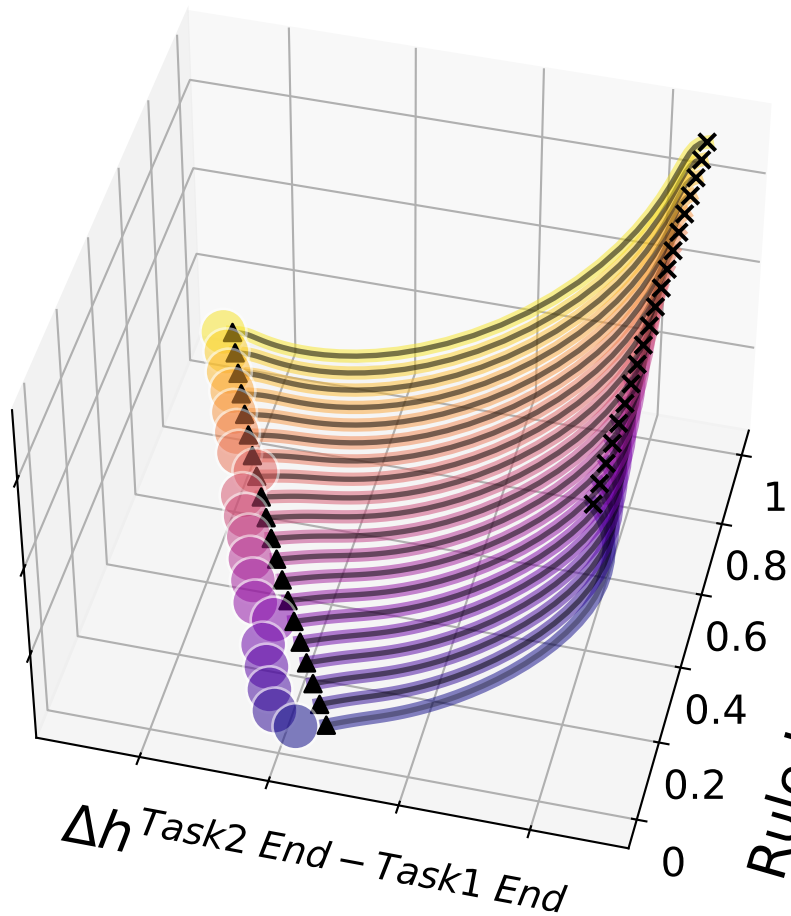


$\Delta h_{\text{Task1 End} - \text{Task1 Start}}$



Rule Input α
Dst. from
Prev. Fixed Point

