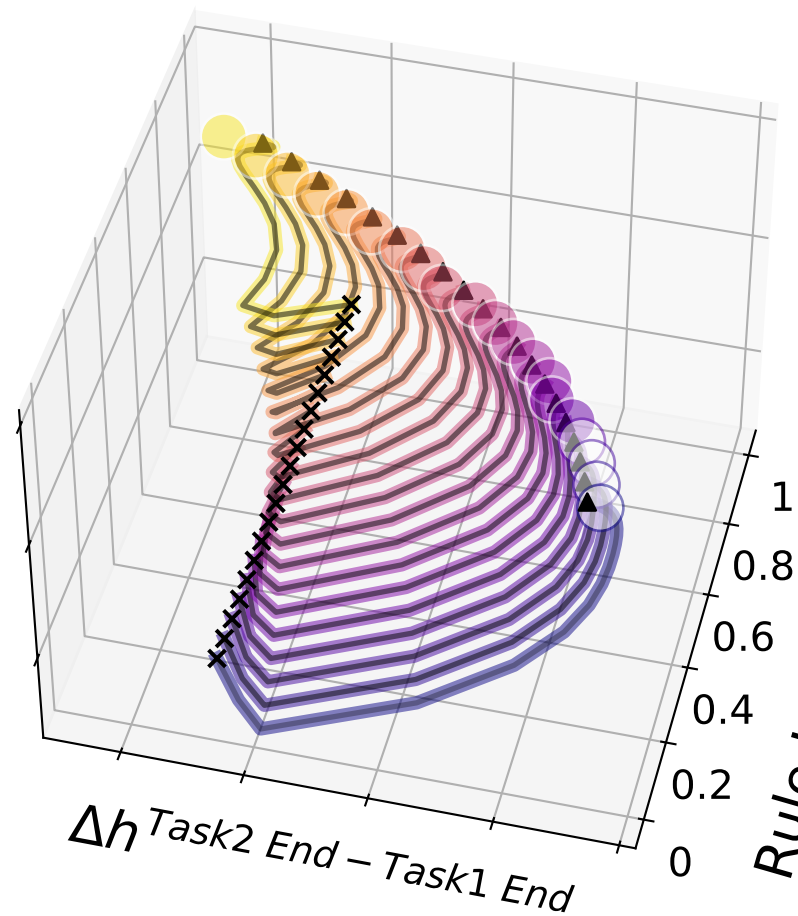


$\Delta h_{\text{Task1 End} - \text{Task1 Start}}$



Rule Input  $\alpha$   
Dst. from  
Prev. Fixed Point

