# **LAUREN JONES**

ljones46@calpoly.edu • 916-517-5383

http://www.linkedin.com/in/lauren-d-jones • https://github.com/laurendjones

#### **EDUCATION**

# CALIFORNIA POLYTECHNIC UNIVERSITY, SAN LUIS OBISPO, CA

**AUG 2022-PRESENT** 

Bachelor of Science, Computer Engineering.

• Data Structures, Digital Design. Enrolled next quarter: Object-Oriented Programming, Computer Design & Assembly

### ST. FRANCIS HIGH SCHOOL, SACRAMENTO, CA

AUG 2018-MAY 2022

#### **EXPERIENCE**

# **CAL POLY RACING BAJA SAE**

Electronics Lead

SEP 2022-PRESENT JUNE 2023-PRESENT

- Designed two PCBs in Altium for the 2024 car: Semi-Active Suspension Controller and Radio.
  - Semi-Active Suspension PCB features a STM32 microcontroller that drives 4 solenoid valves by providing a range of PWM values.
  - Radio PCB that facilitates wireless data communication between the car and home pit and features an Xbee, STM32, and 12V to 3V3 buck controller.
- Developed two schematics for the motherboard PCB.
  - 12V to 5V buck controller schematic for the car's powerboard PCB.
  - Solenoid driver schematic that features overcurrent protection for the car's backplane PCB.
- Created an Xbee network and antenna architecture for a wireless data acquisition system to communicate from the car to home pit with an approximate range of 2 miles.
  - Implemented an XBee network that forwards a data packet, in C++, from a Data Aguisition PCB (DAQ) to an STM32 to an XBee network.
  - Building a live webserver in Python, HTML, Javascript to display sensor data; reads serial from an Xbee.

#### **Electronics Member**

**SEP 2022-JUNE 2023** 

- Designed a live webserver; Created an Xbee network architecture for wireless data communication.
- Developed software in C++ for various car projects: lookup tables for the transmission and sensor integration.

# **GENESEAS ROBOTICS**

**AUG 2019-JULY 2022** 

#### Software Lead and CMO

- Developed a Remotely Operated Vehicle (ROV) designed to perform a variety of marine sustainability tasks through MATE Robotics. Geneseas placed 4th overall at the MATE ROV World Championships.
- Created a new system of power-limiting algorithms in C++ that control the parameters of thruster outputs.
- Built a GUI in Python with full software control of vision and image and live video recognition systems.
- Designed an array of marketing posters and a 25-page technical report using Adobe InDesign. Geneseas' Marketing Display placed 1st at the World Championships and was published in the Journal of Ocean Technology.

#### AEROSPACE MUSEUM OF CALIFORNIA

JUNE 2022-AUG 2023

### STEM Summer Camp Counselor

Taught STEM curriculum in three disciplines: Aviation, Space, and Engineering to over 625 students.

# SECURE AUTOMOTIVE CONTROL FIRMWARE, MIT

**JULY 2021** 

- Developed firmware and bootloader updates encrypted by AES-128 GCM and HMAC SHA-256.
  - Firmware defends against Man in the Middle attacks, buffer overflows, cryptographic signature attacks, and flash memory read attacks.

#### SKILLS

- Programming Experience: C++, Python, C, HTML, CSS, Javascript.
- Cisco Networking Certifications: Cybersecurity Essentials, Introduction to Cybersecurity, Introduction to Packet Tracer, Linux Unhatched.
- Technical Skills: Cybersecurity, Cryptography, Network Security, Arduino, Git, Altium PCB Design, Circuit Design.