Trevor Sherrard
Resume

CONTACT ME

30 Colony Manor Drive Rochester, New York

☎ +1 (440) 799-2705

✉ sherrardtr@gmail.com

⚡ www.trevorsherrard.com

WORK EXPERIENCE

NOVEMBER 2014 – JULY 2015

Cuyahoga Community college

Physics Student Lab Assistant

Responsibilities included taking down and setting up labratory experiments for earth science and physics classes. Also assisted professors during the lab with answering students' questions about the material at hand.

JUNE 2012 – JULY 2015

Saint Edward High School

Engineering camp Instructor

Worked the summers of 2012, 2013, 2014 and 2015. Helped promote interest in STEM related fields, specifically robotics and computer science, to middle school students. Duties included material procurement and classroom instruction.

EDUCATION

2009 – 2013 **Saint Edward High School**
HIGH SCHOOL DIPLOMA
Lakewood, ohio

2014 – 2015 **Cuyahoga Community College**
COMMUNITY COLLEGE
Parma, ohio

2015 – PRESENT **Rochester Institute of Technology**
B.S ELECTRICAL ENGINEERING WITH A FOCUS IN ROBOTICS
Henrietta, New York

ROBOTICS PROJECTS

2014 **SortME (Link)**
The Computer Vision Robot Platform

2015 **RoveME (Link)**
My Large scale, built from scratch ROS robot. Built from a basic andymark differential drive robot chasis, RoveME is my personal robotics testbed.

2015 **ToolID (Link)**
Automatic tool identification for the computer science house project room. Allows user to query the type of tool using computer vision and haar classifiers. A laser diode on a two axis stepper motor gimbal will then point to where that tools resting location is.

COMPUTER VISION PROJECTS

2014 **Haar Training Tutorial Web Page (Link)**
A tutorial I wrote on how to train HAAR classifiers using OpenCV. It covers eveything from sample preperation to training itself.

2015 **Mobile Haar tester application (Link)**
A application that uses the OpenCV on the android platform to test mobile classifiers on the go. It allows for downloading of classifier on the go from a URL.

SOFTWARE SKILLS

ADVACNED LEVEL	C++, python, ROS (Robot Operating System), OpenCV
INTERMEDIATE LEVEL	PCL (point cloud library), LaTeX, OpenCV CUDA acceleration
BASIC LEVEL	Torch, Caffe