2.10.1 Bit Fields

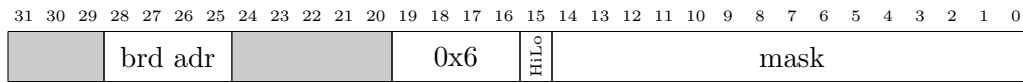


Figure 12: 0x6

| Bits  | Name          | Description                                       |
|-------|---------------|---|
| 28-25 | board address | The address of the board.                         |
| 19-16 | <b>0x6</b>    | Command marker                                    |
| 15    | HiLo          | Which half of the mask is being sent <sup>1</sup> |
| 14-0  | mask          | AC/DC channel mask                                |

### 2.10.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_self_trigger_mask(int mask, bool HiLo, unsigned
    ↪ int boardAdr, int device)
{
    unsigned int hi_cmd;
    if(HiLo) hi_cmd = 0x00068000;
    else     hi_cmd = 0x00060000;

    unsigned int send_word = hi_cmd | mask | boardAdr <<
        ↪ boardAdrOffset;

    createUSBHandles();
    if(device == 0)                usb.sendData((unsigned
        ↪ int)send_word);
    if(device == 1 && mode == USB2x) usb2.sendData((unsigned
        ↪ int)send_word);
```

<sup>1</sup>When set to 0, the values for the 15 least significant bits are sent, which correspond to channels 1-15. When set to 1, the values for the 15 most significant bits are sent, which correspond to channels 16-30.

```
}      closeUSBHandles ( ) ;
```

### 2.10.3 Destination

## 2.11 0x7 - Set Self-trigger Lo

This command sends certain trigger commands

### 2.11.1 Bit Fields

|         |    |    |    |    |    |    |    |    |    |    |    |    |    |    |    |     |    |    |    |     |    |   |   |   |   |       |   |   |   |     |      |     |      |      |     |    |
|---------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|-----|----|---|---|---|---|-------|---|---|---|-----|------|-----|------|------|-----|----|
| 31      | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15  | 14 | 13 | 12 | 11  | 10 | 9 | 8 | 7 | 6 | 5     | 4 | 3 | 2 | 1   | 0    |     |      |      |     |    |
| brd adr |    |    |    |    |    |    |    |    |    |    |    |    |    |    |    | 0x7 |    |    |    | 0x0 |    |   |   | 0 |   | coinc |   |   |   | val | coin | sma | sign | rate | sys | en |

Figure 13: Command 0x7 bit fields

| Bits  | Name               | Description   |
|-------|--------------------|---|
| 28-25 | board address      | The address of the board. Default is 0xF              |
| 19-16 | <b>0x7</b>         | Command marker  |
| 15-12 | <b>0x0</b>         | Optional command marker                               |
| 10-7  | coincidence window | The window of unknown units for the coincidence (<15) |
| 6     | use trig valid     | Use trig valid as a reset on AC/DC                    |
| 5     | use coincidence    | Use channel coincidence                               |
| 4     | use board sma trig | Use SMA input on AC/DC board for trigger              |
| 3     | trig sign          | 1 for rising edge, 0 for falling edge                 |
| 2     | rate only          |   |
| 1     | sys trig option    |   |
| 0     | trig enable        | Enables self-trigger                                  |

### 2.11.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_self_trigger_lo(
    bool ENABLE_TRIG,
    bool SYS_TRIG_OPTION,
    bool RATE_ONLY,
    bool TRIG_SIGN,
    bool USE_BOARD_SMA_TRIG,
    bool USE_COINCIDENCE,
    bool USE_TRIG_VALID_AS_RESET,
    unsigned int coinc_window,
    unsigned int boardAdr,
    int device)
{
```

```

const unsigned int hi_cmd = 0x00070000;
unsigned int send_word = hi_cmd | 0 << 11
    | USE_TRIG_VALID_AS_RESET << 6
    | USE_COINCIDENCE << 5
    | USE_BOARD_SMA_TRIG << 4
    | TRIG_SIGN << 3 | RATE_ONLY << 2
    | SYS_TRIG_OPTION << 1 | ENABLE_TRIG
    | coinc_window << 7
    | boardAdr << boardAdrOffset;
//printf("%i\n", send_word);

createUSBHandles();

if(device == 0)                usb.sendData((unsigned int)
    ↪ send_word);
if(device == 1 && mode == USB2x) usb2.sendData((unsigned int)
    ↪ send_word);

closeUSBHandles();
}

```

### 2.11.3 Destination

---

## 2.12 0x7 - Set Self-trigger hi

This command sends certain trigger commands

### 2.12.1 Bit Fields

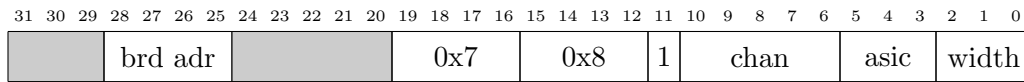


Figure 14: Command 0x7 bit fields

| Bits  | Name                    | Description  |
|-------|-------------------------|--|
| 28-25 | board address           | The address of the board.                              |
| 19-16 | <b>0x7</b>              | Command marker   |
| 15-12 | <b>0x8</b>              | Optional command marker                                |
| 10-6  | channel coincidence min | Number of coincident channels to enable trigger (<30)  |
| 5-3   | asic coincidence min    | Number of coincident asic chips to enable trigger (<5) |
| 2-0   | coincidence pulse width | Width of coincidence pulse in unknown units (<7)       |

### 2.12.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_self_trigger_hi(unsigned int coinc_pulse_width,
    unsigned int asic_coincidence_min,
    unsigned int channel_coincidence_min,
    unsigned int boardAdr,
    int device)
{
    const unsigned int hi_cmd = 0x00078000;
    unsigned int send_word = hi_cmd | 1 << 11
    | channel_coincidence_min << 6
    | asic_coincidence_min << 3
    | coinc_pulse_width
    | boardAdr << boardAdrOffset;
    //printf("%x\n", send_word);

    createUSBHandles();
}
```

```
    if(device == 0) usb.sendData((unsigned int)send_word);  
    if(device == 1 && mode == USB2x) usb2.sendData((unsigned  
        ↪ int)send_word);  
  
    closeUSBHandles();  
}
```

### 2.12.3 Destination

---

## 2.13 0x8 - Set Self-trigger Threshold

This command sets trigger threshold

For some reason this seems to create a word with the psec\_mask value assigned twice. It looks like he bit shifts it 20, but does the same thing again and bit shifts it by a defined value. Sorry if that doesn't make sense just look at the 4th line of the method.

### 2.13.1 Bit Fields

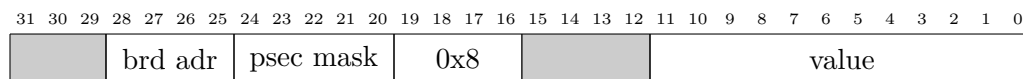


Figure 15: Command 0x8 bit fields

| Bits  | Name          | Description                       |
|-------|---------------|-----------------------------------|
| 28-25 | board address | The address of the board.         |
| 24-20 | psec mask     | Which psec chips to apply this to |
| 19-16 | <b>0x8</b>    | Command marker                    |
| 11-0  | value         | Trigger threshold value           |

### 2.13.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_trig_threshold(unsigned int TRIG_VALUE,
    unsigned int boardAdr,
    int device,
    unsigned int psec_mask)
{
    createUSBHandles();
    const unsigned int hi_cmd = 0x00080000;
    const unsigned int mask = 31; //chip mask
    unsigned int send_word = hi_cmd | TRIG_VALUE | psec_mask
        ↪ << 20 | boardAdr << boardAdrOffset
```



```
        | psec_mask << psecAdrOffset ;  
  
        if (device == 0)                usb.sendData(send_word);  
        if (device == 1 && mode==USB2x)  usb2.sendData(send_word);  
  
        closeUSBHandles();  
    }
```

### 2.13.3 Destination

---

## 2.14 0x9 - Set RO Target Count

This command sets the RO Target count. What is the RO target count?

### 2.14.1 Bit Fields

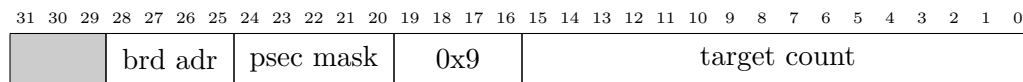


Figure 16: 0x9 Instruct Bit Fields

| Bits  | Name          | Description                       |
|-------|---------------|-----------------------------------|
| 28-25 | board address | The address of the board.         |
| 24-20 | psec mask     | Which psec chips to apply this to |
| 19-16 | <b>0x9</b>    | Command marker                    |
| 15-0  | target count  | The value of the ro target count  |

### 2.14.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::set_ro_target_count(unsigned int TARGET_RO_COUNT,
                                unsigned int boardAdr,
                                int device,
                                unsigned int psec_mask)
{
    createUSBHandles();
    const unsigned int hi_cmd = 0x00090000;
    unsigned int send_word = hi_cmd | TARGET_RO_COUNT |
        ↪ boardAdr << boardAdrOffset
        | psec_mask << psecAdrOffset;

    usb.sendData(send_word);
    if(mode==USB2x) usb2.sendData(send_word);

    closeUSBHandles();
}
```

### 2.14.3 Destination

|  |
|--|
|  |
|--|

## 2.15 0xA - Toggle LED

This command toggles the LED on all connected boards.

### 2.15.1 Bit Fields

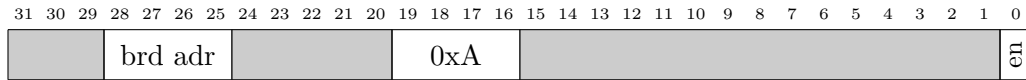


Figure 17: Command 0xA bit fields

| Bits  | Name          | Description                              |
|-------|---------------|--|
| 28-25 | board address | The address of the board. Default is 0xF |
| 19-16 | <b>0xA</b>    | Command marker                           |
| 0     | enable        | Enable the leds                          |

### 2.15.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::toggle_LED (bool EN)
{
    unsigned int boardAdr_all = 15;

    createUSBHandles();
    unsigned int send_word = 0x000A0000;
    send_word = send_word | boardAdr_all << boardAdrOffset;

    if (EN != false) {
        usb.sendData(send_word | 0x1);
        if (mode == USB2x) usb2.sendData(send_word | 0x1);
    }
    else {
        usb.sendData(send_word);
        if (mode == USB2x) usb2.sendData(send_word);
    }
    closeUSBHandles();
}

```

### 2.15.3 Destination

|  |
|--|
|  |
|--|

## 2.16 0xA - Read ACDC Ram

THIS COMMAND DOES NOT FOLLOW ERIC'S BASIC PROTOCOL OUTLINE (section 1, Figure 1)

### 2.16.1 Bit Fields

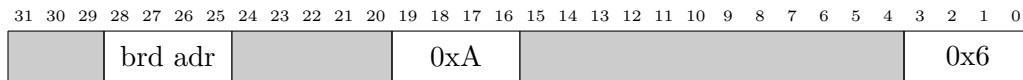


Figure 18: Command 0xA bit fields

| Bits  | Name          | Description                             |
|-------|---------------|---|
| 28-25 | board address | The address of the board (default = 15) |
| 19-16 | <b>0xA</b>    | Command marker                          |
| 3-0   | <b>0x6</b>    | Optional command marker                 |

### 2.16.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::readACDC_RAM(int device, unsigned int boardAdr)
{
    unsigned int boardAdr_override = 15;

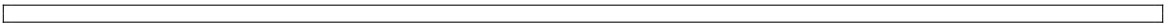
    createUSBHandles();
    unsigned int send_word = 0x000A0006;
    send_word = send_word | boardAdr << boardAdrOffset;

    if(device == 0)                usb.sendData(send_word);
    if(device == 1 && mode==USB2x)  usb2.sendData(send_word);

    closeUSBHandles();
}
```

### 2.16.3 Destination

project:path/to/filename.vhd



## 2.17 0xB - Manage CC FIFO

This command manages the CC FIFO

### 2.17.1 Bit Fields

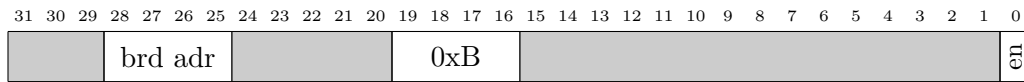


Figure 19: 0xB Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0xB</b>    | Command marker            |
| 0     | enable        | Enable CC FIFO            |

### 2.17.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::manage_cc_fifo(bool VALUE)
{
    usb.createHandles();
    const unsigned int hi_cmd = 0x000B0000;
    unsigned int send_word = hi_cmd | VALUE | 15 <<
        ↪ boardAdrOffset;
    usb.sendData(send_word);
    usb.freeHandles();
}
```

### 2.17.3 Destination



## 2.18 0xB - Prep Sync

This command preps sync

### 2.18.1 Bit Fields

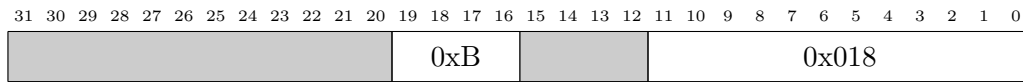


Figure 20: 0xB Instruct Bit Fields

| Bits  | Name         | Description     |
|-------|--------------|-----------------|
| 19-16 | <b>0xB</b>   | Command marker  |
| 11-0  | <b>0x018</b> | Prep sync value |

### 2.18.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::prep_sync()
{
    usb.createHandles();
    const unsigned int hi_cmd = 0x000B0018;
    unsigned int send_word = hi_cmd;
    usb.sendData(send_word);
    usb.freeHandles();
}
```

### 2.18.3 Destination

## 2.19 0xB - Make Sync

This command preps sync

### 2.19.1 Bit Fields

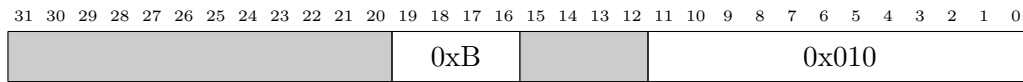


Figure 21: 0xB Instruct Bit Fields

| Bits  | Name         | Description     |
|-------|--------------|-----------------|
| 19-16 | <b>0xB</b>   | Command marker  |
| 11-0  | <b>0x010</b> | Make sync value |

### 2.19.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::make_sync()  
{  
    usb.createHandles();  
    const unsigned int hi_cmd = 0x000B0010;  
    unsigned int send_word = hi_cmd;  
    usb.sendData(send_word);  
    usb.freeHandles();  
}
```

### 2.19.3 Destination

## 2.20 0xB - System Card Trig Valid

This command validates system card triggers.

### 2.20.1 Bit Fields

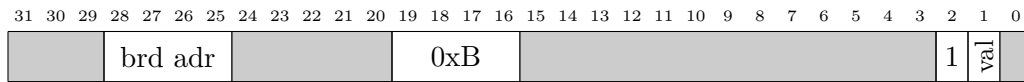


Figure 22: 0xB Instruct Bit Fields

| Bits  | Name          | Description               |
|-------|---------------|---------------------------|
| 28-25 | board address | The address of the board. |
| 19-16 | <b>0xB</b>    | Command marker            |
| 2     | <b>0x1</b>    | Optional command marker   |
| 1     | valid         | Validate system trigger   |

### 2.20.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::system_card_trig_valid(bool valid)
{
    usb.createHandles();
    const unsigned int hi_cmd = 0x000B0004;
    unsigned int send_word = hi_cmd | valid << 1 | 15 <<
        ↪ boardAdrOffset;;
    usb.sendData(send_word);
    usb.freeHandles();
}
```

### 2.20.3 Destination

## 2.21 0xC - Set USB Read Mode

This command sets the USB read mode. In the source code a few different modes are called frequently: 0, 5, and 16. 0 Corresponds to passing the USB instruction straight to the ACDC. 5 corresponds to reading out the CC buffer. 16 corresponds to setting the trig delay to 1.

### 2.21.1 Bit Fields

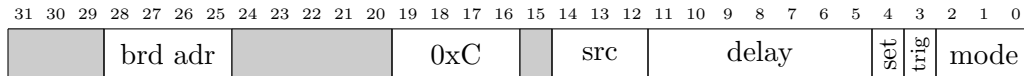


Figure 23: 0xC

| Bits  | Name            | Description   |
|-------|-----------------|---|
| 28-25 | board address   | The address of the board.   |
| 19-16 | <b>0xC</b>      | Command marker  |
| 14-12 | trig source     | If 4 is enabled, defines the trig source  |
| 11-5  | trig delay      |   |
| 4     | set trig source | If enabled, sets the trig source from bits 14-12                                  |
| 3     | trig mode       |   |
| 2-0   | read mode       | The value of the read mode. Shown further in <a href="#">subsubsection 2.21.2</a> |

### 2.21.2 Read Modes

| Bits | Mode                    | Description                |
|------|-------------------------|----------------------------|
| 000  | ACDC instruction        |                            |
| 111  | ACDC trig valid CC only |                            |
| 101  | Read CC buffer          | The value of the read mode |
| 110  |                         |                            |

### 2.21.3 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::set_usb_read_mode(unsigned int READ_MODE)
{
    usb.createHandles();
    const unsigned int hi_cmd = 0x000C0000;
    unsigned int send_word = hi_cmd | READ_MODE | 15 <<
        ↪ boardAdrOffset;
    usb.sendData(send_word);
    usb.freeHandles();
}

```

#### 2.21.4 Destination

##### ACC-2xSPF Firmware:src/usbWrapperACC.vhd

```

when x"C" =>

CC_READ_MODE <= USB_INSTRUCTION(2 downto 0);
if USB_INSTRUCTION(4) = '1' then
    TRIG_MODE <= USB_INSTRUCTION(3);
    TRIG_DELAY (6 downto 0) <= USB_INSTRUCTION(11 downto
        ↪ 5);
    SET_TRIG_SOURCE (2 downto 0) <= USB_INSTRUCTION(14
        ↪ downto 12);
end if;

if delay > 10 then
    delay := 0;
    state <= st1_WAIT;
--this is a hack:
-- basically, only want to send along to AC/DC if certain
    ↪ conditions apply
-- also want to only read CC info buffer if read mode = 0b101
else
    delay := delay + 1;
    if delay > 1 then
        case CC_READ_MODE is
        when "101" =>
            read_cc_buffer <= '1';
            CC_INSTRUCTION <= (others=>'0');

```

```

        CC_INSTRUCT_RDY<= '0';
when "110" =>
    read_cc_buffer <= '0';
    CC_INSTRUCTION <= (others=>'0');
    CC_INSTRUCT_RDY<= '0';
---only send-along data to AC/DC cards when
    ↪ 111 or 000
when "111" =>
    --cc_only_instruct_rdy <= '1';
    trig_valid_CC_only <= '1';
    read_cc_buffer <= '0';
    CC_INSTRUCTION <= (others=>'0');
    CC_INSTRUCT_RDY<= '0';
when "000" =>
    trig_valid_CC_only <= '0';
    read_cc_buffer <= '0';
    CC_INSTRUCTION <= USB_INSTRUCTION;
    CC_INSTRUCT_RDY<= '1';
-----
when others =>
    read_cc_buffer <= '0';
    CC_INSTRUCTION <= (others=>'0');
    CC_INSTRUCT_RDY<= '0';
end case;
end if;
end if;

```

## 2.22 0xD - Align LVDS

This command aligns the LVDS system between the central card and any acdc boards. The LVDS system is the RJ-45 connection.

### 2.22.1 Bit Fields

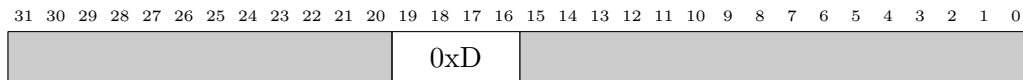


Figure 24: Command 0xD bit fields

| Bits  | Name       | Description    |
|-------|------------|----------------|
| 19-16 | <b>0xD</b> | Command marker |

### 2.22.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::align_lvds()
{
    createUSBHandles();
    usb.sendData((unsigned int)0x000D0000); //toggle align
    ↪ process
    if(mode == USB2x) usb2.sendData((unsigned int)0x000D0000);
    closeUSBHandles();
}
```

### 2.22.3 Destination

## 2.23 0xE - Software Trigger

This command sends a software trigger (maybe).

### 2.23.1 Bit Fields

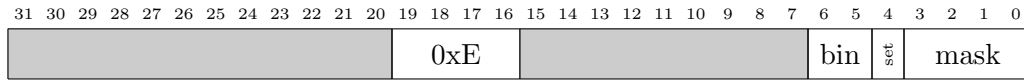


Figure 25: Command 0x7 bit fields

| Bits  | Name       | Description    |
|-------|------------|----------------|
| 19-16 | <b>0xE</b> | Command marker |
| 6-5   | bin        | bin            |
| 4     | set bin    | Enable bin     |
| 3-0   | mask       | Soft trig mask |

### 2.23.2 Source

acdc-daq:src/DAQinstruction.cpp

```
void SuMo::software_trigger(unsigned int SOFT_TRIG_MASK, bool
    ↪ set_bin, unsigned int bin)
{
    usb.createHandles();
    const unsigned int hi_cmd = 0x000E0000;
    unsigned int send_word = hi_cmd | SOFT_TRIG_MASK |
        ↪ set_bin << 4 | bin << 5;
    usb.sendData(send_word);
    usb.freeHandles();
}
```

### 2.23.3 Destination

ACC-2xSPF:src/usbWrapperACC.vhd

```
when x"E" =>    --SOFT_TRIG
```



```
cc_only_instruct_rdy <= '1';
SYNC_TRIG <= '1';
SOFT_TRIG <= '1';
SOFT_TRIG_MASK(3 downto 0) <= USB_INSTRUCTION(3 downto 0);
--SOFT_TRIG_MASK <= (others=>'1'); --trigger every AC/DC
SOFT_TRIG_BIN <= USB_INSTRUCTION(6 downto 4);
if delay > 8 then
    delay := 0;
    state <= st1_WAIT;
else
    delay := delay + 1;
end if;
```

## 2.24 0xF - Sync Usb

This command does something regarding to syncing the usb

### 2.24.1 Bit Fields

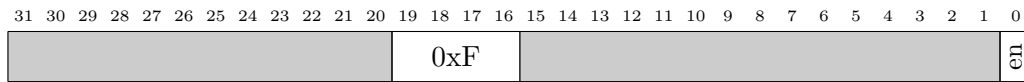


Figure 26: Command 0xF bit fields

| Bits  | Name       | Description     |
|-------|------------|-----------------|
| 19-16 | <b>0xF</b> | Command marker  |
| 0     | enable     | Enable USB sync |

### 2.24.2 Source

acdc-daq:src/DAQinstruction.cpp

```

void SuMo::sync_usb( bool SYNC) {
    createUSBHandles();
    if(SYNC != false) { //enable USB_SYNC
        usb.sendData(( unsigned int)0x000F0001);
        if(mode == USB2x) usb2.sendData(( unsigned int)0x000F0001
        ↪ );
    } else { //disable USB_SYNC
        usb.sendData(( unsigned int)0x000F0000);
        if(mode == USB2x) usb2.sendData(( unsigned int)0x000F0000
        ↪ );
    }
    closeUSBHandles();
}

```

### 2.24.3 Destination