Lara Zlokapa

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Cambridge, Massachusetts, USA



EDUCATION

MIT (Massachusetts Institute of Technology)

Sept. 2020 – May 2022 (Expected)

M.S., Mechanical Engineering Folger Fellow

2020 - 2021

University of California, Berkeley (GPA 3.7/4.0)

Aug. 2016 – May 2020

B.S., Mechanical Engineering

Dean's Honors List Spring 2019, College of Engineering



SPECIAL SKILLS

Design/Modeling: SolidWorks, AutoCAD, Rhino, GD&T dimensioning and tolerancing, FEA, DFM, DFS, 3D printing, machine shop skills (end mill, lathe, etc.), soldering, laser cutting, water jet cutting.

Programming: MATLAB, Python (basic), Arduino, LaTeX, HTML, CSS.

Writing/Communication: Business plan author, essay-writing teacher (high school level), team policy debater.

Languages: English (native), French (intermediate), German (beginner), Serbo-Croatian (beginner).



PUBLICATION

J. Xu, T. Chen, **L. Zlokapa**, W. Matusik, S. Sueda, P. Agrawal, "An End-to-End Differentiable Framework for Contact-Aware Robot Design." *Robotics: Science and Systems (RSS)*, 2021. http://diffhand.csail.mit.edu/



TECHNICAL EXPERIENCE

SuitX, Emeryville, California

May 2019 - Feb. 2020

Engineering Intern

- Independently designing exoskeleton solutions that fit all body sizes for heavy lifting.
- CADding (in SolidWorks), FDM 3D printing prototype models, and performing user testing.
- Conducting SolidWorks FEA on all components and performing physical testing until failure.

Berkeley Expert Systems Technologies (BEST) Lab, UC Berkeley, California

Sept. 2018 – May 2019

Research Intern, Drumming Prosthesis Project under Professor Alice Agogino

- Design cost-effective drumming prosthetic for trans-radial amputees with 6 MEng and PhD students.
- Analyzed drummer survey responses to establish design criteria.
- Designed, FDM 3D printed adjustable drumstick-spring holder using BioFlex for body-powered prosthesis.

Applied BioMechanics, Alameda Island, California

May 2018 – Jan. 2019

Engineering Associate in Accident Reconstruction Simulation

- Simulated vehicle collisions in HVE (dynamics software) and performed manual calculations to verify results.
- Laser scanned collision sites and vehicles and created 3D models of the scans in Rhino for 30+ court cases.

EnableTech, UC Berkeley, California

Jan. 2018 - May 2018

Member, Gripper Project Team

• Designed and laser cut mechanical, cost-effective gripper in interdisciplinary team of 5 for quadriplegic user without grip strength to pick up objects from floor and shelf.



LEADERSHIP & ACTIVITIES

Human Powered Vehicles Club, UC Berkeley, California

Co-President, Frame Subteam lead

Apr. 2018 - Aug. 2019

- Bike goal: design, manufacture, and race a bike at 70mph at the international IHPVA WHPSC competition.
- Organized and oversaw club project management, resource management, and outreach for 30-person club.
- Collaborated with sponsors such as General Motors or Ford.

Society of Women Engineers, Berkeley, California

Committee Member of the Month (March 2017), Shadow an Engineer Committee Member

Jan. 2017 – May 2017

• Coordinated externships with 13 major companies, including AutoDesk.