

# Tutorial 11

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## 1 Orientable Manifolds

We want to integrate  $k$  forms on the  $k$  manifold  $M$ . If there is only a single coordinate chart  $\alpha : U \rightarrow V$ , define

$$\int_M \omega = \int_{\text{Int}(U)} \alpha^* \omega$$

**Definition 1.1.** Let  $g : A \rightarrow B$  be a diffeomorphism of open sets in  $\mathbb{R}^k$ . We say  $g$  is orientation preserving if  $\det Dg > 0$ . Otherwise, it is orientation-reversing.

Associated there is a linear transformation

$$g_* : T_x(\mathbb{R}^k) \rightarrow T_{g(x)}(\mathbb{R}^k)$$

**Definition 1.2.** Let  $M$  be a  $k$  manifold in  $\mathbb{R}^n$  with coordinate patches  $\alpha_i : U_i \rightarrow V_i$  on  $M$ . If  $M$  can be covered by a collection of coordinate charts such that each  $V_i \cap V_j \neq \emptyset$ , we have  $\alpha_i^{-1} \circ \alpha_j$  is orientation-preserving, then we say  $M$  is orientable. Otherwise it is non-orientable.

**Definition 1.3.** Given a collection  $A$  of orientation preserving coordinate charts for  $M$ , extend this collection to all coordinate charts  $\beta$  such that  $\beta^{-1} \circ \alpha$  is orientation preserving  $\forall \alpha \in A$ . This extended collection defines an orientation on  $M$ . A manifold  $M$  together with orientation is called an orientation manifold.

**Definition 1.4.** Let  $M$  be a  $(n-1)$  manifold in  $\mathbb{R}^n$ . If  $p \in M$ , let  $(p; n)$  be a unit vector in the  $n$  dimensional vector space  $T_p(\mathbb{R}^n)$  that is orthogonal to the subspace  $T_p(M)$ . So  $n$  uniquely determined up to sign. Given orientation of  $M$ , choose coordinate patch  $\alpha : U \rightarrow V$  on  $M$  about  $p$  belong to this orientation; let  $\alpha(x) = p$ . Then  $\frac{\partial \alpha}{\partial x_i}$  is a basis for  $T_p(M)$ . So  $(n \ D\alpha(x))$  gives a basis for  $T_p(\mathbb{R}^n)$  and we take  $n$  such that its determinant is positive.

**Example 1.1** (Non Orientable Manifolds). Möbius strip.

**Definition 1.5.** Let  $M$  be an  $n$  manifold in  $\mathbb{R}^n$ . If  $\alpha : U \rightarrow V$  is a coordinate chart on  $M$  then  $D\alpha$  is an  $n \times n$  matrix. Define natural orientation on  $M$  to be all coordinate chart where  $\det D\alpha > 0$ .

To check this,  $M$  may be covered by such coordinate charts. Given  $p \in M$ , let  $\alpha : U \rightarrow V$  be a coordinate patch about  $p$ , with  $U$  open in  $\mathbb{R}^n$  or  $\mathbb{H}^n$ . WLOG  $U$  is connected, so  $\det D\alpha$  is either positive or negative on all of  $U$ . If positive, then  $\alpha$  is our coordinate chart. Else,  $\alpha \circ r$  is our coordinate chart, where  $r$  is the reflection

$$r(x_1, \dots, x_n) = (-x_1, \dots, -x_n)$$

## 2 Induced Orientation of $\partial M$

**Theorem 2.1.** Let  $k > 1$ . If  $M$  is an orientable  $k$  manifold with nonempty boundary, then  $\partial M$  is orientable.

*Proof.* Let  $p \in \partial M$ . Let  $\alpha : U \rightarrow V$  be a coordinate patch about  $p$ . There is a corresponding coordinate patch  $\alpha_0$  on  $\partial M$  that is said to be obtained by restricting  $\alpha$ . Formally, define  $b : \mathbb{R}^{k-1} \rightarrow \mathbb{R}^k$  by the equation

$$b(x_1, \dots, x_{k-1}) = (x_1, \dots, x_{k-1}, 0)$$

Then  $\alpha_0 = \alpha \circ b$ . We show that if  $\alpha, \beta$  are such that  $\det D(\beta^{-1} \circ \alpha) > 0$ , then so is their restrictions. Let  $g : W_0 \rightarrow W_1$  be the transfer function. Then  $\det Dg > 0$ . Now if  $x \in \partial \mathbb{H}^k$  then the derivative  $Dg$  at  $x$  has the last row  $Dg_k = \begin{pmatrix} 0 & 0 & \frac{\partial g_k}{\partial x_k} \end{pmatrix}$  where the last element is positive. Changing  $x_1, \dots, x_{k-1}$  by a little does not change the value of  $g_k$ . But increasing  $x_k$  a little changes value of  $g_k$  non-negatively, so  $\frac{\partial g_k}{\partial x_j} = 0$  for  $j < k$  and  $\frac{\partial g_k}{\partial x_k} > 0$ .  $\square$

**Definition 2.1.** Let  $M$  be an orientable  $k$  manifold with nonempty boundary. Given orientation of  $M$ , the corresponding orientation is: if  $k$  is even, orientation is given by restrictions, else we restrict the opposite orientation.