

LABORATORIO DI SISTEMI SOFTWARE

Introduction

Remember our motto:

there is no code without a project, no project without problem analysis and no problem without requirements.

Requirements

Design and build a ButtonLed software system (bls) that makes human users able to control a led according to different control policies each time a button is pressed:

1. es2-Blink/un-blink the led

The system should be a distributed system, in which the Button and the Led run on a different computational supports, e.g. a Conventional PC, a RaspberryPi or Arduino.

Requirement analysis

```
System sys_bls

Dispatch cmdOn    : cmdOn(ARG)
Dispatch cmdOff   : cmdOff(ARG)
Event    button   : button( KIND )

Context ctxbutton ip [host="localhost" port=8010]
Context ctxled ip [host="127.0.0.1" port=8077]

QActor button context ctxbutton {

    State off initial {
        discardMsg On
        println("  Button pressed: Turned Off    ")
        forward led -m cmdOff : cmdOff(1)
    }
    Transition to whenEvent button -> on

    State on {
        println("  Button pressed: Turned On      ")
        forward led -m cmdOn : cmdOn(1)
    }
    Transition to whenEvent button -> off
}

QActor led context ctxled {

    State off initial {
        discardMsg On
        println("    Turned Off      ")
    }
    Transition to    whenMsg cmdOn -> on

    State on {
        println("    Turned On      ")
        println("    =====Blinking===== ")
    }
    Transition to    whenMsg cmdOff -> off
}

/* For local test */
QActor user context ctxbutton {
    State so initial {
        println("user presses button")
        emit button : button( on )
        delay 2500
        println("user presses button")
        emit button : button( off )
        terminate 0
    }
}
```

Problem analysis

```
System sys_bls

Request  cmdOn    : cmdOn(ARG)
Request  cmdOff   : cmdOff(ARG)
Reply    ack      : ack(ARG)
Event    button   : button( KIND )
Dispatch blink    : blink(ARG)

Context ctxlogicbutton ip [host="localhost" port=8010]
Context ctxlogicled ip [host="127.0.0.1" port=8077]

QActor button context ctxlogicbutton {

    State init initial {
        println("BUTTON init done. Default initial led and button state: Off")
    }
    Goto turningOff

    State turningOff {
```

```

        request led -m cmdOff : cmdOff(0)
    }
    Transition to whenReply ack -> off

    State off {
        printCurrentMessage
        println("  BUTTON turned OFF  ")
    }
    Transition to whenEvent button -> turningOn

    State turningOn {
        request led -m cmdOn : cmdOn(1)
    }
    Transition to whenReply ack -> on

    State on {
        printCurrentMessage
        println("  BUTTON turned ON  ")
    }
    Transition to whenEvent button -> turningOff
}

/*For local test*/
QActor user context ctxlogicbutton {
    State so initial {
        delay 2500
        println("USER presses button")
        emit button : button( on )
        delay 5500
        println("USER presses button")
        emit button : button( off )
        terminate 0
    }
}

QActor led context ctxlogicled {

    State init initial {
        discardMsg On
        println( "  LED init done." )
    }
    Transition to    whenRequest cmdOn -> on
                    whenRequest cmdOff -> off

    State off {
        onMsg(cmdOff : cmdOff(ARG)) {
            [# val V = payloadArg(0)
            val Answer = "ackTo_$(V)"
            #]
            replyTo cmdOff with ack : ack($Answer)
            println( "led has sent ACK with Answer: $Answer")
        }
        println( "led has been turned off")
    }
    Transition to    whenRequest cmdOn -> on

    State on {
        onMsg(cmdOn : cmdOn(ARG)) {
            [# val V = payloadArg(0)
            val Answer = "ackTo_$(V)"
            #]
            replyTo cmdOn with ack : ack($Answer)
            println( "led has sent ACK with Answer: $Answer")
        }

        println( "led has been turned on" )
    }
    Goto blinkOn

    State blinkOn {
        println( "blink ON" )
        delay 500
        forward led -m blink : blink(off)
    }
    Transition to    whenRequest cmdOff -> off
                    whenMsg blink -> blinkOff

    State blinkOff {
        println( "blink OFF" )
        delay 500
        forward led -m blink : blink(on)
    }
    Transition to    whenRequest cmdOff -> off
                    whenMsg blink -> blinkOn
}

```

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