

Coded Aperture Design in Compressive Spectral Imaging based on Side Information

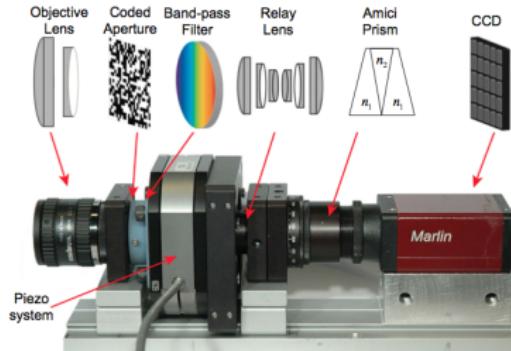
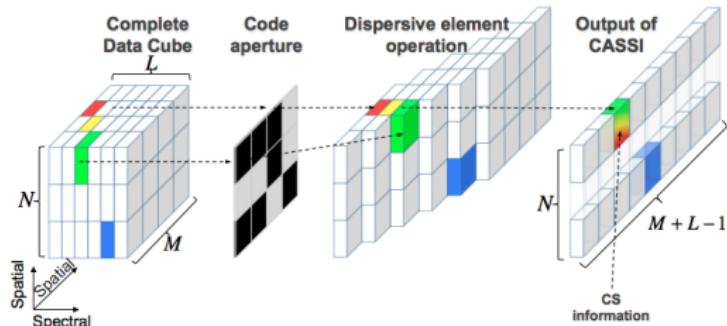
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Coded Aperture Snapshot Spectral Imager (CASSI)

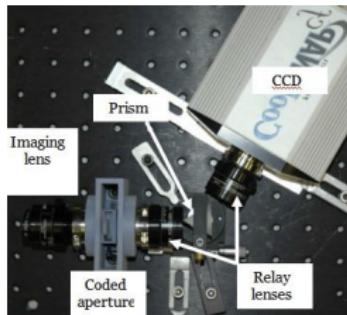


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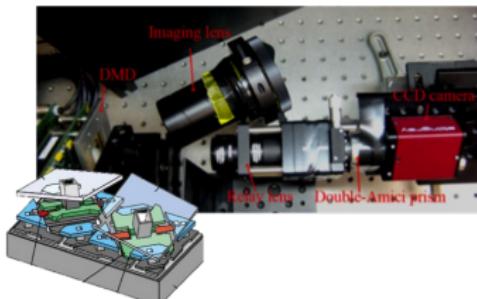
* A. Wagadarikar, R. John, R. Willett, and D. Brady, "Single disperser design for coded aperture snapshot spectral imaging," *Applied Optics*, Vol. 47, No. 10, pp. B44–B51, 2008.

Implementation of Coded apertures patterns

Photomask



Digital Micromirror Device (DMD)

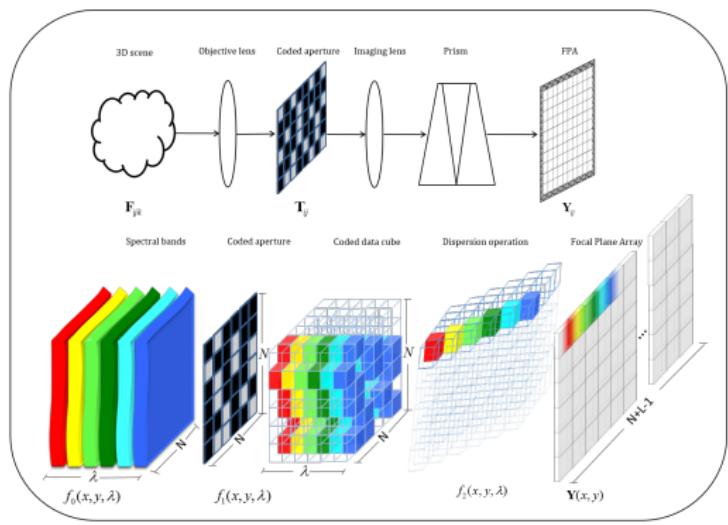


- A new photomask needs to be lithographically fabricated
- The entire system needs to be re-aligned after the installation of the new photomask and it is a very time-consuming process.

- New patterns can be implemented without optical and/or mechanical modification of the system
- Allows multi-shot coding

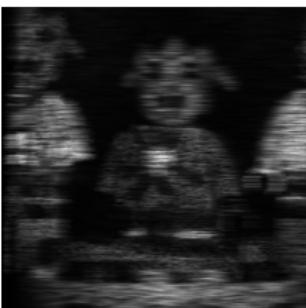
Coded Aperture Snapshot Spectral Imager (CASSI)

Forward Matrix Model



$$\mathbf{Y} = \mathbf{H}\mathbf{f}$$

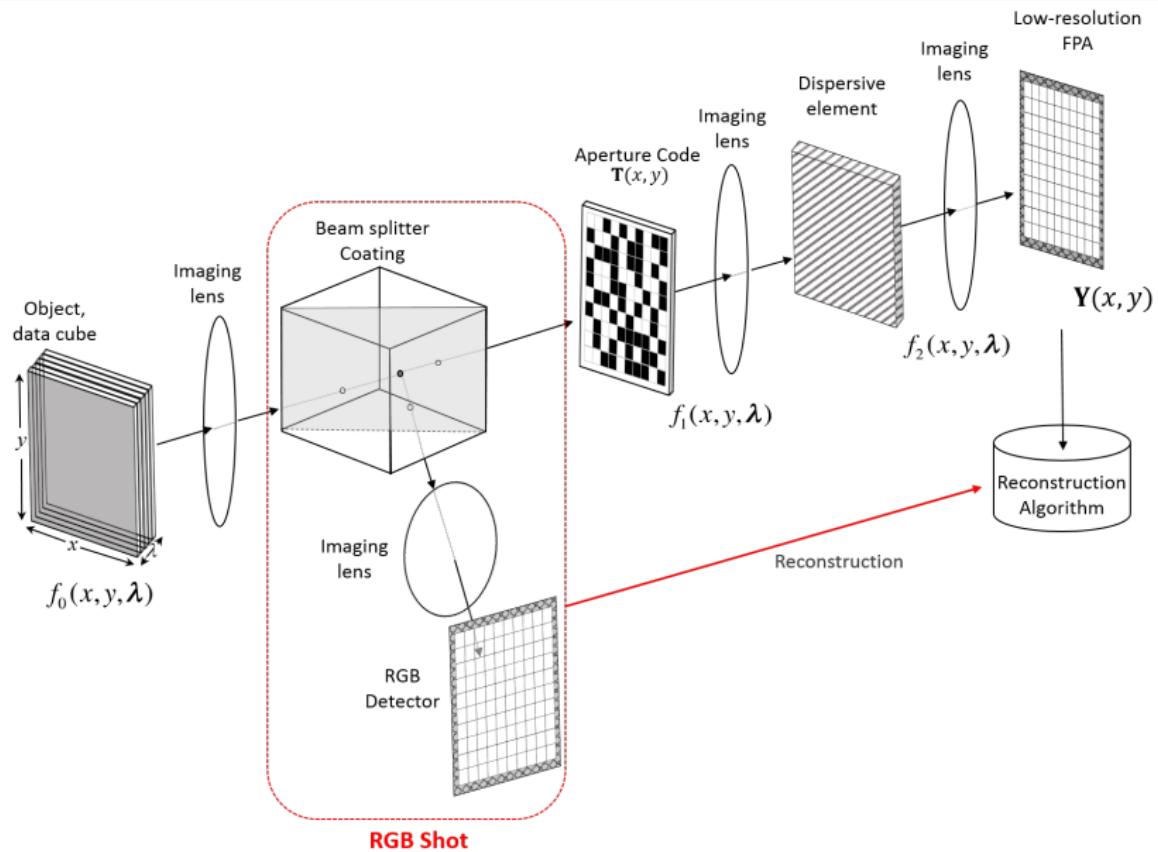
↓ ↘
Coding + Spectral
Dispersion Data cube



Discrete Model

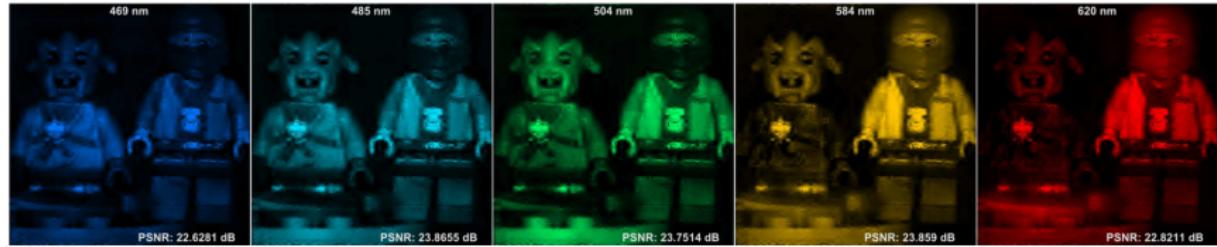
$$Y_{mn} = \sum_{k=0}^{L-1} \mathcal{F}_{m(n-k)k} T_{m(n-k)} + \omega_{mn}$$

Approach: CASSI with Side Information



CASSI shot + RGB Side Information

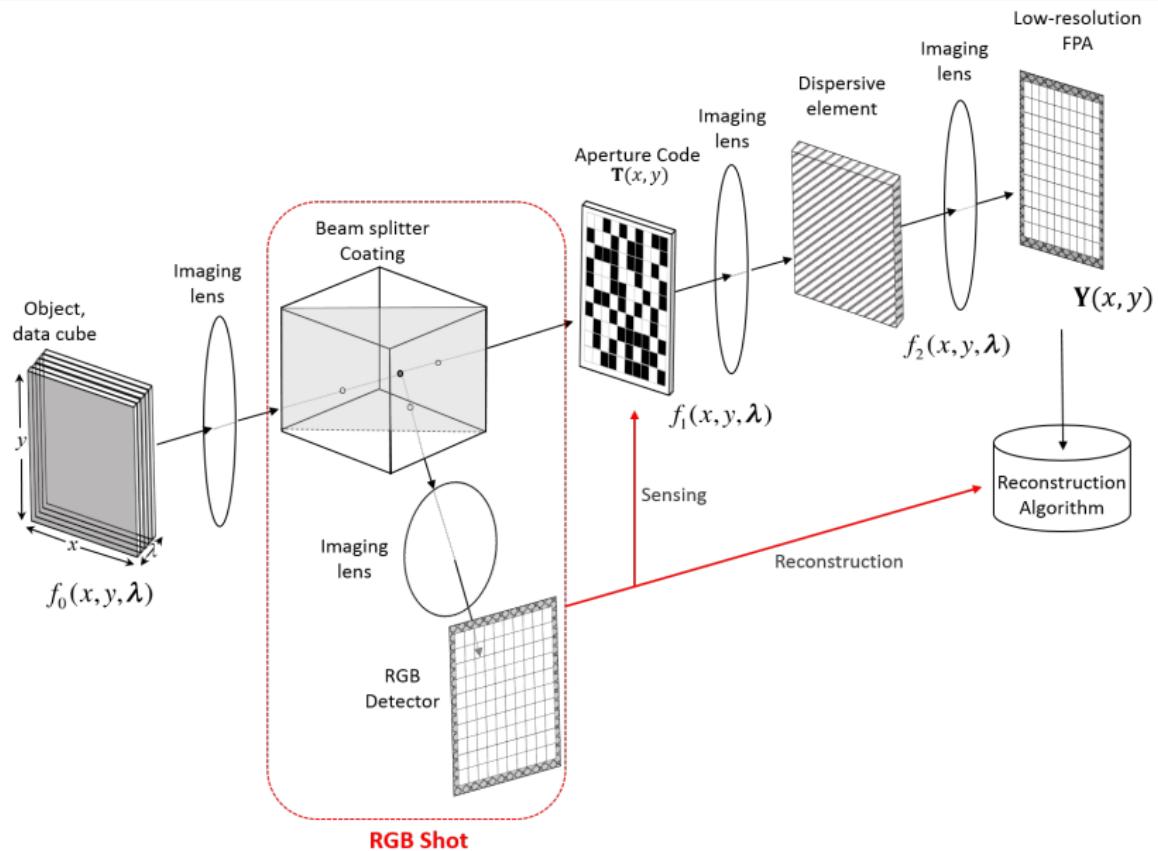
CASSI



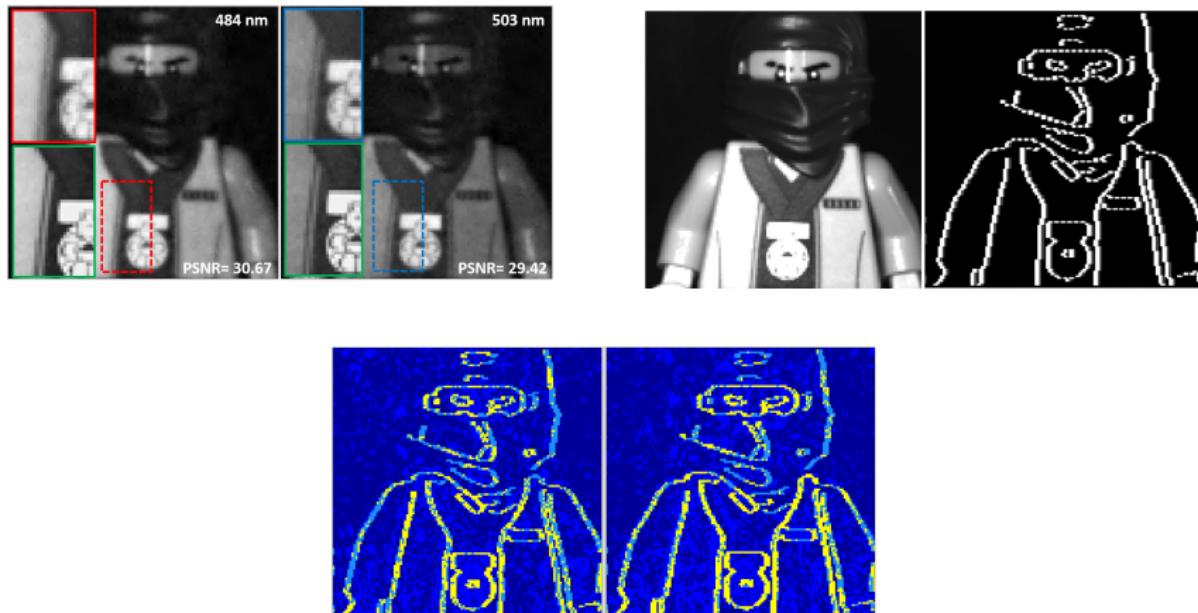
CASSI with RGB Side Information



Approach: CASSI with Side Information



Sensing process: Design of coded apertures based on side information



Correlation between the reconstruction error and the estimated edges. 19.84% and 14.97% (Yellow pixels) corresponds to errors on the edges.

Approach: CASSI with Side Information

The k^{th} spectral band of the spatirospectral image:

$$(\mathbf{F}_k)_{mn} \Rightarrow \mathbf{F}_k = (\mathbf{F}_k)_{mn} \text{ for } m, n = 0, \dots, N-1 \text{ and } k = 0, 1, \dots, L-1.$$

Side Information image:

$$\mathbf{F}_G = \sum_{k=0}^{L-1} w_k \mathbf{F}_k \quad w_k > 0,$$

where \mathbf{w} gives the spectral response of the CCD sensor.

$$\text{Canny}(\mathbf{F}_G) = \text{Canny} \left(\sum_{k=0}^{L-1} w_k \mathbf{F}_k \right).$$

The edges of the side information image \mathbf{F}_G are the linear combination of the edges of each band \mathbf{F}_k

$$\hat{\mathbf{F}}_G = \sum_{k=0}^{L-1} w_k \text{Canny}(\mathbf{F}_k) = \sum_{k=0}^{L-1} w_k \hat{\mathbf{F}}_k,$$

Then can be assumed that $\hat{\mathbf{F}}_G$ contains information of all the spectral bands edges, and it is a good estimation of the edges for the spectral bands $\hat{\mathbf{F}}_k$.

The most representative edges are defined as

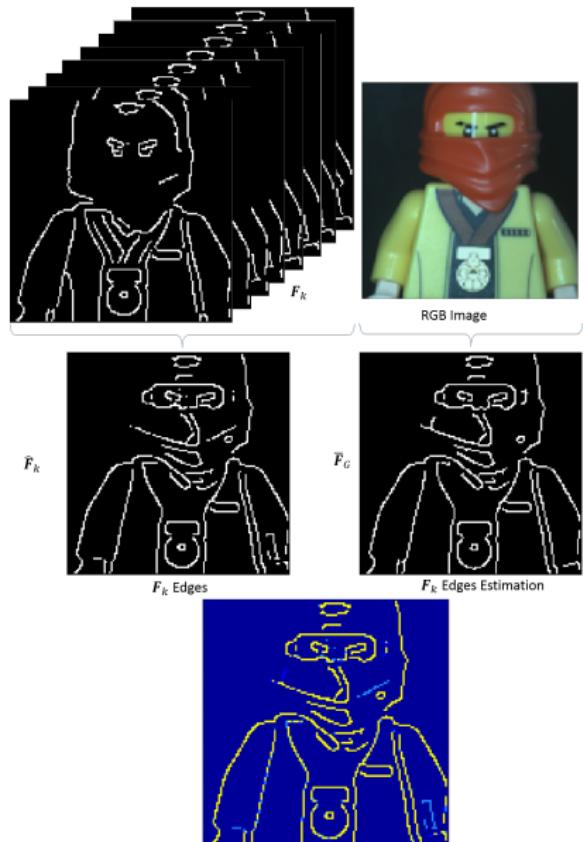
$$(\bar{\mathbf{F}}_G)_{mn} = \begin{cases} (\hat{\mathbf{F}}_G)_{mn}, & \text{if } (\hat{\mathbf{F}}_G)_{mn} > \rho \\ 0, & \text{otherwise,} \end{cases}$$

Design of the codes

$$\mathbf{T} = \mathbf{T}_{b1} \cdot \mathbf{T}_e + \mathbf{T}_{b2} \cdot (1 - \mathbf{T}_e),$$

$$\mathbf{T} = \mathbf{T}_{b1} \cdot \bar{\mathbf{F}}_G + \mathbf{T}_{b2} \cdot (1 - \bar{\mathbf{F}}_G).$$

- First component: Blue noise pattern (in order to achieve a more uniform sensing)
- Second component: Edge component
- $\mathbf{T}_{b1} \neq \mathbf{T}_{b2}$



Approach: CASSI with Side Information

$$Y_{mn} = \sum_{k=0}^{L-1} \left[(\mathbf{T}_{b1})_{m(n-k)} (\bar{\mathbf{F}}_G)_{m(n-k)} + (\mathbf{T}_{b2})_{m(n-k)} (1 - \bar{\mathbf{F}}_G)_{m(n-k)} \right] (\mathbf{F}_k)_{m(n-k)}$$

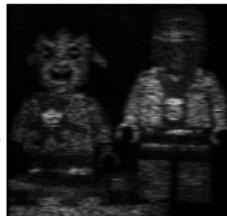
$$Y_{mn} = \underbrace{\sum_{k=0}^{L-1} (\mathbf{T}_{b1})_{m(n-k)} (\bar{\mathbf{F}}_G)_{m(n-k)} (\mathbf{F}_k)_{m(n-k)}}_{\text{a. Sensing of edge sections}} + \underbrace{\sum_{k=0}^{L-1} (\mathbf{T}_{b2})_{m(n-k)} (1 - \bar{\mathbf{F}}_G)_{m(n-k)} (\mathbf{F}_k)_{m(n-k)}}_{\text{b. Sensing of background}},$$

- Several coded apertures patterns can be calculated
- Transmittance of the final coded aperture is in the range of 16% – 26%
- The width of the edges give us many more options of coded apertures to test
- $\mathbf{T}_{b1} \neq \mathbf{T}_{b2}$
- It is possible to use low or high transmittances in the borders

Reconstruction Process

Optimization Problem

$$\tilde{\mathbf{f}} = \Psi \{ \operatorname{argmin}_{\theta} \|\mathbf{y} - \mathbf{H}\Psi\theta\|_2 + \tau \|\theta\|_1 \}$$



CASSI System:

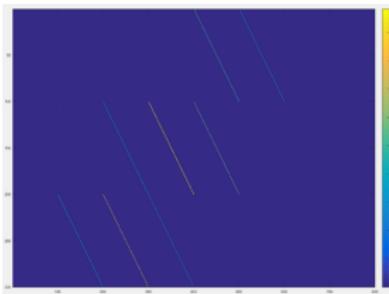
$$\begin{bmatrix} \mathbf{y} \end{bmatrix} = \begin{bmatrix} & & \\ & \mathbf{H} & \\ & & \end{bmatrix} \begin{bmatrix} \mathbf{f} \end{bmatrix}$$



CASSI System + RGB Side Information:



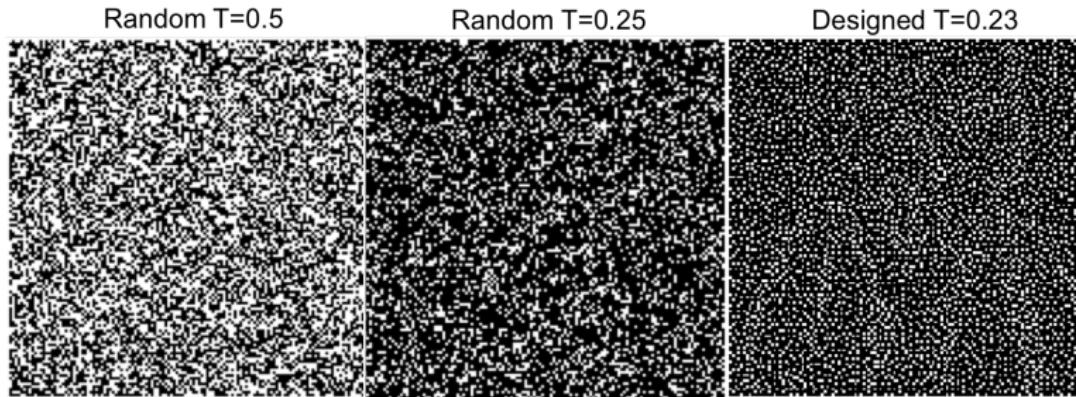
$$\begin{bmatrix} \mathbf{y} \\ \mathbf{y}_R \\ \mathbf{y}_G \\ \mathbf{y}_B \end{bmatrix} = \begin{bmatrix} & & \\ \mathbf{H} & & \\ \mathbf{R} & & \\ \mathbf{G} & & \\ \mathbf{B} & & \end{bmatrix} \begin{bmatrix} \mathbf{f} \end{bmatrix}$$



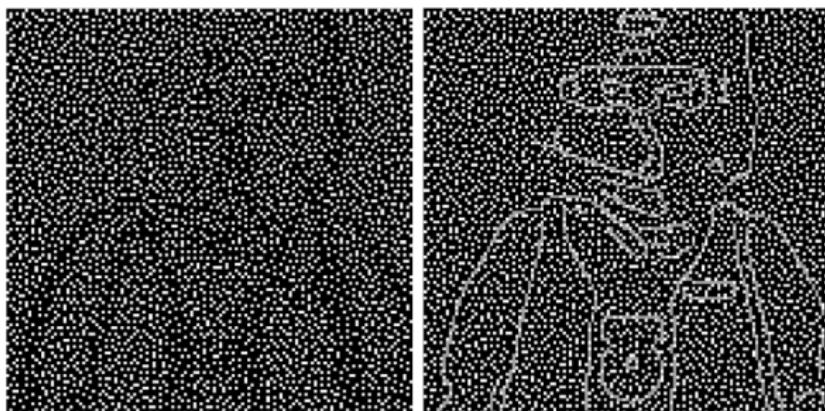
- θ is an S -sparse representation of \mathbf{f}
- τ is a regularization constant
- $\Psi = \Psi_1 \otimes \Psi_2$,
 - Ψ_1 is a 2D-Wavelet Symmlet 8 basis
 - Ψ_2 is the 1D-Discrete Cosine Transform
- GPSR algorithm is used to obtain the reconstructions

Simulations results

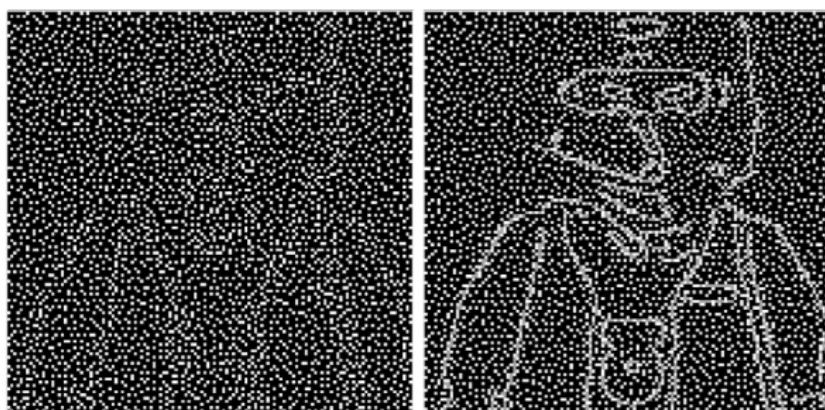
- Test data cube \mathcal{F} : $128 \times 128 \times 8$
- Reconstruction algorithm: GPSR
- Designed coded aperture $T = 0.23$
- Random coded aperture $T = 0.25 - 0.5$



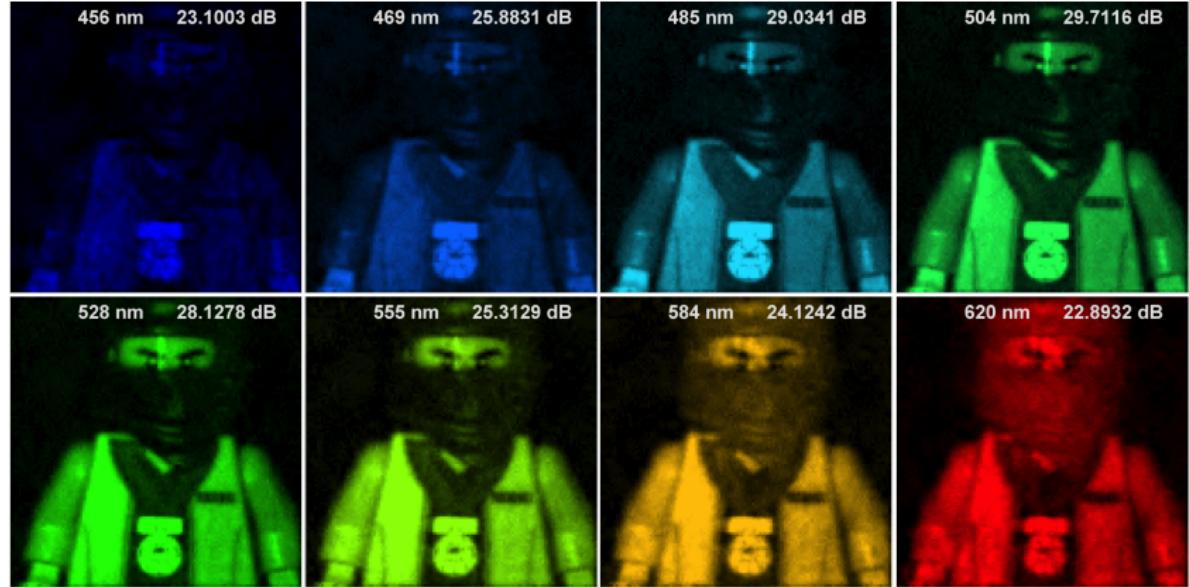
Low transmittance in borders



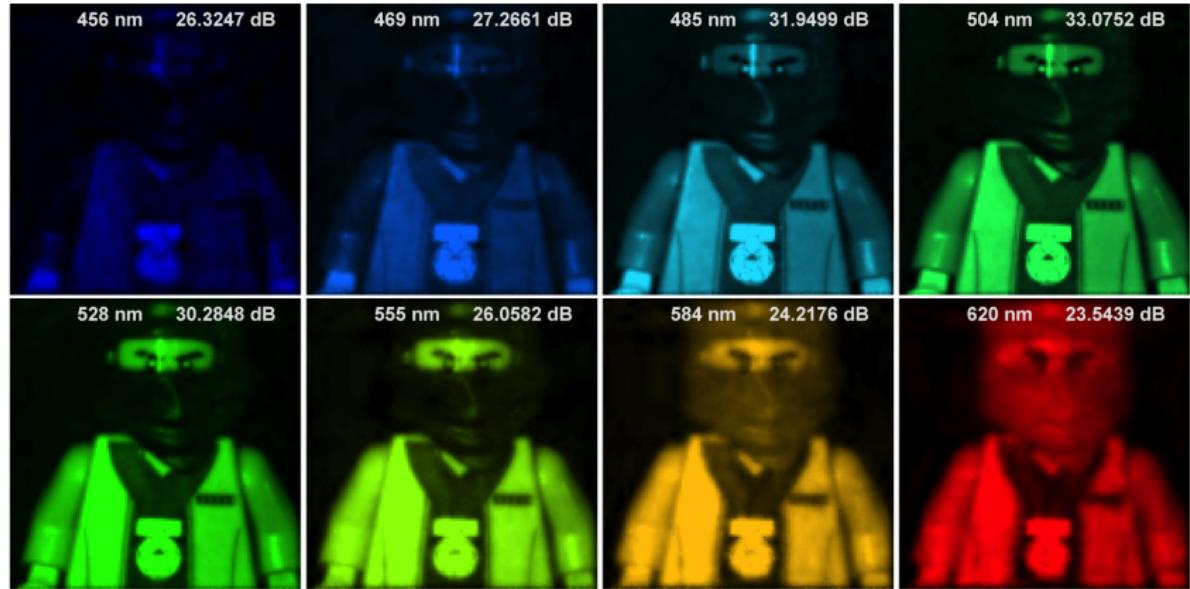
High transmittance in borders



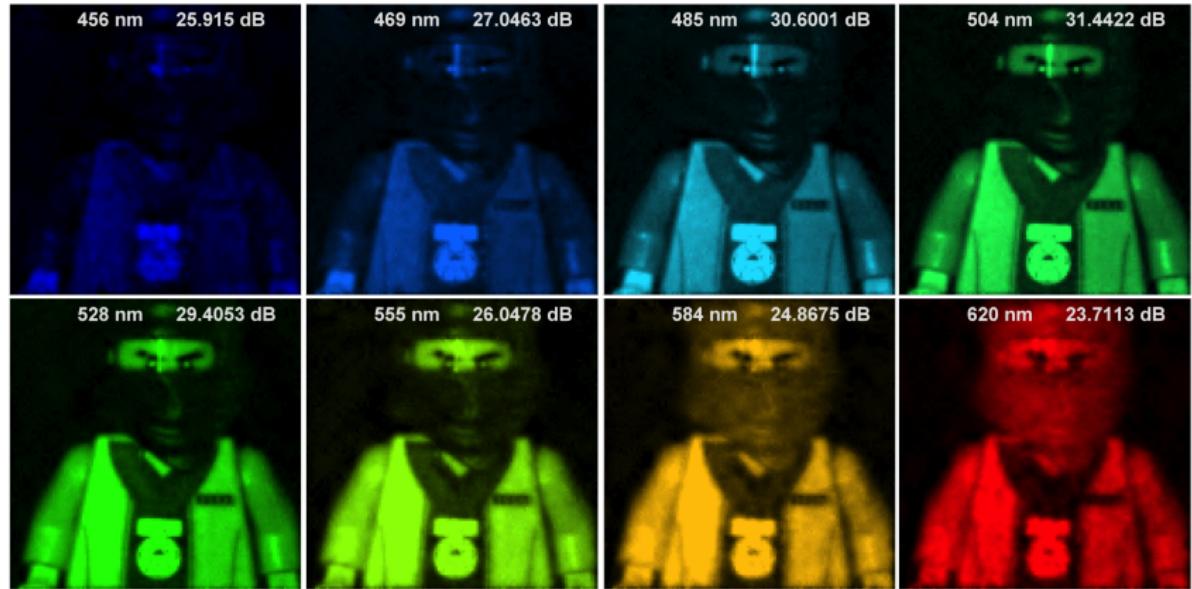
Random coded apertures $T = 0.25$

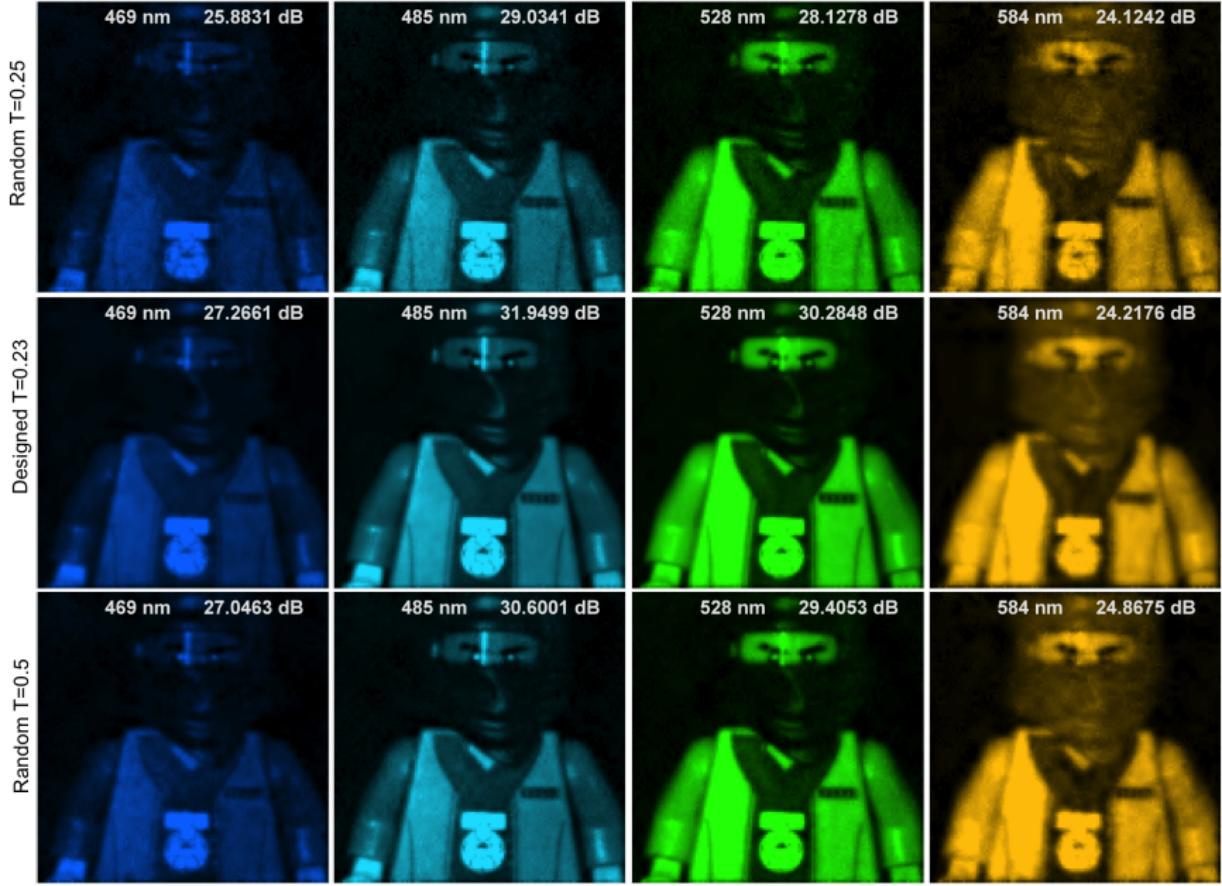


Designed coded apertures $T = 0.23$

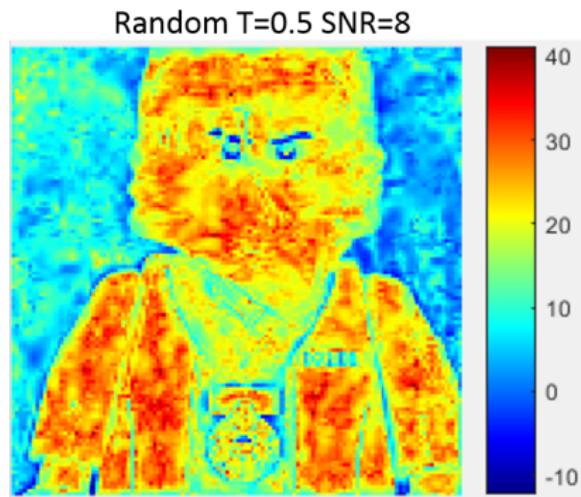


Random coded apertures $T = 0.5$

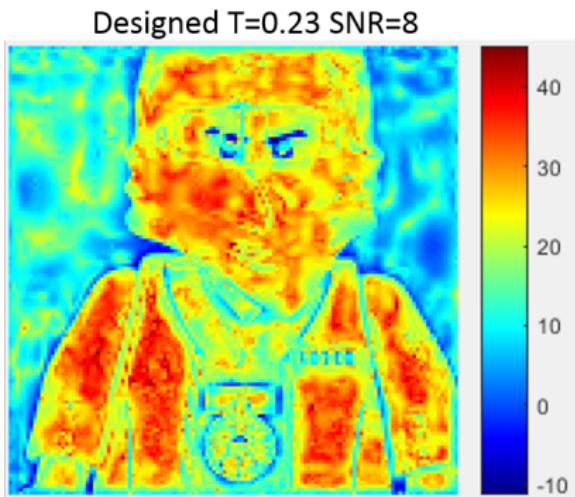




Spectral Reconstruction

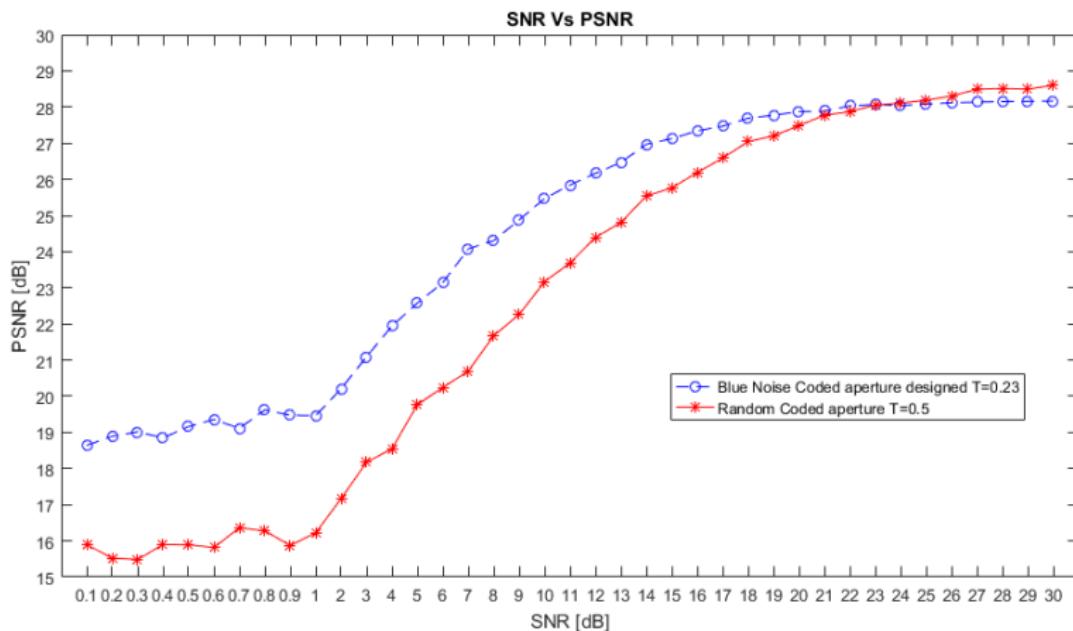


Average spectral reconstruction: 16.99

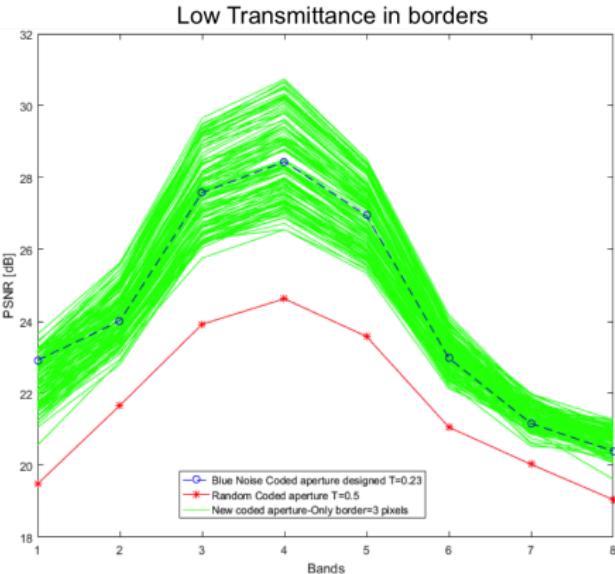
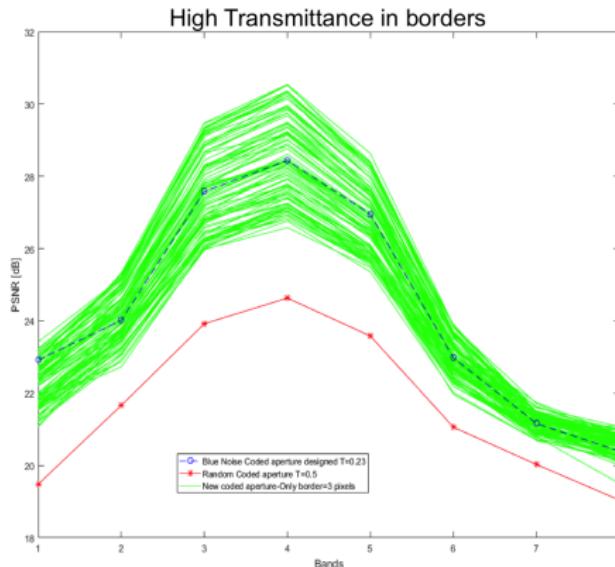


Average spectral reconstruction: 19.51

SNR analysis



Selection of coded apertures



Experimental results

Scene



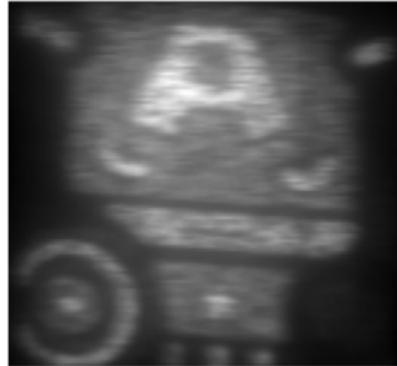
- Test data cube \mathcal{F} : $128 \times 128 \times 10$
- DMD $\Delta_c = 13.68\mu m.$
- A CCD camera $\Delta_d = 6.45\mu m.$
- Coded Aperture T : 128×128 pixels.

Measurements

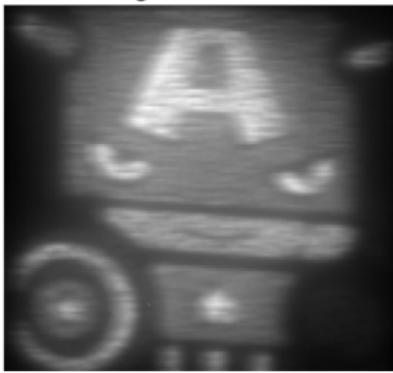
RGB SHOT



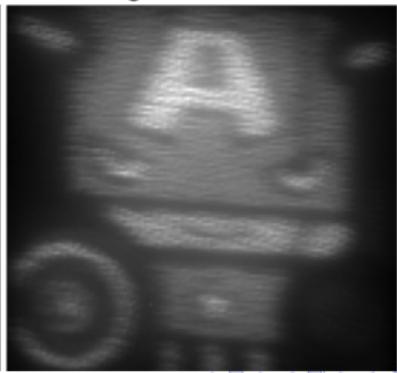
Random T=0.5



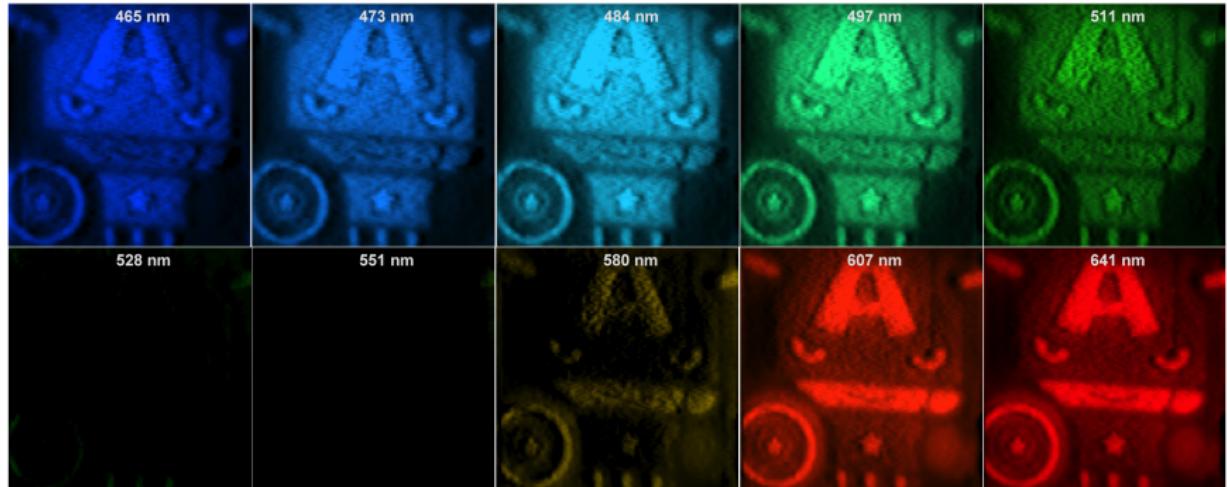
Designed Low T=0.23



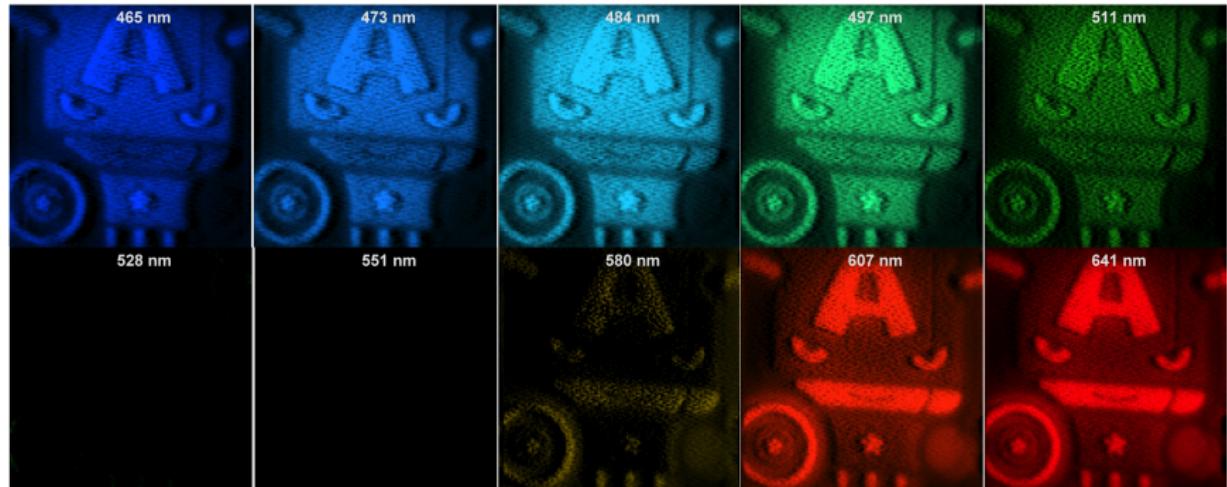
Designed Low T=0.25



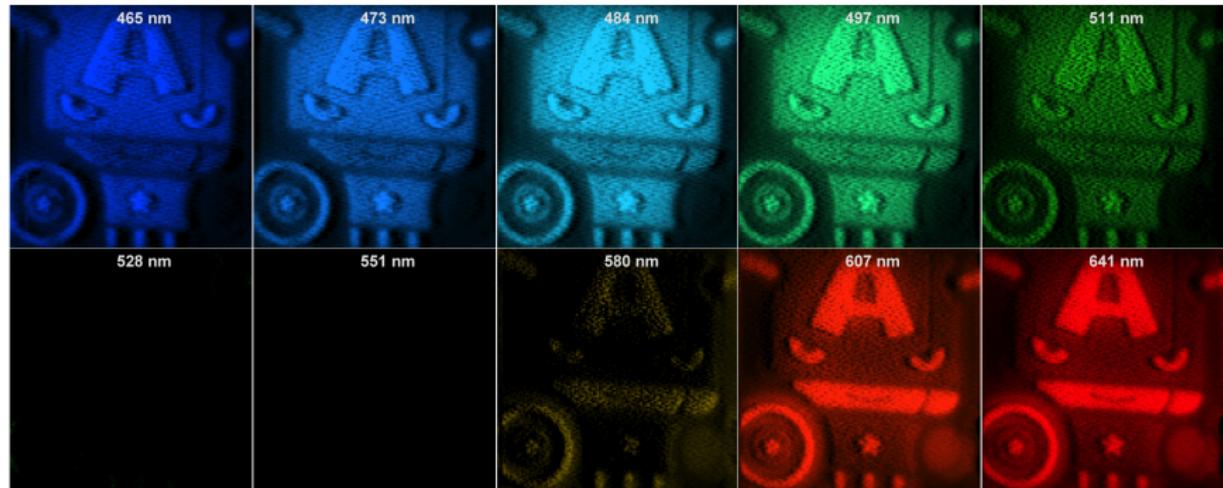
Random coded aperture $T = 0.5$

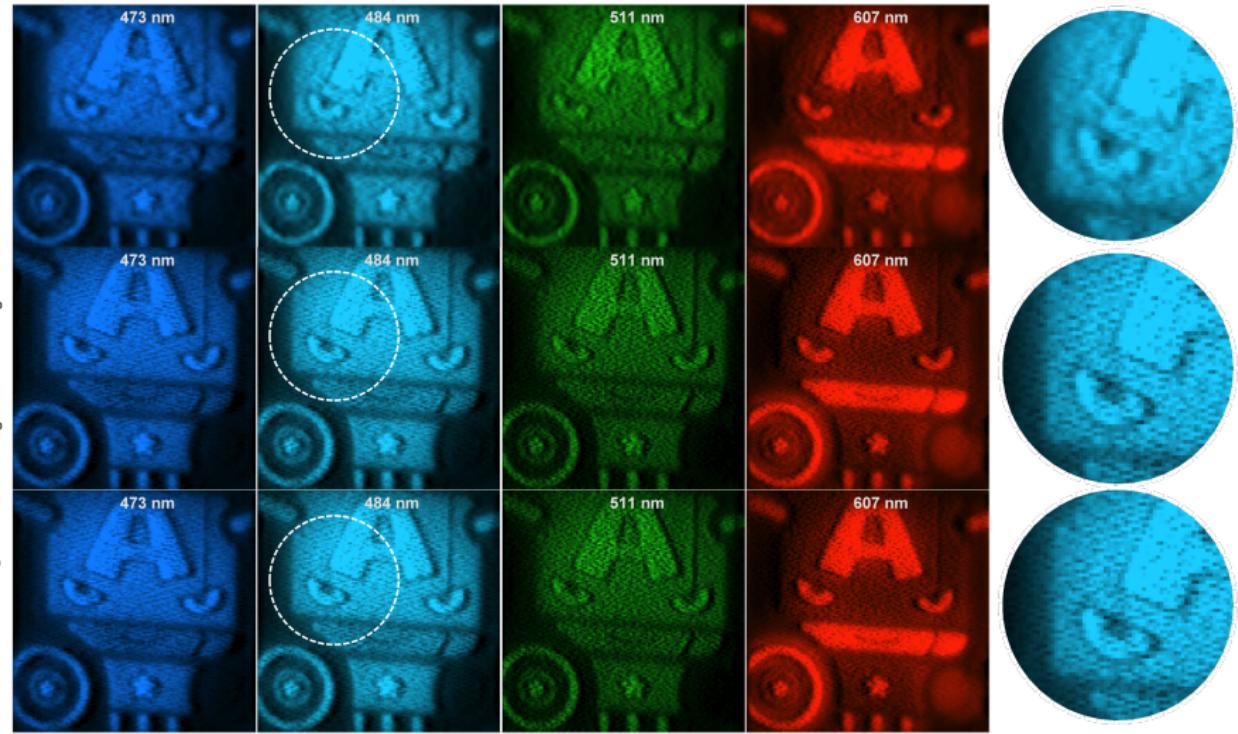


Designed coded aperture, Low T at borders, $T = 0.23$



Designed coded aperture, High T at borders, $T = 0.25$





Conclusions

- A forward model of CASSI with side information has been developed.
- The model uses the side information for the sensing and the reconstruction process.
- The coded aperture design exploits key features in the scene such as scene edges.
- this strategy improves significantly the reconstruction of spectral data cubes, particularly with low SNR measurements.

Questions?

Thanks!