

GeckoBot ControlBoard Manual

Lars Schiller (AmP)

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Contents

1	Quickstart	2
1.1	Power on the Board	2
1.2	Log into BBB	2
1.3	Running the Code	2
1.4	Enable Pneumatic Power	2
1.5	When your session is over	3
2	Setting Up the BBB	4
2.1	Install OS on BBB	4
2.2	Log in BBB for the first time	4
2.3	Set LAN connection on BBB at AmP	5
2.4	Configure SSH Connection to BBB	5
2.5	Configure BBB Device Tree	6
2.6	Set I2C Bus to FastMode (400kHz)	7
2.7	Installing Software on BBB	8
3	Pin Layout	10
4	Wiring the Hardware	11
4.1	The User Interface	11
4.2	Proportional Valves	11
4.3	Discrete Valves	12
4.4	Pressure Sensors	12
4.5	LCD-Display	13
5	Auxiliary	13
5.1	IP-Addresses in AmP	13
5.2	Formatting SD Card with debian	13
5.3	Set WiFi connection	13
5.4	Setup for analog inputs	14
5.5	Autorun	14
5.6	Disable Webserver on BBB	15

1 Quickstart

1.1 Power on the Board

- Check if all Potentionmeter are in zero position (turned left)
- Check if all small black switches are OFF (switched up)
- Check if 24V Switch is OFF (up)
- Check if pressure source is zero (throttle valve turned left, manometer shows 0 bar)
- Check if I2C Interface is connected to robot or pull-up circuit board (red face on red face!)
- Power on main switch of ControlBoard

1.2 Log into BBB

- You will need a computer with LAN access in the AmP network, and a terminal with ssh capabilities. Putty on Windows. Or standard Terminal on Linux.

- For Windows (Putty):

Hostname	Port
134.28.136.51	22

- Linux:

```
1 bianca@bianca:~ ssh root@134.28.136.51
```

- login: root password: root

1.3 Running the Code

To run the geckobot code:

- on BBB as su

```
1 root@beaglebone:~# cd Git/GeckoBot/Code
2 root@beaglebone:~ Git/GeckoBot/Code/# python3 main.py
```

If you want to run the GUI (to have the ability to save experimental data) run the the following piece of code on bianca with **python2**:

```
1 bianca@bianca:~ cd Git/GeckoBot/Code
2 bianca@bbianca:~ Git/GeckoBot/Code/ python pc-liveplotter-main.py
```

- **Note** that you must start both programs more or less at the same time. (main on bbb is tries to connect to bianca. if there is no listing port at bianca, the gui wont start)
- In case there is an error related to the device tree, just run the code again.

1.4 Enable Pneumatic Power

When control program runs, you can enable the pneumatic energy sources:

- 24V Switch ON (down) (valves are enabled now)
- Pressure Source 1.2 bar (turn throttle valve right until manometer shows the 1.2bar)
- Plug in Vacuum Source if needed.

1.5 When your session is over

If you are done with your experiments, first disable the pneumatic power supply, then quit the control program.

- Pressure Source to 0bar
- 24V Switch OFF (up)
- All Potentiometer to zero
- All small black Switches OFF (up)
- Abort the `main.py` programm on BBB by hitting **Ctrl+C**

```
1 root@beaglebone:~ Git/GeckoBot/Code/# python3 main.py
2 ... ^C [a lot of errors]
3 root@beaglebone:~ Git/GeckoBot/Code/#
```

Note the last line in the listing above. This indicates that the terminal is ready again. This line **should** be there. Otherwise some process(es) are still running in the background... (You can use `htop` command and filter (F4) python programs to kill them. You have to use a different terminal for this purpose).

- Main Switch of ControlBoard off
- If it's friday or you know that nobody will use the ControlBoard in the next few days, you may shutdown `bianca` and `Dell Latitude`.

2 Setting Up the BBB

2.1 Install OS on BBB

The developers of BBB embedded linux systems decided to change the device tree structure from `kernel` overlay (till version 8.7), to `uboot` overlay (9.1+). (Don't ask me to explain). However, the PWM setup for all pins is only possible with `kernel` overlay (or at least I'm not able to configure it in version 9.1+). Therefore you have to use the following image:

`bone-debian-8.7-iot-armhf-2017-03-19-4gb.img` (Download: <http://beagleboard.org/latest-images>)

To install it on a 8GB Micro-SD Card follow the instructions:

- You can use Etcher (<https://etcher.io/>).

OR (on debian):

- Instructions from: <http://derekmolloy.ie/write-a-new-image-to-the-beaglebone-black/>
and from: <https://learn.adafruit.com/beaglebone-black-installing-operating-systems?view=all#copying-the-image-to-a-microsd>
- Decompress and write on SD card (need to be `su` and make sure the security locker of SD Adapter is in writing mode):

```
1 $ xz -d bone-debian-*.img.xz
2 $ dd if=./bone-debian-*.img of=/dev/sdX
```

(Here, `sdX` is the mounted empty uSD Card. It can be found with multiple use of the command `mount` or `df`.)

- Obsolete:
 - In order to turn these images into eMMC flasher images, edit the `/boot/uEnv.txt` file on the BBB and remove the `#` on the line with
`cmdline=init=/opt/scripts/tools/eMMC/init-eMMC-flasher-v3.sh`.
Enabling this will cause booting the microSD card to flash the eMMC. Images are no longer provided here to avoid people accidentally overwriting their eMMC flash.
 - Insert the SD Card in the unpowered BBB, and power it by plugging in the USB or the 5VDC supply. Wait until all 4 LED have solid lights. This can take up to 45 minutes.
 - Flash MicroSD 4 with: Debian 8.7 2017-03-19 4GB SD IoT from <http://beagleboard.org/latest-images> (MicroSD 3 is weird ...).
 - Insert MicroSD in (unpowered) BBB, press the USER Button, and apply power.
 - It will take 30-45 minutes to flash the image onto the on-board chip. Once it is done, the bank of 4 LEDs to the right of the Ethernet port will all turn off. You can then power down your BBB.

2.2 Log in BBB for the first time

Assuming you are called `bianca` and your PC is also called `bianca`, your BBB is called `beaglebone` and the default user on BBB is called `debian`, then the following syntax is correct.

- Connect your PC with a MicroUSB cable to the BBB.
- Open a terminal and ssh into BBB as `debian` and then get superuser to configure the Board.

```
1 bianca@bianca:~ ssh debian@192.168.7.2
2 temppwd
3 debian@beaglebone:~ su
4 root
5 root@beaglebone:~ #
```

- Note that the default passwords are:

temppwd	for <code>debian</code>
root	for <code>root</code>

2.3 Set LAN connection on BBB at AmP

This is from:

<https://groups.google.com/forum/#!msg/beaglebone/AS2US9rtNd4/8y0mZ3LxAwAJ>

- You have to configure **eth0** like this:
address 134.28.136.51 (ask administrator for your personal IP)
netmask 255.255.255.0
dns-nameservers 134.28.205.14
gateway 134.28.136.1
- Plug in LAN cable.
- Get the name of the LAN connection:

```
1 su
2 root@beaglebone:/etc/network# connmanctl services
3 *Ac Wired ethernet_689e19b50543_cable
```

- Using the appropriate ethernet service, tell **connman** to setup a static IP address for this service.

Syntax:

```
1 connmanctl config <service> --ipv4 manual <ip_addr> <netmask> <gateway> --nameservers <
  dns_server>
```

In our case:

```
1 connmanctl config ethernet_689e19b50543_cable --ipv4 manual 134.28.136.51 255.255.255.0
  134.28.136.1 --nameservers 134.28.205.14
```

- Reboot and you are done.
- You can revert back to a DHCP configuration simply as follows:

```
1 $ sudo connmanctl config ethernet_689e19b50543_cable --ipv4 dhcp
```

2.4 Configure SSH Connection to BBB

- Source: <https://askubuntu.com/questions/115151/how-to-set-up-passwordless-ssh-access-for-root-user>
- If your Board crashed, and you were forced to reinstall the OS, there already exist a ssh-key. This you have to remove first (this is for USB cable):

```
1 bianca@bianca:~ ssh-keygen -f "/home/bianca/.ssh/known_hosts" -R 192.168.7.2
```

- Generate a new key:

```
1 bianca@bianca:~ ssh-keygen -f "/home/bianca/.ssh/key_bianca"
```

When you are prompted for a password, just hit the enter key and you will generate a key with no password.

- Allow to log in as root with a password on the server, in aim to transfer the created key to it:

```
1 root@beaglebone:# nano /etc/ssh/sshd_config
```

Make sure you allow root to log in with the following syntax

```
1 PermitRootLogin yes
2 PasswordAuthentication yes
```

Restart the ssh-server:

```
1 root@beaglebone:# service ssh restart
```

- Now you are able to transfer the key to the server:

```
1 bianca@bianca:~ ssh-copy-id -i /home/bianca/.ssh/key_bianca root@192.168.7.2
```

- Check if its work:

```
1 bianca@bianca:~ ssh root@192.168.7.2
```

- Now disable root login with password on server (for saftey):

```
1 root@beaglebone:# nano /etc/ssh/sshd_config
```

And modify the Line:

```
1 PermitRootLogin without-password
2 PasswordAuthentication yes
```

This will allow to login as root with valid key, but not with a password. All other users can further login with a password. Restart the ssh-server and you are done:

```
1 root@beaglebone:# service ssh restart
```

2.5 Configure BBB Device Tree

In order to enable P9.28 as pwm pin, you have to load cape-universala. This you gonna do in /boot/uEnv.txt:

- source: <https://groups.google.com/forum/#!topic/beagleboard/EYSwmyxYjdM>
- /boot/uEnv.txt should be looking something like this:

```
1 root@beaglebone:# cat /boot/uEnv.txt | grep -v "#"
3
4 uname_r=4.4.54-ti-r93
4 cmdline=coherent_pool=1M quiet cape_universal=enable
```

Edit it with:

```
1 root@beaglebone:# nano /boot/uEnv.txt
```

Add the following lines, such that /boot/uEnv.txt looks like:

```
1 root@beaglebone:# cat /boot/uEnv.txt | grep -v "#"
3
4 uname_r=4.4.54-ti-r93
4 dtb=am335x-boneblack-overlay.dtb
5 cmdline=coherent_pool=1M quiet cape_universal=enable
6 cape_enable=bone-capemgr.enable_partno=cape-universala
```

- Reboot and you should be able to configure with:

```
1 root@beaglebone:# config-pin P9-28 pwm
```

Note:

- In debian-elinux-version-9.1+ the /boot/uEnv.txt looks like:

```
1 root@beaglebone:# cat /boot/uEnv.txt | grep -v "#"
3
4 uname_r=4.9.82-ti-r102
4 enable_uboot_overlays=1
5 enable_uboot_cape_universal=1
6 cmdline=coherent_pool=1M net.ifnames=0 quiet
```

If you see this, you may want to find a way to enable all the pins. I failed.

Robert C Nelson seems to be the only one, who has an idea whats going on... https://elinux.org/Beagleboard:BeagleBoneBlack_Debian#U-Boot_Overlays

Debian 9 / Kernel v4.14.71-ti-r80:

- Note: you might need to disable HDMI with `disable_uboot_overlay_video=1` in `/boot/uEnv.txt` if the pins are already in use.
- update bootloader (https://elinux.org/Beagleboard:BeagleBoneBlack_Debian#U-Boot_Overlays)
Check version (19-08-07):

```
1 root@beaglebone:~$ cd /opt/scripts/tools/  
2 root@beaglebone:/opt/scripts/tools$ git pull  
3 root@beaglebone:/opt/scripts/tools$ ./version.sh | grep bootloader  
4 bootloader:[eMMC-(default)]:[/dev/mmcblk1]:[U-Boot 2016.01-00001-g4eb802e]:[location: dd  
   MBR]
```

To upgrade your version of U-Boot:

```
1 root@beaglebone:~$ cd /opt/scripts/tools/developers/  
2 root@beaglebone:/opt/scripts/tools/developers$ ./update_bootloader.sh  
3 root@beaglebone:/opt/scripts/tools/developers$ reboot  
  
5 ...  
  
7 root@beaglebone:/opt/scripts/tools$ ./version.sh | grep bootloader  
8 bootloader:[microSD-(push-button)]:[/dev/mmcblk0]:[U-Boot 2019.04-00002-gbb4af0f50f]:[  
   location: dd MBR]  
9 bootloader:[eMMC-(default)]:[/dev/mmcblk1]:[U-Boot 2016.01-00001-g4eb802e]:[location: dd  
   MBR]
```

Delete the old version:

```
1 root@beaglebone:/opt/scripts/tools$ dd if=/dev/zero of=/dev/mmcblk1 bs=1M count=10
```

also make sure the bb-cape-overlays package is upto date

```
1 apt update  
2 apt install --only-upgrade bb-cape-overlays
```

2.6 Set I2C Bus to FastMode (400kHz)

- Kernel version 4.14.xx
- For Kernel version < 4.4.xx replace `am335x-boneblack.dtb` with `am335x-boneblack-overlay.dtb`
- Backup the original .dtb:

```
1 root@beaglebone: /boot/dtbs/4.14.71-ti-r80# cp am335x-boneblack.dtb am335x-boneblack.dtb  
   .orig
```

- Generate source device tree (.dts) from binary block device tree (.dtb) with device tree compiler (dtc):

```
1 root@beaglebone: /boot/dtbs/4.14.71-ti-r80# dtc -I dtb -O dts -o am335x-boneblack.dts  
   am335x-boneblack.dtb
```

- There are 3 different i2c-buses in the .dts:
 - i2c0: 0x44E0B000 (Not available as Pins)
 - i2c1: 0x4802A000 (Not enabled by default)
 - i2c2: 0x4819C000 (The actual one for configured i2c-1 in Linux-Debian, although the register name/-expansion port is i2c2)

We want to increase the speed of the i2c2 bus. Therefore modify the .dts with nano:

```
1 i2c@4819c000 {
2     compatible = "ti,omap4-i2c";
3     #address-cells = <0x1>;
4     #size-cells = <0x0>;
5     ti,hwmods = "i2c3";
6     reg = <0x4819c000 0x1000>;
7     interrupts = <0x1e>;
8     status = "okay";
9     pinctrl-names = "default";
10    pinctrl-0 = <0x35>;
11
12    #clock-frequency = <0x186a0>;
13    clock-frequency = <0x61a80>;
14
15    linux,phandle = <0xa1>;
16    phandle = <0xa1>;
```

The clock-frequency = <0x186a0> is the frequency, 0x186a0 = 100000 = 100kHz here is the default i2c-1 (Expansion port i2c2) frequency for stock beaglebone black image. 0x61a80 = 400000 = 400kHz is the highest frequency possible for i2c-devices. This we gonna use.

- Generate the .dtb from this modified .dts:

```
1 root@beaglebone: /boot/dtbs/4.14.71-ti-r80# dtc -I dts -O dtb -o am335x-boneblack.dtb
   am335x-boneblack.dts
```

- reboot and check:

```
1 root@beaglebone:# dmesg | grep i2c
```

Something like

```
1 ...
2 omap/i2c@4819c000 is enabled at 400kHz
3 ...
```

should be the output.

2.7 Installing Software on BBB

In order to run the GeckoBot software on the BBB install following packages:

- **python3:** on BBB as su

```
1 root@beaglebone:# apt-get update
2 root@beaglebone:# apt-get install ntpdate
3 root@beaglebone:# ntpdate pool.ntp.org
4 root@beaglebone:# apt-get install build-essential python3-pip python3-scipy python3-
   numpy -y
5
6 root@beaglebone:# pip3.5 install Adafruit_BBIO Adafruit_GPIO board Adafruit-Blinka
   adafruit-circuitpython-charlcd
7
8
9 root@beaglebone:~# mkdir Git
10 root@beaglebone:~# cd Git
11 root@beaglebone:~/Git/# git clone https://github.com/larslevity/GeckoBot.git
```

- **python2:** on BBB as su

```
1 root@beaglebone:# apt-get update
2 root@beaglebone:# apt-get install ntpdate
3 root@beaglebone:# ntpdate pool.ntp.org
4 root@beaglebone:# apt-get install build-essential python-dev python-pip -y
5 root@beaglebone:# pip install --upgrade pip
```

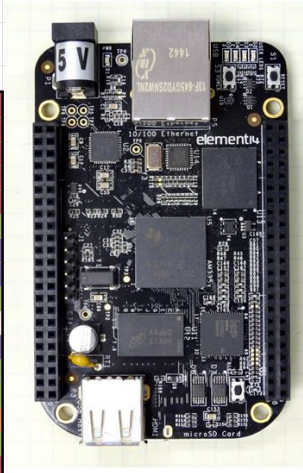


```
6 root@beaglebone:# pip install Adafruit_BBIO
7 root@beaglebone:# pip install Adafruit_GPIO
8 root@beaglebone:# pip install termcolor
9 root@beaglebone:# pip install numpy

11 root@beaglebone:~# mkdir Git
12 root@beaglebone:~# cd Git
13 root@beaglebone:~/Git/# git clone https://github.com/larslevity/GeckoBot.git
```

3 Pin Layout

Figure 1 shows all available pins and there functions of the Beaglebone Board Black and which of these pins are used and for what purpose.

P9					P8			
Function	Physical Pins		Function		Function	Physical Pins		Function
DGND	1	2	DGND		DGND	1	2	DGND
VDD 3.3 V	3	4	VDD 3.3 V		MMC1_DAT6	3	4	MMC1_DAT7
VDD 5V	5	6	VDD 5V		MMC1_DAT2	5	6	MMC1_DAT3
SYS 5V	7	8	SYS 5V		GPIO_66	7	8	GPIO_67
PWR_BUT	9	10	SYS_RESET		GPIO_69	9	10	GPIO_68
UART4_RXD	11	12	GPIO_60		GPIO_45	11	12	GPIO_44
UART4_TXD	13	14	EHRPWM1A		EHRPWM2B	13	14	GPIO_26
GPIO_48	15	16	EHRPWM1B		GPIO_47	15	16	GPIO_46
SPIO_CSO	17	18	SPIO_D1		GPIO_27	17	18	GPIO_65
I2C2_SCL	19	20	I2C_SDA		EHRPWM2A	19	20	MMC1_CMD
SPIO_DO	21	22	SPIO_SLCK		MMC1_CLK	21	22	MMC1_DAT5
GPIO_49	23	24	UART1_TXD		MMC1_DAT4	23	24	MMC1_DAT1
GPIO_117	25	26	UART1_RXD		MMC1_DAT0	25	26	GPIO_61
GPIO_115	27	28	SP11_CSO		LCD_VSYNC	27	28	LCD_PCLK
SP11_DO	29	30	GPIO_112		LCD_HSYNC	29	30	LCD_AC_BIAS
SP11_SCLK	31	32	VDD_ADC		LCD_DATA14	31	32	LCD_DATA15
AIN4	33	34	GND_ADC		LCD_DATA13	33	34	LCD_DATA11
AIN6	35	36	AIN5		LCD_DATA12	35	36	LCD_DATA10
AIN2	37	38	AIN3		LCD_DATA8	37	38	LCD_DATA9
AIN0	39	40	AIN1		LCD_DATA6	39	40	LCD_DATA7
GPIO_20	41	42	ECAPWMO		LCD_DATA4	41	42	LCD_DATA5
DGND	43	44	DGND		LCD_DATA2	43	44	LCD_DATA3
DGND	45	46	DGND		LCD_DATA0	45	46	LCD_DATA1

LEGEND	
Power, Ground, Reset	
Digital Pins	
PWM Output	
1.8 Volt Analog Inputs	
Shared I2C Bus	
Reconfigurable Digital	

P9

DGND	1	2
Bttn PWR 3.3V	3	4
Sens PWR 5V	5	6
	7	8
	9	10
Dvalve 0 Ref	11	12
Dvalve 3 Ref	13	14
Dvalve 2 Ref	15	16
Dvalve 1 Ref	17	18
I2C Clock	19	20
PValve 2 Signal	21	22
PBttn Mode 1	23	24
	25	26
PBttn Mode 2	27	28
	29	30
	31	32
PValve 2 Ref	33	34
PValve 5 Ref	35	36
PValve 6 Ref	37	38
PValve 3 Ref	39	40
	41	42
	43	44
	45	46

P8

	1	2
	3	4
	5	6
Dvalve 1 Signal	7	8
Dvalve 3 Signal	9	10
	11	12
PValve 3 Signal	13	14
LED Mode 1	15	16
LED Mode 3	17	18
PValve 1 Signal	19	20
	21	22
	23	24
	25	26
	27	28
	29	30
	31	32
	33	34
	35	36
	37	38
	39	40
	41	42
	43	44
	45	46

Legend:

pwr
i2c
gpio
pwm
ain

from 28. Juni 2018

Figure 1: Pin layout of BBB

4 Wiring the Hardware

4.1 The User Interface

Figure 2 shows the circuit of the User Interface. It consists of:

- 5 Push-Buttons (3 of them are used as reference for different operating modes, and 2 are used to enable/disable different functions inside these operating modes)
- 5 light emitting diodes, which indicates the actual status of programme, i.e. the operating mode.
- 8 potentiometer, which are used to read the reference signal for the proportional valves.
- 4 switches, which are used to read the reference signal for the discrete valves.
- 9 pull-down resistors, which pull the reference signal for discrete valves and operating modes down again, after activation.

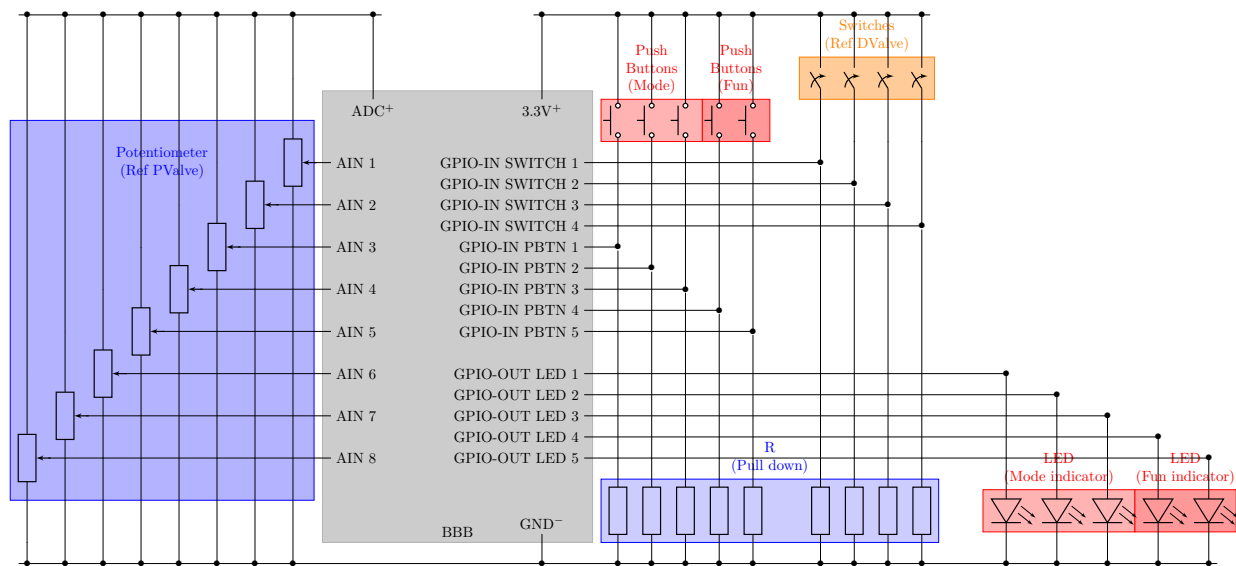
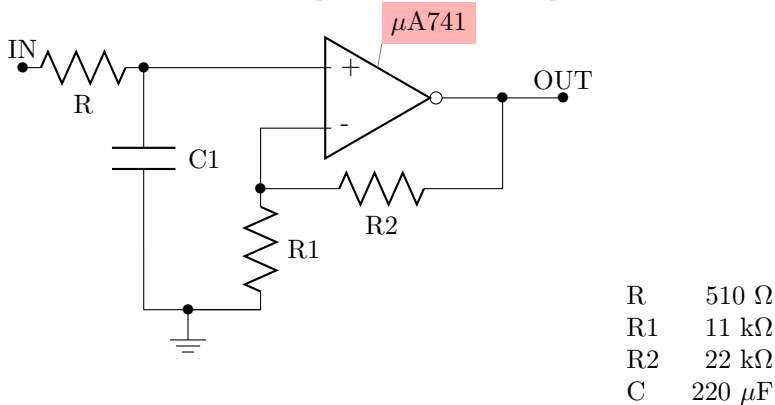


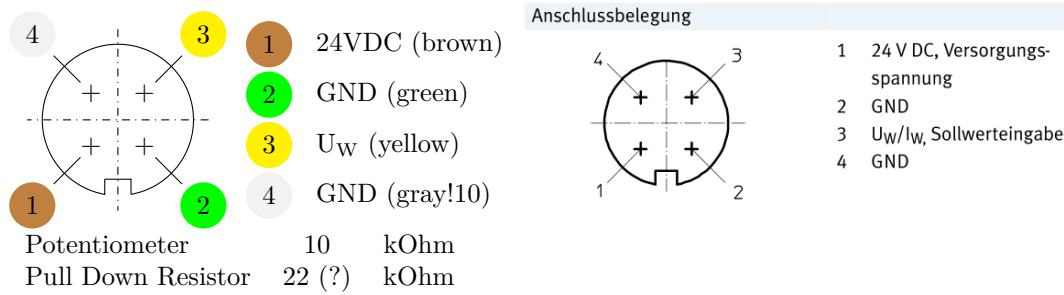
Figure 2: User Interface Wiring

4.2 Proportional Valves

To generate the control signal for the proportional valves, **pwm** is used. Since the pwm-signal oscillating and its level is 3.3V, it must be lowpass-filtered and amplified. Therefore the following circuit is used:

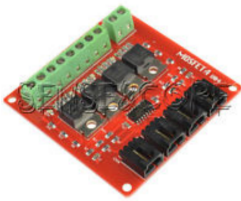


For the proportional valves, the used cable (status: 28.6.18) has the following color scheme (accordingly to the data sheet[1, p. 9]):



4.3 Discrete Valves

The discrete valves are controlled directly via a GPIO. The signal controls a mosfet [3]. A ready-to-use Arduino module is available:



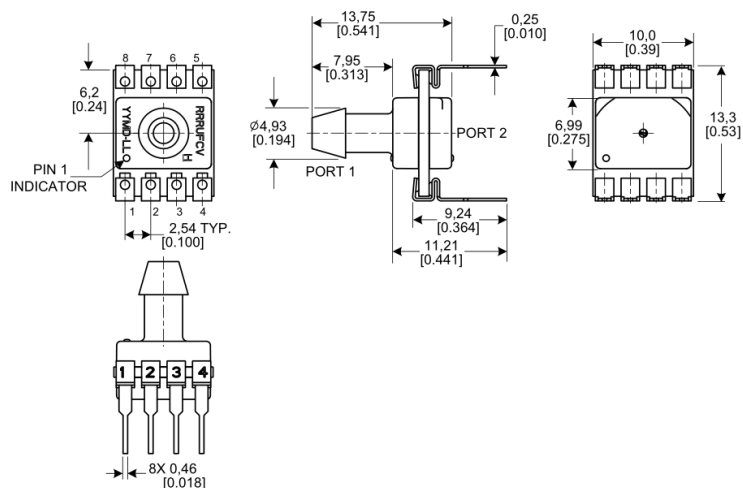
4.4 Pressure Sensors

The following table is from [2, p. 30]. It shows the PinOut of the used pressure Sens. The figure below shows the numbering scheme of the pressure sensors [2, p. 19].

Table 11. Pinouts for DIP and SMT Packages

Output Type	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6	Pin 7	Pin 8
I ² C	GND	V_{supply}	SDA	SCL	NC	NC	NC	NC
SPI	GND	V_{supply}	MISO	SCLK	SS	NC	NC	NC
Analog	NC	V_{supply}	V_{out}	GND	NC	NC	NC	NC

DIP AN: Single axial barbed port



4.5 LCD-Display

Front of LCD PCB

	1	2	5V
I2C Data (red)	3	4	
I2C Clk (yellow)	5	6	DGNG

LCD-Display is connected to I2C.

5 Auxilary

5.1 IP-Addresses in AmP

Subnet	255	.	255	.	255	.	0
Route / Gateway	134	.	28	.	136	.	1
DNS	134	.	28	.	202	.	14
alt. DNS	134	.	28	.	205	.	14
<hr/>							
Main	134	.	28	.	136	.	30
BBB CBoard	134	.	28	.	136	.	51
VR - Mond	134	.	28	.	136	.	129
VR - Bianca	134	.	28	.	136	.	131
RaspPi IMUCam	134	.	28	.	136	.	49
RaspPi GeckoCam	134	.	28	.	136	.	118
DellLat CBoard	134	.	28	.	136	.	70
BBB Rohat	-	.	-	.	-	.	110
BBB experiment	-	.	-	.	-	.	55

5.2 Formatting SD Card with debian

- Source: <https://www.techwalla.com/articles/how-to-format-an-sd-card-in-debian-linux>
- Determine location of SDCard (in the following called: `/dev/mmcblk0p2`) and directory where it is mounted (in the following called: `/media/SDCard`):

```
1 su
2 df
```

- Unmount, format, and remount:

```
1 umount /dev/mmcblk0p2
2 mkdosfs /dev/mmcblk0p2 -F16
3 mount /dev/mmcblk0p2 /media/SDCard
```

- For formatting SD with more than one partition, use:

```
1 cfdisk /dev/mmcblk0
```

and follow the instructions.

5.3 Set WiFi connection

- Order WiFi Antenna TP-LINK WLAN LITEN HI.G USB ADA. WN722N from somewhere.
- Complete this tutorial ...

5.4 Setup for analog inputs

- <https://groups.google.com/forum/#!topic/beagleboard/Lk3vWNIExiQ>
- Insert in command line on BBB:

```
1 su apt-get install bb-cape-overlays
3 cd /opt/source/bb.org-overlays
5 ./dtc-overlay.sh
7 ./install.sh
9 sudo sh -c "echo 'BB-ADC' > /sys/devices/platform/bone-capemgr/slots"
```

- Reboot.
- For readout the ADC input Pins from python: <https://learn.adafruit.com/setting-up-io-python-library-on-beaglebone-black/adc>

5.5 Autorun

In order to autorun this script after booting the BBB use crontab like this:

```
1 root@beaglebone:~# crontab -e -u root
```

adding the following lines to the cron boot jobs:

```
1 @reboot config-pin P9_28 pwm
2 @reboot python /home/debian/Git/GeckoBot/Code/server_hardware_controlled.py &
```

NOTE: Dont forget the & at the end. Otherwise it will block the console. And you wont be able to ssh into it. But with the & it will run as background process and will be able to ssh into the BBB.

Ending Background Processes

Since the python script will run in the background, we need to find it and end it manually. Enter this to find the processing running off the file we wrote earlier.

```
1 ps aux | grep home/debian/GeckoBot/Code/server_hardware_controlled.py
```

You will get something like this:

```
1 root      873      0.1      0.6      7260      3264      ?        S    22:19      0:01 python home/debian/
    GeckoBot/Code/server_hardware_controlled.py
```

The number 873 is the process ID. Then, just use the process ID and kill the process.

```
1 root@beaglebone:~# kill 873
```

Ref: <https://billwaa.wordpress.com/2014/10/03/beaglebone-black-launch-python-script-at-boot-like-arduino-sketch/>

Okay, cron gives error: try with daemontools - Ref: <http://samliu.github.io/2017/01/10/daemontools-cheatsheet.html>

– This is super weird! starting the script every time a error occurs again.

To see what happens in crontab, create a Crontab Logger:

```
1 crontab -e:
2 @reboot /home/debian/Git/GeckoBot/boot_autorun_test/ssh.hack.sh 2>&1 |
3 /home/debian/Git/GeckoBot/boot_autorun_test/timestamp.sh >>>
4 /home/debian/Git/GeckoBot/boot_autorun_test/log/cronlog.log
```

ssh Hack: For some reason the BBIO.PWM module needs a terminal (tty) to initialize. A Job, started by crontab does not have a tty. There is simply no tty. Therefore we ssh into the device from the device itself. So we create a virtual tty. To do so run the ssh_hack.sh script. it will automatically run the start script. But you must enable a ssh-login as root without password. 2 Steps:

1. disable root pw (to clear the password):

```
1 passwd -d root
```

editing

```
1 nano /etc/pam.d/common-auth
```

Find the pam_unix.so line and add nullok to the end if its not there or change nullok_secure to be just nullok if yours says nullok_secure.

2. allow ssh to root login without password: Ref: <https://askubuntu.com/questions/115151/how-to-set-up-passwordless-ssh-access-for-root-user>

Basically, we have to create a public key for root and copy it to the BBB itself. Just follow the instructions on Ref above. But dont set PasswordAuthentication to no! Since than nobody can login with a password anymore, only with a public key. Which is not yet created anywhere else except on the BBB itself.

```
1 nano /etc/ssh/sshd_config
2 PermitRootLogin without-password
```

3. restart ssh service:

```
1 service ssh restart
```

4. disable requiretty for root:

```
1 visudo
```

and add Defaults: root !requiretty

5. spawn a shell:

Ref: <https://netsec.ws/?p=337>

Error: stdin is no tty: <https://michaelseiler.net/2013/04/25/cron-jobs-and-ssh-errors-tty-and-sudo/>

<https://sachinpradeeplinux.wordpress.com/2012/09/28/stdin-is-not-a-tty-error/>

On the destination server, edit /root/.bashrc file and comment out the mesg y line.

If it is no there, please add the following line to .bashrc file .

```
1 if 'tty -s'; then
2     mesg n
3 fi
```

5.6 Disable Webserver on BBB

Webserver

```
1 root@BBB: systemctl stop apache2.service
2 root@BBB: systemctl disable apache2.service
```

NodeJS:

```
1 root@BBB: systemctl stop bonescript-autorun.service
2 root@BBB: systemctl disable bonescript-autorun.service
```

References

[1] Festo. *Proportional-Wegeventile MPYE*, 2017. Datasheet.

[2] Honeywell. *TruStability Board Mount Pressure Sensors – SSC Series*, 2017. Datasheet.

[3] ON Semiconductor. *IRF540 TMOS E-FET*, 2006. Datasheet.