OPLSS'13: Programming and Proving in Agda

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Introduction

In these lectures, we'll discuss programming and proving in the dependently typed programming language Agda [4].

Agda is a pure functional programming language, which means it's like ML/Haskell, except you're not allowed to use any effects, including termination and non-exhaustive matching (or other exceptions). However, this is often not particularly burdensome, because Termination and exhaustiveness are checked "behind the scenes," and the checkers are pretty good (also, you can always turn them off through a compiler flag if they get in the way).

In the first chapter, we'll see how to use Agda to write functional programs. Then, we'll introduce the idea of *dependent types*, which is where Agda goes beyond ML and Haskell by allowing types that mention programs. We'll see how dependent types can be used for program verification, using Okasaki's red-black trees [5] as an example.

In the second chapter, we'll look at one of the cool things you can do in a dependently typed language, which is using *universes* to build domain-specific programming languages. We'll look at a *data description language* [2, 6] and a *functor library*.

In the third chapter, we'll look at some examples of programming in an extension of Agda called *homotopy type theory*.

Agda is based on similar foundations to Coq, but the way of working with the system is somewhat different. While tactics play a central role in Coq, in Agda the emphasis is on writing proof terms directly—and Agda includes some features that Coq doesn't to make this pleasant. It's best not to go in trying to pick a winner between Agda and Coq, but to try to understand the advantages and disadvantages of both styles.

These notes assume you know simply-typed functional programming (ML or Haskell), and can work with bound variables and substitution. They also assume you have some familiarity with the *propositions-as-types* principle, where propositions are represented as types, where programs inhabiting those types correspond to proofs. I also assume you've seen a type theory with non-trivial *definitinal equality*, induced by having some notion of reduction or computation in the type system (like System F^{ω} or a dependently typed language).

Please keep in mind that these notes are a work in progress, and may be updated as the lectures progress.

Chapter 1

Extrinsic and Intrinsic Verification

This chapter will serve as a first introduction to Agda programming, and to several important ideas in dependently typed programming:

- Simply-typed functional programming works much like it does in ML/Haskell, except all functions must be total (no effects, including exceptions and non-termination).
- *Inductive families of types* allow you to define predicates that are useful for program verification. *Dependent pattern matching* is a convenient way to work with inductive families.
- Extrinsic verification is a style of program verification where you first write a function, and then separately prove a spec about.
- *Intrinsic verification* is a style of program verification where the specification and verification is baked into the code—the proof is the code.
- Finally, views are a technique for flexible, user-defined case-analysis in a dependently typed language.

1.1 Simply-typed programming

First, let's see what simply-typed programming looks like in Agda. As an example, we'll use red-black tree insertion, following Okasaki [5]. Red-black trees are a balanced binary search tree.

Red-black trees are paramtrized by the types of the keys and values stored in them. So we need a type Key of keys, and a type Value of values. But we'll also need to be able to test ordering between keys, and to do so we will define our first datatype.

1.1.1 Datatypes

In the companion code for these lectures (Preliminaries.agda), we define a datatype

data Order: Set where Less: Order

Equal : Order Greater : Order

This datatype has three constructors (Less, Greater, Equal) that are used as values and in pattern-matching, exactly like you would expect from ML or Haskell.

Set is the Agda type classifying (small) types, so you use it where you would use type in ML or * in Haskell; more on Sets later. Note the alignment of the constructors: Agda uses whitespace-sensitive layout syntax, similar to Haskell. For example,

data Order: Set where Less: Order Equal: Order Greater: Order

won't parse.

1.1.2 Modules

To parameterize the red-black tree implementation by a type of keys with a comparison function and a type of values, we can make a module with three parameters:

```
module RBT (Key : Set) (compare : Key \rightarrow Key \rightarrow Order) (Value : Set) where
```

We won't use much of Agda's module system in these lectures. For now, all you need to know is

1. A module starts with

```
module ModuleName <params> where
```

and then the body of the module is indented. The parameters are a list of (identifer: classifer) pairs, and the identifiers are bound in the body.

2. From outside the module, you can refer to components as ModuleName.<component>. When a module has parameters, you can either supply the parameters to the module as a whole, such as

```
module IntStringDict = RBT Int Int.compare String
```

If you don't do this, then each component gets separately abstracted over the parameters. For example, if there is a function insert defined in RBT, you can say things like RBT.insert Int Int.compare String to apply insert to these three arguments, or you can use RBT.insert directly as a function of these three parameters.

We will also sometimes open a module, using a declaration

```
open < Module Name >
```

which brings all of the names in <ModuleName> into scope.

3. There are a bunch of other bells and whistles in Agda's module system: **abstract** and **private** delcarations for information hiding; **using**, **hiding**, **renaming**, **public** modifiers for massaging names; interplay between modules and records; We'll discuss those later on if they come up, or you can see the documentation on the Agda Wiki.

1.1.3 Functions

Figure 1.1 shows code for red-black tree insertion.

First, to represent Colors, we define a datatype with two constructors, Red and Black.

Second, we define a datatype representing trees. A Tree is either Empty, or it's a Node, with a left subtree, a color, a key-value pair, and a right subtree. When a datatype constructor has arguments, we give it a (usually curried) function type, which must end in the datatype being defined.

The type $A \times B$ is the type of pairs (a,b), which can be taken apart by pattern-matching, or by projection functions fst: $A \times B \to A$ and snd: $A \times B \to B$. Pairs are not built-in in Agda: they are defined in Preliminaries.agda as a datatype—and in fact it's an instance of a more general construction called a *dependent pair type*, but we'll get to that later. We could equivalently have given Node five arguments:

```
Node : Tree \rightarrow Color \rightarrow Key \rightarrow Value \rightarrow Tree \rightarrow Tree
```

and avoided product types, but in the code it's sometimes convenient to keep the key and value together (see balance). Next, we define four functions; let's read them from the bottom up:

• insert is the function that clients of the module should call. Functions in Agda are defined by giving clauses

```
<functionName> <pattern1> <pattern2> ...
```

with patterns for as many of the curried function arguments as you want (though this number has to be the same in all of the clauses for a given function). In this case, insert has one clause, with two patterns, both of which are variables. The body of the clause says that insert is defined by (1) calling the auxiliary function ins, which does the real work, and then (2) making the root of the resulting tree black, by calling blackenRoot.

• blackenRoot takes a tree and colors the root black. It's our first real example of pattern-matching. blackenRoot has two clauses. The first covers the case for the constructor Empty, in which case we return Empty again. The second case covers the constructor Node applied to arguments I and _ and kv and r. The _ says to ignore the color stored in the Node, because we won't use it. The result of the clause is a Node with the same key-value pair and left and right subtrees, and Black as the color.

Type checking: It almost goes without saying that all of this code is type-checked just like in ML or Haskell; for example, if we wrote

```
blackenRoot (Node I_kv r) = Node Black kv r
```

Agda will highlight "Black" and say

```
Color !=< Tree of type Set when checking that the expression Black has type Tree
```

That is, the type Color is not a subtype of the type Tree, which would be necessary to use Black as the first argument to Node. Subtyping in Agda is essentially for internal use in some aspects of the implementation, so you can read =< as type equality.

Exhaustiveness Checking: Agda checks the exhaustiveness of all functions—this is necessary to ensure that functions are total. For example, if we forgot the case for Empty, Agda would say

```
Incomplete pattern matching for blackenRoot. Missing cases: blackenRoot Empty when checking the definition of blackenRoot
```

• ins does the recursive tree insertion: If the tree is Empty, we make a new Node with the key-value pair kv, Empty subtrees, and we color it Red. Otherwise, we are trying to insert (k, v) into a Node that has (k', v') at its root—note the use of **deep pattern matching** to break up the key-value pair sitting inside the Node. In this case, we compare the keys k and k', and recursively insert into the left tree if k is less, or the right if k is greater, or put the new value at the node if they are the same. This is standard binary tree insertion, except instead of making a new Node using the recursive all, we call an auxilary function balance, where balance I c kv r puts the arguments together into a Node in a clever way.

With: For now, you can think of with as being like case/match in ML/Haskell, with the following lines giving the clauses of the case-analysis on the comparison. More on with later.

Termination checking: Agda checks that every function is terminating. The basic criterion is that recursive calls must be made on structurally smaller terms—i.e. things you find beneath the constructors of inductive datatypes, like I and r here.

• balance performs tree rotations to keep the tree roughly balanced, using the colors to direct traffic. Whenever there is a black node whose child is a red node that itself has a red child, the tree is rotated and the root is colored red and the two children black. See Figure 1.2 for a picture. Using deep pattern matching, it's easy to describe these four cases and the result (which is the same in all four cases—we'll see a way to combine them into one case later on). In all other cases, we simply make a Node. Note the use of a catch-all case with variables, which covers all other cases—if we forget this catch-all, the exhaustiveness checker will report all 91 cases that we forgot.

```
data Color: Set where
  Red: Color
  Black: Color
data Tree: Set where
  Empty: Tree
  Node : Tree \rightarrow Color \rightarrow (Key \times Value) \rightarrow Tree \rightarrow Tree
balance : Tree \rightarrow Color \rightarrow (Key \times Value) \rightarrow Tree \rightarrow Tree
balance (Node (Node a Red x b) Red y c) Black z d = Node (Node a Black x b) Red y (Node c Black z d)
balance (Node a Red x (Node b Red y c)) Black z d = Node (Node a Black x b) Red y (Node c Black z d)
balance a Black x (Node (Node b Red y c) Red z d) = Node (Node a Black x b) Red y (Node c Black z d)
balance a Black x (Node b Red y (Node c Red z d)) = Node (Node a Black x b) Red y (Node c Black z d)
balance I c kv r =
                                                            Node I c kv r
ins : Tree \rightarrow (Key \times Value) \rightarrow Tree
ins Empty kv = Node Empty Red kv Empty
ins (Node I c (k', v') r) (k, v) with compare k k'
                                      Equal = Node I c (k, v) r
                                      Less = balance (ins I(k,v)) c (k',v') r
                                     Greater = balance l c (k', v') (ins r (k, v))
blackenRoot : Tree → Tree
blackenRoot Empty = Empty
blackenRoot (Node I \_ kv r) = Node I Black kv r
insert : Tree \rightarrow Key \times Value \rightarrow Tree
insert t kv = blackenRoot (ins t kv)
```

Figure 1.1: Red-black tree insertion

1.2 Specification and Verification

OK, so red-black trees make perfect sense now, right? On to the next example!

The thing that's missing from the above simply-typed implementation is much indication of *why the code works*. From typing, we know that the functions always terminate successfully—they don't crash or loop—and that they produce values of the right shapes. But that alone doesn't distinguish a correct implementation of red-black trees from an incorrect one: If we forgot to balance, or to blackenRoot, or inserted into the wrong side, it would still type check. So what else might we want to know?

- 1. The implementation correctly implements a *dictionary*. E.g. if you lookup a key after inserting it, you get back the value you inserted.
- 2. insert t kv produces a sorted tree, where Empty is sorted; and Node lc(k,v) r is sorted if every key in l is less than or equal to k, which is less than or equal to every key in r, and l and r are sorted.
- 3. The implementation is fast.
- 4. The operations have good asymptotic complexity—e.g., inserting and looking up are logarthmic in the size of the tree.
- 5. insert preserves the red-black tree invariants:

A tree has **black height** n if every path from the root to Empty has exactly n black nodes (Empty is considered black).

A tree is **well-red** if both children of every red node are black.

My point is that there are many different specifications for red-black trees. The first two above are about *behavioral correctness*: The first says that the code implements the abstraction that it is supposed to implement (and this can be

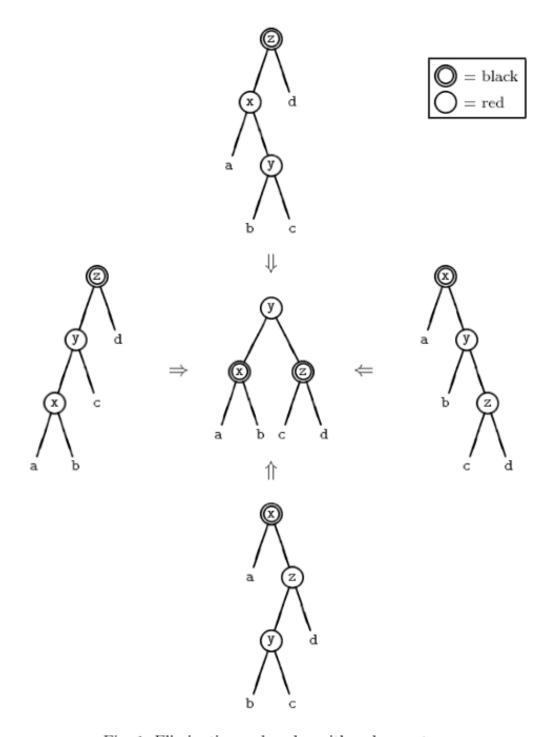


Fig. 1. Eliminating red nodes with red parents.

Figure 1.2: Red-black Tree Balancing, from Okasaki [5]

specified in many different ways—an axiomatic specification relating the operations; equivalence with a reference implementation). The second is an invariant that helps prove this kind of behavioral correctness: the reason you want a tree to be sorted is to justify the lookup function that uses the value at the root of a Node to determine whether to go left or right. The last three concern *efficiency*: what we really want is a fast implementation, and asymptotic complexity is often a good predictor of this. A nice property of red-black trees is that the asymptotic complexity can be factored into (1) showing that the operations preserve certain local, structural invariants (being well-red and having a black height) and (2) showing that these structural invariants imply that the tree is (roughly) balanced, and (3) showing that, for balanced trees, the operations (insert, lookup) have logarithmic complexity.

As we will soon see, dependently typed programming languages give you the tools to state and prove specifications about your code. But it's important to keep in mind that you get to decide how much you want to verify—there is no monolithic notion of absolute correctness—to balance the costs and benefits of verification. There is a spectrum, from using Agda as a slightly more expressive ML/Haskell—where you get a little bit more information out of the type checker with little additional work—all the way to doing complete proofs of every spec you can think of.

We'll use the asymptotic complexity of red-black tree insert as an example. It's easy to see that insert (and lookup, defined in the obvious way) take time proportional to the depth of the tree, because they do a constant amount of work around one recursive call. Additionally, a little bit of math shows that if the longest path in a tree is no more than twice the length of the shortest path, then the depth is logarithmic (the tree can't be that skewed). The red-black invariants imply this: because the tree has a black-height, each path from the root to a leaf has the same number of black nodes. Because no red node has a red child, you can, at most, alternate red and black nodes, so the length of every path from the root to a leaf is at most twice the black-height. Thus, it suffices to show that the operations on red-black trees preserve the black-height and well-red invariants.

To my mind, the above paragraph is a pretty clear and convincing argument that the invariants imply the time complexity, and is a good thing to include in a comment for the person reading your code. If you wanted to be more sure, you use Agda to check some or all of these steps. The tricky part of red-black trees is checking that the operations maintain the invariants. Moreover, if balance seemed mysterious to you before, this is the part that will explain why balance is written the way it is: understanding the invariants will help you understand the code. So, we'll use Agda to verify these invariants.

1.3 Black Height, Extrinsically

As a first example, let's verify that insert t kv maintains the black-height invariant: if t has a black height, then so does insert t kv. This example will be a bit slow-going, because we'll use it to introduce most of Agda's features. The complete proof is in Figure 1.3 if you want to see where we're going.

We represent heights by unary natural numbers:

 $\label{eq:data_norm} \begin{array}{l} \textbf{data} \ \text{Nat} \ : \ \textbf{Set where} \\ \textbf{Z} \ : \ \textbf{Nat} \\ \textbf{S} \ : \ \textbf{Nat} \rightarrow \textbf{Nat} \end{array}$

Agda has special syntax that allows numerals 0, 1, etc. can be used to write Nats. (E.g. 2 is syntax for S (S Z)).

1.3.1 Inductive Families

First, we need to define what it means for a tree to have a black height. In Agda, the nicest way to do this is with an *inductively defined family of types*, or *inductive family*. In this case, we define a family HasBH tn, where t: Tree and n: Nat—t and n are called the *indices* of the family HasBH. In Agda, this is represented by the following datatype definition:

```
\begin{array}{c} \rightarrow \text{HasBH (Node I Red kv r) n} \\ \text{HBH-Node-Black}: (n: \text{Nat) (I r}: \text{Tree}) \text{ (kv}: \text{Key} \times \text{Value)} \\ \rightarrow \text{HasBH I n} \\ \rightarrow \text{HasBH r n} \\ \rightarrow \text{HasBH (Node I Black kv r) (S n)} \end{array}
```

The first line says that HasBH has type Tree → Nat → Set; i.e. for every t and n, HasBH t n is a Set. Next, we populate the datatype with three constructors, which are named HBH-Empty ("has-black-height empty"), HBH-Node-Red ("has-black-height node red"), and HBH-Node-Black. The type of HBH-Empty is HasBH Empty 1: this constructors asserts that the empty tree has black-height 1. The type of HBH-Node-Red is our first example of a **dependent function** type.

1.3.2 Dependent Function Types

A dependent function type $(x : A) \rightarrow B$ is well-formed when A is a Set and B is a Set under the assumption x:A; this is a generalization of the simple function type $A \rightarrow B$ in which the type B is allowed to depend on the argument. The inhabitants of the type are functions, which can be defined by named clausal function definitions, just like simply-typed functions—as we shall soon see. (Agda also has anonymous functions, but we won't need those for a bit.) When you apply a dependent function $f : (x : A) \rightarrow B$ to an argument a:A, the result has type B [a/x] - B with a substituted for x.

OK, back to the example. The type

```
(n:Nat) \rightarrow (I:Tree) \rightarrow (r:Tree) \rightarrow (kv:Key \times Value) \rightarrow HasBHIn \rightarrow HasBHrn \rightarrow HasBH (Node I Red kvr) n
```

consists of 4 dependent function types followed by 2 simple function types. By convention, the body of a dependent function type extends as far to the right as possible, and simple function types are right-associated, so this is really

```
(n: Nat) \rightarrow ((I: Tree) \rightarrow ((r: Tree) \rightarrow ((kv: Key \times Value) \rightarrow (HasBHIn \rightarrow (HasBHrn \rightarrow HasBH (Node IRed kvr) n)))))
```

This should be read as "HBH-Node-Red is a function, that, given a number n, trees I and r, and a key-value pair kv, along with a term of type HasBH I n and a term of type HasBH rn, returns a term of type HasBH (Node I Red kv r) n. Under props as types, you can read this as "for all n, Ir, and kv, if HasBH I n and HasBH rn, then HasBH (Node I Red kv r) n"—dependent functions are like a universal quantifier. But it's important to keep in mind that (unlike inductive *props* in Coq) there is no difference in Agda between data and proofs: inhabitants of HasBH t n are data, just like trees.

The type of HBH-Node-Black is essentially the same, except we use it to illustrate a couple of syntactic simplifications: (1) When you have multiple dependent functions in a row ((x : A) \rightarrow (y : B) \rightarrow C), you can omit the \rightarrow : ((x : A) (y : B) \rightarrow C). (2) When you have multiple variables of the same type, you can list them together ((Ir: Tree)). Under these assumptions, Node I Black kv r has black-height S n—i.e. a black node has a black-height that is one more than the black height of its subtrees.

The reason HasBH is an inductively defined *family* of types is that all instances of HasBH t n must be defined together. In contrast, the usual definition of lists (List A) can be viewed as a *family of inductively defined types*: first you fix A, and then you define List A—for each A, there is a separate inductive definition of List A. Here, for example, HasBH t (S n) must be defined mutually with HasBH t' n, because to inhabit the former, you need elements of the latter.

1.3.3 Interactive Editing

Let's prove that a tree has a black height. We'll use this to introduce Agda's interactive editor.

To get started, we'll assume some keys k1 k2 and some values v1 v2, and make a tree named t:

```
\label{eq:module} \begin{split} & \textbf{module} \; \mathsf{Example} \; (\mathsf{k1} \; \mathsf{k2} \; \mathsf{:} \; \mathsf{Key}) \; (\mathsf{v1} \; \mathsf{v2} \; \mathsf{:} \; \mathsf{Value}) \; \textbf{where} \\ & t \; \mathsf{:} \; \mathsf{Tree} \\ & t \; = \; \mathsf{Node} \; (\mathsf{Node} \; \mathsf{Empty} \; \mathsf{Red} \; (\mathsf{k1}, \mathsf{v1}) \; \mathsf{Empty}) \; \mathsf{Black} \; (\mathsf{k2}, \mathsf{v2}) \; \mathsf{Empty} \end{split}
```

Now we'd like to prove that t has a black-height, in this case 2. First, we write a line like this, where t-bh is defined to be {!!}:

```
t-bh: HasBHt2
t-bh = \{!!\}
```

The {!!} is a goal that you can fill in using Agda's editor (a goal can also be written?). First, load the file. The goal should turn blue and be labeled with the number 0:

At the bottom of the screen, in the Agda information window, you should see

```
?0: HasBHt2
```

which means "goal 0 needs to have type HasBH t 2". If there were more goals, you would see them listed here too. There are various commands for working inside goals. Let's try some of them.

- load (C-c C-1) the file first, to ask Agda to type check it.
- goal-type (C-c C-t) shows you the type of the current goal. For example:

```
HasBH (Node (Node Empty Red (k1,v1) Empty) Black (k2,v2) Empty) 2
```

goal-type normalizes the goal—here Agda has expanded the definition of t.

HasBHt2

• goal-and-context (C-c C-,) shows you the type of the current goal, as well as the types of the variables in the context:

Goal: HasBH (Node (Node Empty Red (k1, v1) Empty) Black (k2, v2) Empty) 2

v2 : Value : Value v1 k2 : Key k1 : Key Value : Set compare : $Key \rightarrow Key \rightarrow Order$

Key: Set

- Now, type something in the goal, say t. infer-type will tell you the type of the expression in the goal, in this case Tree.
- goal-and-context-and-inferred (C-c C-.) will show you all of this information: the type of the goal, the context, and the type of the expression currently in the goal.

Goal: HasBH (Node (Node Empty Red (k1,v1) Empty) Black (k2,v2) Empty) 2 Have: Tree

v2 : Value v1 : Value k2 : Key : Key k1 Value: Set

compare : $Key \rightarrow Key \rightarrow Order$

Key: Set

• give (C-c C-space) If the type of the expression in the goal matches the type of the goal, then replace the goal with the expression in it. Otherwise, you get a type error.

- refine (C-c C-r) Like give when the types match. Additionally, suppose the expression in the goal is a function that produces with something matching the goal. Then the goal will be replaced by the expression, applied to new goals for the necessary arguments. (Note: You could always use give, because the expression you give can contain new goals, but this way Agda infers how many goals to insert for you.) Also, if a solution is forced by typing (e.g. only one datatype constructor applies), Agda will fill it in.
- **make-case** (C-c C-c) case-analyze one of the variables in the function clause, replacing the clause with some number of specialized clauses. We will also call this *splitting* a variable.
- Don't normalize (C-u ...): for many commands, including **goal-type**, **goal-and-context**, **infer-type**, and **goal-and-context-and-inferred** you can use a prefix argument (C-u) to see the same information, but without normalization. This is sometimes useful when the terms involved get big.

Let's use **give** and **refine** to prove that t has black-height 2. t is a Black node, so we need to start constructing the proof with HBH-Node-Black. This constructor has 6 arguments, so we can start writing by writing this in the goal:

```
t-bh: HasBHt2
  t-bh = {! HBH-Node-Black?????!}
Now give, and you will see that Agda makes 6 new goals:
  t-bh: HasBHt2
  t-bh = HBH-Node-Black 1 (Node Empty Red (k1,v1) Empty) Empty (k2,v2) { !! } { !! }
and reports their types as follows:
  ?1 : Nat
  ?2 : Tree
  ?3 : Tree
  ?4 : \Sigma (\lambda \rightarrow Value)
  ?5: HasBH (Node Empty Red (k1,v1) Empty) 1
  ?6: HasBH Empty 1
It's clear what the first four goals have to be, so we can fill them in:
  t-bh: HasBHt2
  t-bh = HBH-Node-Black 1 (Node Empty Red (k1,v1) Empty) Empty (k2,v2) {!!} {!!}
Asking Agda for the type of the next goal, we see that it is
```

```
HasBH (Node Empty Red (k1,v1) Empty) 1
```

so we should start the proof with HBH-Node-Red. Rather than writing the six arguments explicitly, we can write HBH-Node-Red in the goal and then **refine**, at which point Agda generates the appropriate goals.

It's clear what the first four of the resulting goals should be:

```
 \begin{array}{l} \text{t-bh}: \text{HasBH t 2} \\ \text{t-bh} = \text{HBH-Node-Black 1 (Node Empty Red (k1,v1) Empty)} \\ \text{Empty (k2,v2)} \\ \text{(HBH-Node-Red 1 Empty Empty (k1,v1) $\{!!\}$ } \\ \text{$\{!!\}$} \end{array}
```

Now all three remaining goals have type

```
?0: HasBH Empty 1
?1: HasBH Empty 1
?2: HasBH Empty 1
```

so we can fill the first one with HBH-Empty:

```
 \begin{array}{ll} \text{t-bh}: \text{HasBH t 2} \\ \text{t-bh} &= \text{HBH-Node-Black 1 (Node Empty Red (k1,v1) Empty) Empty (k2,v2)} \\ &\qquad \qquad (\text{HBH-Node-Red 1 Empty Empty (k1,v1) HBH-Empty } \{!!\}) \\ &\qquad \qquad \{!!\} \end{array}
```

In fact, HBH-Empty is the only datatype constructor that applies, so if we just **refine** in the goal, Agda will fill it. Finally, we get the following proof:

```
 \begin{array}{l} \text{t-bh}: \text{HasBH t 2} \\ \text{t-bh} = \text{HBH-Node-Black 1 (Node Empty Red (k1,v1) Empty) Empty (k2,v2)} \\ \text{(HBH-Node-Red 1 Empty Empty (k1,v1) HBH-Empty HBH-Empty)} \\ \text{HBH-Empty} \end{array}
```

Suppose we had made the left subtree Black instead:

```
t': Tree t' = \text{Node}(\text{Node Empty Black}(k1,v1) \text{ Empty}) \text{ Black}(k2,v2) \text{ Empty}
```

Then we'd get into trouble because

?0 : HasBH Empty 0 ?1 : HasBH Empty 0

we'd ultimately need to show that Empty has height 0, and there is no way to prove this.

1.3.4 Unification

It's pretty redundant to write the tree, nat, and key-value arguments to HBH-Node-Black and HBH-Node-Red, because writing anything other than what we've written will result in a type error: these arguments are forced by typing. Fortunately, Agda can infer them using unification. If part of a term can be inferred by unification, you can replace it with an _. Note that unification in Agda succeeds only when there is a unique solution (unlike Coq, which sometimes guesses). So we can simplify the above proof to:

```
t-bh': HasBH t 2
t-bh' = HBH-Node-Black _ _ _ (HBH-Node-Red _ _ _ HBH-Empty HBH-Empty) HBH-Empty
```

1.3.5 Dependent Pairs

Next, we'll look at insert. The main thing we care about is that a tree as *some* black height; at the outside, we don't particularly care what the height is. To express "a tree with some black-height", we can use a type constructor called a *dependent pair type*. For reasons that we will explain in a bit, a dependent pair type is written Σ (λ (x : A) \rightarrow B) where B can mention the variable a. The elements of a dependent pair type are pairs (a,b) where a : A and b : B [a/x]. Dependent pairs can be taken apart by pattern matching, or by fst and snd projection. Second projection has a dependent type, expressing the dependency on the first projection:

```
\begin{array}{l} \text{fst} : \left( \Sigma \left( \lambda \left( x : A \right) \to B \right) \right) \to A \\ \text{snd} : \left( p : \Sigma \left( \lambda \left( x : A \right) \to B \right) \right) \to B \left[ \text{fst } p/a \right] \end{array}
```

Logically, Σ is like an existential quantifier.

1.3.6 Pattern matching and inversion

Let's look at the spec for blackenRoot first: blackenRoot takes a tree with black height n and produces a tree with some black height. In fact, the black-height will be n (if it was already black) or n+1 (if it was red), but we won't need to know this. So, we can state the following spec:

```
blackenRoot-bh: (t: Tree) \ (n: Nat) \rightarrow HasBH \ t \ n \rightarrow \Sigma \ (\lambda \ (m: Nat) \rightarrow (HasBH \ (blackenRoot \ t) \ m))
```

For all trees t with black height n, there exists an m such that blackenRoot t has black-height m. Now let's construct a proof of this fact—i.e. a function with this type. We'll start by making a goal:

```
blackenRoot-bh t n h = \{!!\}
```

The goal has type Σ ($n \to HasBH$ (blackenRoot t) n). How can we fill it in? The most direct way is to apply one of the constructors of HasBH. However, the constructors for HasBH all require that we know what constructor the tree is built from. Unfortunately, blackenRoot t is *stuck*—because blackenRoot is defined by pattern matching, it doesn't compute on a variable t. To get it to compute, we need to case-analyze t. We could fill in the cases ourselves, but it's easier to use Agda to do it. Type t in the goal and then **make-case**, and you'll get the following cases:

```
blackenRoot-bh Empty n h = \{!!\}
blackenRoot-bh (Node t x x_1 t_1) n h = \{!!\}
```

Let's proceed with the Empty case first. The un-normalized type of the goal is

```
\Sigma (\lambda (m : Nat) \rightarrow HasBH (blackenRoot Empty m))
```

But the normalized type of the goal is

```
\Sigma (\lambda (m : Nat) \rightarrow HasBH Empty m)
```

That is, because blackenRoot Empty computes to Empty by the first clause of the definition of blackenRoot, Agda replaces one with the other—you do not need to mark uses of definitional equality in your proof.

In general, when we need to give a term of a Σ -type, we can always introduce a pair of two new goals, and try solving them. We can do this by writing

```
blackenRoot-bh Empty n h = \{!?,?!\} and then refining to get  blackenRoot-bh \ Empty \ n \ h = \{!!\},\{!!\}
```

Now, we need to fill in the first goal with some number, and to fill in the second goal with a proof that blackenRoot Empty has that number as its black-height. So we can fill the goals in with 1 and HBH-Empty.

```
blackenRoot-bh Empty n h = 1, HBH-Empty
```

Of course, we could also have let Agda fill in the 1, because it's forced by the type of HBH-Empty:

```
blackenRoot-bh Empty n h = _,HBH-Empty
```

Note that we didn't need to use h in this case.

Now, we have to do the Node case, which we can start by introducing a pair, and then working on the second component of that pair.

```
blackenRoot-bh (Node I c kv r) n h = \{!!\},\{!!\}
```

The second component has type HasBH (Node | Black kv r) (?0 Key compare Value | c kv r n h), where (?0 ...) is the goal for the first component of the pair (the arguments indicate which variables the first component is allowed to depend on). We can start with HBH-Node-Black, which is the only constructor that applies.

```
blackenRoot-bh (Node I c kv r) n h = S {!!}, HBH-Node-Black {!!} I r kv {!!} {!!}
```

If you look at the types of the last two goals, you'll see that what we need now is some number m that is the black-height of I and r. Where will we get the black-height of I and r? It has to come from h! h has type HasBH (Node I c kv r) n, so we don't know whether it was constructed by HBH-Node-Red or HBH-Node-Black.

At this point, we can proceed in one of two ways. The first is to *case analyze the tree and number enough that the constructor for h is forced*. Unfortunately, you can only **make-case** when the right-hand side is a single goal, so let's back out of HBH-Node-Black for now. First, we distinguish cases on c:

```
blackenRoot-bh (Node I Red kv r) n h = \{!!\} blackenRoot-bh (Node I Black kv r) n h = \{!!\}
```

Now, in the Red case, h must be constructed with HBH-Node-Red, so if we **make-case**, Agda will not make a case for HBH-Node-Black or HBH-Empty. In an informal proof by rule induction, you might say *by inversion*, h must be constructed by HBH-Node-Red....

```
blackenRoot-bh (Node I Red kv r) n (HBH-Node-Red .n .l .r .kv hl hr) =\{!!!\} blackenRoot-bh (Node I Black kv r) n h =\{!!!\}
```

We also see our first example of **dot patterns**. A dot pattern .e means "this argument is forced to be the expression e by typing." In this case, the first four arguments of HBH-Node-Red are forced, because in order for HBH-Node-Red to have the right type, they must be n I r and kv.

Now if you goal-and-context, you'll see that we've uncovered that I and r have black-height n:

```
hr: HasBHrn
hl: HasBHln
```

So we can finish the case as follows:

```
blackenRoot\text{-}bh\ (Node\ I\ Red\ kv\ r)\ n\ (HBH\text{-}Node\text{-}Red\ .n\ .l\ .r\ .kv\ hl\ hr)\ =\ \_, HBH\text{-}Node\text{-}Black\ \_\_\_\ hl\ hr\ blackenRoot\text{-}bh\ (Node\ I\ Black\ kv\ r)\ n\ h\ =\ \{!!\}
```

Or, if you like, you can fill in all the underscores: S n, HBH-Node-Black n I r kv hl hr.

Now, the black case. For HBH-Node-Black to apply, the height n must be of the form S something. So let's case-analyze n:

```
blackenRoot\text{-}bh\ (Node\ I\ Red\ kv\ r)\ n\ (HBH\text{-}Node\text{-}Red\ .n\ .I\ .r\ .kv\ hl\ hr)}\ =\ \_, HBH\text{-}Node\text{-}Black\ \_\_\_\ hl\ hr\ blackenRoot\text{-}bh\ (Node\ I\ Black\ kv\ r)\ Z\ h\ =\ \{!!\}\ blackenRoot\text{-}bh\ (Node\ I\ Black\ kv\ r)\ (S\ n')\ h\ =\ \{!!\}
```

In the case for S n', h must now be HBH-Node-Black, so we can invert h, and then fill in the goal:

```
blackenRoot\text{-}bh\ (Node\ I\ Red\ kv\ r)\ n\ (HBH\text{-}Node\text{-}Red\ .n\ .l\ .r\ .kv\ hl\ hr) = \_, HBH\text{-}Node\text{-}Black\ \_\_\_\ hl\ hr} blackenRoot\text{-}bh\ (Node\ I\ Black\ kv\ r)\ (S\ n')\ (HBH\text{-}Node\text{-}Black\ .n'\ .l\ .r\ .kv\ hl\ hr) = \_, HBH\text{-}Node\text{-}Black\ \_\_\_\ hl\ hr}
```

What about the Z case? In this case, h has type HasBH (Node I Black kv r) 0. But there are no constructors inhabiting this type, because the only constructor for black nodes has a height S _, which is different than Z. So the assumed h is contradictory. If we **make-case**, then Agda will fill in an *absurd pattern* (), which means "this argument is contradictory." When there is an absurd pattern, you leave off the right-hand side of the clause:

1.3.7 Dependent Pattern Matching

In the above proof of blackenRoot-bh, we *case-analyzed* simply-typed data (trees, colors, height), and then *inverted* dependently-typed data (HasBH t n) once we knew exactly which constructor applied. This is what you would have to do if, for example, your programming language erased the dependently typed data before run-time—e.g. if they were propositions in Coq. However, it makes the proof kind of convoluted: in the Empty case, we didn't look at h at all, and the Node case, we had to decide to case-analyze the color and the height.

Fortunately, in Agda, there is no distinction between data and proofs, and you can directly pattern-match on dependently typed data. This often leads to cleaner proofs, because *case-analyzing dependently typed data tells you information about the indices*.

Here's an alternate way to write blackenRoot-bh. Start at the very beginning:

```
blackenRoot\text{-}bh2\ t\ n\ h\ =\ \{!!\} then\ case\text{-}analyze\ h! blackenRoot\text{-}bh2\ .Empty\ .1\ HBH\text{-}Empty\ =\ \{!!\} blackenRoot\text{-}bh2\ .(Node\ l\ Red\ kv\ r)\ .n\ (HBH\text{-}Node\text{-}Red\ n\ l\ r\ kv\ hl\ hr)\ =\ \{!!\} blackenRoot\text{-}bh2\ .(Node\ l\ Black\ kv\ r)\ .(S\ n')\ (HBH\text{-}Node\text{-}Black\ n'\ l\ r\ kv\ hl\ hr)\ =\ \{!!\}
```

Giving cases for the three constructors for HasBH *tells you* that the tree and height must be split into the three cases we had before, for Empty, a Red Node, and a Black Node, and in the last case the height must be S n'.

Then we can fill in the right-hand sides as before:

```
blackenRoot\text{-}bh2 \ . Empty \ .1 \ HBH\text{-}Empty = \_, HBH\text{-}Empty \\ blackenRoot\text{-}bh2 \ . (Node \ I \ Red \ kv \ r) \ .n \ (HBH\text{-}Node\text{-}Red \ n \ I \ r \ kv \ hI \ hr) = \_, HBH\text{-}Node\text{-}Black \ \_\_\_ \ hI \ hr \\ blackenRoot\text{-}bh2 \ . (Node \ I \ Black \ kv \ r) \ . (S \ n') \ (HBH\text{-}Node\text{-}Black \ n' \ I \ r \ kv \ hI \ hr) = \_, HBH\text{-}Node\text{-}Black \ \_\_\_ \ hI \ hr \\ blackenRoot\text{-}bh2 \ . (Node \ I \ Black \ kv \ r) \ . (S \ n') \ .
```

Case-analyzing dependently typed data often leads to much clearer proofs, because it tells you more.

Note that the above uses of "inversion" are actually special cases of dependent pattern-matching. For example, when we concluded that in the case

```
blackenRoot-bh (Node I Red kv r) n h = \{ !! \}
```

that HBH-Node-Red is the *only* constructor that applies, so h *must be* (HBH-Node-Red .n .l .r .kv hl hr), we were doing a special case of what Agda does all the time:

When you case-analyze a variable x whose type is an inductive family, Agda unifies the indices in the type of x with the indices of the constructors, and only gives you cases for the ones that match—and in these cases, the goal is specialized with the knowledge gained by unification. Here, h: HasBH (Node | Red kv r) n, so it asks

- 1. Can HasBH Empty 1 equal HasBH (Node | Red kv r) n? No, because Empty is different than Node. Therefore no case for HBH-Empty.
- 2. Can HasBH (Node I1 Black kv1 r1) (S n1) equal HasBH (Node I Red kv r) n? No, because Red is different than Black. Therefore, no case for HBH-Node-Black.
- 3. Can HasBH (Node I1 Red kv1 r1) n1 equal HasBH (Node I Red kv r) n? Yes, but only if I1 = I, kv1 = kv, r1 = r, and n1 = n. So we get the case

```
blackenRoot-bh (Node I Red kv r) n (HBH-Node-Red .n .l .r .kv h h_1) = \{!!\}
```

Sometimes, like in the version of the proof where we matched on h first, when it has type HasBH t n, the indices of the variable are completely general. In this case, you get cases for all possible constructors. In other cases, some constructors are ruled out, but more than one applies—the two proofs we gave here are extremal points (one constructor / all constructors), but anything in between works too.

1.3.8 Implicit Arguments

In the above proof, Agda could always fill in the first four arguments to HBH-Node-Red and HBH-Node-Black by unification. When you expect a certain argument to often/always be filled in by unification, it's somewhat cumbersome to have to write the $_$ each time. This can be solved by using *implicit arguments*. Instead of writing a dependent function type as $(x : A) \to B$, you can write $\{x : A\} \to B$ for an *implicit dependent function type*. There is no deep semantic difference between the two; it just changes the syntax.

For example, if we make n and I and r and kv implicit arguments to the constructors:

```
data HasBH: Tree → Nat → Set where

HBH-Empty: HasBH Empty 1

HBH-Node-Red: {n: Nat} {Ir: Tree} {kv: Key × Value}

→ HasBH In

→ HasBH rn

→ HasBH (Node | Red kvr) n

HBH-Node-Black: {n: Nat} {Ir: Tree} {kv: Key × Value}

→ HasBH In

→ HasBH In

→ HasBH rn

→ HasBH rn

→ HasBH (Node | Black kvr) (S n)

then
then t-bh looks like this:

t-bh: HasBH t 2

t-bh = HBH-Node-Black (HBH-Node-Red HBH-Empty HBH-Empty)

HBH-Empty
```

By default, the arguments of an implicit dependent function are filled in by unification. If you want to supply them explicitly, you can do so using { }; for example:

```
 \begin{array}{ll} \text{t-bh} &=& \text{HBH-Node-Black} \left\{1\right\} \left\{-\right\} \left\{\text{Empty}\right\} \left(\text{HBH-Node-Red HBH-Empty HBH-Empty}\right) \\ &+& \text{HBH-Empty} \end{array}
```

As this example shows, when you have multiple curried implicit functions, you can explicitly apply them to as many arguments as you want, but you have to use _s if the arguments you want to supply come after arguments that you don't.

Here's how blackenRoot-bh looks if we make t and n implicit:

```
blackenRoot-bh : \{t: Tree\} \{n: Nat\} \rightarrow HasBH \ t \ n \rightarrow \Sigma \ (\lambda \ (m: Nat) \rightarrow (HasBH \ (blackenRoot \ t) \ m)) blackenRoot-bh HBH-Empty = _, HBH-Empty blackenRoot-bh (HBH-Node-Red hl hr) = _, (HBH-Node-Black hl hr) blackenRoot-bh (HBH-Node-Black hl hr) = _, HBH-Node-Black hl hr
```

Much cleaner!

Sometimes you want to bind a name to an implicit argument in a function definition, because you need the name to define the function, but you expect it to be inferable at call sites. In this case, you can use { } in the function clause:

```
blackenRoot-bh \{t\} \{n\} h = \{!!\}
```

Because you can explicitly supply implicit arguments when you want to, implicit arguments are pretty flexible—it's really just a question of whether you want an application by default or not.

1.3.9 Revising Definitions

It's a bit annoying that the code for blackenRoot has two cases (Empty, and Node of any color), whereas the proof has three cases (Empty, red Node, black Node). The reason is that, in the code, we don't pattern-match on the color c, but in the proof, we match on HBH-Node-Red and HBH-Node-Black to extract hl and hr. One solution would be to write

a helper function that pulled out these pieces. However, since this will come up again later in the proof, it's worth it to see if we can improve the definition. This is a common theme in formal proofs: *definitions matter a lot*. There are often many equivalent ways to define a concept, and when you're reasoning loosely or informally, you can sometimes be kind of sloppy about things. But for formal proofs, choosing the "right" definition can make a big difference in how much work it is to do your proof. It's usually a good idea to keep the different possibilities in mind and experiment a little as you go, because it's hard to pick the best definition a priori. Moreover, which kinds of definitions work well depends on what proof assistant you're using and how you're doing your proof—there is definitely some art to it.

In this case, what we'd like to do is to abstract over the differences between HBH-Node-Red and HBH-Node-Black. What are the differences? The former constructs a Red node and keeps the height of the result the same; the latter constructs a Black node and increments the height of the result. So, first, we can parametrize by a color c:

```
 \begin{tabular}{ll} \textbf{data} \ \textbf{HasBH} : \ \textbf{Tree} \rightarrow \textbf{Nat} \rightarrow \textbf{Set where} \\ \ \textbf{HBH-Empty} : \ \textbf{HasBH Empty 1} \\ \ \textbf{HBH-Node} : \ \{n: \textbf{Nat}\} \ \{c: \textbf{Color}\} \ \{\textbf{Ir}: \textbf{Tree}\} \ \{\textbf{kv}: \textbf{Key} \times \textbf{Value}\} \\ \ \rightarrow \textbf{HasBH In} \\ \ \rightarrow \textbf{HasBH rn} \\ \ \rightarrow \textbf{HasBH} \ (\textbf{Node Ickvr}) \ \{!!\} \end{tabular}
```

Now, what we need to express is the relationship between the color c, the height n of the subtrees, and the height of the Node. We can do this using another inductive family:

```
 \begin{tabular}{ll} \textbf{data} & Color Height: Color $\rightarrow$ Nat $\rightarrow$ Nat $\rightarrow$ Set \textbf{where} \\ & CH-Red: \{n: Nat\} $\rightarrow$ Color Height Red n n \\ & CH-Black: \{n: Nat\} $\rightarrow$ Color Height Black n (S n) \\ \end{tabular}
```

ColorHeight gives two possibilites: the color is red, and the two numbers are the same; or the color is black, and the second is one more than the first. Now we can define

```
data HasBH: Tree \rightarrow Nat \rightarrow Set where 
HBH-Empty: HasBH Empty 1
HBH-Node: \{n \text{ m} : \text{Nat}\} \{c : \text{Color}\} \{\text{Ir} : \text{Tree}\} \{\text{kv} : \text{Key} \times \text{Value}\} \rightarrow \text{HasBH I n} \rightarrow \text{ColorHeight c n m} \rightarrow \text{HasBH r n} \rightarrow \text{HasBH (Node I c kv r) m}
```

Now blackenRoot-bh can be defined with only two clauses, because in the Node case we can choose not to match on the color argument:

```
blackenRoot-bh : \{t: Tree\} \{n: Nat\} \rightarrow HasBH \ t \ n \rightarrow \Sigma \ (\lambda \ (m: Nat) \rightarrow (HasBH \ (blackenRoot \ t) \ m)) blackenRoot-bh HBH-Empty = _,HBH-Empty blackenRoot-bh (HBH-Node hl ch hr) = _,(HBH-Node hl CH-Black hr)
```

1.3.10 More on pattern matching

OK, let's move on and look at a spec for balance. balance I c kv r is like making a Node I c kv r, except it sometimes rotates the tree. But in any case, it has the same black-height that Node I c kv r does. So balance has the following spec:

```
balance-bh: \{I: Tree\} \{c: Color\} \{kv: (Key \times Value)\} \{r: Tree\} \{n \ m: Nat\} \\ \rightarrow HasBHIn \rightarrow ColorHeight cn m \rightarrow HasBHrn \rightarrow HasBH (balance Ickvr) m
```

To prove this, we can match on the implicit arguments, with the same cases used to define balance. The first one is:

```
balance-bh \{(Node (Node a Red x b) Red y c)\} \{Black\} \{z\} \{d\}  (HBH-Node (HBH-Node ha CH-Red hb) CH-Red hc) CH-Black hd = HBH-Node (HBH-Node ha CH-Black hb) CH-Red (HBH-Node hc CH-Black hd)
```

In this case, the call to balance in the goal computes to (Node (Node a Black x b) Red y (Node c Black z d)), and we can match on HasBH I n to extract the heights of a and b and c. Then we can put the heights of a b c and d together in the new rotation to prove the goal.

Unfortunately, the remaining cases are not so easy:

```
balance-bh \left\{ (Node\ a\ Red\ x\ (Node\ b\ Red\ y\ c)) \right\} \left\{ Black \right\} \left\{ z \right\} \left\{ d \right\} \ hl\ ch\ hr = \left\{ !! \right\} \\ balance-bh \left\{ a \right\} \left\{ Black \right\} \left\{ x \right\} \left\{ (Node\ (Node\ b\ Red\ y\ (Node\ c\ Red\ z\ d)) \right\} \ hl\ ch\ hr = \left\{ !! \right\} \\ balance-bh\ hl\ ch\ hr = \left\{ !! \right\} \\ balance-bh\ hl\ ch\ hr = \left\{ !! \right\}
```

If you look at the type of the goal in the first one, you'll see

```
HasBH (balance (Node a Red x (Node b Red y c)) Black z d) .m
```

Why didn't balance compute? The reason is that *not all function clauses are definitional equalities in Agda*. If you think about it for a second, it's obvious that this has to be true. For example, the final (catch-all) clause of balance overlaps with the other four, but gives a different result: so if both clauses held as equations, the behavior would be non-deterministic. Instead, Agda has a *first-match* semantics, like ML or Haskell, where the first matching equation is selected.

However, this means that in order for a function application to compute, Agda has to see that no previous clause applies. In this case, we when call (balance (Node a Red x (Node b Red y c)) Black z d) it's not clear whether the first clause applied—a might be a Red Node, or it might not. Thus, the application does not compute, even though the form it matches the second clause. Agda makes these decisions by internally representing pattern-matching as a case-tree, where (generally) matching is sequenced from left to right.

This complicates reasoning about functions like balance, which have overlapping clauses. One option is to expand the pattern-match far enough that things reduce, but this gets pretty ugly in this case. We'll see one solution later this lecture, and another next time.

1.3.11 More on with

Let's set aside balance for now and look at ins. To get the induction to go through, we need to know not only than ins t kv has a black-height, but that it's the same as the black-height of t (because we insert into only one side of the tree).

We can start by matching on h, and filling in the Empty case is easy:

```
ins-bh : \{t: Tree\} \{kv: Key \times Value\} \{n: Nat\} \rightarrow HasBH t n \rightarrow HasBH (ins t kv) n ins-bh HBH-Empty = HBH-Node HBH-Empty CH-Red HBH-Empty ins-bh <math>\{.\} \{k,v\} (HBH-Node \{n\} \{m\} \{c\} \{l\} \{r\} \{k',v'\} hl ch hr) = \{!!\}
```

The type of the goal in the Node branch (where I've filled in some implicit args to name the variables) is something we haven't seen before:

```
 \begin{array}{ll} \text{HasBH (ins Key compare Value (Node I Red (k',v') r) (k,v)} \; \mid \; \text{compare k k')} \\ \text{m} \end{array}
```

The first argument of HasBH is Agda's way of notating "the function ins, applied to the module arguments Key, compare, and Value (the parameters to the module, which are implicitly parameters to the function), and the normal arguments (Node | Red (k',v') r) and (k,v), where the with case-analysis is on the expression compare k k'. You can think of with as adding another column to the pattern-matching, by saying what to case-analyze in that column. The bar is Agda's way of displaying what is being case-analyzed by a with. (In fact, with is implemented by making an anonymous function with an extra argument, and this is Agda's way of notating the application of that anonymous function. But for the most part you don't need to know that.)

The point is that, because compare k k' is treated like an extra argument to the function, and the function has separate clauses matching on whether this argument is Less or Equal or Greater, ins will not compute until we know which of these results compare k k' computes. That is, because the code case-analyzes compare k k', we need to do the analogous case-analysis in the proof. Fortunately, we can use the same mechanism to do it: with!

```
ins-bh : \{t: Tree\} \{kv: Key \times Value\} \{n: Nat\} \rightarrow HasBH \ (n) \rightarrow HasBH \ (ins \ t \ kv) \ n ins-bh HBH-Empty = HBH-Node HBH-Empty CH-Red HBH-Empty ins-bh \{.\} \{k,v\} (HBH-Node \ n\} \{m\} \{c\} \{l\} \{r\} \{k',v'\} \ hl \ ch \ hr) with compare k k' ... | compare-result = \{!!\}
```

If you look at the the goal, you'll see that something slightly magical has happened:

```
Goal: HasBH (ins Key compare Value (Node I Red (k',v') r) (k,v) | compare-result) m ... compare-result : Order
```

When you do a **with**, Agda replaces all occurences (in the context and goal) of the expression being case-analyzed with the result of the **with**. In this case, this means that the one occurence of compare k k' in the goal is replaced with the variable compare-result. (This expression doesn't occur in the context, so no replacement happens there. We didn't notice this feature of **with** when writing ins because compare k k' didn't appear in any types there, because all the code was simply-typed.) So now, if we case-analyze compare-result, ins will be applied to a constructor, and will reduce.

```
ins-bh : \{t: Tree\} \{kv: Key \times Value\} \{n: Nat\} \rightarrow HasBH \ t \ n \rightarrow HasBH \ (ins \ t \ kv) \ n ins-bh HBH-Empty = HBH-Node HBH-Empty CH-Red HBH-Empty ins-bh \{.\} \{k,v\} (HBH-Node \{n\} \{m\} \{c\} \{I\} \{r\} \{k',v'\} hl ch hr) with compare k k' ... | Less = \{!!\} ... | Equal = \{!!\} ... | Greater = \{!!\}
```

For example, in the Less case, the goal is now HasBH (balance (ins I (k,v)) Red (k',v') r),, which we can solve by appealing to balance-bh, using the recursive call and hI and hr: The Greater case is analogous, the Equal case is just making a Node.

1.3.12 Tying it all together

With these lemmas in hand, proving the overall theorem is easy: if t has a black-height then insert t kv does too, by composing the lemmas about blackRoot and ins. Since the above development involved a bunch of false starts and iteration, to explain the various necessary Agda features, the complete proof (modulo the cases of balance-bh that we haven't done yet) is in Figure 1.3.

This development is an example of what we will call *extrinsic verification*: First, we wrote the code for red-black trees, as a traditional simply-typed program. Then, we wrote a separate proof of a correctness property of it, using dependent types to reason about the code.

1.3.13 Propositional Equality

One very important inductive family is *propositional equality*. This a type $M \equiv N$, where M N : A, representing equality of M and N. It is defined with one constructor, Refl:

```
\label{eq:data} \begin{array}{l} \mbox{data} \_{==} \_ \left\{ \mbox{A} : \mbox{Set} \right\} : \mbox{A} \rightarrow \mbox{Set} \mbox{ where} \\ \mbox{Refl} : \left\{ \mbox{M} : \mbox{A} \right\} \rightarrow \mbox{M} \ \equiv \ \mbox{M} \end{array}
```

Reflexivity says that $M \equiv M$.

```
data ColorHeight : Color \rightarrow Nat \rightarrow Nat \rightarrow Set where
  CH-Red: {n: Nat} → ColorHeight Red n n
  CH-Black : \{n : Nat\} \rightarrow ColorHeight Black n (S n)
\textbf{data} \ HasBH: \ Tree \rightarrow Nat \rightarrow Set \ \textbf{where}
  HBH-Empty: HasBH Empty 1
  HBH-Node: \{n m : Nat\} \{c : Color\} \{lr : Tree\} \{kv : Key \times Value\}
               \rightarrow \text{HasBHIn}
               \rightarrow ColorHeight c n m
               \rightarrow HasBH r n
               \rightarrow HasBH (Node I c kv r) m
blackenRoot-bh : \{t : Tree\} \{n : Nat\} \rightarrow HasBH t n \rightarrow \Sigma \backslash m \rightarrow (HasBH (blackenRoot t) m)
blackenRoot-bh HBH-Empty = _,HBH-Empty
blackenRoot-bh (HBH-Node hl ch hr) = _{-}, (HBH-Node hl CH-Black hr)
balance-bh: \{I: Tree\} \{c: Color\} \{kv: (Key \times Value)\} \{r: Tree\} \{n \ m: Nat\}
             \rightarrow HasBH I n \rightarrow ColorHeight c n m \rightarrow HasBH r n \rightarrow HasBH (balance I c kv r) m
balance-bh {(Node (Node a Red x b) Red y c)} {Black} {z} {d}
                (HBH-Node (HBH-Node ha CH-Red hb) CH-Red hc) CH-Black hd =
  HBH-Node (HBH-Node ha CH-Black hb) CH-Red (HBH-Node hc CH-Black hd)
balance-bh \{(Node\ a\ Red\ x\ (Node\ b\ Red\ y\ c))\} \{Black\} \{z\} \{d\}\ hl\ ch\ hr\ =\ \{!!\}
balance-bh \{a\} \{Black\} \{x\} \{(Node (Node b Red y c) Red z d)\} hl ch hr = \{!!\}
balance-bh \{a\} \{Black\} \{x\} \{(Node b Red y (Node c Red z d))\} hl ch hr = \{!!\}
balance-bh hl ch hr = \{!!\}
ins-bh : \{t : Tree\} \{kv : Key \times Value\} \{n : Nat\} \rightarrow HasBH t n \rightarrow HasBH (ins t kv) n
ins-bh HBH-Empty = HBH-Node HBH-Empty CH-Red HBH-Empty
ins-bh \{.\} \{k,v\} (HBH-Node \{n\} \{m\} \{c\} \{I\} \{r\} \{k',v'\} hl ch hr) with compare k k'
                                                                               | Less = balance-bh (ins-bh hl) ch hr
                                                                                 Equal = HBH-Node hl ch hr
...
                                                                                Greater = balance-bh hl ch (ins-bh hr)
insert-bh : \{n : Nat\} \{t : Tree\} \{kv : (Key \times Value)\} \rightarrow HasBH t n \rightarrow \Sigma (\lambda m \rightarrow (HasBH (insert t kv) m))\}
insert-bh h = blackenRoot-bh (ins-bh h)
```

Figure 1.3: Black Height, Extrinsically

Propositional equality can be used to prove equational specifications about functions; you'll see this in lab. We will also sometimes use it to write tests.

Another use of propositional equality is computational definitions. For example, here's another way to define HasBH tn: First, we define a function computing the black-height of a tree. Then we say that a tree has a black-height if that function returns Some:

```
incr-if-black : Color \rightarrow Nat \rightarrow Nat incr-if-black Red x = x incr-if-black Black x = S x black-height : Tree \rightarrow Maybe Nat black-height Empty = Some 0 black-height (Node I c _ r) with (black-height I) | (black-height r) ... | Some Ih | Some rh with Nat.equal Ih rh ... | True = Some (incr-if-black c Ih) ... | False = None black-height (Node I c _ r) | _ | _ = None HasBH : Tree \rightarrow Nat \rightarrow Set HasBH t n = black-height t \equiv Some n
```

These kinds of definitions can sometimes be useful for automating proofs using computation (like the ssreflect library in Coq). However, the style of proofs that we did above, which used dependent pattern matching, work better when properties are defined via inductive families.

1.4 Black Height, Intrinsically

Compare the code in Figure 1.1 with the proof in Figure 1.3. What you should notice is that *the proof has exactly the same structure as the code!* There is one lemma in the proof for each function in the code, and the proof of each lemma exactly mirrors the corresponding function: the proof manipulates the derivations of HasBH t n in exactly the same way that the code manipulates trees. This suggests that this example is ripe for *intrinsic verification*: rather than first writing the code, and then doing a proof about it, we can bake the proof into the code.

Instead of first defining trees, and then defining HasBH t n, we just define *trees of height n* as the basic data structure. Colors become indexed by the "input" and "output" size, just like ColorHeight is. Then, we take the blackheight specs that we *proved* above, and make them the *types* of the functions. Then, except for some $_$'s because of the Σ -type in the result of blackenRoot, *the exact same code as above type-checks with these fancier types*. Moreover, we avoid the issue where balance was hard to reason about, because of its pattern-matching, because we never reason *about* the reduction behavior of the code. The reason this works out so nicely is that the proof has the same structure as the code, so we can merge the two without changing the code.

There are pros and cons of intrinsic and extrinsic verification:

• **Finding bugs** With intrinsic verification, the type checker will help you find bugs as you write the code. For example, mis-coloring the result of balance

```
balance (Node (Node a Red x b) Red y c) Black z d = Node (Node a Black x b) Black y (Node c Black z d)
will be a type error

S.n!=.n of type Nat
when checking that the expression
Node (Node a Black x b) Black y (Node c Black z d) has type
Tree (S.n)

Extrinsically, you'll find the same bug if you try to do the proof as you write the code:
```

```
balance-bh \left\{ (Node \ (Node \ a \ Red \ x \ b) \ Red \ y \ c) \right\} \left\{ Black \right\} \left\{ z \right\} \left\{ d \right\} \\ (HBH-Node \ (HBH-Node \ ha \ CH-Red \ hb) \ CH-Red \ hc) \ CH-Black \ hd) \\ = HBH-Node \ (HBH-Node \ ha \ CH-Black \ hb) \ XXX \ (HBH-Node \ hc \ CH-Black \ hd)
```

```
data Color (n : Nat) : Nat → Set where
   Red: Color n n
   Black: Color n (S n)
data Tree : Nat \rightarrow Set where
   Empty: Tree 1
  Node : \{n \text{ m} : \text{Nat}\} \rightarrow \text{Tree } n \rightarrow (c : \text{Color } n \text{ m}) \rightarrow (\text{Key} \times \text{Value}) \rightarrow \text{Tree } n \rightarrow \text{Tree } m
balance: \{n \ m : Nat\} \rightarrow Tree \ n \rightarrow (c: Color \ n \ m) \ (kv: (Key \times Value)) \rightarrow Tree \ n \rightarrow Tree \ m
balance (Node (Node a Red x b) Red y c) Black z d = Node (Node a Black x b) Red y (Node c Black z d)
balance (Node a Red x (Node b Red y c)) Black z d = Node (Node a Black x b) Red y (Node c Black z d)
balance a Black x (Node (Node b Red y c) Red z d) = Node (Node a Black x b) Red y (Node c Black z d)
balance a Black x (Node b Red y (Node c Red z d)) = Node (Node a Black x b) Red y (Node c Black z d)
balance I c kv r = Node I c kv r
ins : \{n : Nat\} \rightarrow Tree \ n \rightarrow (Key \times Value) \rightarrow Tree \ n
ins Empty kv = Node Empty Red kv Empty
ins (Node I c (k', v') r) (k, v) with compare k k'
... | Equal = Node lc(k, v) r
... | Less = balance (ins I(k,v)) c (k',v') r
... | Greater = balance lc(k', v') (ins r(k, v))
blacken-root : \{n : Nat\} \rightarrow Tree \ n \rightarrow \Sigma \ (\lambda \ (m : Nat) \rightarrow Tree \ m)
blacken-root Empty = _, Empty
blacken-root (Node I _ kv r) = _, Node I Black kv r
insert : \{n : Nat\} \rightarrow Tree \ n \rightarrow Key \times Value \rightarrow \Sigma \ (\lambda \ (m : Nat) \rightarrow Tree \ m)
insert t kv = blacken-root (ins t kv)
```

Figure 1.4: Black Height, Intrinsically

Here, XXX must have type ColorHeight Black (S n) (S n).

- How easy is it to write? Intrinsic verification often leads to a shorter overall artifact. On the other hand, sometimes writing the code and proof at once takes more thought than writing the code, and then banging out the proof.
- How easy is it to read? Sometimes, intrinsically verified code is easier to read, because you see the code and
 its proprties at once—especially when the intrisically verified code is pretty close to the code you would have
 written anyway, like above. However, sometimes the proof has a very different structure than the code, so when
 you combine them, the combined artifact is harder to read.
- Separation of properties Extrinsically, you can prove separate properties separately—for example, if we want to verify the well-red invariant, or sortedness, we can do a completely separate proof about the same piece of code. Intrinsically, there is only one artifact, so we would have to change the above code to include some additional verification.
- Efficiency Extrinsically, you can write the code however you want, and the proofs, or the data necessary to do the proofs (like the black-height), do not influence how it runs. However, even extrinsically, it's often the case that writing code with the proofs in mind will make the overall effort easier—sometimes it's worth making the code a bit less efficient to make it easier to reason about.
 - Intrinsically, you're running the proof, so the data and control-flow necessary for the proof influences the efficiency of your code. In the example above, there are additional natural numbers (the black height) carried around at run time—unless the compiler optimizes them away [1]. In the above example, we didn't need to change the code, but sometimes the proof requires a slightly different structure, as we'll see below.

Both are important tools to have in your toolbox; picking between them is kind of an art.

1.5 Well-Red, Extrinsically

Next, let's look at the well-red invariant, extrinsically and intrinsically. There are a few lessons from this example: In the extrinsic verification, we'll see an example of a common technique called *views*, and use this to solve the problem with verifying balance that we had above. The intrinsic verification will be a good opportunity to revisit the trade-offs listed above, because the proof will change the structure of the code somewhat.

1.5.1 Views

Recall the issue with balance that we had above: it was hard to reason about because of overlaping patterns. In this section, we'll see a way to get around this problem—which is not perfect, but at least gets the job done. The first step is to make the code for balance not rely on overlapping patterns. We do this by defining a *view*, an auxiliary datatype that describes the relevant cases. The two cases relevant to balance are (1) there is a violation, or (2) there is no violation. In each case, we will record the data that we used to construct the result of balance above: When there is a violation, we need to record the subtrees/key-values a x b y c z d. When there is no violation, we record the l c kv r that were passed in:

```
data BalanceView : Set where
Violation : Tree \rightarrow (Key \times Value) \rightarrow Tree \rightarrow (Key \times Value) \rightarrow Tree \rightarrow (Key \times Value) \rightarrow Tree \rightarrow BalanceView \\ OK : Tree \rightarrow Color \rightarrow Key \times Value \rightarrow Tree \rightarrow BalanceView
```

Now, given I co kv r, we can detect whether there was a violation with the same case-analysis that we used above in balance.

```
view : Tree \rightarrow Color \rightarrow (Key \times Value) \rightarrow Tree \rightarrow BalanceView view (Node (Node a Red x b) Red y c) Black z d = Violation a x b y c z d view (Node a Red x (Node b Red y c)) Black z d = Violation a x b y c z d view a Black x (Node (Node b Red y c) Red z d) = Violation a x b y c z d view a Black x (Node b Red y (Node c Red z d)) = Violation a x b y c z d view I co kv r = OK I co kv r
```

And, now balance has non-overlapping patterns: if there is a violation, we rotate; otherwise, we make a Node:

```
balance : Tree \rightarrow (c : Color) (kv : (Key \times Value)) \rightarrow Tree \rightarrow Tree balance I co kv r with view I co kv r ... | Violation a x b y c z d = Node (Node a Black x b) Red y (Node c Black z d) ... | OK I' co' kv' r' = Node I' co' kv' r'
```

Of course, you might object that we've just squeezed the balloon: balance avoids overlapping patterns, but view uses them! This is true, but this balloon-squeezing is helpful, because it localizes the annoying reasoning to view, which will be easier than doing it directly in balance.

The rest of the code (ins, blackenRoot, insert) is unchanged from above:

1.5.2 Correctness of the view

First we need a spec for view. If you think about the code carefully, it obeys the following spec. Either

- view I co kv r returns Violation a x b y c z d, where the node made from I co kv r is one of the red-red violations below a black root (e.g., I is (Node (Node a Red x b) Red y c), co is Black, kv is z and r is d)
- view | Black kv r returns OK | Black kv r, and there is no red-red violation at the root of | or r (because such a red-red violation would be flagged as a violation).
- view I Red kv r returns OK I Red kv r, and there might be a red-red violation (because such violations at the root are not flagged).

For now, it's OK if it's a bit of a mystery why the cases that view divides things into are useful; to really understand them, you need understand how they fit with the spec for balance and ins below.

Let's proceed and describe these possibilities using some inductive families. The first, ViolationType a x b y c z d l co kv r, has four constructors, one for each possible orientation of the violation. For example, Violation1 corresponds to the first violation, where l is (Node (Node a Red x b) Red y c), co is Black, kv is z and r is d.

```
data ViolationType (a : Tree) (x : Key × Value) (b : Tree) (y : Key × Value) (c : Tree) (z : Key × Value) (d : Tree) : Tree → Color → Key × Value → Tree → Set where

Violation1 : ViolationType a x b y c z d (Node (Node a Red x b) Red y c) Black z d

Violation2 : ViolationType a x b y c z d (Node a Red x (Node b Red y c)) Black z d

Violation3 : ViolationType a x b y c z d a Black x (Node (Node b Red y c) Red z d)

Violation4 : ViolationType a x b y c z d a Black x (Node b Red y (Node c Red z d))
```

Note that the first six arguments are *the same* in each constructor, so we can put them to the left of the colon, which brings them into scope for the constructors. These are called *parameters* of the type family. The next four arguments are *different* in different constructor; these are called *indices*. The fact that the indices can be different in each constructor is what enables one to represent equality constraints with inductive families. For example, case-analyzing a value of type ViolationType a x b y c z d l co kv r will give you information about l, co, kv, and r.

Next, we need to specify what it means for there to be no red-red violation at the root of a node. First, we define an inductive family specifying the color of a node (Empty is considered black):

```
data RootColored: Tree \rightarrow Color \rightarrow Set where
RC-Empty: RootColored Empty Black
RC-Red: {I: Tree} {kv: Key \times Value} {r: Tree} \rightarrow RootColored (Node I Red kv r) Red
RC-Black: {I: Tree} {kv: Key \times Value} {r: Tree} \rightarrow RootColored (Node I Black kv r) Black
```

Then, the root of a tree is okay if it's empty; or if it's a black node; or if it's a red node and the subtrees are black:

```
\begin{tabular}{ll} \textbf{data} \ RootOK: Tree \rightarrow Set \ \textbf{where} \\ ROK-Empty: RootOK \ Empty \\ ROK-Black: \{I: Tree\} \ \{kv: Key \times Value\} \ \{r: Tree\} \rightarrow RootOK \ (Node \ I \ Black \ kv \ r) \\ ROK-Red: \{I: Tree\} \ \{kv: Key \times Value\} \ \{r: Tree\} \rightarrow RootColored \ I \ Black \rightarrow RootColored \ r \ Black \rightarrow RootOK \ (Node \ I \ Red \ kv \ r) \\ \end{tabular}
```

Finally, we define an inductive family ViewInvariant I co kv r bv, with one constructor for each of the three possibilities mentioned above: when there is a black root with a red-red violation below it, when there is a black root with no red-red violations, and when there is a red root:

The syntax $\forall \{l kv r\} \rightarrow ...$ is shorthand for $\{l : _\} \{kv : _\} \{r : _\} \rightarrow ...$ It's convenient when there are a bunch of quantifiers in a row and you want to omit the type annotations on all of them.

To prove that view satisfies this invariant, we show that ViewInvariant holds for all arguments I, co, kv, and r:

```
view-ok : (I : Tree) (co : Color) (kv : Key \times Value) (r : Tree) \rightarrow ViewInvariant I co kv r (view I co kv r)
```

The proof is rather ugly (133 cases!), because there is a lot of duplication necessary to expand things enough that view computes (see the discussion about balance above). But the cases can be generated by Agda, and the right-hand side is a trivial application of constructors, which can be constructed automatically by Agda, using mechanisms that we haven't talked about yet. The benefit of making a view datatype, as opposed to doing the same case-analysis directly in balance, is that we need to do this ugly proof only once, and can henceforth reason in terms of the the view's invariant. For example, we will be able to use this proof to prove the well-red invariant, the black-height invariant, and the sortedness invariant.

1.5.3 Insert is Well-Red

Next, we'd like to prove that the result of insert is well-red, assuming the input is. Recall that a tree is well-red if both children of every red node are black. We can specify this more formally as follows: the empty tree is well-red; a black node is well-red if its subtrees are; a red node is well-red if its subtrees are, and the roots of both are black.

```
data WellRed: Tree → Set where
     WR-Empty: WellRed Empty
     WR-Black : \{I : Tree\} \{kv : Key \times Value\} \{r : Tree\}
               \rightarrow WellRed I
               → WellRed r
               → WellRed (Node I Black kv r)
     WR\text{-Red}: \{I: Tree\} \{kv: Key \times Value\} \{r: Tree\}
               \rightarrow WellRed I
               \rightarrow WellRed r
               \rightarrow RootColored I Black
               → RootColored r Black
               → WellRed (Node I Red kv r)
Now, we'd like to prove
  insert-wellred : \{t : Tree\} \{kv : Key \times Value\}
      → WellRed t
      → WellRed (insert t kv)
```

But to prove this, we'll need to invent some lemmas about blackenRoot and ins and balance, and these lemmas are somewhat subtle. For example, it's not the case that ins t kv always returns a well-red tree! As a counterexample, we can instantiate the module mapping Nats to Unit, and construct the tree

which has a red-red violation! The tricky part of red-black trees is that rotating the tree to balance it sometimes creates red-red violations—but these then get fixed up.

So we need to figure out the discipline to this process: why do the violations always get fixed? The essence of the idea is that whenever there is a black grandparent with a red child that itself has a red child, we fix the red-red violation (these are the cases of balance). But when there is a red node that acquires a new grandchild, we sometimes create a red-red violation. But this violation will be fixed by its parent, which must be black (because the input is well-red). What if it doesn't have a parent, because it's the root? Then it will be fixed by blackening the root. This logic—the clever part of red-black trees—is somewhat obscured in the above code, but the proof really clarifies it.

Because the responsibility for fixing a red-red violation lies with the enclosing black grandparent, these violations will get fixed as the recursion in ins percolates up the tree. The only place where they won't get fixed is at the root, because there might not be a black grandparent. Thus, we need to describe a tree that has no red-red violations, except possibly at the root. We say tht such a tree is *almost well-red*:

```
 \begin{tabular}{ll} \textbf{data} & \textbf{AlmostWellRed} : \textbf{Tree} & \rightarrow \textbf{Set where} \\ & \textbf{AWR-Empty} : \textbf{AlmostWellRed Empty} \\ & \textbf{AWR-Node} : \{\textbf{I}: \textbf{Tree}\} \, \{\textbf{kv}: \textbf{Key} \times \textbf{Value}\} \, \{\textbf{r}: \textbf{Tree}\} \, \{\textbf{c}: \textbf{Color}\} \\ & \rightarrow \textbf{WellRed I} \\ & \rightarrow \textbf{WellRed I} \\ & \rightarrow \textbf{AlmostWellRed} \, (\textbf{Node I c kv r}) \\ \end{tabular}
```

The empty tree is almost well-red; a node (of any color) is well-red if its subtrees are well-red.

It's immediate that an almost well-red tree whose root has no violation, in the sense defined above, is in fact well-red; and that any well-red tree is almost well-red:

```
combine : \{t: Tree\} \rightarrow RootOK\ t \rightarrow AlmostWellRed\ t \rightarrow WellRed\ t combine ROK-Empty a=WR-Empty combine ROK-Black (AWR-Node wl wr) = WR-Black wl wr combine (ROK-Red rl rr) (AWR-Node wl wr) = WR-Red wl wr rl rr forget : \{t: Tree\} \rightarrow WellRed\ t \rightarrow AlmostWellRed\ t forget WR-Empty = AWR-Empty forget (WR-Red wl wr _ _) = AWR-Node wl wr forget (WR-Black wl wr) = AWR-Node wl wr
```

Correctness of ins Based on the above discussion, we can start by trying to prove the following two invariants: First, if you ins into a well-red black tree, then you get a well-red tree, because any red-red violations will ultimately be fixed. Second, if you ins into a red well-red tree, then the result will be almost well-red. We'll need some lemmas about balance to prove this, but we can discover them as we go.

```
ins-black : (t : Tree) (kv : Key \times Value) \rightarrow RootColored t Black \rightarrow WellRed t \rightarrow WellRed (ins t kv) ins-red : <math>(t : Tree) (kv : Key \times Value) \rightarrow RootColored t Red \rightarrow WellRed t \rightarrow AlmostWellRed (ins t kv)
```

Let's tackle ins-black first. First, we can split on the proof that t is well-red. Then it's easy to fill in the case for Empty, and the case for WR-Red is impossible because of rt.

```
ins-black .Empty kv rt WR-Empty = WR-Red WR-Empty WR-Empty RC-Empty RC-Empty ins-black .(Node I Red (k',v') r) kv () (WR-Red \{I\} \{k',v'\} \{r\} wl wr rl rr) ins-black .(Node I Black (k',v') r) (k,v) rt (WR-Black \{I\} \{k',v'\} \{r\} wl wr) = \{!!\}
```

In the WR-Black case, we need to show WellRed (ins (Node I Black (k', v') r) (k, v)), but computationa is stuck on compare k k' because of the with. So we need to do a with in the proof:

```
ins-black .Empty kv rt WR-Empty = WR-Red WR-Empty WR-Empty RC-Empty ins-black .(Node I Red (k',v') r) kv () (WR-Red \{I\} \{k',v'\} \{r\} wl wr rl rr) ins-black .(Node I Black (k',v') r) (k,v) rt (WR-Black \{I\} \{k',v'\} \{r\} wl wr) with compare k k' ... | Less = \{!!\} ... | Equal = WR-Black wl wr ... | Greater = \{!!\}
```

The Equal case is obvious, because the structure of the tree doesn't change. In the Less case, we need to show that balance (ins I(k,v)) Black (k',v') r is well-red. This will clearly require a lemma about balance, as well as an inductive hypothesis about ins I(k,v).

However, we don't know whether the root of I is black or red, so it's unclear whether the IH will be a call to ins-black or ins-red. Fortunately, it doesn't matter: it will be enough to know that ins I(k, v) is almost well-red, which is true whether the root is red (because that's what ins-red says) or whether the root is black (because we can forget that the tree is well-red, and remember only that it's almost well-red).

```
\label{eq:decide-root} \begin{tabular}{ll} $\operatorname{decide-root}: (t: Tree) \to \operatorname{Either} (\operatorname{RootColored} t \operatorname{Black}) \ (\operatorname{RootColored} t \operatorname{Red}) \\ \end{tabular} \begin{tabular}{ll} \operatorname{decide-root} (\operatorname{Empty} & \operatorname{Inl} \operatorname{RC-Empty} \\ \end{tabular} \begin{tabular}{ll} \operatorname{decide-root} (\operatorname{Node} \ _{-}\operatorname{Red} \ _{-}\ _{-}) & \operatorname{Inr} \operatorname{RC-Red} \\ \end{tabular}
```

```
\label{eq:decide-root} \begin{array}{l} \text{decide-root} \ (\text{Node} \_ \, \text{Black} \_\_) \ = \ \text{InI} \ RC\text{-Black} \\ \text{ins-any} : \ (t: Tree) \ (kv: Key \times Value) \rightarrow WellRed \ t \rightarrow AlmostWellRed \ (ins \ t \ kv) \\ \text{ins-any} \ t \ kv \ wt \ \textbf{with} \ decide-root \ t \\ \dots \ | \ InI \ rt \ = \ forget \ (ins\text{-black} \ t \ kv \ rt \ wt) \\ \dots \ | \ Inr \ rt \ = \ ins\text{-red} \ t \ kv \ rt \ wt \end{array}
```

This suggests the first lemma about balance that we'll need: by ins-any, ins I(k, v) will be almost well-red, and r is well-red, so it suffices to show:

balance-fix-left: If I is almost well-red, and r is well-red, and co is Black, then balance I co ky r is well-red.

That is, when the root is black, and one side is almost well-red, and the other is well-red, then balance will do a tree rotation to fix the violation.

We defer the proof of this lemma, and a symmetric one where r is almost well-red and l is well-red:

```
\begin{array}{l} \text{balance-fix-left}: (I: \mathsf{Tree}) \ (\mathsf{kv}: \mathsf{Key} \times \mathsf{Value}) \ (\mathsf{r}: \mathsf{Tree}) \\ \to \mathsf{AlmostWellRed} \ \mathsf{I} \\ \to \mathsf{WellRed} \ \mathsf{r} \\ \to \mathsf{WellRed} \ (\mathsf{balance} \ \mathsf{I} \ \mathsf{Black} \ \mathsf{kv} \ \mathsf{r}) \\ \mathsf{balance-fix-right}: \ (\mathsf{I}: \mathsf{Tree}) \ (\mathsf{kv}: \mathsf{Key} \times \mathsf{Value}) \ (\mathsf{r}: \mathsf{Tree}) \\ \to \mathsf{WellRed} \ \mathsf{I} \\ \to \mathsf{AlmostWellRed} \ \mathsf{r} \\ \to \mathsf{WellRed} \ (\mathsf{balance} \ \mathsf{I} \ \mathsf{Black} \ \mathsf{kv} \ \mathsf{r}) \end{array}
```

and complete the proof of ins-black:

```
\label{eq:continuous_problem} \begin{split} & \text{ins-black .Empty kv rt WR-Empty} &= \text{WR-Red WR-Empty WR-Empty RC-Empty ins-black .} \\ & \text{(Node I Red kv' r) kv () (WR-Red {I} {kv'} {r} y y' y0 y1)} \\ & \text{ins-black .} \\ & \text{(Node I Black (k',v') r) (k,v) rt (WR-Black {I} {k',v'} {r} wl wr) \textbf{with } compare k k' ... | Less = balance-fix-left (ins I (k,v)) (k',v') r (ins-any I (k,v) wl) wr ... | Equal = WR-Black wl wr ... | Greater = balance-fix-right I (k',v') (ins r (k,v)) wl (ins-any r (k,v) wr)} \end{split}
```

On to ins-red. Split on the proof that t is well-red, and then it's easy to fill in the Empty case, and to contradict the Black case. In the Red case we need to look at compare k k' for the same reason as above, and the Equal case is easy.

```
ins-red : (t : Tree) (kv : Key \times Value) \rightarrow RootColored t Red \rightarrow WellRed t \rightarrow AlmostWellRed (ins t kv) ins-red .Empty kv rc WR-Empty = AWR-Node WR-Empty WR-Empty ins-red .(Node I Black kv' r) kv () (WR-Black {I} {kv'} {r} y y') ins-red .(Node I Red (k',v') r) (k,v) rc (WR-Red {I} {k',v'} {r} wl wr rl rr) with compare k k' ... | Less = {!!} ... | Equal = AWR-Node wl wr ... | Greater = {!!}
```

In the Less case, we need to show

AlmostWellRed (balance Key compare Value (ins I (k,v)) Red (k',v') r)

```
rr : RootColored r Black
rl : RootColored l Black
wr : WellRed r
wl : WellRed l
```

That is, because the root is red, in this case, we know that I and r are both black. Therefore we can use the inductive call ins-black to conclude that ins I(k,v) is well-red, and we already know that r is well-red. Thus, the final lemma that we need about balance is as follows:

```
\begin{array}{l} \text{balance-break} : (I: \mathsf{Tree}) \; (\mathsf{kv}: \mathsf{Key} \times \mathsf{Value}) \; (\mathsf{r}: \mathsf{Tree}) \\ \to \mathsf{WellRed} \; \mathsf{I} \\ \to \mathsf{WellRed} \; \mathsf{r} \\ \to \mathsf{AlmostWellRed} \; (\mathsf{balance} \; \mathsf{I} \; \mathsf{Red} \; \mathsf{kv} \; \mathsf{r}) \\ \mathsf{balance-break} \; = \; \{!!\} \end{array}
```

If both I and r are well-red, and the root is red, then balance returns an almost well-red tree. Recall the counter-example above, which shows that it doesn't always create a well-red—it's important that we give ins the slack to return an almost well-red tree when the root is red!

To complete the proof we just need to apply this lemma to the IH and the assumption about r:

```
ins-black .(Node I Black (k',v') r) (k,v) rt (WR\text{-Black }\{I\}\{k',v'\}\{r\}\text{ wl wr}) with compare k k' ... | Less = balance-fix-left (ins I (k,v)) (k',v') r (ins-any I (k,v) wl) wr ... | Equal = WR-Black wl wr ... | Greater = balance-fix-right I (k',v') (ins r (k,v)) wl (ins-any r (k,v) wr)
```

Now, by ins-any, we know that ins t(k, v) is always almost well-red. To finish off insert, we need to take an almost well-red tree and make it well-red. This is exactly the purpose of blackenRoot: if we make the root black, that fixes any possible red-red violation at the root!

```
blackenRoot\text{-}fix: \{t: Tree\} \rightarrow AlmostWellRed\ t \rightarrow WellRed\ (blackenRoot\ t) \\ blackenRoot\text{-}fix\ AWR\text{-}Empty = WR\text{-}Empty \\ blackenRoot\text{-}fix\ (AWR\text{-}Node\ wl\ wr) = WR\text{-}Black\ wl\ wr
```

Figure 1.5 collects the bits of proof that we've developed so far, and concludes with insert-wellred. One detail that we skipped above: because ins-black and ins-red and ins-any all call each other, they are *mutually inductive*. In Agda, this is notated by putting them in a mutual block.

Correctness of balance To prove balance-fix-left, we will use our invariant about view from above. Before we do that, let's see why we need it. Suppose we try to prove the theorem. We clearly need to do a **with** on view, because that's what balance does: the goal is

WellRed (balance Key compare Value | Black kv r | view | Black kv r)

```
balance\text{-fix-left}: (I: Tree) \ (kv: Key \times Value) \ (r: Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ (balance \ I \ Black \ kv \ r) \\ balance\text{-fix-left} \ I \ kv \ r \ al \ wr \ \textbf{with} \ view \ I \ Black \ kv \ r \\ ... \ | \ bv \ = \ \{!!\}
```

So far, so good: the goal is now

WellRed (balance Key compare Value I Black kv r | bv)

so we can match on by and make progress:

```
balance-fix-left: (I: Tree) \ (kv: Key \times Value) \ (r: Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ (balance \ I \ Black \ kv \ r) \\ balance-fix-left \ I \ kv \ r \ al \ wr \ | \ Violation \ a \ x \ b \ y \ c \ z \ d \ = \ \{!!\} \\ balance-fix-left \ I \ kv \ r \ al \ wr \ | \ OK \ I' \ co' \ kv' \ r' \ = \ \{!!\}
```

Now, the goal has reduced appropriately, to WellRed (Node (Node a Black x b) Red y (Node c Black z d)) in the first case, and to WellRed (Node l' co' kv' r'). The outer structure of the Violation case is obvious:

```
balance-fix-left: (I:Tree) \ (kv:Key \times Value) \ (r:Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ (balance\ I \ Black \ kv \ r) \\ balance-fix-left\ I \ kv \ r \ al \ wr \ | \ Violation \ ax \ by \ cz \ d = WR-Red \ (WR-Black \ \{!!\} \ \{!!\}) \ (WR-Black \ \{!!\} \ \{!!\}) \ RC-Black \ RC-Black \ balance-fix-left\ I \ kv \ r \ al \ wr \ | \ OK \ I'co' \ kv' \ r' = \ \{!!\}
```

```
balance-fix-left: (I:Tree) \ (kv:Key \times Value) \ (r:Tree) \ \rightarrow \ AlmostWellRed \ I \ \rightarrow \ WellRed \ (balance \ I \ Black \ kv \ r)
balance-fix-left = \{!!\}
balance-fix-right: (I:Tree) (kv:Key \times Value) (r:Tree) \rightarrow WellRed I \rightarrow AlmostWellRed r \rightarrow WellRed (balance I Black kv r)
balance-fix-right = \{!!\}
balance-break: (I:Tree) \ (kv:Key \times Value) \ (r:Tree) \rightarrow WellRed \ I \rightarrow WellRed \ r \rightarrow AlmostWellRed \ (balance\ I\ Red\ kv\ r)
balance-break = \{!!\}
decide-root : (t : Tree) → Either (RootColored t Black) (RootColored t Red)
decide-root Empty = Inl RC-Empty
decide-root (Node _ Red _ _) = Inr RC-Red
decide-root (Node _ Black _ _) = Inl RC-Black
mutual
  ins-black : (t : Tree) (kv : Key \times Value) \rightarrow RootColored t Black \rightarrow WellRed (ins t kv)
  ins-black .Empty kv rt WR-Empty = WR-Red WR-Empty WR-Empty RC-Empty RC-Empty
  ins-black .(Node I Red kv' r) kv () (WR-Red {I} {kv'} {r} y y' y0 y1)
  ins-black .(Node I Black (k',v') r) (k,v) rt (WR-Black {I} {k',v'} {r} wl wr) with compare k k'
  ... | Less = balance-fix-left (ins I(k,v)) (k',v') r (ins-any I(k,v) wl) wr
  ... | Equal = WR-Black wl wr
  ... | Greater = balance-fix-right | (k', v') (ins r(k, v)) w| (ins-any r(k, v) wr)
  ins-red: (t: Tree) (kv: Key × Value) → RootColored t Red → WellRed t → AlmostWellRed (ins t kv)
  ins-red .Empty kv rc WR-Empty = AWR-Node WR-Empty WR-Empty
  ins-red .(Node I Black kv' r) kv () (WR-Black {I} {kv'} {r} y y')
  ins-red .(Node | Red (k',v') r) (k,v) rc (WR-Red \{ \} \{ k',v' \} \{ r \}  wl wr rl rr) with compare k k'
  ... | Less = balance-break (ins I(k,v)) (k',v') r (ins-black I(k,v) rl wl) wr
  ... | Equal = AWR-Node wl wr
  ... | Greater = balance-break I(k', v') (ins r(k, v)) wl (ins-black r(k, v) rr wr)
  ins-any : (t : Tree) (kv : Key \times Value) \rightarrow WellRed t \rightarrow AlmostWellRed (ins t kv)
  ins-any t kv wt with decide-root t
  ... | Inl rt = forget (ins-black t kv rt wt)
  ... | Inr rt = ins-red t kv rt wt
blackenRoot-fix : \{t : Tree\} \rightarrow AlmostWellRed t \rightarrow WellRed (blackenRoot t)
blackenRoot-fix AWR-Empty = WR-Empty
blackenRoot-fix (AWR-Node wl wr) = WR-Black wl wr
insert-wellred : \{t : Tree\} \{kv : Key \times Value\} \rightarrow WellRed t \rightarrow WellRed (insert t kv)
insert-wellred w = blackenRoot-fix (ins-any _ _ w)
```

Figure 1.5: Correctness of insert

But now we need

?0: WellRed a ?1: WellRed b ?2: WellRed c ?3: WellRed d

to finish the proof. What do we have in the context?

wr : WellRed r al : AlmostWellRed I

Morally, this is enough information: when view | Black kv r returns Violation a x b y c z d, the trees a b c d are subtrees of | or r, and the above info is enough to see that they are well-red. However, in the code, we've lost the connection between | and r and a b c d. That's where ViewInvariant comes in.

Something similar happens in the second case: we've lost the connection between I' co' kv' r' and I Black kv r. Moreover, we have no way of knowing that there was no red-red violation in I, which is necessary to conclude that it is well-red.

On to take 2: we use view-ok from above:

```
balance-fix-left : (I : Tree) (kv : Key \times Value) (r : Tree) \rightarrow AlmostWellRed I \rightarrow WellRed (balance I Black kv r) balance-fix-left I kv r al wr with view-ok I Black kv r ... | vok = \{! \text{ vok}!\}
```

Now, we want to split on vok, but if we try to do so, we get the following error message:

Cannot decide whether there should be a case for the constructor ViolationInv, since the unification gets stuck on unifying the inferred indices $[I_2, co, kv_2, r_2, Violation \ a \ x \ b \ y \ c \ z \ d]$ **with** the expected indices $[I_1, Black, kv_1, r_1, view \ I_1]$ Black $kv_1 \ r_1]$

What gives? Splitting vok would require deciding whether there are some $l_1 \text{ kv}_1 \text{ r}_1$ such that view $l_1 \text{ Black kv}_1 \text{ r}_1$ equals Violation a x b y c z d: if there are, we need to give a case for ViolationOK; if there aren't, we don't. However, there's no unique way to solve this equation: it could be any of the red-red violations. So Agda gets stuck. But this seems wrong, since the whole point of view-ok is to tell us what happened with view!

The solution is to do a *double with*: we need to look at both view and view-ok simultaneously! The syntax is to separate multiple withs with a |—think of this as adding *two* columns to the pattern-match.

```
balance-fix-left : (I : Tree) (kv : Key \times Value) (r : Tree) \rightarrow AlmostWellRed I \rightarrow WellRed (balance I Black kv r) balance-fix-left I kv r al wr with view I Black kv r | view-ok I Black kv r ... | vw | vok = \{! \text{ vok!}\}
```

Now, we're in the following state:

Goal: WellRed (balance Key compare Value I Black kv r | vw)

vok: ViewInvariant I Black kv r vw

Because of the first column, Agda replaces all occurences of view | Black kv r, including the one balance is stuck on, with the variable vw. Because of the second column, we also have vok: ViewInvariant | Black kv r vw—which, unlike above, is a general enough instance of the inductive family that we can split on it. Doing so gives the following cases:

```
balance-fix-left: (I:Tree) \ (kv:Key\times Value) \ (r:Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ r \rightarrow WellRed \ (balance\ I \ Black\ kv\ r) \\ balance-fix-left\ I \ kv\ r \ al\ wr\ | \ .(OK\ I \ Black\ kv\ r) \ | \ OKBlack\ lnv\ r|\ r= \{!!\} \\ balance-fix-left\ I \ kv\ r \ al\ wr\ | \ .(Violation\ a\ x\ b\ y\ c\ z\ d) \ | \ Violation\ lnv\ \{.I\}\ \{.Black\}\ \{.kv\}\ \{a\}\ \{x\}\ \{b\}\ \{y\}\ \{c\}\ \{d\}\ vt= \{!!\} \\
```

By splitting vok, we learn what vw is—so now we know what view returned, and balance computes. And we have the additional info that we need: in the OKBlackInv case, we have

Goal: WellRed (Node I Black kv r)

wr: WellRed r al: AlmostWellRed I rr: RootOK r rl: RootOK I

So we can finish the case as follows:

```
balance-fix-left: (I: Tree) \ (kv: Key \times Value) \ (r: Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ r \rightarrow WellRed \ (balance \ I \ Black \ kv \ r)
balance-fix-left \ I \ kv \ r \ al \ wr \ | \ .(OK \ I \ Black \ kv \ r) \ | \ OKBlack \ lnv \ r \ r = \ WR-Black \ (combine \ rl \ al) \ wr
balance-fix-left \ I \ kv \ r \ al \ wr \ | \ .(Violation \ a \ x \ b \ y \ c \ z \ d) \ | \ Violation \ lnv \ \{.I\} \ \{.kv\} \ \{.r\} \ \{a\} \ \{x\} \ \{b\} \ \{y\} \ \{c\} \ \{d\} \ vt = \ \{!!\} \ \{.kv\} \ \{.r\} \ \{a\} \ \{x\} \ \{b\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{!!\} \ \{.r\} \ \{a\} \ \{x\} \ \{b\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{!!\} \ \{.r\} \ \{a\} \ \{x\} \ \{b\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{!!\} \ \{.r\} \ \{a\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{!!\} \ \{.r\} \ \{a\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{.r\} \ \{a\} \ \{v\} \ \{c\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{v\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{v\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \ \{d\} \ \{d\} \ \{d\} \ vt = \ \{.r\} \ \{d\} \
```

In the ViolationInv case, we have

Goal: WellRed (Node (Node a Black x b) Red y (Node c Black z d))

wr: WellRed r al: AlmostWellRed I vt: ViolationType a x b y c z d I Black kv r

Above, it was a problem that we knew that I and r were (almost) well-red, but needed to prove something about a b c d. Here, we have a proof of ViolationType conntecting them! If we split on vt, we learn what I kv r were in each case:

```
balance-fix-left: (I: Tree) \ (kv: Key \times Value) \ (r: Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ r \rightarrow WellRed \ (balance \ I Black \ kv \ r) \ balance-fix-left \ I kv \ r \ al \ wr \ with \ view \ I Black \ kv \ r \ | \ view-ok \ I Black \ kv \ r \ | \ balance-fix-left \ I kv \ r \ al \ wr \ | \ .(OK \ I Black \ kv \ r) \ | \ OKBlack \ lnv \ rI \ rr \ = \ WR-Black \ (combine \ rI \ al) \ wr \ balance-fix-left \ .(Node \ (Node \ a \ Red \ x \ b) \ Red \ y \ c) \ .z \ .d \ awabc \ wd \ | \ Violation \ a \ x \ b \ y \ c \ z \ d \ | \ Violation \ lnv \ l
```

For example, in the first case, we now have:

Goal: WellRed (Node (Node a Black x b) Red y (Node c Black z d))

```
\begin{array}{ll} wd & : WellRed\ d\\ awabc : AlmostWellRed\ (Node\ (Node\ a\ Red\ x\ b)\ Red\ y\ c) \end{array}
```

So we can break up awabc to get the necessary information!

```
balance-fix-left: (I: Tree) \ (kv: Key \times Value) \ (r: Tree) \rightarrow AlmostWellRed \ I \rightarrow WellRed \ r \rightarrow WellRed \ (balance \ I Black \ kv \ r)  balance-fix-left \ I \ kv \ r \ al \ wr \ \textbf{with} \ view \ I \ Black \ kv \ r \ | \ view-ok \ I \ Black \ kv \ r  balance-fix-left \ I \ kv \ r \ al \ wr \ | \ . (OK \ I \ Black \ kv \ r) \ | \ OKBlack \ lnv \ r \ r \ = \ WR-Black \ (combine \ rl \ al) \ wr  balance-fix-left \ . (Node \ (Node \ a \ Red \ x \ b) \ Red \ y \ c) \ . z \ . (AWR-Node \ (WR-Red \ wa \ wb \ ca \ cb) \ wc) \ wd   | \ Violation \ a \ x \ b \ y \ c \ z \ d \ | \ Violation \ lnv \ ln
```

The next case is analogous, and the next two are contradictory, because in Violation3 and Violation4 the violation is in r, but here we know that r is well-red. The final proof is as follows:

```
balance-fix-left: (I: Tree) (kv: Key × Value) (r: Tree) → AlmostWellRed I → WellRed r → WellRed (balance I Black kv r) balance-fix-left I kv r al wr with view I Black kv r | view-ok I Black kv r balance-fix-left. (Node (Node a Red x b) Red y c) .z .d (AWR-Node (WR-Red wa wb ca cb) wc) wd | Violation a x b y c z d | ViolationInv Violation1 = WR-Red (WR-Black wa wb) (WR-Black wc wd) RC-Black RC-Black balance-fix-left. (Node a Red x (Node b Red y c)) .z .d (AWR-Node wa (WR-Red wb wc rb rc)) wd | Violation a x b y c z d | ViolationInv Violation2 = WR-Red (WR-Black wa wb) (WR-Black wc wd) RC-Black RC-Black balance-fix-left .a .x .(Node (Node b Red y c) Red z d) al (WR-Red _ _ _ () _ ) | Violation a x b y c z d | ViolationInv Violation3 balance-fix-left .a .x .(Node b Red y (Node c Red z d)) al (WR-Red _ _ _ ()) | Violation a x b y c z d | ViolationInv Violation4 ... | .(OK I Black kv r) | OKBlackInv rI _ = WR-Black (combine rI al) wr
```

balance-fix-right is analogous. For balance-break, the only possible case is OKRedInv, in which case the result follows from the assumptions that I and r are well-red.

The key new technique you should learn from this is the two-column **with**. This is useful when you want to match on something (here, the ViewInvariant), but one of its indices is something specific (like view I Black kv r), which prevents splitting. In this case, you can use a two-column view to replace the specific term with something general, so that you can split.

1.5.4 Discussion

The main thing to take away from this example is that insert is a simple function, with a more complex correctness proof: in the code, it's not apparent that ins is doing different things depending on whether the root is red or black (sometimes it creates violations; sometimes it fixes them), or that balance actually has three different specs. The reasoning necessary to understand the code is much more involved than the actual steps of the algorithm itself.

1.6 Well-Red, Intrinsically

Like before, we can alternatively do an *intrinsic* verification of the well-red invariant, by baking the appropriate invariants into the data structures. Essentially, we "erase" the trees from the above proof, and use that as the algorithm. For the black-height, this kept the code unchanged. Here, the code will change, because, as we discussed, the above proof has a different structure than the code.

First, let's set up the data structures, by erasing the tree arguments from the above definitions of WellRed and AlmostWellRed:

```
data Color: Set where
  Red: Color
  Black: Color
mutual
  data WellRedTree: Set where
    Empty: WellRedTree
    RedNode: (I: WellRedTree)
                \rightarrow (kv : Key \times Value)
                \rightarrow (r : WellRedTree)
                → (rl : RootColored | Black)
                → (rr : RootColored r Black)
                → WellRedTree
    BlackNode: (I: WellRedTree)
                \rightarrow (kv : Key \times Value)
                \rightarrow (r : WellRedTree)
                → WellRedTree
  data RootColored : WellRedTree \rightarrow Color \rightarrow Set where
    RC-Empty: RootColored Empty Black
```

```
RC-Red : {I : WellRedTree} {kv : Key \times Value} {r : WellRedTree} {cl : RootColored | Black} {cr : RootColored r Black} \rightarrow RC-Black : {I : WellRedTree} {kv : Key \times Value} {r : WellRedTree} \rightarrow RootColored (BlackNode | kv r) Black
```

Something a little bit new is going on here: we're mutually defining a datatype (well red trees) along with another inductive family indexed by that datatype (RootColored). This is called an *inductive-inductive* definition [3].

We will also need AlmostWellRedTrees:

```
 \begin{tabular}{ll} \textbf{data} & \textbf{AlmostWellRedTree} : \textbf{Set where} \\ & \textbf{AEmpty} : \textbf{AlmostWellRedTree} \\ & \textbf{ANode} : (I: WellRedTree) \\ & \rightarrow (c: Color) \\ & \rightarrow (kv: Key \times Value) \\ & \rightarrow (r: WellRedTree) \\ & \rightarrow \textbf{AlmostWellRedTree} \\ \end{tabular}
```

Now, the code for balance is similar to the *proof* above: balance is separated into three functions, one which fixes a potential red-red violation on the left (balance-left), on which fixes a potential red-red violation on the right (balance-right), and one which creates a potential violation (balance-break). Here's the code for balance-left:

```
balance-left: AlmostWellRedTree → Key × Value → WellRedTree → WellRedTree

-- these are the two rotation cases

balance-left (ANode (RedNode a x b ra rb) Red y c) z d = RedNode (BlackNode a x b) y (BlackNode c z d) RC-Black RC-Black

balance-left (ANode a Red x (RedNode b y c rb rc)) z d = RedNode (BlackNode a x b) y (BlackNode c z d) RC-Black RC-Black

-- instances of the catch-all

balance-left (ANode a Black x b) kv r = BlackNode (BlackNode a x b) kv r

balance-left (ANode Empty Red x Empty) kv r = BlackNode (RedNode Empty x Empty RC-Empty RC-Empty) kv r

balance-left (ANode Empty Red x (BlackNode I kv r)) kv' r' =

BlackNode (RedNode Empty x (BlackNode I kv r) RC-Empty RC-Black) kv r'

balance-left (ANode (BlackNode a1 x1 a2) Red x Empty) y c =

BlackNode (RedNode (BlackNode a1 x1 a2) Red x (BlackNode b1 y1 b2)) y c =

BlackNode (RedNode (BlackNode a1 x1 a2) Red x (BlackNode b1 y1 b2)) y c =

BlackNode (RedNode (BlackNode a1 x1 a2) x (BlackNode b1 y1 b2)) RC-Black RC-Black) y c
```

You should think of this as analogous to balance I Black kv r, where only I may have a red-red violation. The first two clauses do the two necessary rotations. The remaining clauses are instances of the catch-all case in the simply-typed balance but here we need to expand them because the *proof* is different in each case.

balance-right is symmetric and balance-break is trivial:

```
balance-right: WellRedTree → Key × Value → AlmostWellRedTree → WellRedTree
  -- these are the two rotation cases
balance-right a x (ANode (RedNode b y c _ _) Red z d) = RedNode (BlackNode a x b) y (BlackNode c z d) RC-Black RC-Black
balance-right a x (ANode b Red y (RedNode c z d _ _)) = RedNode (BlackNode a x b) y (BlackNode c z d) RC-Black RC-Black
  -- instances of the catch-all
balance-right a x AEmpty = BlackNode a x Empty
balance-right a x (ANode Empty Red kv Empty) = BlackNode a x (RedNode Empty kv Empty RC-Empty)
balance-right a x (ANode Empty Red kv (BlackNode I kv' r)) =
  BlackNode a x (RedNode Empty kv (BlackNode I kv'r) RC-Empty RC-Black)
balance-right a x (ANode (BlackNode I kv r) Red kv' Empty) =
  BlackNode a x (RedNode (BlackNode I kv r) kv' Empty RC-Black RC-Empty)
balance-right a x (ANode (BlackNode I kv r) Red kv' (BlackNode I' kv0 r')) =
  BlackNode a x (RedNode (BlackNode I kv r) kv' (BlackNode I' kv0 r') RC-Black RC-Black)
balance-right a x (ANode I Black kv r) = BlackNode a x (BlackNode I kv r)
balance\text{-}break: WellRedTree \rightarrow Key \times Value \rightarrow WellRedTree \rightarrow AlmostWellRedTree
balance-break I kv r = ANode I Red kv r
```

Similarly, the code for ins has the same structure as the above proof:

```
decide-root: (t: WellRedTree) → Either (RootColored t Black) (RootColored t Red)
decide-root Empty = Inl RC-Empty
decide-root (RedNode \_ \_ \_ \_) = Inr RC-Red
decide-root (BlackNode _ _ _ ) = Inl RC-Black
forget: WellRedTree \, \rightarrow \, AlmostWellRedTree
forget Empty = AEmpty
forget \, (RedNode \, I \, kv \, r \, \_ \, \_) \, = \, ANode \, I \, Red \, kv \, r \,
forget (BlackNode I kv r) = ANode I Black kv r
  ins-red: (t: WellRedTree) (kv: Key × Value) → RootColored t Red → AlmostWellRedTree
  ins-red Empty kv ()
  ins-red (RedNode I (k', v') r rI rr) (k, v) rc with compare k k'
  ... | Less = balance-break (ins-black I(k, v) rI(k', v') r
  ... | Greater = balance-break | (k', v') (ins-black r (k, v) rr)
  ... | Equal = ANode I Red(k, v) r
  ins-red (BlackNode I kv r) kv' ()
  ins\text{-}black: (t:WellRedTree) \ (kv:Key \times Value) \rightarrow RootColored \ t \ Black \rightarrow WellRedTree
  ins-black Empty kv rt = RedNode Empty kv Empty RC-Empty
  ins-black (RedNode I kv r rI rr) kv' ()
  ins-black (BlackNode I (k', v') r) (k, v) rt with compare k k'
  ... | Less = balance-left (ins-any I(k,v)) (k',v') r
  ... | Greater = balance-right | (k,v) (ins-any r(k,v))
  ... | Equal = BlackNode I (k, v) r
  ins-any : (t : WellRedTree) (kv : Key \times Value) \rightarrow AlmostWellRedTree
  ins-any t kv with decide-root t
  ... | Inl rt = forget (ins-black t kv rt)
  ... | Inr rt = ins-red t kv rt
blacken\text{-}root: AlmostWellRedTree \rightarrow WellRedTree
blacken-root AEmpty = Empty
blacken-root (ANode I_kv r) = BlackNode I_kv r
insert : WellRedTree \rightarrow Key \times Value \rightarrow WellRedTree
insert t kv = blacken-root (ins-any t kv)
```

1.6.1 Discussion

Is this a better or worse piece of code than the extrinsic version? Evaluate in terms of finding bugs, how easy is it to write and read, separation of properties, and efficiency.

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