



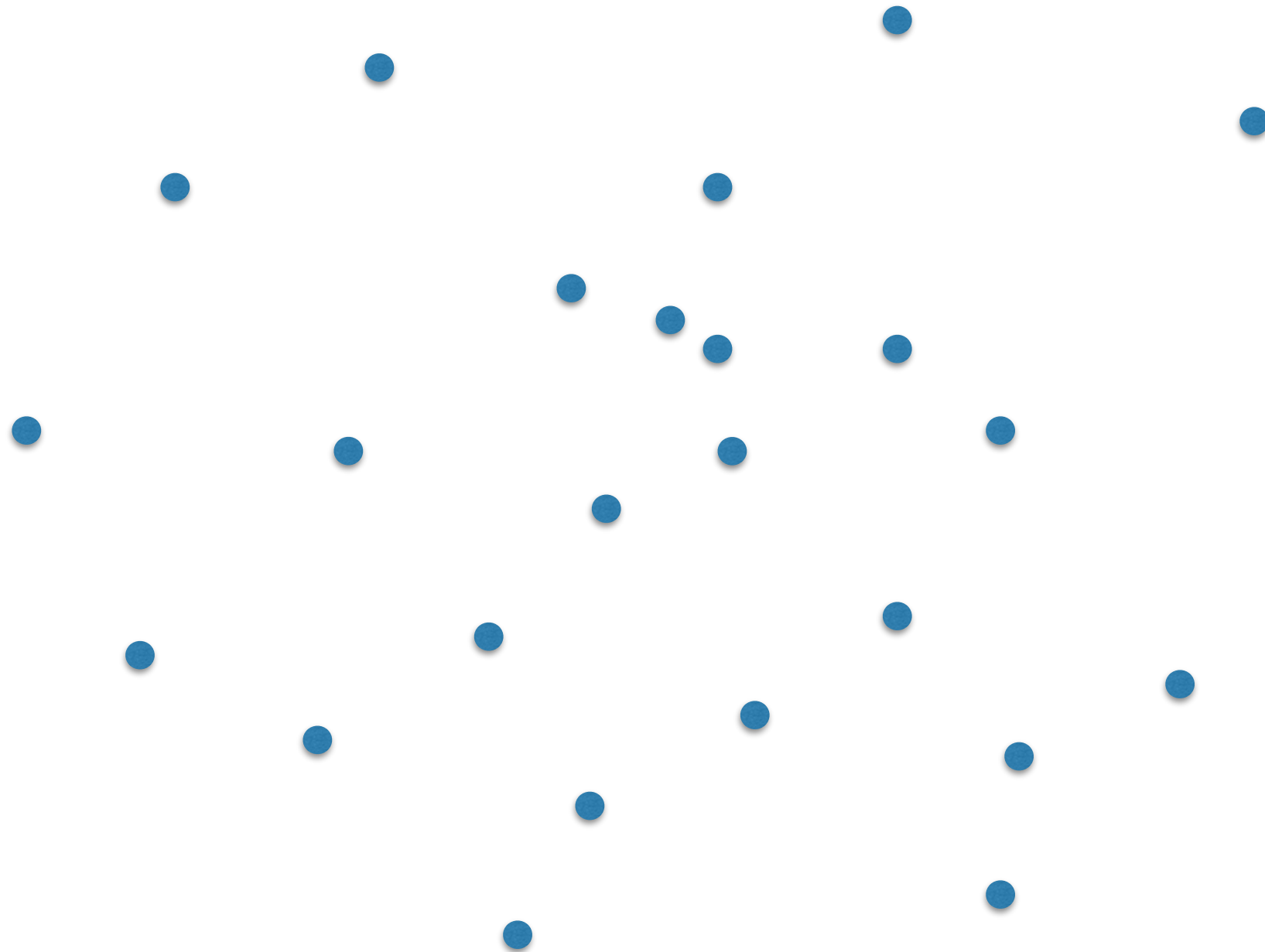
Finding the closest pair

Computational Geometry [csci 3250]

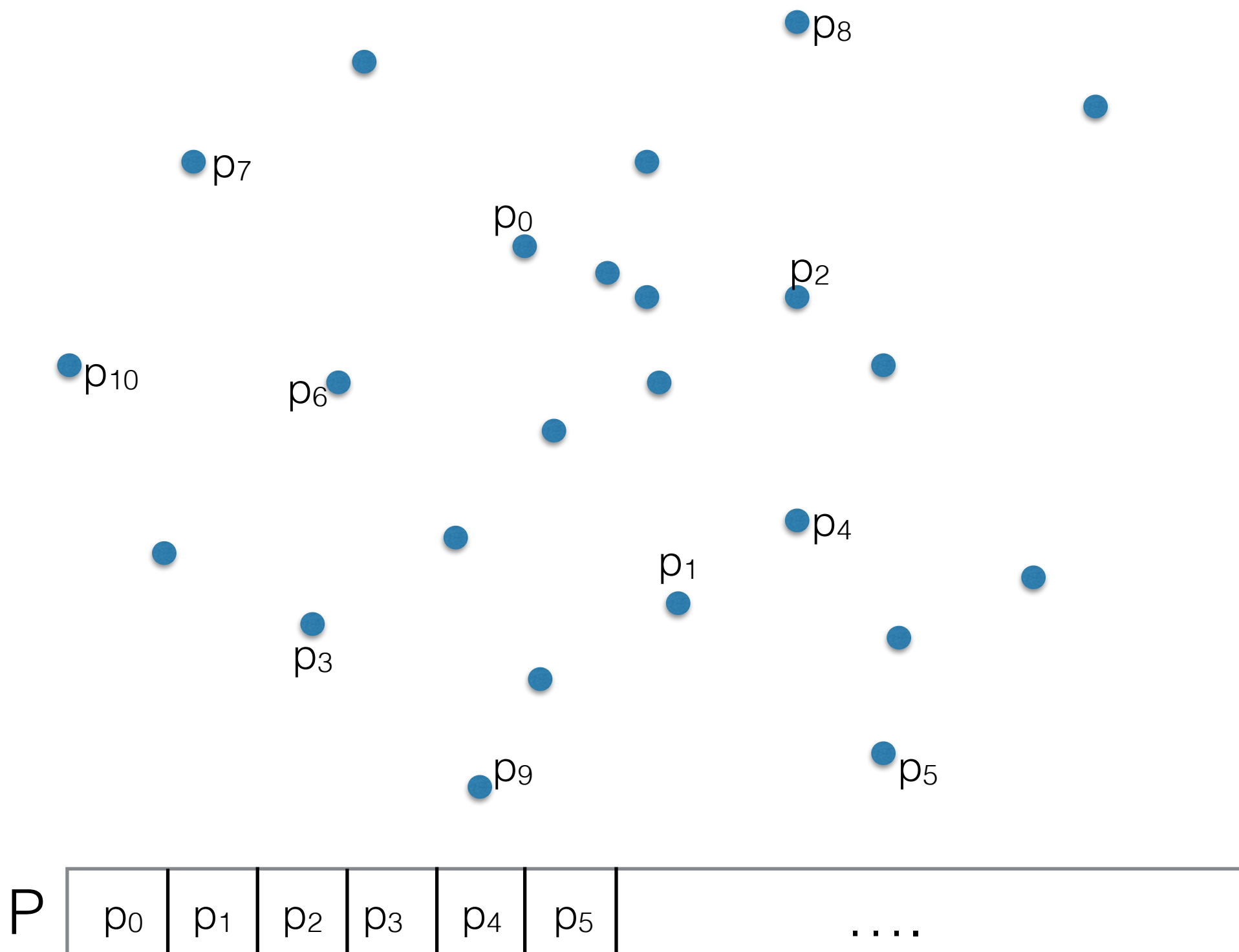
Laura Toma

Bowdoin College

Given an array of points in 2D, find the closest pair.



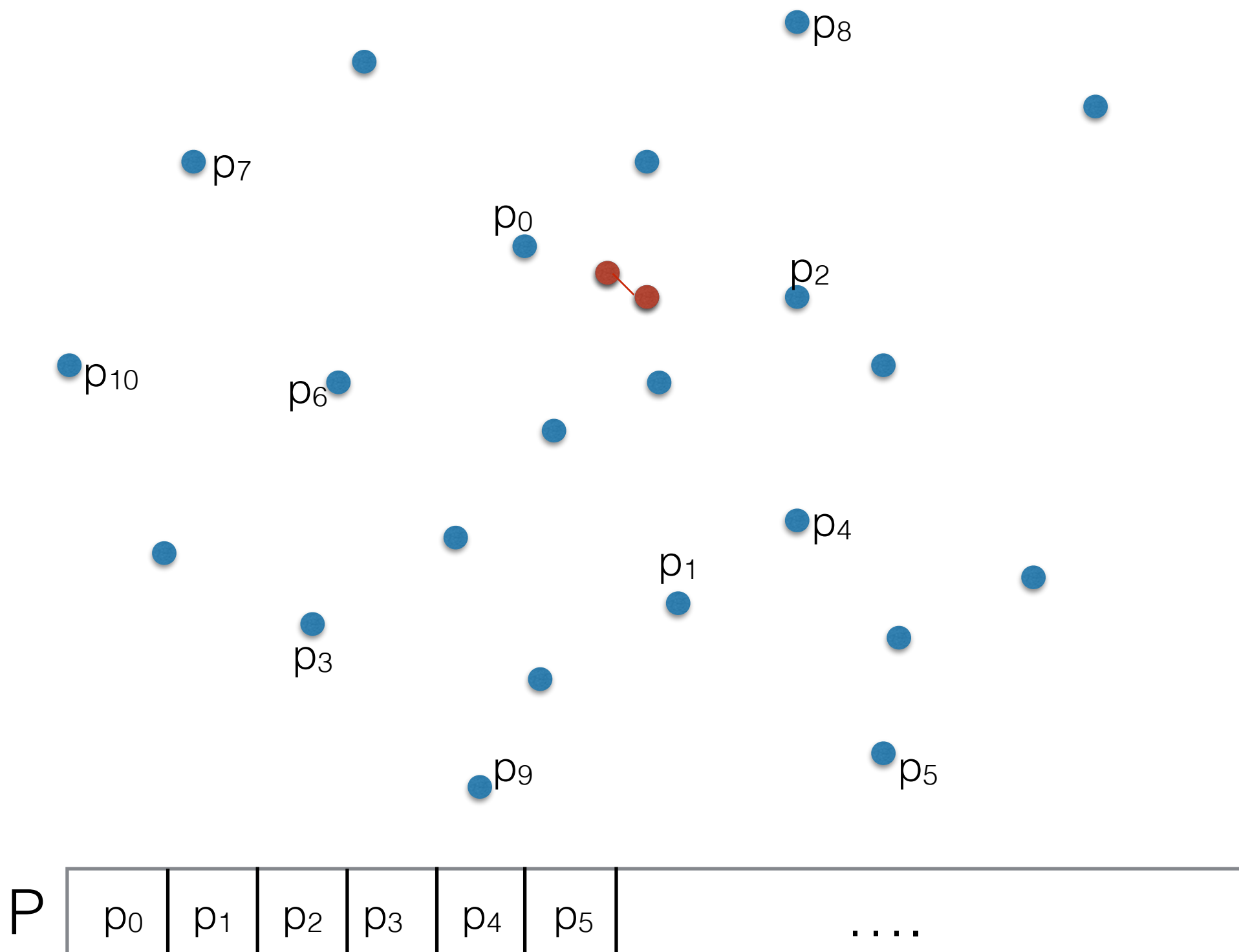
Given an array of points in 2D, find the closest pair.



The distance between two points p and q is given by the Euclidian distance given by the formula:

$$d(p,q) = \sqrt{(x_p-x_q)^2 + (y_p-y_q)^2}$$

Given an array of points in 2D, find the closest pair.



Given an array of points in 2D, find the closest pair.

Brute force:

- `mindist = VERY_LARGE_VALUE`
- for all distinct pairs of points p_i, p_j
 - $d = \text{distance}(p_i, p_j)$
 - if ($d < \text{mindist}$): `mindist=d`

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Hint: use divide-and-conquer

Divide-and-conquer refresher

Divide-and-conquer

mergesort(array A)

- if A has 1 element, there's nothing to sort, so just return it
- else

//divide input A into two halves, A1 and A2

- A1 = first half of A
- A2 = second half of A

//sort recursively each half

- sorted_A1 = **mergesort**(array A1)
- sorted_A2 = **mergesort**(array A2)

//merge

- result = merge_sorted_arrays(sorted_A1, sorted_A2)
- return result

Divide-and-conquer

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Analysis: $T(n) = 2T(n/2) + O(n) \Rightarrow O(n \lg n)$

D&C, in general

DC(input P)

if P is small, solve and return

else

//divide

divide input P into two halves, P1 and P2

//recurse

result1 = **DC(P1)**

result2 = **DC(P2)**

//merge

do_something_to_figure_out_result_for_P

return result

Analysis: $T(n) = 2T(n/2) + O(\text{merge phase})$

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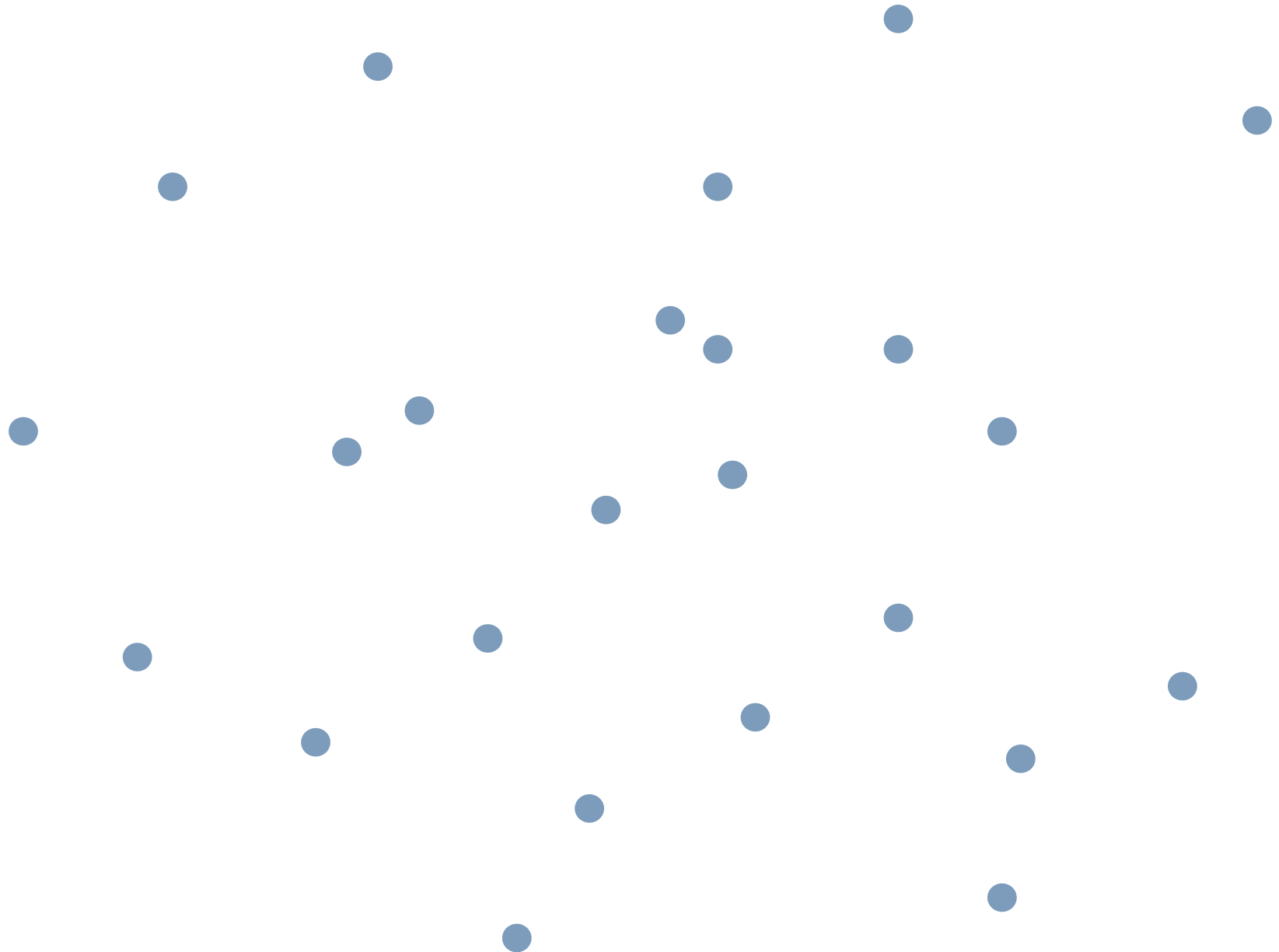
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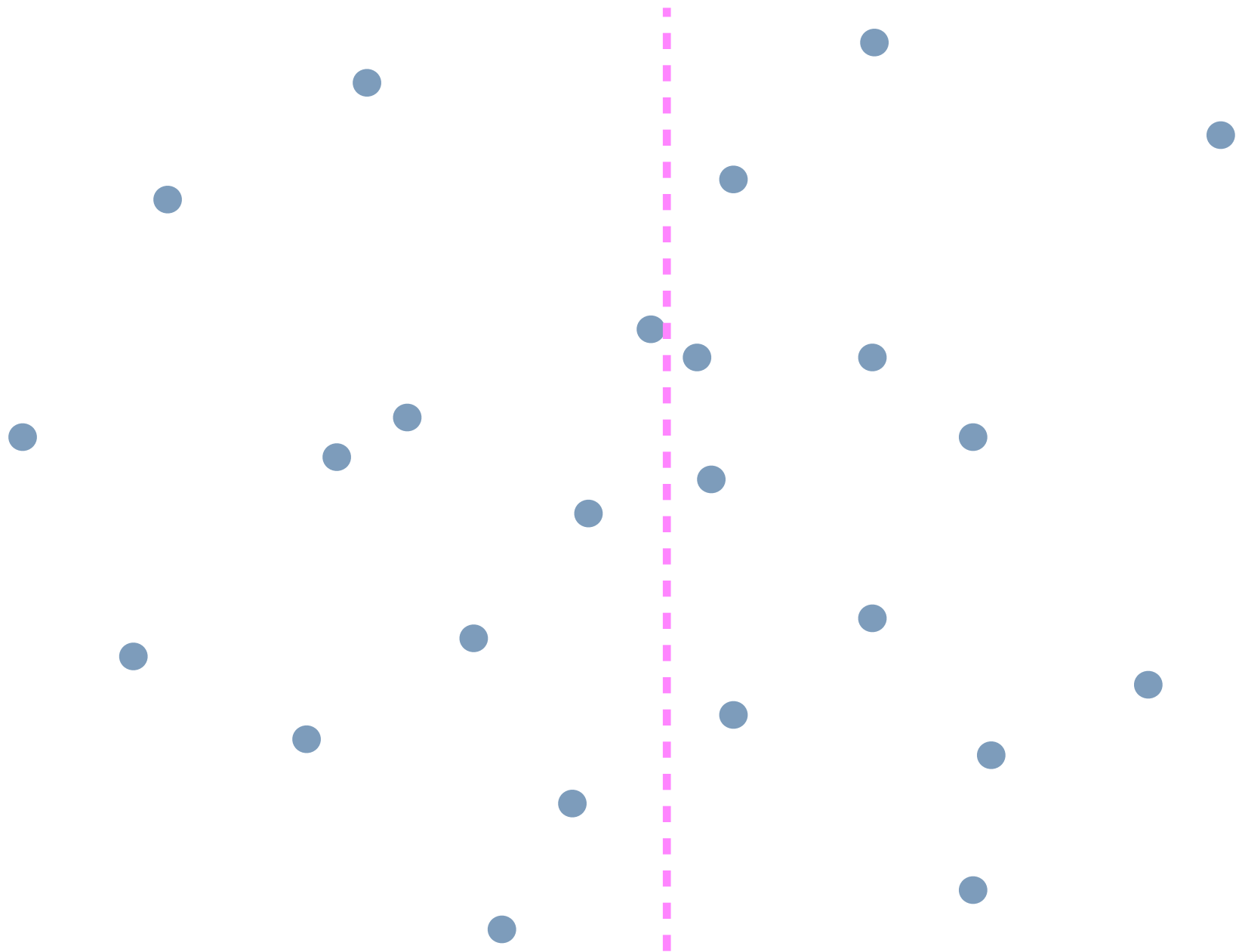
- if merge phase is **$O(n)$** : $T(n) = 2T(n/2) + O(n) \Rightarrow O(n \lg n)$
- if merge phase is **$O(n \lg n)$** : $T(n) = 2T(n/2) + O(n \lg n) \Rightarrow O(n \lg^2 n)$

Closest pair, divide-and-conquer



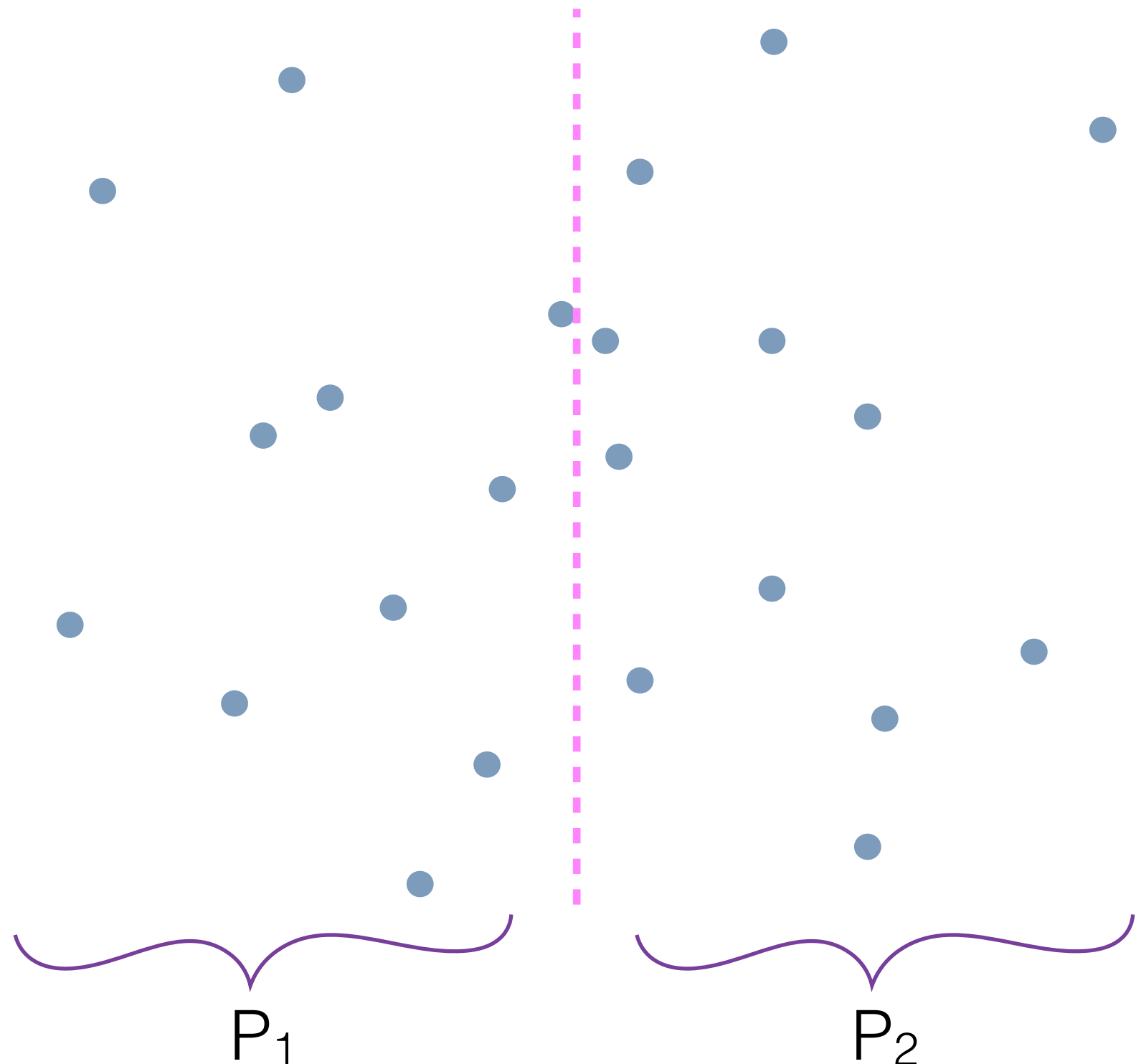
Closest pair, divide-and-conquer

- find vertical line that splits P in half



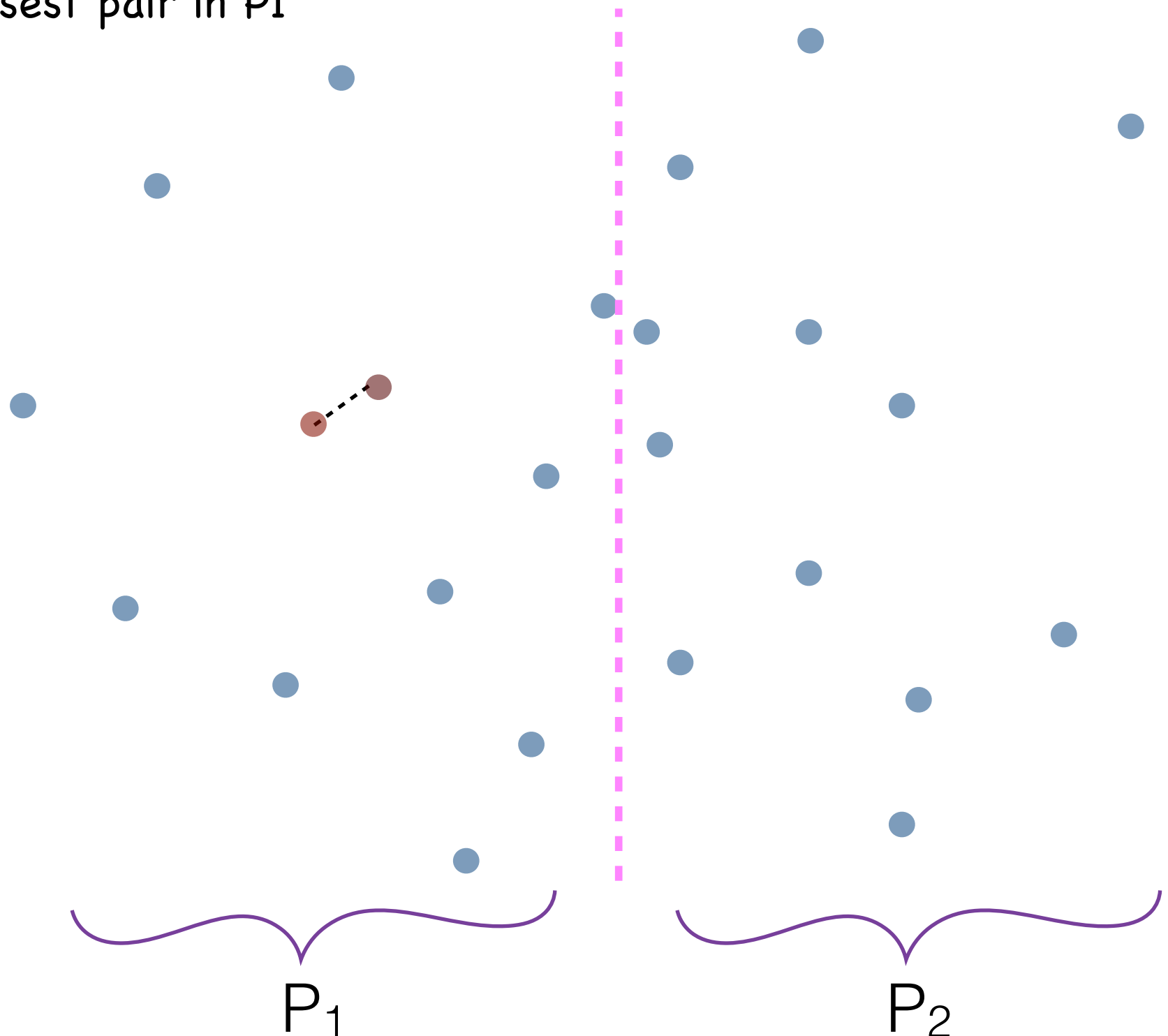
Closest pair, divide-and-conquer

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line



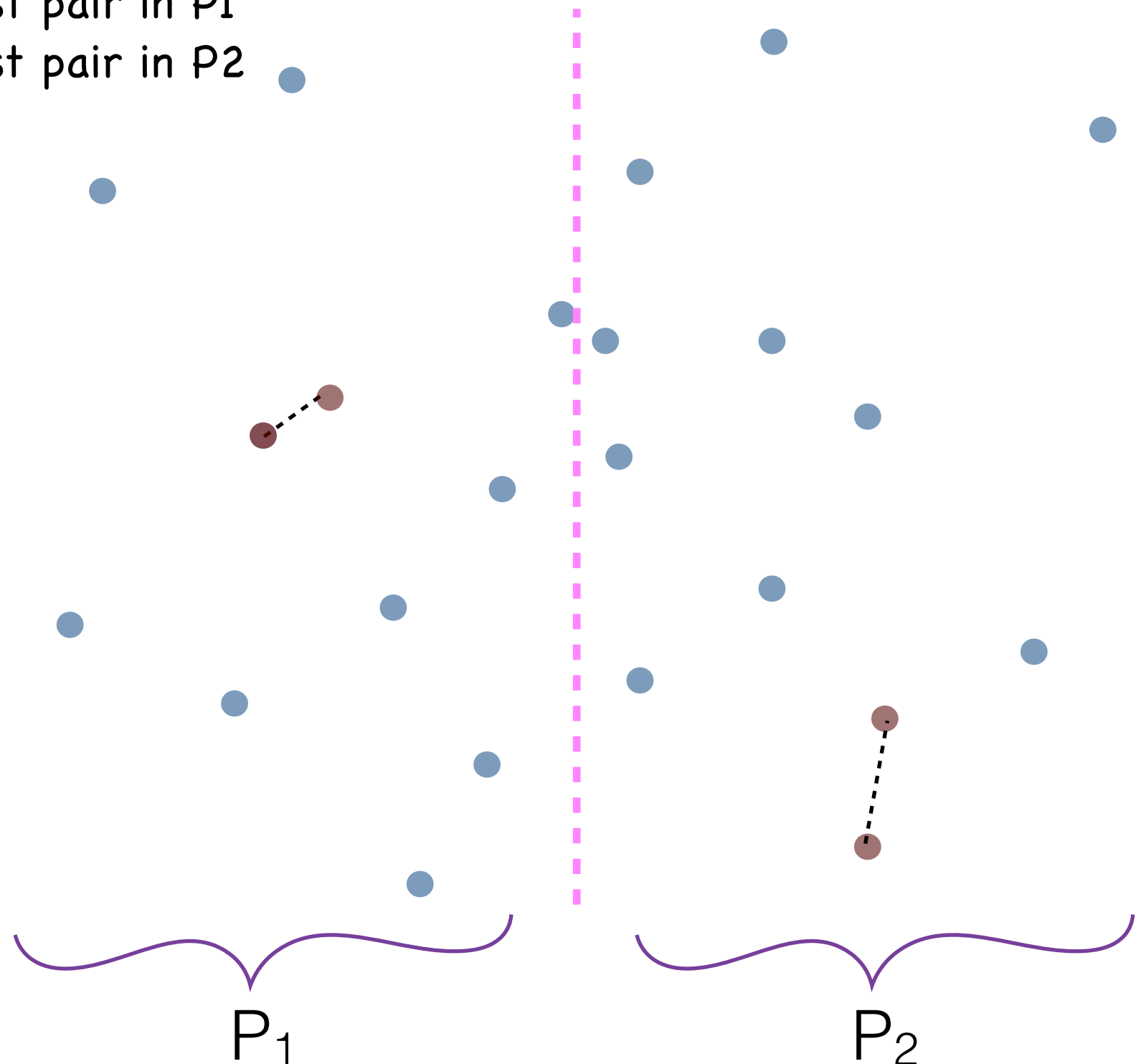
Closest pair, divide-and-conquer

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1



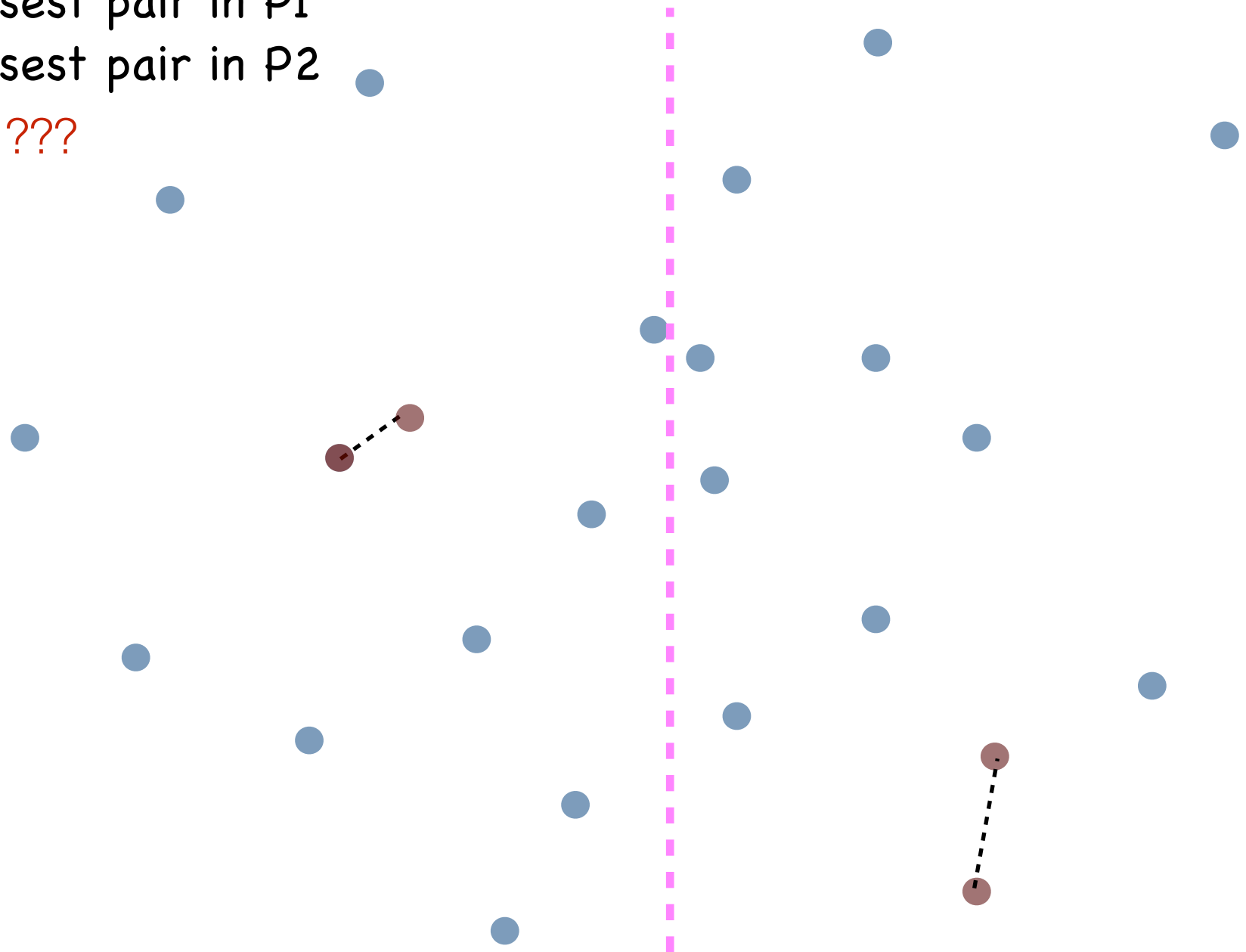
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- find vertical line that splits P in half
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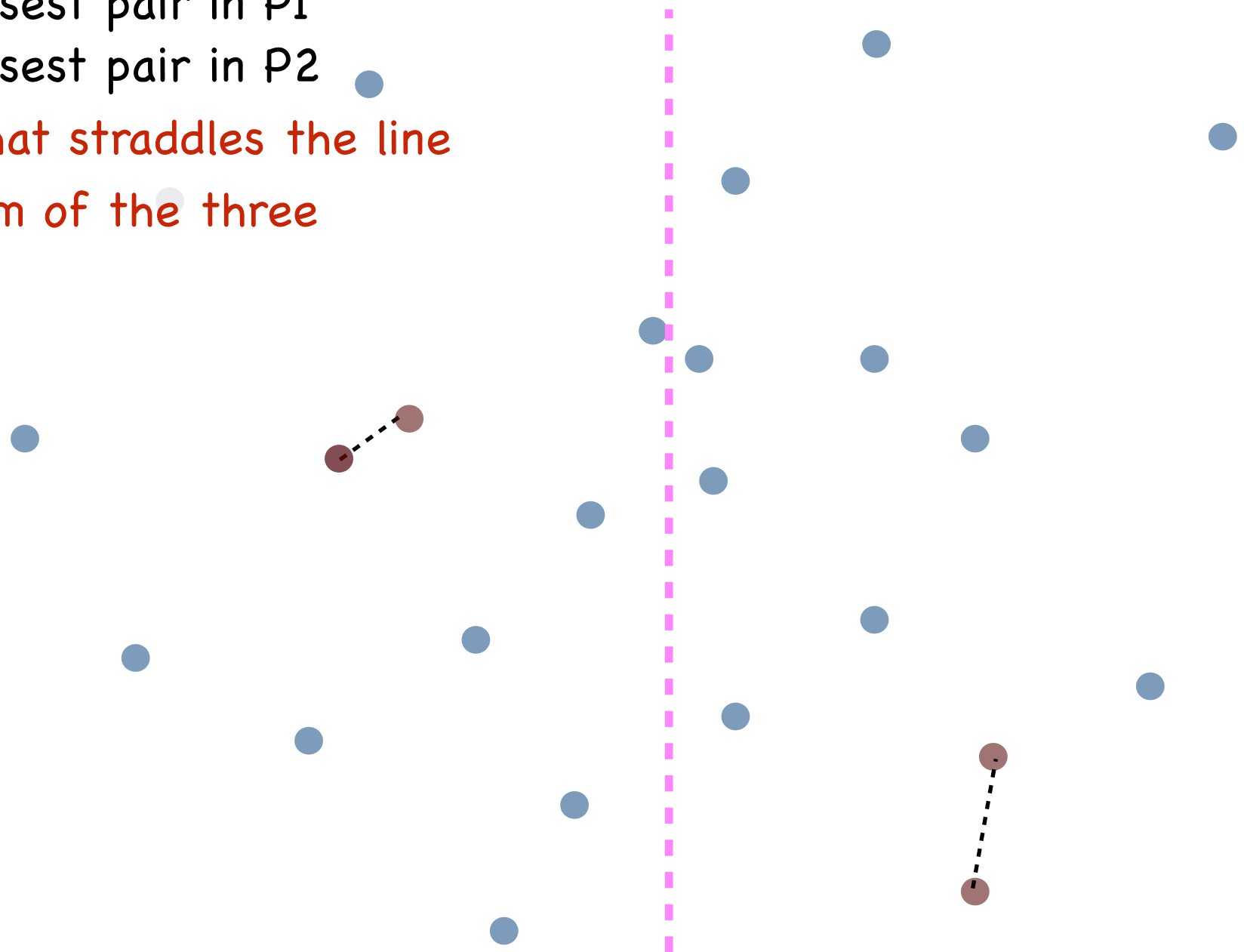
Closest pair, divide-and-conquer

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2
- //..... NOW WHAT ???



Closest pair, divide-and-conquer

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2
- find closest pair that straddles the line
- return the minimum of the three



Closest pair, divide-and-conquer

FindClosestPair(P)

//basecase

- if P has 1 point, return infinity
- if P has 2 points, return their distance
- else
 - find vertical line that splits P in half
 - let P_1, P_2 = set of points to the left/right of line
 - $d_1 = \text{FindClosestPair}(P_1)$
 - $d_2 = \text{FindClosestPair}(P_2)$

//compute closest pair across

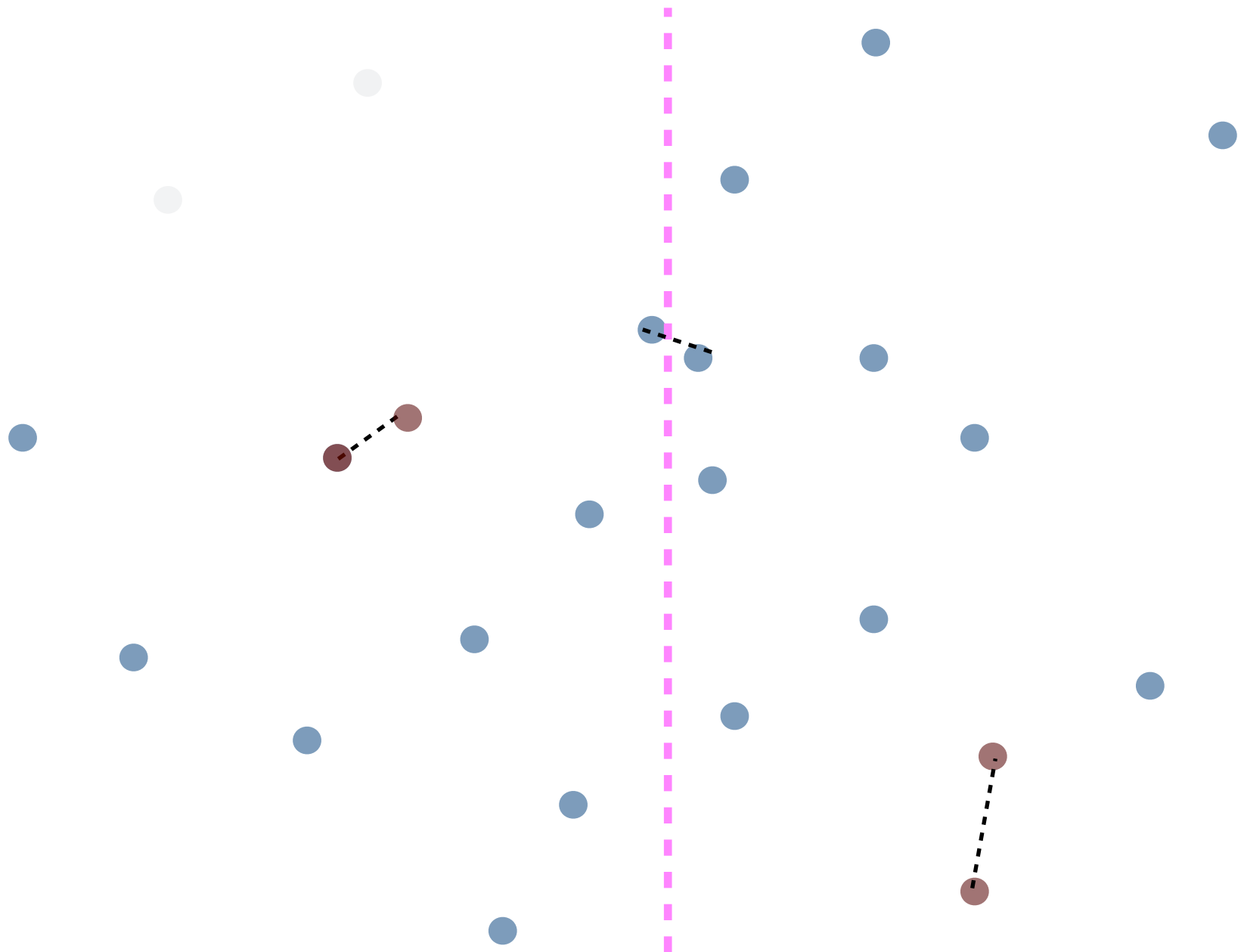
- mindist=infinity
- for each p in P_1 , for each q in P_2
 - compute distance $d(p,q)$
 - $\text{mindist} = \min\{d_1, d_2, d(p,q)\}$

//return smallest of the three

- return $\min\{d_1, d_2, \text{mindist}\}$

Is this correct?

Closest pair, divide-and-conquer



Closest pair, divide-and-conquer

Correct, because the closest pair in P must be one of:

- **Both points are in P_1 :** then it is found by the recursive call on P_1
- **Both points are in P_2 :** then it is found by the recursive call on P_2
- **One point is in P_1 and one in P_2 :** then it is found in the merge phase, because the merge phase considers all such pairs

Closest pair, divide-and-conquer

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//return smallest of the three

- return $\min\{d_1, d_2, \text{mindist}\}$

Running time?

Closest pair, divide-and-conquer

FindClosestPair(P)

//basecase

- if P has 1 point, return infinity
- if P has 2 points, return their distance
- else
 - find vertical line that splits P in half
 - let P₁, P₂ = set of points to the left/right of line
 - d₁ = FindClosestPair(P₁)
 - d₂ = FindClosestPair(P₂)

//compute closest pair across

- mindist=infinity
- for each p in P₁, for each q in P₂
 - compute distance d(p,q)
 - mindist = min{d₁, d₂, d(p,q)}

//return smallest of the three

- return min {d₁, d₂, mindist}

Running time?

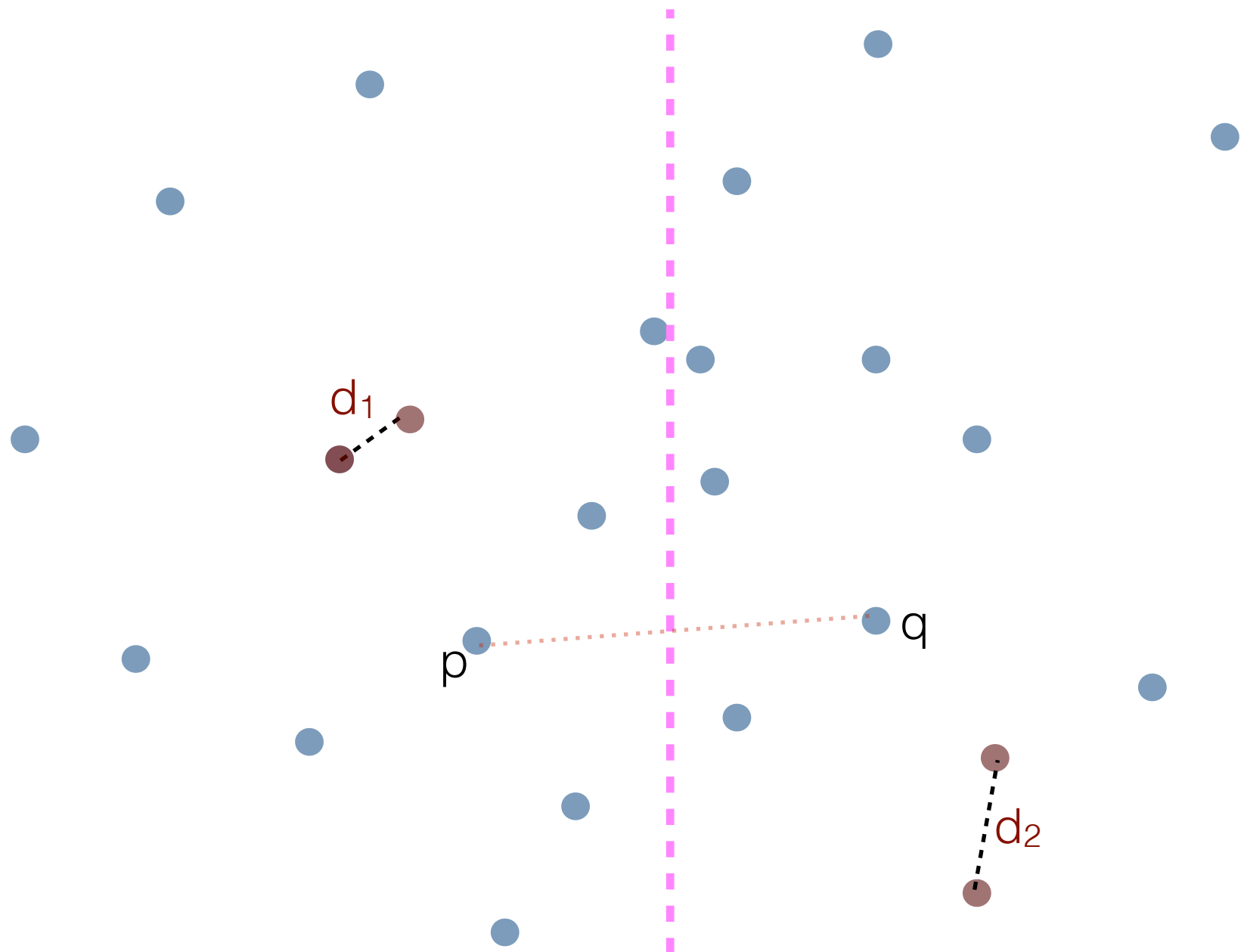
$$T(n) = 2T(n/2) + O(n^2)$$

solves to $O(n^2)$

Can we do better?

Refining the merge

Do we need to examine all pairs (p,q) , with p in P_1 , q in P_2 ?

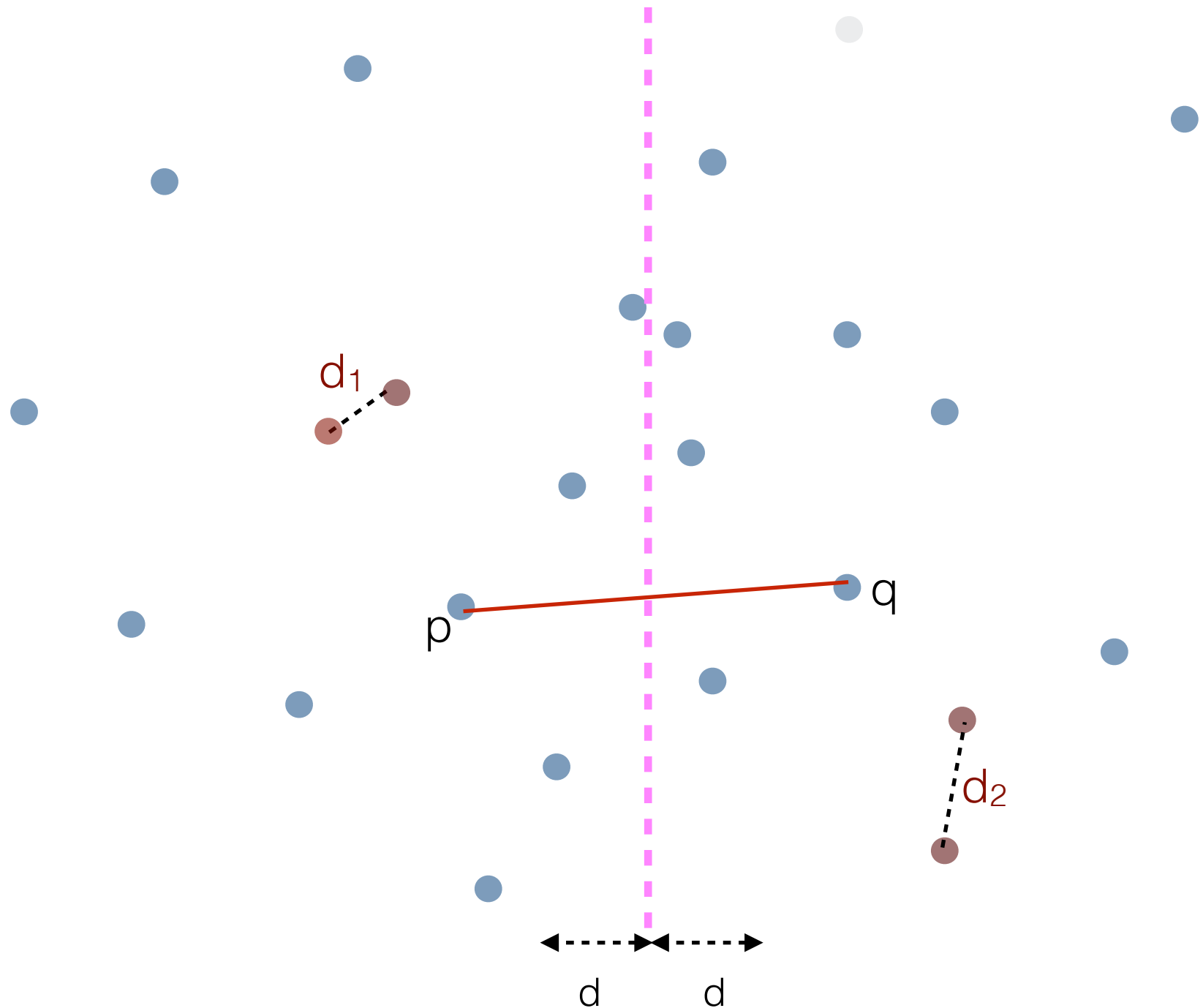


Can (p,q) be the closest pair?

Why not?

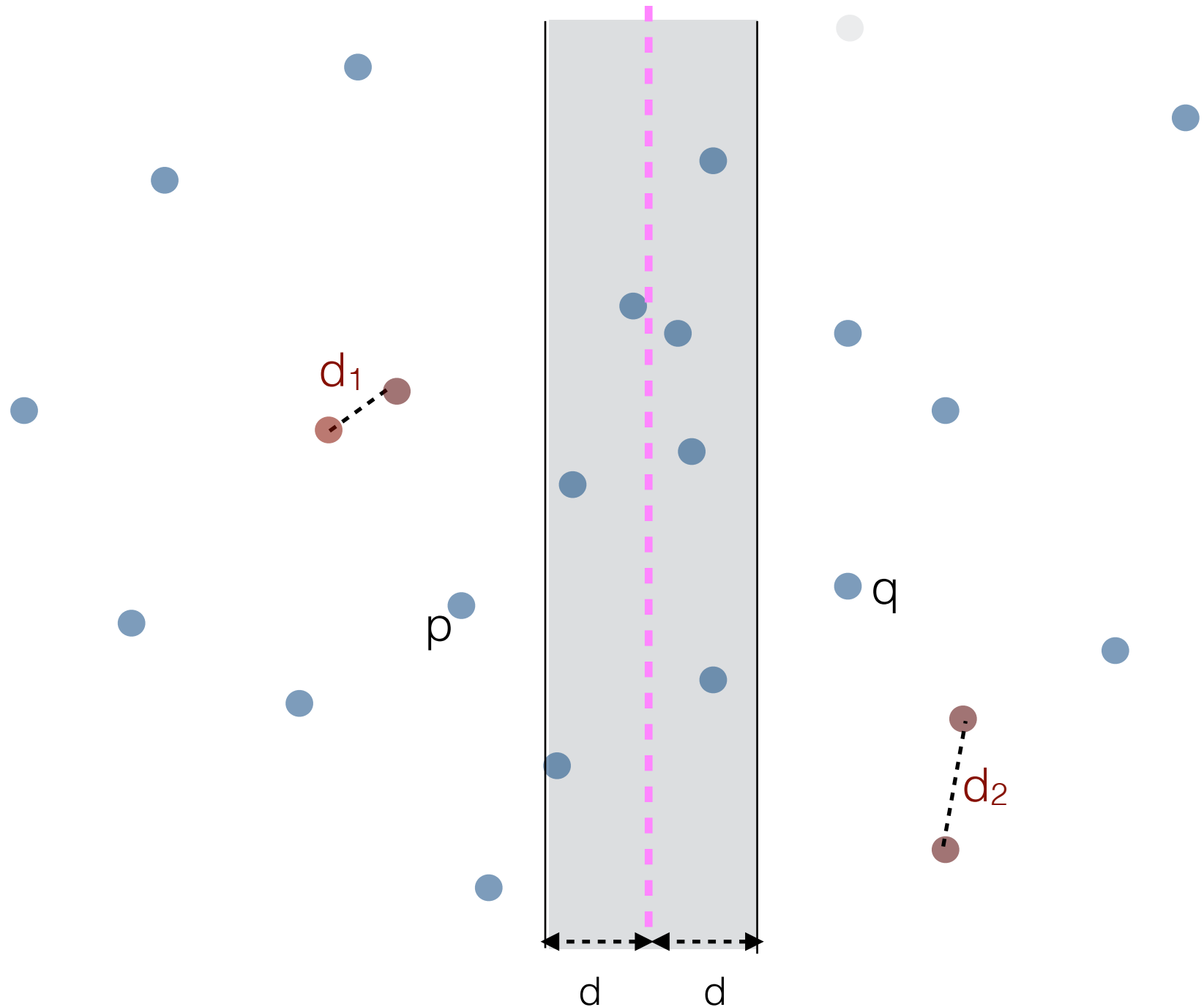
Notation: $d = \min \{d_1, d_2\}$

Claim: In order for $\text{dist}(p,q)$ to be smaller than d , it must be that both the horizontal and vertical distance between p and q must be smaller than d .



Notation: $d = \min \{d_1, d_2\}$

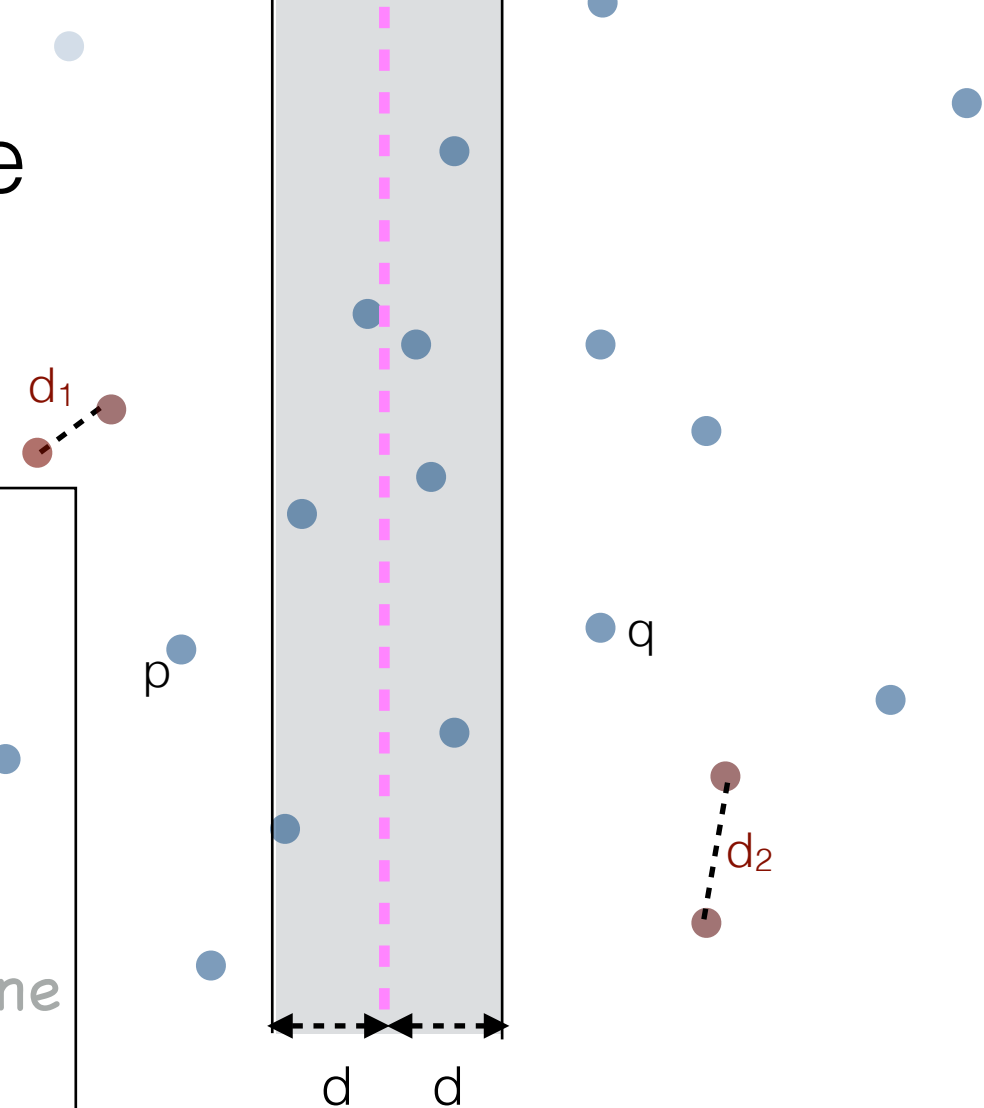
\Rightarrow In order to be candidates for closest pair, points p, q must lie in the d -by- d strip centered at the median.



Refining the merge

FindClosestPair(P)

- if P has 1 point, return infinity
- if P has 2 points, return their distance
- else
 - find vertical line that splits P in half
 - let P_1, P_2 = set of points to the left/right of line
 - $d_1 = \text{FindClosestPair}(P_1)$
 - $d_2 = \text{FindClosestPair}(P_2)$
 - traverse P_1 and select all points P_1' in the strip
 - traverse P_2 and select all points P_2' in the strip
 - for each p in P_1'
 - for each point q in P_2'
 - compute distance $d(p,q)$
 - $\text{mindist} = \min\{d_1, d_2, d(p,q)\}$
- return $\min\{d_1, d_2, \text{mindist}\}$

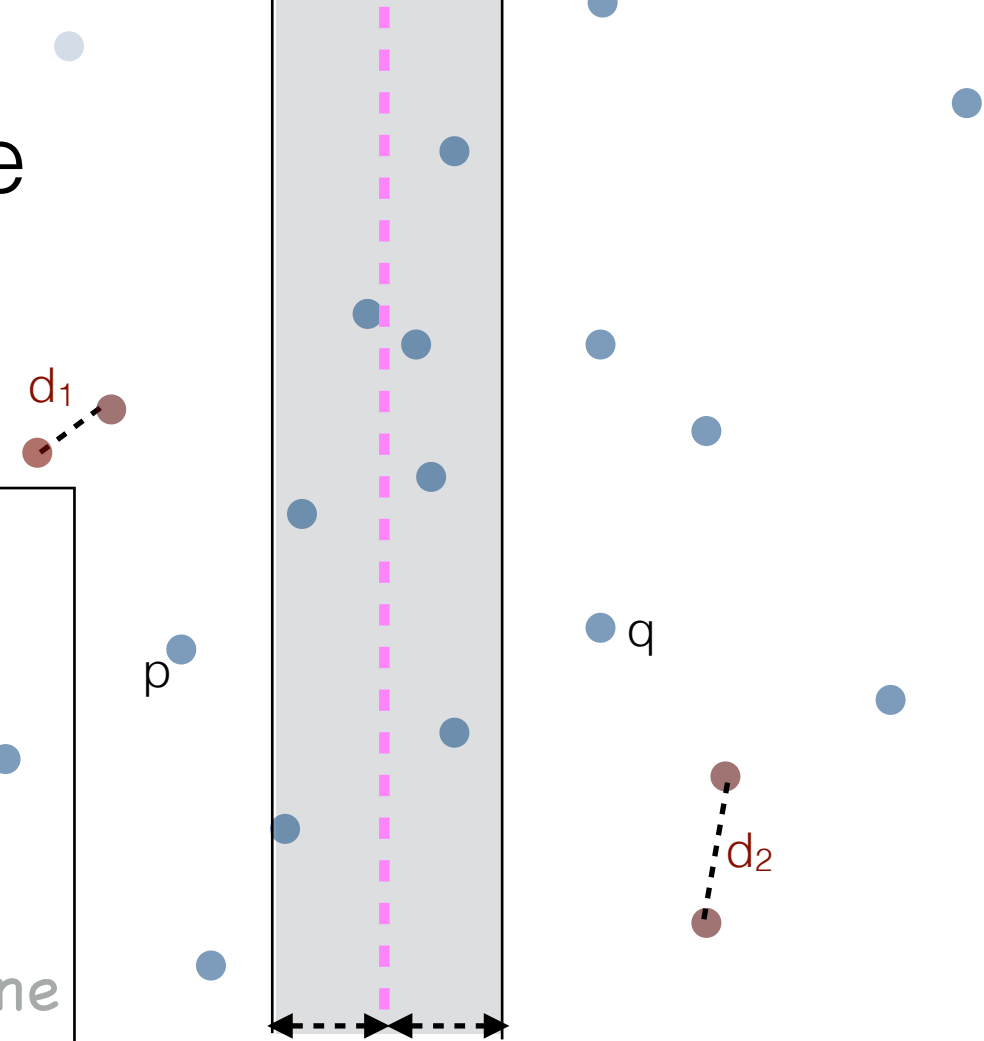


Running time?

Refining the merge

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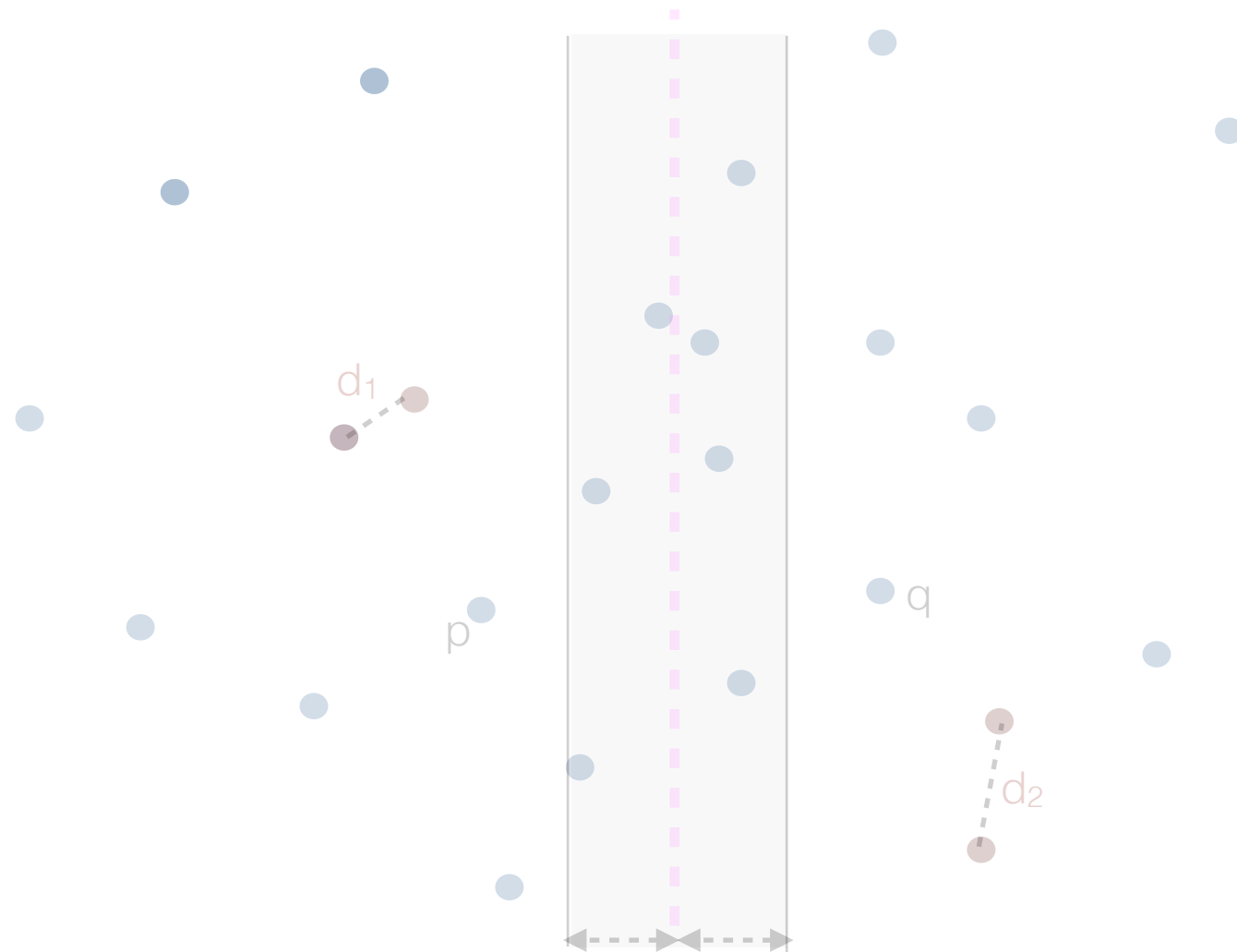


Running time?

It's possible that all $n/2$ points on either side lie inside the strip

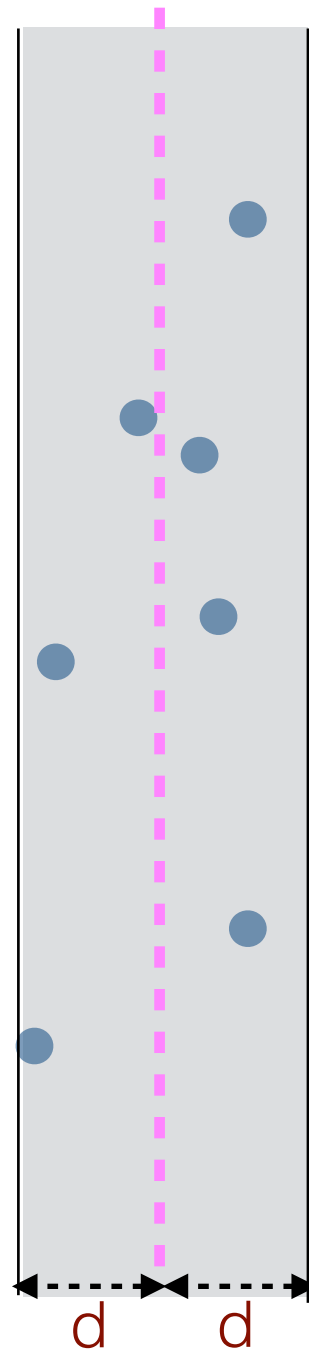
Refining the merge

- Show an example where the strip may contain $\Omega(n)$ points.
- What does this imply for the running time?



Refining the merge

- Filtering the points in the strip is not enough..
- But, we can show that the points in the strip have a special structure which will enable us to merge faster

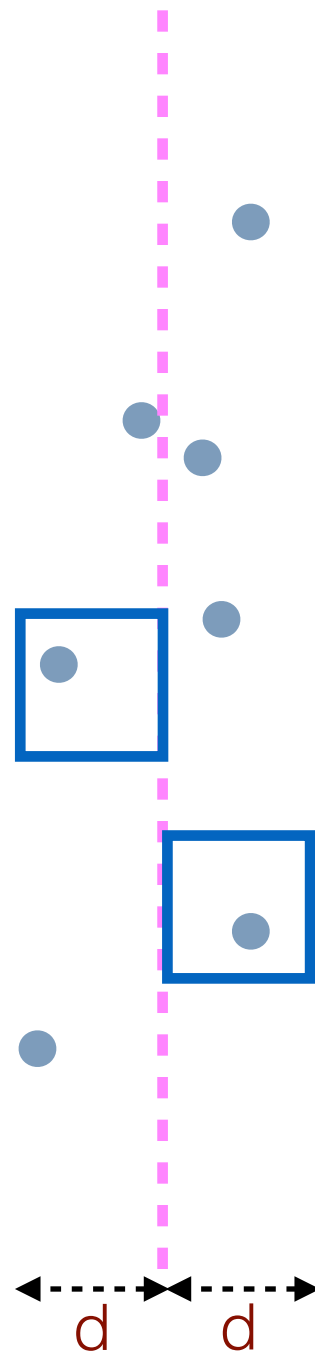


Refining the merge

Points on both sides are “sparse”

Any pair of points in P_1
must be at least d away

Any pair of points in P_2
must be at least d away



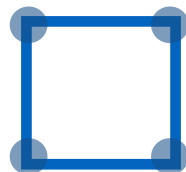
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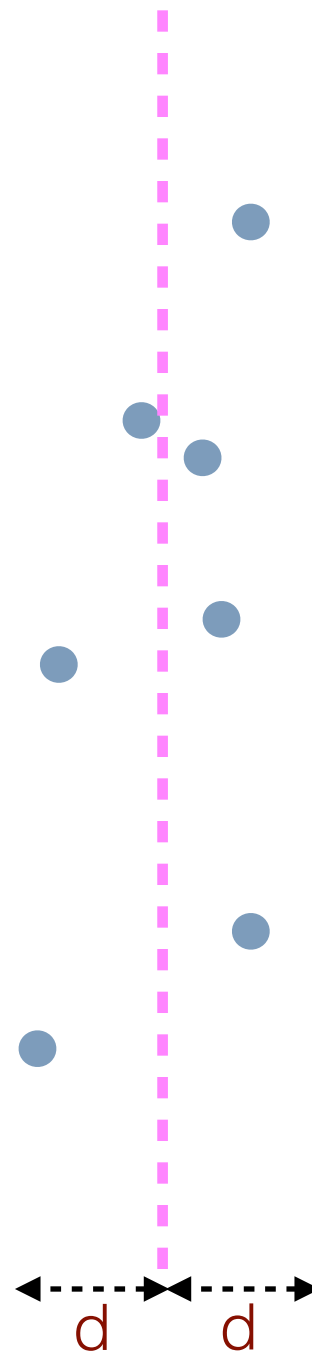
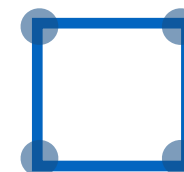
Any square with side d
contains at most 4 points of P_1



Any pair of points in P_2
must be at least d away

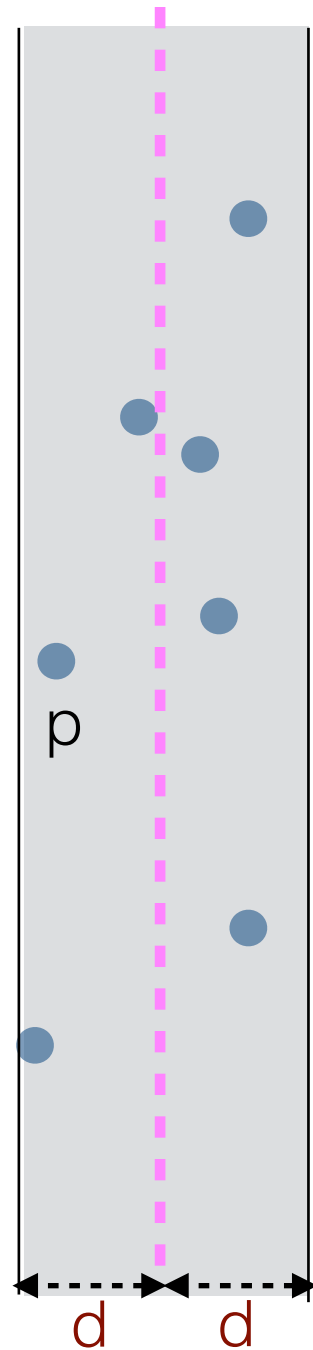


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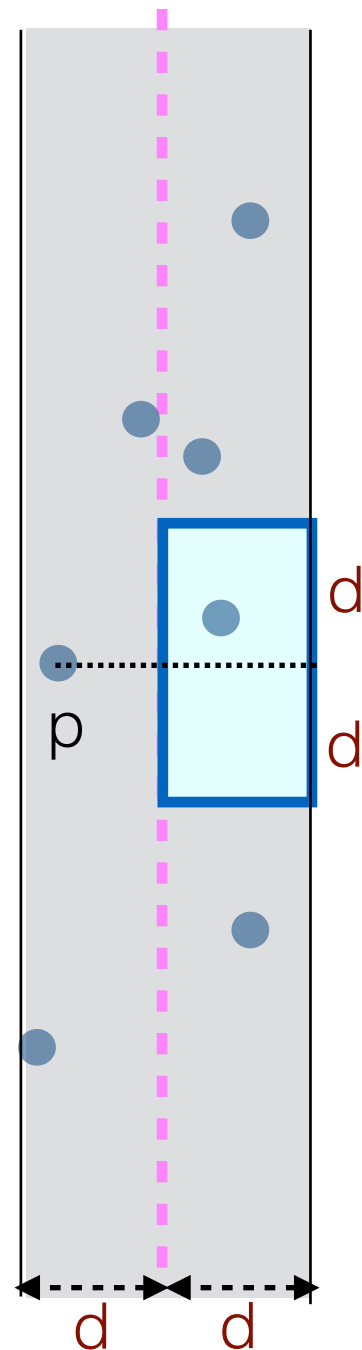
How can we use this?

- Consider a point p in P_1'
- We don't need to compute the distances from p to all points in P_2'



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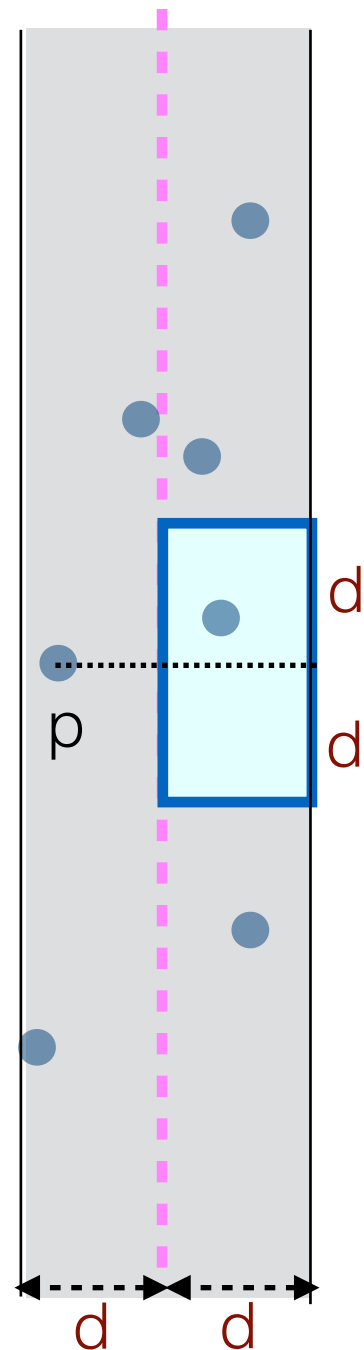
- Consider a point p in P_1'
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- CLAIM: All points of P_2' within distance d of p are vertically above or below p by at most d
 \implies they must lie in a rectangle $d \times 2d$

How can we use this?

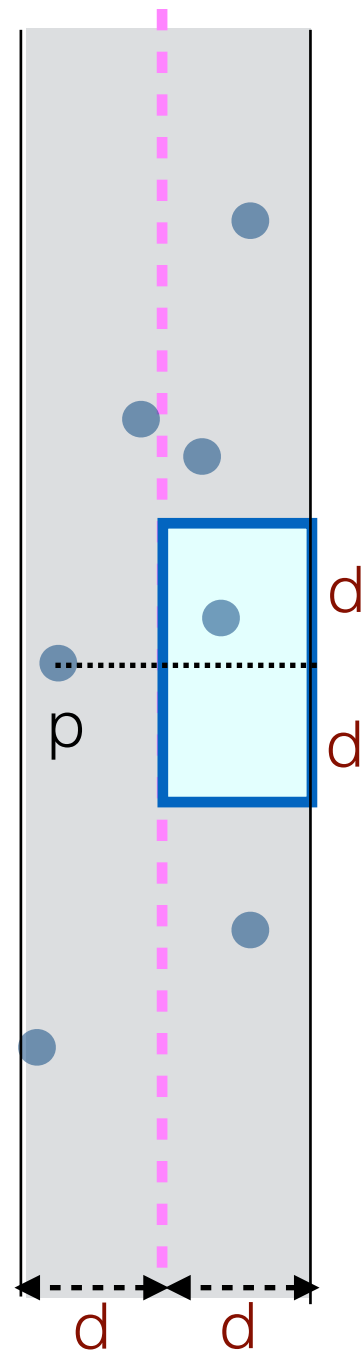
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- How many points q of P_2' can there be in a rectangle of size $d \times 2d$? (knowing that any pair of points in P_2' must be at least d away).

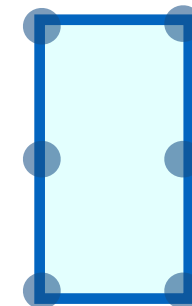
Refining the merge

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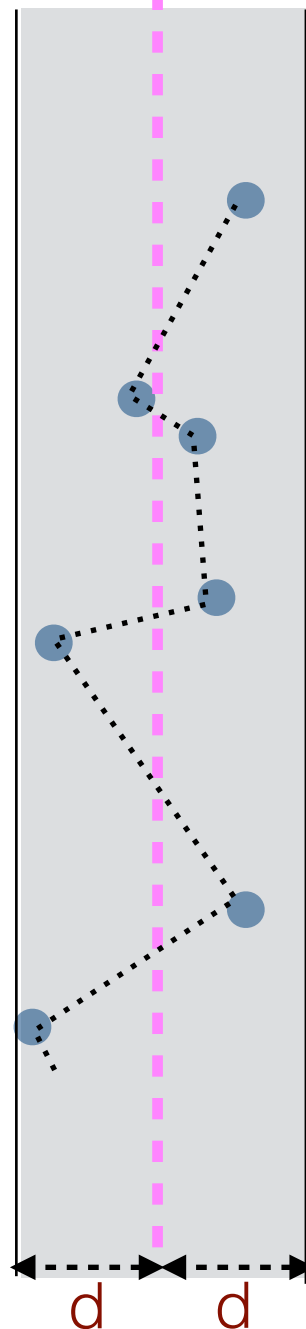
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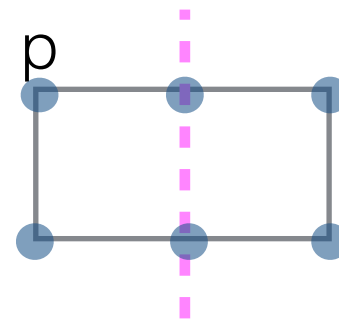
\implies So for every p in P_1' , we only need to check at most 6 points!

Refining the merge

- An elegant (simple?) way to do this is by traversing the points in P_1' and P_2' in y-order
- A point p needs to check only the points following it, and there can be at most 5 points following p in y-order that are within d from p .



Note: Assume no duplicate points.



Refining the merge

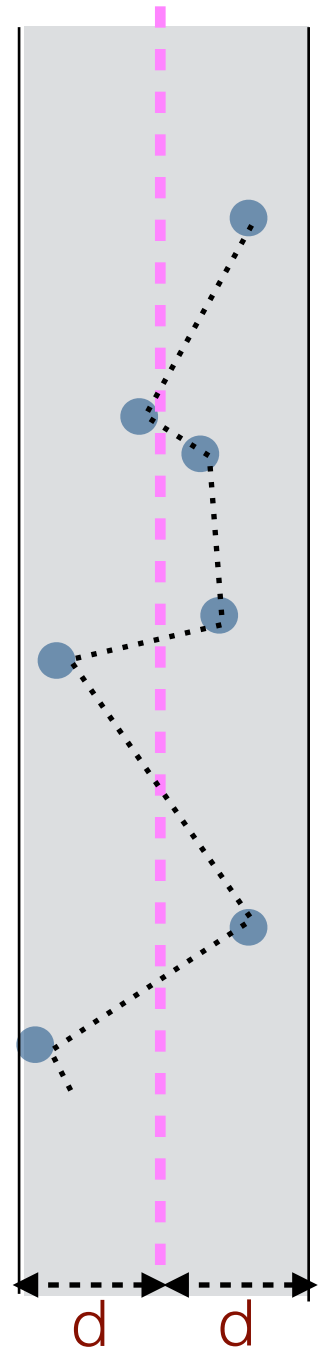
closestPair(P)

//divide

- find vertical line l that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- $d_1 = \text{closestPair}(P_1)$
- $d_2 = \text{closestPair}(P_2)$

//merge

- let $d = \min\{d_1, d_2\}$
- Strip = empty
- for all p in P_1 : if $x_p > x_l - d$: add p to Strip
- for all p in P_2 : if $x_p < x_l + d$: add p to Strip
- sort Strip by y -coord
- initialize mindist = d
- for each p in Strip in sorted order
 - compute its distance to the 5 points that come after it in sorted order
 - if any of these is smaller than mindist, update mindist
- return mindist



Refining the merge

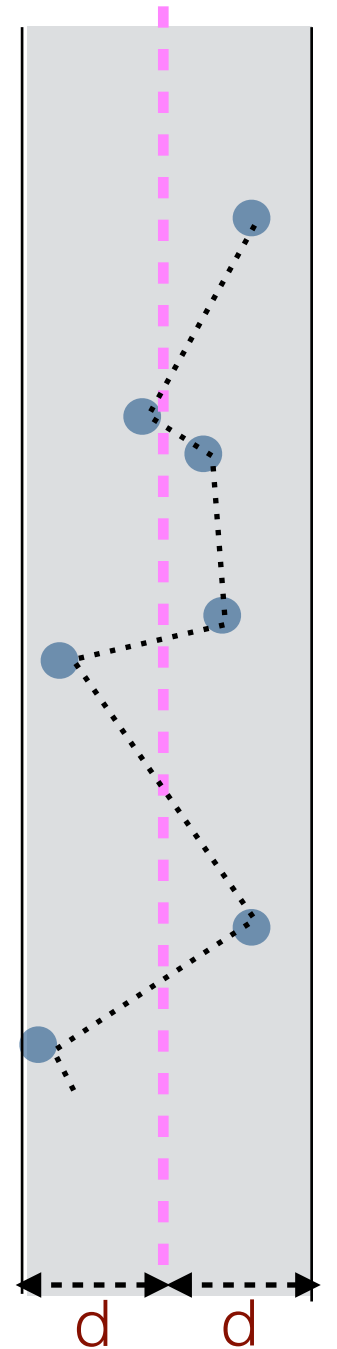
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Analysis: $T(n) = 2T(n/2) + O(n \lg n) \Rightarrow O(n \lg^2 n)$

Closest pair, divide-and-conquer

- The sorted list of points in the strip can be obtained from pre-sorting P

closestPair($P_{\text{sorted_by_x}}$, $P_{\text{sorted_by_y}}$)

- Sort P at the beginning and maintain it through recursion
- Final recurrence is $T(n) = 2T(n/2) + O(n)$, which solves to $O(n \lg n)$