

# Introduction to Complex Exponentials Direction Finding

# TSE2280 Signal Processing

# Lab 1, Spring 2025

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## 1 Introduction

## 1.1 Background and Motivation

The lab demonstrates concepts from Chapters 2 and 3 in the course textbook *DSP First* [1], by illustrating how sinusoidal signals are described with complex amplitudes called *phasors*.

The first part of the lab gives training in sinusoidal signals and complex exponentials. The last part applies this to find the direction to a sound source from the phase difference at two microphones. This principle is the basis for steering and focusing antennas without moving them, such as *phased arrays* used in radar, Wi-Fi, and 5G, and sonar and medical ultrasound transducers.

The lab is based on *Lab P-3: Introduction to Complex Exponentials – Direction Finding* [2] that accompanies the textbook. The original lab has been converted from Matlab to Python and some contents has been modified.

## 1.2 Software Tools: Python with Spyder and JupyterLab

The programs are written in Python. The module NumPy [3, 4] is used to represent signals and Matplotlib [5, 6] to plot graphs. Including Python's cmath and math modules can make the code easier to read, but be aware that cmath and math only handle scalars. Note also that cmath always returns a complex number, even when the imaginary part is zero. The recommended setup for importing the modules is shown in Table 1.

The recommended Python programming environment is *Spyder* [7], which is included in the *Anaconda* [8] package management. However, any Python package management and programming environment can be used.

All code files shall be included with the lab report. We recommend collecting everything, text, code, and figures, into a single JupyterLab Notebook [9], but a pdf with separate Python files is also acceptable.

## 2 Theory

## 2.1 Sinusoidal Signals and Phasors

Recall from the lectures that a sinusoidal signal x(t) is written as

$$x(t) = A\cos(\omega t + \phi) = \operatorname{Re}\left\{Ae^{j(\omega t + \phi)}\right\} = \operatorname{Re}\left\{Xe^{j\omega t}\right\} , \qquad X = Ae^{j\phi}$$
 (1)

where A is the amplitude,  $\omega=2\pi f$  is the angular frequency, f is the frequency, and  $\phi$  is the phase. X is a *phasor* or *complex amplitude* that includes both the amplitude and the phase of the signal. Analysis of sinusoidal signals like x(t) can be simplified by manipulating complex phasors instead of working with the amplitude and phase separately. See Chapter 2 in the textbook [1] for details.

## 2.2 Adding Sinusoids Using Complex Exponentials

Consider a signal that is the sum of sinusoids with equal frequency  $f_0$ , but where the amplitudes  $A_k$  and phases  $\phi_k$  of the individual signals can be different,

$$x_s(t) = \sum_{k=1}^{N} A_k \cos(2\pi f_0 t + \phi_k) .$$
 (2)

The resulting signal can be found by representing the individual components as complex vectors. This is called *phasor summation* and is in general easier than using trigonometric identities,

$$x_s(t) = \text{Re}\left\{\sum_{k=1}^N A_k e^{j\phi_k} e^{j2\pi f_0 t}\right\} = \text{Re}\left\{\sum_{k=1}^N X_k e^{j2\pi f_0 t}\right\} \qquad , \qquad X_k = A_k e^{j\phi_k} . \tag{3}$$

The factor  $e^{j2\pi f_0t}$  in (3) is equal for all the individual signals. Hence, the amplitude  $A_k$  and phase  $\phi_k$  of the summed signal  $x_s(t)$  can be found by summing the complex amplitudes,

$$x_s(t) = \text{Re}\left\{X_s e^{j\omega t}\right\} = A_s \cos(2\pi f_0 t + \phi_s), \qquad X_s = \sum_{k=1}^N X_k = A_s e^{j\phi_k}.$$
 (4)

The resulting signal will have the same frequency  $f_0$  and period  $T_0 = 1/f_0$  as the original signals.

**Table 1.** Recommended format for importing Python modules. NumPy is used to manipulate signals as arrays, Matplotlib to plot results. The real-valued mathematics library math is loaded for simple access to the trigonometric functions and  $\pi$ . The complex mathematics library cmath is included for simpler access to selected complex-valued functions. Note that math and cmath work only on scalars, not on arrays.

```
import numpy as np
import matplotlib.pyplot as plt
from math import pi, cos, sin, tan # For readability, also covered by NumPy
from cmath import exp, sqrt, phase
```

## 2.3 Harmonics and Periodic signals

Consider another signal  $x_h(t)$  where the frequencies  $f_k$  of the individual cosine-waves are different, but integer multiples of a fundamental frequency  $f_0$ ,

$$f_k = k f_0$$
 ,  $k = 0, 1, 2, \dots$  (5)

The individual signals  $\cos(2\pi k f_0 t + \phi_k)$  are called *harmonics*. The summed signal  $x_h(t)$  can be written as

$$x_h(t) = \sum_{k=1}^{N} A_k \cos(2\pi k f_0 t + \phi_k) = \text{Re}\left\{\sum_{k=1}^{N} X_k e^{j2\pi k f_0 t}\right\}.$$
 (6)

The period  $T_0$  of the fundamental frequency  $f_0$  is

$$T_0 = \frac{1}{f_0} \,, \tag{7}$$

while the periods  $T_k$  of the harmonics are

$$T_k = \frac{1}{f_k} = \frac{1}{kf_0} = \frac{T_0}{k} \,. \tag{8}$$

The signal with frequency  $kf_0$  will repeat itself after the period  $T_k = T_0/k$ . It will therefore have repeated itself k times after the fundamental period  $T_0$ . Hence, all the frequency components  $kf_0$  will also be periodic with period  $T_0$ , and the summed signal  $x_h(t)$  will be periodic with period  $T_0$  given by the fundamental frequency.

# 3 Programming Tips

## 3.1 Complex Numbers in Python with NumPy

Python can handle complex numbers like any other numbers. The module cmath contains elementary mathematical functions for use on *scalar* complex numbers, while NumPy includes mathematical functions for use on *arrays* of complex numbers.

Basic operations on complex numbers in Python are listed in Table 2. A complex number in Python has three public members, real, imag, and conjugate(), while other operations on can be found in cmath or NumPy. Note that the format of the functions calls depends on how the modules NumPy and cmath were imported. The list in Table 2 assumes the mudules were imported as in Table 1.

## 3.2 Displaying Phasors

The Python file <code>zplot.py</code> contains functions to plot complex numbers as phasors, called Argand-diagrams. This is done by the function <code>zplot.phasor()</code>, see description in Table 3.

#### 3.3 Vectorization

The NumPy module allows mathematical operations to be used on arrays. This is convenient when defining signals as function of time. In the cosine-function  $x(t) = A\cos(2\pi f t + \phi)$ , the amplitude A and phase  $\phi$  are scalars, while the time t is a vector spanning the time interval to be investigated. Vectors covering a defined interval can be created in NumPy by one of the following methods.

**Table 2.** Overview of complex number operations in Python. Details are found in the documentation for cmath and NumPy. The code assumes the modules cmath and NumPy are imported as described in Table 1. Note that the operations on scalar complex numbers are a mix of internal members (z.real, z.imag, z.conjugate()), built-in functions (abs) and functions from the cmath module (phase, exp). The NumPy functions can be used on both scalars and arrays.

Scalar	Array	Description	Mathematical notation
z = complex(2,3)		Creates a complex number.	z = x + jy = 2 + 3j.
z = 2 + 3j		Same as above	
1j		Imaginary unit, $i$ or $j$ .	$i = j = \sqrt{-1}$
z.conjugate()	np.conj(z)	Complex conjugate.	$z^* = x - jy$
abs(z)	np.abs(z)	Absolute value.	$ z  = \sqrt{x^2 + y^2}$
phase(z)	np.angle(z)	Phase in radians.	$\angle z$
z.real	np.real(z)	Real part.	$\operatorname{Re}\{z\} = x$
z.imag	np.imag(z)	Imaginary part.	$\operatorname{Im}\{z\} = y$
exp(1j*theta)	np.exp(1j*theta)	Complex exponential.	$e^{j\theta} = \cos\theta + j\sin\theta$

**Table 3.** Function phasor() to show complex numbers as phasors in the complex plane (Argand-diagrams). The function is found in the file zplot.py included for this lab.

```
def phasor(zk, labels=[], include_sum=False, include_signal=False, frequency=1):
    """Show complex amplitudes and resulting signals.
   Parameters
   zk : Complex or list of complex
       Complex numbers to show
   labels=[] : List of strings, optional
       List of labels to mark phasors
   include_sum=False : Boolean, optional
       Show the sum of all numbers as a phasor
   include_signal=False : Boolean, optional
       Include a plot of signals as function of time
   frequency=1 : Float, optional
       Frequency used to plot the signals
   Returns
   ax : List of Matplotlib Axes
       Handle to axes containing the plots
```

1) t = np.arange(t\_start, t\_end, dt)

Specify start, stop, and step between the samples in the time vector. t\_start is the first point in the vector, t\_end marks the end of t, and dt is the interval between the time points. Note that t\_end is not included in the time vector, t ends on the last point before t\_end.

2) t = np.linspace(t\_start, t\_end, n\_points)

Specify start, stop, and total number of points in the time vector.  $t_start$  is the first point in t, t\_end marks the end of t, and n\_points is number of points in the vector. Note that for this function, t\_end is included in t.

3) t = np.geomspace(t\_start, t\_end, n\_points)

This is the same as linspace, but the numbers are evenly spaced on a logarithmic scale, i.e., a geometric sequence.

## 3.4 Comparing Graphs

We sometimes want to compare graphs. Two useful methods to do this in Matplotlib are

- 1) Use subplot to stack the graphs vertically or horizontally.
- 2) Plot the two curves in the same graph, the first with a solid line ('-') and the second with a dashed line ('--'). Even if the curves are very similar, the first one will be visible behind the second.

Example code for this is shown in Table 4, more information is found in the documentation for Matplotlib.

**Table 4.** Code for stacking graphs using subplot (Example 1) and for using dashed lines to distinguish between similar graphs (Example 2).

```
# Example 1: Using subplot to stack plots
plt.subplot(2, 1, 1)  # Two plots stacked vertically, use first (upper) graph
plt.plot(t, x1)  # Plot first result (x1) as function of t

#-- Formatting of the first subplot comes here (labels, axis limits etc.) ---

plt.subplot(2, 1, 2)  # Two plots stacked vertically, use second (lower) graph
plt.plot(t, x2)  # Plot second result (x2) as function of t

#-- Formatting of the second subplot comes here ---

# Example 2: Showing two similar graphs in one plot
plt.plot(t, x1, '-')  # Plot first result (x1) with a solid line
plt.plot(t, x2, '--')  # Plot second result (x2) with a dashed line

#-- Formatting of the graph comes here ---
```

# 4 Training Exercises

## Reporting

Collect answers and code in a JupyterLab notebook. Export this to pdf and upload it to Canvas.

You may prefer to do some of the coding in a development tool with better options for testing and debugging, such as Spyder. If so, the code can be pasted into JupyterLab, or the .py-files from from Spyder can be loaded into JupyterLab.

## 4.1 Complex Numbers

- 1) Load <code>zplot</code> and enter the two complex numbers  $z_1 = 2e^{j\pi/3}$  and  $z_2 = -\sqrt{2} + 5j$ .

  Use Python to find the real and imaginary parts, magnitude, and phase of  $z_1$  and  $z_2$ .

  Display  $z_1$  and  $z_2$  and the sum  $z_1 + z_2$  as phasors with <code>zplot.phasor</code>. The input to <code>zplot.phasor</code> is specified as a <code>list</code>, this is made by enclosing the numbers in square brackets, e.g., <code>[z1, z2]</code>.
- 2) Find the complex conjugate  $z^*$  and inverse 1/z for  $z_1$  and  $z_2$  and plot them together with  $z_1$  and  $z_2$  using zplot. Recall what you have learned about complex numbers in math courses. Are the results as expected?
- 3) Calculate the product  $z_1z_2$  and ratio  $z_1/z_2$  and plot them using zplot. Are these results as expected?
- 4) Calculate the products of the conjugates,  $z_1z_1^*$  and  $z_2z_2^*$ . Plot them in the same diagram as  $z_1$  and  $z_2$  and explain the result.
- 5) Calculate the sums  $z_1 + z_1^*$  and differences  $z_1 z_1^*$  of the conjugates and plot them in the same diagram as  $z_1$ . Do the same for  $z_2$ . Explain these results.

## 4.2 Python Function to Generate a Sinusoid Signal

1) Write a function (def in Python) that generates a single sinusoid,  $x(t) = A\cos(2\pi ft + \phi)$  from the four input arguments amplitude A, frequency f, phase  $\phi$  and duration.

The function shall return the signal x(t) and the time vector t with the time-points where the signal is evaluated.

The function shall generate exactly 32 values of the sinusoid per period.

A skeleton for this function make\_cos with the recommended function call and documentation string is listed in Table 5.

2) Demonstrate that your function works by plotting the output for the following parameters:

$$A = 10^4$$
  $f = 1.5 \,\mathrm{MHz}$   $\phi = -45^\circ$  Duration  $10^{-6} \,\mathrm{s}$ 

Note that the phase must be converted to radians before calculating the result.

Calculate the value of x(t) at t = 0. Does this agree with the plot?

What is the period of the signal? Does this agree with the plot?

**Table 5.** Skeleton for a function to generate a cosine signal from amplitude, frequency, and phase. The first lines are the recommended function call and docstring. The last line specifies that the signal x and time vector t are returned.

```
def make_cos(A, f0, phase, duration):
"""Make a cosine-function from specified parameters.
Parameters
A : float
   Amplitude
f0: float
   Frequency [Hz]
phase: float
   Phase [radians]
duration: float
   Duration of signal [seconds]
Returns
x: 1D array of float
   Cosine-wave
t: 1D array of float
   Time vector [seconds]
#-- Your code comes here ---
return x, t
```

## 4.3 Python Function to Generate a Sum of Sinusoid Signals

Signals are often described as a sum of sinusoids with different amplitudes, frequencies, and phases. It can therefore be convenient to have a function that generates a sum from several cosine-functions, each specified by its amplitude  $A_k$ , frequency  $f_k$ , and phase  $\phi_k$ .

1) Write a function that generates a signal

$$x(t) = \sum_{k=1}^{N} A_k \cos(2\pi f_k t + \phi_k) = \sum_{k=1}^{N} X_k e^{j2\pi f_k t}.$$
 (9)

The arguments to the function are the frequencies  $f_k$  and complex amplitudes  $X_k = A_k e^{j\phi}$ , the sample rate  $f_s$  and the signal duration.

The function shall return the summed signal x(t) and the time vector t where the signal is evaluated.

The frequencies  $f_k$  and complex amplitudes  $X_k$  shall be specified as lists or NumPy arrays, and the function shall accept any number of frequency components.

Each frequency  $f_k$  has a complex amplitude  $X_k$ , so the vectors  $f_k$  and  $X_k$  must have equal length. The function shall return an error message if this is not fulfilled.

A skeleton of this function make\_summed\_cos with the recommended function call and documentation string is listed in Table 6.

2) Demonstrate that your function works by plotting the output for a signal that is the sum of the following components.

	Frequency	Complex amplitude
k	$f_k$ [Hz]	$X_k$
1	0	10
2	100	$14e^{-j\pi/3}$
3	250	8j

Set the sample rate to  $10\,000\,\mathrm{Samples/s}$ , the duration of the signal to  $0.1\,\mathrm{s}$ , and the start time to  $0\,\mathrm{s}$ . Plot the result with Matplotlib.

Make a new subplot and plot the individual frequency components of the signal in this subplot.

3) Measure the period  $T_0$  of the signal from the graph. Compare this to the periods  $T_k$  of the individual frequency components  $f_k$ .

Explain how the period of the summed signal can be calculated from the periods of the individual components.

4) Generate the signal

$$x(t) = \operatorname{Re}\left\{-2e^{j50\pi t} - e^{j50\pi(t-0.02)} + (2-3j)e^{j50\pi t}\right\}$$

over a time range that covers 2 periods.

Plot the signal x as function of time t.

5) All frequency components in the signal above are equal. Hence, the amplitude and phase can be calculated by summing its complex amplitudes, *phasors*.

Use the function <code>zplot.phasor</code> from earlier to plot the phasor diagram for this signal, and check that this agrees with the result from <code>make\_summed\_cos</code>.

zplot.phasor has optional arguments that can be set to illustrate this better, see Table 3.

include\_sum = True Include the sum of all the phasors to the plot.
include\_signal = True Plot the signals corresponding to the phasors.
frequency = <value> Frequency to use when plotting the signals.

# 5 Lab Exercise: Direction Finding

The text in this exercise is taken from [2] and somewhat modified.

Why do humans have two ears? One answer is that the brain can process acoustic signals received at the two ears and determine the direction to the source of the acoustic energy. Using sinusoids, we can describe and analyze a simple scenario that explains this direction finding capability in terms of phase differences or time-delay differences. This principle is the basis for a wide range of other applications, such as radars that locate and track airplanes, 5G and wifi antennas, and phased array transducers for medical ultrasound imaging and sonar.

**Table 6.** Skeleton for a function <code>make\_summed\_cos</code> to generate a signal by summing cosine-functions with different complex amplitudes and frequencies. The first lines are the recommended function call and docstring. The last line specifies that the signal x and time vector t are to be returned. Note how the start time <code>t\_start</code> is specified as an optional argument with default value 0.

```
def make_summed_cos(fk, Xk, fs, duration, t_start=0):
    """Synthesize a signal as a sum of cosine waves
   Parameters
   fk: List of floats
       Frequencies [Hz]
   Xk: List of floats
       Complex amplitudes (phasors)
   fs: float
       Sample rate [Samples/second]
   duration: float
       Duration of signal [s]
   t_start : float, optional
       Start time, first point of time-vector [seconds]
   fk and Xk must have the same lengths.
   Returns
   x: 1D array of float
       Signal as the sum of the frequency components
   t: 1D array of float
       Time vector [seconds]
    #-- Your code comes here ---
   return x, t
```

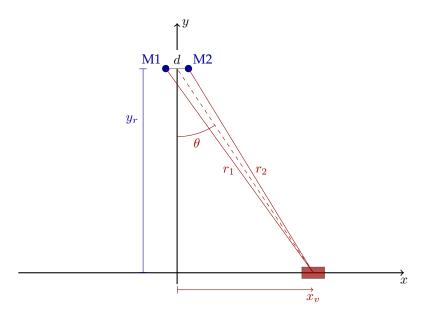
## **Direction Finding With Microphones**

Consider a system consisting of two microphones that both hear the same source signal. The microphones are placed some distance apart, so the sound must travel different paths from the source to the receivers. When the travel paths have different lengths, the two signals will arrive at different times.

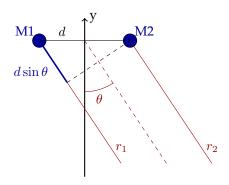
The direction to the source can be calculated from the time difference between the signals received by the two microphones. If the source signal is a sinusoid, the time difference can be calculated from the phase difference. The scenario is illustrated in Figure 1. A vehicle traveling along the roadway has a siren that transmits a tone with frequency  $f_v$ =400 Hz. The roadway forms the x-axis of a coordinate system. Two microphones are located some distance away and aligned parallel to the roadway. The distance from the road to the microphones is  $y_r$ =100 m and the microphone separation is d=0.40 m. The task is to process the signals from the microphones to find the direction to the vehicle, described by the angle  $\theta$  in Figure 1.

- 1) The time from the sound is transmitted by the source until it is received by one of the microphones can be computed for the two propagation paths  $r_1$  and  $r_2$ . The time is given by the distance from the vehicle location at coordinate  $(x_v, 0)$  to either M1 at coordinate  $(-\frac{1}{2}d, y_r)$  or M2 at  $(+\frac{1}{2}d, y_r)$ .
  - The speed of sound in air is  $c=340\,\mathrm{m/s}$ . Write mathematical expressions for the time  $t_1$  it takes for the sound to travel from the source to M1 and for  $t_2$  from the source to to M2. Plot  $t_1$  and  $t_2$  as functions of the vehicle position  $x_v$  from  $-400\,\mathrm{m}$  to  $400\,\mathrm{m}$ .
  - Can you see any difference between  $t_1$  and  $t_2$  in the graph?
- 2) In the simplest model, the signals received by the microphones,  $s_1(t)$  at M1 and  $s_2(t)$  at M2, are delayed copies of the transmitted signal s(t),

$$s_1(t) = s(t - t_1)$$
  $s_2(t) = s(t - t_2)$  (10)



**Figure 1.** Direction finding using two microphones. A vehicle at position  $x_v$  travels along the x-axis while emitting a sound with frequency  $f_v$ =400 Hz. The sound is picked up by two microphones M1 and M2 positioned with spacing d=0.40 m. The difference in path length  $\Delta r = r_1 - r_2$  causes a phase-shift between the signals received by the two microphones. This phase shift can be used to estimate the direction to the vehicle, specified by the angle  $\theta$ .



**Figure 2.** Zoomed-in version of Figure 1. When the distance to the source is very long compared to the spacing between the microphones,  $r_1, r_2 \gg d$ , the paths can be approximated as parallel. In this case, the difference in travel length to the two microphones is  $r_1 - r_2 = \Delta r \approx d \sin \theta$ .

where s(t) is the signal transmitted from  $x_v$ .

Assume that the tone s(t) emitted from the source is a sinusoid with zero phase, frequency  $f_v$ =400 Hz, and amplitude A=1. The phases  $\phi_1$  and  $\phi_2$  of the received signals  $s_1(t)$  and  $s_2(t)$  can be found from the delays  $t_1$  and  $t_2$ .

Find the phases  $\phi_1$  and  $\phi_2$ .

Plot the phases  $\phi_1$  and  $\phi_2$  as functions of  $x_v$  from  $-400\,\mathrm{m}$  to  $400\,\mathrm{m}$  in one subplot.

Plot the phase difference  $\Delta \phi = \phi_2 - \phi_1$  as function of  $x_v$  in another subplot.

Comment the results.

3) The received signals can be represented as phasors.

Use zplot to show the signals received by M1 and M2 when the vehicle is at positions  $x_v$ = $-400\,\mathrm{m}, -100\,\mathrm{m}, 0\,\mathrm{m}, 100\,\mathrm{m}$ , and  $400\,\mathrm{m}$ .

Set optional argument include\_signal=True to display the signals, and set the argument frequency to the correct frequency.

Calculate the phase differences by hand and compare this with the plots.

4) The next step is to convert the relative time-shifts into a direction  $\theta$ .

The distance from the microphones to the source is much larger than the distance between the microphones, making the the paths to M1 and M2 almost parallel. This is illustrated in Figure 2, where we have zoomed in on the microphones in Figure 1.

Figure 2 shows that the difference  $\Delta r$  in propagation distance for paths  $r_1$  and  $r_2$  can be approximated to

$$\Delta r = r_1 - r_2 \approx d \sin \theta \,. \tag{11}$$

This is called the *far field approximation* and is often used to find the beam pattern from antennas, loudspeakers, ultrasound transducers, and other transmitters or receivers for waves.

Calculate the propagation time difference  $\Delta t = t_2 - t_1$  from the approximation (11). Use this to find the approximated phase difference  $\Delta \phi_F$  between the two received signals. Plot  $\Delta \phi_F$  in the same graph as the correct value  $\Delta \phi$  found previously.

Comment the result.

5) The last step is to write a Python function to process the received signals and find the direction  $\theta$ . Show first that the phase difference between two phasors  $X_1$  and  $X_2$  is given by

$$\Delta \phi = -\angle (X_1 X_2^*)$$

where the superscript \* denotes the complex conjugate and  $\angle$  is the phase of a complex number.

Calculate the complex amplitudes  $X_1 = A_1 e^{j\phi_1}$  and  $X_2 = A_2 e^{j\phi_2}$  received at M1 and M2 as function of vehicle position  $x_v$ . Assume no propagation loss, so that the amplitudes are unchanged,  $A_1 = A_2 = A$ .

Use this and earlier results to write a Python-function that will compute the direction  $\theta$  from the complex amplitudes.

Run this function for the vehicle moving from  $x_v = -400 \,\mathrm{m}$  to  $400 \,\mathrm{m}$  and plot the angle  $\theta_F$  calculated from the phase-shifts using the far-field approximation. Use degrees [°] when plotting the angle.

Compare  $\theta_F$  to the true angle calculated from the actual position of the vehicle.

Comment the result.

## 5.1 Concluding Remarks

This exercise has illustrated how the direction to a sound source can be estimated using two receivers separated by a distance much smaller than the distance to the source. This principle is the basis for how sound and radar beams can be steered and focused without moving parts in *phased arrays*. Such arrays are used to steer medical ultrasound beams by GE Vingmed Ultrasound and in underwater sonars made by Kongsberg Discovery.

## References

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