Exp: Test Delay Re-clone or R- download the Framework Repository from bitbucket in (input signal) Klace types: PI, Pz, in: String Constant Places: One: Integer (1) Fine: Integer (5) Grd & Map Ti: grd! (Pi + null) AND (in + null) P2 = P1; Ti. Delay = Fine;

grd2: (PI Inull) AND (in == null)

P2 = Pi;

Ti. Delay = One;

Ta: $(P_2 \neq null)$ $P_1 = P_2$.

Excercise: Modify 4 phase controller
from Project 5 and test it
with lanes and Intersection
from Project 4 " Test the case
of traffic jam by sending
4 cars to one of the lanes
before receiving a green light"

in2 inl 91525354 tz t3 [5] 41121314 5,525354 r1927374 £955] ini **Y4** 4152 13 YH 17 y 2 13 4 OPU 93 t8Es3 3 4 ts[5] 4, rev394 (11129314 rirzysry telsz Din 4 Modifications: : Dada String add in , .. 4 add constant Places: Fine: (5) Integer Ten: (10) Integer

Modify: Ti, T3, T5, and T7 Ti: grd : (rirarar4 = null)

AND (in == null) 91828384 = 8182 8384 OP. Send Over Network ("green") Ti. Dynamic Delay = Fine grod 2: (8,82 ×3×4 + null)

AND (in + null) 91828384 = 81828384 OP. Send Over Network ("grow")

Same for T3, T5, and T7

Ti. Dynamic Delay = Ten