## Lecc

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March 25, 2024

## 1 Dual Transformations

Recall for  $T: V \to W, b \in \Omega^l(W)$ , we define

$$T^*b(v_1,\ldots,v_l)=b(Tv_1,\ldots,Tv_l)$$

Similarly,

$$\alpha_*(x;v) = (\alpha(x), D\alpha \cdot v)$$

This gives the general transformation

$$\alpha^*\omega(x;v_1,\ldots,v_l)=\omega(\alpha(x);\alpha_*(x,v_1),\ldots,\alpha_*(x,v_l))$$

This preserves linear and wedge structure, as one can easily verify. Now we want to show that this commutes with d. By linearity, we need only show this for elementary  $dx_i$  or  $dx_I$ . For 1-forms,

$$\alpha^*(dx_i)(x;v) = dx_i(x)(\alpha_*(x;v))$$

$$= D\alpha(x)_i \cdot v$$

$$= \sum_j D_j \alpha_i(x) v_j$$

$$= \sum_j \frac{\partial \alpha_i}{\partial x_j} dx_j(v)$$

$$\alpha^*(dx_i) = \sum_j \frac{\partial \alpha_i}{\partial x_j} dx_j$$

$$= d\alpha_i$$