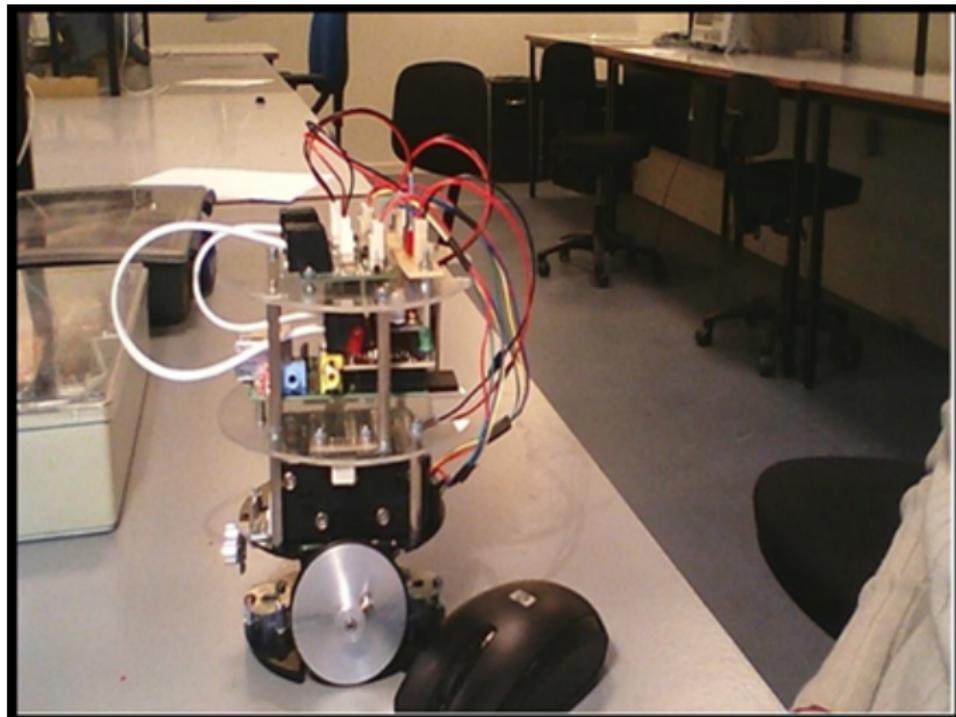


Rover



In this project i was part of a group that built a robot that is able to map a maze and calculate the shortest path between points in the maze using the Dijkstra algorithm. i was responsible for the auto-correction algorithm and the ultra sonic sensors.

Adden on 28/05/2017 - 15:44

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