# Exam #2

**Instructions.** This is a 150-minute test. You may use your notes. You may assume anything that we proved in class or in the homework is true.

Question	Score	Points
1		10
2		10
3		10
4		10
5		10
Out Of		50

Name:	
edX Username:	

## 1. [Basic Probability]

Consider a joint distribution on X, Y, with  $\text{Prob}(X = i, Y = j) = p_{ij}$ , where  $X \in \{1, 2\}$  and  $Y \in \{1, 2, 3\}$ . This is summarized in the following table:

Assume  $p_{ij}$  are all positive. In the following, write your answers in terms of elements of the joint distribution above.

(a) Calculate the marginal distribution Prob(X = 2) and Prob(Y = 1).

(b) Calculate  $Prob(Y = 1 \mid X = 2)$ .

(c) Calculate the probability Prob(X < Y), where X < Y is the event that the value of X is smaller than the value of Y.

#### 2. [MLE and Bayesian Inference]

Every time when we go to Starbucks, we join a line with a number of people ahead of us. Let us build a probabilistic model to estimate the waiting time.

From queueing theory, scientists have found that when there are k people ahead of us (k is a positive integer), the waiting time X follows a Gamma distribution, denoted by  $\mathbf{Gamma}(k,\theta)$ , whose density function is defined as follows:

$$p(x \mid \theta; k) = \frac{1}{\Gamma(k)} \times \theta^k x^{k-1} \exp(-\theta x), \quad \forall x \in (0, \infty),$$

where  $\theta$  is a positive unknown parameter and  $\Gamma(k)$  is the so called Gamma function, defined by an integration:

$$\Gamma(k) = \int_0^\infty z^{k-1} \exp(-z) dz.$$

We want to estimate  $\theta$ , because once we know  $\theta$ , we would know the distribution of the waiting time when there are k people ahead. This would allow us to make prediction about the waiting time.

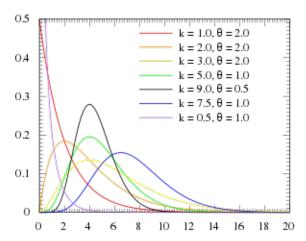
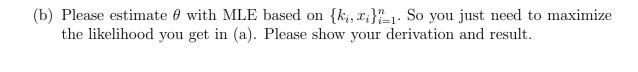


Figure 1: Examples of density functions of Gamma distributions with different parameters.

(a) Assume we went to the store for n times; at the i-th time, there were  $k_i$  people ahead and the waiting time was  $x_i$ . Assume  $\{k_i, x_i\}_{i=1}^n$  are i.i.d. for different i. Please write down the likelihood function of  $\theta$  based on those observations. Show your work.



(c) Let us consider the Bayesian approach now. Assume the prior of  $\theta$  is  $\mathbf{Gamma}(k_0, x_0)$ , where  $k_0$  and  $x_0$  are fixed and known numbers. Please derive the posterior distribution  $p(\theta \mid \{k_i, x_i\}_{i=1}^n)$ . (Hint: the posterior distribution is also a Gamma distribution, say  $\mathbf{Gamma}(k_{post}, x_{post})$ ; please decide the value of  $k_{post}$  and  $x_{post}$ )

#### 3. [Multivariate Gaussian]

Assume we have the following three dimensional normal random variable

$$\boldsymbol{X} = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 3 & 0 & -1 \\ 0 & 1 & -1 \\ -1 & -1 & 2 \end{bmatrix} \right).$$

It will be useful to know that the inverse matrix of  $\begin{bmatrix} 3 & 0 & -1 \\ 0 & 1 & -1 \\ -1 & -1 & 2 \end{bmatrix}$  is  $\begin{bmatrix} 1/2 & 1/2 & 1/2 \\ 1/2 & 5/2 & 3/2 \\ 1/2 & 3/2 & 3/2 \end{bmatrix}$ .

The inverse of  $\begin{bmatrix} 5/2 & 3/2 \\ 3/2 & 3/2 \end{bmatrix}$  is  $\begin{bmatrix} 1 & -1 \\ -1 & 5/3 \end{bmatrix}$ .

(a) Which two variables are independent with each other?

## (b) Define

$$Z = X_1 - aX_2 + bX_3, (1)$$

where  $a, b \in \mathbb{R}$  are two constants. Is it possible to set the values of a and b such that Z is independent with  $X_3$  (that is,  $Z \perp X_3$ )? If so, give an example of such a and b.

(c) For  $Z = X_1 - aX_2 + bX_3$ , is it possible to set the value of a and b such that Z is independent with  $X_2$  conditional on  $X_1 = x_1$  (i.e.,  $Z \perp X_2 \mid X_1 = x_1$ ), for any fixed value  $x_1 \in \mathbb{R}$ ? In other word, we hope to make  $X_2$  and Z independent conditional on that  $X_1$  equals to a fixed number  $x_1$ , regardless what the value of  $x_1$  is. If this can be done, give an example of (a, b) that satisfy the condition.

### 4. [Clustering, K-means]

We want to cluster the following dataset into K=3 clusters using the K-means algorithm:

$$x^{(1)} = 4,$$
  
 $x^{(2)} = 10,$   
 $x^{(3)} = 16,$   
 $x^{(4)} = 20,$   
 $x^{(5)} = 26,$ 

where each  $x^{(i)}$  is an one-dimensional data point.

(a) Please analyze how K-means updates the centroids of the clusters if we initialize the centroids of the K=3 clusters by:  $\mu_1=2, \ \mu_2=3, \ \text{and} \ \mu_3=4.$  What values would the centroids  $(\mu_1,\mu_2,\mu_3)$  converge to when K-means determines? Please show the centroid locations at each iteration of K-means. (If no points are assigned to a cluster at a given iteration, do **NOT** update its centroid).

(b)	s the solution unique regardless of the initialization? If not, show an example which the final clustering is different from what the K-means algorithm estimate (a).	

#### 5. [General Knowledge]

Please decide if the following statements are true. You can either provide a binary decision of 1 or 0, or, if you are uncertain, give a probabilisitic estimation in the interval [0,1]. An answer of 0 corresponds to deciding the statement is false and, conversely, an answer of 1 corresponds to deciding the statement is true. Assume your estimation is q, then you will get  $q \times 100\%$  credit if the statement is correct, and  $(1-q) \times 100\%$  if the statement is wrong. Your answers should not be written as 'true' or 'false', but instead be in the form of a number in the interval [0,1]. Grading will be based on the number you provide.

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Example: 1+1=2 (Answer: 0.8)

[You will get 0.8 of the credit since the statement is true.]

Example: 1+1=4 (Answer: 0.3)

[You will get 1-0.3=0.7 of the credit since the statement is false.]

Example: 1+1=3 (Answer: 0.8)

[You will get 1-0.8=0.2 of the credit since the statement is false.]
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- (a) Any random variables  $X_1$  and  $X_2$  are independent if they are uncorrelated. (Answer:
- (b) The goal for Bayesian inference is to find a parameter that maximize the posterior.

(Answer:\_\_\_\_)

(c) Assume the prior distribution of a parameter is Gaussian, then its posterior distribution is always Gaussian.

(Answer:\_\_\_\_)

(d) EM algorithm is equivalent to coordinate ascend on a tight lower bound of the marginal likelihood function, so the objective will monotonically decrease and converge to global optimal.

(Answer:\_\_\_\_)

(e) K-means guarantees to monotonically improve the loss function, and will converge within a *finite* number of steps.

(Answer:\_\_\_\_)

(f)	Assume $Q = [q_{ij}]_{ij=1}^d$ is the inverse covariance matrix (i.e. precision matrix) of a multivariate normal random variable $X = (X_1, \dots, X_d)$ . Then $X_i \perp X_j$ if and only if $q_{ij} = 0$ .
	(Answer:)
(g)	Kernel regression yields a non-convex optimization if we pick Gaussian radial basis function (RBF) kernel.
	(Answer:)
(h)	In kernel regression, if we use a kernel $k(x, x') = x^{T}x' + 1$ , we would obtain a linear function (i.e., it is effectively doing a linear regression).
	(Answer:)
(i)	Consider a simple neural network with two ReLU neurons:
	$f(x; [w_1, w_2]) = \max(0, x - w_1) + \max(0, x - w_2).$
	Then $f(x; [w_1, w_2])$ is a convex function of both $x$ and $[w_1, w_2]$ , but estimating $[w_1, w_2]$ by minimizing the mean square error (MSE) loss would yield a non-convex optimization on $[w_1, w_2]$ .

(Answer:\_\_\_\_)