Appendix 1: Management Procedures

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1 Management Procedures

1.1 Empirical

1.1.1 CCSBT

CCSBT developed an MP where The TAC is an average of candidate TACs obtained from two HCRs (?).

The first HCR used a single index for the adult stock and then increased or decreased the current catch if that index was increasing or decreasing respectively, while the second compared the current value of an index to a reference period.

In the first, the TAC is updated depending on the trend in an index (I)

$$TAC_{y+1}^{1} = TAC_{y} \times \begin{cases} 1 - k_{1}|\lambda|^{\gamma} & \text{for } \lambda < 0\\ 1 + k_{2}\lambda & \text{for } \lambda \ge 0 \end{cases}$$
 (1)

where λ is the slope in the regression of $\ln I_y$ against year for the most recent n years. k_1 and k_2 are gain parameters and γ actions asymmetry so that decreases in the index do not result in the same relative change as as an increase.

The second HCR uses both an adult and juvenile indies i.e.

$$TAC_{y+1}^2 = 0.5 \times \left(TAC_y + C_y^{\text{targ}} \Delta_y^R\right) \tag{2}$$

where

$$C_y^{\text{targ}} = \begin{cases} \delta \begin{bmatrix} \frac{I_y}{I^*} \end{bmatrix}^{1-\varepsilon_b} & \text{for } I_y \ge I^* \\ \delta \begin{bmatrix} \frac{I_y}{I^*} \end{bmatrix}^{1+\varepsilon_b} & \text{for } I_y < I^* \end{cases}$$
 (3)

$$\Delta_y^R = \begin{cases} \left[\frac{\bar{R}}{\bar{R}}\right]^{1-\varepsilon_r} & \text{for } \bar{R} \ge \mathcal{R} \\ \left[\frac{\bar{R}}{\bar{R}}\right]^{1+\varepsilon_r} & \text{for } \bar{R} < \mathcal{R} \end{cases}$$

$$(4)$$

where δ is the target catch; I^* the target adult index (e.g. a mean observed CPUE corresponding to a period where the stock was at a desired fraction of B_0 or M_{MSY}) and \bar{R} is the average recent juvenile biomass i.e.

$$\bar{R} = \frac{1}{\tau_R} \sum_{i=y-\tau_R+1}^{y} R_i \tag{5}$$

 \mathcal{R} is a "limit" level derived from the mean recruitment over a reference period; while $\varepsilon[0,1]$ actions asymmetry so that increases in TAC do not occur at the same level as decreases.

Table 1: Derivative MP tunable parameters

Parameter	Symbol	Description	Default
Gain term	b	Sets change based on adult index in	0.25
		HCR 1	
Gain term	r	Sets sets change based on recruit in-	0.75
		dex HCR 1	
Gain term	k_1	Sets decrease level when stock de-	1.5
		clines in HCR 2	
Gain term	k_2	Sets increase level when stock in-	3.0
		creases in HCR 2	
Exponent	γ	Additional decrease control in HCR	1
		2	

1.1.2 Proportional

A proportional control rule (P) is so called as the action is determined in proportion to the error between a signal and a reference value

$$C_y^{\text{targ}} = \begin{cases} \delta \begin{bmatrix} \frac{I_y}{I^*} \end{bmatrix}^{1-\varepsilon_k 1} & \text{for } I_y \ge I^* \\ \delta \begin{bmatrix} \frac{I_y}{I^*} \end{bmatrix}^{1+\varepsilon_k 2} & \text{for } I_y < I^* \end{cases}$$
 (6)

where δ is the target catch and k_1 and k_2 are the gain terms

The TAC is then the average of the last TAC and the value output by the HCR.

$$TAC_{y+1} = 0.5 \times \left(TAC_y + C_y^{\text{targ}}\right) \tag{7}$$

Table 2: Proportion MP tunable parameters

Table 2. I Toportion III tallable parameters			
Parameter	Symbol	Description	Default
Gain term	k_1	Sets decrease level when stock declines	0.25
Gain term	k_2	Sets increase level when stock in-	0.75
		creases	

1.1.3 Derivative

A derivative control rule (D) is so called as the control signal is derived from the trend in the signal, i.e. to the derivative of the error.

$$TAC_{y+1}^{1} = TAC_{y} \times \begin{cases} 1 - k_{1}|\lambda|^{\gamma} & \text{for } \lambda < 0\\ 1 + k_{2}\lambda & \text{for } \lambda \ge 0 \end{cases}$$
 (8)

where λ is the slope in the regression of $\ln I_y$ against year for the most recent n years and k_1 and k_2 are gain parameters and γ actions asymmetry so that decreases in the index do not result in the same relative change as as an increase.

The TAC is then the average of the last TAC and the value output by the HCR.

$$TAC_{y+1} = 0.5 \times \left(TAC_y + C_y^{\text{targ}}\right) \tag{9}$$

Table 3: Derivative MP tunable parameters

Table 9. Derivative wir variable parameters			
Parameter	Symbol	Description	Default
Gain term	k_1	Sets decrease level when stock de-	1.5
		clines	
Gain term	k_2	Sets increase level when stock in-	3.0
		creases	
Exponent	γ	Additional decrease control	1

1.1.4 iRate

The iRate Management Procedure uses CPUE as an index of biomass (I) and sets a total allowable catch or TAC (\bar{S}) that, over most of the range of CPUE, is proportional to that index.

In each year a smoothed index (\bar{I}) is calculated using an exponential moving average with the responsivesness control parameter, r:

$$\bar{I}_t = rI_t + (1 - r)\bar{I}_{t+1} \tag{10}$$

Higher values of r produce greater responsiveness because they put more weight on more recent values of CPUE and produce a index that is less smoothed. When r=1 there is no smoothing and $\bar{I}_t = r\bar{I}_t$. Smoothing may be advantageous in that it reduces the influence of annual random variation in CPUE due catchability or operational variations. However, smoothing also reduces adds a lag to the index.

Using \bar{I} the recommended catch scaler (\bar{S}) is calculated as follows.

$$\bar{S} = \begin{cases} 0 & \bar{I} < i_t \\ m\hat{S} & \bar{I} > i_t \\ \frac{m\hat{S}}{i_t - i_l} (\bar{I} - i_l) & \text{otherwise} \end{cases}$$
 (11)

The recommended catch scaler is used to calculate the recommended TAC (\bar{S}) by multiplying the harvest rate by the biomass index,

$$\bar{C} = \min(\bar{S}\bar{I}, u) \tag{12}$$

which is applied to the fishery in the following year,

$$C_{t+1} = \bar{C}_{\phi} \tag{13}$$

where ϕ is a lognormally distributed multiplicative error with mean of 1 and standard deviation of ε ,

$$\phi \sim LN(1,\varepsilon) \tag{14}$$

Table 4: iRate tunable parameters

Parameter	Symbol	Description	Default
Reference years	r	Years used when computing refer-	0.5
		ence values	
Responsiveness	m	Target harvest rate relative to his-	0.9
		toric levels Target harvest i.e $0.9 =$	
		90% of historic average	
Threshold index	i_t	Index at which the harvest rate is	0.7
		reduced relative to historic levels i.e.	
		0.7 = reduce harvest rate when the	
		biomas index is at 70% of historic	
		levels	
Limit index	i_l	Index at which harvest rate is zero	0.2
		relative to historic levels i.e. $0.2 =$	
		close the fishery when the biomas in-	
		dex is at 20historic levels	
Maximum change	f	Maximum allowable percenatge	0.4
		change in effort	
Maximum TAC	u	Maximum total allowable catch	1000

References

R. Hillary, A. Ann Preece, and C. Davies. MP estimation performance relative to current input cpue and aerial survey data. CCSBT Extended Scientific Committee held in Canberra, 1309(19), 2013.