Print all the cycles in an undirected graph

Detect cycle in an undirected graph using BFS

Samsung Semiconductor Institute of Research(SSIR Software) intern/FTE | Set-3

Check if a given graph is Bipartite using DFS

Largest connected component on a grid

Nutanix Interview Experience (On-Campus)

ıskal's Algorithm (Simple Implementation for Adiacency Matrix)

Detect Cycle in a Directed Graph using BFS

Find the number of distinct islands in a 2D

Sum of the minimum elements in all connected components of an undirected

Tree, Back, Edge and Cross Edges in DFS of

Level Ancestor Problem

Maximum number of edges among all connected components of an undirected graph

Minimum cost path from source node to destination node via an intermediate node

Johnson's algorithm for All-pairs shortest paths | Implementation

Dijkstra's shortest path with minimum edges

Applications of Graph Data Structure

Coloring a Cycle Graph

Number of Isosceles triangles in a binary tree

Edge Coloring of a Graph

Prim's Algorithm (Simple Implementation for Adjacency Matrix Representation)

Minimum time to return array to its original state after given modifications

Find the probability of a state at a given time in a Markov chain | Set 1

Number of Walks from source to destination

Find whether it is possible to finish all tasks or not from given dependencies

Find the ordering of tasks from given

Subtree of all nodes in a tree using DFS

Graph Types and Applications

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Find maximum path length in a binary matrix

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Prim's MST for Adjacency List Representation | Greedy Algo-6

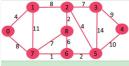
We recommend to read following two posts as a prerequisite of this post.

- 1. Greedy Algorithms | Set 5 (Prim's Minimum Spanning Tree (MST))

We have discussed Prim's algorithm and its implementation for adjacency matrix representation of graphs. The time complexity for the matrix representation is O(V^2). In this post, O(ELogV) algorithm for adjacency list representation is discussed As discussed in the previous post, in Prim's algorithm, two sets are maintained, one set contains list of vertices already included in MST, other set contains vertices not yet included. With adjacency list representation, all vertices of a graph can be traversed in O(V+E) time using BFS. The idea is to traverse all vertices of graph using BFS and use a Min Heap to store the vertices not yet included in MST. Min Heap is used as a priority queue to get the minimum weight edge from the cut. Min Heap is used as time complexity of operations like extracting minimum element and decreasing key value is O(LogV) in Min Heap.

- 1) Create a Min Heap of size V where V is the number of vertices in the given graph. Every node of min heap contains vertex number and key value of the vertex
- 2) Initialize Min Heap with first vertex as root (the key value assigned to first vertex is 0). The key value assigned to all other vertices is INF (infinite).
- 3) While Min Heap is not empty, do following
- ...a) Extract the min value node from Min Heap. Let the extracted vertex be u.
-b) For every adjacent vertex v of u. check if v is in Min Heap (not vet included in MST). If v is in Min Heap and its key value is more than weight of u-v, then update the key value of v as weight of u-v.

Let us understand the above algorithm with the following example:



Initially, key value of first vertex is 0 and INF (infinite) for all other vertices. So vertex 0 is extracted from Min Heap and key values of vertices adjacent to 0 (1 and 7) are updated. Min Heap contains all vertices except vertex 0.

The vertices in green color are the vertices included in MST.



Since key value of vertex 1 is minimum among all nodes in Min Heap, it is extracted from Min Heap and key values of vertices adjacent to 1 are updated (Key is updated if the a vertex is not in Min Heap and previous key value is greater than the weight of edge from 1 to the adjacent). Min Heap contains all vertices except vertex 0 and 1.



Since key value of vertex 7 is minimum among all nodes in Min Heap, it is extracted from Min Heap and key values of vertices adjacent to 7 are updated (Key is updated if the a vertex is not in Min Heap and previous key value is greater than the weight of edge from 7 to the adjacent). Min Heap contains all vertices except vertex 0, 1 and 7.



Since key value of vertex 6 is minimum among all nodes in Min Heap, it is extracted from Min Heap and key values of vertices adjacent to 6 are updated (Key is updated if the a vertex is not in Min Heap and previous key value is greater than the weight of edge from 6 to the adjacent). Min Heap contains all vertices except vertex 0, 1, 7 and 6.



above steps are repeated for rest of the nodes in Min Heap till Min Heap becomes empty



Python







// Java program for Prim's MST for // adjacency list representation of graph import java.util.LinkedList;
import java.util.PriorityQueue; import java.util.Comparator;

public class prims {

// Stores destination vertex in adjacency list
int dest;



De Bruijn sequence | Set 1

Degree of a Cycle Graph

Maximum and minimum isolated vertices in a graph

Total number of Spanning trees in a Cycle Graph

Minimum difference between the highest and the smallest value of mines distributed

Most visited in Greedy

Maximum sum by picking elements from two arrays in order

Coin game of two corners (Greedy Approach)

Maximum sum of all elements of array after performing given operations

Check if an array is Wave Array

Water drop problem





```
// Stores weight of a vertex in adjacency list
int weight;
         // Constructor
node1(int a, int b)
                dest = a;
weight = b;
 static class Graph {
         // Number of vertices in the graph
         // List of adjacent nodes of a given vertex
LinkedList<node1>[] adj;
         // Constructor
Graph(int e)
             V = e;
adj = new LinkedList[V];
for (int o = 0; o < V; o++)
    adj[o] = new LinkedList<>();
       }
// class to represent a node in PriorityQueue
// Stores a vertex and its corresponding
// key value
class node {
   int vertex;
   int key;
}
// Comparator class created for PriorityQueue
// returns 1 if node0.key > node1.key
// returns 0 if node0.key < node1.key and
// returns -1 otherwise
class comparator implements Comparator<node> {
          public int compare(node node0, node node1)
               return node0.key - node1.key;
        }
// method to add an edge
// between two vertices
void addEdge(Graph graph, int src, int dest, int weight)
{
        node1 node0 = new node1(dest, weight);
node1 node = new node1(src, weight);
graph.adj[src].addLast(node0);
graph.adj[dest].addLast(node);
// method used to find the mst
 ,, mechod used to find the r
void prims_mst(Graph graph)
{
         // Whether a vertex is in PriorityQueue or not
Boolean[] mstset = new Boolean[graph.V];
node[] e = new node[graph.V];
         // Stores the parents of a verte
int[] parent = new int[graph.V];
        for (int o = 0; o < graph.V; o++)
    e[o] = new node();</pre>
         for (int o = 0; o < graph.V; o++) {</pre>
                 // Initialize to false
mstset[o] = false;
                 // Initialize key values to infinity
e[o].key = Integer.MAX_VALUE;
e[o].vertex = o;
parent[o] = -1;
         // Include the source vertex in mstset
mstset[0] = true;
        // Set key value to 0
// so that it is extracted first
// out of PriorityQueue
e[0].key = 0;
         // PriorityOueue
         PriorityQueue<node> queue = new PriorityQueue<>(graph.V, new comparator());
         for (int o = 0; o < graph.V; o++)</pre>
                 queue.add(e[o]);
         // Loops until the PriorityQueue is not empty
while (!queue.isEmpty()) {
                // Extracts a node with min key value
node node0 = queue.poll();
                // Include that node into mstset
mstset[node0.vertex] = true;
                 // For all adjacent vertex of the extracted vertex V
for (node1 iterator : graph.adj[node0.vertex]) {
                        // If V is in PriorityQueue
if (mstset[iterator.dest] == false) {
    // If the key value of the adjacent vertex is
    // more than the extracted key
    // update the key value of adjacent vertex
    // to update first remove and add the updated vertex
if (e[iterator.dest].key > iterator.weight) {
    queue.remove(e[iterator.dest]);
    e[iterator.dest].key = iterator.weight;
    queue.add(e[iterator.dest]);
    parent[iterator.dest] = node0.vertex;
}
      } }
         // Prints the vertex pair of mst
         for (int o = 1; o < graph.V; o++)
    System.out.println(parent[o] +</pre>
                                                      + "-" + 0);
}
 public static void main(String[] args)
{
        Graph graph = new Graph(V);
        prims e = new prims();
        e.addEdge(graph, 0, 1, 4);
e.addEdge(graph, 0, 7, 8);
```

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```
e.addEdge(graph, 1, 2, 8);
e.addEdge(graph, 1, 7, 11);
e.addEdge(graph, 2, 3, 7);
e.addEdge(graph, 2, 8, 2);
                         e.addtdge(graph, 2, 8, 2);
e.addtdge(graph, 3, 4, 9);
e.addtdge(graph, 3, 4, 9);
e.addtdge(graph, 3, 5, 14);
e.addtdge(graph, 4, 5, 10);
e.addtdge(graph, 5, 6, 2);
e.addtdge(graph, 6, 7, 1);
e.addtdge(graph, 6, 8, 6);
e.addtdge(graph, 7, 8, 7);
                           // Method invoked
                           e.prims_mst(graph);
}
// This code is contributed by Vikash Kumar Dubey
```

Output:

- 0 1
- 5 2 2 - 3
- 3 4
- 6 5
- 0 7 2 - 8

Time Complexity: The time complexity of the above code/algorithm looks O(V^2) as there are two nested while loops. If we take a closer look, we can observe that the statements in inner loop are executed O(V+E) times (similar to BFS). The inner loop has decreaseKey() operation which takes O(LogV) time. So overall time complexity is O(E+V)*O(LogV) which is O((E+V)*LogV) = O(ELogV) (For a connected graph, V = O(E))



References:

Introduction to Algorithms by Clifford Stein, Thomas H. Cormen, Charles E. Leiserson, Ronald L.

http://en.wikipedia.org/wiki/Prim's_algorithm

This article is compiled by Aashish Barnwal and reviewed by GeeksforGeeks team. Please write comments if you find anything incorrect, or you want to share more information about the topic discussed above.

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