

On the sign of Jacobian and orientation of parametrized surfaces

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Let $\varphi : \mathbb{R}^m \rightarrow \mathbb{R}^m$ be a local diffeomorphism at the point $a \in \mathbb{R}^m$. Then the tangent map $\varphi_* : T_a(\mathbb{R}^m) \rightarrow T_b(\mathbb{R}^m)$ is a linear isomorphism given by

$$\varphi_*(a, v) = (\varphi(a), \varphi'(a)v),$$

here we use (a, v) to denote a tangent vector based at a and in the direction $v \in \mathbb{R}^m$. Taking determinant on both sides of the following matrix identity

$$(\varphi'(a)v_1, \dots, \varphi'(a)v_m) = \varphi'(a)(v_1, \dots, v_m),$$

it follows that if $\det \varphi'(a) > 0$ and $\{e_i\}_{i=1}^m$ being $e_i = (a, v_i)$ is a positive base of $T_a(\mathbb{R}^m)$, meaning that the determinant with columns v_1, \dots, v_m is positive, then $\{\varphi_* e_i\}_{i=1}^m$ is a positive base of $T_b(\mathbb{R}^m)$. We say that diffeomorphisms with positive Jacobian preserve orientation.

Suppose that $\varphi : \bar{\Omega} \rightarrow \bar{D}$ is a C^1 -diffeomorphism between two smooth domains in \mathbb{R}^m , $a \in \partial\Omega$. It is well known that the submanifold $\partial\Omega$ is orientable and its orientation can be interpreted by a nonzero normal vector N at a . In many applications, N is given by a local parametrization $x : U \rightarrow \partial\Omega$ near a via

$$N = \left(\frac{\partial(x^2, \dots, x^m)}{\partial(u^1, \dots, u^{m-1})}, -\frac{\partial(x^1, x^3, \dots, x^m)}{\partial(u^1, \dots, u^{m-1})}, \dots, (-1)^{m+1} \frac{\partial(x^1, \dots, x^{m-1})}{\partial(u^1, \dots, u^{m-1})} \right)_{u_0},$$

being U an open subset of \mathbb{R}^{m-1} and $u_0 \in U$ such that $a = x(u_0)$. Because φ is a diffeomorphism between $\partial\Omega$ and ∂D , we automatically get a local parametrization $y = \varphi \circ x$ of ∂D near $b = \varphi(a)$, which gives rise to a normal vector

$$\tilde{N} = \left(\frac{\partial(y^2, \dots, y^m)}{\partial(u^1, \dots, u^{m-1})}, -\frac{\partial(y^1, y^3, \dots, y^m)}{\partial(u^1, \dots, u^{m-1})}, \dots, (-1)^{m+1} \frac{\partial(y^1, \dots, y^{m-1})}{\partial(u^1, \dots, u^{m-1})} \right)_{u_0}$$

of ∂D at b . The main result of this note is the following theorem.

Theorem 0.1. *Let $\varphi : \bar{\Omega} \rightarrow \bar{D}$ be a C^1 -diffeomorphism, $a \in \partial\Omega$, $J_\varphi(a) > 0$. If N is an outward normal vector of $\partial\Omega$ at a , then \tilde{N} is an outward normal vector of ∂D at b .*

Firstly we explain what an outward normal vector means. For $x \in \mathbb{R}^m$, let $\mathcal{N}(x)$ denotes the set of all open neighborhoods of x in \mathbb{R}^m . Let Ω be an open subset of \mathbb{R}^m . We say that $\partial\Omega$ is of class C^k , if for every $a \in \partial\Omega$, there are $U \in \mathcal{N}(a)$ and a C^k -function $g : U \rightarrow \mathbb{R}$

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such that $\phi(a) = 0$ and

$$\phi(U \cap \Omega) = V \cap \{y^m > 0\}, \quad \phi(U \cap \partial\Omega) = V \cap \{y^m = 0\}. \quad (0.1)$$

Obviously $\partial\Omega \cap U = \{\phi^m = 0\}$ and since ϕ is a C^1 -diffeomorphism, the Jacobi matrix

$$\phi'(a) = \begin{pmatrix} \partial_1 \phi^1 & \cdots & \partial_m \phi^1 \\ \vdots & & \vdots \\ \partial_1 \phi^m & \cdots & \partial_m \phi^m \end{pmatrix}_a = \begin{pmatrix} \nabla \phi^1(a) \\ \vdots \\ \nabla \phi^m(a) \end{pmatrix}$$

is invertible, which implies that $\nabla \phi^m(a) \neq 0$. Actually, $\nabla \phi^m(a)$ is a normal vector of $\partial\Omega$ at a .

Suppose N is a nonzero normal vector of $\partial\Omega$ at a . Since a is an interior point of U , for some $\delta > 0$ we can define a C^1 -function $\eta : (-\delta, \delta) \rightarrow \mathbb{R}$ by $\eta(t) = \phi^m(a + tN)$. Obviously,

$$\eta(0) = \phi^m(a) = 0, \quad \dot{\eta}(0) = \nabla \phi^m(a) \cdot N \neq 0$$

because N is parallel to $\nabla \phi^m(a)$. Assume $\dot{\eta}(0) < 0$, then there exists $\varepsilon > 0$ such that

$$\phi^m(a + tN) = \eta(t) > \eta(0) = 0$$

for $t \in (-\varepsilon, 0)$. From (0.1) we get $a + tN \in \Omega$. If $\dot{\eta}(0) > 0$ we will get $a - tN \in \Omega$ for $t \in (-\varepsilon, 0)$. The above discussion justifies the following definition.

Definition 0.2. Let Ω be an open subset of \mathbb{R}^m with C^1 -boundary $\partial\Omega$, $a \in \partial\Omega$ and N is a normal vector of $\partial\Omega$ at a . If there exists $\varepsilon > 0$ such that $a + tN \in \Omega$ for $t \in (-\varepsilon, 0)$, then we say that N is an *outward normal vector* of $\partial\Omega$ at a .

Proof (Proof of Theorem 0.1). By the chain rule,

$$\begin{pmatrix} \frac{\partial y^1}{\partial u^1} & \frac{\partial y^1}{\partial u^2} & \cdots & \frac{\partial y^1}{\partial u^{m-1}} \\ \frac{\partial y^2}{\partial u^1} & \frac{\partial y^2}{\partial u^2} & \cdots & \frac{\partial y^2}{\partial u^{m-1}} \\ \vdots & \vdots & & \vdots \\ \frac{\partial y^m}{\partial u^1} & \frac{\partial y^m}{\partial u^2} & \cdots & \frac{\partial y^m}{\partial u^{m-1}} \end{pmatrix} = \begin{pmatrix} \frac{\partial y^1}{\partial x^1} & \frac{\partial y^1}{\partial x^2} & \cdots & \frac{\partial y^1}{\partial x^m} \\ \frac{\partial y^2}{\partial x^1} & \frac{\partial y^2}{\partial x^2} & \cdots & \frac{\partial y^2}{\partial x^m} \\ \vdots & \vdots & & \vdots \\ \frac{\partial y^m}{\partial x^1} & \frac{\partial y^m}{\partial x^2} & \cdots & \frac{\partial y^m}{\partial x^m} \end{pmatrix} \begin{pmatrix} \frac{\partial x^1}{\partial u^1} & \frac{\partial x^1}{\partial u^2} & \cdots & \frac{\partial x^1}{\partial u^{m-1}} \\ \frac{\partial x^2}{\partial u^1} & \frac{\partial x^2}{\partial u^2} & \cdots & \frac{\partial x^2}{\partial u^{m-1}} \\ \vdots & \vdots & & \vdots \\ \frac{\partial x^m}{\partial u^1} & \frac{\partial x^m}{\partial u^2} & \cdots & \frac{\partial x^m}{\partial u^{m-1}} \end{pmatrix},$$

here and in what follows, $\partial_{u^i} y^j$, $\partial_{x^i} y^j$ and $\partial_{u^i} x^j$ are evaluated at u_0 , a and u_0 , respectively. Let A_i^j be the cofactor of $\partial_{x^i} y^j$ in $A = \phi'(a)$, A^* be the adjugate matrix of A . By the Cauchy-Binet formula,

$$\begin{aligned} \tilde{N}^j &= (-1)^{j+1} \frac{\partial(y^1, \dots, \hat{y}^j, \dots, y^m)}{\partial(u^1, \dots, u^{m-1})} \\ &= (-1)^{j+1} \sum_{i=1}^m \frac{\partial(y^1, \dots, \hat{y}^j, \dots, y^m)}{\partial(x^1, \dots, \hat{x}^i, \dots, x^m)} \frac{\partial(x^1, \dots, \hat{x}^i, \dots, x^m)}{\partial(u^1, \dots, u^{m-1})} \\ &= \sum_{i=1}^m \left\{ (-1)^{i+j} \frac{\partial(y^1, \dots, \hat{y}^j, \dots, y^m)}{\partial(x^1, \dots, \hat{x}^i, \dots, x^m)} \right\} \left\{ (-1)^{i+1} \frac{\partial(x^1, \dots, \hat{x}^i, \dots, x^m)}{\partial(u^1, \dots, u^{m-1})} \right\} \\ &= \sum_{i=1}^m A_i^j N^i. \end{aligned}$$

Therefore

$$\tilde{N} = \begin{pmatrix} A_1^1 & \cdots & A_m^1 \\ \vdots & & \vdots \\ A_1^m & \cdots & A_m^m \end{pmatrix} N = (A^*)^T N. \quad (0.2)$$

Since $a \in \partial\Omega$ and N is an outward normal vector of $\partial\Omega$ at a , there is $\varepsilon > 0$, such that for $t \in (-\varepsilon, 0)$ we have $a + tN \in \Omega$ and consequently $\varphi(a + tN) \in D$. Thus,

$$\gamma : t \mapsto \varphi(a + tN), \quad t \in (-\varepsilon, 0]$$

is a smooth curve from the interior of D to $b \in \partial D$, whose velocity vector at $b = \varphi(a)$ is

$$v = \left. \frac{d}{dt} \right|_{t=0} \varphi(a + tN) = \varphi'(a)N = AN$$

Because $A^*A = J_\varphi(a)I_m$, where I_m is the $m \times m$ identity matrix, we deduce from (0.2) that

$$\begin{aligned} v \cdot \tilde{N} &= (AN)^T (A^*)^T N \\ &= N^T A^T (A^*)^T N \\ &= N^T (A^*A)^T N = J_\varphi(a) |N|^2 > 0. \end{aligned}$$

On the other hand, since ∂D is of class C^1 , we can choose $U \in \mathcal{N}(b)$ and a C^1 -function $g : U \rightarrow \mathbb{R}$ such that $g(b) = 0$,

$$U \cap D = \{g > 0\}, \quad U \cap \partial D = \{g = 0\}.$$

Because $\nabla g(b)$ is a normal vector of ∂D at b , there exists a constant $k \neq 0$ such that $\nabla g(b) = k\tilde{N}$.

We claim that $k < 0$. In fact, take $r > 0$ such that $\gamma(t) \in U$ for $t \in (-r, 0)$, then consider the function $f : (-r, 0] \rightarrow \mathbb{R}$ defined by $f(t) = g(\gamma(t))$. We have $f(0) = g(b) = 0$,

$$\begin{aligned} k\tilde{N} \cdot v &= \nabla g(b) \cdot \dot{\gamma}(0) \\ &= \dot{f}(0) = \lim_{t \rightarrow 0^-} \frac{g(\gamma(t))}{t} \leq 0, \end{aligned}$$

because $\gamma(t) \in D$ for $t \in (-r, 0)$. Since $v \cdot \tilde{N} > 0$ and $k \neq 0$, we deduce that $k < 0$.

To conclude the proof, we need to find a $\delta > 0$ such that $b + t\tilde{N} \in D$ for $t \in (-\delta, 0)$. For this purpose, consider the C^1 -function $\eta : (-s, 0] \rightarrow \mathbb{R}$ defined by $\eta(t) = g(b + t\tilde{N})$ for some $s > 0$ small enough. Then $\eta(0) = g(b) = 0$,

$$\dot{\eta}(0) = \nabla g(b) \cdot \tilde{N} = k\tilde{N} \cdot \tilde{N} = k|\tilde{N}|^2 < 0.$$

Hence, there exists $\delta > 0$ such that for $t \in (-\delta, 0)$ we have

$$g(b + t\tilde{N}) = \eta(t) > 0,$$

that is $b + t\tilde{N} \in D$. Consequently, \tilde{N} is an outward normal vector of ∂D at b .