

Laboratorio di Architetture e Programmazione dei Sistemi Elettronici Industriali

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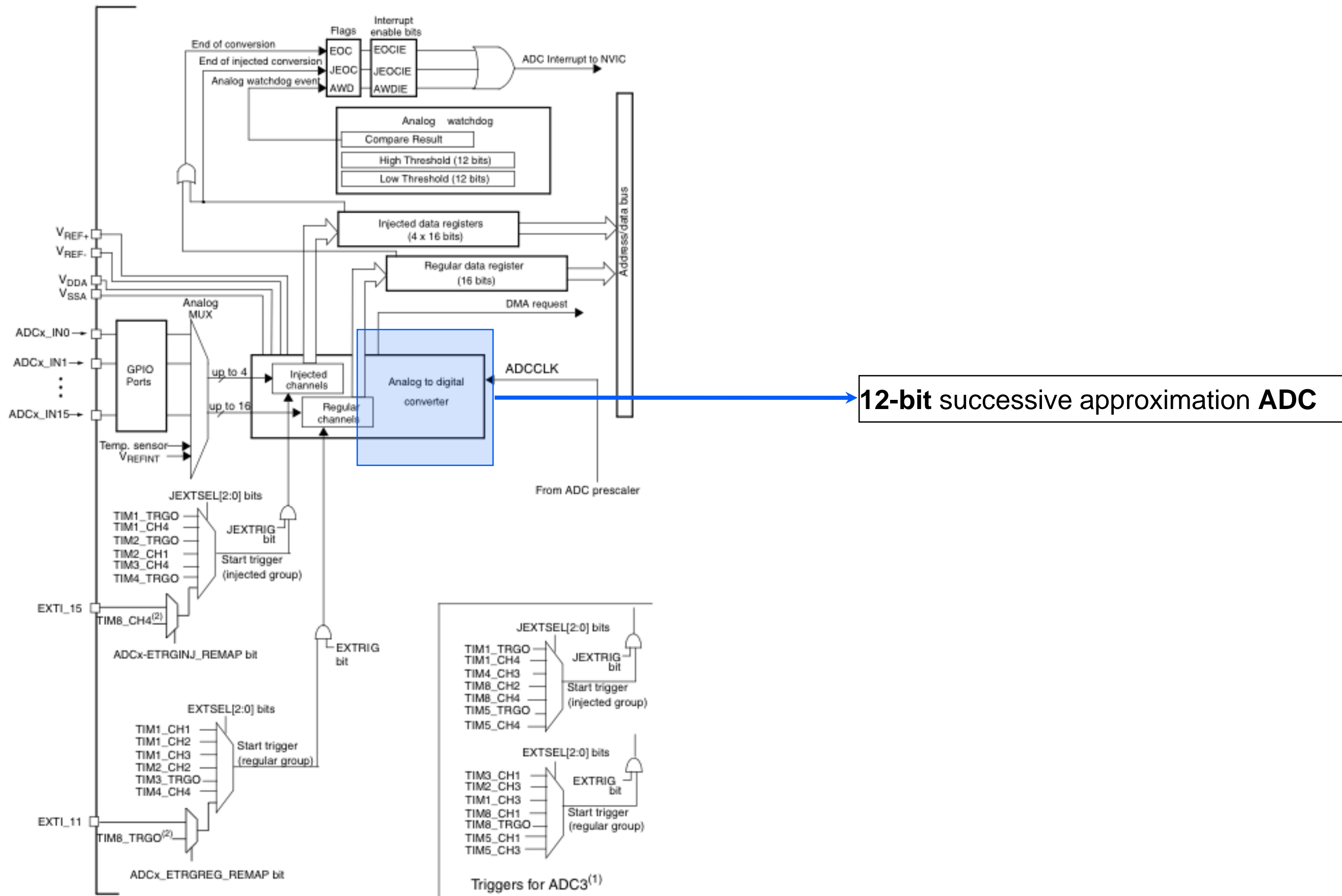
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#8 ADC

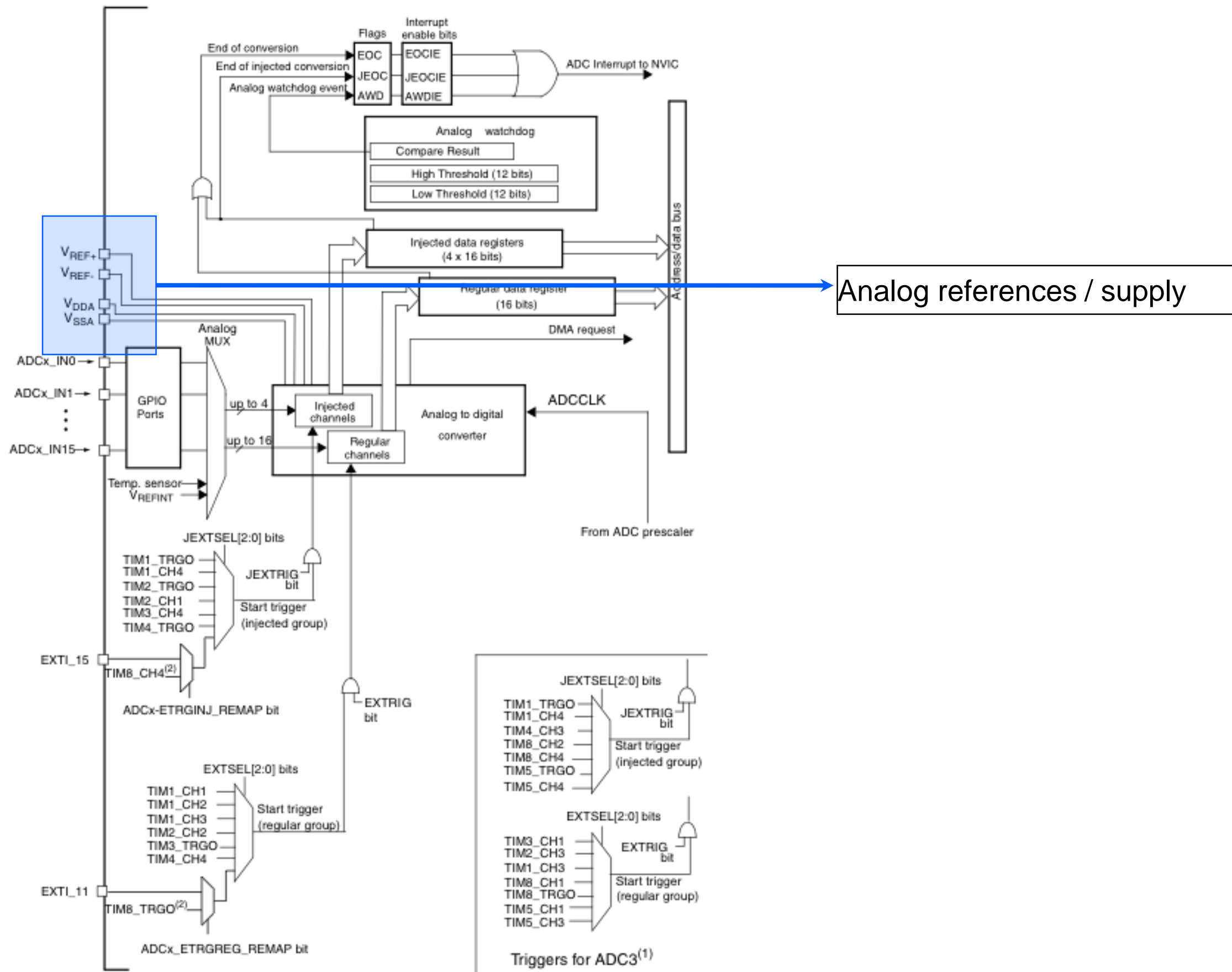
ADC

- The **12-bit ADC** is a successive approximation analog-to-digital converter. It has up to 18 multiplexed channels allowing it measure signals from **16 external and two internal sources**.
- A/D conversion of the various channels can be performed in single, continuous, scan or discontinuous mode. The result of the ADC is stored in a left-aligned or right-aligned 16-bit data register.
- The **analog watchdog** feature allows the application to detect if the input voltage goes outside the user-defined high or low thresholds.
- The **ADC input clock** is generated from the PCLK2 clock divided by a prescaler and it must not exceed 14 MHz

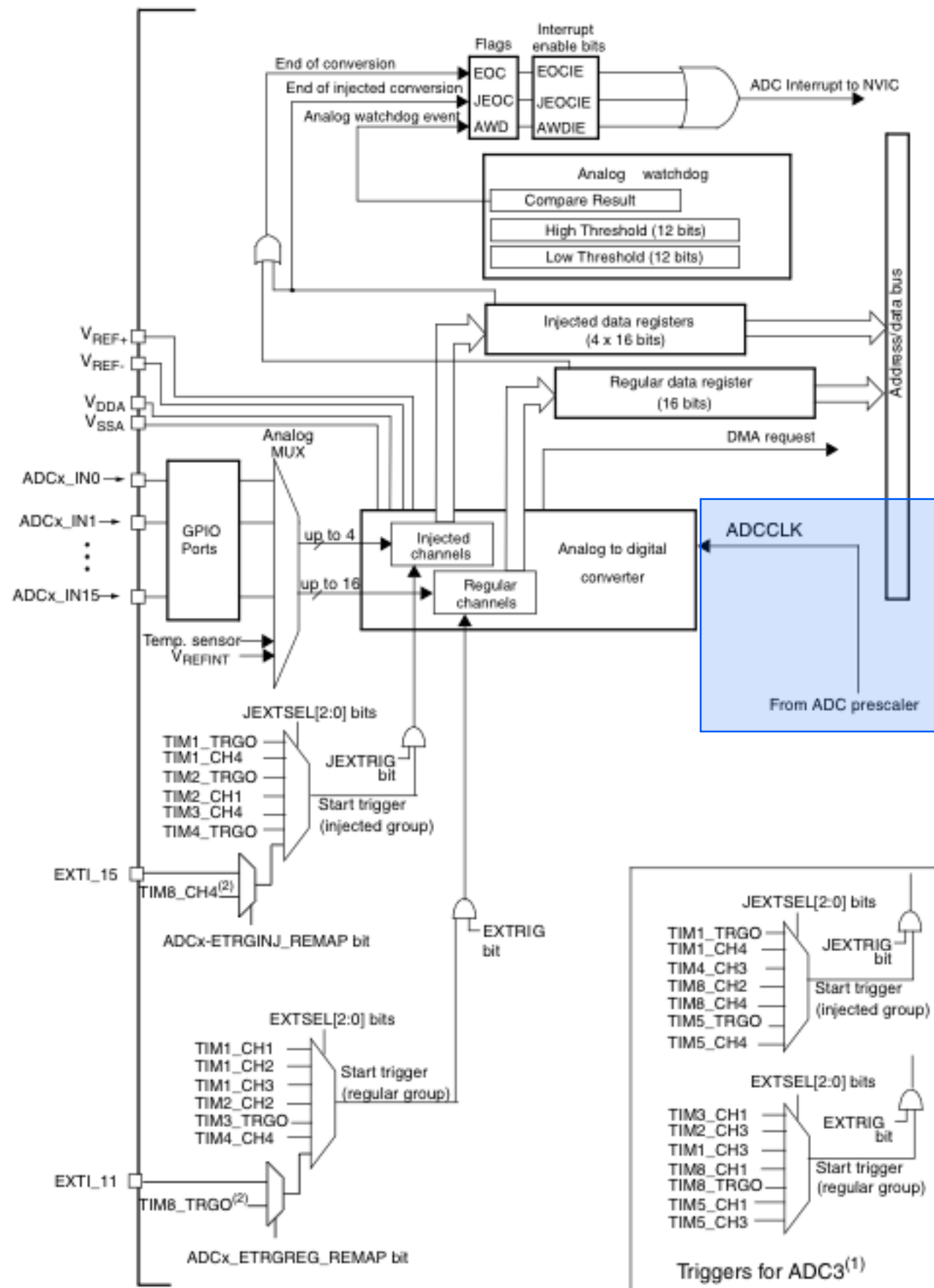
ADC



ADC

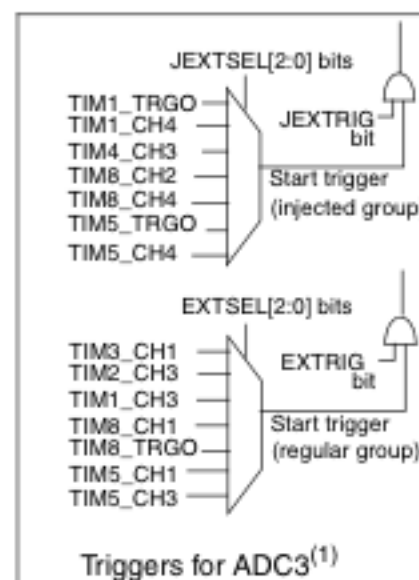


ADC

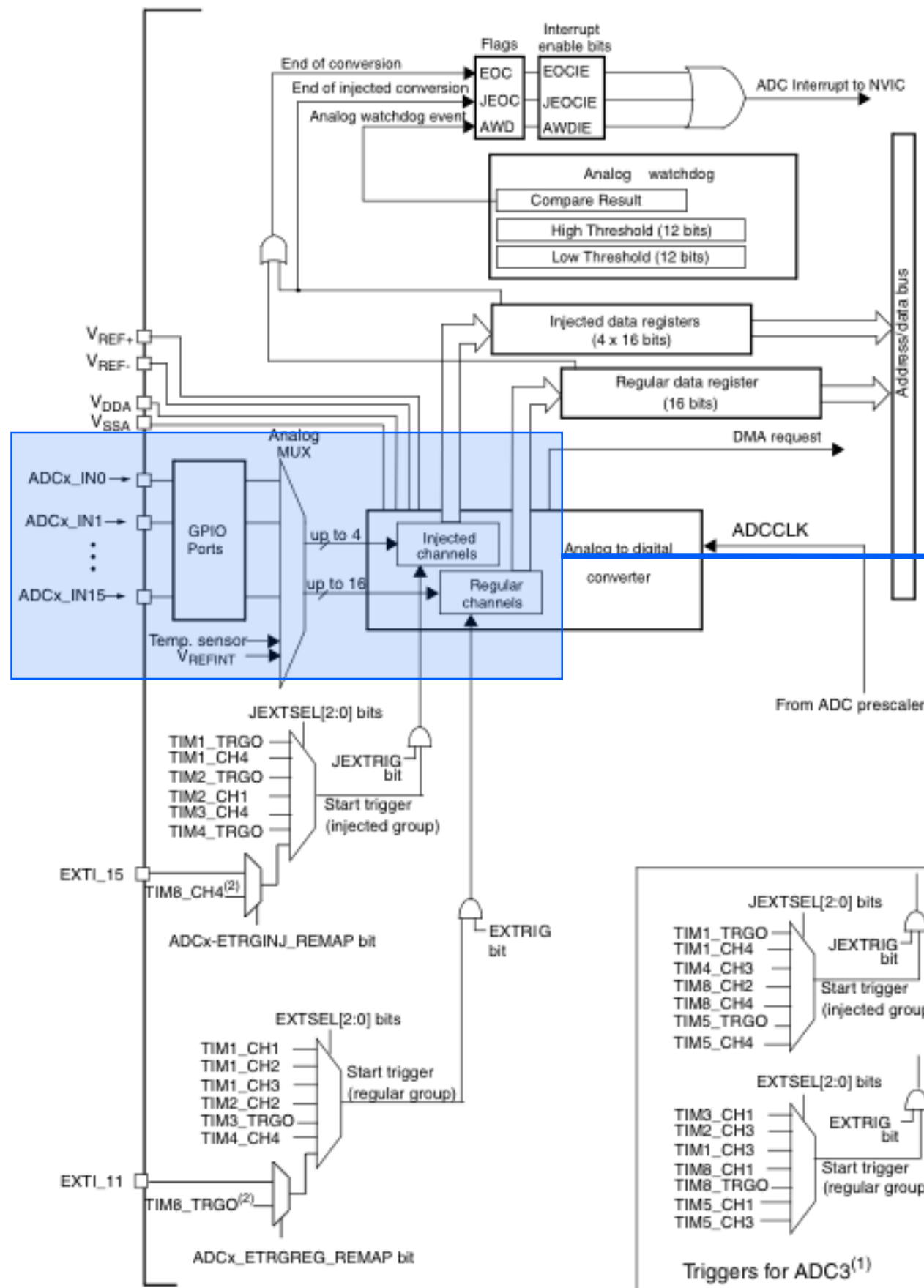


The **ADCCLK** clock provided by the Clock Controller is synchronous with the **PCLK2** (APB2 clock). The RCC controller has a dedicated programmable **prescaler** for the ADC clock (**max 14MHz**)

If prescaler == 0 on the STM32 discovery **ADCCLK==24MHz**



ADC

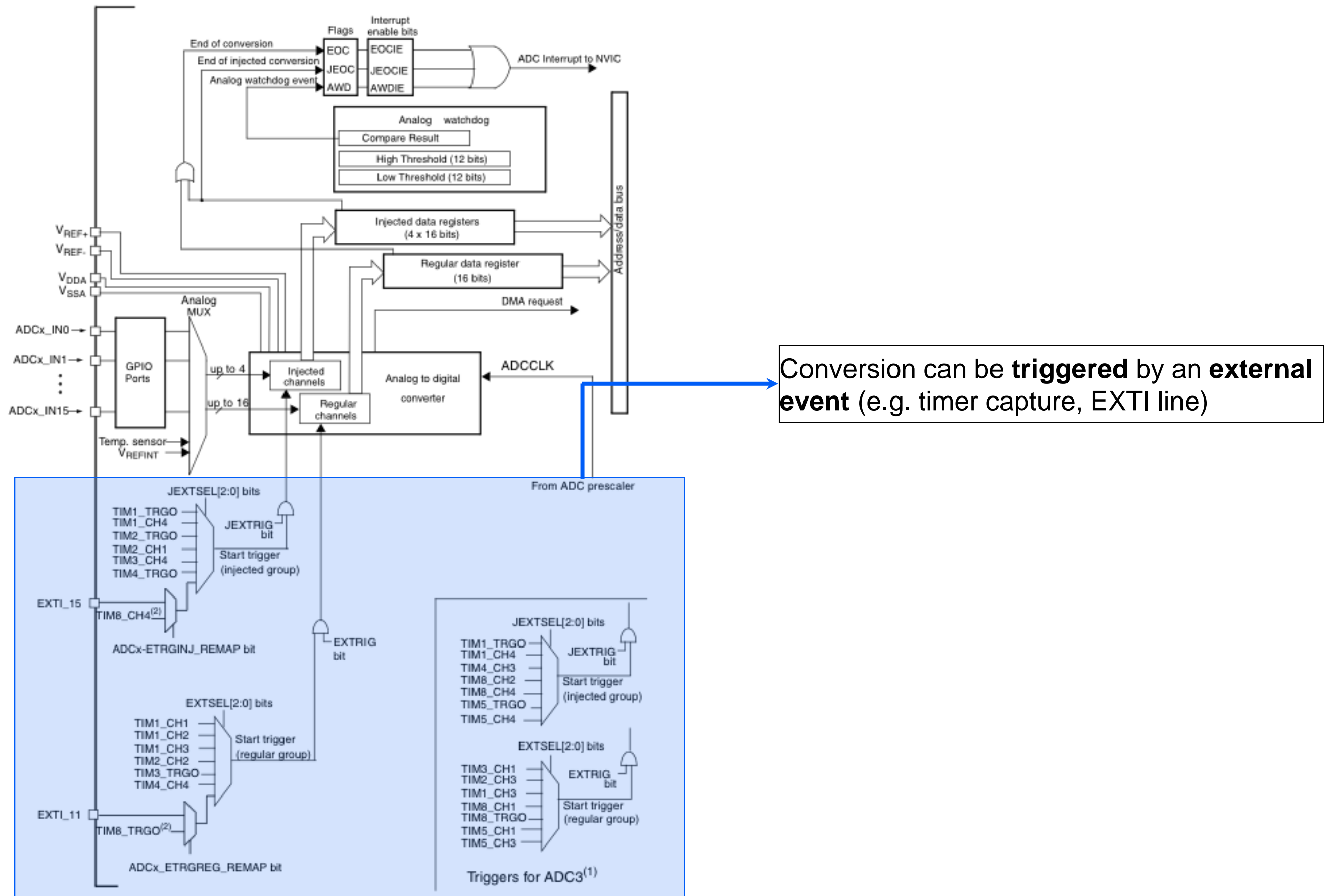


There are **16 multiplexed channels**. It is possible to organize the conversions in two groups: **regular** and **injected**. A group consists of a sequence of conversions which can be done on any channel and in any order.

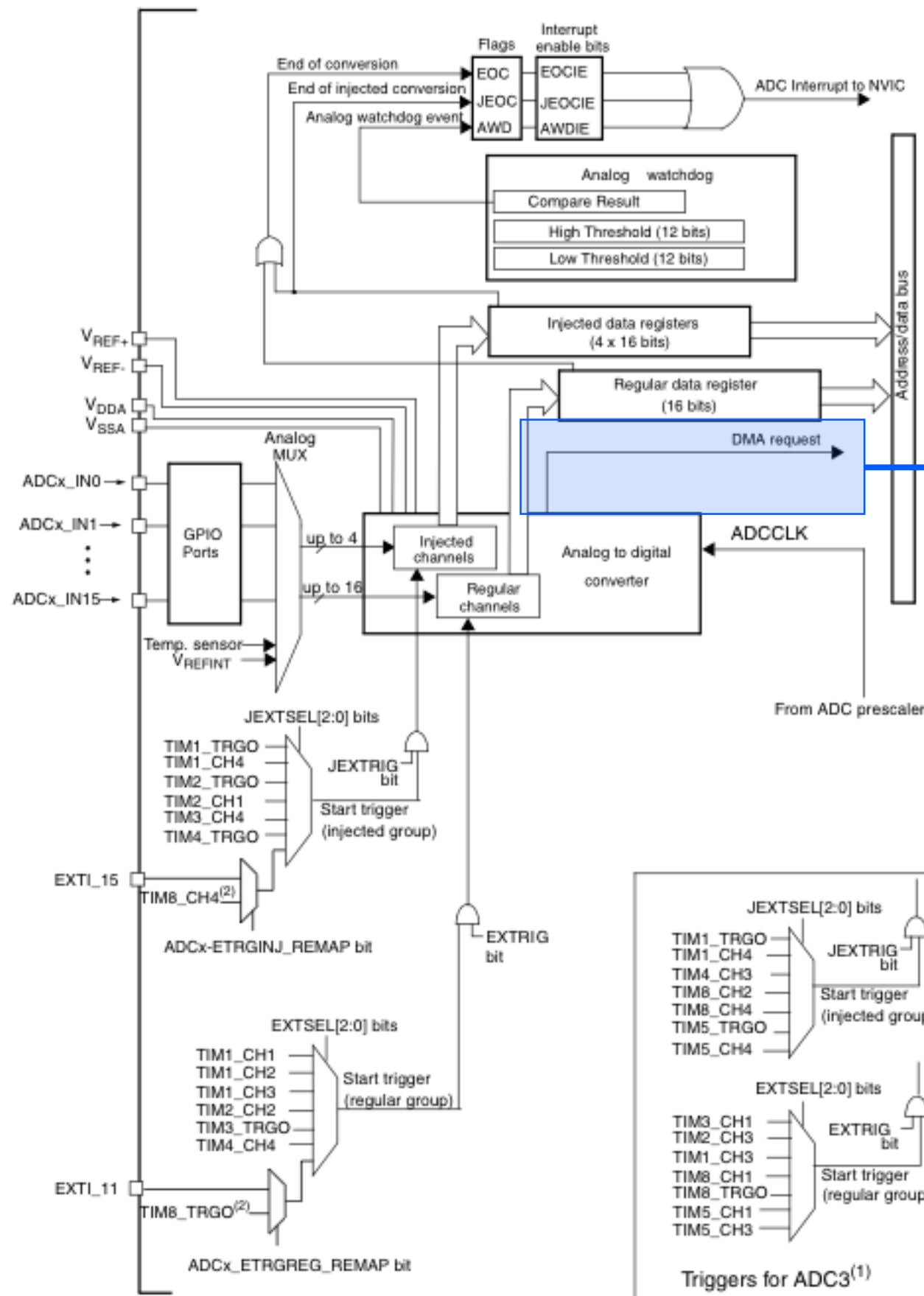
The **Temperature sensor** is connected to channel $ADCx_IN16$ and the internal reference voltage V_{REFINT} is connected to $ADCx_IN17$. These two **internal channels** can be selected and converted as injected or regular channels.

The recommended sampling time for the temperature sensor is $17.1 \mu s$.

ADC



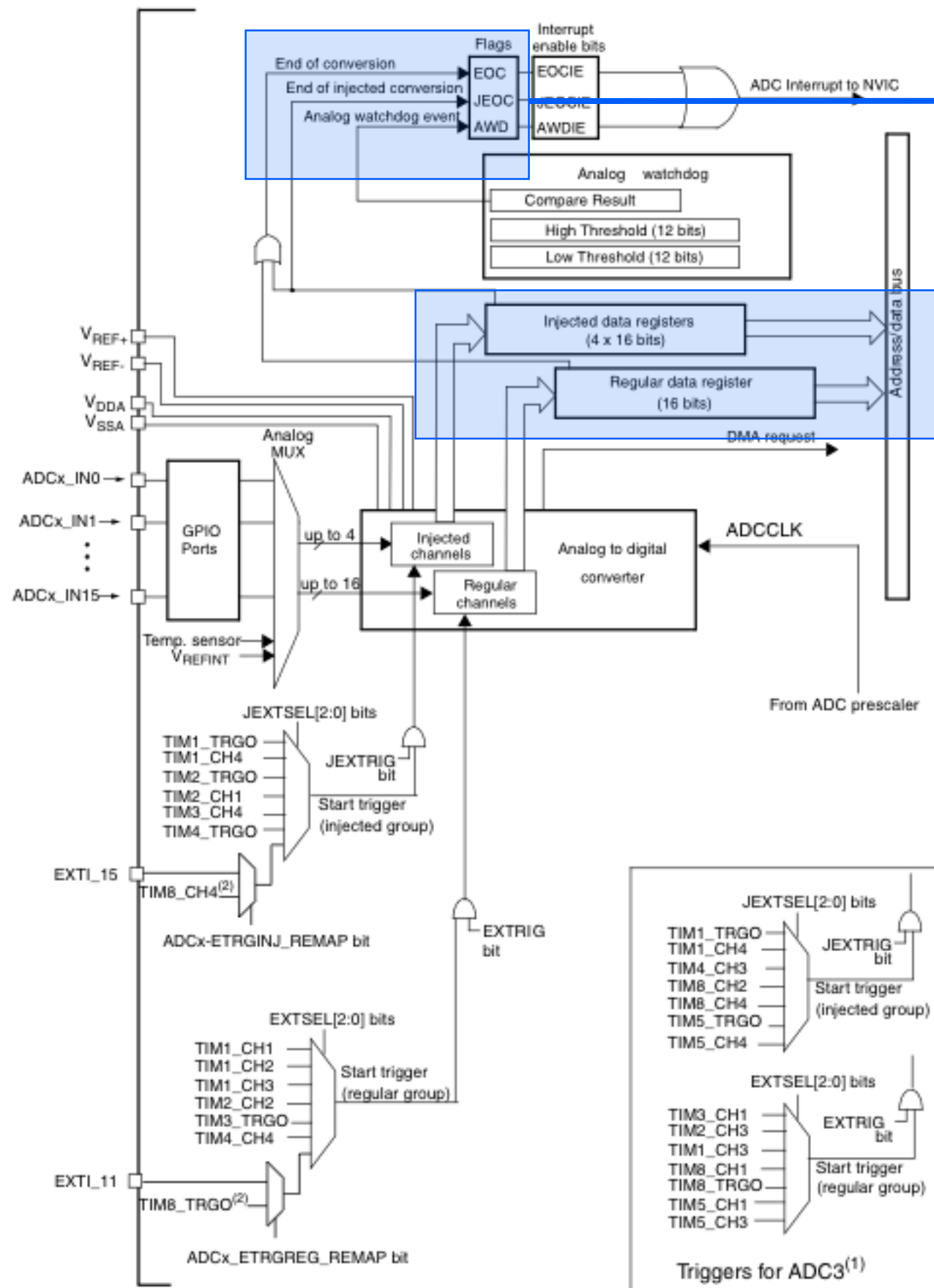
ADC



Since converted regular channels value are stored in a unique data register, it is necessary to use **DMA** for conversion of more than one regular channel.

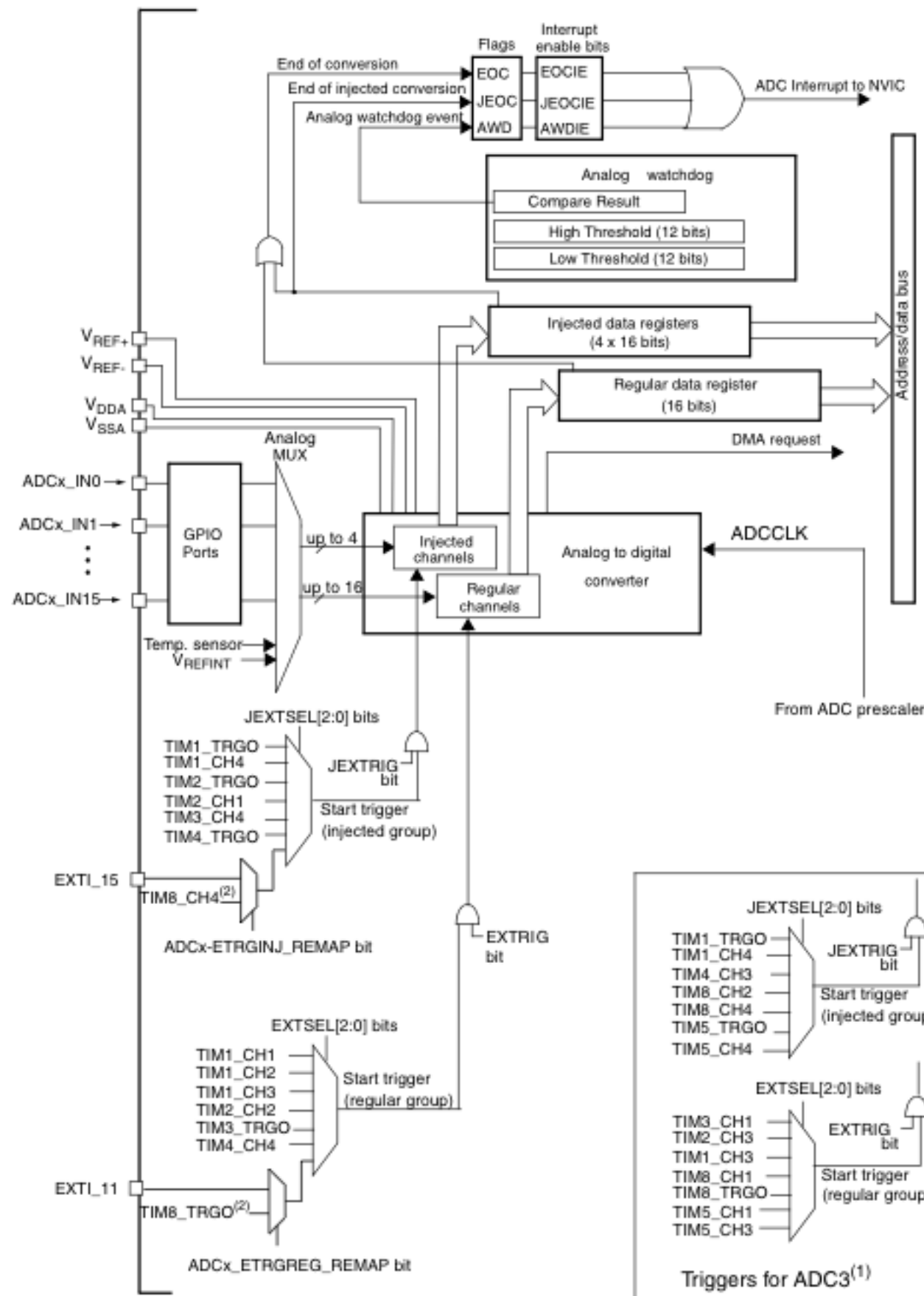
Only the end of conversion of a regular channel generates a **DMA request**, which allows the transfer of its converted data from the ADC_DR register to the destination location selected by the user.

ADC



When the conversion is done, data is stored in 16 bits **registers** and the proper **flags** are set to indicate the **end of conversion**

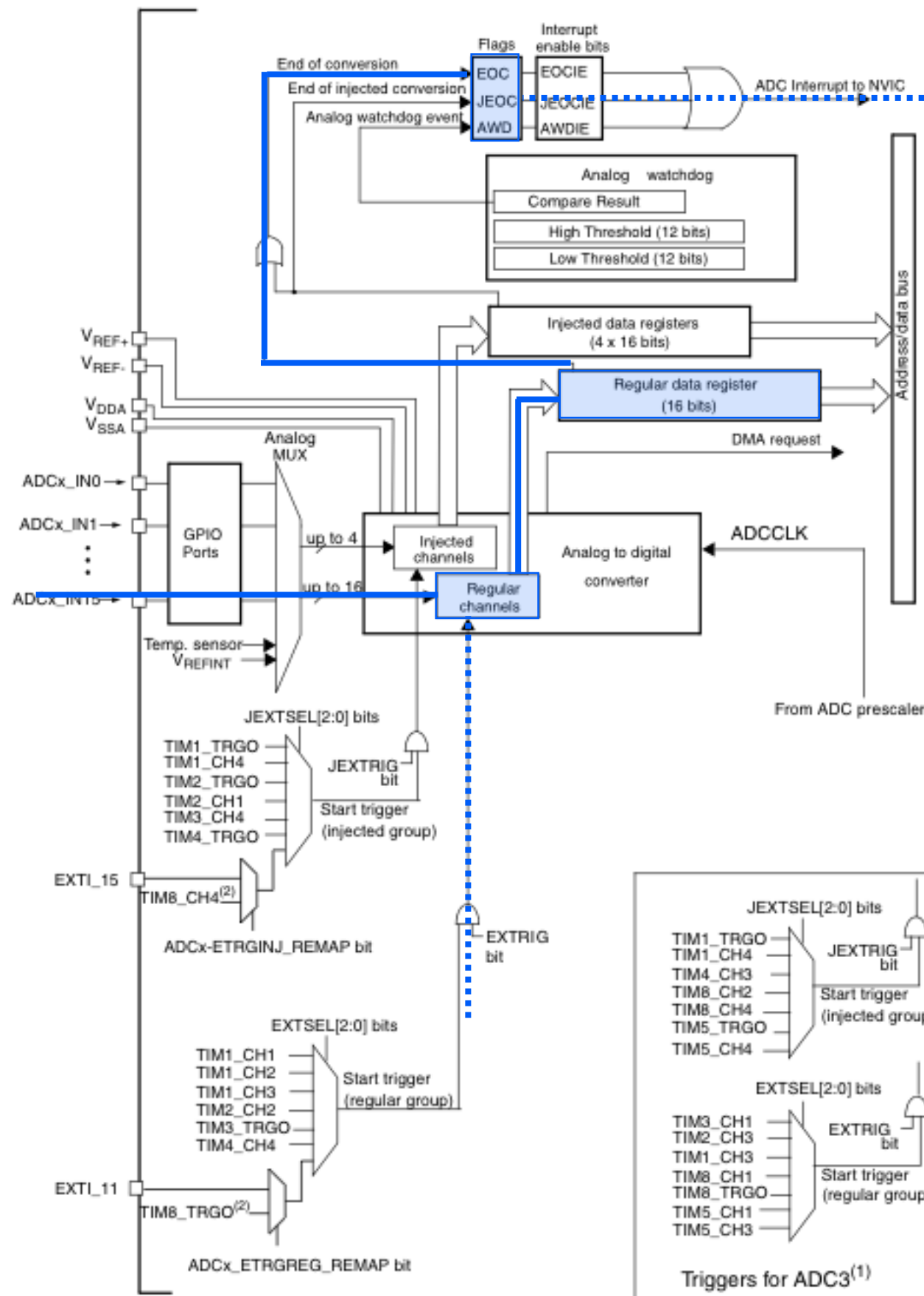
ADC



Calibration

The ADC has an built-in **self calibration mode**. Calibration significantly **reduces accuracy errors** due to internal capacitor bank variations. During calibration, an error-correction code (digital word) is calculated for each capacitor, and during all subsequent conversions, the error contribution of each capacitor is removed using this code.

ADC

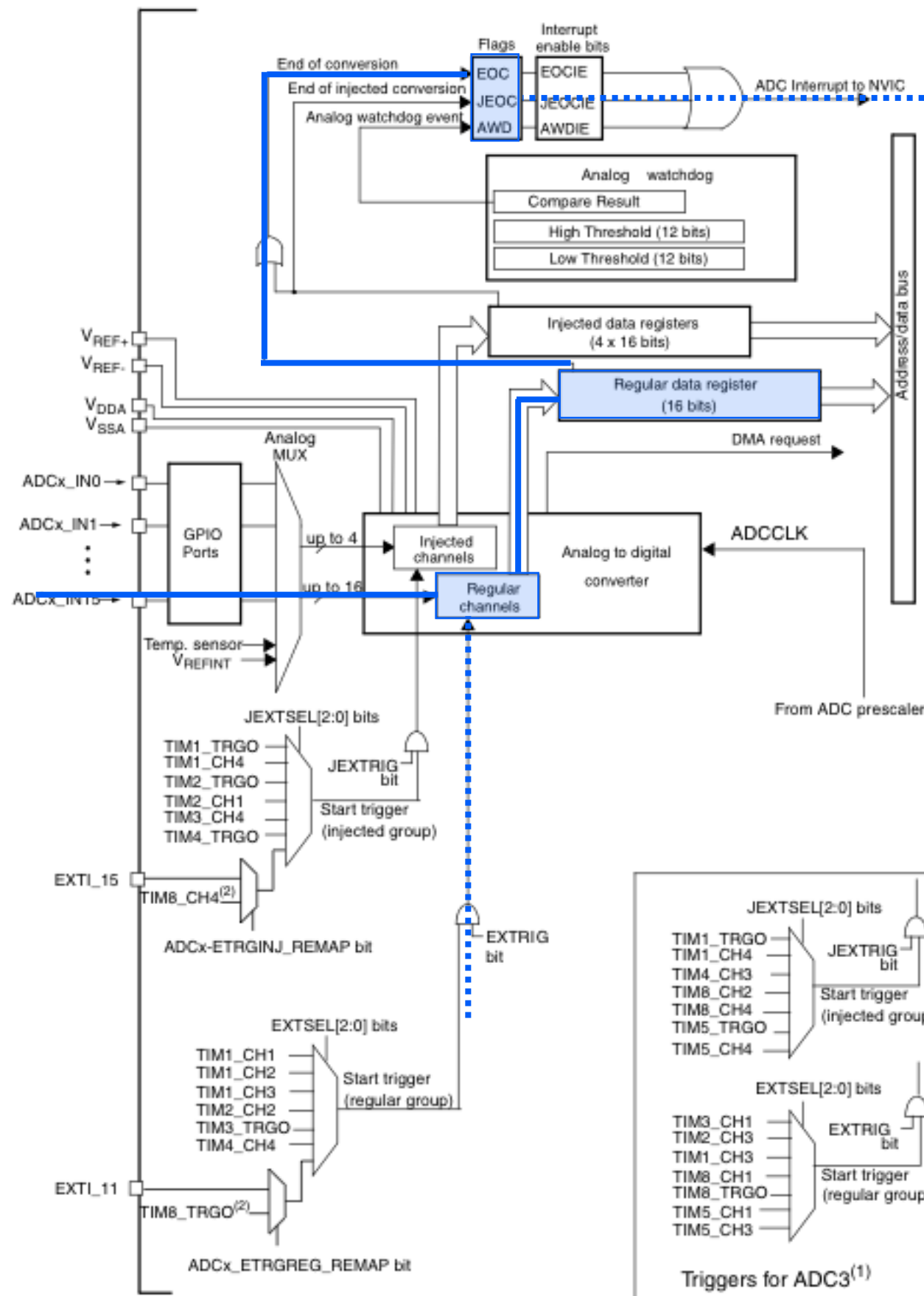


Conversion Mode (single / continuous)

1. The converted data is stored in the 16-bit register
2. The EOC (End Of Conversion) flag is set
3. An interrupt is eventually generated

- **Single conversion mode**: in Single conversion mode the ADC does one conversion.
- **Continuous conversion mode**: in continuous conversion mode ADC starts another conversion as soon as it finishes one.

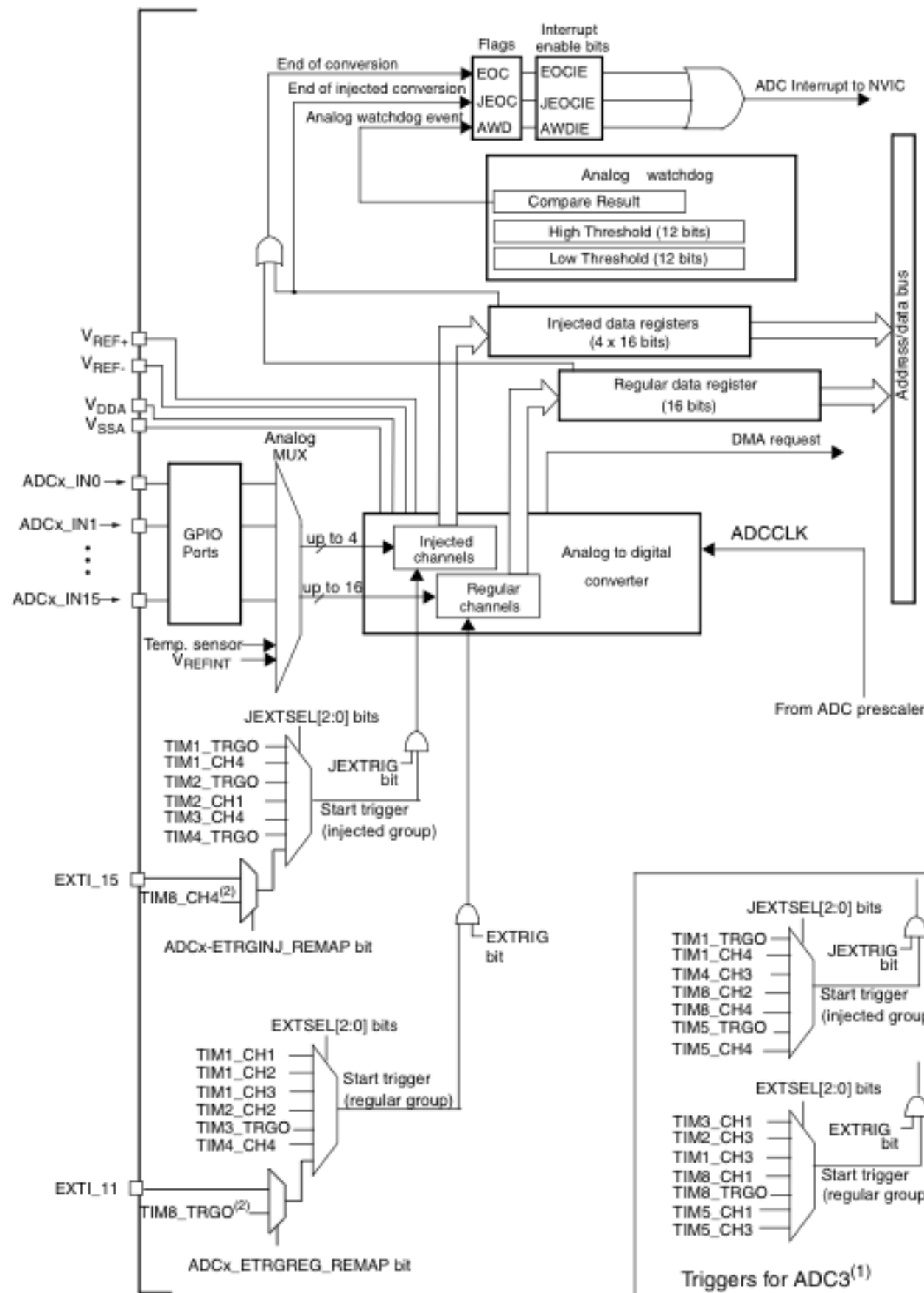
ADC



Conversion Mode (scan / single)

- **Scan (multichannel)**: This mode is used to scan a group of analog channels. A single conversion is performed for each channel of the group. After each end of conversion the next channel of the group is converted automatically.
- **Single (one channel)**: one single channel is used

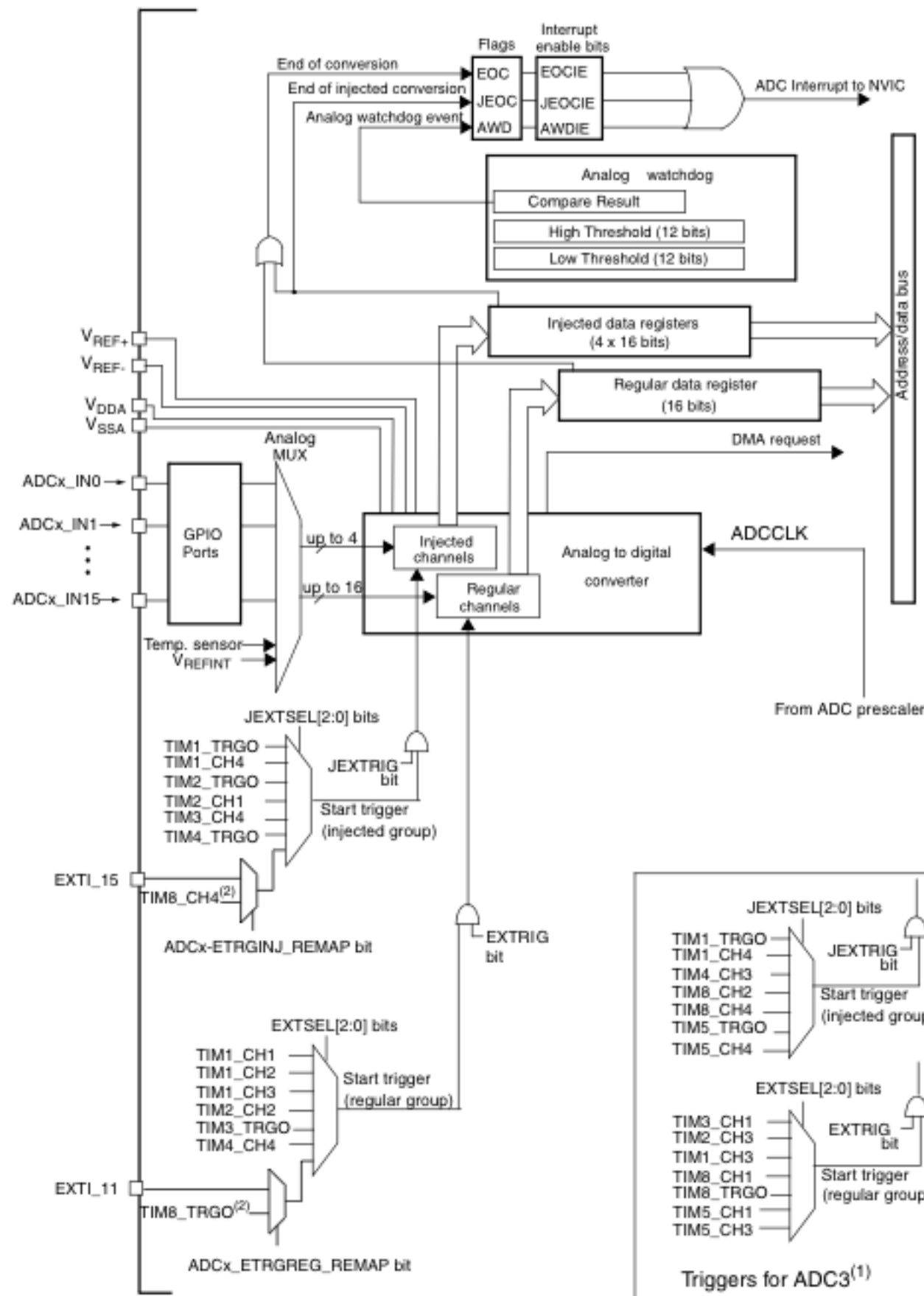
ADC



ADC mode (independent / dual)

- **Independent mode**: one ADC is used
- **Dual mode**: In dual ADC mode the start of conversion is triggered alternately or simultaneously by the ADC1 master to the ADC2 slave

ADC



Channel-by-channel programmable sample time

ADC samples the input voltage for a number of **ADCCLK cycles** which can be modified and each channel can be sampled with a **different sample time**.

The total conversion time is calculated as follows:

$$T_{\text{conv}} = \text{Sampling time} + 12.5 \text{ cycles}$$

ADC

- We want to use a **DMA** and **ADC** to sample the temperature from ADCx_IN16 input channel.

- **Configure and enable DMA**

1. Configure and enable ADC

1. Configure the prescaler for ADCCLK
2. Configure and init the ADC (conversion mode, sampling time, etc...)
3. Calibrate ADC
4. Starting the acquisition

ADC

1. Configure and enable DMA

Address of the register where the result of the acquisition is saved

```
#define ADC1_DR_Address ((uint32_t)0x4001244C)
DMA_InitTypeDef DMA_InitStructure;
__IO uint16_t ADCConvertedValue;

RCC_AHBPeriphClockCmd(RCC_AHBPeriph_DMA1, ENABLE);

/* DMA1 channel1 configuration -----*/
DMA_DeInit(DMA1_Channel1);
DMA_InitStructure.DMA_PeripheralBaseAddr = ADC1_DR_Address;
DMA_InitStructure.DMA_MemoryBaseAddr = (uint32_t)&ADCConvertedValue;
DMA_InitStructure.DMA_DIR = DMA_DIR_PeripheralSRC;
DMA_InitStructure.DMA_BufferSize = 1;
DMA_InitStructure.DMA_PeripheralInc = DMA_PeripheralInc_Disable;
DMA_InitStructure.DMA_MemoryInc = DMA_MemoryInc_Disable;
DMA_InitStructure.DMA_PeripheralDataSize = DMA_PeripheralDataSize_HalfWord;
DMA_InitStructure.DMA_MemoryDataSize = DMA_MemoryDataSize_HalfWord;
DMA_InitStructure.DMA_Mode = DMA_Mode_Circular;
DMA_InitStructure.DMA_Priority = DMA_Priority_High;
DMA_InitStructure.DMA_M2M = DMA_M2M_Disable;
DMA_Init(DMA1_Channel1, &DMA_InitStructure);
/* Enable DMA1 channel1 */
DMA_Cmd(DMA1_Channel1, ENABLE);
```

ADC

1. Configure and enable DMA

```
#define ADC1_DR_Address  ((uint32_t)0x4001244C)
DMA_InitTypeDef DMA_InitStructure;
__IO uint16_t ADCConvertedValue;

RCC_AHBPeriphClockCmd(RCC_AHBPeriph_DMA1, ENABLE);

/* DMA1 channel1 configuration -----*/
DMA_DeInit(DMA1_Channel1);
DMA_InitStructure.DMA_PeripheralBaseAddr = ADC1_DR_Address;
DMA_InitStructure.DMA_MemoryBaseAddr = (uint32_t)&ADCConvertedValue;
DMA_InitStructure.DMA_DIR = DMA_DIR_PeripheralSRC;
DMA_InitStructure.DMA_BufferSize = 1;
DMA_InitStructure.DMA_PeripheralInc = DMA_PeripheralInc_Disable;
DMA_InitStructure.DMA_MemoryInc = DMA_MemoryInc_Disable;
DMA_InitStructure.DMA_PeripheralDataSize = DMA_PeripheralDataSize_HalfWord;
DMA_InitStructure.DMA_MemoryDataSize = DMA_MemoryDataSize_HalfWord;
DMA_InitStructure.DMA_Mode = DMA_Mode_Circular;
DMA_InitStructure.DMA_Priority = DMA_Priority_High;
DMA_InitStructure.DMA_M2M = DMA_M2M_Disable;
DMA_Init(DMA1_Channel1, &DMA_InitStructure);
/* Enable DMA1 channel1 */
DMA_Cmd(DMA1_Channel1, ENABLE);
```

We read 16bits from ADC and save
16bits in the `ADCConvertedValue` variable

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;
```

We set the prescaler to have **ADCCLK==12MHz**

```
RCC_ADCCLKConfig(RCC_PCLK2_Div2);  
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);
```

```
/* ADC1 configuration */  
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;  
ADC_InitStructure.ADC_ScanConvMode = ENABLE;  
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;  
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;  
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;  
ADC_InitStructure.ADC_NbrOfChannel = 1;  
ADC_Init(ADC1, &ADC_InitStructure);  
/* ADC1 regular channel14 configuration */  
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);  
  
/* Enable the temperature sensor */  
ADC_TempSensorVrefintCmd(ENABLE);  
/* Enable ADC1 DMA */  
ADC_DMACmd(ADC1, ENABLE);  
/* Enable ADC1 */  
ADC_Cmd(ADC1, ENABLE);  
/* Enable ADC1 reset calibration register */  
ADC_ResetCalibration(ADC1);  
/* Check the end of ADC1 reset calibration register */  
while(ADC_GetResetCalibrationStatus(ADC1));  
/* Start ADC1 calibration */  
ADC_StartCalibration(ADC1);  
/* Check the end of ADC1 calibration */  
while(ADC_GetCalibrationStatus(ADC1));  
/* Start ADC1 Software Conversion */  
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

ADC in independent mode

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

ADC in **continuous scan mode**

ADC

2. Configure and enable ADC

```
RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

no trigger

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

one single channel

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

The recommended **sampling time** for the temperature sensor is **17.1 μ s**.

With **ADCCLK==12MHz** we have **12 cycles** in **1 μ s**.

So the **sampling time in cycles** is **12 * 17.1 == 206 cycles**

We set the sampling time to **239.5 cycles**

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

Enabling the temperature sensor

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

Enabling DMA and ADC

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

Calibration phase

ADC

2. Configure and enable ADC

```
ADC_InitTypeDef ADC_InitStructure;

RCC_ADCCLKConfig(RCC_PCLK2_Div2);
RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);

/* ADC1 configuration */
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);

/* Enable the temperature sensor */
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
```

Start conversion

ADC (code)

stm32f10x_conf.h

...

```
#include "stm32f10x_adc.h"
/* #include "stm32f10x_bkp.h" */
/* #include "stm32f10x_can.h" */
/* #include "stm32f10x_crc.h" */
/* #include "stm32f10x_dac.h" */
/* #include "stm32f10x_dbgmcu.h" */
#include "stm32f10x_dma.h"
#include "stm32f10x_exti.h"
#include "stm32f10x_flash.h"
/* #include "stm32f10x_fsmc.h" */
#include "stm32f10x_gpio.h"
/* #include "stm32f10x_i2c.h" */
/* #include "stm32f10x_iwdg.h" */
#include "stm32f10x_pwr.h"
#include "stm32f10x_rcc.h"
/* #include "stm32f10x_rtc.h" */
/* #include "stm32f10x_sdio.h" */
/* #include "stm32f10x_spi.h" */
#include "stm32f10x_tim.h"
/* #include "stm32f10x_usart.h" */
/* #include "stm32f10x_wwdg.h" */
```

...

ADC (code)

main.c

```
#include "stm32f10x.h"
#define ADC1_DR_Address  ((uint32_t)0x4001244C)
ADC_InitTypeDef ADC_InitStructure;
DMA_InitTypeDef DMA_InitStructure;
__IO uint16_t ADCConvertedValue;
void RCC_Configuration(void);
void GPIO_Configuration(void);
int main(void)
{
    RCC_Configuration();
    /* DMA1 channel1 configuration -----*/
    DMA_DeInit(DMA1_Channel1);
    DMA_InitStructure.DMA_PeripheralBaseAddr = ADC1_DR_Address;
    DMA_InitStructure.DMA_MemoryBaseAddr = (uint32_t)&ADCConvertedValue;
    DMA_InitStructure.DMA_DIR = DMA_DIR_PeripheralSRC;
    DMA_InitStructure.DMA_BufferSize = 1;
    DMA_InitStructure.DMA_PeripheralInc = DMA_PeripheralInc_Disable;
    DMA_InitStructure.DMA_MemoryInc = DMA_MemoryInc_Disable;
    DMA_InitStructure.DMA_PeripheralDataSize = DMA_PeripheralDataSize_HalfWord;
    DMA_InitStructure.DMA_MemoryDataSize = DMA_MemoryDataSize_HalfWord;
    DMA_InitStructure.DMA_Mode = DMA_Mode_Circular;
    DMA_InitStructure.DMA_Priority = DMA_Priority_High;
    DMA_InitStructure.DMA_M2M = DMA_M2M_Disable;
    DMA_Init(DMA1_Channel1, &DMA_InitStructure);
    /* Enable DMA1 channel1 */
    DMA_Cmd(DMA1_Channel1, ENABLE);
```

...

ADC (code)

main.c

```
...
/* ADC1 configuration -----*/
ADC_InitStructure.ADC_Mode = ADC_Mode_Independent;
ADC_InitStructure.ADC_ScanConvMode = ENABLE;
ADC_InitStructure.ADC_ContinuousConvMode = ENABLE;
ADC_InitStructure.ADC_ExternalTrigConv = ADC_ExternalTrigConv_None;
ADC_InitStructure.ADC_DataAlign = ADC_DataAlign_Right;
ADC_InitStructure.ADC_NbrOfChannel = 1;
ADC_Init(ADC1, &ADC_InitStructure);
/* ADC1 regular channel14 configuration */
ADC_RegularChannelConfig(ADC1, ADC_Channel_16, 1, ADC_SampleTime_239Cycles5);
ADC_TempSensorVrefintCmd(ENABLE);
/* Enable ADC1 DMA */
ADC_DMACmd(ADC1, ENABLE);
/* Enable ADC1 */
ADC_Cmd(ADC1, ENABLE);
/* Enable ADC1 reset calibration register */
ADC_ResetCalibration(ADC1);
/* Check the end of ADC1 reset calibration register */
while(ADC_GetResetCalibrationStatus(ADC1));
/* Start ADC1 calibration */
ADC_StartCalibration(ADC1);
/* Check the end of ADC1 calibration */
while(ADC_GetCalibrationStatus(ADC1));
/* Start ADC1 Software Conversion */
ADC_SoftwareStartConvCmd(ADC1, ENABLE);
while (1);
}
```

ADC (code)

main.c

```
/**
 * @brief Configures the different system clocks.
 * @param None
 * @retval None
 */
void RCC_Configuration(void)
{
    /* ADCCLK = PCLK2/2 */
    RCC_ADCCLKConfig(RCC_PCLK2_Div2);
    /* Enable peripheral clocks -----*/
    /* Enable DMA1 clock */
    RCC_AHBPeriphClockCmd(RCC_AHBPeriph_DMA1, ENABLE);
    /* Enable ADC1 and GPIOC clock */
    RCC_APB2PeriphClockCmd(RCC_APB2Periph_ADC1, ENABLE);
}
```


ADC (exercises and questions)

1. What the read value is? What does it mean?
2. Search the conversion formula in the manual. How many degrees are we measuring? How is it possible?
2. Write a program to monitor the temperature for 10 min with a sampling time of 30 sec, writing data in SRAM memory using DMA.
3. Write a program to turn on a LED if the temperature is above a certain threshold and turn off again if the temperature falls below the threshold.

Table 64. TS characteristics

Symbol	Parameter	Min	Typ	Max	Unit
T _L	V _{SENSE} linearity with temperature		±1	±2	°C
Avg_Slope	Average slope	4.0	4.3	4.6	mV/°C
V ₂₅	Voltage at 25 °C	1.34	1.43	1.52	V
t _{START} ⁽¹⁾	Startup time	4		10	µs
T _{S_temp} ⁽²⁾⁽¹⁾	ADC sampling time when reading the temperature			17.1	µs

1. Guaranteed by design, not tested in production.

2. Shortest sampling time can be determined in the application by multiple iterations.

#9 Project

Project

The project consist in writing the code for a device able to transmit maximum and average value of a waveform connected to a pin of the microcontroller

Project description:

- When the STM32 Discovery is turned on the green LED starts blinking at 2 Hz.
- When the user presses the button the signal is sampled using the ADC and the data is stored in SRAM memory buffer using DMA.
- The memory buffer is used to compute maximum, minimum and average value
- The blinking frequency of the blue LED is set according to signal amplitude (peak to peak value, use maximum – minimum) when amplitude is below 100 mv blink frequency is 0.1Hz, when above 3V frequency is 20Hz
- If the user press again the button the second LED is turned off and the acquisition is stopped.
- Each time the maximum, minimum and average value are extracted, a string containing data is sent through serial port.

Tips and project requirements:

- Convert the ADC value in Volt and use “sprintf (char * str, const char * format, ...);” to convert ADC value to a string
- The memory buffer has to be the size of 100 elements, chose arbitrary waveform, with a frequency around kHz
- The acquisition can be performed using the channel14 of ADC1 (corresponding to the Pin4 of the GPIOC that has to be configured in INPUT mode)