

# Study Guide: PAC Learning Framework

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## 1 Introduction to PAC Learning (Section 3.1)

The **Probably Approximately Correct (PAC) Learning** framework formalizes the goal of machine learning: to find a hypothesis  $h$  that generalizes well from a limited number of training examples. A hypothesis  $h \in H$  is chosen from a hypothesis class  $H$ , and the objective is to minimize the risk  $L_D(h) = \mathbb{P}_{x \sim D}[h(x) \neq f(x)]$ , where  $f$  is the target function and  $D$  is the distribution over the domain  $\mathcal{X}$ .

### 1.1 PAC Learnability Definition

A hypothesis class  $H$  is PAC learnable if there exists an algorithm  $\mathcal{A}$ , and for every distribution  $D$ , every target function  $f$ , and for every  $\epsilon, \delta > 0$ , the algorithm produces a hypothesis  $h \in H$  such that, with probability at least  $1 - \delta$ ,

$$L_D(h) \leq \epsilon.$$

The algorithm must run in time polynomial in  $1/\epsilon$ ,  $1/\delta$ , and the size of the input.

### 1.2 Sample Complexity

The number of training examples required to guarantee PAC learnability is called the **sample complexity**. For a hypothesis class  $H$ , the sample complexity is a function of  $\epsilon$ ,  $\delta$ , and the complexity of  $H$ . Generally, the sample complexity grows with the size of  $H$ , as larger hypothesis classes have more potential to overfit the data.

## 2 Uniform Convergence (Section 3.2)

A key concept in PAC learning is **uniform convergence**, which guarantees that the empirical risk  $L_S(h)$  is close to the true risk  $L_D(h)$  for all hypotheses  $h \in H$ . This ensures that minimizing the empirical risk leads to a hypothesis with low true risk.

### 2.1 Empirical Risk Minimization (ERM)

The Empirical Risk Minimization (ERM) principle selects the hypothesis  $h \in H$  that minimizes the empirical risk over the sample  $S$ :

$$L_S(h) = \frac{1}{|S|} \sum_{i=1}^{|S|} \mathbb{I}[h(x_i) \neq f(x_i)].$$

Uniform convergence ensures that, with high probability,  $L_D(h) \approx L_S(h)$ .

### 2.2 VC Dimension and Learnability (Section 3.3)

The **VC (Vapnik-Chervonenkis) dimension** is a measure of the capacity or complexity of a hypothesis class. A class  $H$  can shatter a set of  $m$  points if, for every possible labeling of the points, there exists a hypothesis in  $H$  that perfectly classifies them. The VC dimension of  $H$ , denoted as  $\text{VC}(H)$ , is the maximum number of points that  $H$  can shatter.

**Theorem (PAC Learnability and VC Dimension):** A hypothesis class  $H$  is PAC learnable if and only if  $\text{VC}(H)$  is finite.

### 3 Agnostic PAC Learning (Section 3.4)

In the **agnostic setting**, we relax the assumption that the target function  $f$  belongs to the hypothesis class  $H$ . Here, the goal is to find the hypothesis  $h \in H$  that minimizes the *true risk*:

$$h^* = \arg \min_{h \in H} L_D(h).$$

The PAC framework can be extended to the agnostic setting, and the sample complexity depends on both  $\epsilon$  and the approximation error of the best hypothesis in  $H$ .

### 4 Summary (Section 3.5)

- The PAC learning framework provides a formal method for understanding learnability, based on the probability of producing a hypothesis with low error.
- Uniform convergence and the VC dimension are central concepts in determining whether a hypothesis class is PAC learnable.
- In agnostic PAC learning, the goal is to minimize the true risk even when the target function may not belong to the hypothesis class.

# Brief Study Guide on PAC Learning on a Finite Hypothesis Class

## Study Notes

### 1 Overview of PAC Learning

PAC (Probably Approximately Correct) learning is a framework in machine learning introduced by Leslie Valiant in 1984. It formalizes the concept of learning a function from a set of examples, providing theoretical guarantees on how efficiently a learning algorithm can approximate an unknown target function.

The key objective in PAC learning is to learn a hypothesis  $h$  from a finite hypothesis class  $H$ , based on random samples drawn from a distribution  $D$ , such that the hypothesis closely approximates the unknown target function  $f$ .

In PAC learning, the goal is to find a hypothesis  $h \in H$  that has low error with high probability. More formally, the learner must find  $h$  such that with probability at least  $1 - \delta$ , the hypothesis  $h$  has error less than  $\epsilon$ , where  $\epsilon$  is the allowable error and  $\delta$  is the failure probability.

### 2 How PAC Learning Works

PAC learning operates with the following key components:

- **Target Function  $f$ :** An unknown function mapping inputs to outputs.
- **Hypothesis Class  $H$ :** A finite set of candidate hypotheses, one of which is to be selected based on training data.
- **Distribution  $D$ :** A fixed but unknown distribution from which the training examples are drawn.
- **Error  $\epsilon$ :** A small parameter representing the allowable error. The goal is to find a hypothesis  $h \in H$  whose error is less than  $\epsilon$  with high probability.
- **Confidence  $1 - \delta$ :** A parameter specifying the probability that the learning algorithm successfully finds a good hypothesis. The algorithm is allowed to fail with probability at most  $\delta$ .

The hypothesis  $h$  is considered PAC-learned if:

$$\Pr_{x \sim D} (h(x) \neq f(x)) < \epsilon$$

with probability at least  $1 - \delta$ .

### 3 Sample Complexity for a Finite Hypothesis Class

When the hypothesis class  $H$  is finite, the sample complexity, or the number of training examples  $m$  required to PAC-learn the target function, can be derived as follows:

$$m \geq \frac{\log \left( \frac{|H|}{\delta} \right)}{\epsilon}$$

This formula gives the minimum number of samples needed to ensure that, with high probability, the hypothesis  $h$  will have an error of at most  $\epsilon$ . The components of the formula are:

- $|H|$ : The number of hypotheses in the hypothesis class. The larger the hypothesis class, the more samples we need to distinguish between the hypotheses.
- $\delta$ : The confidence parameter. A smaller  $\delta$  (higher confidence) requires more samples.
- $\epsilon$ : The accuracy parameter. A smaller  $\epsilon$  (lower error) requires more samples.

This formula shows that the number of samples depends logarithmically on the size of the hypothesis class, meaning that even a modest increase in the number of hypotheses can lead to a significant increase in the required sample size.

## 4 How to Tell if a Function is PAC Learnable (Finite Case)

In the finite hypothesis case, the learnability of a function class  $H$  depends on the following conditions:

- **Finite Hypothesis Class:** The hypothesis class  $H$  must be finite. If  $|H|$  is finite, the formula for sample complexity applies directly.
- **Efficient Algorithm:** There must exist a learning algorithm that can output a hypothesis that meets the PAC learning criteria (i.e., within  $\epsilon$  error and  $1 - \delta$  confidence).

The sample complexity formula  $m \geq \frac{\log(\frac{|H|}{\delta})}{\epsilon}$  shows that if we can get enough samples, the hypothesis class is PAC-learnable.

## 5 Solving a Simple PAC Learning Problem

Consider a finite hypothesis class  $H$  consisting of 100 different hypotheses. Suppose we want to PAC-learn the target function with error  $\epsilon = 0.05$  and confidence  $1 - \delta = 0.99$  (i.e.,  $\delta = 0.01$ ).

### 5.1 Problem:

How many samples  $m$  are required to PAC-learn the target function with these parameters?

### 5.2 Solution Outline

We use the sample complexity formula for a finite hypothesis class:

$$m \geq \frac{\log\left(\frac{|H|}{\delta}\right)}{\epsilon}$$

Substitute the values:

$$\begin{aligned} |H| &= 100 \\ \delta &= 0.01 \\ \epsilon &= 0.05 \end{aligned}$$

Calculate the logarithmic term:

$$\log\left(\frac{|H|}{\delta}\right) = \log\left(\frac{100}{0.01}\right) = \log(10,000) = 4 \log(10) = 4 \times 2.3026 = 9.2103$$

Plug in the values:

$$m \geq \frac{9.2103}{0.05} = 184.21$$

Thus, at least 185 samples are required to PAC-learn the target function with error  $\epsilon = 0.05$  and confidence  $1 - \delta = 0.99$ .

## 6 Summary

- In PAC Learning with a finite hypothesis class, the goal is to find a hypothesis  $h \in H$  that approximates the unknown target function  $f$  with low error and high probability.
- The sample complexity for PAC learning depends on the size of the hypothesis class  $|H|$ , the error  $\epsilon$ , and the confidence  $1 - \delta$ .
- The formula for the number of samples needed to PAC-learn a finite hypothesis class is:

$$m \geq \frac{\log\left(\frac{|H|}{\delta}\right)}{\epsilon}$$

- For a finite hypothesis class, the number of samples grows logarithmically with the size of the class, meaning that even a modest increase in the number of hypotheses can significantly increase the sample size required for learning.