

Assignment 1: Interpolation Methods

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Abstract

The following sections give answers to Assignment 1 in the UiO course MAT4110: Introduction to Numerical Analysis. The codes producing the results discussed in Problem 1 and Problem 3, are available at <https://github.com/lasse-steinnes/MAT4110/tree/master/Assignment1>.

Problem 1

Let $f(x) = e^x$ for $x \in [0, 1]$. Want to find the approximation in \mathbb{P}_1 w.r.t. the L2-norm

$$\|g\|_{L^2} = \left(\int_0^1 |g(x)|^2 dx \right)^{\frac{1}{2}}. \quad (1)$$

Hence, want to minimize

$$E = \langle f - p, f - p \rangle = \|f - p\|_{L^2}^2 = \left(\int_0^1 |f - p|^2 dx \right)^{\frac{1}{2}}, \quad (2)$$

so that

$$E = \|f\|^2 - \sum_{i=0}^1 (2c_i \langle f, p_i \rangle + c_i^2 \langle p_i, p_i \rangle) \quad (3)$$

Choose basis $\mathbb{P}_1 = \{1, x - 1/2\}$ to be used in the interpolation. \mathbb{P}_1 has a monic and orthogonal basis, since the inner product $\langle p_0, p_1 \rangle = 0$. To minimize eq. 1 one has to find the coefficients c_i so that

$$\frac{\delta E}{\delta c_i} = -2 \langle p_i, f \rangle + 2c_i \langle p_i, p_i \rangle = 0, \quad (4)$$

or by rewriting

$$c_i = \frac{\langle p_i, f \rangle}{\langle p_i, p_i \rangle}. \quad (5)$$

For $i = 0$ one gets

$$\langle p_0, f \rangle = \int_0^1 e^x dx = [e^x]_0^1 = e - 1, \quad (6)$$

and since $\langle p_0, p_0 \rangle = 1$,

$$c_0 = e - 1. \quad (7)$$

For $i = 1$,

$$\langle p_i, f \rangle = \int_0^1 \left(x - \frac{1}{2}\right) e^x dx. \quad (8)$$

Using integration by parts yields

$$\langle p_i, f \rangle = [xe^x]_0^1 - \int_0^1 e^x dx - \int_0^1 \frac{1}{2} e^x dx \quad (9)$$

$$= e - (e - 1) - \frac{1}{2}(e - 1) = \frac{3 - e}{2}, \quad (10)$$

and

$$\langle p_1, p_1 \rangle = \int_0^1 \left(x - \frac{1}{2}\right)^2 dx = \int_0^1 x^2 - x + \frac{1}{4} dx \quad (11)$$

$$= \left[\frac{1}{3}x^3 - \frac{x^2}{2} + \frac{x}{4} \right]_0^1 = \frac{1}{12}. \quad (12)$$

All together

$$c_1 = \frac{12}{2}(3 - e) = 6(3 - e). \quad (13)$$

$$p = c_0 p_0 + c_1 p_1 = (e - 1) + 6(e - 3)\left(x - \frac{1}{2}\right) \quad (14)$$

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The interpolation p gives the least squares best approximation of f (Fig. 1).

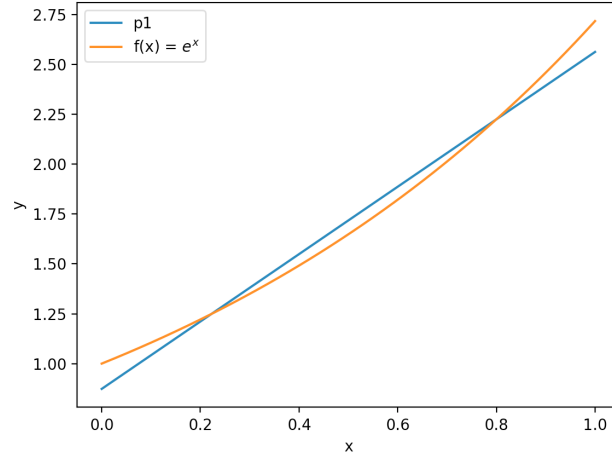


Figure 1: **Least squares best approximation of $f(x) = e^x$:** The $\mathbb{P}_1 = \{1, x - 1/2\}$ approximation and the analytical function is plotted as a function of x .

Problem 2

When $f \in C^{n+1}([a, b])$ and \mathbb{P}_n interpolates f in $x_0, \dots, x_n \in [a, b]$, then

$$|f - p|_{C([a, b])} \leq \prod_{k=0}^n \frac{|x - x_k|}{(n+1)!} \|f^{(n+1)}\|_{C([a, b])} \quad (15)$$

a)

A maximum estimate of the error (eq. 15) is

$$|f - p|_{C([a, b])} \leq \|f - p\|_{C([a, b])} = \sup_{x \in [a, b]} |f - p|. \quad (16)$$

Since $x \in [a, b]$, then $|x - x_k| \leq (b - a)$,

$$\|f - p\|_{C([a, b])} \leq \frac{(b - a)^{n+1}}{(n+1)!} \|f^{(n+1)}\|_{C([a, b])}. \quad (17)$$

b)

If $[a, b] = [-1, 1]$ and the interpolating points are the Chebycheff points on $[a, b]$, then

$$\sup_{x \in [-1,1]} \prod_{k=0}^n |x - x_k| = 2^{-n}. \quad (18)$$

On a general interval $[a,b]$, to use the Chebycheff points, let $y \in [a,b]$ and $x \in [-1,1]$ so that

$$g(y) = f(a_0 + a_1 x). \quad (19)$$

Want to determine a_0 and a_1 . Knows that $x = -1 \rightarrow y = a$, and $x = 1 \rightarrow y = b$. Which gives the set of equations

$$\begin{aligned} a &= a_0 + a_1 \cdot (-1), \\ b &= a_0 + a_1 \cdot 1, \\ \Rightarrow a_0 &= \frac{a+b}{2}, \\ \Rightarrow a_1 &= \frac{b-a}{2}. \end{aligned} \quad (20)$$

It follows that

$$y = \frac{a+b}{2} + \frac{b-a}{2}x. \quad (21)$$

Thus using eq. 15 with the Chebycheff points for interpolation

$$\|f - p\|_{C([a,b])} \leq \prod_{k=0}^n \frac{1}{2^n(n+1)!} \|g^{(n+1)}\|_{C([a,b])}. \quad (22)$$

Need to use chain rule $(f \circ y)' = (f' \circ y) \cdot y'$, so that

$$\|f - p\|_{C([a,b])} \leq \prod_{k=0}^n \frac{(b-a)^{n+1}}{2^{2n+1}(n+1)!} \|f^{(n+1)}\|_{C([a,b])}. \quad (23)$$

Problem 3

Spline interpolation is an alternative to high order polynomial interpolation. Fix an interval $x \in [a,b]$ and consider the uniform mesh $x_i = a + ih, i = 0, 1, \dots, N$, where $h = (b-a)/N$. In the following problems consider the space of splines

$$S_k^0 = \{s \in C^0([a,b]) : s|_{(x_{i-1}, x_i)} \in \mathbb{P}_k \forall i = 1, 2, \dots, N\} \quad (24)$$

a)

Let $f \in C([a, b])$ and $s \in S_k^0$ the function which in each subinterval $[x_{i-1}, x_i]$ interpolates f at points

$$x_j = x_{i-1} + \frac{j}{k}h, \quad j = 0, 1, \dots, k. \quad (25)$$

Since s should be equal to f at these $k+1$ points, this raises $k+1$ conditions on s . For a polynomial of degree k , there are $k+1$ degrees of freedom (d.o.f.) to determine. Thus for each d.o.f, there is one condition, and each polynomial $s \in \mathbb{P}_k$ is uniquely determined on $[x_{i-1}, x_i]$, according to the uniqueness of polynomial interpolation (lemma 3.1 in [1]).

b)

Assume $f \in C^{k+1}([a, b])$ and $x \in [x_{i-1}, x_i]$. Let $s = \Pi_k^N f$. Thus f is in the space of $k+1$ continuously derivative functions, so that

$$|f(x) - \Pi_k^N f(x)| = \frac{\prod_{j=0}^k |x - x_j|}{(k+1)!} \left| f^{(k+1)} \right|_{C([x_{i-1}, x_i])}. \quad (26)$$

Since $x - x_j \leq h$ and $|f^{(k+1)}| \leq \|f^{(k+1)}\|$, then

$$|f(x) - \Pi_k^N f(x)| \leq \frac{h^{k+1}}{(k+1)!} \|f^{(k+1)}\|_{C([x_{i-1}, x_i])} \quad (27)$$

c)

Inserting for $h = (b - a)/N$ in eq. 27, gives an upper error estimate on the interval $x \in [a, b]$,

$$|f(x) - \Pi_k^N f(x)| \leq \|f(x) - \Pi_k^N f(x)\|_{C([a, b])} \leq \frac{(b - a)^{k+1}}{N^{k+1} (k+1)!} \|f^{(k+1)}\|_{C([a, b])} \quad (28)$$

d)

The computational cost $c = k + 1 + (N - 1)k = Nk + 1$ is the number of evaluations of f required to find s . Want to find the values of N, k for a fixed c that minimize eq. 28 for

$$(i) \quad \sin(x), \quad x \in [-\pi, \pi] \quad (29)$$

and

$$(ii) \quad \frac{1}{1+25x^2}, \quad x \in [-1, 1]. \quad (30)$$

For (i) $|f^{(k+1)}|_{C([- \pi, \pi])} = 1$ and $b - a = 2\pi$, thus

$$\|f(x) - \Pi_k^N\| \leq \frac{(2\pi)^{k+1}}{N^{k+1}(k+1)!} \approx \left[\frac{2\pi e}{N(k+1)} \right]^{k+1} (k+1)^{1/2} = \left[\frac{2\pi k e}{(c-1)(k+1)} \right]^{k+1} (k+1)^{1/2}. \quad (31)$$

In the last two equalities, $N = (c-1)/k$ and Stirling's approximation were used. Stirling's approximation says that $(k+1)! \approx (k+1)^{(k+1)+1/2} e^{-(k+1)}$.

In the case of Runge's equation (ii), then $|f^{(k+1)}|_{C([-1,1])} = 5^{k+1}(k+1)!$ and $b - a = 2$. It follows that

$$\|f(x) - \Pi_k^N\| \leq \frac{2^{k+1}}{N^{k+1}(k+1)!} 5^{k+1}(k+1)! = \left[\frac{10}{N} \right]^{k+1} = \left[\frac{10k}{c-1} \right]^{k+1}. \quad (32)$$

In the last equality, $N = (c-1)/k$ was inserted into the equation. Thus, for a fixed computational cost c , the upper error estimates only depends on k .

For $c \rightarrow \infty$ (asymptotic behaviour) it is clear that the error for $\sin(x)$ decrease for all k (Fig. 2). A requirement for a decreasing error for $\sin(x)$ (eq. 31) is $N(k+1) > 2\pi e$ since $(k+1)^{1/2}$ increase slowly. However with Runge's function, the error increases for $k > 10$ (Fig. 2). From eq. 32 a requirement for the error to decrease with increasing k is $N > 10$.

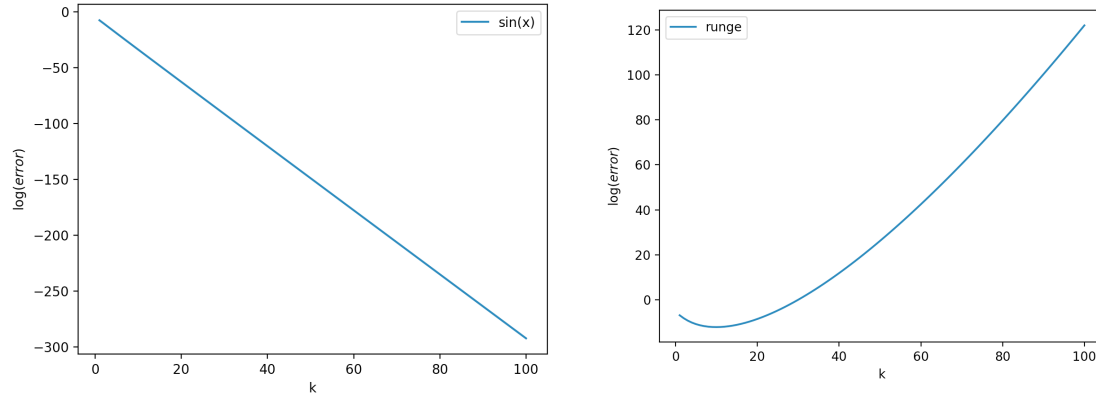


Figure 2: **Error estimates of spline interpolation. Left: $\sin(x)$ Right: Runge's function.** See eq. 31 and eq. 32 for error estimates. Plotted with $c = 300$ (asymptotic behaviour).

e)

The function `piecewisepol(f, a, b, N, k)` interpolates the function f on the interval $x \in [a, b]$, divided into N sub-intervals with splines of degree k and smoothness 0 (Fig 3 and 4).

For $\sin x$ a low number of sub-intervals N ($N = 1$), and high k ($k = 8$) better describes the oscillatory behaviour of this function, rather than $(N, k) = (8, 1)$ (Fig. 3).

However, in the case of Runge's function, which has an increasing Lebesgue constant with k and a quickly growing k -th order derivative, $(N, k) = (8, 1)$ performs a lot better than $(N, k) = (1, 8)$. So a low order polynomial interpolating spline $s \in \mathbb{P}_k$ would be preferable for Runge with N large (optimally $N > 10$ as decribed above).

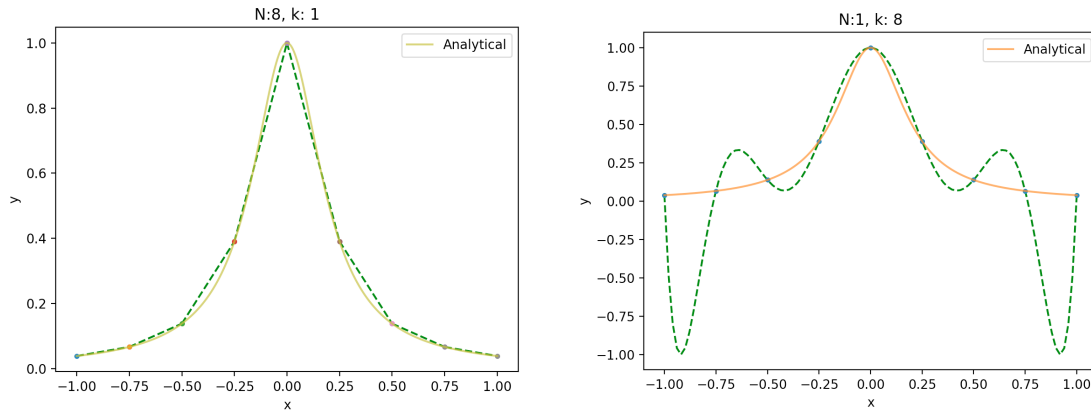


Figure 3: **Interpolation of Runge's function.** **Left:** Spline of degree 1 (k) for 8 sub-intervals (N). **Right:** Spline of degree 8 (k) for 1 sub-interval (N).

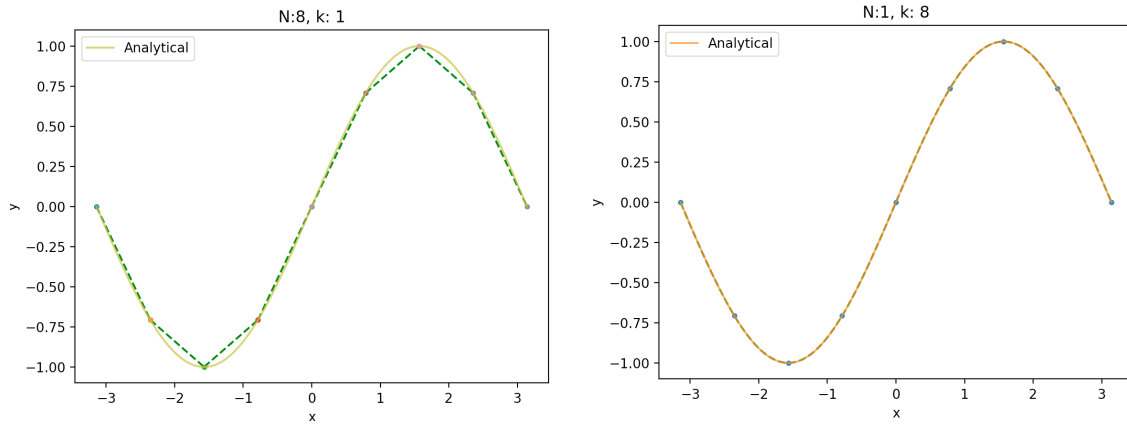


Figure 4: **Interpolation of $\sin x$.** **Left:** Spline of degree 1 (k) for 8 sub-intervals (N). **Right:** Spline of degree 8 (k) for 1 sub-interval (N).

References

- [1] A.C. Faul. *A Concise Introduction to Numerical Analysis*. CRC Press, 2016.

I Appendix

PS: The graphs became very nice with a better (N,k) fit (Fig. 5).

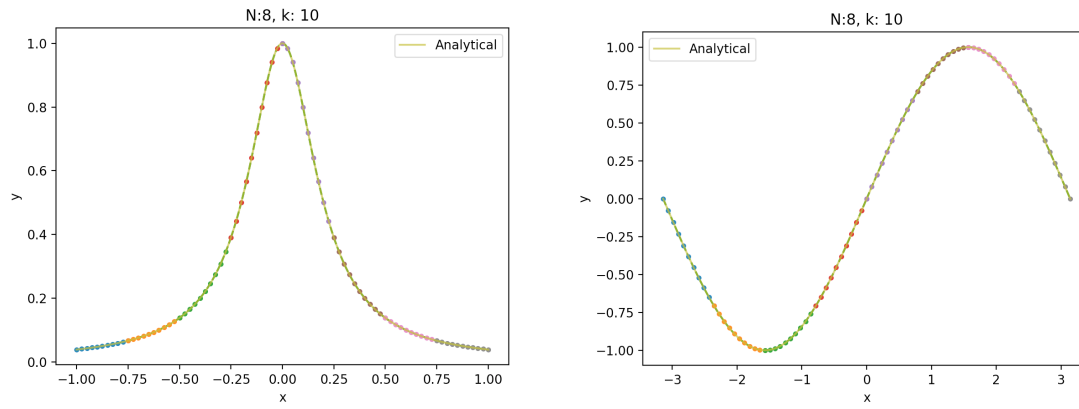


Figure 5: **Interpolation with better (N,k) fit.** **Left:** Runge with splines of degree 10 (k) for 8 sub-intervals (N). **Right:** $\sin x$ with splines of degree 10 (k) for 8 sub-interval (N).