## HULTIPLE LINEAR RECIRESSION

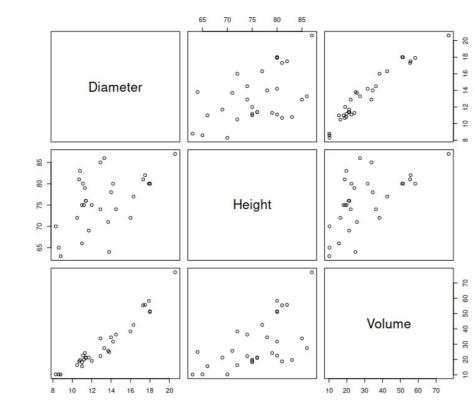
There are now p>1 covoriates x2,..., xp.

Example: "trees" R dateset contains date on 31 cherry trees. In particular, we have

-diemeter (inches) -height (feet)

- volume

With 3 or more voriables we can no congen visualize the relationship with a scatterplat, We have to use a "matrix of scatterplats" which shows all the PAIRWIST combinations.



We could use a linear model volume: =  $\beta_1 + \beta_2$  diameter: +  $\beta_3$  height: + E:

The good is to product the volume given the other 2 measures

However, in this case, we obtain a better fit if we consider a transformation of the covariates.

If we think at the shape of a true, we could think of approximating it to a cyclinder

+ NOT LINEAR

= 
$$\pi$$
·  $(d/2)^2$ · height

Hence we could specify a model where volume:  $\approx \pi$ ·  $(\frac{diameteri}{2})^2$ · height;

volume = TC · radius 2 · height

log (volume: ) ≈ log  $\pi$  + log  $\pi$  + log (diameter: ) + log (height: )

We can consider the transformed variables Y= log (volume)

log(Diameter)

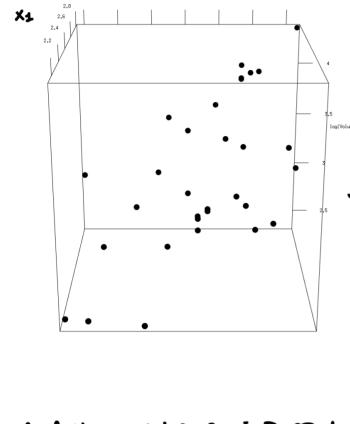
X2 = Og (height)

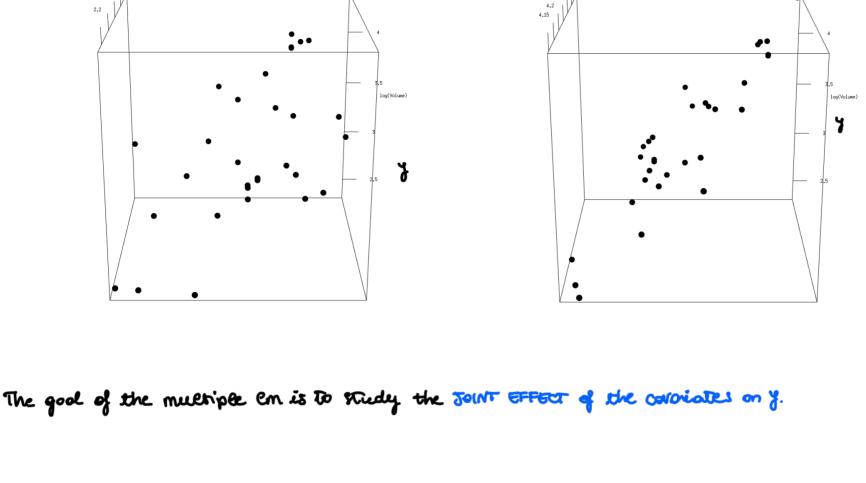
However, the relationship can be cinemized

X1 = Rog (diameter)

Χī XZ X1

only in the case of two convoicites we can still see the joint effect using a 30 representation





We now observe (yi, xiz, xiz,..., xij, ... xip) for i= 4,...,n. response variable p covariates

## Define the model 4 = jui + &i

KODEL SPECIFICATION

= B1 xin + B2 xin + ... + Bp xip + & i=1,..., n If we want to include the intercept, we define xis = 1 for all i = 1, ..., n (constant variable) and we obtain the model

Yi = P2 + B2 x in + ... + P3 xij + ... + P4 xip + &i

NOTATION :

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\begin{cases} Y_{1} = \beta_{1} \times x_{11} + \beta_{2} \times x_{12} + \dots + \beta_{j} \times x_{j}^{*} + \dots + \beta_{p} \times x_{p} + \delta_{4} \\ \vdots \\ Y_{i} = \beta_{4} \times x_{i1} + \beta_{2} \times x_{i2} + \dots + \beta_{j} \times x_{i}^{*} + \dots + \beta_{p} \times x_{p} + \delta_{4} \\ \vdots \\ \vdots \\ Y_{n} \end{cases} \Rightarrow Y = \begin{bmatrix} Y_{2} \\ \vdots \\ Y_{n} \\ \vdots \\ Y_{n} \end{bmatrix} \xrightarrow{\xi_{1}} \begin{bmatrix} \xi_{2} \\ \vdots \\ \xi_{n} \end{bmatrix}
\begin{cases} \xi_{2} \\ \vdots \\ \xi_{n} \end{bmatrix}
\begin{cases} \xi_{1} \\ \vdots \\ \xi_{n} \end{bmatrix}
\begin{cases} \xi_{2} \\ \vdots \\ \xi_{n} \end{bmatrix}
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\begin{cases} \xi_{2} \\ \vdots \\ \xi_{n} \end{bmatrix}
\begin{cases} \xi_{1} \\ \vdots \\ \xi_{n} \end{bmatrix}
                                       -> Y = β1 ×1 + ... + β × + ε
                                      => Y = [ ] | S + E
                                       \Rightarrow \frac{\mathbf{Y} = \mathbf{X} \mathbf{D} + \mathbf{E}}{\mathbf{n} \mathbf{x} \mathbf{p} \mathbf{p} \mathbf{x} \mathbf{1}} \quad \mathbf{n} \mathbf{x} \mathbf{1}
              where
              → ×j is the j-th covoriate (n-din reasor)
                                       observed on the n units
               __ Xi is the vector of the values
                                                                                                                                (p_dim rector)
                                       of the p covariates on the i-th unit
           and \underline{\beta} \in \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_p \end{bmatrix}
              Y is a vector of random voviables (nx1)
              X is a matrix of known constants
              B is a vector of unknown constants (px1)
              E is a vector of random voriables (nxx)
     The assumptions don't change (they one just adjusted for the general case)
(3) · normality, homoscedasticity, corr=0 → &: N(0,62) i=1,..., n
(2) · lincoity: li= P2xis+...+ Ppxip
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⇒ the information contained in ≥; can Not be derived from the other variables. Examples of collinearity: . the same variable is expressed using two measurement units (cm/m)

(3) · absence of multicollinearity of the x; : the covariates must be linearly INDEPENDENT

What is the meaning of this hypothesis on ×1,..., ×p (i.e., on the matrix X)?

· one variable is a linear combination of the others (e.g. Xx = total years of education; X2 = years of pre-university education;

ext's analyze the 3 hypotheses:

Looking now at our einear model

(3) ASSENCE OF KINTLICOLTY NEWSTY

 $x_3 = years of post-university education; <math>\Rightarrow x_1 = x_2 + x_3$ What happens when this hypothesis is not satisfied?

Q1 x1 + Q2 x2 + ... + QP xp = 0

This means that I can write the j-th voliable as:  $\Sigma_{i} = -\frac{a_{i}}{a_{i}} \times_{1} - ... - \frac{a_{i+1}}{a_{i}} \times_{j+1} - \frac{a_{j+1}}{a_{i}} \times_{j+1} - ... - \frac{a_{i}}{a_{i}} \times_{p}$  (\*)

Y= B x1 + B x2 + ... + Bj. xj. + Bj. xj + Bj. xj. + ... + B xp + &

by definition, it means that there are p scalars as,..., ap, not all zero, such that

Intuitively, it means that each covariable &j should have an individual contribution for predicting Y

Y = P1×1 + P2×2 + ... + P3 ×3 + F3 (- 20 ×1 - ... - 20 ×p) + ... + P ×p + 6  $= \left(\underbrace{\beta_{i} - \beta_{j} \cdot \frac{\alpha_{i}}{\alpha_{j}}}_{\beta_{i}^{*}}\right) \times_{1} + ... + \left(\underbrace{\beta_{j-1} - \beta_{j} \cdot \frac{\alpha_{j-1}}{\alpha_{j}}}_{\beta_{j-1}^{*}}\right) \times_{j-1} + \left(\underbrace{\beta_{j+1} - \beta_{j} \cdot \frac{\alpha_{j+1}}{\alpha_{j}}}_{\beta_{j}^{*}}\right) \times_{j+1} + ... + \left(\underbrace{\beta_{j} - \beta_{j} \cdot \frac{\alpha_{j}}{\alpha_{j}}}_{\beta_{j-1}^{*}}\right) \times_{p} + \underline{\varepsilon}$ 

 $\Rightarrow$  We can not have  $von(x_i) = 0$  for i = 2, ..., p

We can substitute &j with (\*), obtaining

Assume that is, is, ..., is are unearly dependent:

We have expressed the same model using only P-1 voilables. Hence we need to require that the covariates one linearly independent  $\Rightarrow$  rank(x) = pREHARK: p is the number of columns of X

If we include the INTERCEPT in the model  $\Rightarrow \stackrel{\times}{\sim} = 1$  constant vector of ones

Hence, to avoid collinearity, I can not have another  $x_j$  that is constant for all i = 1,...,n

This is the assumption we had in the simple em (which included the intercept)

2 LINEARITY LE ZE BIX: - XB (1) DISTRIBUTION: normality, homoscudashicity, incorrelation

eff. diagonal elements = 0

 $= \mathbb{E}\left[\underbrace{\mathbb{E}}_{\mathbb{E}}^{\mathbb{E}}\right]$ what is this  $\underbrace{\mathbb{E}}_{\mathbb{E}}^{\mathbb{E}} = \begin{bmatrix} \mathbb{E}_{1} \\ \mathbb{E}_{2} \\ \mathbb{E}_{3} \end{bmatrix} \begin{bmatrix} \mathbb{E}_{1}, \dots, \mathbb{E}_{N} \end{bmatrix} = \begin{bmatrix} \mathbb{E}_{1}^{\mathbb{E}} & \mathbb{E}_{1}^{\mathbb{E}} & \mathbb{E}_{2}^{\mathbb{E}} & \mathbb{E}_{1}^{\mathbb{E}} \\ \mathbb{E}_{2}^{\mathbb{E}} & \mathbb{E}_{2}^{\mathbb{E}} & \mathbb{E}_{3}^{\mathbb{E}} \\ \mathbb{E}_{3}^{\mathbb{E}} & \mathbb{E}_{4}^{\mathbb{E}} & \mathbb{E}_{2}^{\mathbb{E}} \\ \mathbb{E}_{3}^{\mathbb{E}} & \mathbb{E}_{4}^{\mathbb{E}} & \mathbb{E}_{3}^{\mathbb{E}} \\ \mathbb{E}_{4}^{\mathbb{E}} & \mathbb{E}_{4}^{\mathbb{E}} & \mathbb{E}_{4}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\ \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} & \mathbb{E}_{5}^{\mathbb{E}} \\$  $E[E] = \begin{bmatrix} E[E] & E[E] & \dots & E[E] & \dots \\ E[E] & E[E] & \dots & \dots \\ E[E] & \dots & \dots & \dots \end{bmatrix}$   $Since \quad E[E] = 0 \quad \text{for } i \neq k$   $E[E] = 0^2 \quad \text{for } i = 1, \dots, n$ 

IE[E] = 0 n-dimensional vector of seros

vo.( €) = [E[( €- [E] €])( €- [E] €]) ]

E = | Ei | vector of the errors

. expectation:

· vouance

=  $6^2 \text{ In}$  (nxn) matrix, diagonal elements =  $6^2$ 

Hence 
$$\xi : \stackrel{iid}{\sim} N(0, \delta^2) := 1, ..., n \Rightarrow \xi \sim N_n(0, \delta^2 I_n)$$
 consequence for the response voriable

E[Y] = E[XB+ &] = XB

. INTERPRETATION OF THE COFFICIENTS \$1,..., \$

 $\operatorname{var}(\underline{Y}) = \operatorname{var}(\underline{X}\underline{\beta} + \underline{\varepsilon}) = \operatorname{var}(\underline{\varepsilon}) = 6^2 \operatorname{In}$ 

we have seen that in the simple linear model Y:= B2+B2×+6; B2 is the expected change in Y: (i.e., the change in  $\mu i = E[Y_i]$ ) when we increase  $x_i$  by one unit. (or, equivalently, the expected difference in Y when we consider two individuals i and k

μι = β1 + β2 x2 + ... + βj xij + ... + βρ xip

 $= \beta_1 + \beta_2 \times \beta_1 + ... + \beta_j \times 0 + ... + \beta_p \times \phi$ 

which differ in x by 1 unit:  $\beta_2 = E[Y_K] - E[Y_C]$ , when  $x_1 = x_0$  and  $x_K = x_0 + 1$ ) How do we interpret B, j = 4, ..., P, in the case of multiple linear repression? Yi= B1 + B2 xi2 + ... + Bp xip + Ei Let's consider the mean of Y of two units i and k, IE[Yi]=Mi and IE[Yk]=Mk.

Finally, the normality of  $\underline{\varepsilon}$  implies the normality of  $\underline{Y} \Rightarrow \underline{Y} \sim N_n(\underline{x}\underline{\beta}, \underline{\varepsilon}^2\underline{T}_n)$ 

xi,j+1 = xk,j+1 ,... , xip = xkp Let's now compare their means:

while the other covariates are all equal: Xiz = XKz, Xiz = XKz, ..., Xi,j-1 = XK,j-1,

Assume that the values of the j-th covariate on these individuals one  $x_i = x_0 + 1$ 

MK = B1 + B2 XK2 + ... + Bj XKj + ... + Bp XKp =  $\beta_1 + \beta_2 \times_{K2} + ... + \beta_1 (x_0+1) + ... + \beta_p \times_{Kp}$ = β1 + β2 × κ2 + ... + β; × + β; + ... + βρ × κρ

meon of individual i

mean of individual k

If we study the difference in their means => MK-Mi = Bj B; now represents the expected charge in Yi (i.e., the charge in Mi), when we increase xij by one unit, while keeping all other covoriates fixed.