

MLS	Dataset	PLS(AIC)	PLS(AICc)	PLS(BIC)	PLS(HQIC)	PLS(GMDL)
Ridge	abalone	<b>46.85</b> (3)	<b>46.85</b> (3)	<b>46.85</b> (3)	<b>46.85</b> (3)	<b>46.85</b> (3)
	airfoil_self_noise	<b>51.16</b> (2)	<b>51.16</b> (2)	<b>51.16</b> (2)	<b>51.16</b> (2)	62.68(5)
	auto_mpg	<b>19.12</b> (3)	<b>19.12</b> (3)	<b>19.12</b> (3)	<b>19.12</b> (3)	<b>19.12</b> (3)
	automobile	18.23(4)	18.23(4)	<b>18.17</b> (1)	18.23(4)	<b>18.17</b> (1)
	concrete_data	<b>39.50</b> (3)	<b>39.50</b> (3)	<b>39.50</b> (3)	<b>39.50</b> (3)	<b>39.50</b> (3)
	crime	<b>35.61</b> (3)	<b>35.61</b> (3)	<b>35.61</b> (3)	<b>35.61</b> (3)	<b>35.61</b> (3)
	fertility	<b>106.17</b> (3)	<b>106.17</b> (3)	<b>106.17</b> (3)	<b>106.17</b> (3)	<b>106.17</b> (3)
	flow	68.85(4)	68.85(4)	<b>64.45</b> (1)	68.85(4)	<b>64.45</b> (1)
	forest	<b>101.42</b> (3)	<b>101.42</b> (3)	<b>101.42</b> (3)	<b>101.42</b> (3)	<b>101.42</b> (3)
	qsar	<b>43.07</b> (3)	<b>43.07</b> (3)	<b>43.07</b> (3)	<b>43.07</b> (3)	<b>43.07</b> (3)
	servo	<b>60.05</b> (1)	<b>60.05</b> (1)	61.66(4)	61.66(4)	61.66(4)
	slump	<b>86.52</b> (2)	90.65(5)	<b>86.52</b> (2)	<b>86.52</b> (2)	<b>86.52</b> (2)
	traffic	<b>43.91</b> (2)	43.97(5)	<b>43.91</b> (2)	<b>43.91</b> (2)	<b>43.91</b> (2)
	wine_red	<b>65.93</b> (3)	<b>65.93</b> (3)	<b>65.93</b> (3)	<b>65.93</b> (3)	<b>65.93</b> (3)
	wine_white	<b>74.76</b> (3)	<b>74.76</b> (3)	<b>74.76</b> (3)	<b>74.76</b> (3)	<b>74.76</b> (3)
Avg. Rank		(2.93)	(3.27)	(2.77)	(3.10)	(2.93)
SVR	abalone	<b>43.61</b> (2)	<b>43.61</b> (2)	47.18(4)	<b>43.61</b> (2)	47.18(4)
	airfoil_self_noise	<b>89.32</b> (2)	101.76(5)	<b>89.32</b> (2)	<b>89.32</b> (2)	<b>89.32</b> (2)
	auto_mpg	<b>25.65</b> (2)	<b>25.65</b> (2)	25.74(4)	<b>25.65</b> (2)	26.90(5)
	automobile	<b>19.99</b> (3)	<b>19.99</b> (3)	<b>19.99</b> (3)	<b>19.99</b> (3)	<b>19.99</b> (3)
	concrete_data	<b>42.45</b> (3)	<b>42.45</b> (3)	<b>42.45</b> (3)	<b>42.45</b> (3)	<b>42.45</b> (3)
	crime	<b>35.02</b> (2)	<b>35.02</b> (2)	<b>35.02</b> (2)	<b>35.02</b> (2)	38.73(5)
	fertility	<b>121.15</b> (3)	<b>121.15</b> (3)	<b>121.15</b> (3)	<b>121.15</b> (3)	<b>121.15</b> (3)
	flow	<b>68.17</b> (3)	<b>68.17</b> (3)	<b>68.17</b> (3)	<b>68.17</b> (3)	<b>68.17</b> (3)
	forest	<b>100.88</b> (3)	<b>100.88</b> (3)	<b>100.88</b> (3)	<b>100.88</b> (3)	<b>100.88</b> (3)
	qsar	<b>38.01</b> (3)	<b>38.01</b> (3)	<b>38.01</b> (3)	<b>38.01</b> (3)	<b>38.01</b> (3)
	servo	18.50(3)	<b>16.14</b> (1)	18.91(4)	18.39(2)	18.91(4)
	slump	83.61(3)	83.61(3)	83.61(3)	83.61(3)	<b>80.94</b> (1)
	traffic	44.65(3)	47.94(4)	<b>40.92</b> (1)	47.94(4)	<b>40.92</b> (1)
	wine_red	<b>58.35</b> (3)	<b>58.35</b> (3)	<b>58.35</b> (3)	<b>58.35</b> (3)	<b>58.35</b> (3)
	wine_white	<b>58.30</b> (3)	<b>58.30</b> (3)	<b>58.30</b> (3)	<b>58.30</b> (3)	<b>58.30</b> (3)
Avg. Rank		(2.83)	(2.97)	(3.13)	(2.87)	(3.20)
RFR	abalone	<b>45.88</b> (2)	<b>45.88</b> (2)	47.92(4)	<b>45.88</b> (2)	51.70(5)
	airfoil_self_noise	<b>16.59</b> (2)	<b>16.59</b> (2)	16.87(4)	<b>16.59</b> (2)	23.67(5)
	auto_mpg	<b>13.88</b> (2)	<b>13.88</b> (2)	14.16(4)	<b>13.88</b> (2)	15.01(5)
	automobile	23.70(2)	25.45(5)	23.70(2)	24.47(4)	<b>16.72</b> (1)
	concrete_data	<b>11.99</b> (3)	<b>11.99</b> (3)	<b>11.99</b> (3)	<b>11.99</b> (3)	<b>11.99</b> (3)
	crime	37.16(2)	<b>36.05</b> (1)	38.55(4)	38.12(3)	38.55(4)
	fertility	129.79(3)	139.92(5)	128.24(2)	129.79(3)	<b>111.11</b> (1)
	flow	64.70(4)	73.19(5)	61.74(2)	64.44(3)	<b>60.71</b> (1)
	forest	<b>107.25</b> (3)	<b>107.25</b> (3)	<b>107.25</b> (3)	<b>107.25</b> (3)	<b>107.25</b> (3)
	qsar	40.51(2)	<b>38.95</b> (1)	42.21(4)	40.51(2)	42.21(4)
	servo	<b>23.47</b> (2)	28.00(5)	<b>23.47</b> (2)	<b>23.47</b> (2)	24.07(4)
	slump	91.45(5)	88.26(3)	74.92(2)	88.74(4)	<b>69.76</b> (1)
	traffic	49.29(2)	50.34(4)	49.29(2)	50.54(5)	<b>48.33</b> (1)
	wine_red	59.65(2)	<b>57.64</b> (1)	61.65(4)	61.65(4)	61.65(4)
	wine_white	<b>62.48</b> (2)	<b>62.48</b> (2)	68.41(4)	<b>62.48</b> (2)	68.41(4)
Avg. Rank		(2.67)	(2.93)	(3.23)	(3.00)	(3.17)
Mean Rank		(2.81)	(3.06)	(3.04)	(2.99)	(3.10)

Table 8: The 3-fold cross validation relative mean squared error and Friedman ranks for all the datasets when PLS, using several stop criteria (AIC, AICc, BIC, HQIC and GMDL), taking into account some baseline systems (Ridge, SVR and RFR) and the RS sampling strategy.