

Optimization Project in Energy PGE 306

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2 ON/OFF devices

Hydro valley

Indices

- Set of dams \mathcal{I}
- Set of rivers $\mathcal{E} \subset \mathcal{I} \times \mathcal{I}$:
 $(i, j) \in \mathcal{E} \iff$ river flows from dam i to dam j .
- Set of time intervals: $\{1, \dots, T\}$.

Optimization variables

- $q_{i,t}$: water level of dam i at the beginning of time interval $t \in \{1, \dots, T + 1\}$
- $x_{i,t}$: amount of water exploited at dam i during time interval $t \in \{1, \dots, T\}$
- $y_{(i,j),t}$: amount of water transported over the river (i, j) during the time interval $t \in \{1, \dots, T\}$
- $z_{i,t}$: amount of water exploited at dam i during the time interval $t \in \{1, \dots, T\}$, not transported to any other dam.

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Parameters

- $P_{i,t}$: precipitation at i , during the time interval t
- Q_i : storage capacity of dam i
- K_i : initial level of dam i
- D_t : electricity demand during the time interval t

Functions

- $f_i: x \mapsto f_i(x)$: exploitation cost on a given time interval at dam i , as a function of the amount of exploited water x .
- $g_i: x \mapsto g_i(x)$: electricity production as a function of the amount of exploited water at dam i .

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Cost function

$$\min_{q,x,y,z} \sum_{t=1}^T \sum_{i \in I} f_i(x_{i,t}).$$

Constraints

- Nonnegativity of the variables:

$$q_{i,t} \geq 0, \quad x_{i,t} \geq 0, \quad y_{(i,j),t} \geq 0, \quad z_{i,t} \geq 0.$$

- Bounds:

$$q_{i,t} \leq Q_i, \quad \forall t \in \{1, \dots, T+1\}.$$

- Initial condition:

$$q_{1,i} = K_i.$$

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- Demand satisfaction:

$$\sum_{i \in \mathcal{I}} g_i(x_{i,t}) = D_t, \quad \forall t \in \{1, \dots, T\}.$$

- Evolution of the water level in each dam:

$$q_{i,t+1} = q_{i,t} + P_{i,t} - x_{i,t} + \sum_{\substack{j \in \mathcal{I} \\ (j,i) \in \mathcal{E}}} y_{(j,i),t}, \quad \forall t \in \{1, \dots, T\}.$$

- Amount of exploited water:

$$x_{i,t} = \sum_{\substack{j \in \mathcal{I} \\ (i,j) \in \mathcal{I}}} y_{(i,j),t} + z_{i,t}, \quad \forall t \in \{1, \dots, T\}.$$

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Dynamic programming.

We parametrize the problem by

- the initial time interval t
- the initial level of water in every dam $q \in \mathbb{R}^I$.

Let $V(t, q)$ denote the corresponding optimal cost.

We have $V(T + 1, q) = 0$.

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Dynamic programming principle

Let $t \in \{1, \dots, T\}$ and let $q \in \prod_{i \in \mathcal{I}} [0, Q_i]$. Then

$$V(t, q) = \inf_{\substack{q' \in \mathbb{R}^{\mathcal{I}}, x \in \mathbb{R}^{\mathcal{I}}, \\ y \in \mathbb{R}^{\mathcal{E}}, z \in \mathbb{R}^{\mathcal{I}}}} \left(\sum_{i \in \mathcal{I}} f_i(x_i) \right) + V(t+1, q'), \quad (DP(t, q))$$

subject to:

- Non-negativity: $q'_i \geq 0$, $x_i \geq 0$, $y_{(i,j)} \geq 0$, $z_i \geq 0$.
- Bounds: $q'_i \leq Q_i$.
- Demand: $\sum_{i \in \mathcal{I}} g_i(x_i) = D_t$.
- Conservation: $q'_i = q_i + P_{i,t} - x_i + \sum_{\substack{j \in \mathcal{I} \\ (j,i) \in \mathcal{E}}} y_{(j,i)}$.
- Exploitation : $x_i = \sum_{\substack{j \in \mathcal{I} \\ (i,j) \in \mathcal{I}}} y_{(i,j)} + z_i$.

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Remarks.

- Why does it work?
 - The level of water in the dams at time t is a **sufficient information** to take optimal decisions from t until the end of the optimization process.
 - Knowing the level of water in the dams at time t , one can completely **forget** what happened in the past.
- The dynamic programming principle characterizes globally optimal solutions, even if the original problem is non convex.
- In the practical implementation of the method, one needs to **discretize** the variable q . The number of discretization points grows **exponentially** with the number of dams. This phenomenon is called **curse of dimensionality**.

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ON/OFF devices

Context:

- Set of $\{1, \dots, I\}$ production units (e.g. nuclear power plants).
- These plants can be put into standby and reactivated after some time, at some time to be optimized.

Constraints on disactivation and activation (unit i):

- Maximal activity duration: X_i^{on} days.
- Minimal standby duration: X_i^{off} days.

Decision variables on time interval t , associated with unit i :

- Production $u_i(t)$ (if i is activated).
- Activation/Disactivation/No change.

ON/OFF devices

States set:

The set \mathcal{X}_i describes of possible states of the unit i .

It is defined by

$$\mathcal{X}_i = \{(0, x) \mid x = 0, \dots, X_i^{\text{off}}\} \cup \{(1, x) \mid x = 0, \dots, X_i^{\text{on}}\}.$$

Interpretation:

- $(0, x)$: unit i has been OFF for x days,
- $(1, x)$: unit i has been ON for x days.

If the unit i has been OFF for strictly more that X_i^{off} , the state is represented by $(0, X_i^{\text{off}})$.

ON/OFF devices

Transitions:

We denote $\mathcal{E}_i \subset \mathcal{X}_i \times \mathcal{X}_i$ the set of possible transitions from one state to the other. We have

Transition e	Coût $f(e)$
$(1, x) \rightarrow (1, x + 1), \quad x = 0, \dots, X_i^{\text{on}} - 1$	0
$(1, x) \rightarrow (0, 0), \quad x = 0, \dots, X_i^{\text{on}} - 1$	0
$(0, x) \rightarrow (0, x + 1), \quad x = 0, \dots, X_i^{\text{off}} - 1$	0
$(0, X_i^{\text{off}}) \rightarrow (0, X_i^{\text{off}})$	0
$(0, X_i^{\text{off}}) \rightarrow (1, 0)$	$C_i > 0$

The only transition with non-zero cost is the one corresponding to the activation of unit i .

ON/OFF devices

Other parameters:

- $D(t)$: electricity demand on interval t
- U_i : maximal production of unit i (if the unit is activated).

Optimization variables:

- $x_i(t)$: state of the unit i at the beginning of the time interval t
- $u_i(t)$: production of unit i over the interval t .

Production constraint: $(x_i(t), u_i(t)) \in \mathcal{C}_i$, where

$$\mathcal{C}_i := \{((0, x), 0) \mid x = 1, \dots, X_i^{\text{off}}\} \cup_{u \in [0, U_i]} \{((1, x), u) \mid x = 1, \dots, X_i^{\text{on}}\}.$$

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Problem:

$$\begin{aligned} \min_{\substack{x_i(t), t=1, \dots, T+1 \\ u_i(t), t=1, \dots, t}} \quad & \sum_{t=1}^T \sum_{i=1}^I \ell_i(u_i(t)) + f_i(x_i(t), x_i(t+1)), \\ \text{subject to:} \quad & \begin{cases} (x_i(t), u_i(t)) \in \mathcal{C}_i, \\ (x_i(t), x_i(t+1)) \in \mathcal{E}_i, \\ \sum_{i=1}^I u_i(t) = d(t), \\ x_i(1) = y_i. \end{cases} \end{aligned}$$

ON/OFF devices

Dynamic programming.

We parametrize the problem by

- initial state t
- state of the units $x \in \prod \mathcal{X}_i$.

Let $V(t, x)$ denote the corresponding cost.

ON/OFF devices

Dynamic programming principle

Let $t \in \{1, \dots, T\}$ and let $x \in \prod \mathcal{X}_i$. It holds:

$$V(t, x) = \begin{cases} \inf_{\substack{x' \in \prod \mathcal{X}_i, \\ u \in \mathbb{R}^I}} \left(\sum_{i=1}^I \ell_i(u_i) + f_i(x_i, x'_i) \right) + V(t+1, x') \\ \text{subject to: } \begin{cases} (x_i, u_i) \in \mathcal{C}_i, \\ (x_i, x'_i) \in \mathcal{E}_i, \\ \sum_{i=1}^I u_i = d. \end{cases} \end{cases}$$

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Remarks.

- Originally a combinatorial problem.
- Curse of dimensionality.