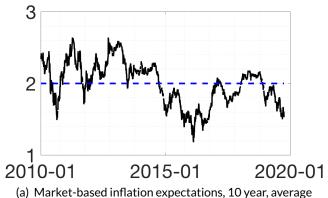
Monetary Policy & Anchored Expectations

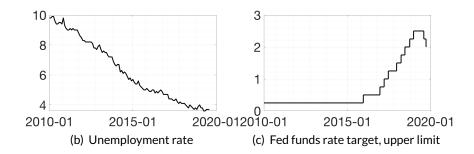
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Inflation expectations moving down





This project

I embed an endogenous anchoring mechanism (AM) in a standard model of monetary policy

Results

- Anchoring expectations is a new objective of monetary policy
- Great Inflation was a period of unanchored expectations
- Optimal policy should take recent economic environment into account when responding to current shocks

STRUCTURE OF TALK

- 1 Related literature
- 2 Intuition: what is anchoring and why should it matter?
- 3 A MODEL OF ANCHORING
- 4 Full model with anchoring mechanism
- 5 SIMULATIONS

Related Literature

Optimal monetary policy in New Keynesian models
 Clarida, Gali & Gertler (1999), Woodford (2003)

Econometric learning
 Evans & Honkapohja (2001), Preston (2005), Graham (2011)

Anchoring
 Carvalho et al (2019), Svensson (2015), Hooper et al (2019)

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PHILLIPS CURVE

$$\pi_t = \beta \hat{\mathbb{E}}_t \pi_{t+1} + \kappa \mathbf{x}_t$$

- $\pi_t = \text{inflation}$
- $x_t = \text{output gap}$
- $\hat{\mathbb{E}}_t$ = expectation-operator (not necessarily rational)

Suppose a negative demand shock:

$$\pi_{t} = \beta \hat{\mathbb{E}}_{t} \pi_{t+1} + \kappa \mathbf{x}_{t} \downarrow$$

If expectations do not move:

$$\pi_{t} = \beta \hat{\mathbb{E}}_{t} \pi_{t+1} + \kappa \mathbf{x}_{t} \downarrow$$

If seeing π_t , expectations adjust:

$$\pi_{t} = \beta \hat{\mathbb{E}}_{t} \pi_{t+1} + \kappa \mathbf{x}_{t}$$

$$\downarrow \downarrow \qquad \downarrow$$

Keeping expectations stable may be desirable

 \rightarrow "Anchored": notion of stable expectations

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A LEARNING MODEL OF EXPECTATION FORMATION

Suppose firms and households

• observe everything up to time t

do not observe future variables

 $\bullet~$ KEY: are unsure about the long-run mean of inflation, $\bar{\pi}$

Agents construct one-period-ahead inflation forecasts as

$$\hat{\mathbb{E}}_t \pi_{t+1} = \bar{\pi}_{t-1} + bs_t \tag{1}$$

 $\bar{\pi} = \text{estimate of inflation drift (= long-run mean, "target")}$

 $\hat{\mathbb{E}} = \text{subjective}$ expectation operator (not rational expectations, $\mathbb{E})$

b = matrix of constants

s = shocks

Anchoring mechanism

$$\bar{\pi}_t = \bar{\pi}_{t-1} + k_t \underbrace{\left(\pi_t - (\bar{\pi}_{t-1} + bs_{t-1})\right)}^{\text{short-run forecast error}} \tag{2}$$

$$k_{t} = \begin{cases} \frac{1}{k_{t-1}+1} & \text{if } \widehat{|\hat{\mathbb{E}}_{t-1}\pi_{t} - \mathbb{E}_{t-1}\pi_{t}|/\sigma_{s}} \leq \bar{\theta} \\ \bar{g} & \text{otherwise} \end{cases}$$
 (3)

Equation (3): endogenous gain

- Carvalho et al (2019)
- Difference to standard econometric learning

	 _	_	_	
Expectations				

• Expectations unanchored = when agents choose **constant** gains

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THE MODEL

Households maximize

$$\hat{\mathbb{E}}_t^i \sum_{T=t}^{\infty} \beta^{T-t} \bigg(U(C_T^i) - v(H_T^i) \bigg)$$

(4)

Household budget constraint:

$$B_t^i \leq (1 + i_{t-1})B_{t-1}^i + W_tH_t^i + \Pi_t^i - T_t - P_tC_t^i$$

(5)

Firms: monopolistic competition in varieties C^{j} , Calvo price setting

Expectations: $\hat{\mathbb{E}}$ as in (1)

3-Equation New Keynesian Model

$$\mathbf{x}_{t} = -\sigma \mathbf{i}_{t} + \hat{\mathbb{E}}_{t} \sum_{T=t}^{\infty} \beta^{T-t} ((\mathbf{1} - \beta) \mathbf{x}_{T+1} - \sigma(\beta \mathbf{i}_{T+1} - \pi_{T+1}) + \sigma \mathbf{r}_{T}^{n})$$

$$\mathbf{i_t} = \psi_\pi \pi_\mathbf{t} + \psi_\mathbf{x} \mathbf{x_t} + \overline{\mathbf{i_t}}$$

 $\pi_{t} = \kappa \mathbf{x}_{t} + \hat{\mathbb{E}}_{t} \sum_{T=1}^{\infty} (\alpha \beta)^{T-t} (\kappa \alpha \beta \mathbf{x}_{T+1} + (\mathbf{1} - \alpha) \beta \pi_{T+1} + \mathbf{u}_{T})$

"Long-horizon forecasts" \rightarrow agents do not know the model

Derivations

Preston (2005)

(6)

(7)

(8)

STRUCTURE OF TALK

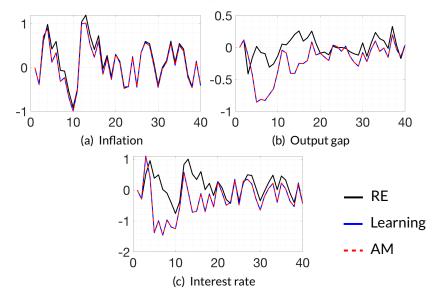
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CALIBRATION

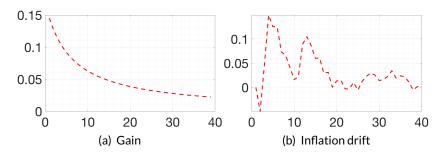
β	0.98	stochastic discount factor	
$\overline{\sigma}$	0.5	intertemporal elasticity of substitution	
α	0.5	Calvo probability of not adjusting prices	
ψ_{π}	1.5	coefficient of inflation in Taylor rule	
$\overline{\psi_{X}}$	1.5	coefficient of the output gap in Taylor rule	
	0.145*	value of the constant gain	
$ar{ar{ heta}}$	5*	threshold deviation between subjective & objective ${\mathbb E}$	
ρ_{r}	0	persistence of natural rate shock	
ρ_{i}	0.877*	persistence of monetary policy shock	
$\overline{\rho_{u}}$	0	persistence of cost-push shock	
σ_{i}	0.359*	standard deviation of natural rate shock	
σ_{r}	0.1	standard deviation of monetary policy shock	
$\sigma_{\sf u}$	0.277*	standard deviation of cost-push shock	

^{*} Carvalho et al (2019)'s estimates. Exception: $\bar{\theta}=$ 0.029.

When always anchored, AM = LEARNING



 ${\rm Figure:} \ \ Rational\ expectations\ (RE), learning\ and\ anchoring\ mechanism\ (AM)$



 $\operatorname{Figure}\colon$ Well anchored expectations: decreasing gain

A lower $\bar{\theta}$: A brief unanchored period

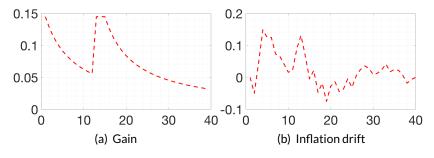
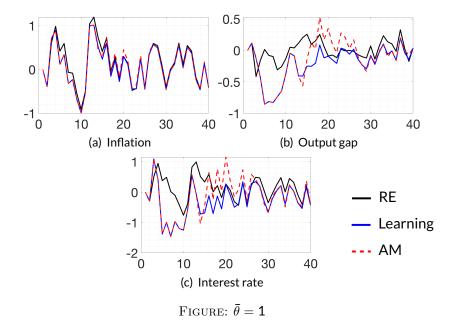


FIGURE: $\bar{\theta}=$ 1. Short unanchored episode: constant gain



A much lower $\bar{\theta}$

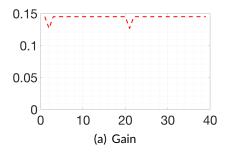


Figure: $\bar{\theta} =$ 0.029. Carvalho et al's estimate extremely unanchored!

GAIN WHEN VARYING TAYLOR-RULE COEFFICIENTS

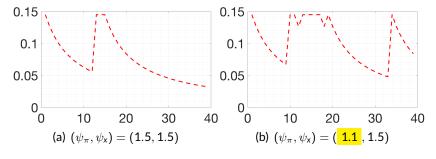
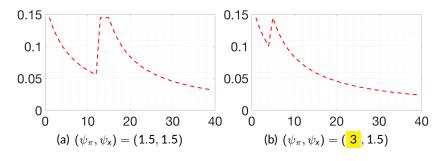


FIGURE: Less aggressive on inflation



 $\operatorname{Figure} :$ More aggressive on inflation

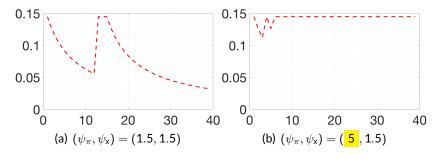


FIGURE: Too aggressive on inflation?

Today's conclusion and work ahead

- Model of anchoring + macro model with monetary policy
 - \rightarrow investigation of new constraint on monetary policy
- Next steps
 - Write and solve monetary policy problem
 - Estimate model

Thank you!

DERIVATIONS

Household FOCs

$$\hat{C}_t^i = \hat{\mathbb{E}}_t^i \hat{C}_{t+1}^i - \sigma(\hat{i}_t - \hat{\mathbb{E}}_t^i \hat{\pi}_{t+1})$$
(9)

$$\hat{\mathbb{E}}_{t}^{i} \sum_{s=0}^{\infty} \beta^{s} \hat{C}_{t}^{i} = \omega_{t}^{i} + \hat{\mathbb{E}}_{t}^{i} \sum_{s=0}^{\infty} \beta^{s} \hat{Y}_{t}^{i}$$
(10)

where a hat denotes log-linear approximation and $\omega_t^i \equiv \frac{(1+i_{t-1})B_{t-1}^i}{P_tY^*}$.

- Solve (9) backward to some date t, take expectations at t
- Sub in (10)
- Aggregate over households i
- \rightarrow Obtain (6)



Compact notation

$$z_t = \mathsf{A}_1 \mathsf{f}_{a,t} + \mathsf{A}_2 \mathsf{f}_{b,t} + \mathsf{A}_3 \mathsf{s}_t$$

 $S_t = PS_{t-1} + \epsilon_t$

$$z_t \equiv \begin{pmatrix} \pi_t \\ x_t \\ i_t \end{pmatrix}$$
 $s_t \equiv \begin{pmatrix} r_t^n \\ \bar{i}_t \\ u_t \end{pmatrix}$

$$\equiv \begin{pmatrix} \frac{r_t^n}{\bar{i}_t} \\ u_t \end{pmatrix}$$

(11)

(12)

and
$$f_{a,t} \equiv \hat{\mathbb{E}}_t \sum_{T=t}^\infty (\alpha \beta)^{T-t} \mathsf{z}_{T+1} \qquad \qquad f_{b,t} \equiv \hat{\mathbb{E}}_t \sum_{T=t}^\infty (\beta)^{T-t} \mathsf{z}_{T+1}$$