4.2 Elastic Deformation of an Axially Loaded Member

Here we wish to find the relative displacement (delta) of one end of the bar with respect to the other end as caused by this loading.

Using the method of sections, a differential element (or wafer) of length dx and cross-sectional area A(x) is isolated from the bar at the arbitrary position x. The stress and strain in the element are

$$\frac{\nabla P(x)}{A(x)} \text{ and } (\epsilon) = \frac{d\delta}{dx}$$

Provided the stress does not exceed the proportional limit, we can apply Hooke's law;

$$\begin{array}{c}
\sigma = E(x)e \\
\frac{P(x)}{A(x)} = E(x) \begin{pmatrix} d\delta \\ dx \end{pmatrix}
\end{array}$$

$$\begin{array}{c}
P(x)d\delta \\
F(x)d\delta
\end{array}$$

 $\delta =$ displacement of one point on the bar relative to the other point

L = original length of bar P(x) = internal axial force at the section, located a distance x from one end

A(x) = cross-sectional area of the bar expressed as a function of x

E(x) = modulus of elasticity for the material expressed as a function of x.



mal Area. In many cases the bar will have a constant cross-sectional area A; and the material will be homogeneous, so E is constant. the internal force P throughout the length of the bar is also constant.

$$\delta = \frac{PL}{AE}$$
 (4-2)

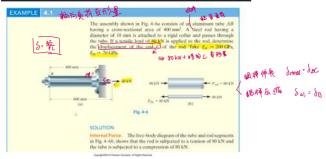
If the bar is subjected to several different axial forces along its length, or the cross-sectional area or modulus of elasticity changes abruptly from one region of the bar to the next, the above equation can be applied to each seg nent of the bar where these quantities remain

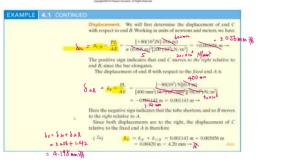


Sign Convention. we will consider both the force and displacement to be positive if they cause tension and elongation, respectively, Fig. 4-4; whereas a negative force and displacement will cause ompression and contraction, respectively.





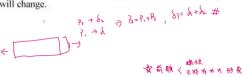


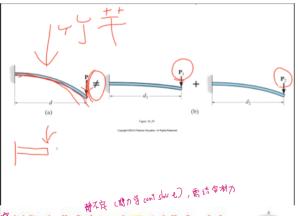


4.3 Principle of Superposition 量力。 定理

The following two conditions must be satisfied if the principle of superposition is to be applied.

- 1. The loading must be linearly related to the stress or displacement that is to be determined. For example, the equations $\sigma = P/A$ and $\delta = PL/AE$ involve a linear relationship between P and σ or δ .
- 2. The loading must not significantly change the original geometry or configuration of the member. If significant changes do occur, the direction and location of the applied forces and their moment arms will change.



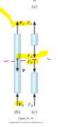


4.4 Statically Indeterminate Axially Loaded Member

Consider the bar shown in Fig. 4-10a which is fixed supported at both of its ends. From the free-body diagram, Fig. 4-10b, equilibrium requires

$$+\uparrow\Sigma F=0; \qquad F_B+F_A-P=0$$

This type of problem is called statically indeterminate, since the equilibrium equation(s) are not sufficient to determine the two reactions on the bar.



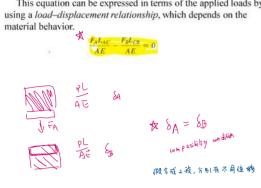
In order to establish an additional equation needed for solution, it is necessary to consider how points on the bar displace. Specifically, an equation that specifies the conditions for displacement is referred to as a compatibility or kinematic condition. Hence, the compatibility condition becomes

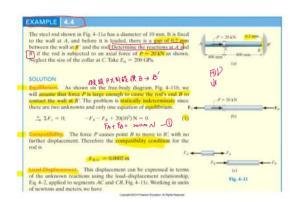
 $\delta_{A/B} = 0$ This equation can be expressed in terms of the applied leads by

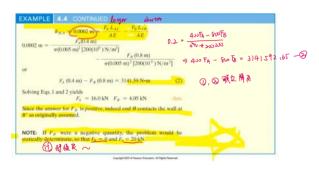
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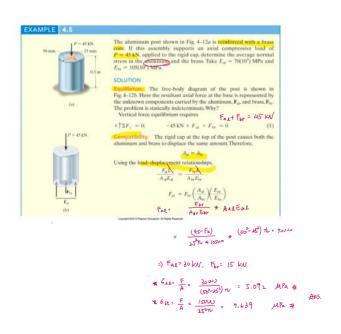
 $\delta_{A/B} = 0$

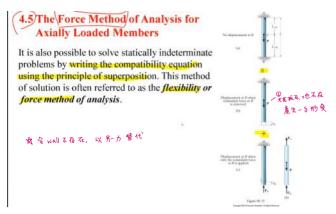
This equation can be expressed in terms of the applied loads by using a load-displacement relationship, which depends on the

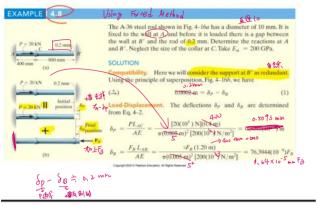


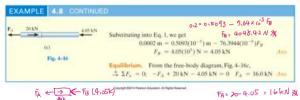






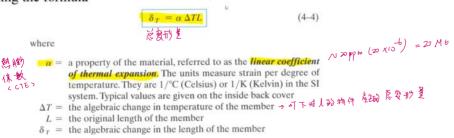




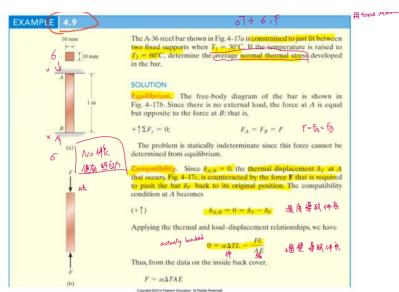


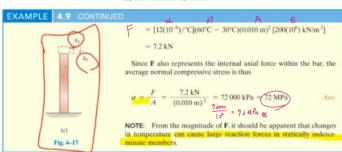
4.6 Thermal Stress . 熱應t e

A change in temperature can cause a body to change its dimensions. Generally, if the temperature increases, the body will expand, whereas if the temperature decreases, it will contract. Ordinarily this expansion or contraction is *linearly* related to the temperature increase or decrease that occurs. If this is the case, and the material is homogeneous and isotropic, it has been found from experiment that the displacement of a member having a length L can be calculated 8720 using the formula

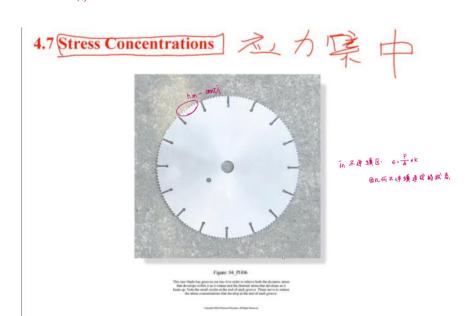


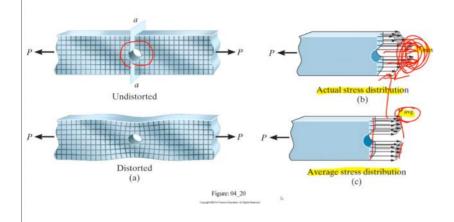
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F= 2 STAT SMPN &



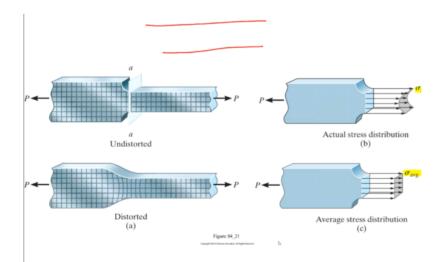


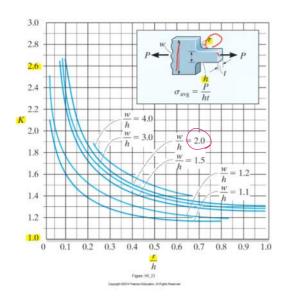
In both of these cases, *force equilibrium* requires the magnitude of the *resultant force* developed by the stress distribution to be equal to P. In other words,

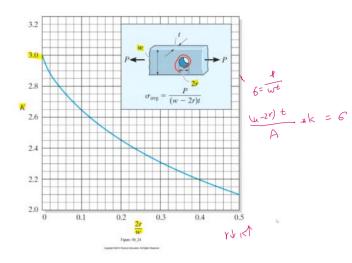
 $P = \int_A \sigma \, dA$

This integral *graphically* represents the total *volume* under each of the stress-distribution diagrams shown in Fig. 4–20b or Fig. 4–21b. The resultant **P** must act through the *centroid* of each *volume*. The results of these investigations are usually reported in graphical form using a *stress-concentration factor K*. We define K as a ratio of the Maximum stress to the average normal stress acting at the eross section; i.e.,

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• 4-5, 8, 15, 23, 35, 37, 59, 70, 89