功能：通过语音控制拍照，调整被拍照者的位置。

运行步骤：

- $ roslaunch rchomeedu\_speech lm.launch dict:=/home/caiy2/catkin\_ws/src/rc-home-edu-learn-ros/rchomeedu\_speech/database/database.dic lm:=/home/caiy2/catkin\_ws/src/rc-home-edu-learn-ros/rchomeedu\_speech/database/database.lm

- $ roslaunch usb\_cam usb\_cam-test.launch

- $ roslaunch opencv\_apps face\_detection.launch image:=/usb\_cam/image\_raw

- $ roslaunch rchomeedu\_vision take\_photo.launch

各节点及其相互关系图：

