

#### Distributed Systems and Al

Ray: Programming at Any Scale <a href="https://github.com/ray-project/ray">https://github.com/ray-project/ray</a>

**Robert Nishihara** 



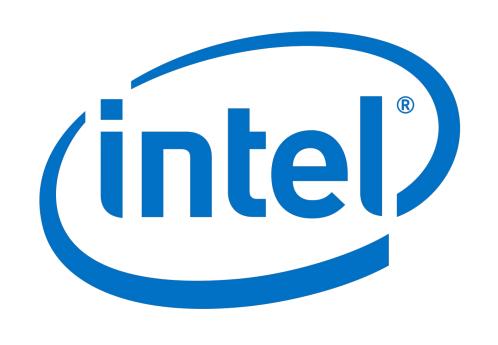
#### A Growing Number of Use Cases















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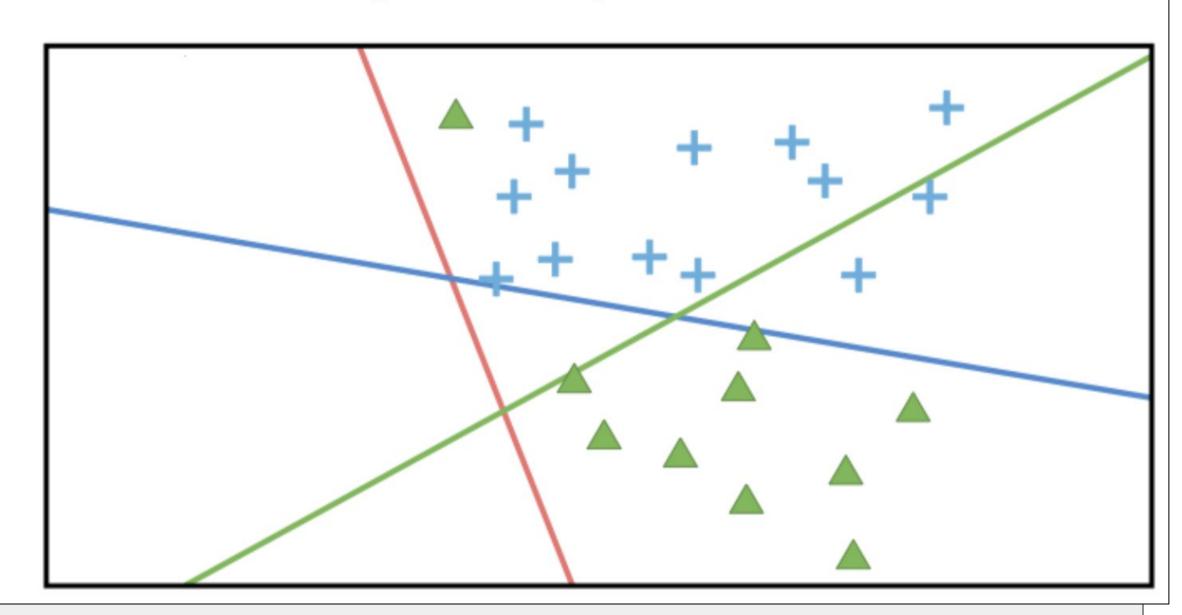


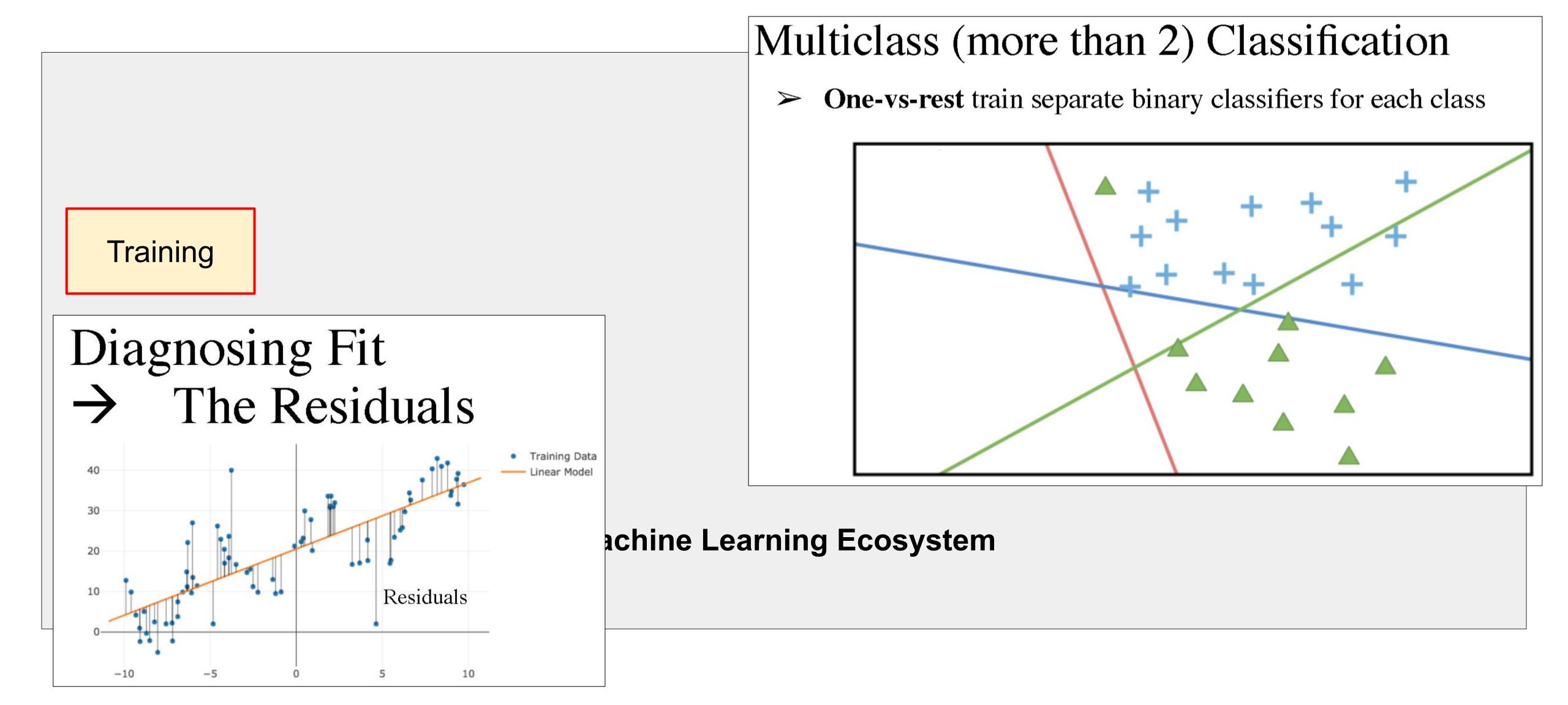
Training **Machine Learning Ecosystem** 

Training

#### Multiclass (more than 2) Classification

> One-vs-rest train separate binary classifiers for each class



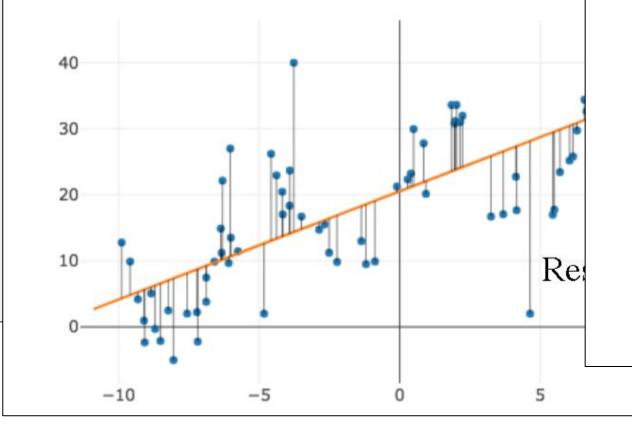


#### Multiclass (more than 2) Classification

> One-vs-rest train separate binary classifiers for each class

#### Training

# Diagnosing Fit The Residu



#### Stochastic Gradient Descent

> For many learning problems the gradient is a sum:

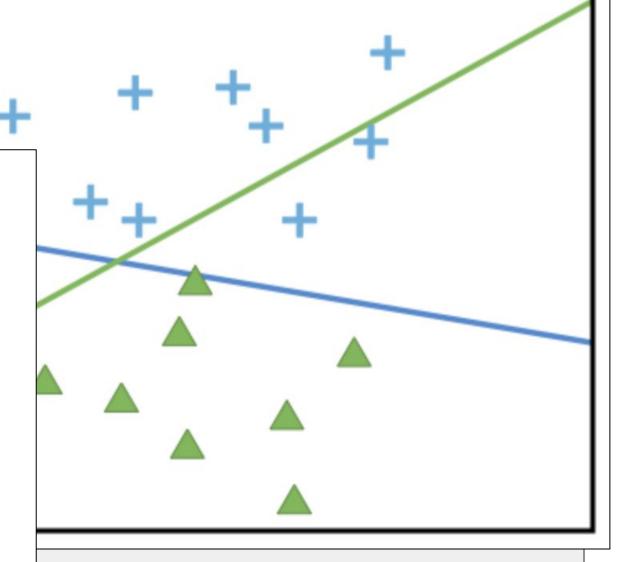
$$\nabla_{\theta} \mathbf{L}(\theta) = \frac{1}{n} \sum_{i=1}^{n} \left( \sigma \left( \phi(x_i)^T \theta \right) - y_i \right) \phi(x_i)$$

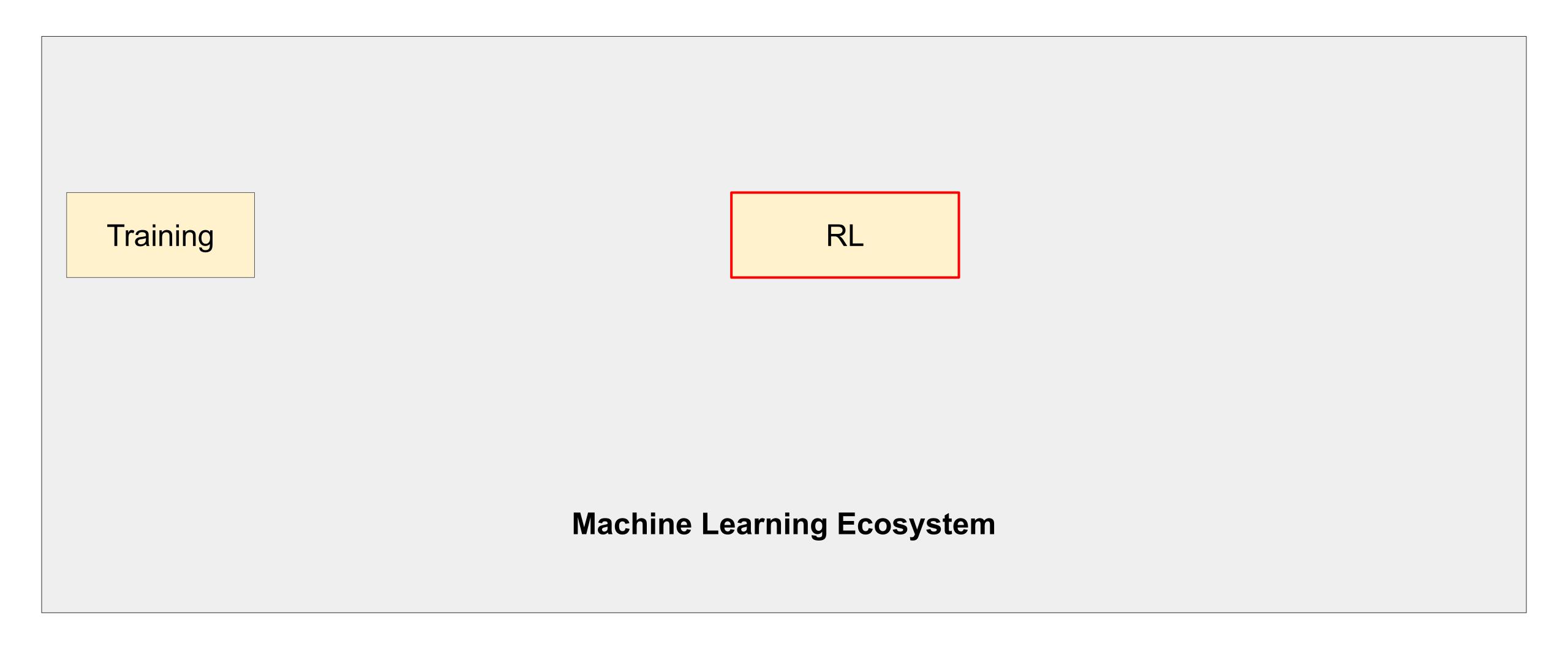
> For large n this can be costly

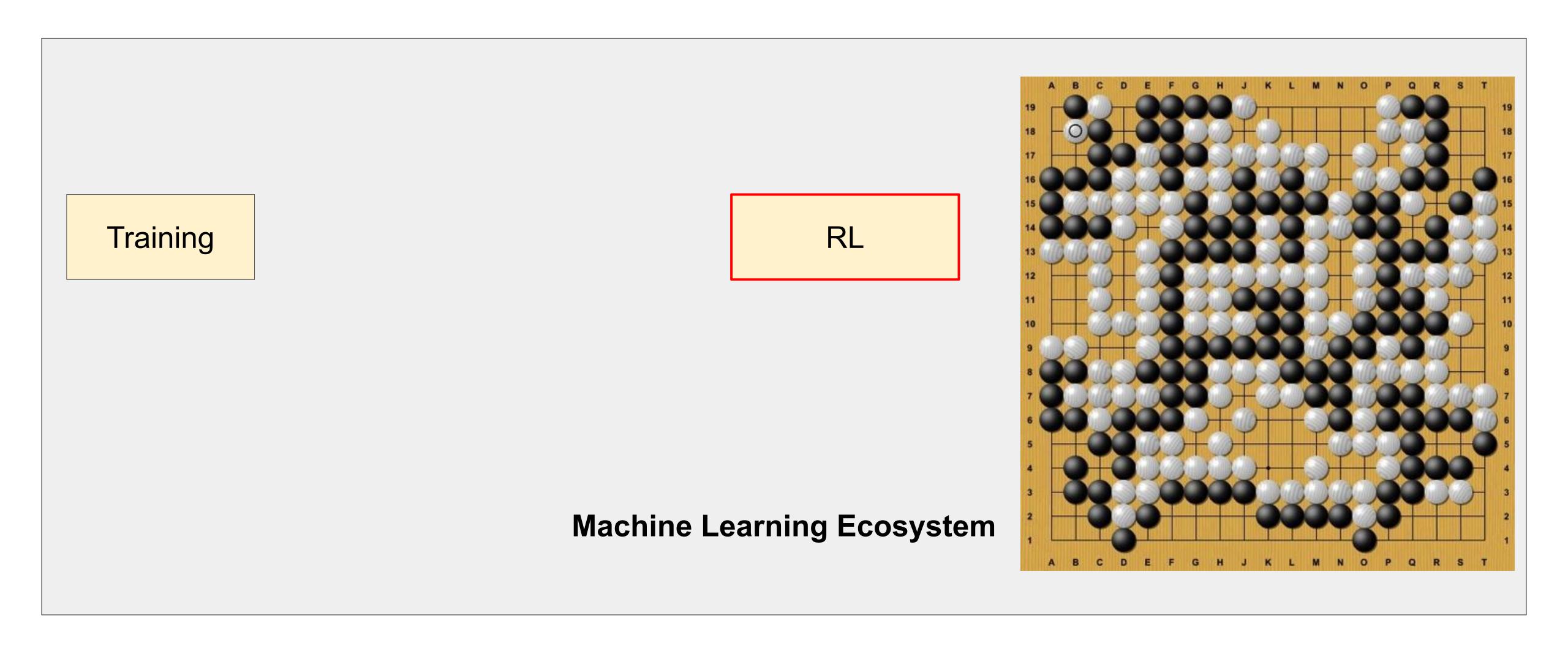
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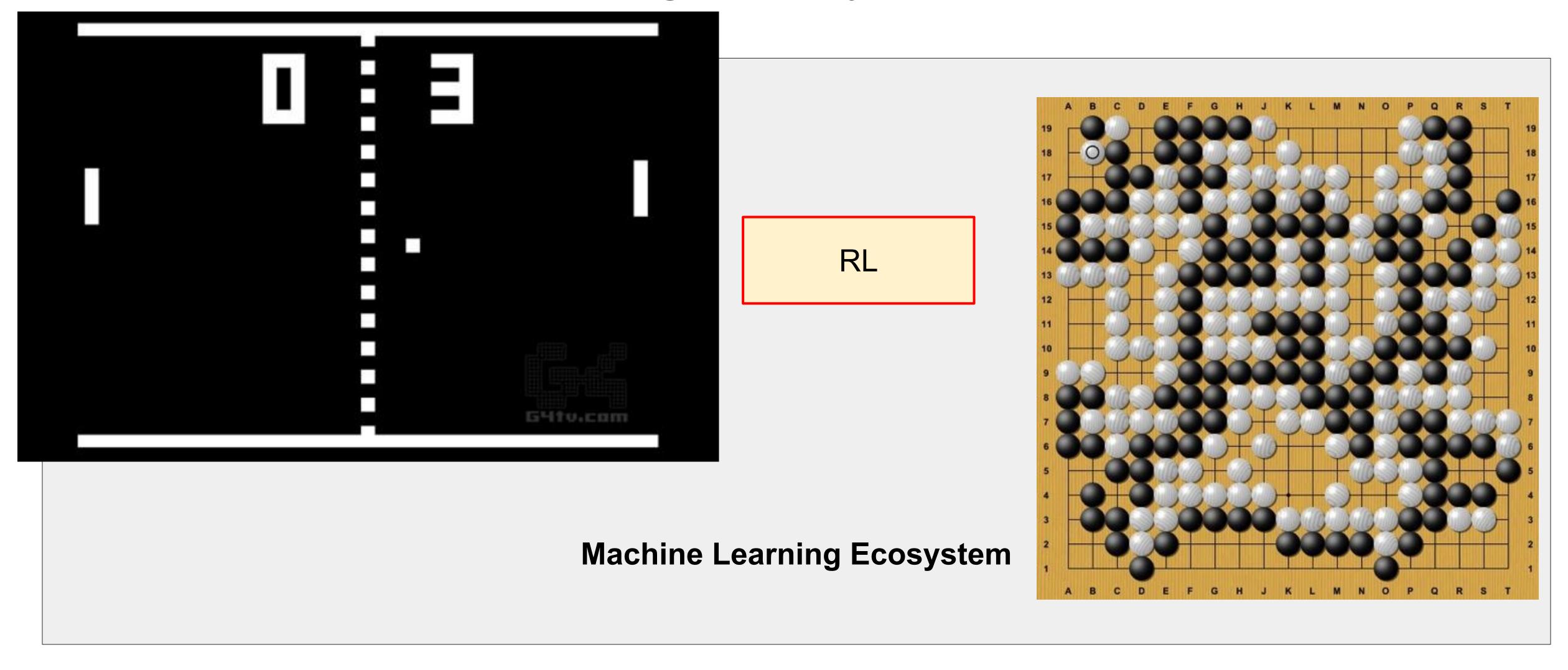
What if we approximated the gradient by looking at a few random points:

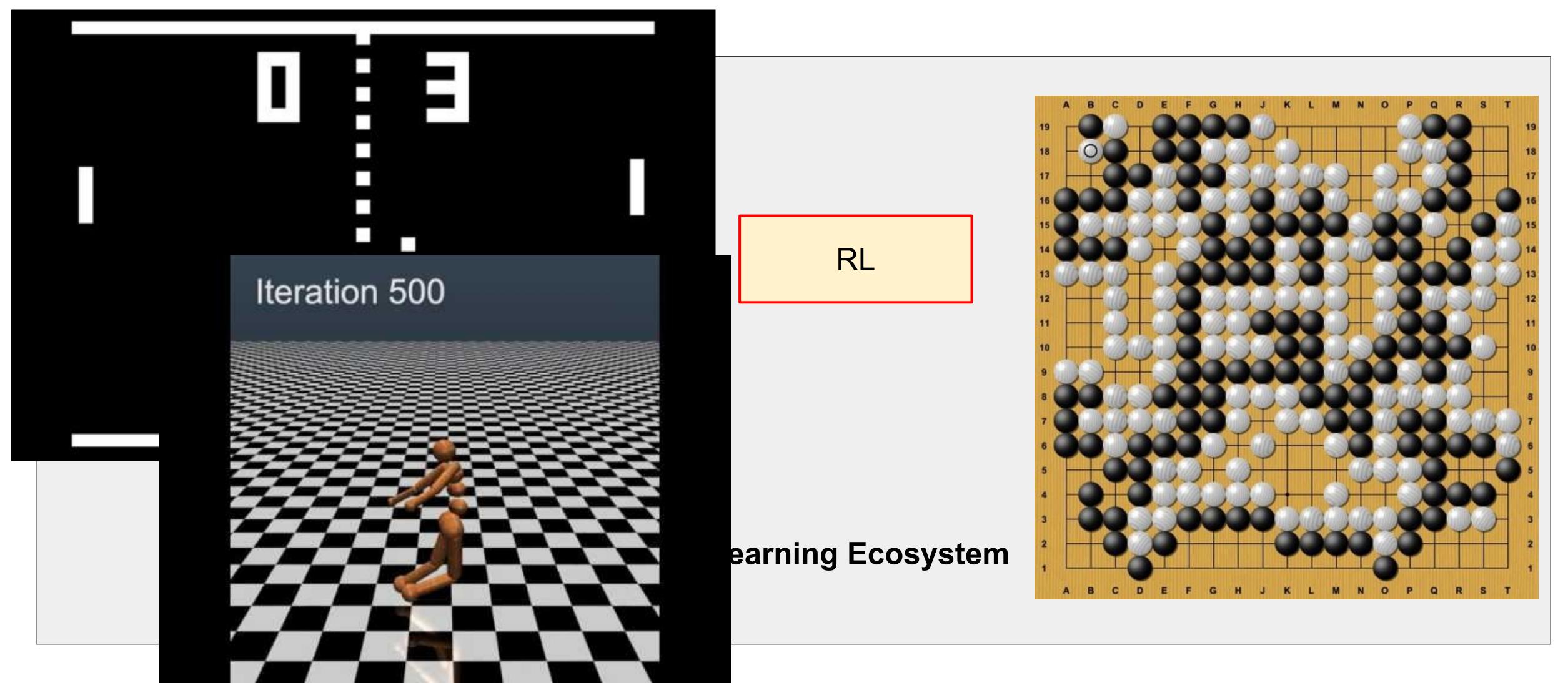
$$\nabla_{\theta} \mathbf{L}(\theta) \approx \frac{1}{|\mathcal{B}|} \sum_{i \in \mathcal{B}} \left( \sigma \left( \phi(x_i)^T \theta \right) - y_i \right) \phi(x_i)$$

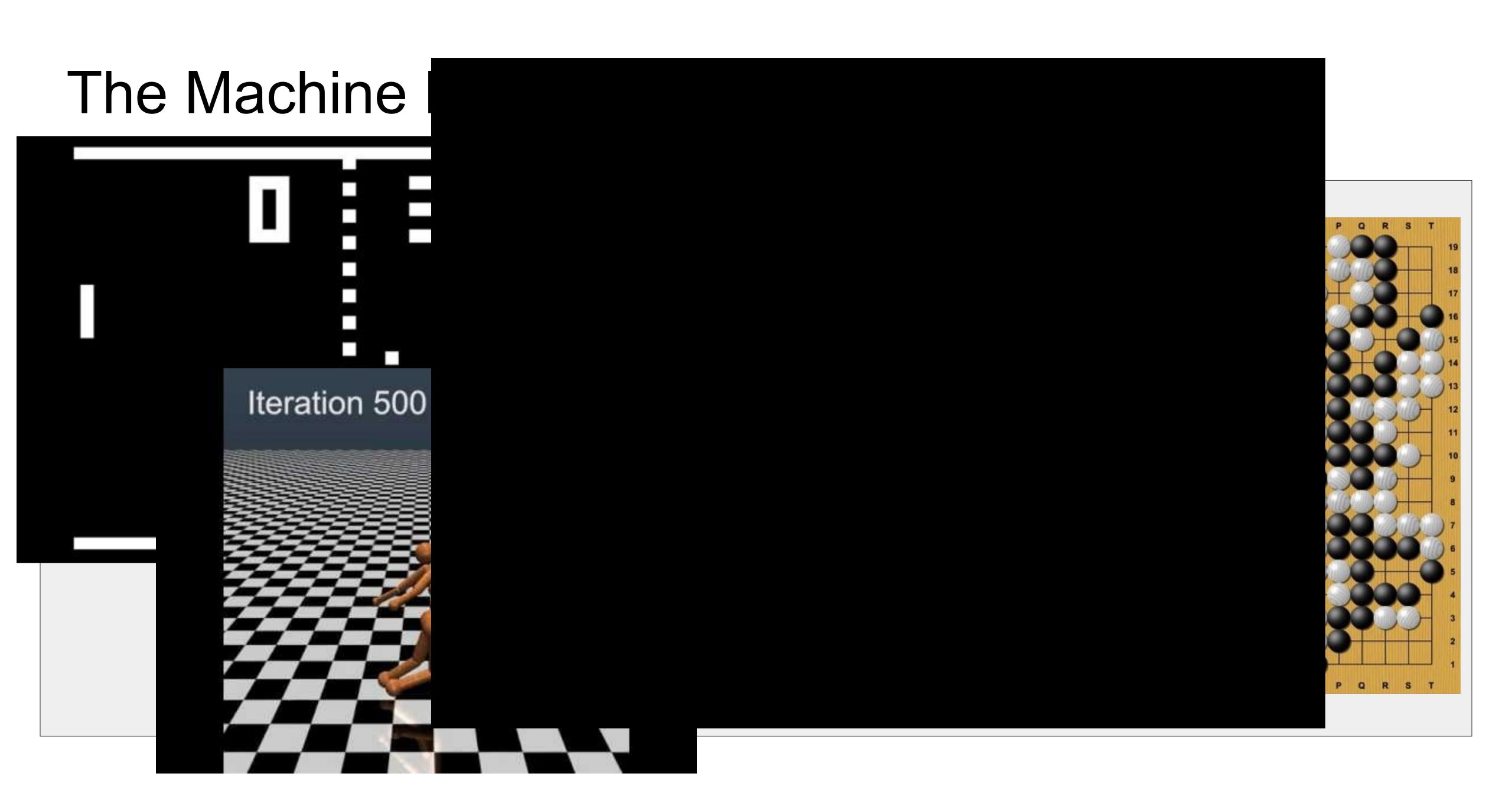


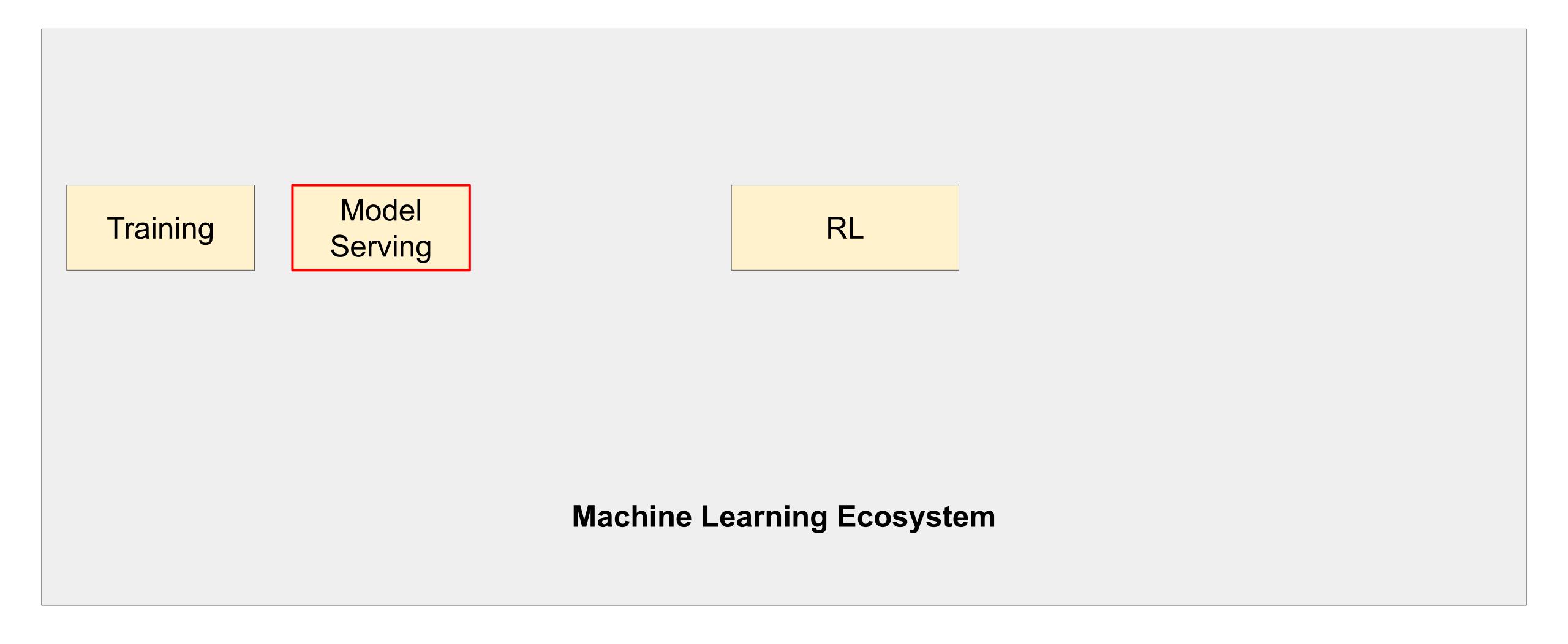


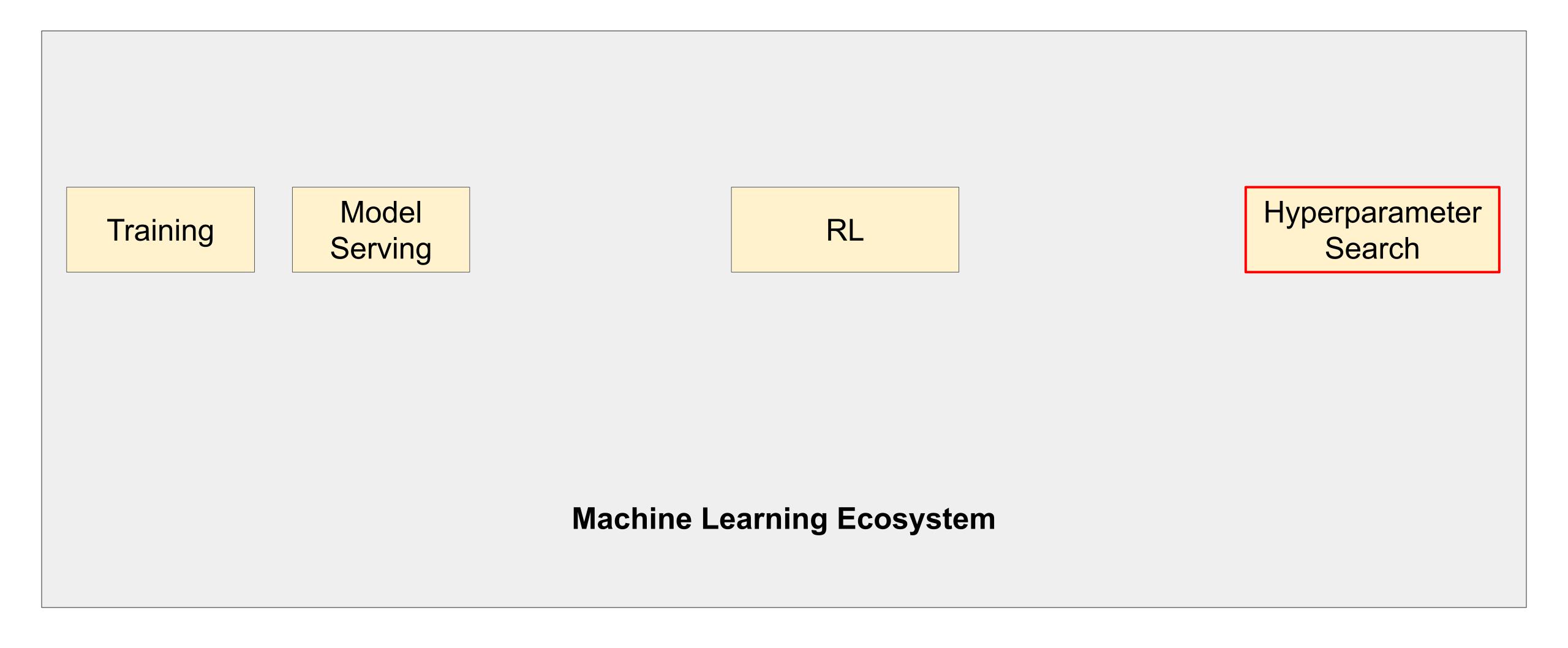


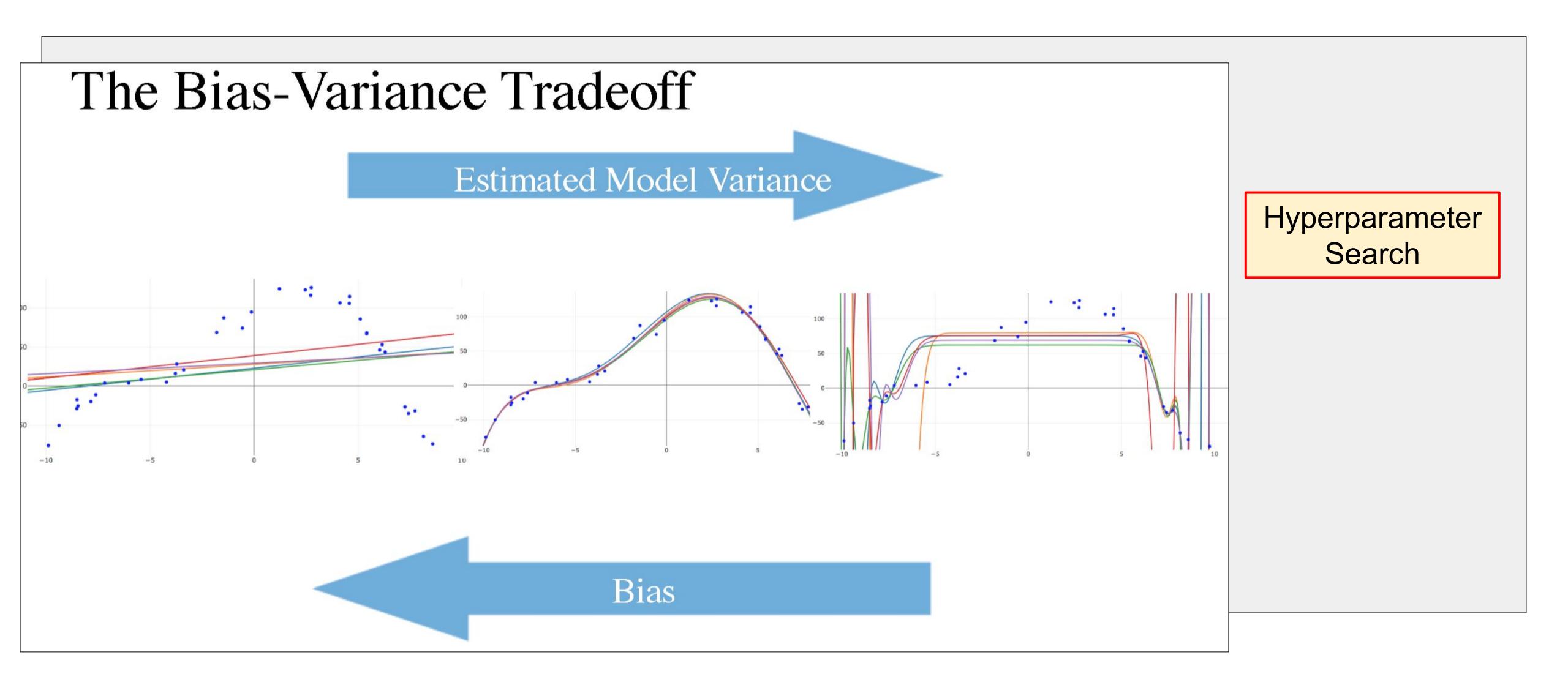


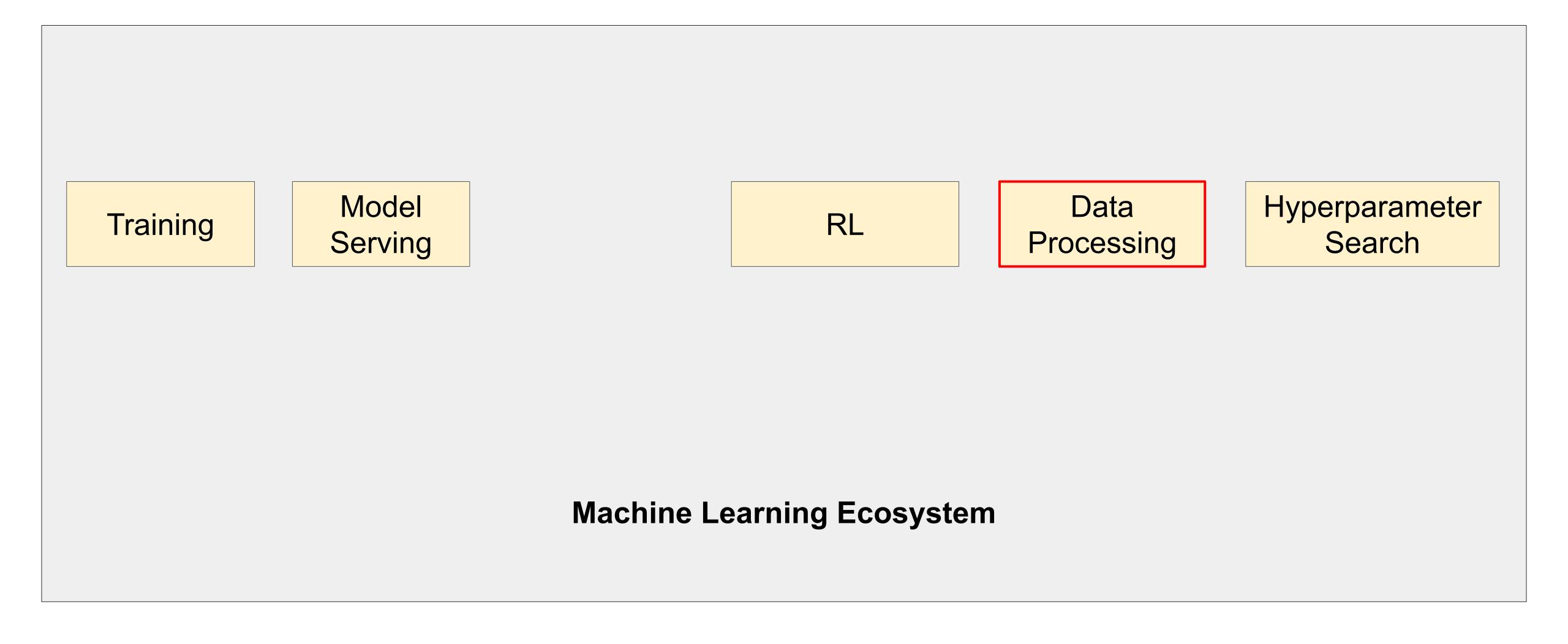


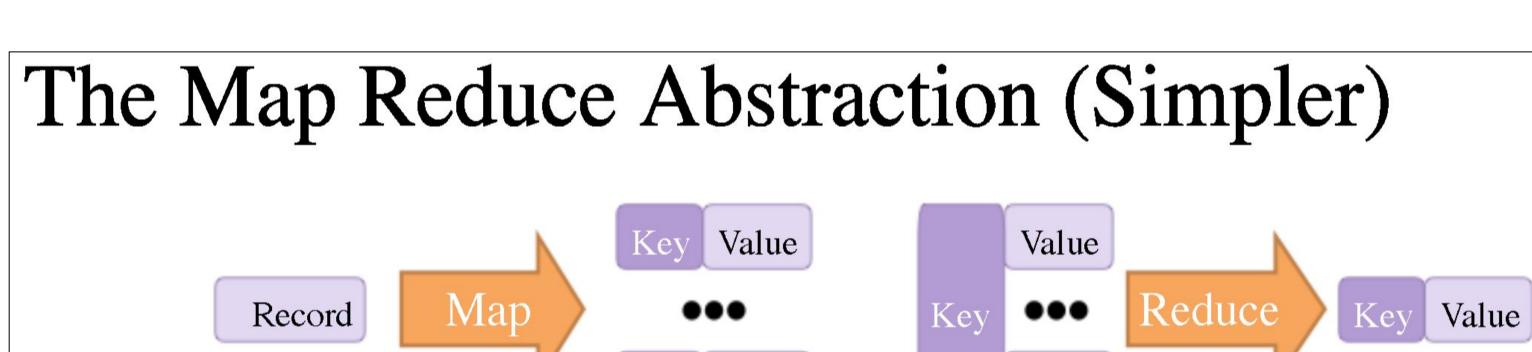










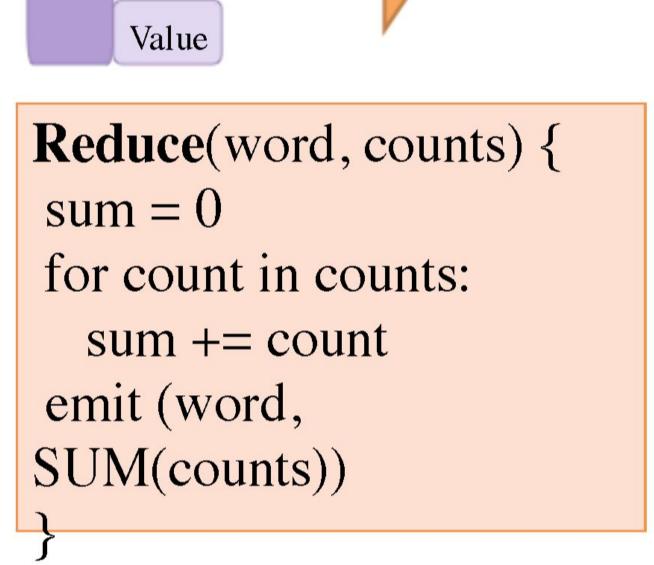


Value

Example: Word-Count

Map(book):
for (word in book):
emit (word, 1)

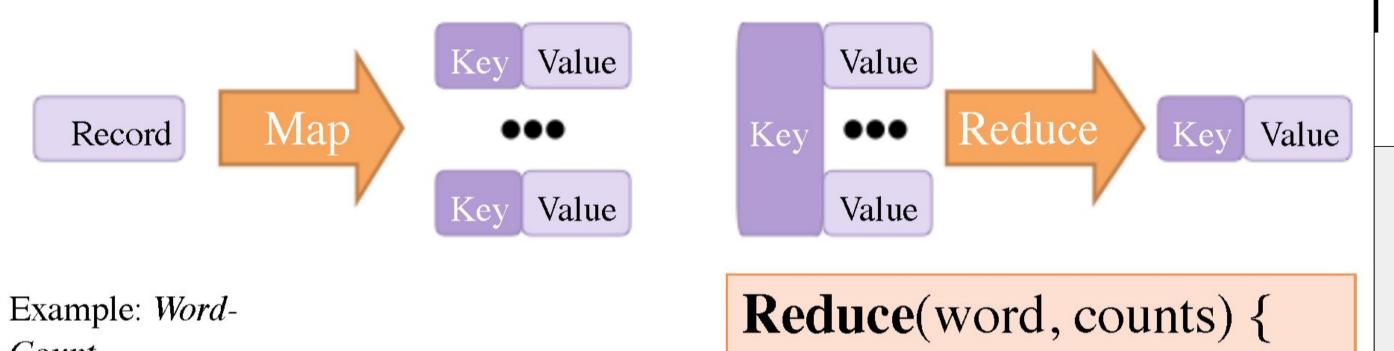
Key Value



Data Processing

Hyperparameter Search

#### The Map Reduce Abstraction (Simpler)

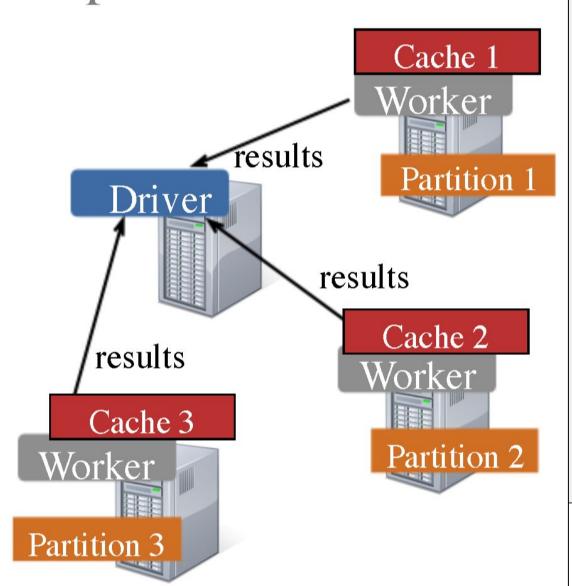


#### Example: Log Mining

Load error messages from a log into memory, then interactively search for various patterns

```
lines = spark.textFile("hdfs://file.txt")
errors = lines.filter(lambda s: s.startswith("ERROR"))
messages = errors.map(lambda s: s.split("\t")[2])
messages.cache()

messages.filter(lambda s: "mysql" in s).count()
messages.filter(lambda s: "php" in s).count()
```



Data Processing Hyperparameter Search

Hyperparameter Model Data Training Streaming RL Processing Serving Search **Machine Learning Ecosystem** 

Distributed System

Training

Distributed System

Model Serving Distributed System

Streaming

Distributed System

RL

Distributed System

Data Processing Distributed System

Hyperparameter Search

## Distributed System

Training

Horovod,
Distributed TF,
Parameter Server

### Distributed System

Model Serving

Clipper, TensorFlow Serving

### Distributed System

Streaming

Flink, many others

### Distributed System

RL

Baselines, RLlab, ELF, Coach, TensorForce, ChainerRL

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Data Processing

MapReduce, Hadoop, Spark

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Hyperparameter Search

Vizier, many internal systems at companies

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- More work (computation) than one machine can do in a reasonable amount of time.
- More data than can fit in one machine.

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Aspects of a distributed system

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#### Aspects of a distributed system

- Units of work "tasks" executed in parallel
- Scheduling (which tasks run on which machines and when)
- Data transfer
- Failure handling
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#### The Machine Learning Eco

#### Why is this a problem?

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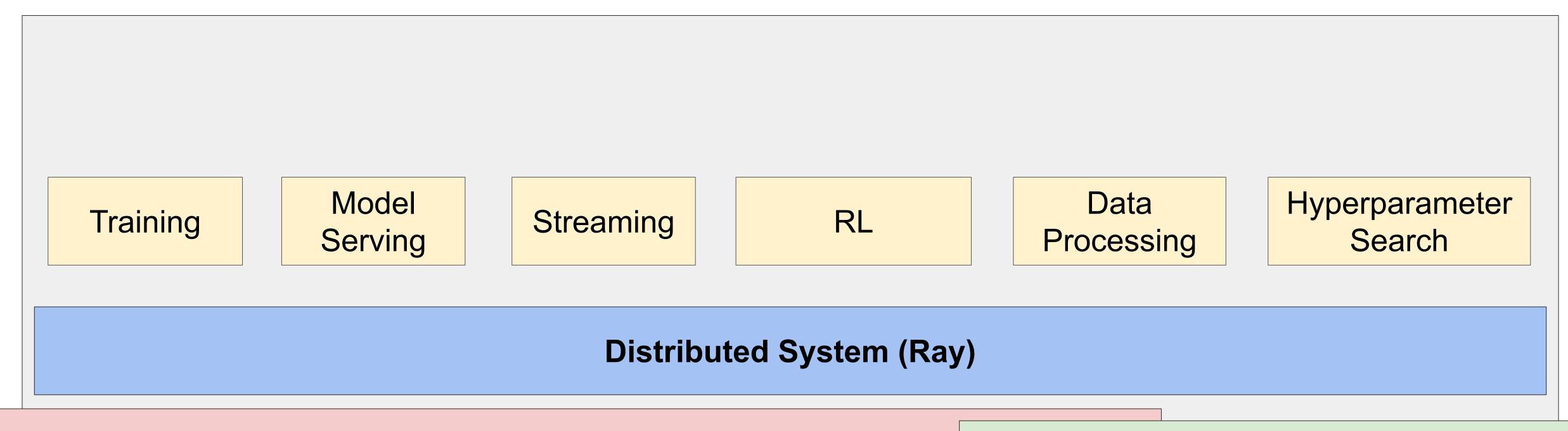
Training Model Serving Streaming RL Data Processing Hyperparameter Search

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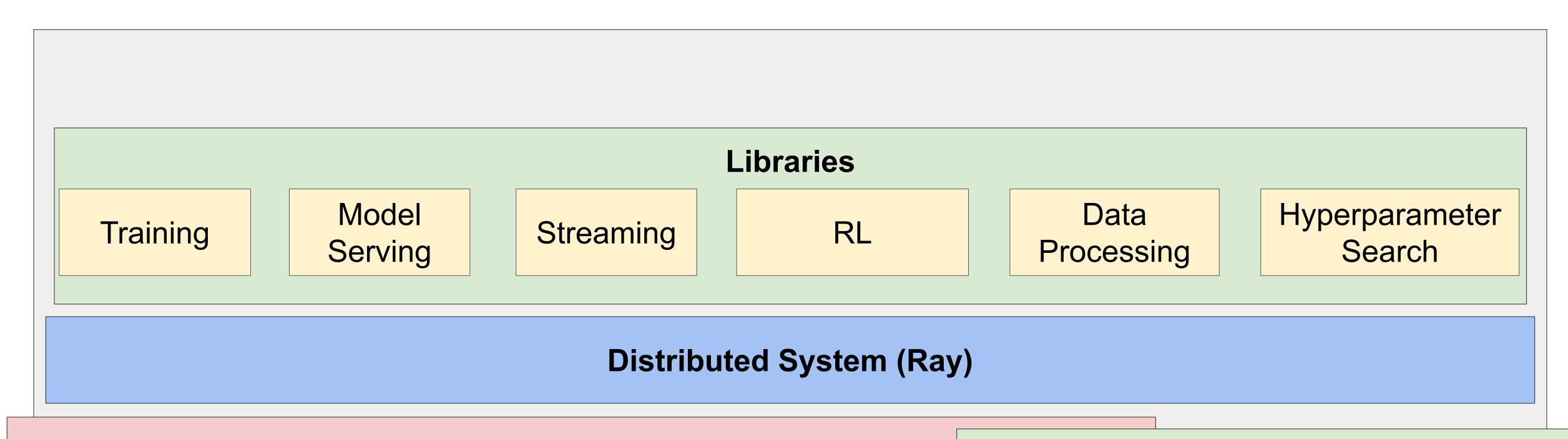


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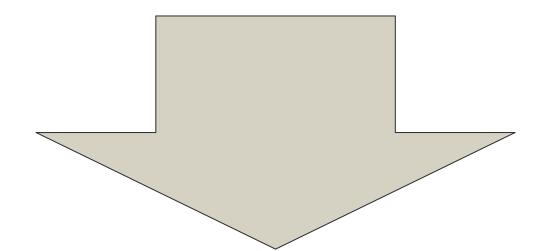
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Hyperparameter Search

Vizier, many internal systems at companies



#### Training

Model Serving

Streaming

#### Libraries

RL

Data Processing Hyperparameter Search

#### **Distributed System (Ray)**

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### Distributed System

Hyperparameter Search

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## This requires a very general underlying distributed system.

#### Training

Model Serving

Streaming

#### Libraries

RL

Data Processing Hyperparameter Search

#### **Distributed System (Ray)**

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### Distributed System

Hyperparameter Search

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This requires a very **general** underlying distributed system.

Generality comes from tasks (functions) and actors (classes).

Training

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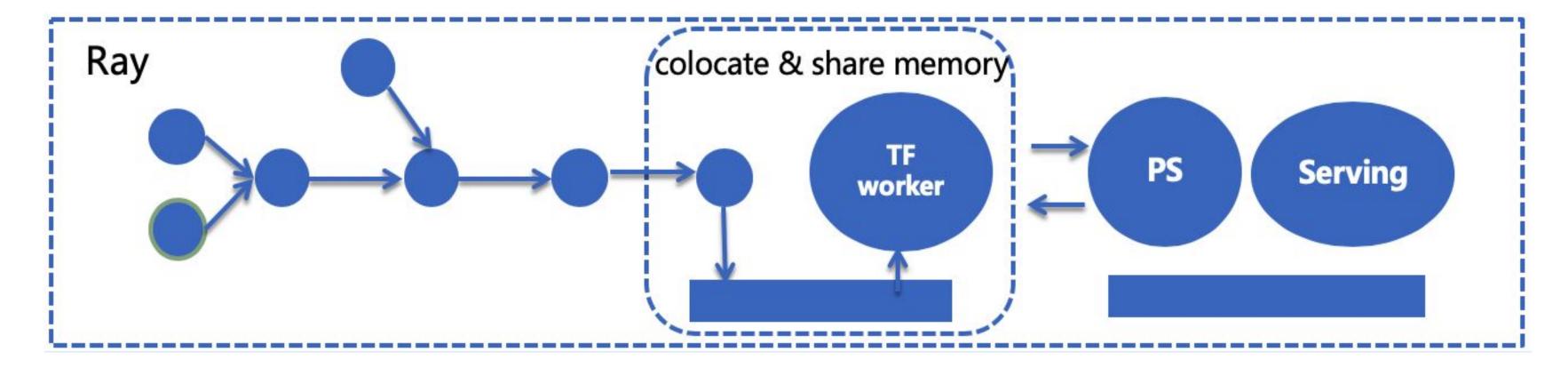
#### **Distributed System (Ray)**

Libraries

#### Use Case: Online Machine Learning







- 3 min, streaming + model training, from feature / label to model output
- 5 min, streaming + training + serving, from feature / label to model deploy
- 5% CTR improvement comparing to offline model; 1% CTR improvement comparing to blink solution



#### Ray API

#### Functions -> Tasks

```
def read_array(file):
    # read array "a" from "file"
    return a

def add(a, b):
    return np.add(a, b)
```

#### Ray API

36

#### Functions -> Tasks

```
@ray.remote
def read_array(file):
    # read array "a" from "file"
    return a

@ray.remote
def add(a, b):
    return np.add(a, b)
```

#### Functions -> Tasks

```
@ray.remote
                                    read_array
def read_array(file):
    # read array "a" from "file"
    return a
                                        id1
@ray.remote
def add(a, b):
    return np.add(a, b)
id1 = read_array.remote([5, 5])
```

#### Functions -> Tasks

```
@ray.remote
def add(a, b):
    return np.add(a, b)

id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
```



#### Functions -> Tasks

id3 = add.remote(id1, id2)

```
@ray.remote
                                    read_array
                                                     read_array
def read_array(file):
    # read array "a" from "file"
                                         id1
                                                       id2
    return a
@ray.remote
                                                add
def add(a, b):
    return np.add(a, b)
                                                id3
id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
```

©2017 RISELab

#### Functions -> Tasks

ray.get(id3)

```
@ray.remote
                                      read_array
                                                       read_array
def read array(file):
    # read array "a" from "file"
                                          id1
                                                         id2
    return a
@ray.remote
                                                 add
def add(a, b):
    return np.add(a, b)
                                                  id3
id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
id3 = add.remote(id1, id2)
                                   ©2017 RISELab
```

Functions -> Tasks

```
@ray.remote
def read_array(file):
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id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
id3 = add.remote(id1, id2)
                                  ©2017 RISELab
ray.get(id3)
```

Classes -> Actors

# Functions -> Tasks

```
@ray.remote
def read array(file):
    # read array "a" from "file"
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@ray.remote
def add(a, b):
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id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
id3 = add.remote(id1, id2)
                                  ©2017 RISELab
ray.get(id3)
```

#### Classes -> Actors

```
@ray.remote(num_gpus=1)
class Counter(object):
    def __init__(self):
        self.value = 0
    def inc(self):
        self.value += 1
        return self.value
```

#### Functions -> Tasks @ray.remote def read array(file): # read array "a" from "file" return a @ray.remote def add(a, b): return np.add(a, b) id1 = read\_array.remote([5, 5]) id2 = read\_array.remote([5, 5]) id3 = add.remote(id1, id2) ray.get(id3)

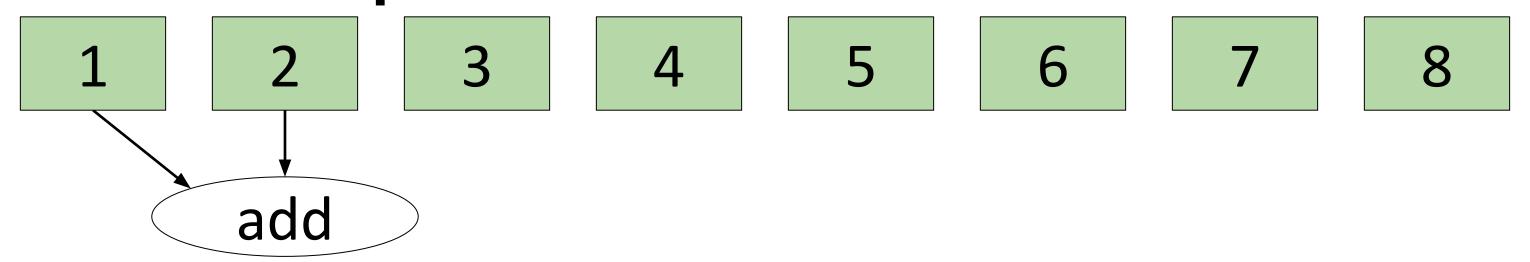
#### **Classes -> Actors**

```
@ray.remote(num gpus=1)
class Counter(object):
    def init (self):
        self.value = 0
    def inc(self):
        self.value += 1
        return self.value
c = Counter.remote()
id4 = c.inc.remote()
id5 = c.inc.remote()
ray.get([id4, id5])
```

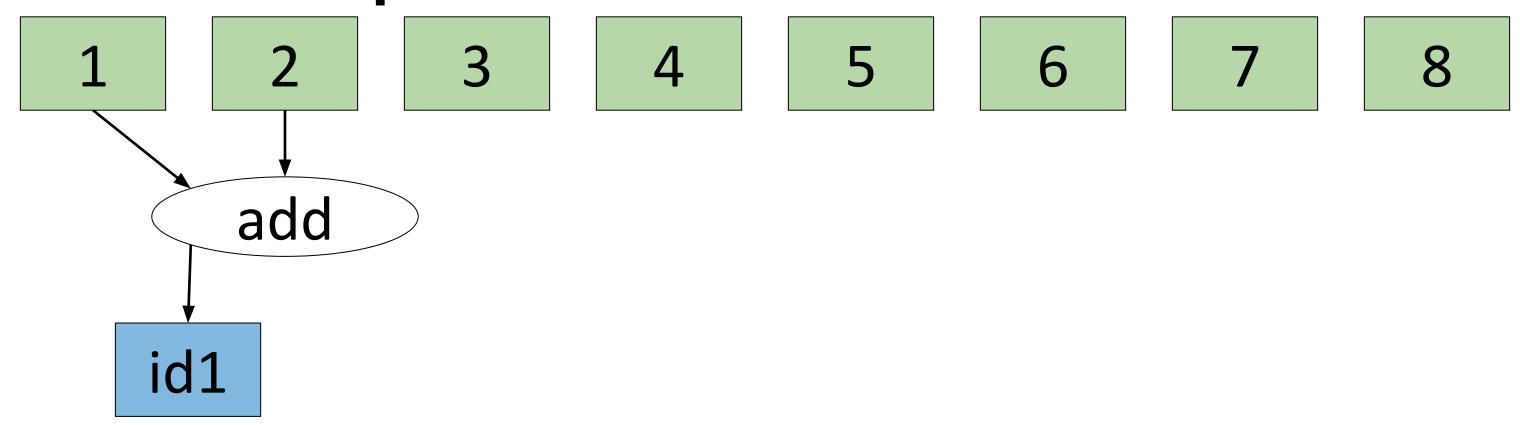
1 2 3 4 5 6 7 8

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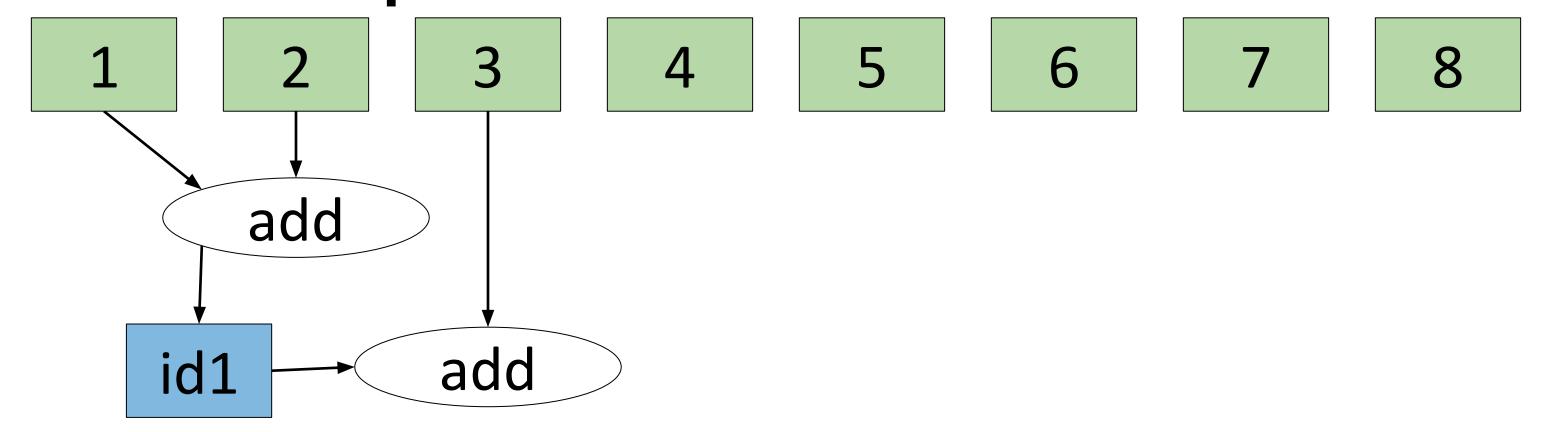
```
@ray.remote
def add(x, y):
    time.sleep(0.5)
    return x + y
```



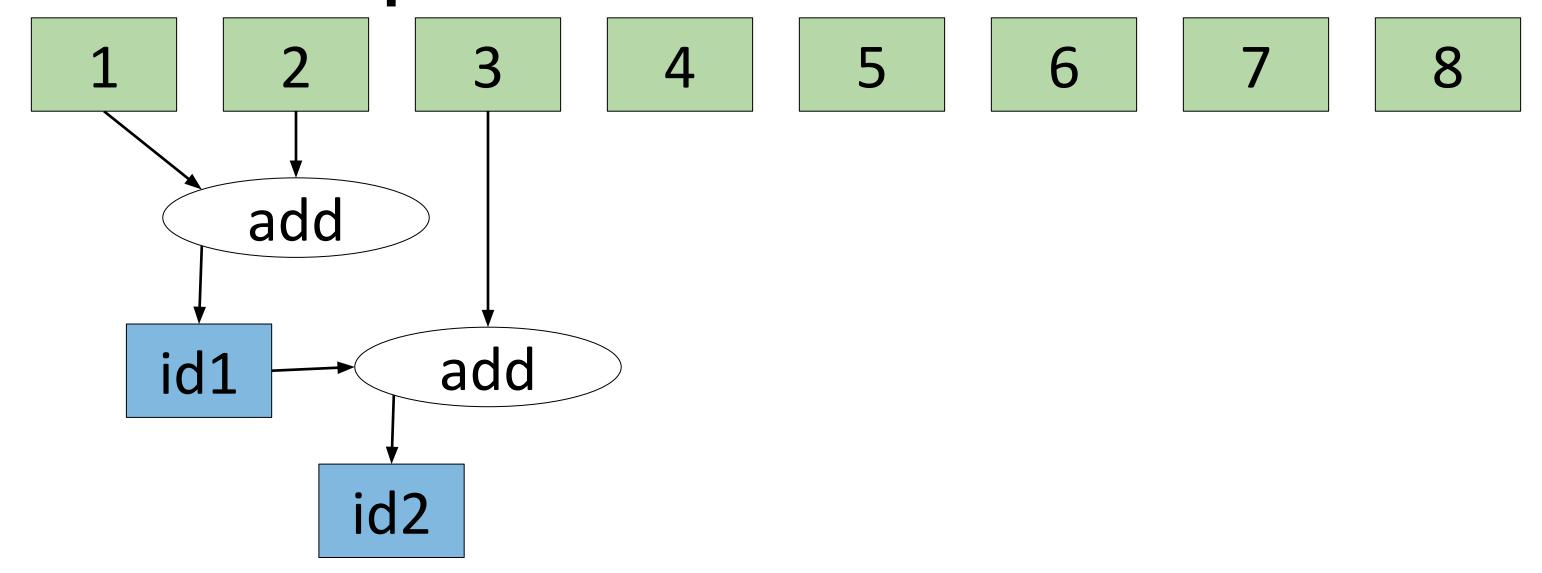
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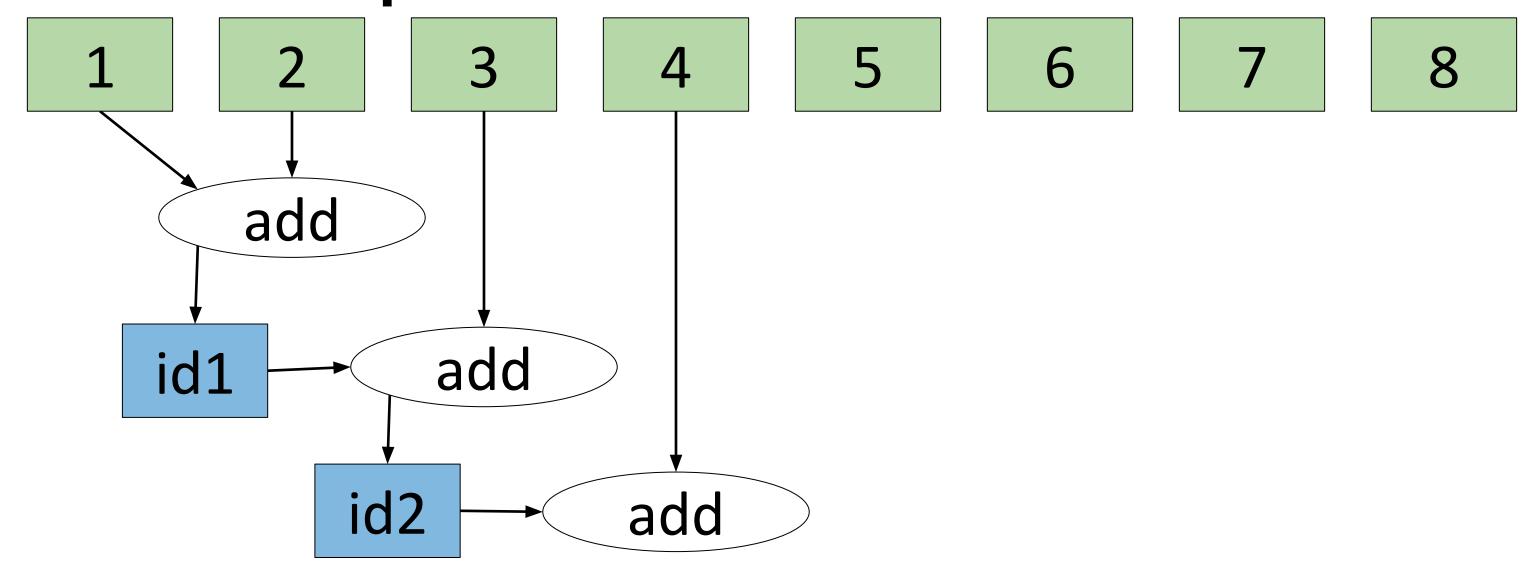
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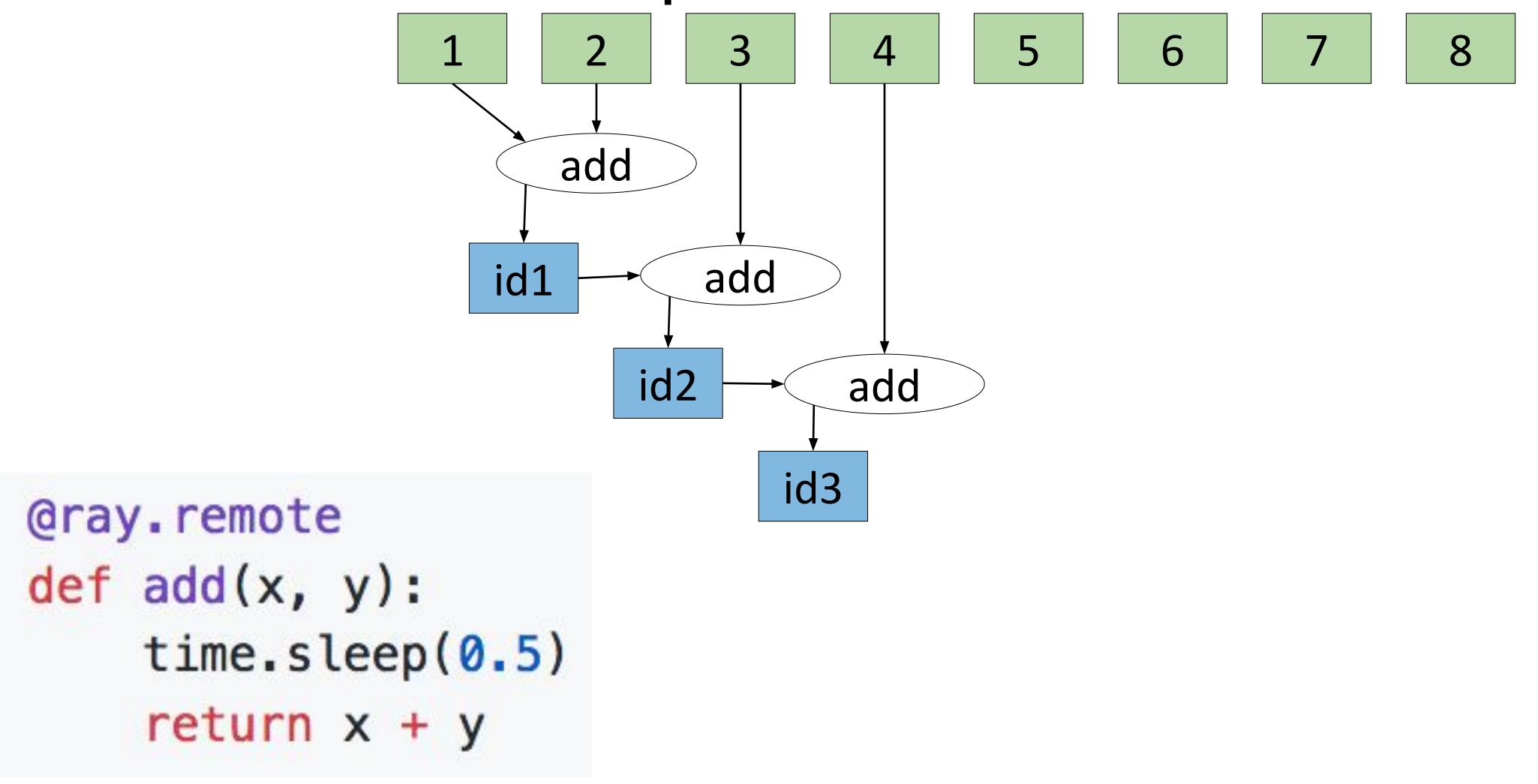
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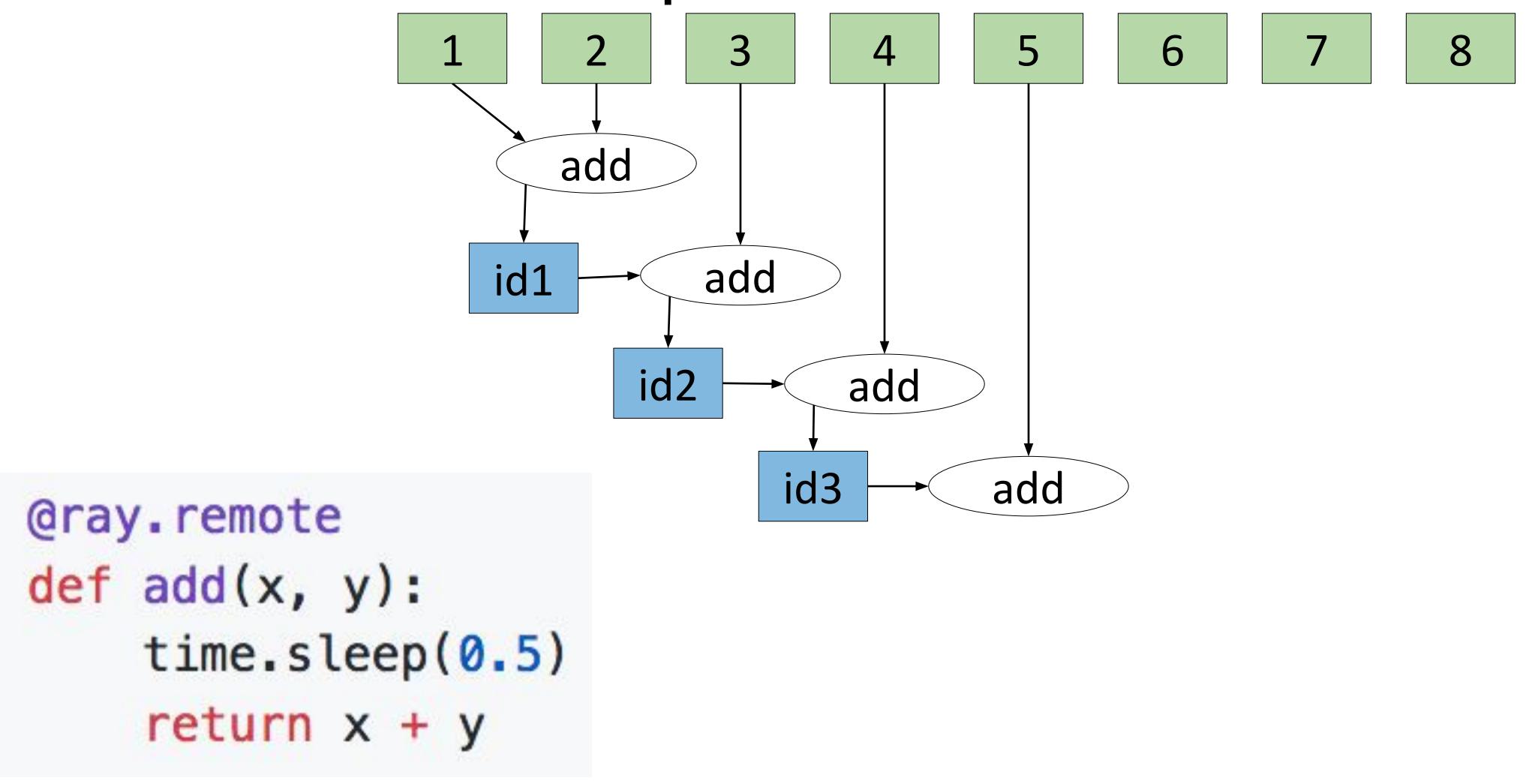


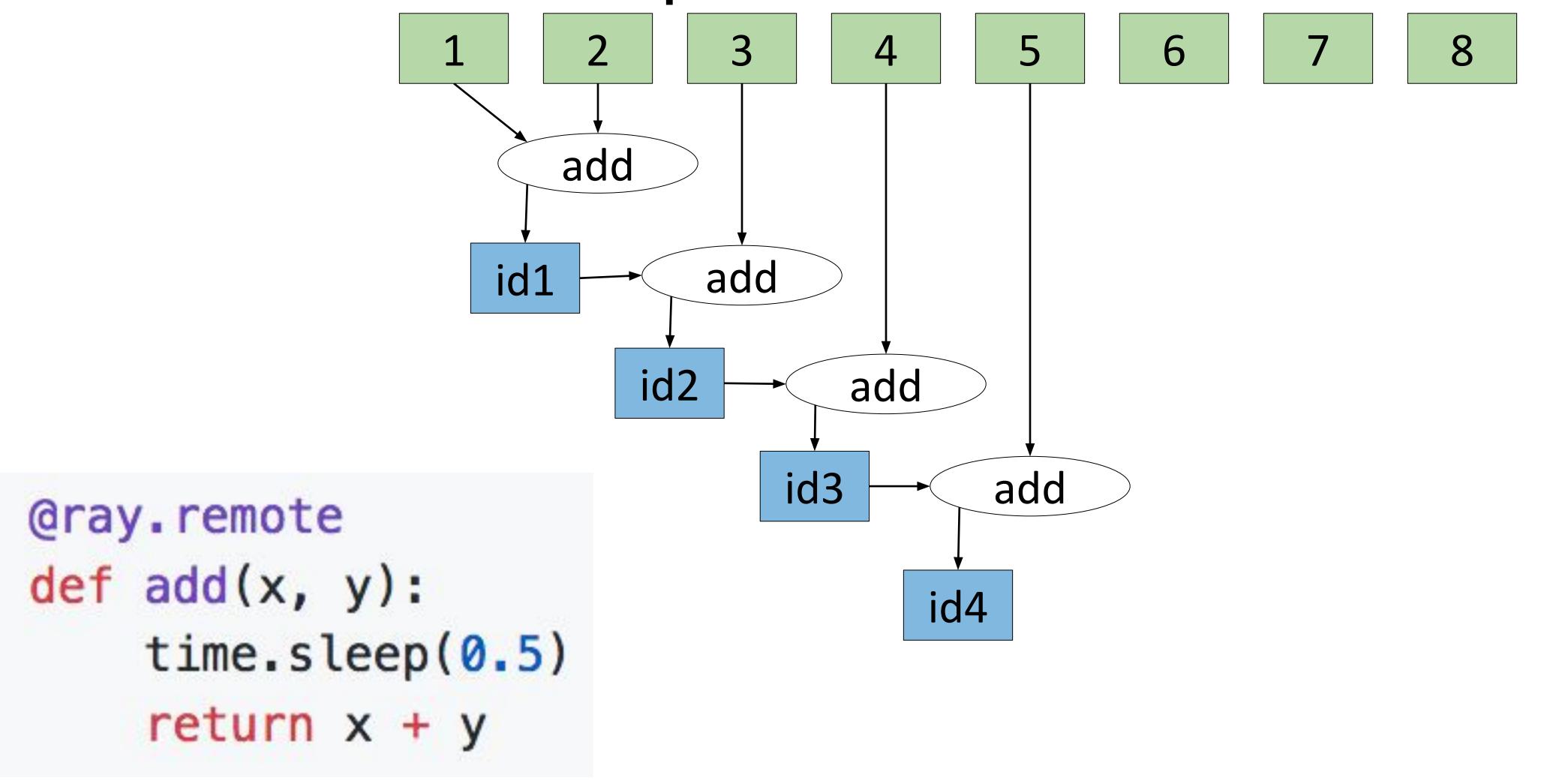
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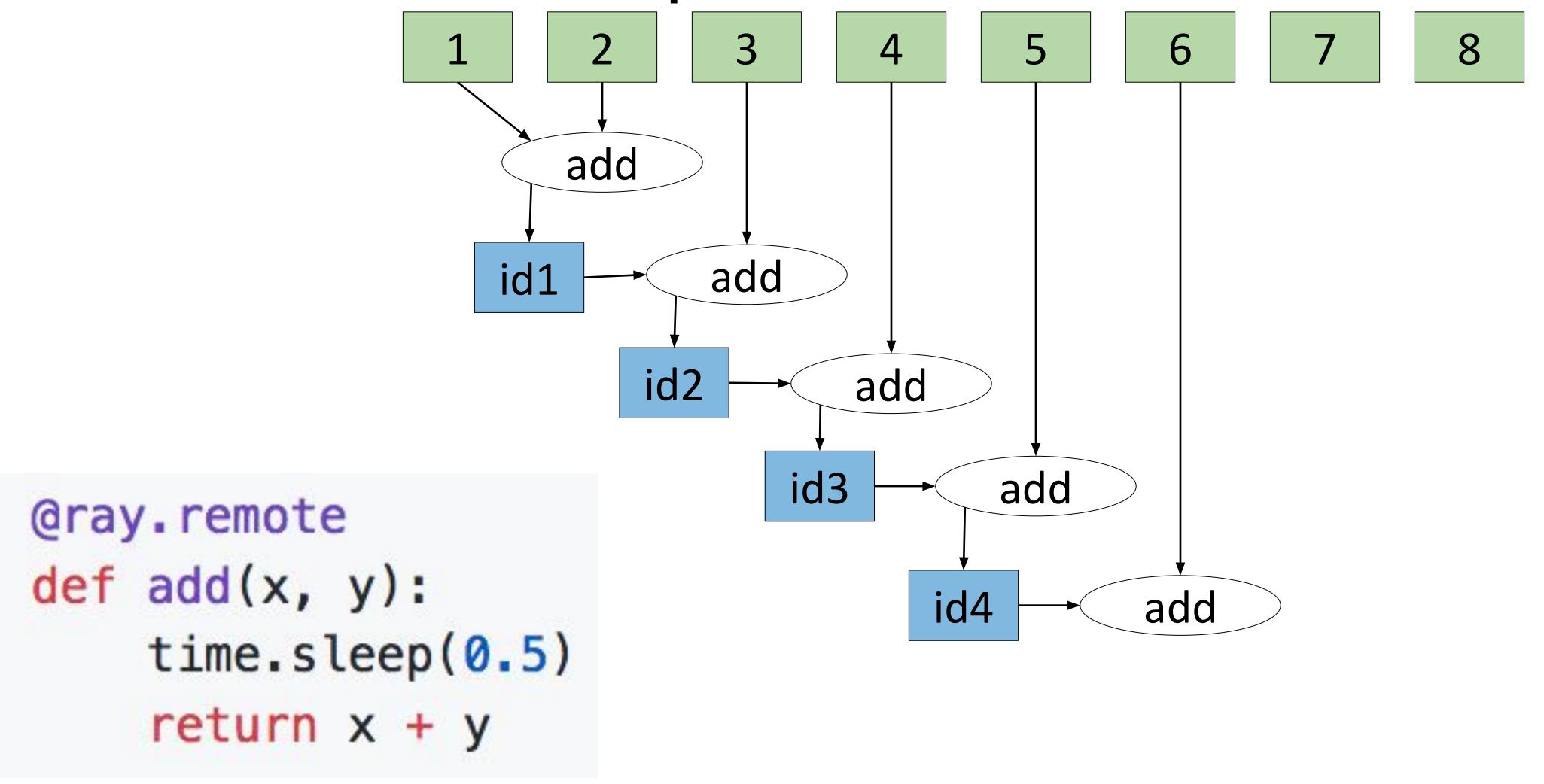


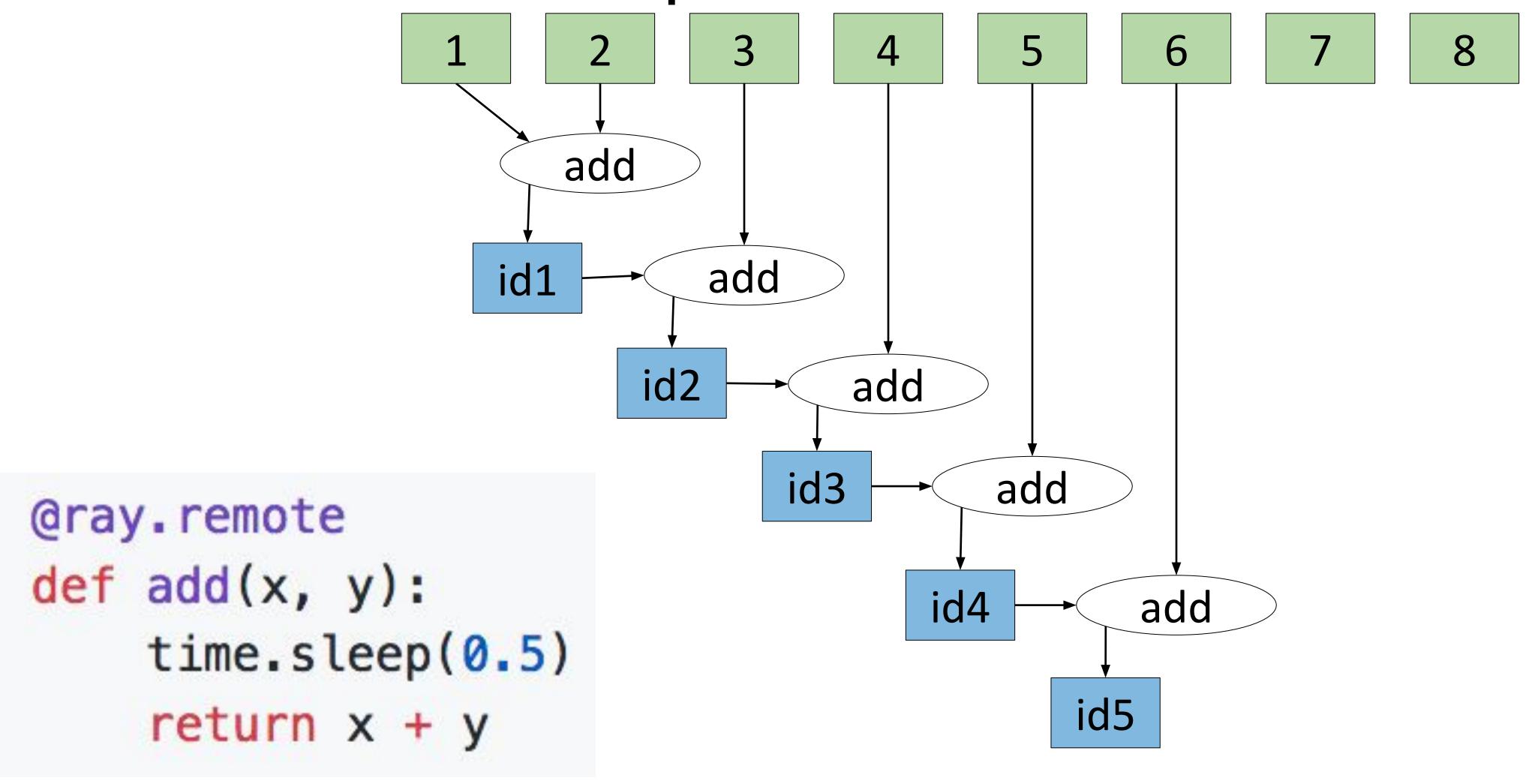
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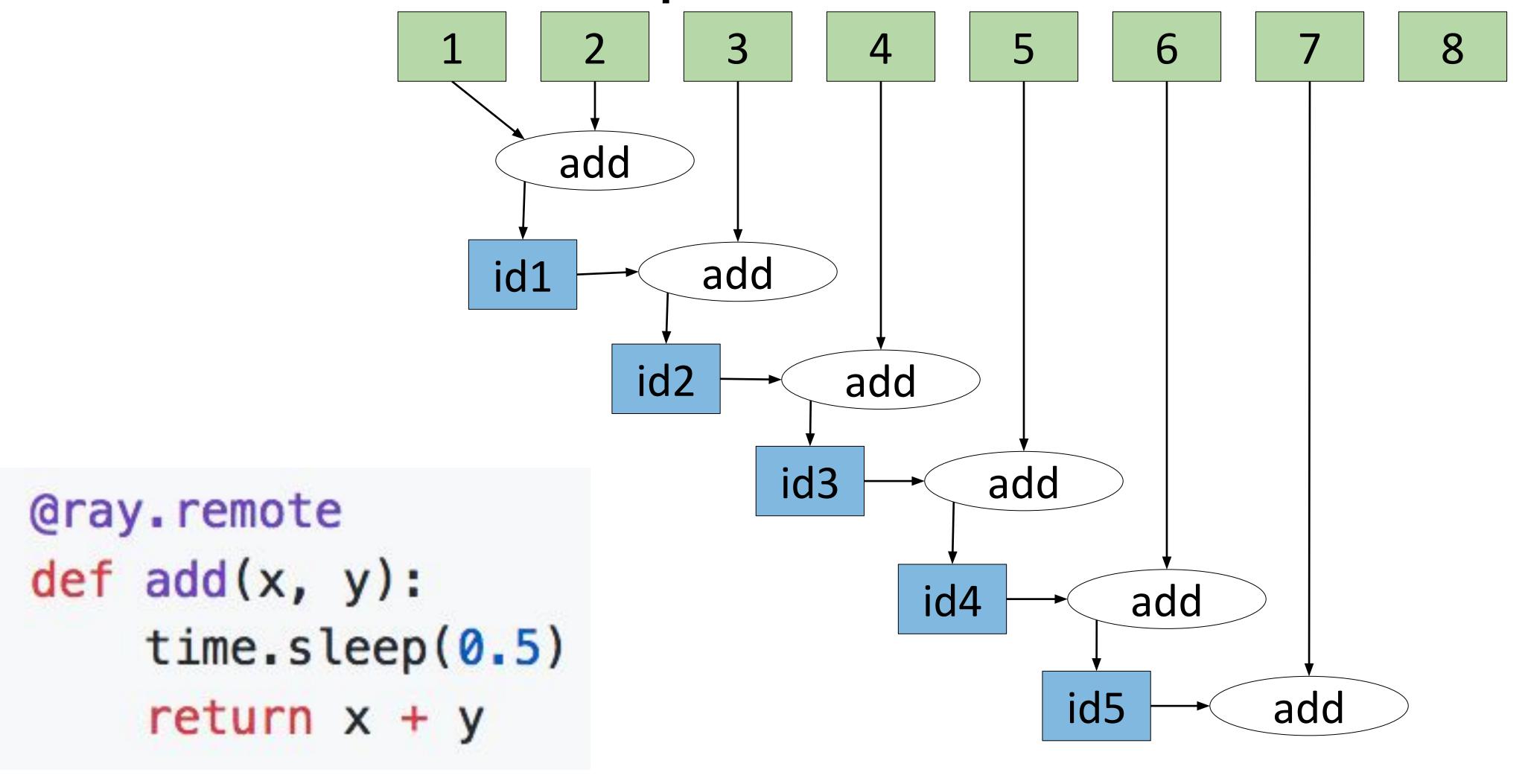


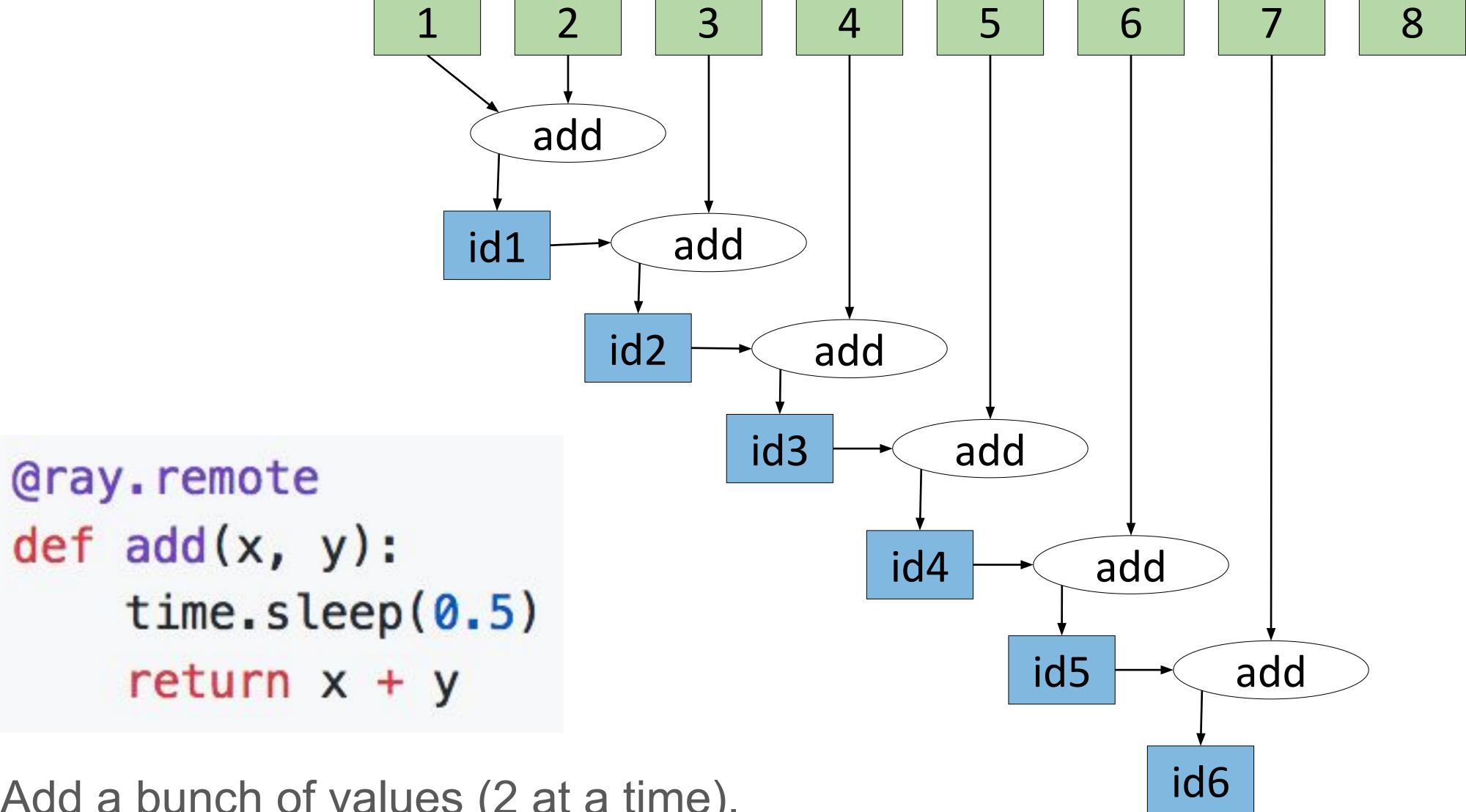


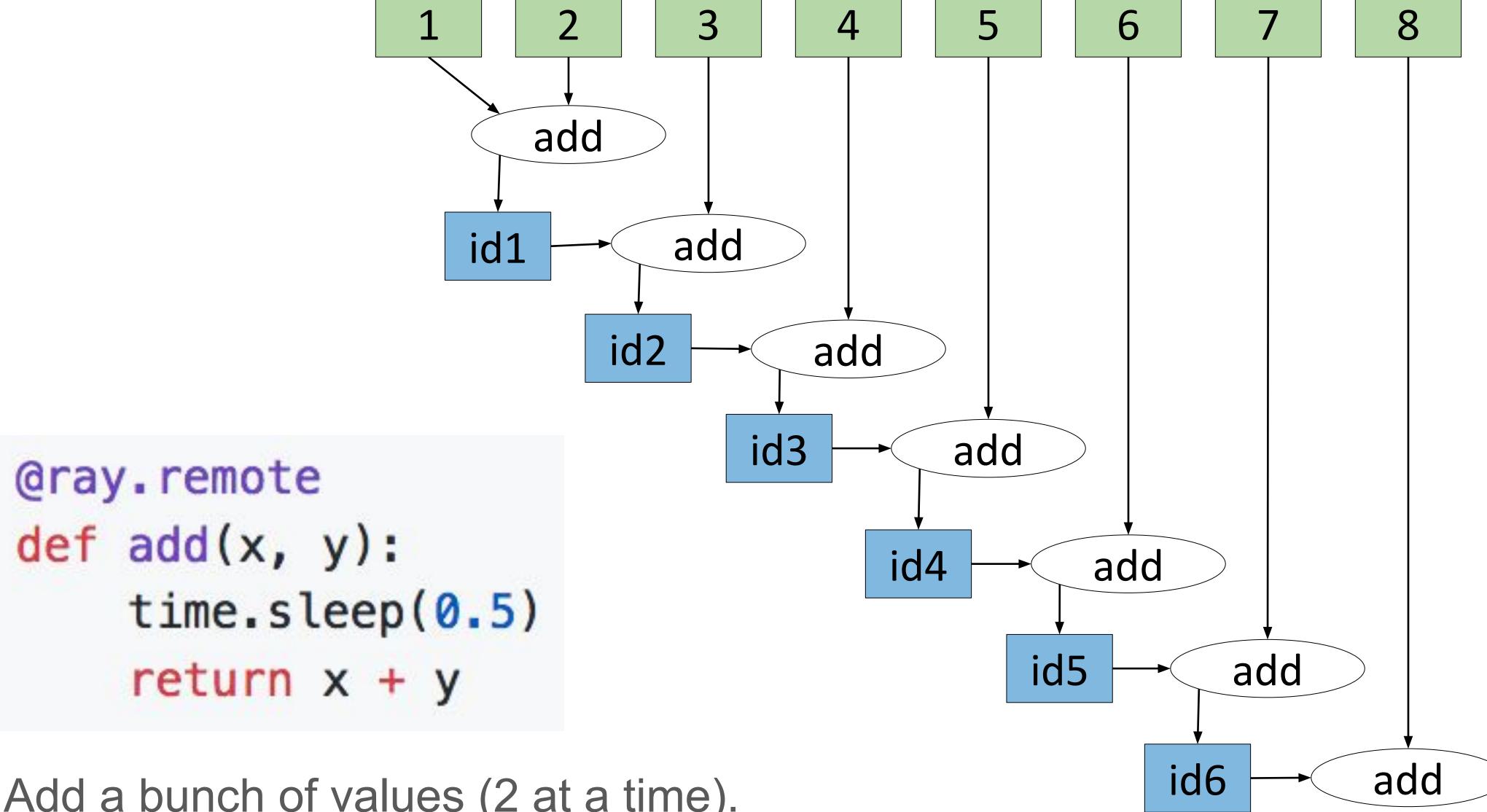


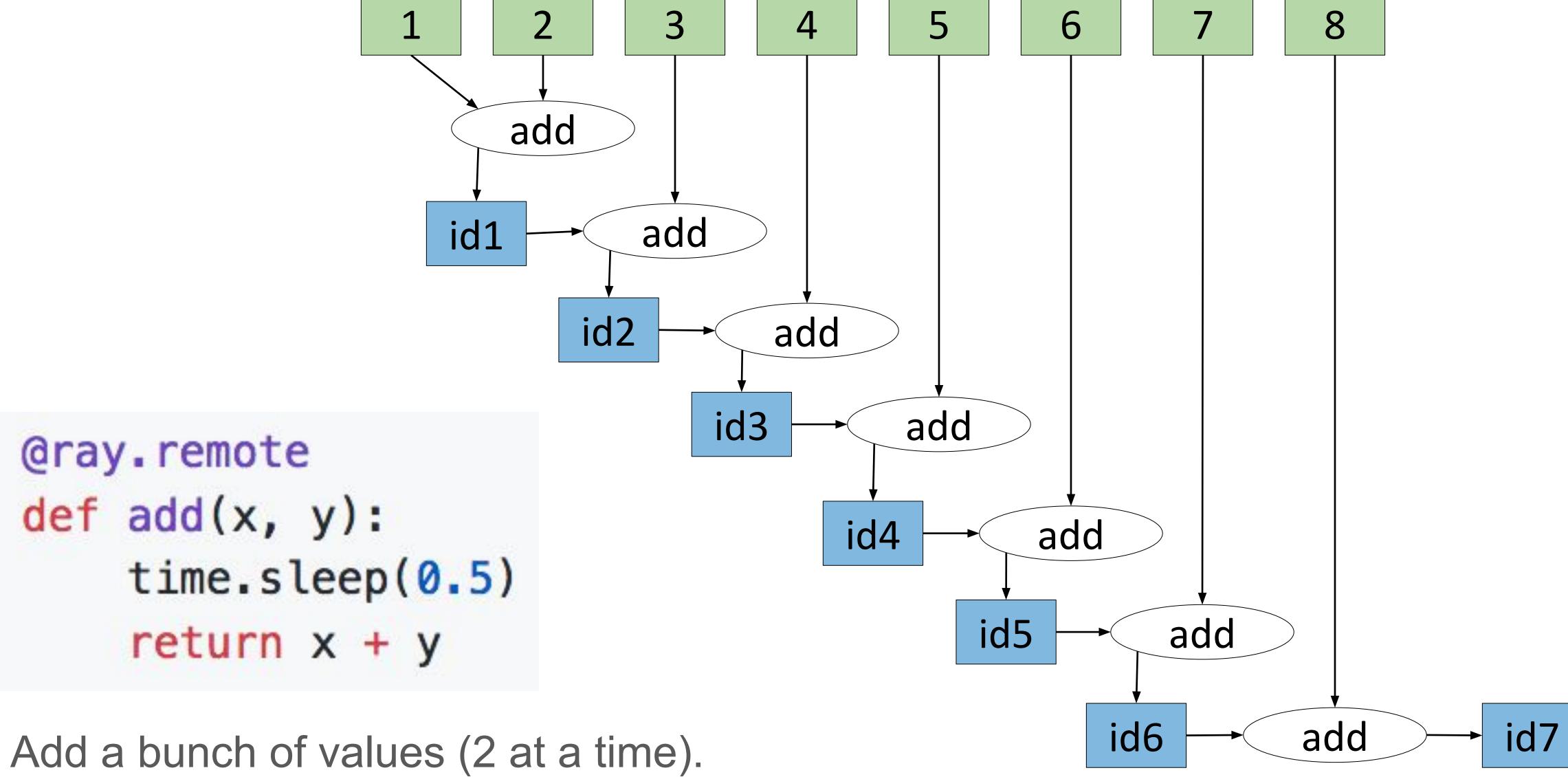






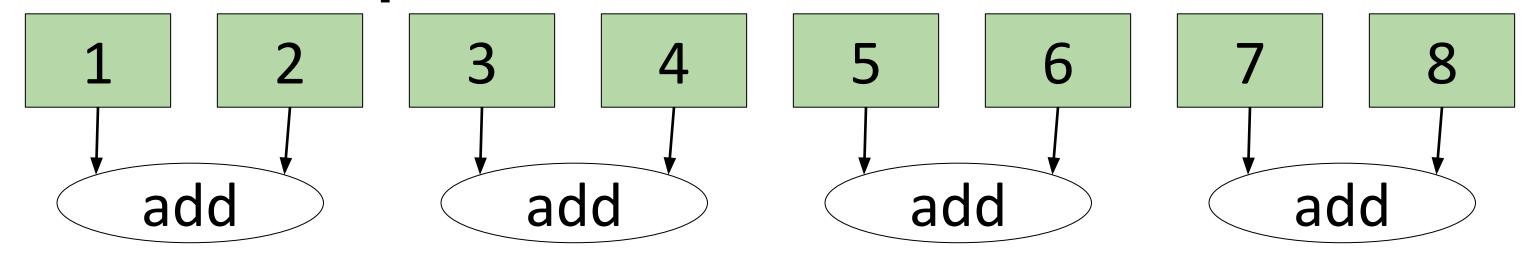




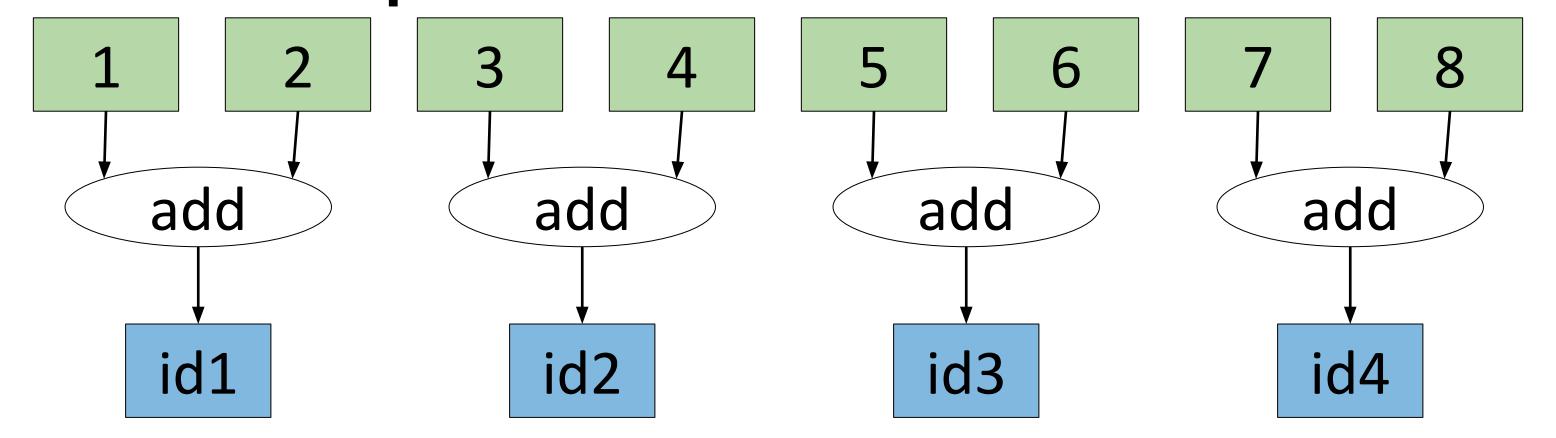


1 2 3 4 5 6 7 8

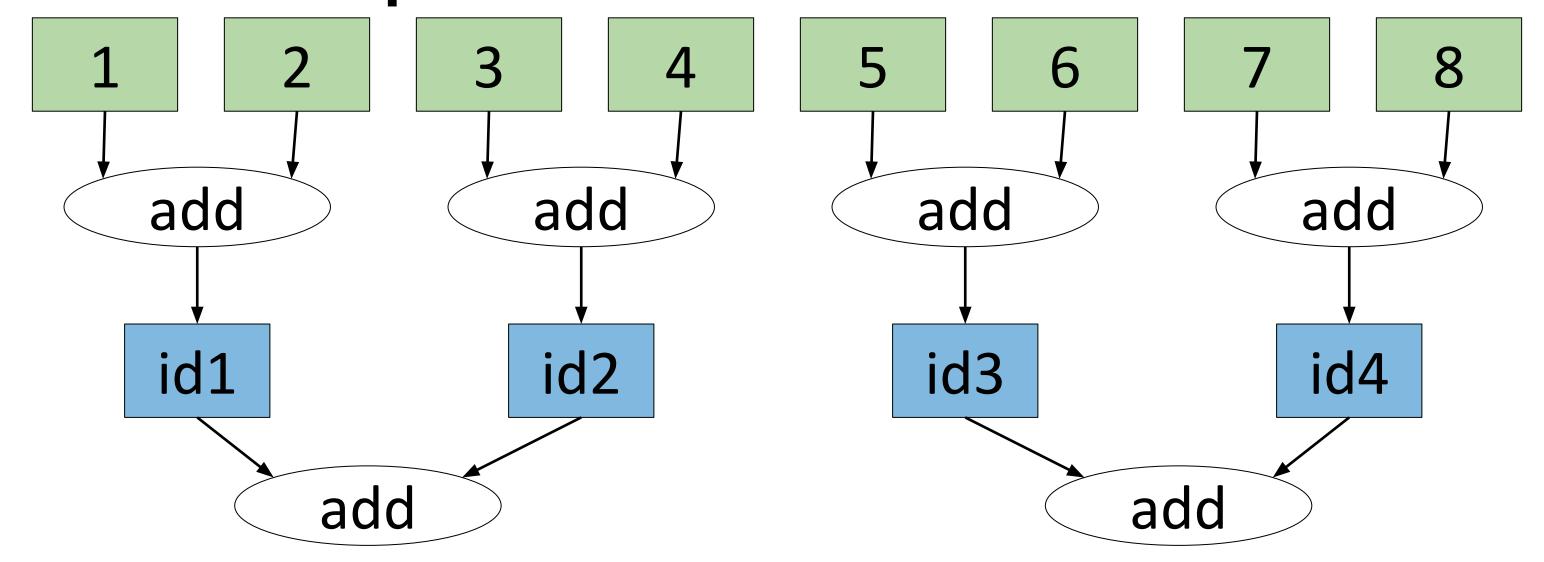
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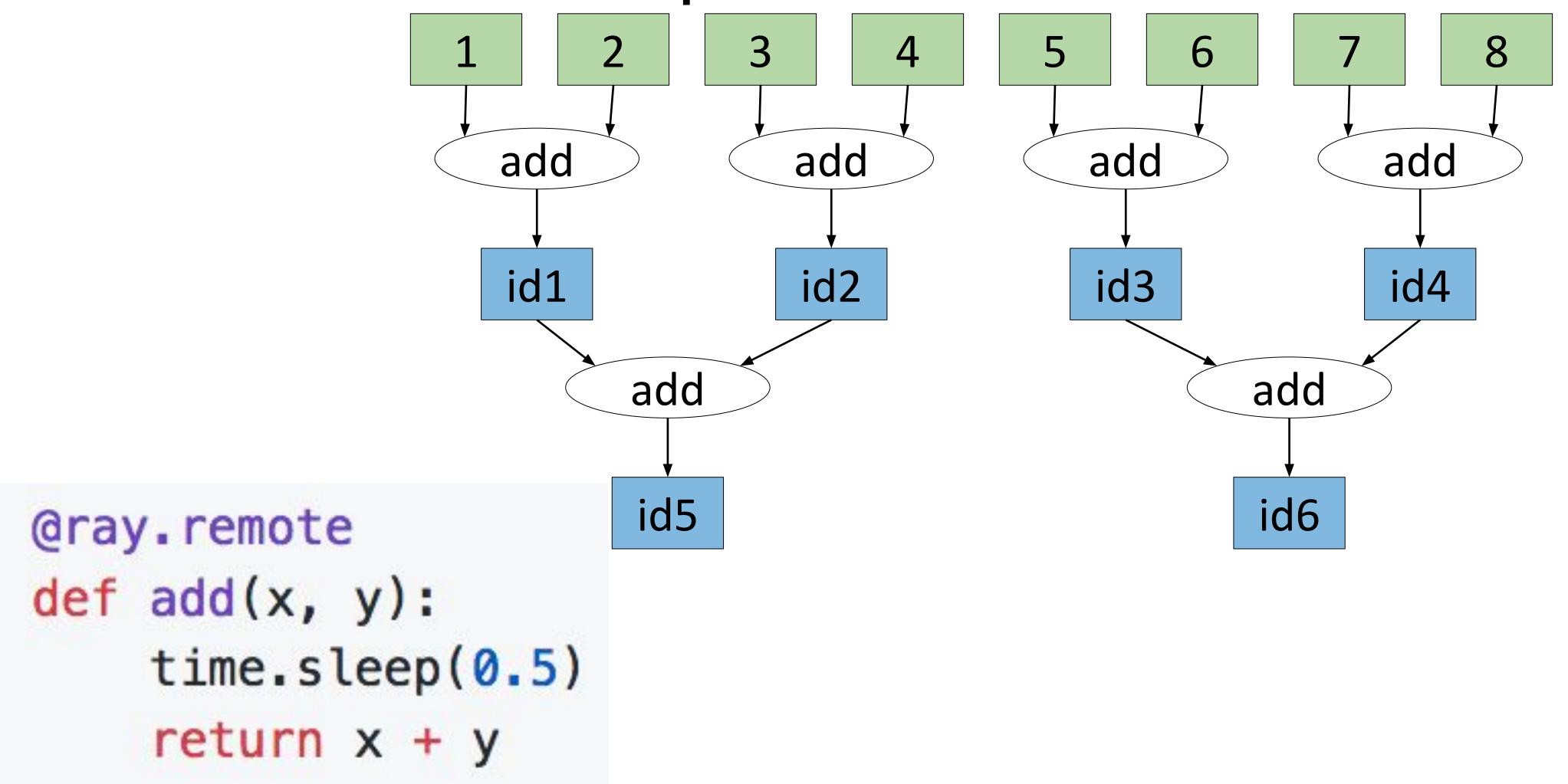
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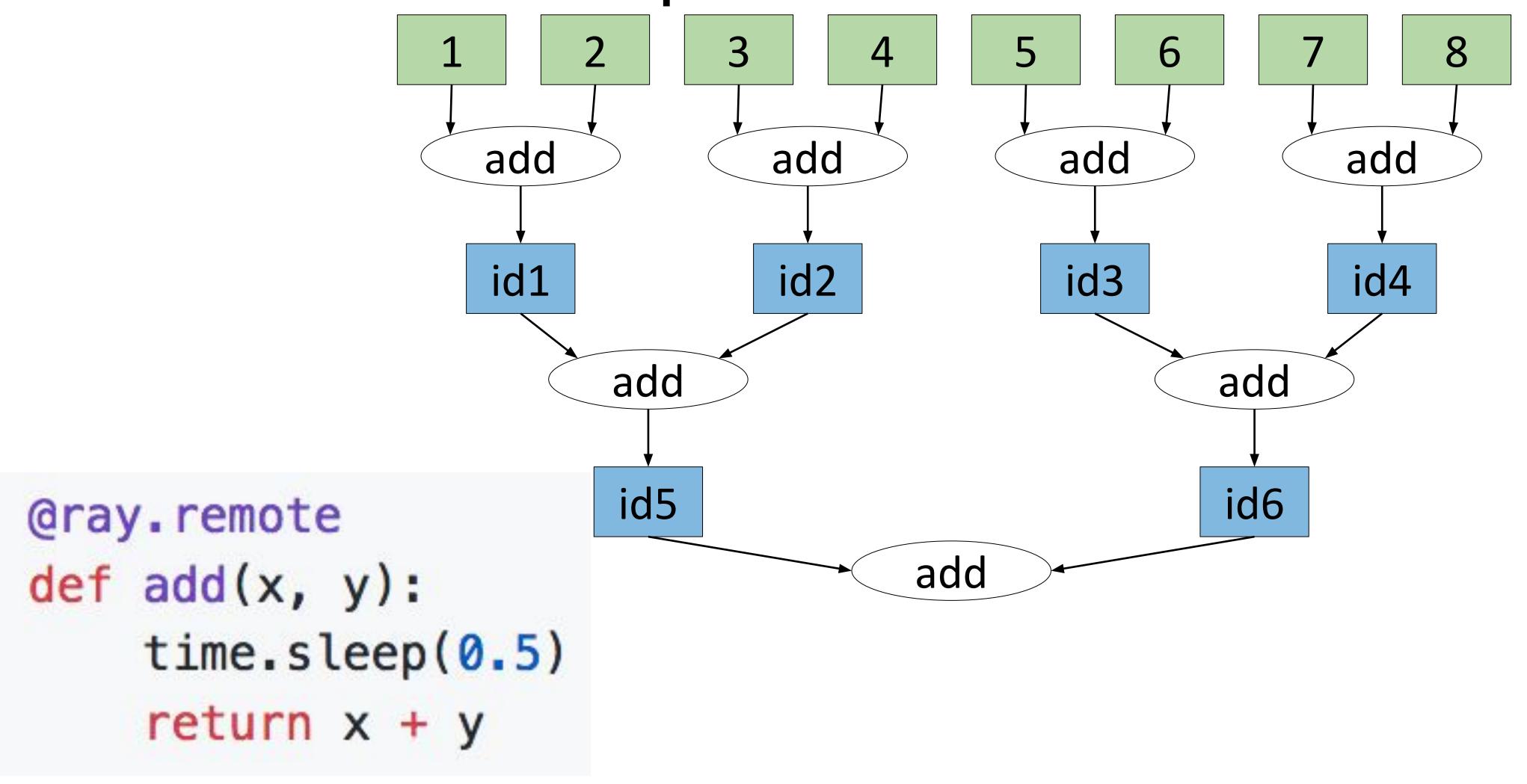


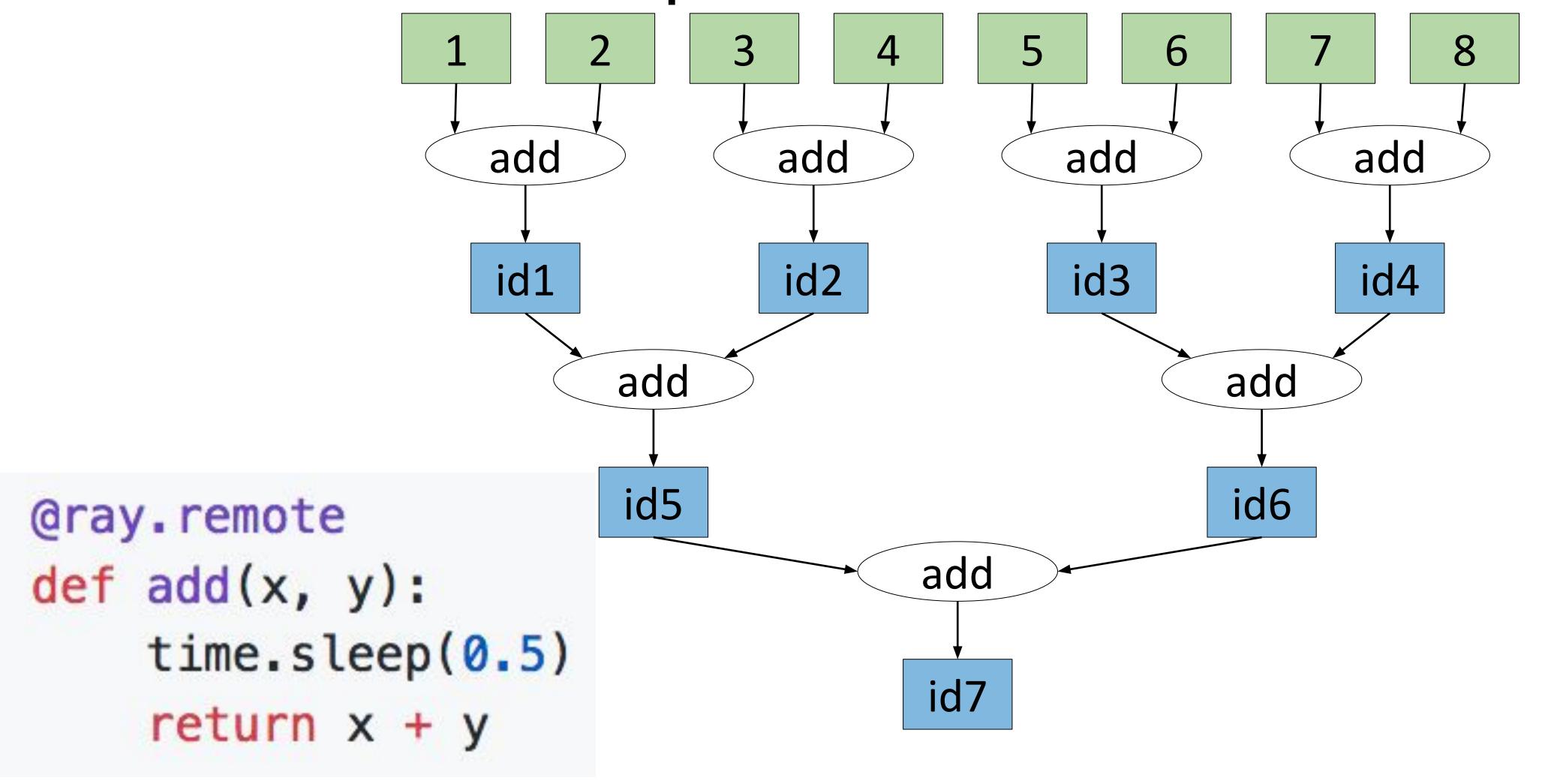
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```
vals = [1, 2, 3, 4, 5, 6, 7, 8]
while len(vals) > 1:
    new_val = add.remote(vals[0], vals[1])
    vals = [new_val] + vals[2:]
vals = [1, 2, 3, 4, 5, 6, 7, 8]
while len(vals) > 1:
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```

#### Actors: Parameter Server Example

```
@ray.remote
class ParameterServer(object):
    def __init__(self):
        self.params = np.zeros(10)
    def get_params(self):
        return self.params
    def update_params(self, grad):
        self.params -= grad
```

#### Actors: Parameter Server Example

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```



```
@ray.remote(num_gpus=1)
def worker(ps):
    while True:
        params = ray.get(ps.get_params.remote())
        grad = ... # Use TensorFlow
        ps.update_params.remote(grad)
```

#### Actors: Parameter Server Example

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                                                             @ray.remote(num_gpus=1)
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                                                             def worker(ps):
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    def update_params(self, grad):
        self.params -= grad
                                                        @ray.remote(num_gpus=1)
                                                        def worker(ps):
                                                            while True:
```

```
@ray.remote(num_gpus=1)
def worker(ps):
    while True:
        params = ray.get(ps.get_params.remote())
        grad = ... # Use TensorFlow
        ps.update_params.remote(grad)
```



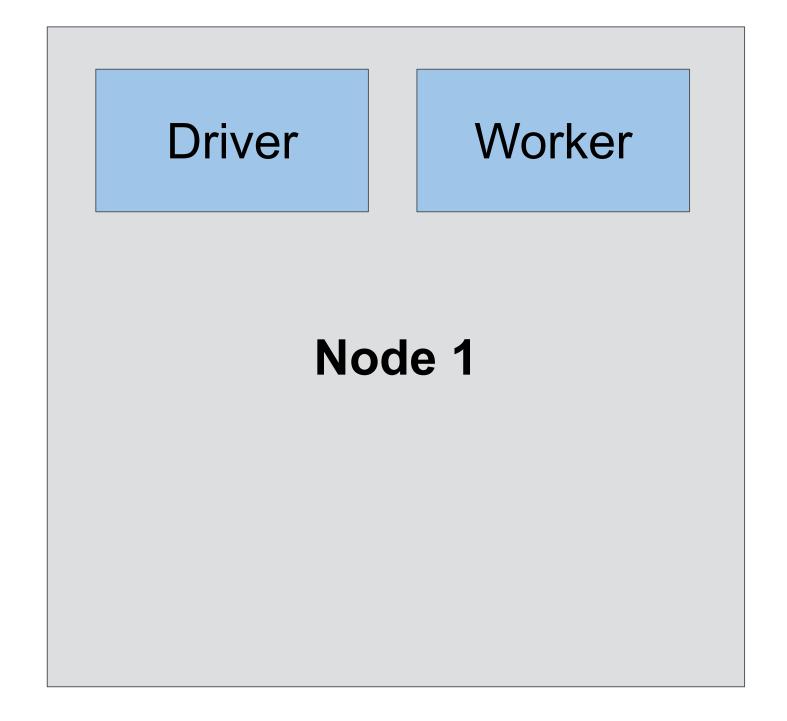
#### Actors: Parameter Server Example

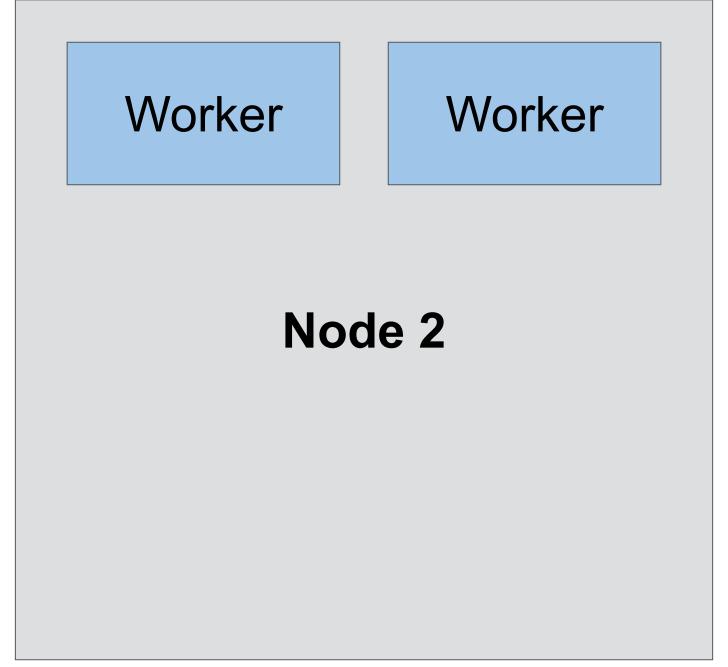
```
@ray.remote
                                                                     @ray.remote(num_gpus=1)
   @ray.remote
                                                                     def worker(ps):
                                                                         while True:
@ray.remote
class ParameterServer(object):
    def __init__(self):
        self.params = np.zeros(10)
    def get params(self):
                                                                @ray.remote(num_gpus=1)
        return self.params
                                                                def worker(ps):
    def update params(self, grad):
                                                                    while True:
        self.params -= grad
```

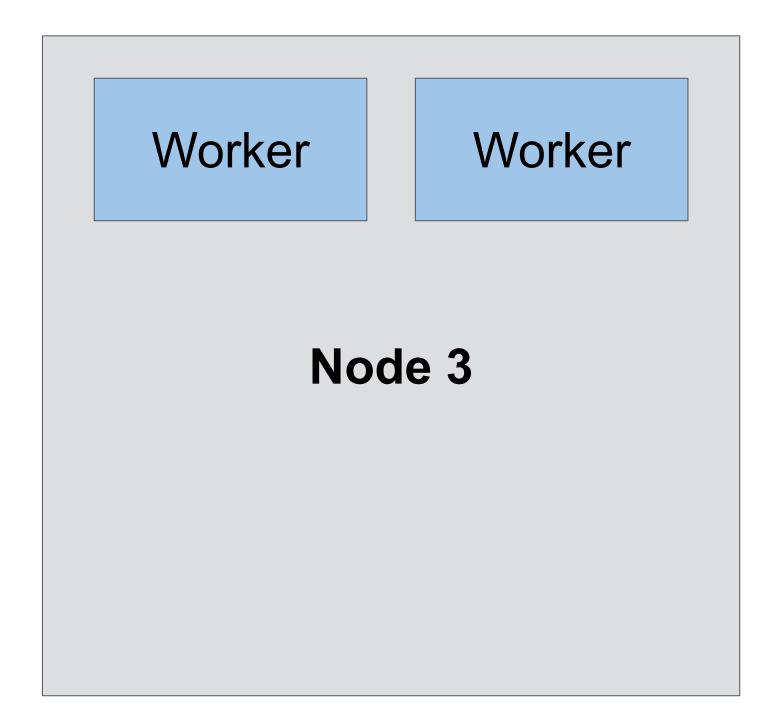
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```

Node 1 Node 2 Node 3

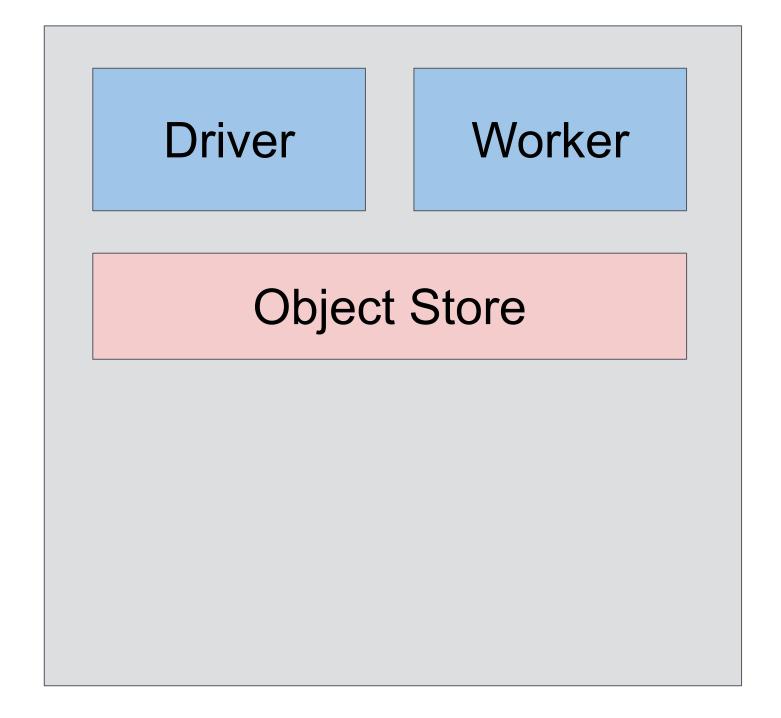


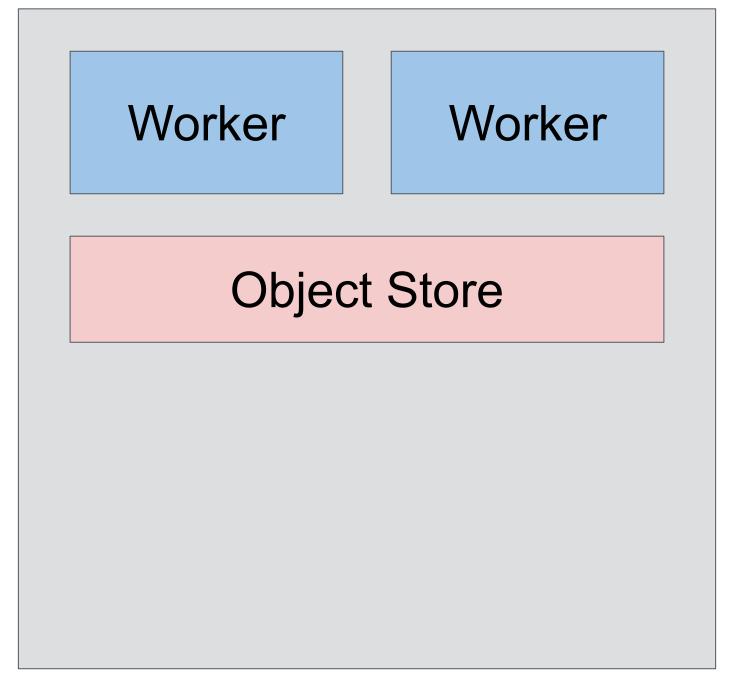


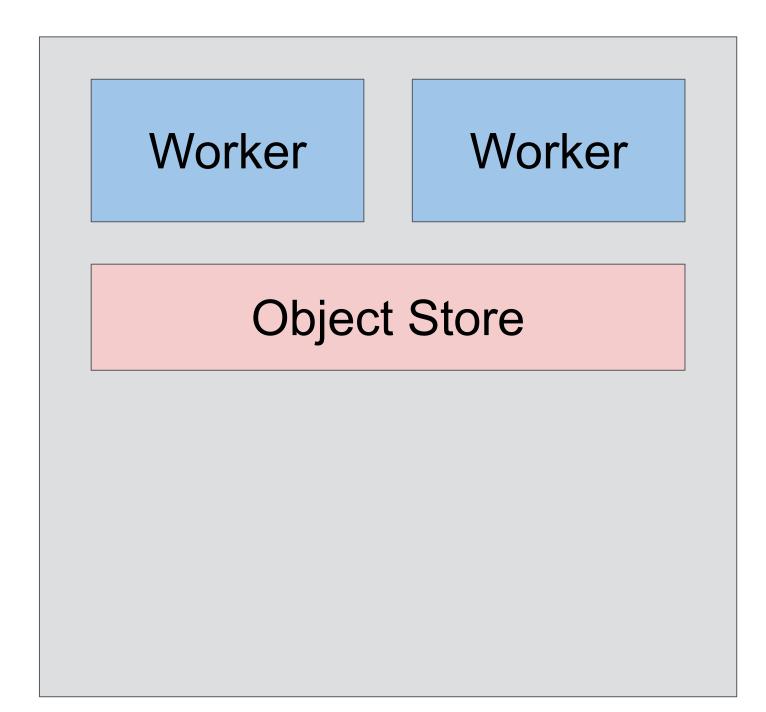




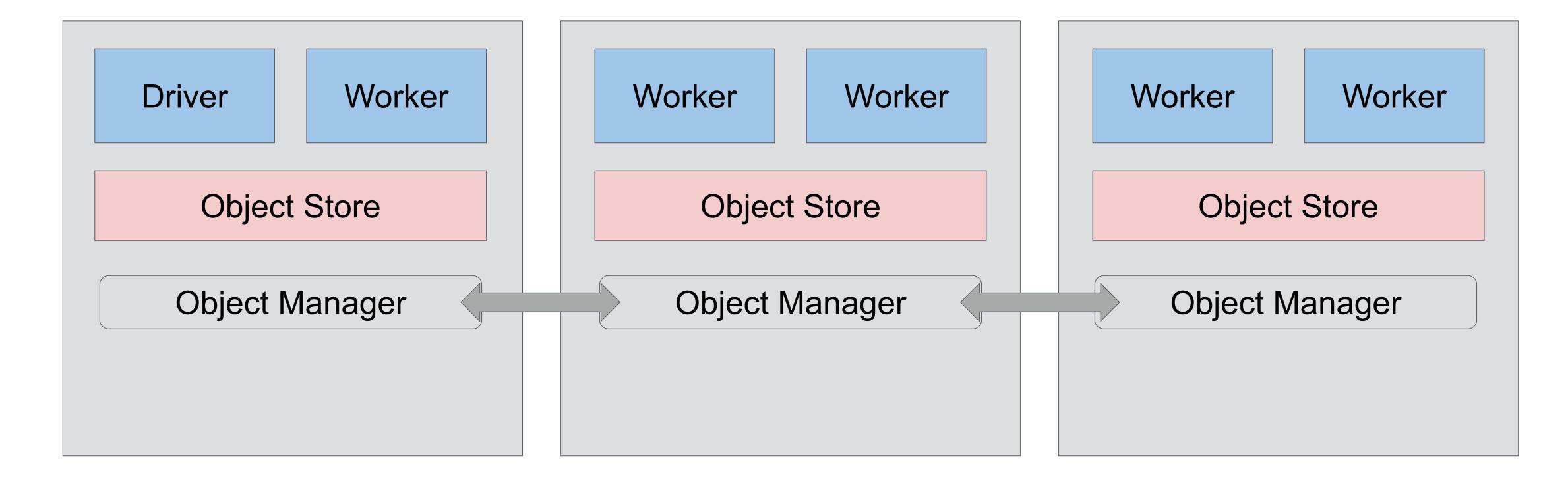




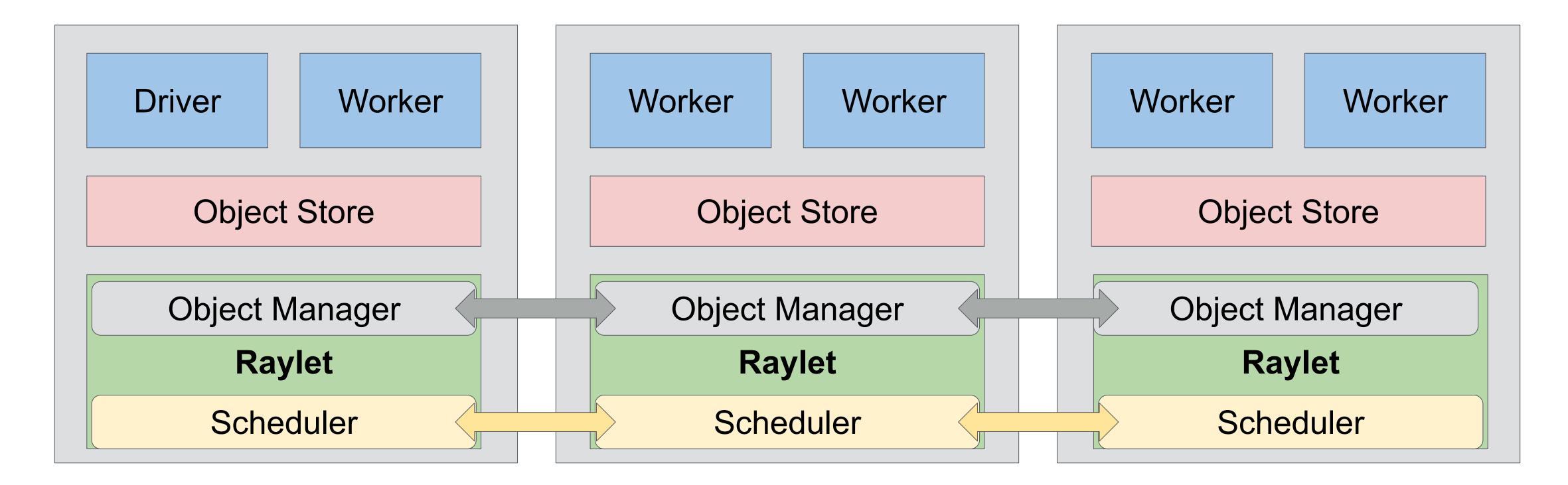






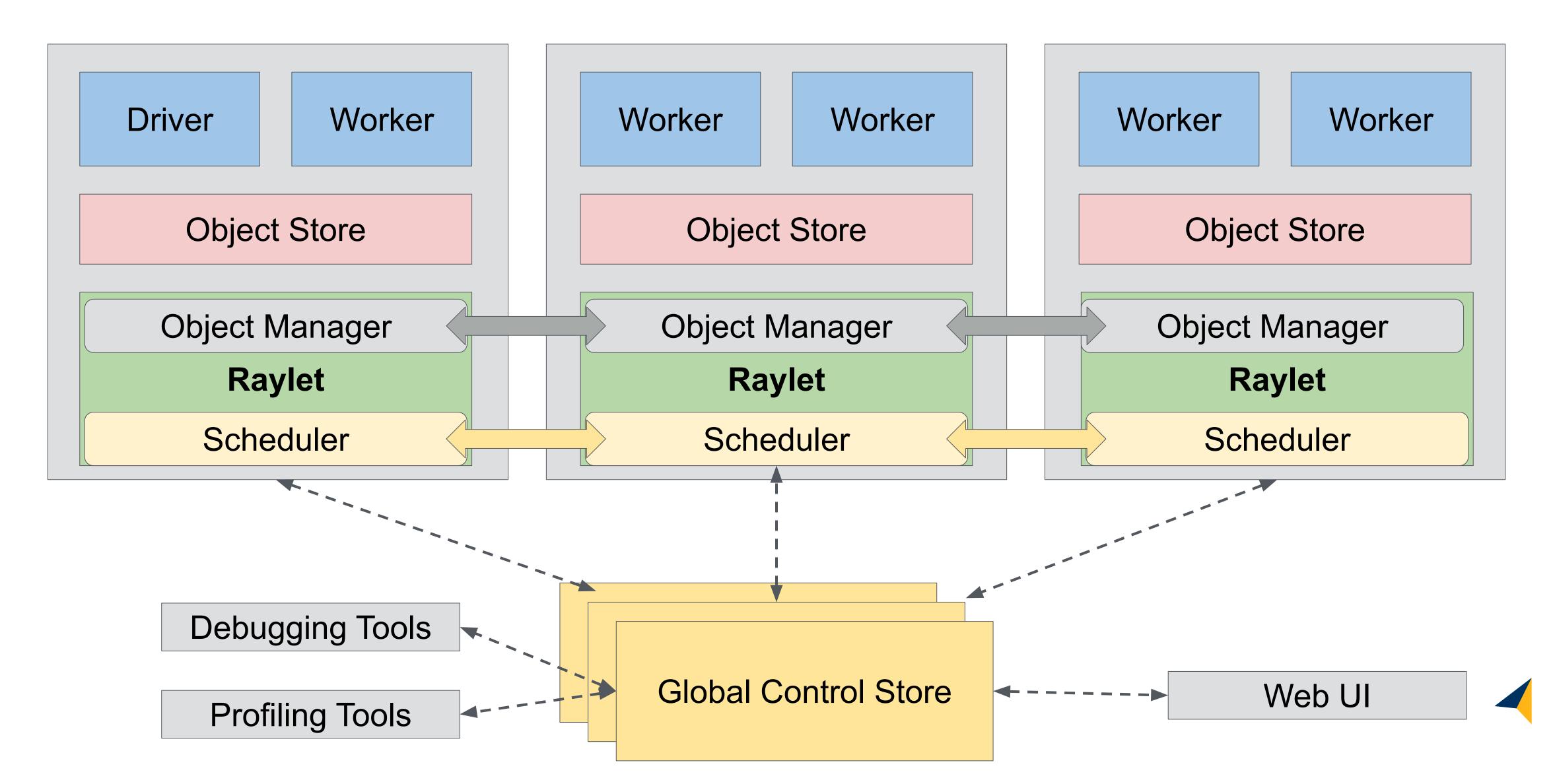








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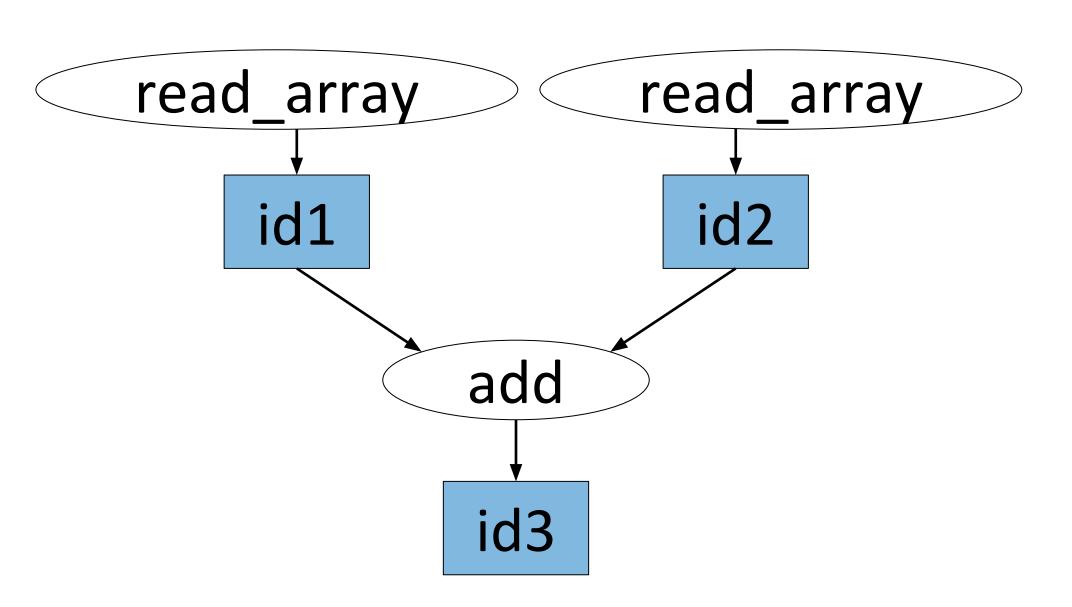


How does this work under the hood?

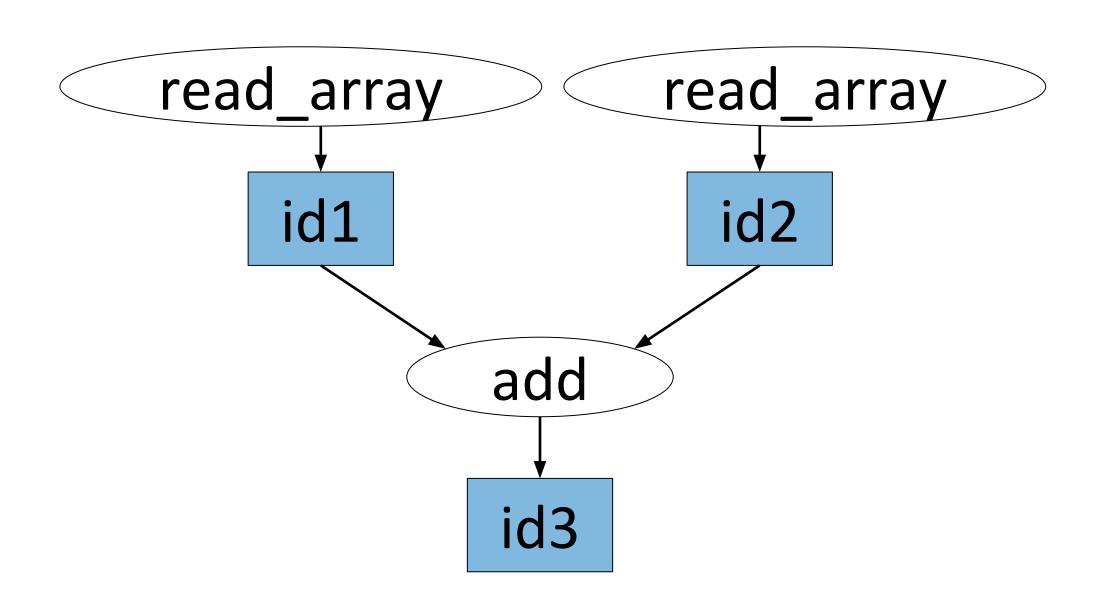
#### How does this work under the hood?

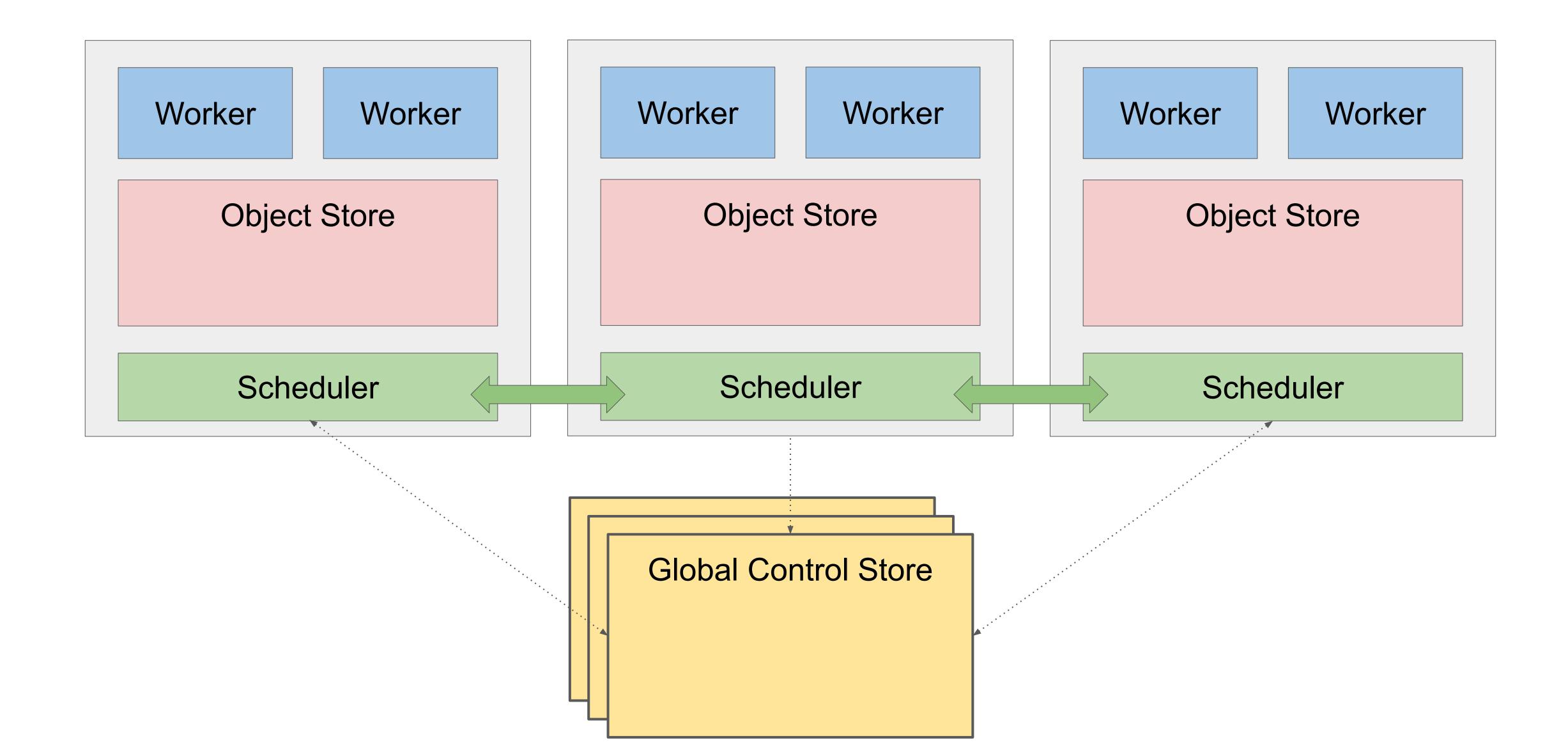
#### **Tasks**

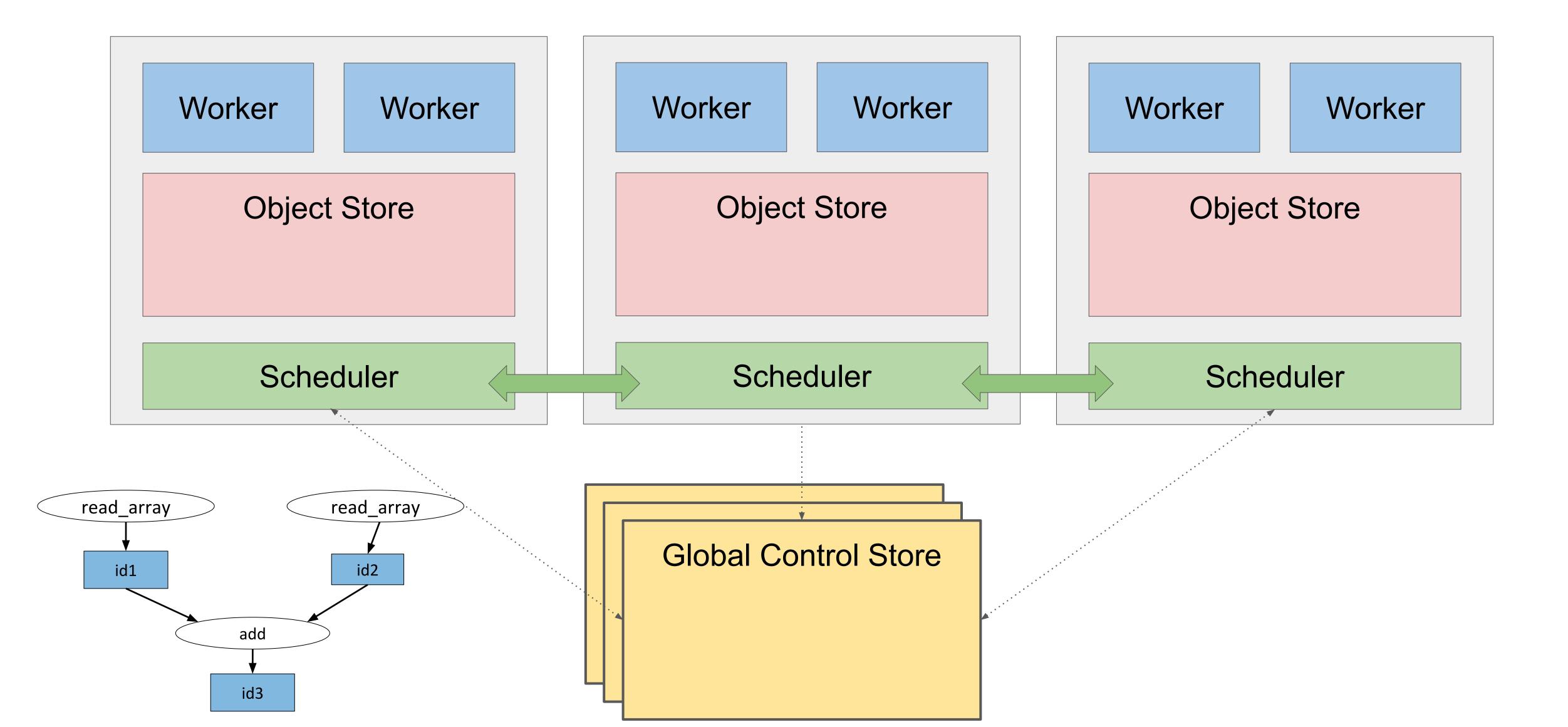
```
@ray.remote
def read_array(file):
    # read array "a" from "file"
    return a
@ray.remote
def add(a, b):
    return np.add(a, b)
id1 = read_array.remote([5, 5])
id2 = read_array.remote([5, 5])
id3 = add.remote(id1, id2)
ray.get(id3)
```

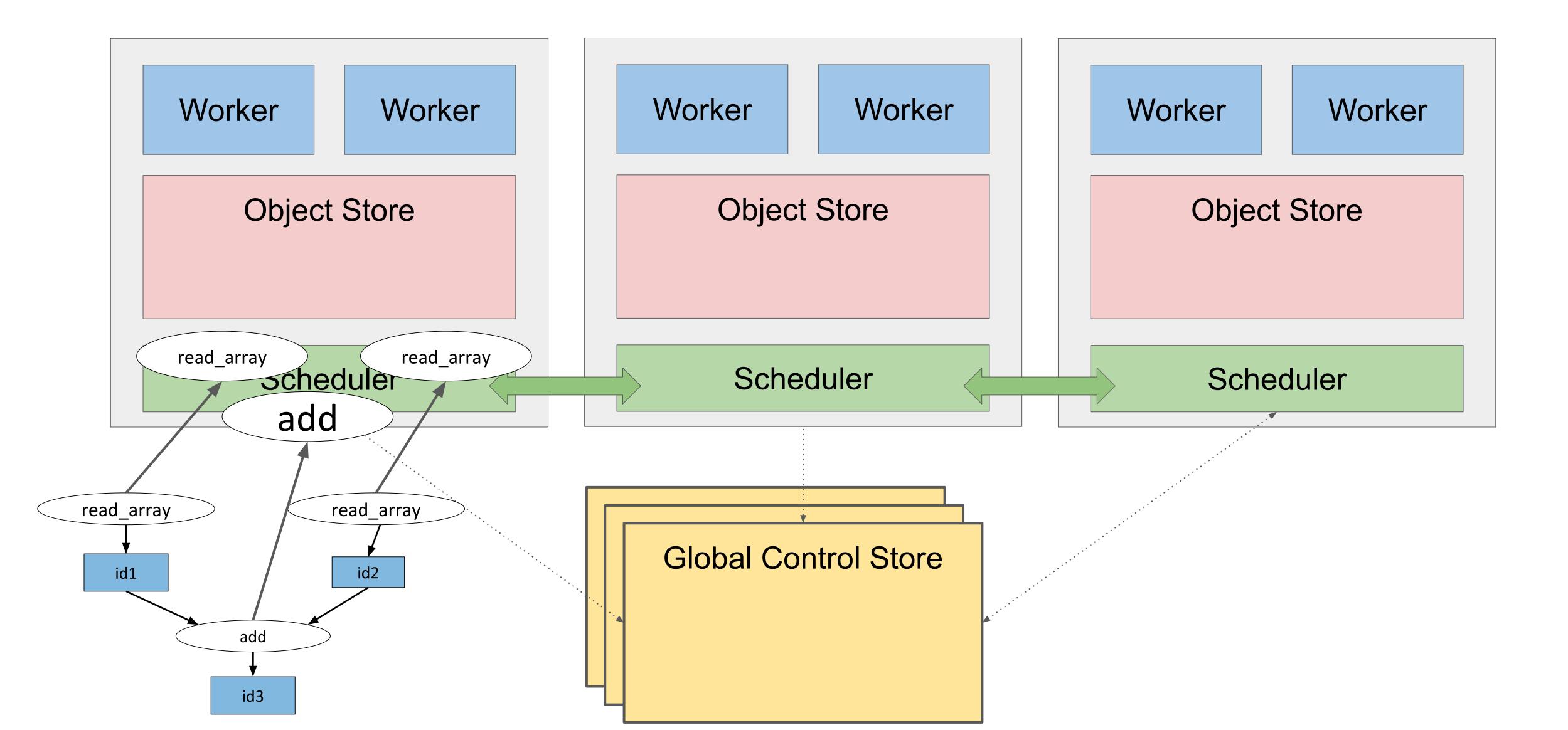


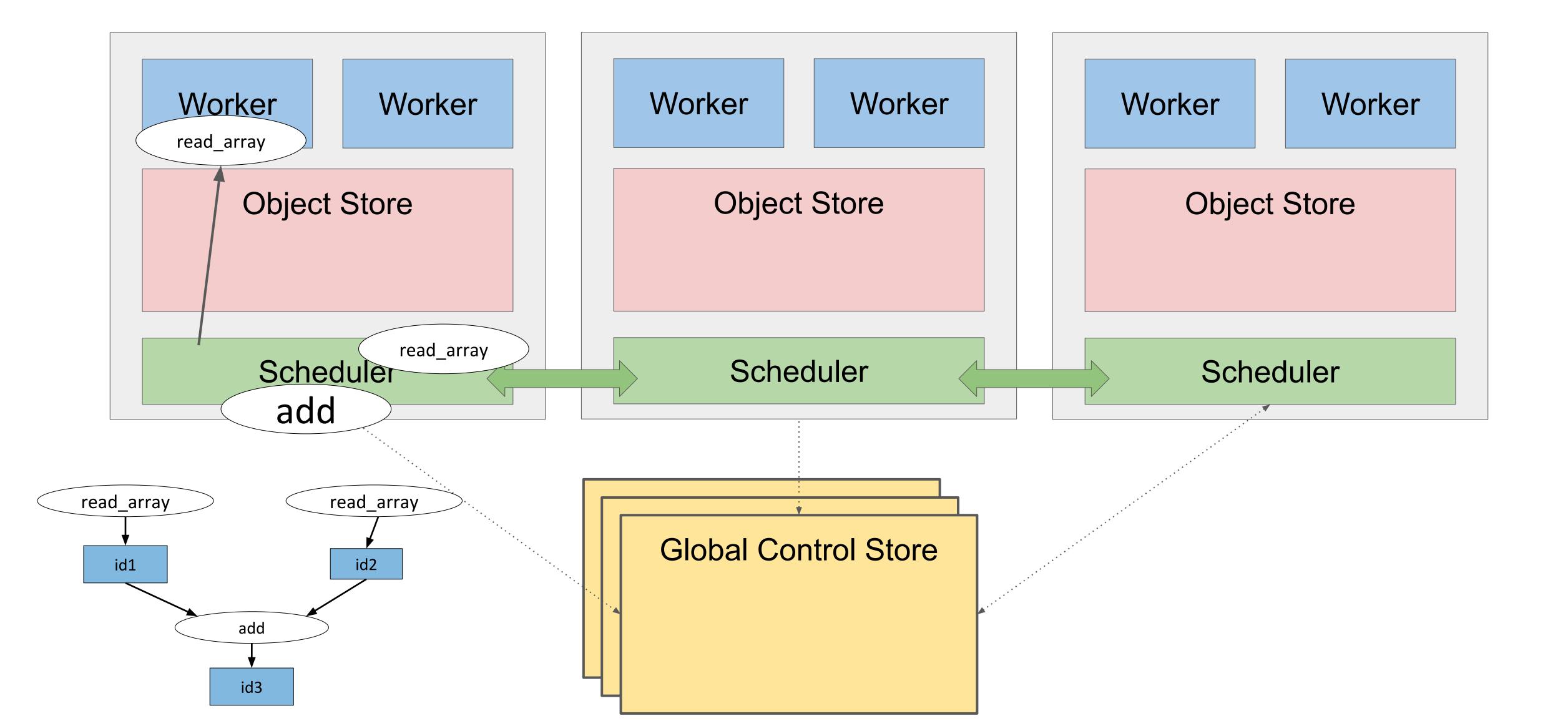
#### How does this work under the hood?

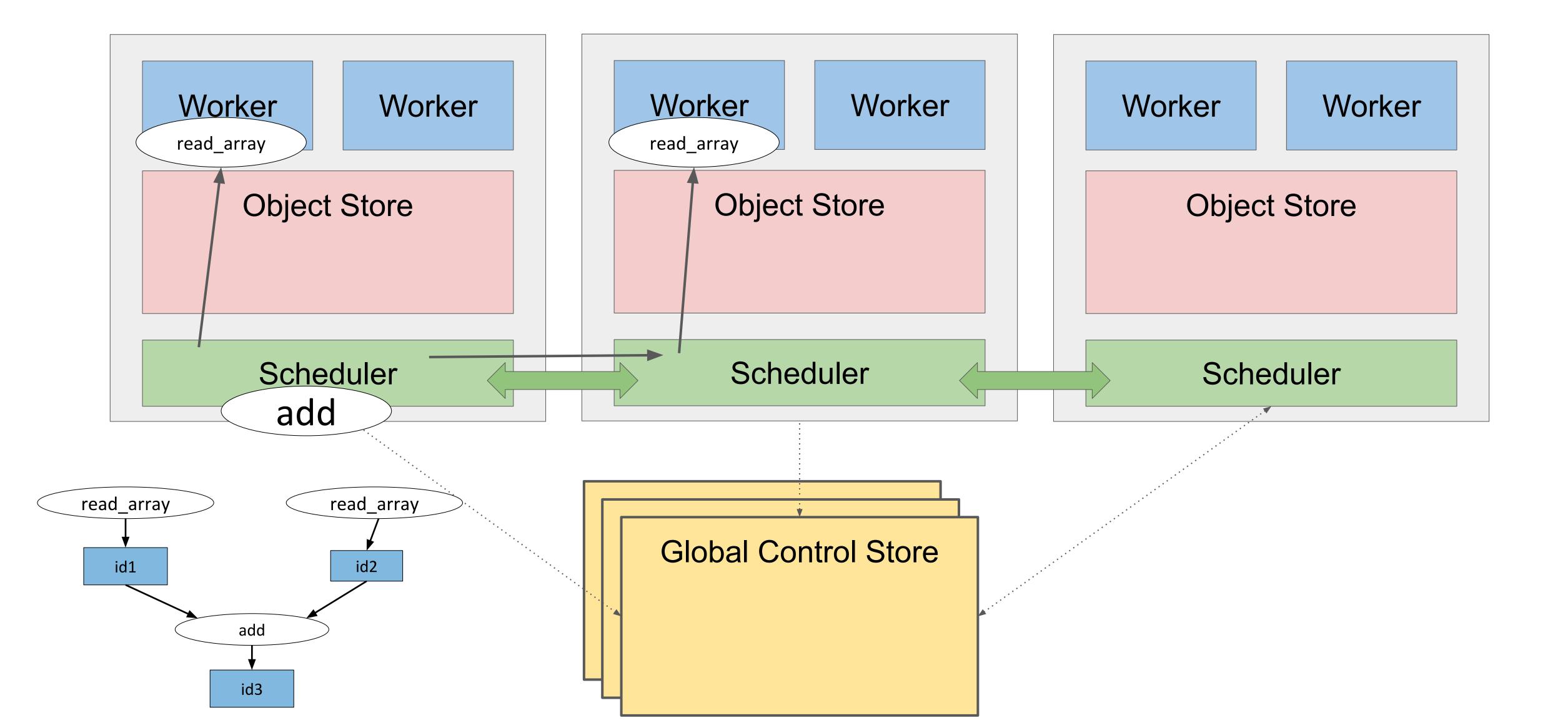


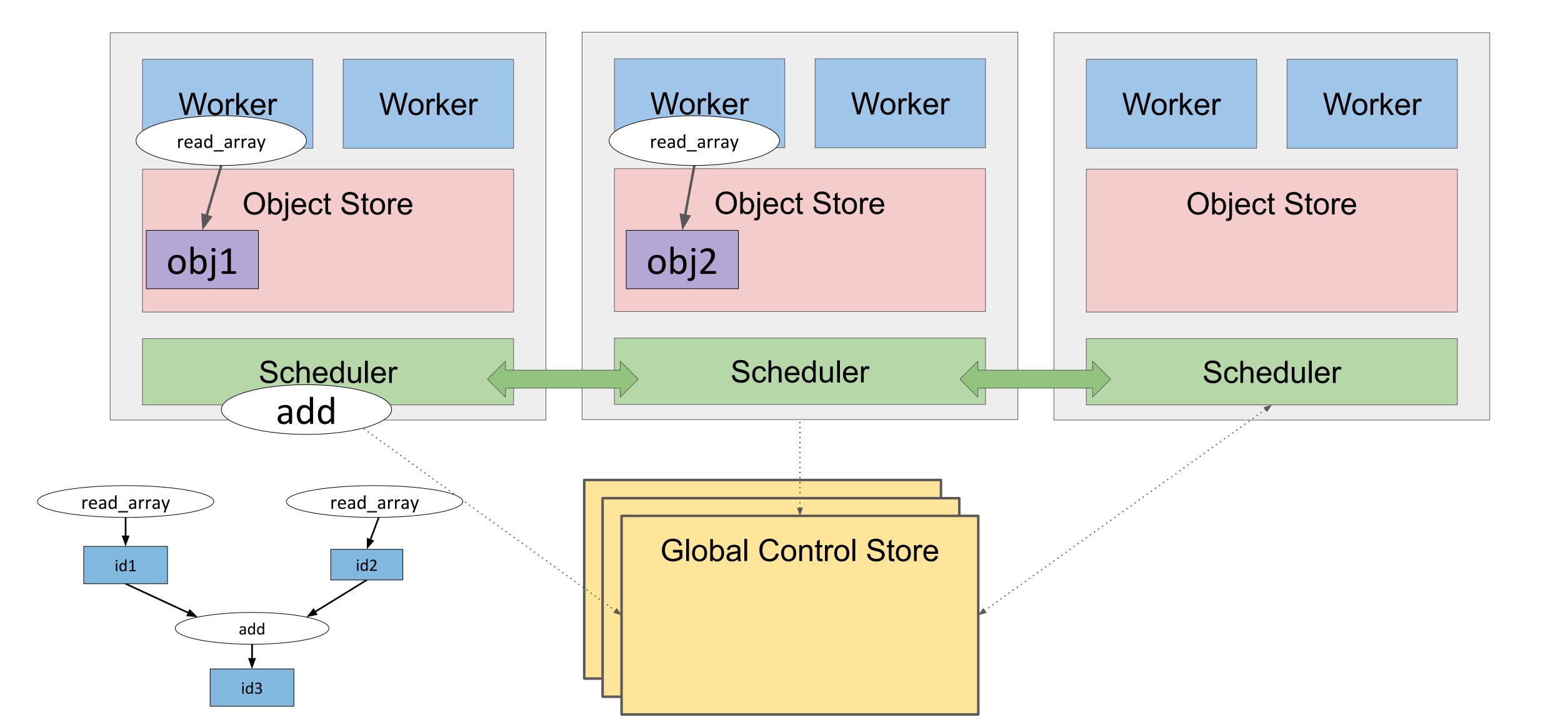


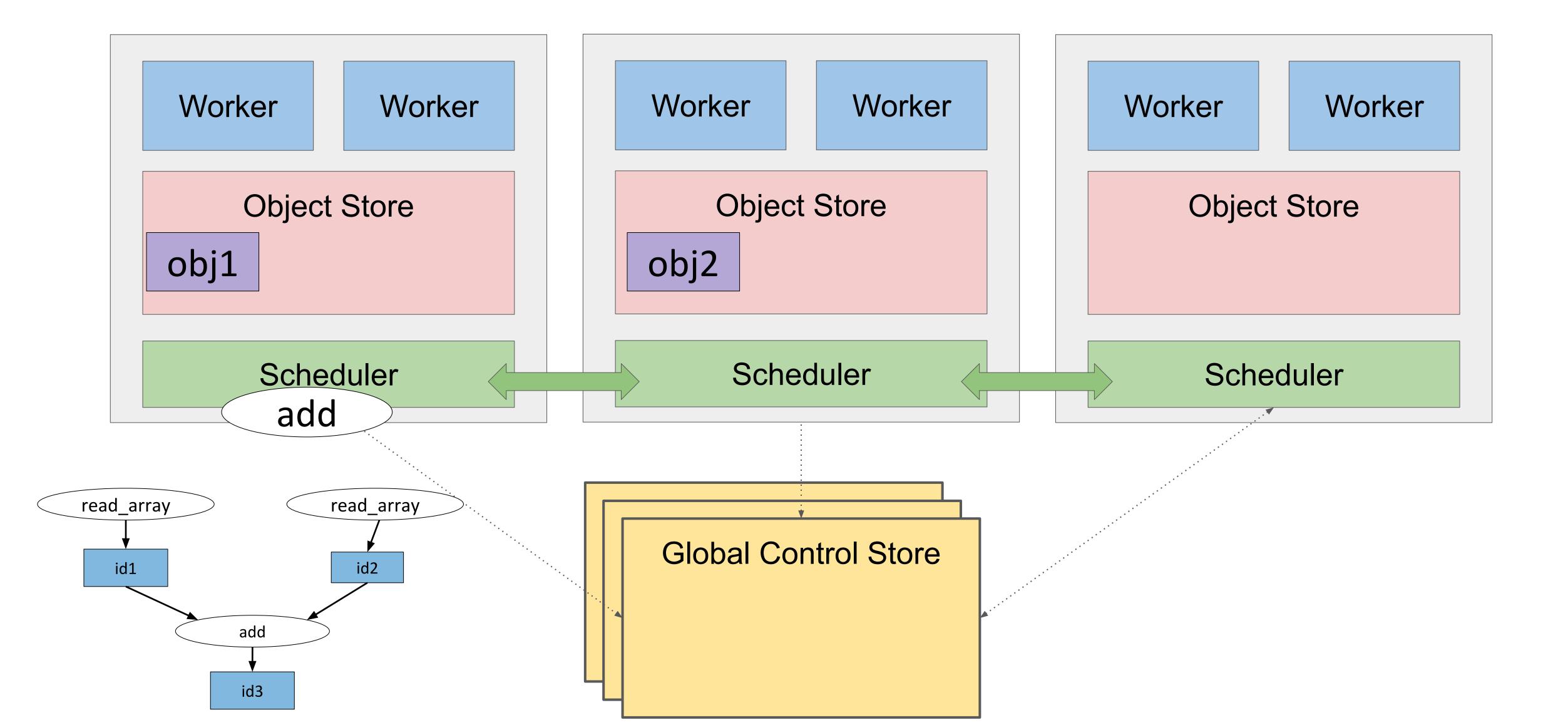


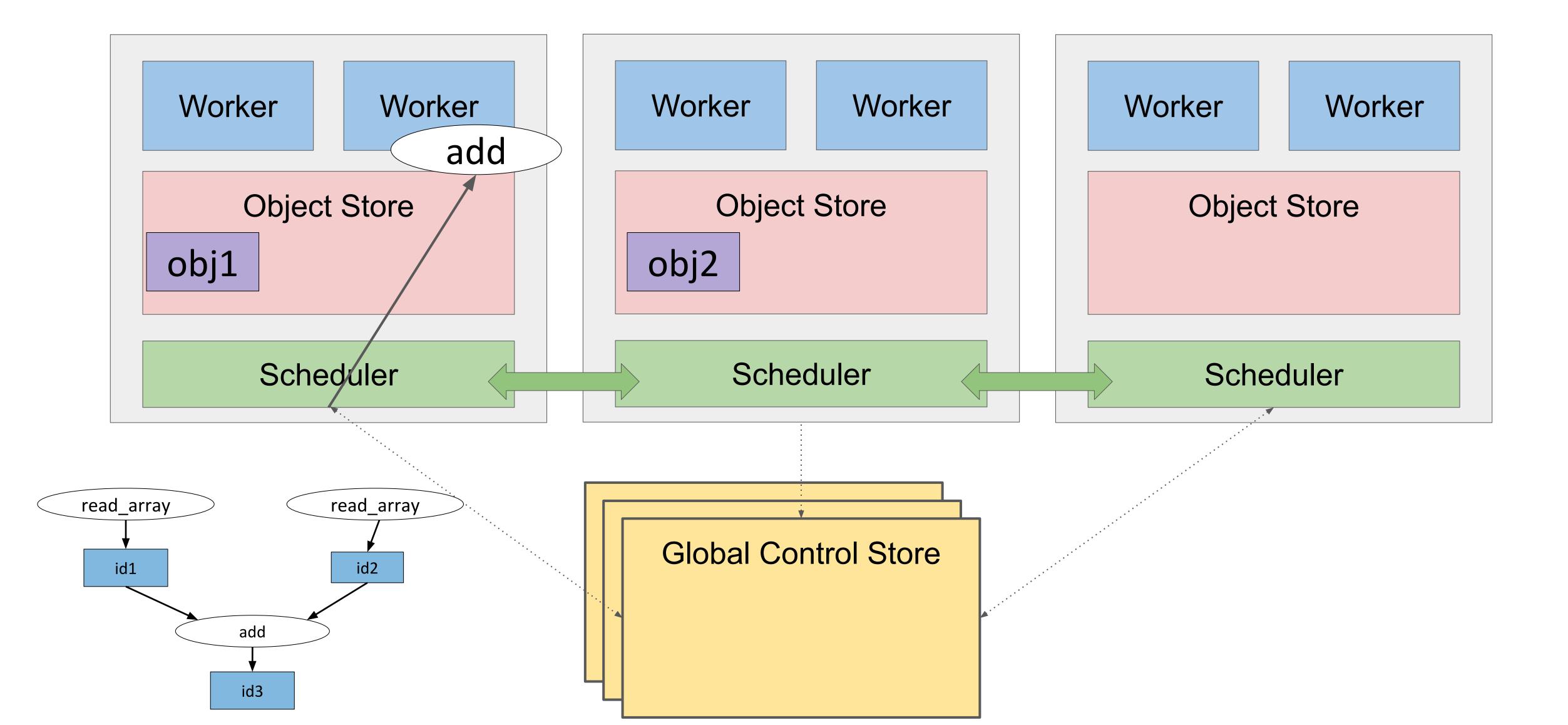


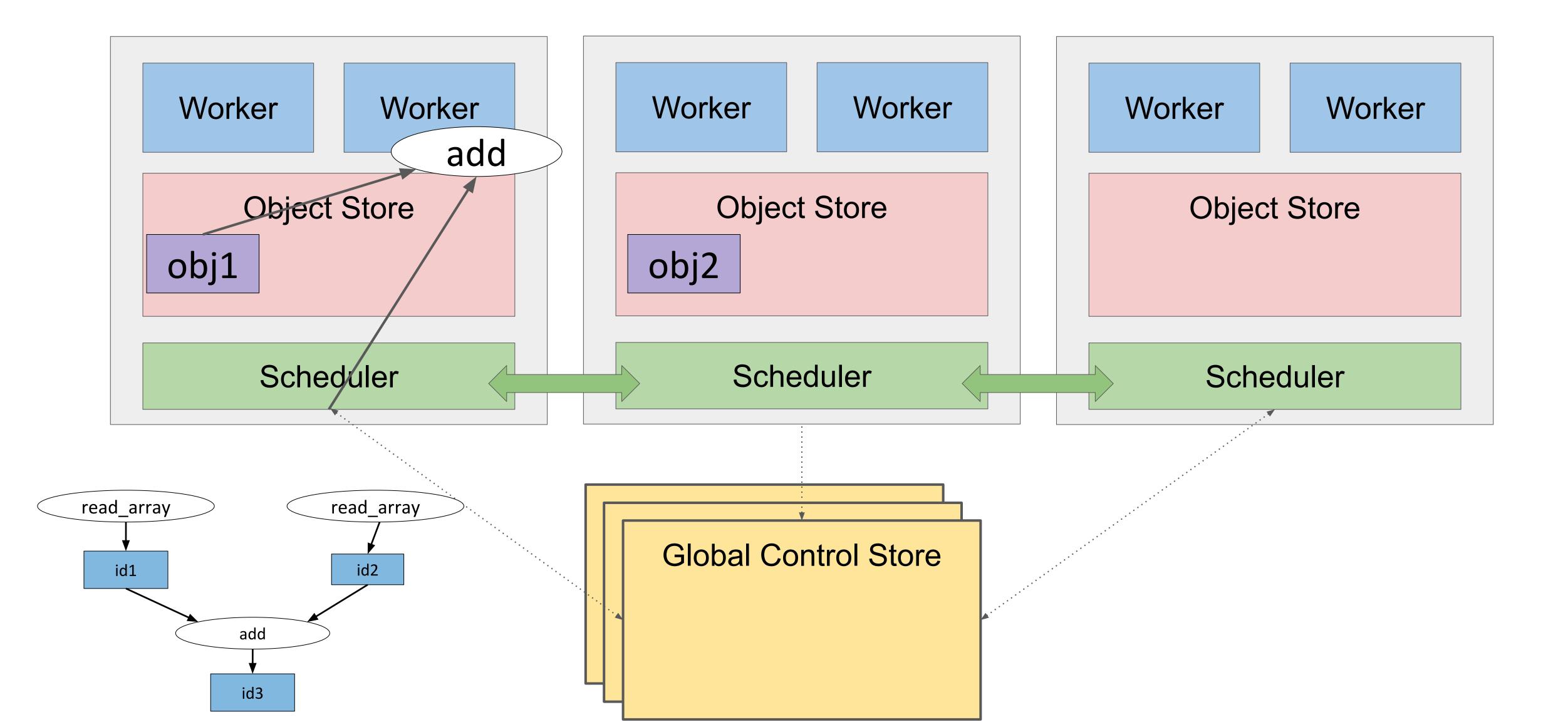


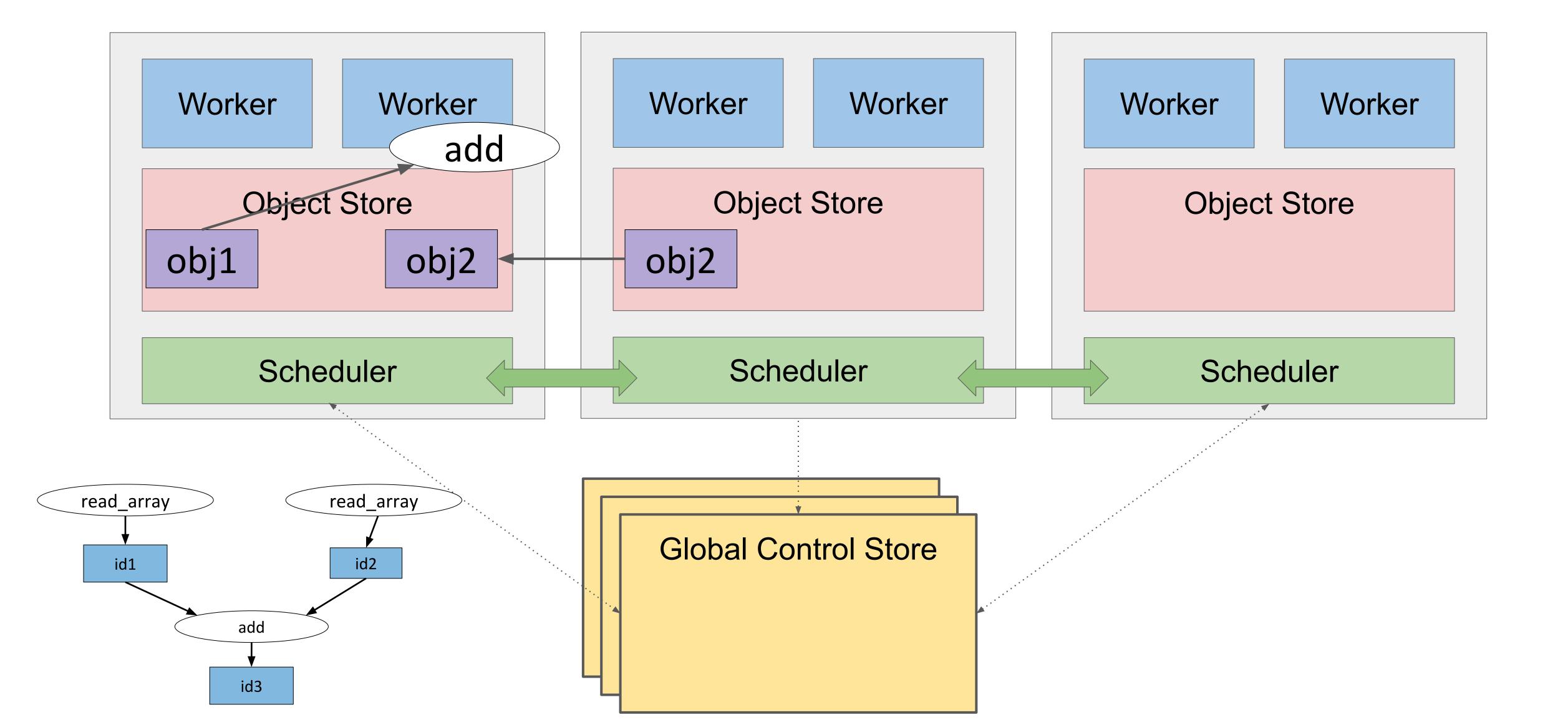


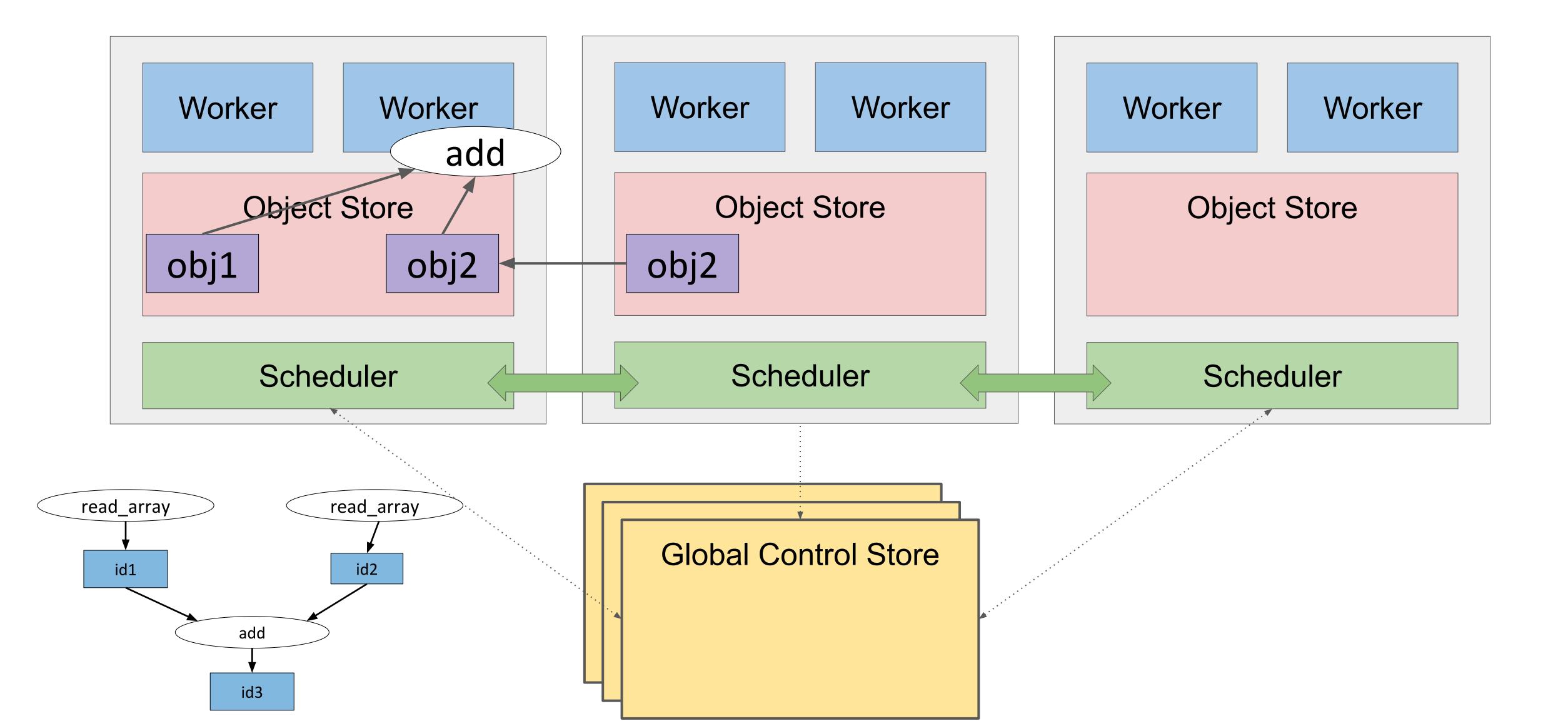


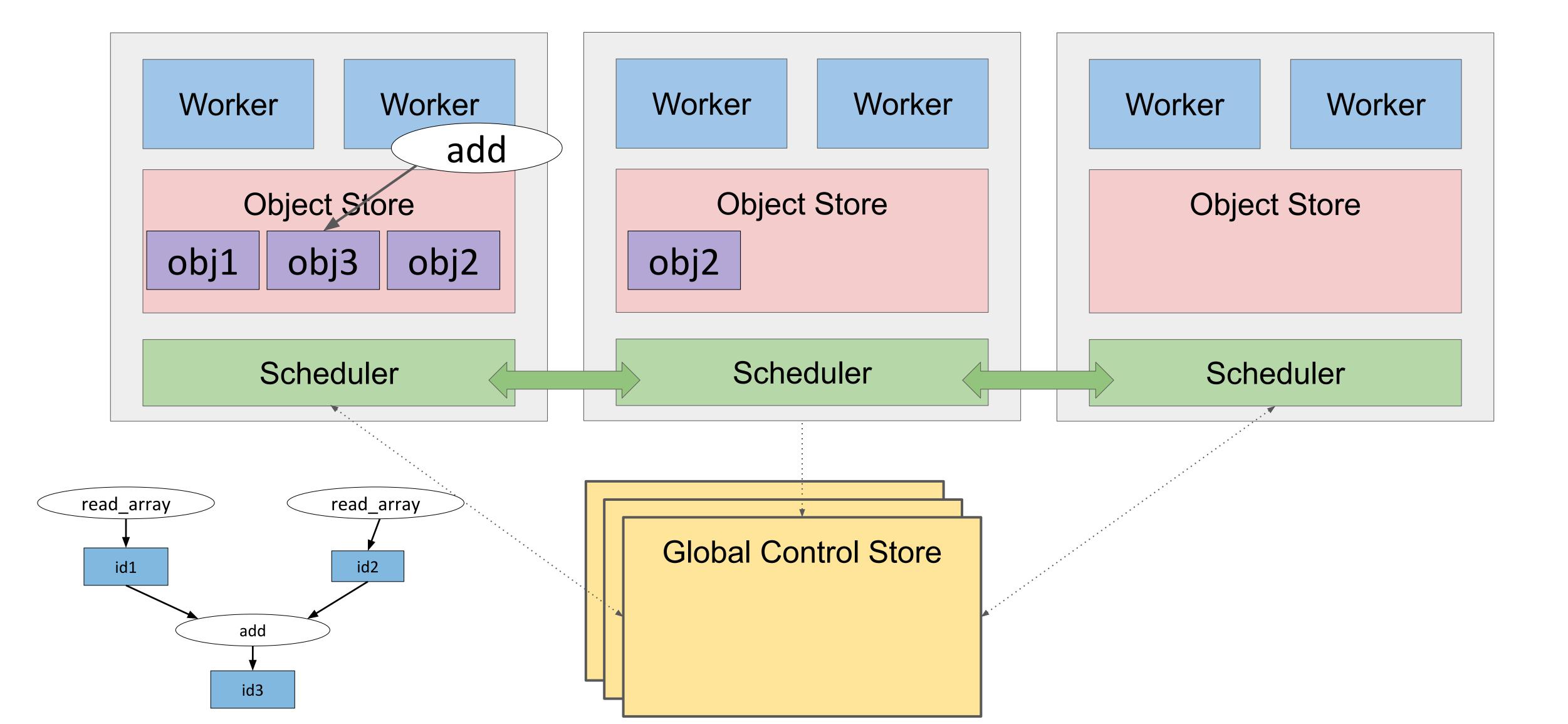


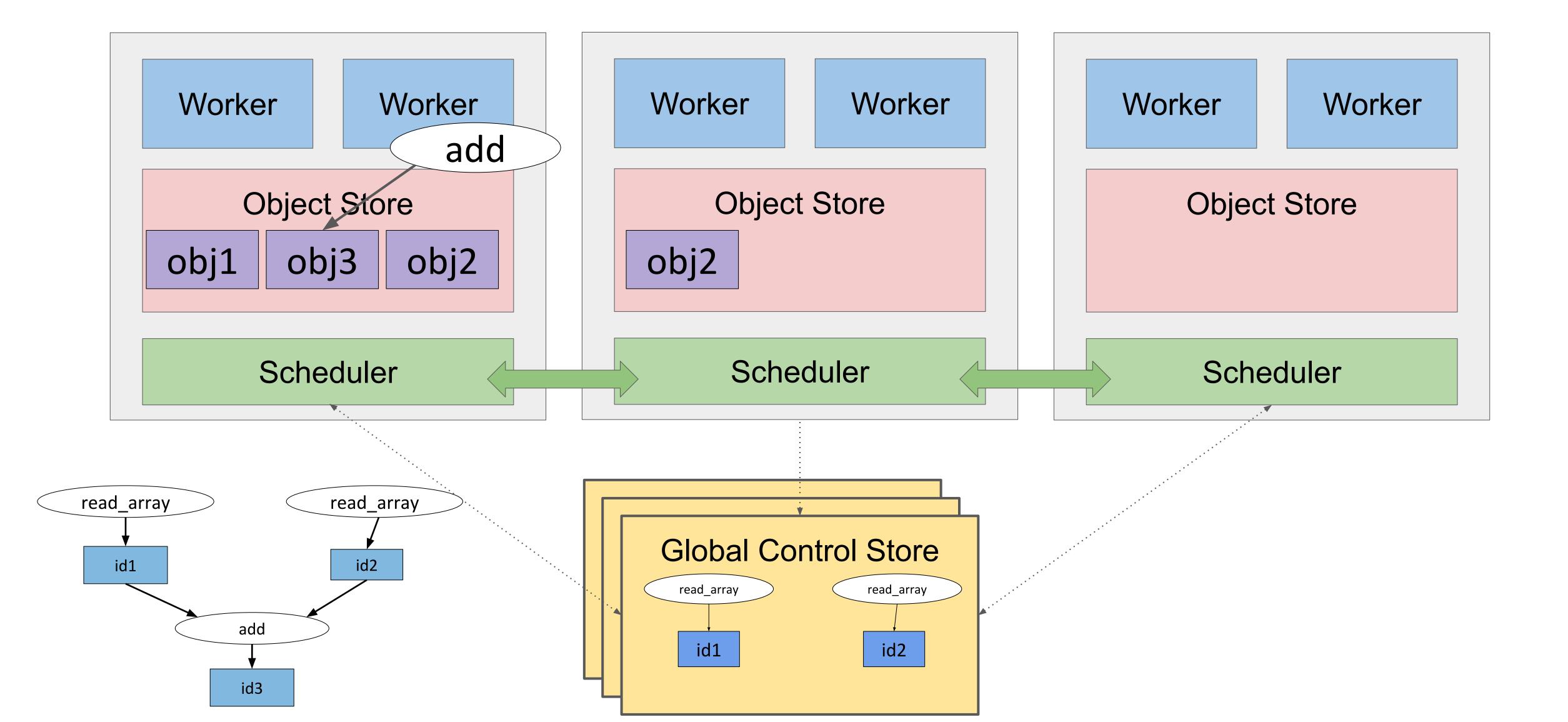












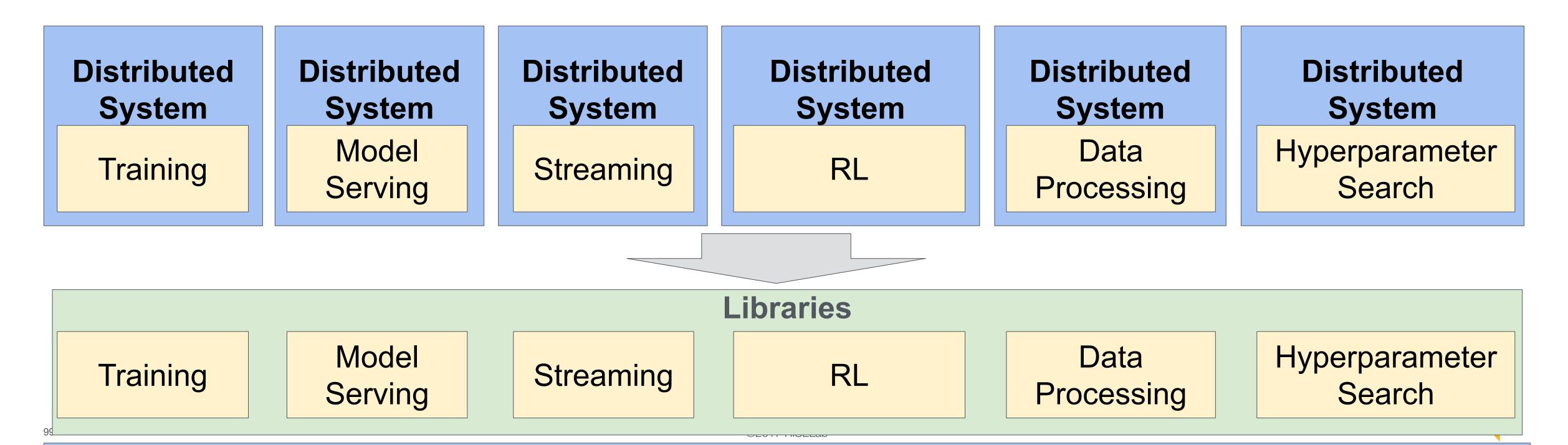
#### Conclusion

- · Ray is an open source project for distributed computing
- special-purpose distributed systems -> general-purpose distributed system
- Support for the full ML lifecycle (data collection, training, simulation, serving)



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Distributed System (Ray)