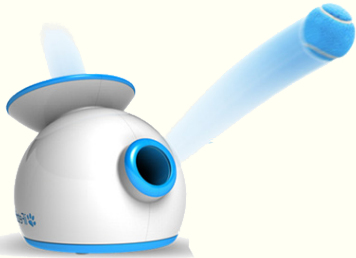
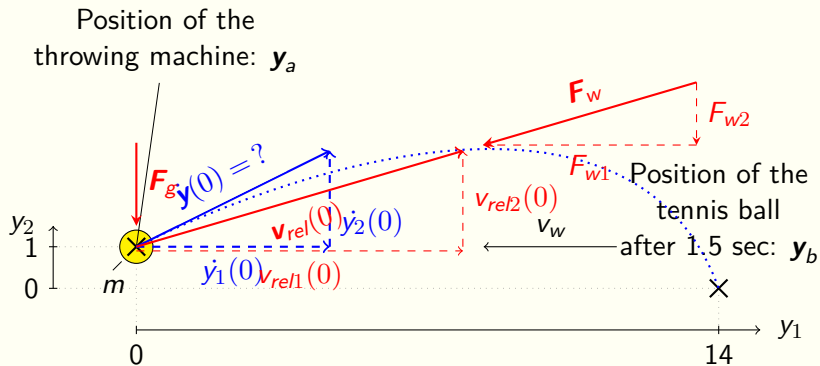


Simulation of a tennis ball throwing machine

A competition announced by the E-10 Simulation GmbH

by Lars Schiller





- ❖ We are looking for $\boldsymbol{\eta} := [\dot{y}_1(0) \ \dot{y}_2(0)]^T$, the dropping velocity of the ball.

By defining $y_3 = \dot{y}_1$, $y_4 = \dot{y}_2$ and the state vector $\mathbf{y} = [y_1 \ y_2 \ y_3 \ y_4]^T$ we can set up a system of 1st order (non linear) differential equations:

$$\dot{\mathbf{y}} := f(\mathbf{y}) = \begin{bmatrix} y_3 \\ y_4 \\ -\frac{k}{m}|v_{rel}|(y_3 - v_w) \\ -\frac{k}{m}|v_{rel}|y_4 - g \end{bmatrix}, \quad (1)$$

with $|v_{rel}| = \sqrt{(\dot{y}_1 - v_w)^2 + \dot{y}_2^2}$.

Set up the Residual function:

$$F(\boldsymbol{\eta}) := \mathbf{y}_{\eta}(t_f) - \mathbf{y}_b = 0, \quad (2)$$

where $\mathbf{y}_{\eta}(t_f)$ is the solution of the initial value problem given in eq. 1 with the initial condition $\mathbf{y}_0 = [\mathbf{y}_a \ \boldsymbol{\eta}]^T$ evaluated at $t = 1.5$.

- ❖ We need a method to find the zero of the residual function F given in eq. 2:
- ❖ The *Newton*-method
 - ❖ calculates the Jacobian of F in each iteration step,
 - ❖ needs $n + 1$ evaluations of F per step.
- ❖ The *Broyden*-method
 - ❖ gets along with an approximation of the Jacobian,
 - ❖ needs only 1 evaluation of F per step.
- ❖ For more detailed information look up in the technical report.

- ❖ *Newton* converges a bit faster,
- ❖ *Broyden* needs less function evaluations and computational time.
- ❖ Therefore its reasonable to prefer the *Broyden*-method.

method	iteration steps	total evals of f	comp. time [sec]
<i>Newton</i>	3	1010	0.0444
<i>Broyden</i>	4	509	0.0238

