

## Step 1 : Define input parameters & Design space

1. Select uncertain input parameters ( $E_{\text{mem}}$ ,  $\nu_{\text{mem}}$ ,  $\sigma_{\text{mem}}$ ,  $f_{\text{mem}}$ ,  $\sigma_{\text{edg}}$ ,  $\sigma_{\text{sup}}$ , ...)
2. Use mean and standard deviation from slides to define distributions
3. Truncate each distribution within a reasonable interval (e.g.,  $\pm 3\sigma$  or quantile range)
  - To avoid extremely unreasonable inputs and maintain simulation stability
4. Construct normalized design space
  - Design the vector  $X = (X_1, X_2, \dots, X_d)$ , d depends on the number of parameters
  - Normalize all physical parameters to the interval [0,1]
  - Construct input space as a d-dimensional unit hypercube , i.e.,  $[0,1]^d$

## Step 2 : Generate Space Filling Design Points (Latin Hyper-cube Sampling + Maximin Design)

1. Choose sample size  $n_{max} < 200$
2. Generate LHS in  $[0,1]^d$ 
  - Divide each dimension into n intervals over  $[0,1]$
  - Randomly select a point within each interval
  - Randomly pair the points across dimensions to obtain the initial  $n \times d$  design matrix U
3. Optimize using maximin criterion
  - Calculate the Euclidean distance between all pairs of points.
  - Maximize the minimum distance:  $\max_U \min_{i \neq j} \|U_i - U_j\|$
  - Improve the design by swapping rows/columns, simulated annealing, or other heuristic algorithms
4. Map normalized points to physical space
  - Inverse-CDF mapping preserves the stratification property of LHS in each dimension.  
or Quantile function

## Step 3 : Coupling FEM Model and Surrogate Model

### 1. Run FEM model

- Run Kratos FEM for each design point  $x^{(i)}$
- Obtain maximum Cauchy stress:  $y^{(i)} = \sigma_{mem,max}(x^{(i)})$
- Form the training set:  $\mathcal{D} = \{(x^{(i)}, y^{(i)})\}$

### 2. Build the Surrogate Model (Kriging / GP)

- Construct a Gaussian Process model:  $Y(x) \sim GP(m(x), k(x, x'))$

### 3. Assess Design Quality and Surrogate Accuracy

- Inspect spatial distribution of predictive variance