

# Chapter 4

## Greedy Algorithms



Slides by Kevin Wayne.  
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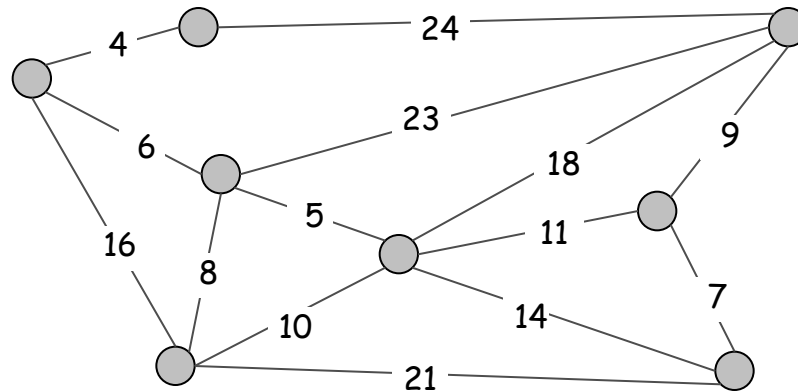
## 4.5 Minimum Spanning Tree

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# Minimum Spanning Tree

**Minimum spanning tree.** Given a connected graph  $G = (V, E)$  with real-valued edge **positive** weights  $c_e$ , find a subset  $E' \subseteq E$  such that

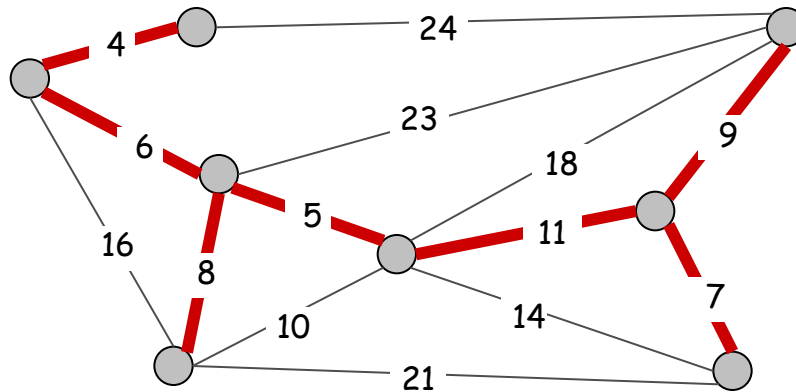
- (i) the graph  $G'=(V,E')$  is connected
- (ii) smallest possible cost



# Minimum Spanning Tree

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**Key Observation.** The optimal solution **does not contain cycles**  $\Rightarrow$  it is a tree

# Applications

MST is fundamental problem with diverse applications.

- Network design.
  - telephone, electrical, hydraulic, TV cable, computer, road
- Approximation algorithms for NP-hard problems.
  - traveling salesperson problem, Steiner tree
- Indirect applications.
  - max bottleneck paths
  - LDPC codes for error correction
  - image registration with Renyi entropy
  - learning salient features for real-time face verification
  - reducing data storage in sequencing amino acids in a protein
  - model locality of particle interactions in turbulent fluid flows
  - autoconfig protocol for Ethernet bridging to avoid cycles in a network
- Cluster analysis.

# Greedy Algorithms

**Kruskal's algorithm.** Start with  $T = \emptyset$ . Consider edges in ascending order of cost. Insert edge  $e$  in  $T$  unless doing so would create a cycle.

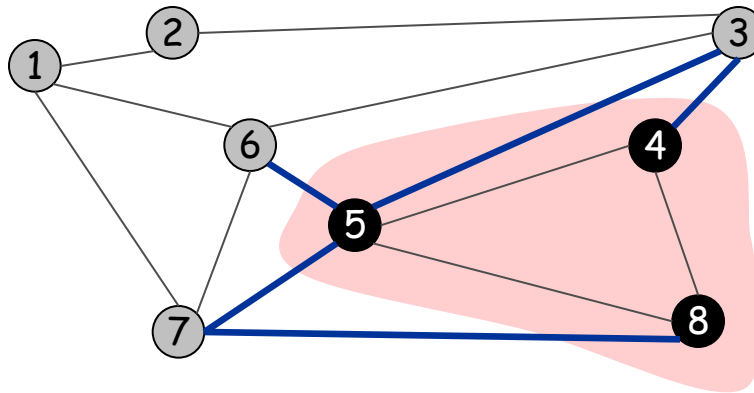
**Reverse-Delete algorithm.** Start with  $T = E$ . Consider edges in descending order of cost. Delete edge  $e$  from  $T$  unless doing so would disconnect  $T$ .

**Prim's algorithm.** Start with some root node  $s$  and greedily grow a tree  $T$  from  $s$  outward. At each step, add the cheapest edge  $e$  to  $T$  that has exactly one endpoint in  $T$ .

**Remark.** All three algorithms produce an MST.

# Cycles and Cuts

**Cut.** A cut for a graph  $G=(V,E)$  is a subset of nodes  $S$ .



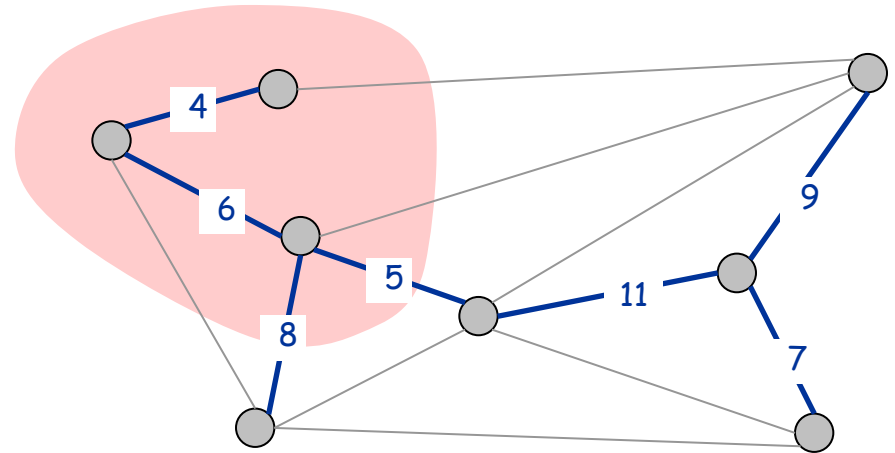
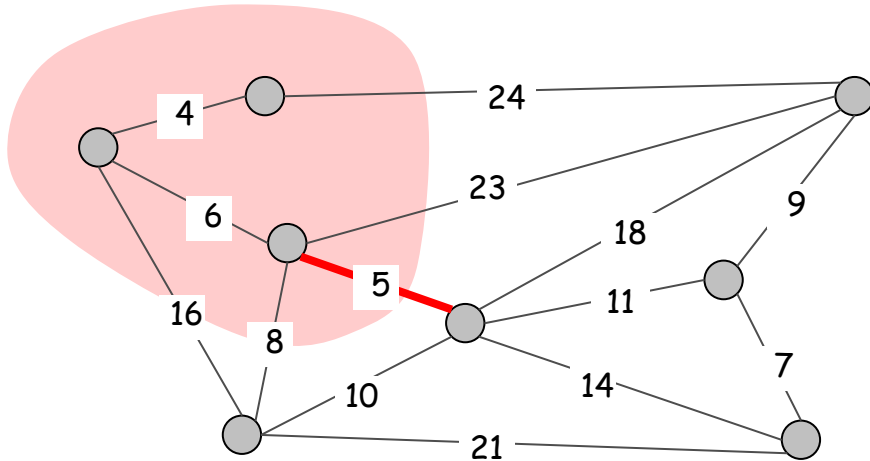
Cut  $S = \{4, 5, 8\}$   
Crossing edges = 5-6, 5-7, 3-4, 3-5, 7-8

- An edge  $e$  **crosses** a cut  $S$  if  $e$  has an endpoint in  $S$  and the other one in  $V-S$

# Greedy Algorithms

To simplify, assume all edge weights are different  $\Rightarrow$  there is **unique MST**

**Cut property (baby version).** Consider a graph  $G$ . Pick any cut  $S$ . If  $e$  is the lightest edge that crosses  $S$ , then  $e$  belongs to the MST

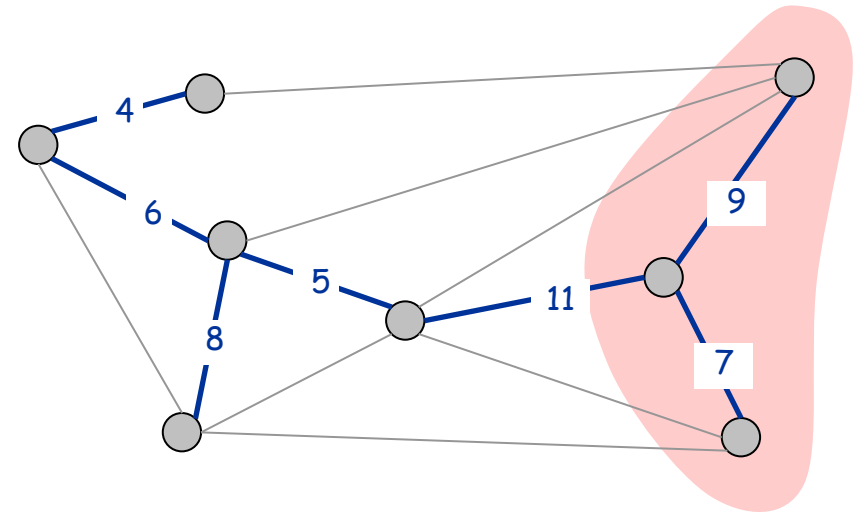
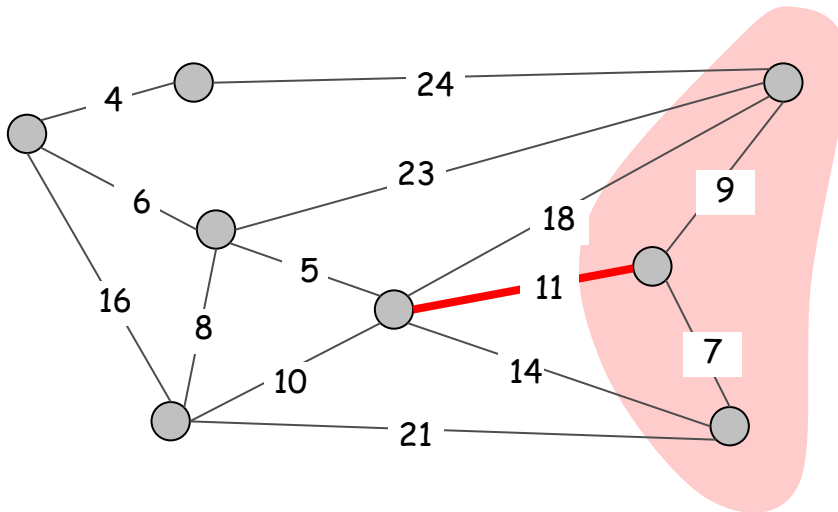




# Greedy Algorithms

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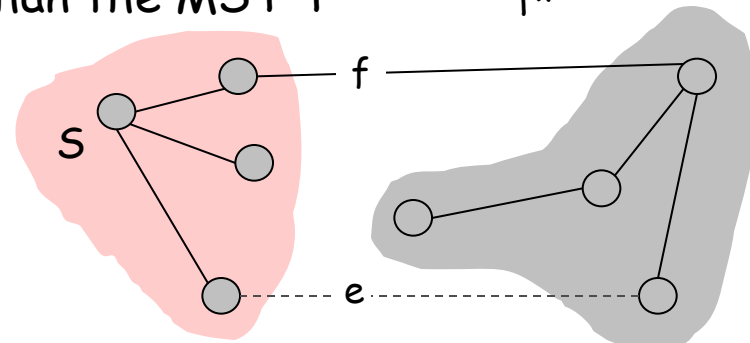
# Greedy Algorithms

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**Cut property (baby version).** Consider a graph  $G$ . Pick any cut  $S$ . If  $e$  is the lightest edge that crosses  $S$ , then  $e$  belongs to the MST

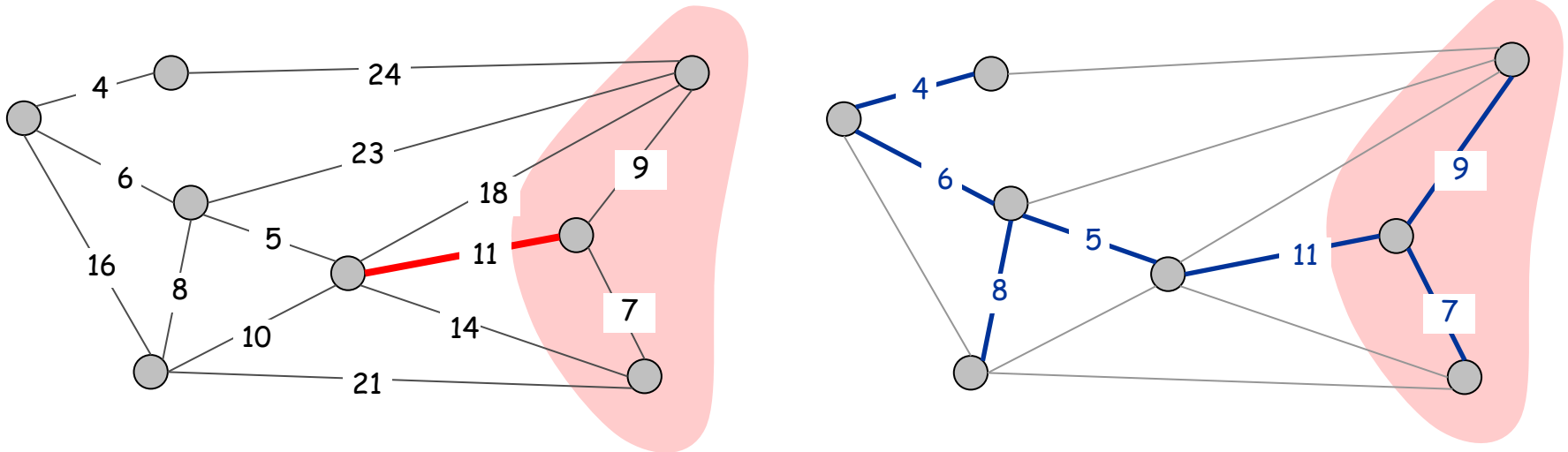
**Pf.** (exchange argument)

- Consider the MST  $T^*$
- Suppose lightest edge  $e$  does not belong to  $T^*$   $\Rightarrow$  there is another edge  $f$  connecting cut to outside of the cut
- Adding  $e$  to  $T^*$  creates a cycle containing  $f$
- $T' = T^* \cup \{e\} - \{f\}$  is also a spanning tree
- Since  $c_e < c_f$ , the new tree  $T'$  is **cheaper** than the MST  $T^*$   
 $\Rightarrow$  contradiction



# Greedy Algorithms

This property help us to start building the MST: just look at any cut, add the lightest edge to the solution

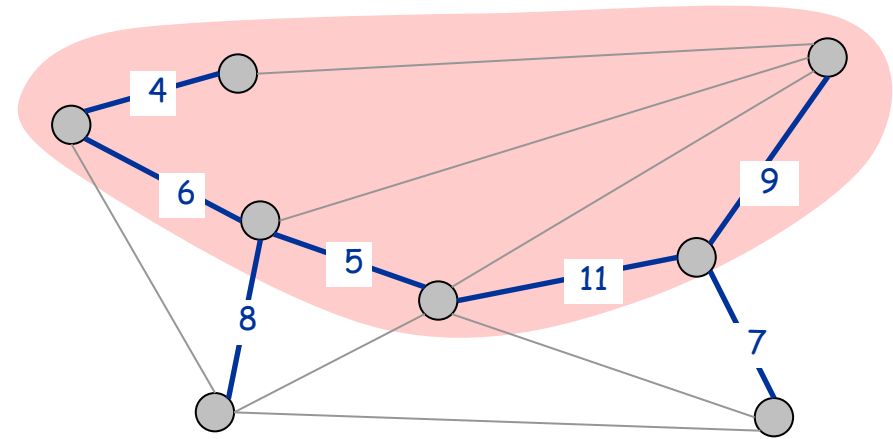
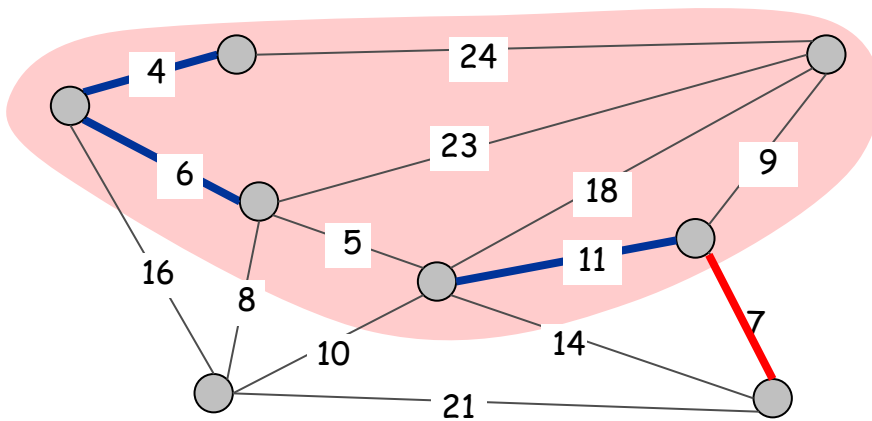


We will prove a stronger version the allows us to **continue this process** to add other edges until we get the MST

# Greedy Algorithms

**Cut property.** Suppose you have already found a set of edges **X** that belongs to the **MST**

Pick a cut **S** containing all edges in **X**. If **e** is the lightest edge that crosses **S** then **e** also belongs to the **MST**



## Greedy Algorithms

**Cut property.** Suppose you have already found a set of edges  $X$  that belongs to the MST

Pick a cut  $S$  containing all edges in  $X$ . If  $e$  is the lightest edge that crosses  $S$  then  $e$  also belongs to the MST

**Proof:** Exactly the same as the “baby version”

# Greedy Algorithms

## Cut property.

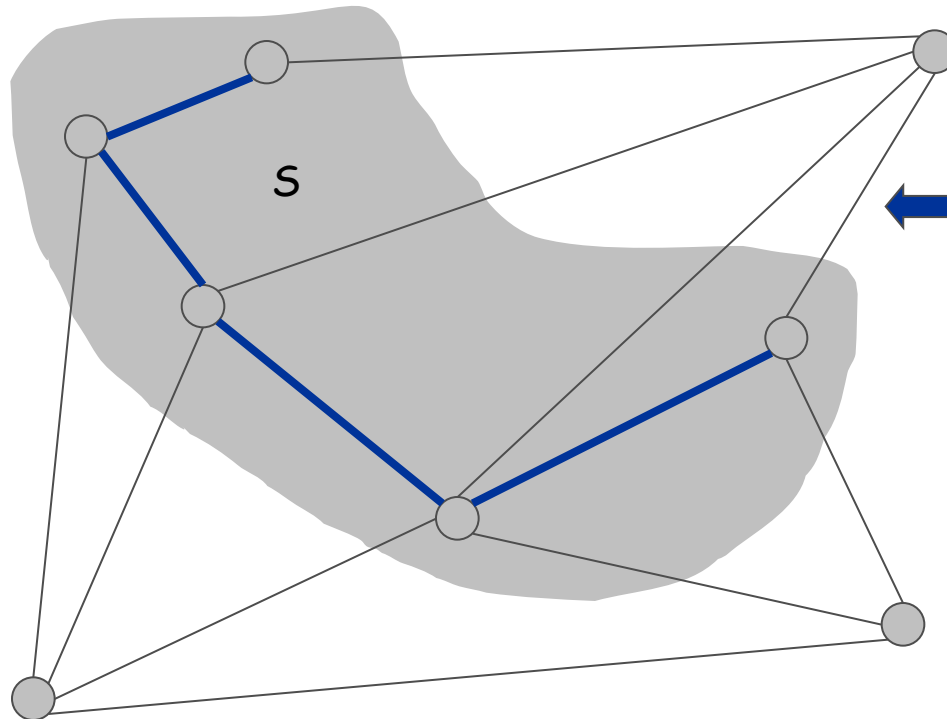
- . Different applications of Cut property lead to different algorithms for constructing Minimal Spanning Trees.
- . Prim and Kruskal algorithm construct a MST applying the Cut property  $n-1$  times.

# Prim's Algorithm

Idea: keep growing the **same cut**

Prim's algorithm. [Jarník 1930, Dijkstra 1957, Prim 1959]

- Initialize  $S$  = any node, tree  $T$  = empty
- Apply cut property to  $S$ .
- Add min cost edge that crosses  $S$  to  $T$ , and add one new explored node  $u$  to  $S$ .



# Bad Implementation: Prim's Algorithm

## Implementation (Naïve)

- Maintain set of explored nodes  $S$ .
- Find the lightest edge that crosses  $S$  in  $O(m)$  time
- Total complexity  $O(m.n)$



# Good Implementation: Prim's Algorithm

**Implementation.** Use a priority queue.

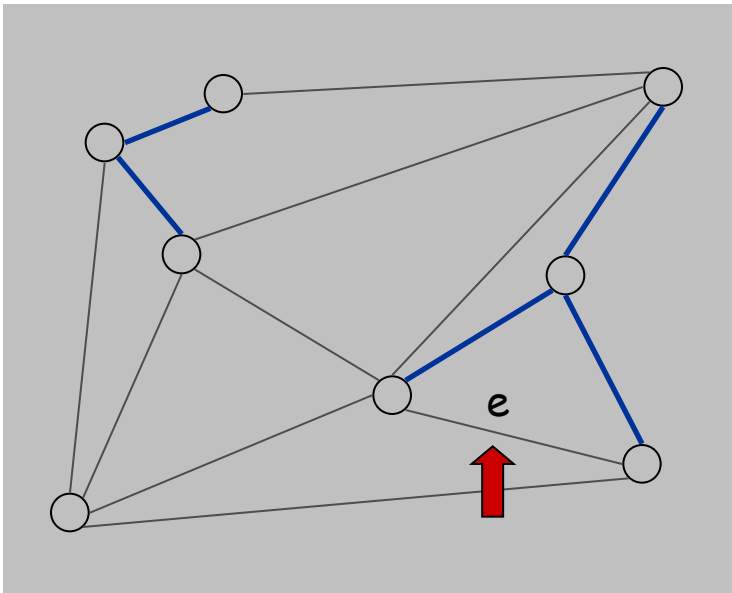
- Maintain set of explored nodes  $S$ .
- For each unexplored node  $v$ , maintain attachment cost  $a[v]$  = cost of cheapest edge  $v$  to a node in  $S$ .
- $O(n^2)$  with an array;  $O(m \log n)$  with a binary heap.

```
Prim(G, c) {  
    foreach (v ∈ V) a[v] ← ∞  
    Initialize an empty priority queue Q  
    foreach (v ∈ V) insert v onto Q  
    Initialize set of explored nodes S ← ∅  
  
    while (Q is not empty) {  
        u ← delete min element from Q  
        S ← S ∪ { u }  
        foreach (edge e = (u, v) incident to u)  
            if ((v ∉ S) and (ce < a[v]))  
                decrease priority a[v] to ce  
    }  
}
```

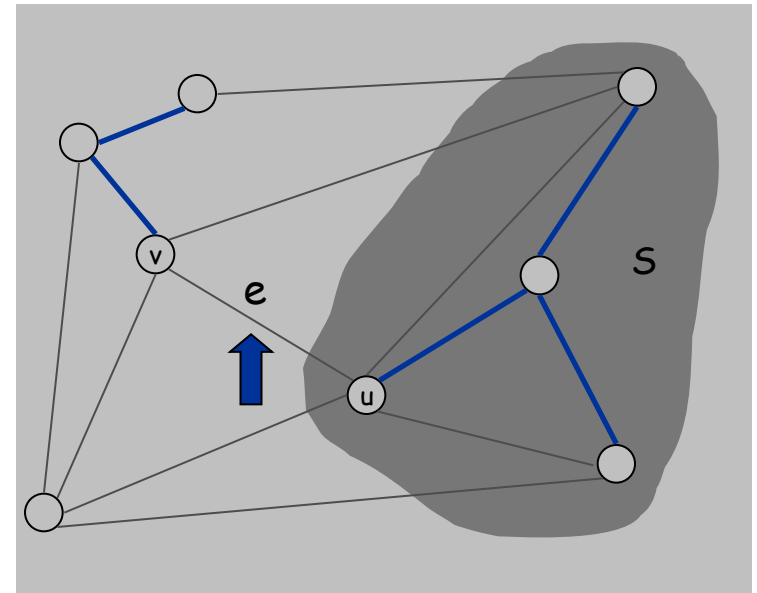
# Kruskal's Algorithm

Kruskal's algorithm. [Kruskal, 1956]

- Consider edges in ascending order of weight.
- Case 1: If adding  $e$  to  $T$  creates a cycle, discard  $e$
- Case 2: Otherwise, insert  $e = (u, v)$  into  $T$   
(set  $S$  to be the connected component containing  $u$ )



Case 1

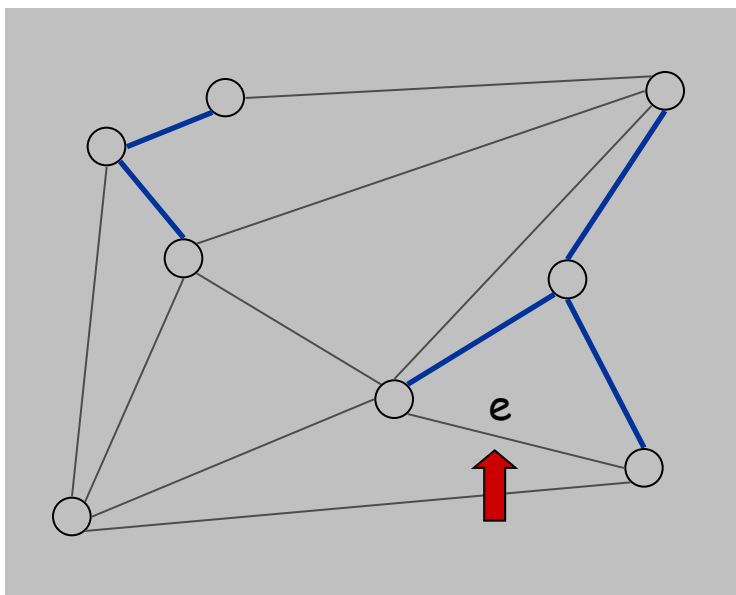


Case 2

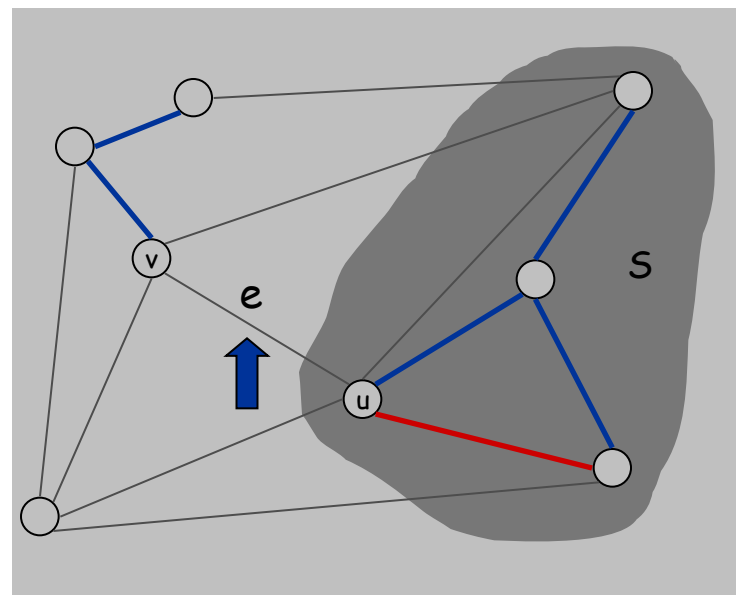
# Kruskal's Algorithm: Proof of correctness

Kruskal's algorithm. [Kruskal, 1956]

- Case 1: If adding  $e$  to  $T$  creates a cycle, discard  $e$ 
  - Optimal solution does not have a cycle
- Case 2: Otherwise, insert  $e = (u, v)$  into  $T$ 
  - Pick the cut  $S$  as the nodes that are reachable from  $u$  in  $T$



Case 1



Case 2

# Kruskal's Algorithm: Bad Implementation

Kruskal's algorithm. [Kruskal, 1956]

- Sorting the edges  $O(m \log m)$
- Testing the existence of a cycle while considering edge  $e$ :  $O(n)$  via a DFS( BFS). Note that a tree has at most  $n$  edges.
- For all edges  $O(m.n)$
- Total complexity  $O(m \log m) + O(m n) = O(n.m)$

# Implementation: Kruskal's Algorithm

**Implementation.** Use the **union-find** data structure.

- Build set  $T$  of edges in the MST.
- Maintain set for each connected component.
- $O(m \log n)$  for sorting and  $O(m \underbrace{\alpha(m, n)}_{\text{essentially a constant}})$  for union-find.

$\swarrow$   $m \leq n^2 \Rightarrow \log m$  is  $O(\log n)$   $\searrow$  essentially a constant

```
Kruskal(G, c) {  
    Sort edges weights so that  $c_1 \leq c_2 \leq \dots \leq c_m$ .  
     $T \leftarrow \phi$   
  
    foreach ( $u \in V$ ) make a set containing singleton  $u$   
  
    for  $i = 1$  to  $m$     are  $u$  and  $v$  in different connected components?  
         $(u, v) = e_i$   $\swarrow$   
        if ( $u$  and  $v$  are in different sets) {  
             $T \leftarrow T \cup \{e_i\}$   
            merge the sets containing  $u$  and  $v$   
        }  $\swarrow$  merge two components  
    return  $T$   
}
```

# MST Algorithms: Theory

## Deterministic comparison based algorithms.

- $O(m \log n)$  [Jarník, Prim, Dijkstra, Kruskal, Boruvka]
- $O(m \log \log n)$ . [Cheriton-Tarjan 1976, Yao 1975]
- $O(m \beta(m, n))$ . [Fredman-Tarjan 1987]
- $O(m \log \beta(m, n))$ . [Gabow-Galil-Spencer-Tarjan 1986]
- $O(m \alpha(m, n))$ . [Chazelle 2000]

## Holy grail. $O(m)$ .

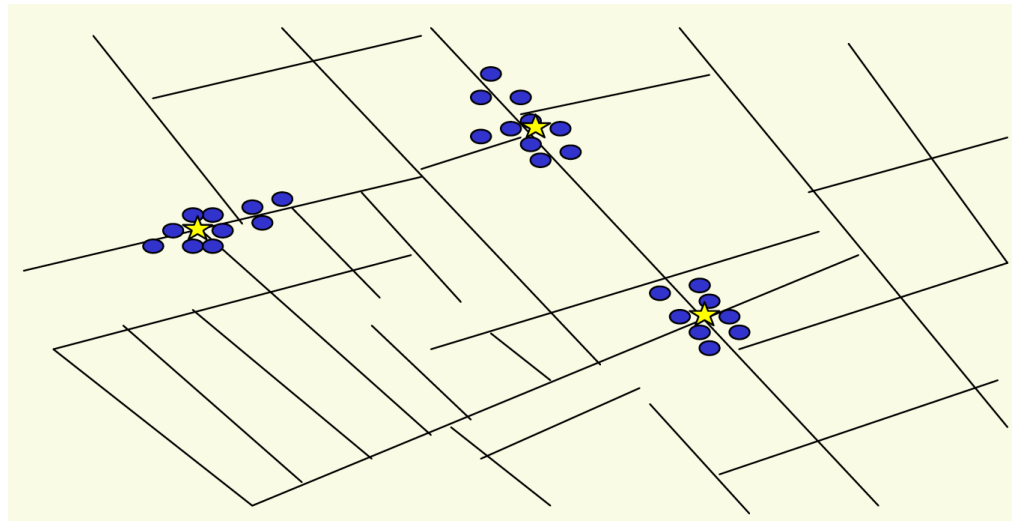
## Notable.

- $O(m)$  randomized. [Karger-Klein-Tarjan 1995]
- $O(m)$  verification. [Dixon-Rauch-Tarjan 1992]

## Euclidean.

- 2-d:  $O(n \log n)$ . compute MST of edges in Delaunay
- k-d:  $O(k n^2)$ . dense Prim

## 4.7 Clustering



Outbreak of cholera deaths in London in 1850s.  
Reference: Nina Mishra, HP Labs

# Clustering

**Clustering.** Given a set  $U$  of  $n$  objects labeled  $p_1, \dots, p_n$ , classify into coherent groups.

↑  
photos, documents, micro-organisms

**Distance function.** Numeric value specifying "closeness" of two objects.

↑  
number of corresponding pixels whose intensities differ by some threshold

**Fundamental problem.** Divide into clusters so that points in different clusters are far apart.

- Routing in mobile ad hoc networks.
- Identify patterns in gene expression.
- Document categorization for web search.
- Similarity searching in medical image databases
- Skycat: cluster  $10^9$  sky objects into stars, quasars, galaxies.



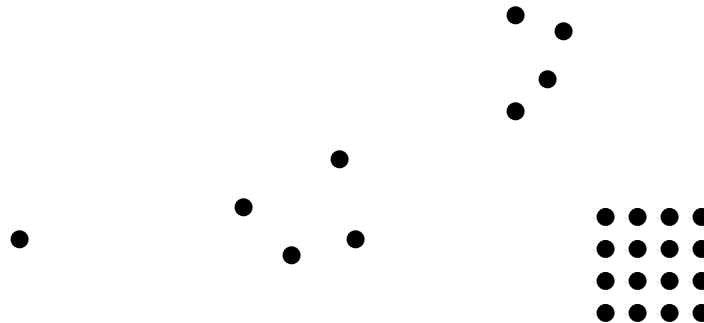
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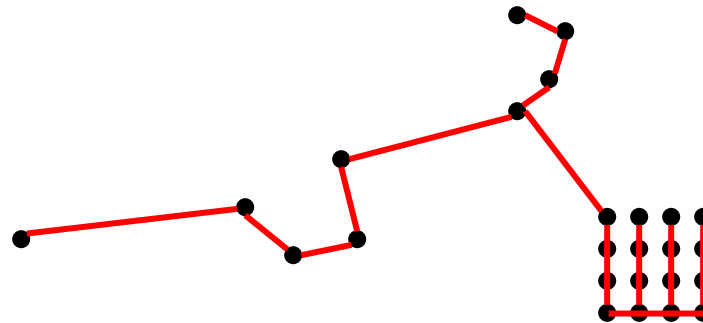


# Clustering of Maximum Spacing

**k-clustering.** Divide objects into  $k$  non-empty groups.

**Q:** Can we use an MST to perform k-clustering?

**A:** Start with MST, keep removing heaviest edge until we get  $k$  connected components



$k = 4$

# Clustering of Maximum Spacing

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**Q:** Can we use an MST to perform k-clustering?

**A:** Start with MST, keep removing heaviest edge until we get  $k$  connected components

**Guarantees:**

1. This algorithm gives cheapest way of forming  $k$  connected components (generalizes MST, which gives cheapest 1 conn. comp)
2. Maximizes **spacing**: minimum space between different classes

