

$$\begin{aligned}
&_{nonlinearmodel}\left\{\begin{array}{l} \dot{x}=f(x)+G\tau \\ y=h(x) \end{array}\right. \\
&\left\{\begin{array}{l} \dot{x}_{\delta}=f_{\delta}\left(x_{\delta}, \delta_c\right) \\ \delta=h_{\delta}\left(x_{\delta}\right) \end{array}\right._{eq; ntrovsys \in} \\
&R^n \tau y \in \\
&R^m \delta \in \\
&\Omega \subset \\
&R^p \\
&G \in \\
&R^m f: \\
&R^n \rightarrow \\
&R^n g: \\
&R^n \times \\
&R^p \rightarrow \\
&R^n h: \\
&R^n \rightarrow \\
&R^m \rightarrow \\
&R^a tuacor_{\delta} \in \\
&R^q \delta_c \in \\
&\Omega \\
&f_{\delta}: \\
&R^q \rightarrow \\
&R^q h_{\delta}: \\
&R^q \rightarrow \\
&R^p \tau \in \\
&\Phi \subset \\
&R^m m< \\
&P \\
&\tau=\overline{M(x, \delta)} \\
&M: \\
&R^n \times \\
&R^p \rightarrow \\
&R^m m \tau \\
&\Omega R^p \Omega \delta M R^p R^m \Phi \tau \in \\
&\Phi \tau \\
&_{ ntrovsys \tau_c \in} \\
&R^m_{\tau_c \tau_{c e f f e t o r_m o d e l e q_a t u a c o r \delta_c} \in} \\
&\Omega \tau_{\tau_{c i} ntrovsys} \\
&\delta \delta_{0 e f f e t o r_m o d e l \delta_0} \\
&\tau=\overline{B\left(\delta-\delta_0\right)+} \\
&\tau_0 \\
&\tau_0 M\left(x, \delta_0\right) \\
&B \partial \tau \partial \delta=\left[\begin{array}{l} \partial \tau_1 \partial \delta_1 \quad \partial \tau_1 \partial \delta_2 \cdots \partial \tau_1 \partial \delta_p \\ \partial \tau_2 \partial \delta_1 \quad \partial \tau_2 \partial \delta_2 \cdots \partial \tau_2 \partial \delta_p \\ \partial \tau_m \partial \delta_1 \partial \tau_m \partial \delta_2 \cdots \partial \tau_m \partial \delta_p \end{array}\right] \\
&B \in \\
&R^{m \times p} B \tau_0 ? \delta_0 \tau_0 \delta_{0 t} a y l e r e q_e f f e t o r_m o d e l \\
&\delta) B \tau_{0 t} a y l e r \tau= \\
&B \delta+ \\
&\eta= \\
&\tau_0- \\
&B \delta_0 \tau= \\
&\tau_c- \\
&\eta= \\
&\tau=\overline{B \delta} \\
&_{i n e a r_m o d e l} \\
&\delta_{c a} t u a c o r \delta= \\
&\delta_c \delta \quad \tau= \\
&\tau_c- \\
&\eta B \Omega \delta \tau= \\
&B \delta \delta \in \\
&\Omega_{i n e a r_m o d e l} \\
&\tau \delta ?? \\
&\Omega R^p \\
&\delta \delta_{1, \min } \delta_{2, \min } \delta_{p, \min } \bar{\delta}=\delta_{1, \max } \delta_{2, \max } \delta_{p, \max }, \delta=\delta_1 \delta_2 \delta_p \\
&\frac{\nabla i}{1,2, \ldots, p \delta_{i, \min }} \leq \\
&\delta_i \leq \\
&\delta_{i, \max } \delta \leq \\
&\delta \leq \\
&\bar{\delta} \\
&\Omega= \\
&\left\{\delta|\bar{\delta} \leq \delta \leq \bar{\delta}\right\} \\
&_{i n e a r_m o d e l} A M S A M S e q_{i n e a r_m o d e l}[?] \delta_0 T u_m \\
&m \leq \\
&\delta- \\
&\delta_0 \leq \\
&T u_m \\
&\bar{\delta}'= \\
&\min \left\{\bar{\delta}-\delta_0, T u_m\right\} \\
&\delta'= \\
&\max \left\{\bar{\delta}-\delta_0,-T\right\} \\
&\Delta \delta= \\
&\delta- \\
&\delta_0 \\
&\Omega=
\end{aligned}$$