

Lecture 15: PSPACE Completeness

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NB: These notes are from CIS511 at Penn. The course followed Michael Sipser's *Introduction to the Theory of Computation* (3ed) text.

The Class *PSPACE-Complete*

Definition 15.1 A language L is *PSPACE-Complete* if L is in *PSPACE* and for all $A \in \text{PSPACE}$, there exists a mapping reduction from A to L in polynomial time.

Definition 15.2 A **quantified boolean formula** is a formula of the form $\forall x_1 \exists x_2 \forall x_3 \dots \phi(x_1, x_2, \dots)$, where ϕ is a boolean formula over the x_i .

Claim 15.3 The language of True Quantified Boolean Formulas (TQBF) is *PSPACE-Complete*.

Proof:

We'll think of a machine that decides this language as taking a quantified boolean formula as input and accepting if it is true, rejecting if it is false.

This language is obviously in *PSPACE*, we can simply check each allowable assignment and accept if the formula is true.

To show that it is *PSPACE-Complete*, we need to show that every other *PSPACE* language can be reduced to it in polynomial time. Let L be a language in *PSPACE*. Without loss of generality, we can say that a decider for L takes $O(2^{n^k})$ time.

We saw in the Cook-Levin Theorem how to think of states of computation as boolean formulas, and we will do something similar here. Let C_{init} be the initial configuration and C_{accept} as the canonical accepting configuration. We write $\Phi(C_a, C_b, t)$ to denote the quantified boolean formula corresponding to 'there exists a sequence of computation steps of length at most t such that the machine moves from configuration C_a to C_b '. We want to find formula equivalent to $\Phi(C_{\text{init}}, C_{\text{accept}}, 2^{n^k})$ which is true if and only if the input x to the decider for L is in L .

We start by observing that if $x \in L$, then there must be some intermediate configuration C_m which the machine passes through in its computation. We can then write

$$\Phi(C_{\text{init}}, C_{\text{accept}}, 2^{n^k}) \iff \Phi(C_{\text{init}}, C_m, \frac{2^{n^k}}{2}) \wedge \Phi(C_m, C_{\text{accept}}, \frac{2^{n^k}}{2})$$

We can also consider quarter-way and eighth-way points, and so on and do the same thing, however, we get an exponentially large formula by the time we get down to step sizes of $t = 1$.

We get around this by introducing two new variables C_3, C_4 and universally quantifying them over our configuration pairs $(C_1, m), (m, C_2)$ such that we have

$$\Phi(C_1, C_2, t) = \exists m \forall (C_3, C_4) \in \{(C_1, m), (m, C_2)\} (\Phi(C_3, C_4, \frac{t}{2}))$$

We only need polynomial space for this, hence L is reducible to TQBF, and TQBF is PSPACE-Complete.

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Example: The language Generalized Geography (GG) is PSPACE-Complete. GG is a two player game on a directed graph. One player picks a node, then the other picks a node for which there exists an arc from the previous player's choice into that node. A player loses if there are no nodes for her to legally choose (i.e. the previous player picked a node with out degree zero). Player One's first choice is a designated start node. The language GG is the decision problem of whether, given a directed graph with a start node, Player One can always win given perfect play.

We can think of this as a TQBF in the following way: Player One has a winning strategy if there exists a node with out-degree zero such that for any previous choice made by Player Two there exists a previous choice by Player One, and so on.