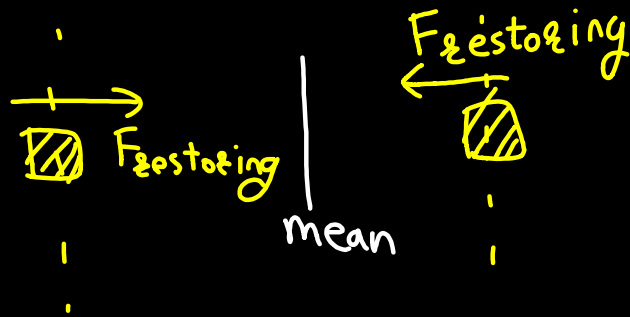
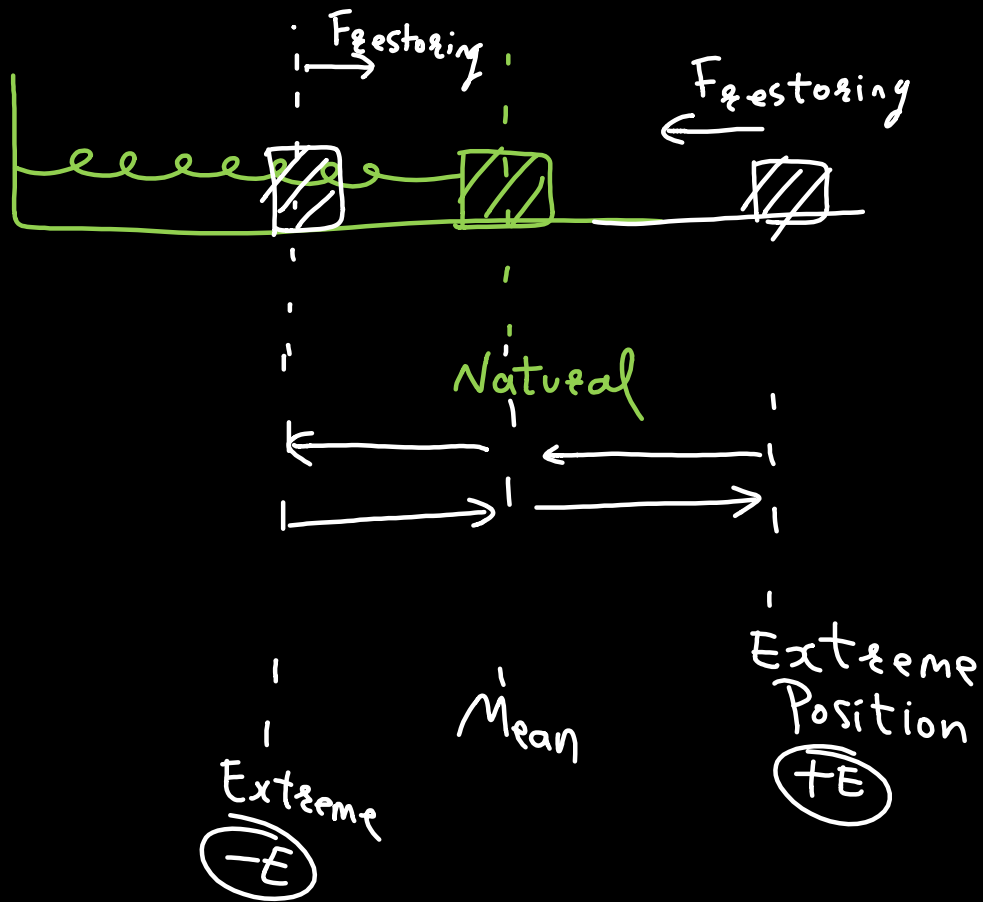


SHM

Oscillation \rightarrow to & fro motion about mean position

mean/equilibrium net $F = 0$





Cause

Restoring

↓
direction always towards
mean

Suppose

$\rightarrow F$
 $x - ve$
 $F \text{ in } +ve \hat{i}$

$x=0$

mean

$\leftarrow F$
 $x + ve$
 $F \text{ in } -ve \hat{i}$

SHM

$F = -kx$ ✓ restoring

$F = -kx^2$ ✗

$F = -kx^3$ ✓

$F = -kx^4$ ✗

$F = -kx^5$ ✓

SHM

$F_{\text{net}} \propto (-ve) \text{ displacement from mean}$ *

$$F = -Kx$$

$$ma = -Kx$$

$$a = -\frac{K}{m}x$$

$$\frac{d^2x}{dt^2} = -\frac{K}{m}x$$

$$\frac{d^2x}{dt^2} \propto (-ve)x$$

double diff $\propto - (x)$
of x

a
displ
↓ diff
vel
↓ diff
acc

$$a = \frac{d^2x}{dt^2}$$

$$\sin \theta$$

↓ diff

$$\cos \theta$$

↓ diff

$$-\sin \theta$$

$$\cos \theta$$

↓ diff

$$-\sin \theta$$

↓ diff

$$-\cos \theta$$

General Eq. of SHM

$$\# \boxed{F = -Kx}$$

$$\boxed{\frac{d^2x}{dt^2} \propto (-ve) x}$$

Ex

$$x = 5 \sin(6t)$$

$$x = 5 \sin(\underline{6t})$$

↓ diff

$$vel = 5 \cos(6t) \times 6$$

$$vel = 5(6) \cos(\underline{6t})$$

↓ diff.

$$acc = 5(6) - \sin(\underline{6t}) \times 6$$

$$acc = -5(6)^2 \sin(6t)$$

$$\sin(\omega t)$$

$\omega \rightarrow$ angular freq

$$x = A \sin(\underline{\omega t})$$

↓ diff

$$v = A\omega \cos(\omega t)$$

↓ diff

$$acc = -A\omega^2 \sin(\omega t)$$

Standard Eq.

$$F = -kx$$

$$a = -\frac{k}{m}x$$

$$a = -\omega^2 x$$

$$\omega^2 = \frac{k}{m}$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$x = A \sin(\omega t + \phi)$$

$$vel = A\omega \cos(\omega t + \phi)$$

$$acc = -A\omega^2 \sin(\omega t + \phi)$$

$$acc = -\omega^2 x$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$

$A \rightarrow$ amplitude

$\omega \rightarrow$ ang. freq.

$\phi \rightarrow$ initial phase

$$freq = \frac{1}{T}$$

freq = no. of cycles/oscillations
in one sec.

Q

$$F = -kx$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$a = -\omega^2 x$$

$$T = \frac{2\pi}{\omega}$$

Q

$$F = -5x$$

$$m = 2 \text{ kg} \quad T = ?$$

$$F = -5x$$

$$m = 2$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$T = 2\pi \sqrt{\frac{2}{5}}$$

Q

$$g \frac{d^2 x}{dt^2} + 4x = 0$$

$$m = 2 \text{ kg}$$

$$T = ?$$

$$g a + 4x = 0$$

$$a = -\frac{4}{g} x$$

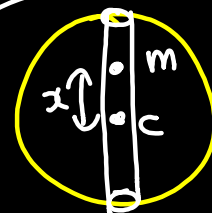
$$F = ma = -\frac{8}{g} x$$

$$k = 8/g \quad m = 2$$

$$T = 2\pi \sqrt{\frac{2}{8/g}} = 2\pi \sqrt{\frac{g}{4}}$$

$$=$$

Q



earth M_e
 R_e

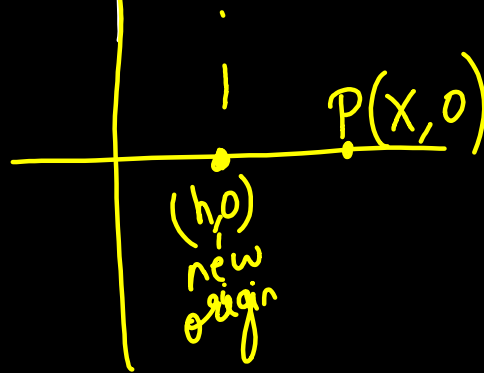
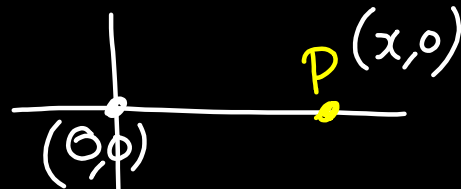
inside
solid
sphere

$$\text{Force on } (m) = -\frac{G M m x}{R^3}$$

$$T = 2\pi \sqrt{\frac{m}{G M m / R^3}}$$

$$T = 2\pi \sqrt{\frac{R^3}{G M}}$$

change of origin (maths)
shift of origin



$$X = x - h$$

$$a = -\omega^2 x$$

$$a = -\frac{4}{g} x$$

$$\omega^2 = \frac{4}{g}$$

$$\omega = \sqrt{\frac{4}{g}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{g}{4}}$$

Q

$$F = 5 - 8x$$

$$m = 2 \text{ kg}$$

Find mean position &
Time period.

$$F = 0$$

$$5 - 8x = 0$$

$$5 = 8x$$

$$\frac{5}{8} = x$$

$$F = -kx$$

$$F = -8 \left[\frac{5}{-8} + x \right]$$

$$F = -8 \left[\frac{x - \frac{5}{8}}{x - h} \right]$$

$$F = -8X$$

$$T = 2\pi \sqrt{\frac{m}{k}} = 2\pi \sqrt{\frac{2}{8}} = 2\pi \sqrt{\frac{1}{4}} = \frac{2\pi}{2} = \pi$$

$$x = A \sin(\omega t + \phi)$$

$$x = 5 \sin\left(\pi t + \frac{\pi}{3}\right)$$

Phase $(\omega t + \phi)$

Initial
Phase
 $t=0$ = ϕ

max x
max displ from
mean $\Rightarrow 5 = \text{Amplitude}$

$$\omega = \pi$$

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{\pi} = 2 \text{ sec}$$

initial phase = $\phi = \frac{\pi}{3}$

initial phase \rightarrow starting position

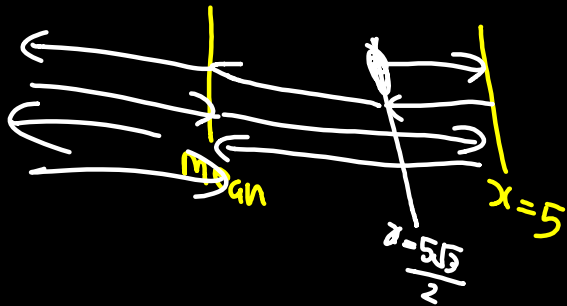
$$x = 5 \sin\left(\pi t + \frac{\pi}{3}\right)$$

$$t = 0$$

$$x = 5 \sin\left(\frac{\pi}{3}\right)$$

$$= 5 \sin(60^\circ)$$

$$x = 5 \left(\frac{\sqrt{3}}{2}\right)$$



$$x = 5 \sin(\omega t)$$

$$t = 0$$

$$x = 0$$

mean

$$x = 5 \sin(\omega t + 90^\circ)$$

$$x = 5 \cos(\omega t)$$

$$t = 0$$

$$x = 5$$

extreme.

$$x = A \sin(\omega t)$$

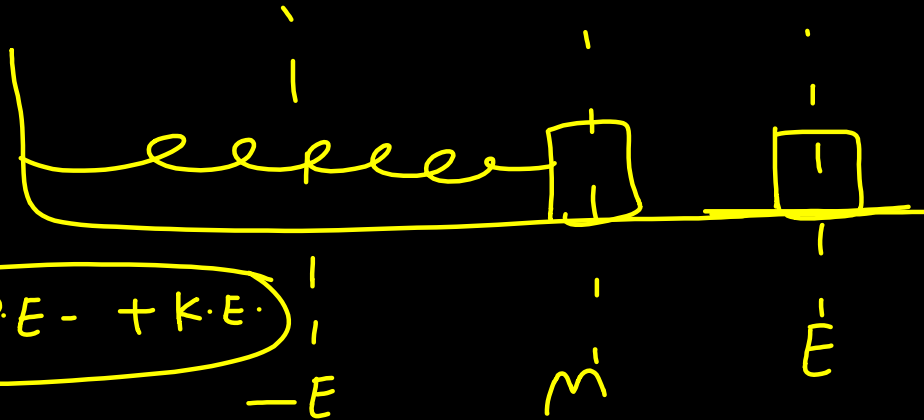
Simplicity $\phi = 0$ start from mean

$$v = A\omega \cos(\omega t)$$

$$a = -A\omega^2 \sin(\omega t)$$

$$\text{max Speed} = A\omega$$

$$\text{max acc} = A\omega^2$$



$$TE = PE + KE$$

$$PE = \frac{1}{2}kx^2$$

$$TE = \frac{1}{2}kx^2 + \frac{1}{2}mv^2$$

SHM

TE constant

$$TE = \text{constant}$$

$$KE \rightarrow \begin{cases} \text{max mean} \\ 0 \text{ extreme} \end{cases}$$

$$PE \rightarrow \begin{cases} \text{mini mean} \\ \text{max extreme} \end{cases}$$

$$\text{extreme speed} = 0$$

$$\text{mean speed max} = A\omega$$

$$\text{acc mean} = 0$$

$$\text{acc extreme max} = A\omega^2$$

$$x = A \sin(\omega t)$$

$$v = A\omega \cos(\omega t)$$

$$acc = -A\omega^2 \sin(\omega t)$$

$$KE = \frac{1}{2}mv^2 =$$

$$KE = \frac{1}{2}m\omega^2 A^2 \cos^2(\omega t)$$

$$PE = \frac{1}{2}Kx^2 + PE_{\text{mean}}$$

$$= \frac{1}{2}Kx^2 + PE_0$$

$$PE = \frac{1}{2}Kx^2 + U_0$$

$$PE = \frac{1}{2}KA^2 \sin^2(\omega t) + U_0$$

$$PE = \frac{1}{2}m\omega^2 A^2 \sin^2(\omega t) + U_0$$

$$a = -\frac{K}{m}x$$

$$a = -\omega^2 x$$

$$\omega^2 = \frac{K}{m}$$

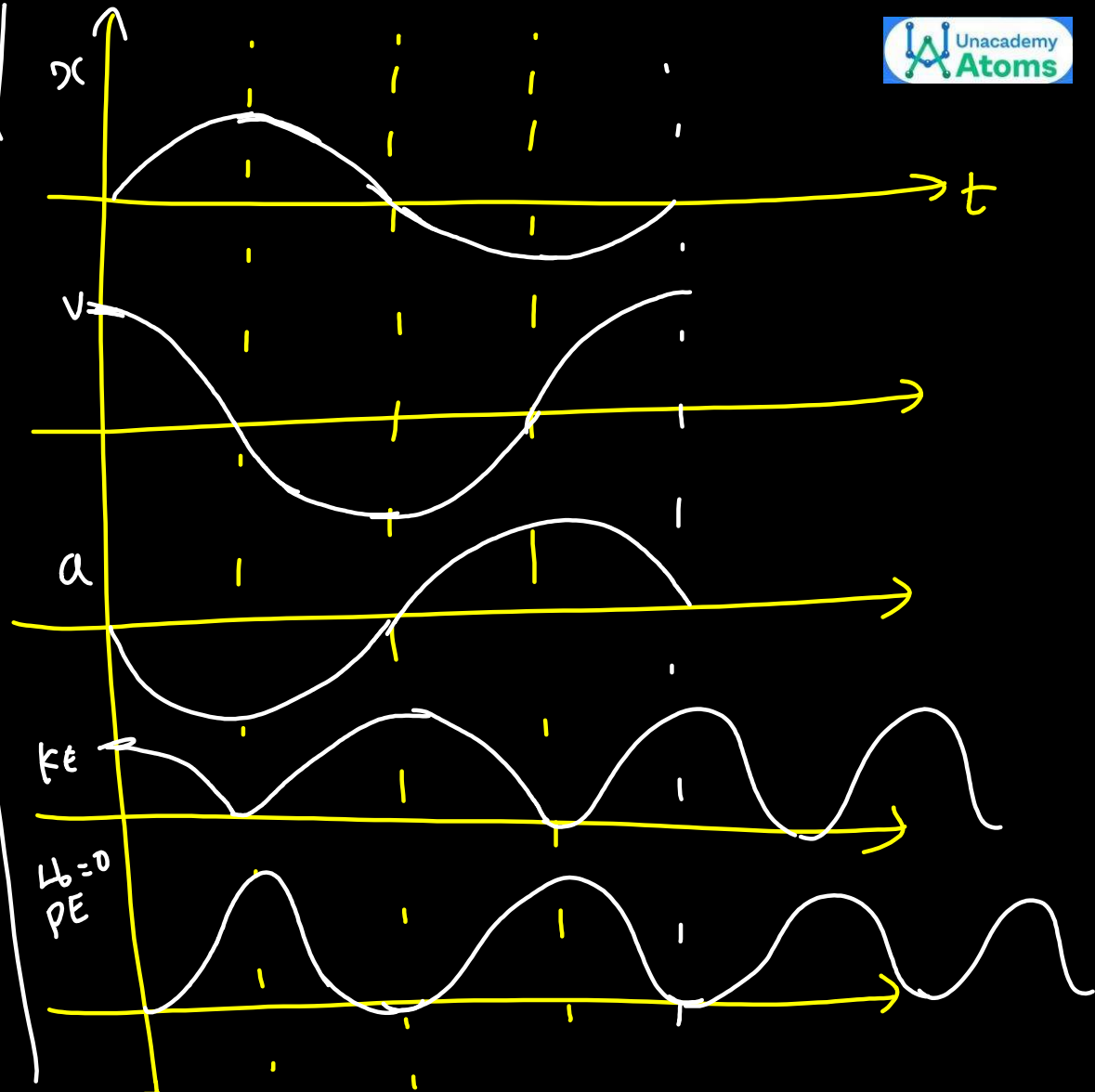
$$\boxed{m\omega^2 = K}$$

$$KE = \frac{1}{2} m \omega^2 A^2 (\cos^2 \omega t)$$

$$PE = \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t) + U_0$$

$$TE = KE + PE$$

$$TE = \frac{1}{2} m \omega^2 A^2 + U_0$$



Q $m = 2 \text{ kg}$

$TE = 9 \text{ Joule}$

$PE \text{ at mean} = 5 \text{ Joule}$

$A = 0.01 \text{ m}$

Find $T = ?$

a) $\frac{\pi}{10}$

c) $\pi/50$

b) $\frac{\pi}{20}$

~~d) $\pi/100$~~

$$TE = \frac{1}{2} m A^2 \omega^2 + U_0$$

$$9 = \frac{1}{2} (2) (0.01)^2 \omega^2 + 5$$

$$4 = (0.01)^2 \omega^2$$

$$4 = \frac{1}{10000} \omega^2$$

$$40000 = \omega^2$$

$$200 = \omega$$

$$T = \frac{2\pi}{\omega}$$

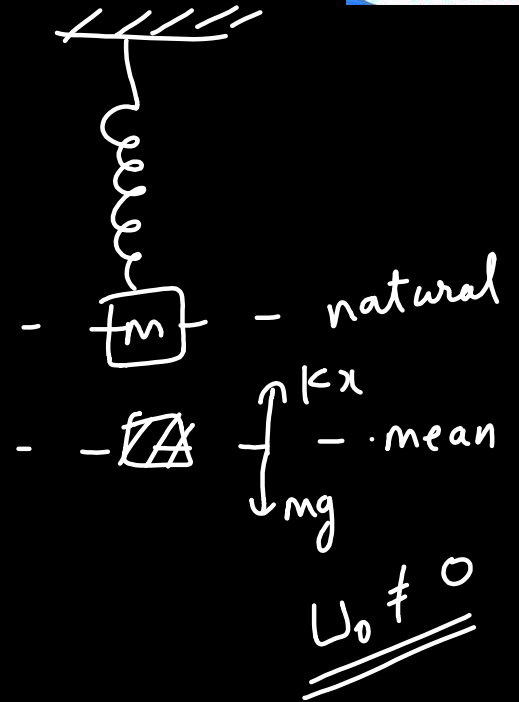
$$= \frac{2\pi}{200}$$

$$T = \frac{\pi}{100}$$

Basic Ex



Natural
mean
PE = 0
mean
 $U_0 = 0$



$$TE = KE + PE$$

$$TE = KE_{max} + PE_{min}$$

$$TE = KE_{min} + PE_{max}$$

$$KE_{min} = 0$$

Q // Suppose

$$U = U_0 \sin^2(\omega t)$$

(PE)

Find TE

~~a) U_0~~ b) $\frac{U_0}{2}$

c) $\frac{U_0}{3}$ d) $\frac{U_0}{4}$

$$PE_{max} = U_0$$

$$KE_{min} = 0$$

$$TE = PE_{max} + KE_{min}$$

$$TE = U_0$$

Relationship with x

$$a = -\omega^2 x$$

$$F = -kx$$

$$x = A \sin(\omega t)$$

$$v = A\omega \cos(\omega t)$$

$$\sin^2 + \cos^2 = 1$$

$$\frac{x^2}{A^2} + \frac{v^2}{A^2 \omega^2} = 1 \quad \text{ellipse}$$

$$v = \omega \sqrt{A^2 - x^2}$$

$$KE = \frac{1}{2}mv^2$$

$$KE = \frac{1}{2}m\omega^2(A^2 - x^2)$$

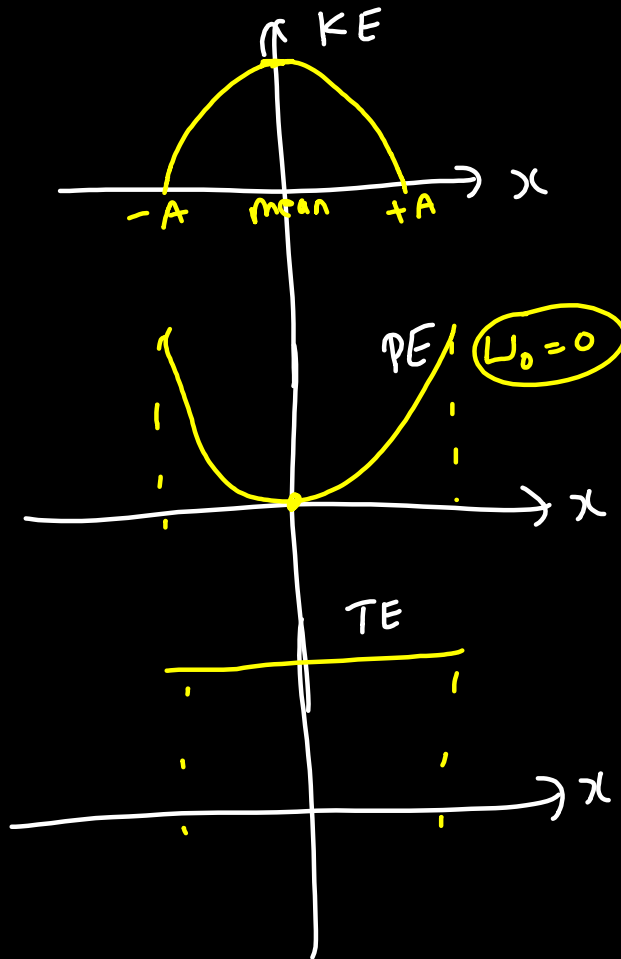
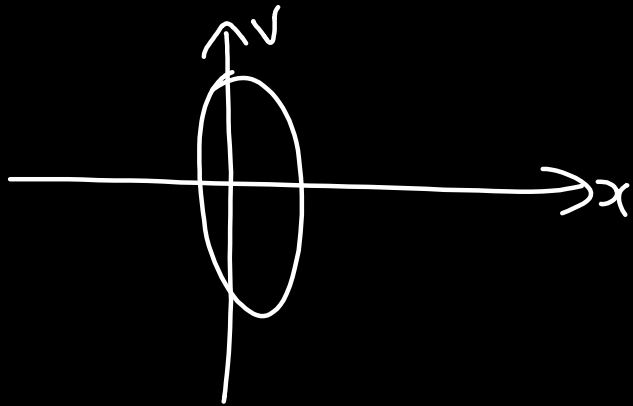
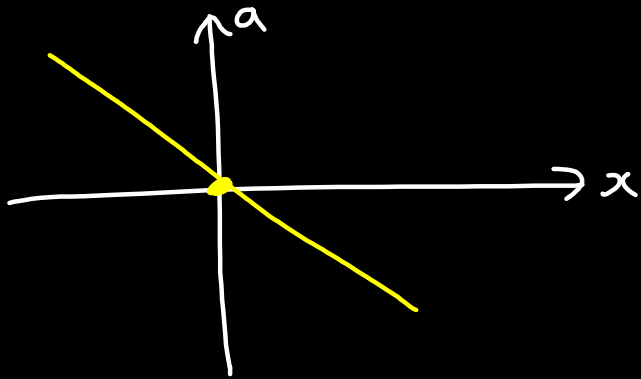
$$PE = \frac{1}{2}kx^2 + U_0$$

$$k = m\omega^2$$

$$PE = \frac{1}{2}m\omega^2 x^2 + U_0$$

$$TE = KE + PE$$

$$TE = \frac{1}{2}m\omega^2 A^2$$



Q Find t when $PE = KE$

Q Find position where $PE = KE$

① $PE = KE$

$$\frac{1}{2} m A^2 \omega^2 \sin^2 \omega t = \frac{1}{2} m A^2 \omega^2 \cos^2 \omega t$$

$$\sin^2 = \cos^2$$

$$\sin = \cos$$

$$\theta = 45^\circ = \frac{\pi}{4}$$

$$\theta = \omega t$$
$$\frac{\pi}{4} = \omega t$$

$$T = \frac{2\pi}{\omega}$$

$$\omega = \frac{2\pi}{T}$$

$$\frac{\pi}{4} = \frac{2\pi}{T} t$$

$$\boxed{\frac{T}{8} = t}$$

given starts from $t=0$ at $x=0$

$$PE_{\text{mean}} = 0$$

$$\text{time} = T$$

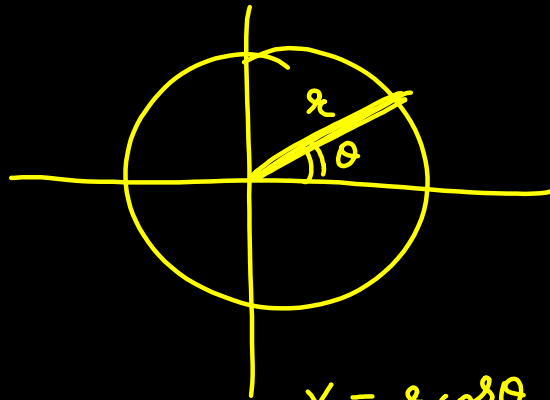
$$\text{amplitude} = A.$$

② $\frac{1}{2} m \omega^2 x^2 = \frac{1}{2} m \omega^2 (A^2 - x^2)$

$$2x^2 = A^2$$

$$x = \frac{A}{\sqrt{2}}$$

Phasor Diagram



$$x = r \cos \theta$$

$$y = r \sin \theta$$

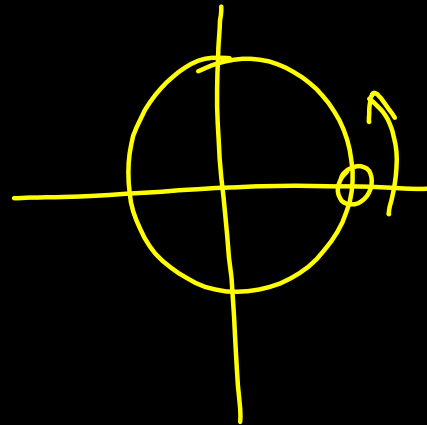
Circular

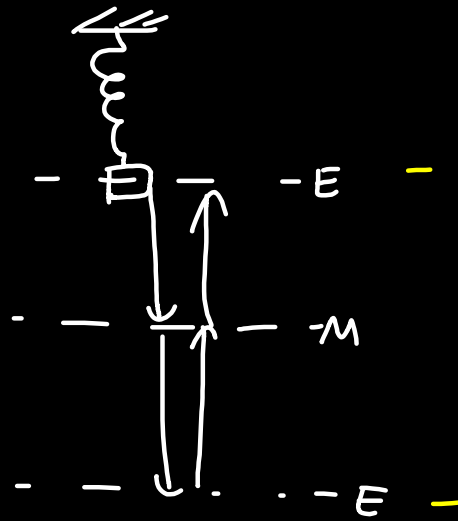
$$s = ut + \frac{1}{2}at^2$$

$$\theta = \omega t + \frac{1}{2}\alpha t^2$$

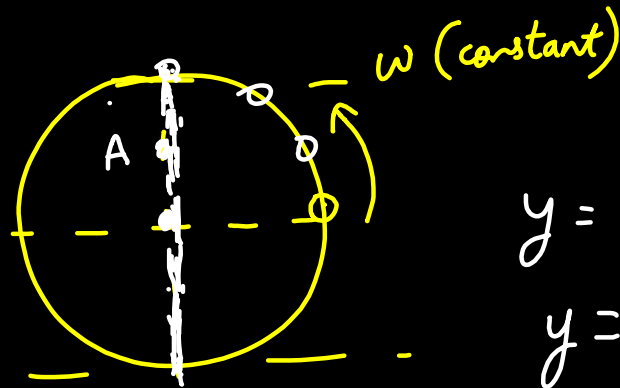
Uniform circular motion
 $\alpha = 0$

$$\boxed{\theta = \omega t}$$





$$y = A \sin(\omega t)$$



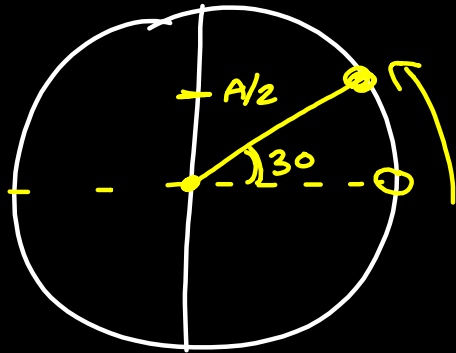
$$y = A \sin \theta$$

$$y = A \sin(\omega t)$$

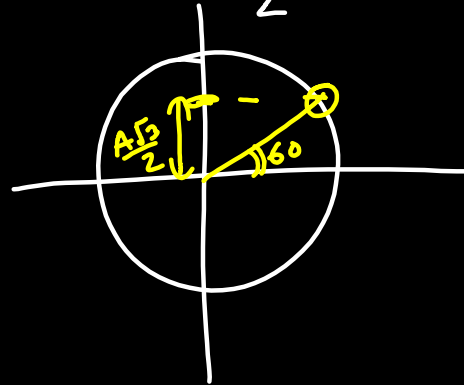


$$\theta_{\text{rotated}} = \omega t$$

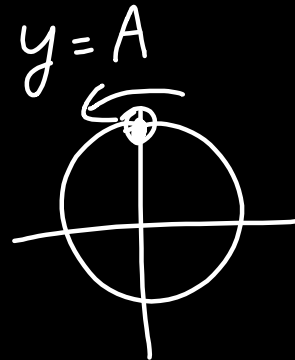
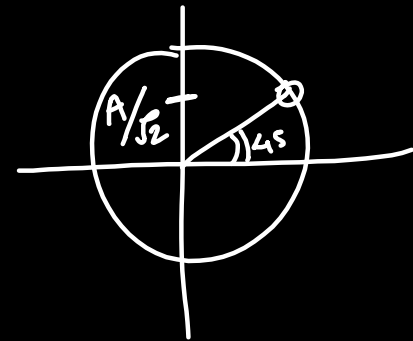
$$\underline{x = A \sin(\omega t)}$$



$$x = \frac{A\sqrt{3}}{2}$$



$$y = A/\sqrt{2}$$



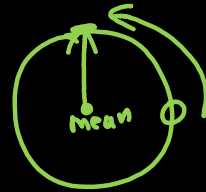
Find time taken from (direct)

(1) T

$\omega = \frac{2\pi}{T}$

$\theta_{\text{rot}} = \omega t$

(1) $x=0$ to $x=A$



90° $\theta = \omega t$

$\frac{\pi}{2} = \frac{2\pi}{T} t$

$t = T/4$

(2) $x=0$ to $x=A/2$



30°

$\theta = \omega t$

$\frac{\pi}{6} = \frac{2\pi}{T} t$

$t = T/12$

(3) $x=A/2$ to $x=A$



60°

$\frac{\pi}{3} = \frac{2\pi}{T} t$

$\Rightarrow t = T/6$

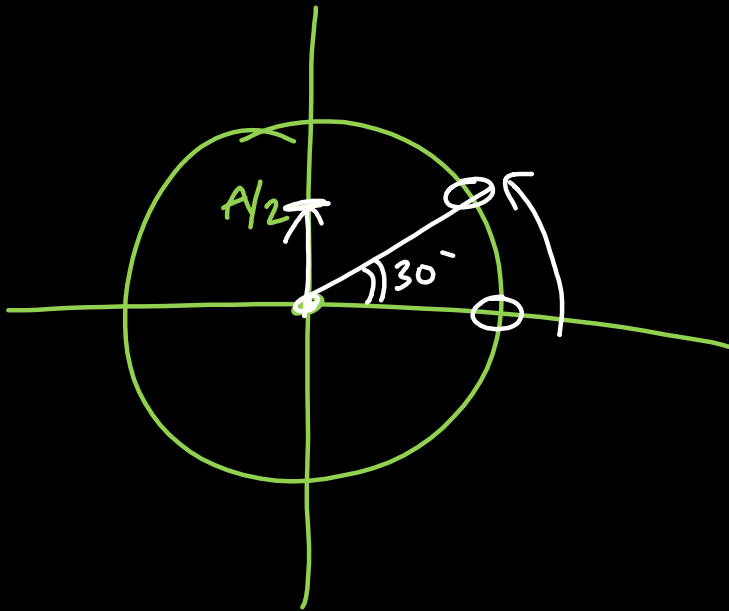
(4) $x=0$ to $x=A/\sqrt{2}$

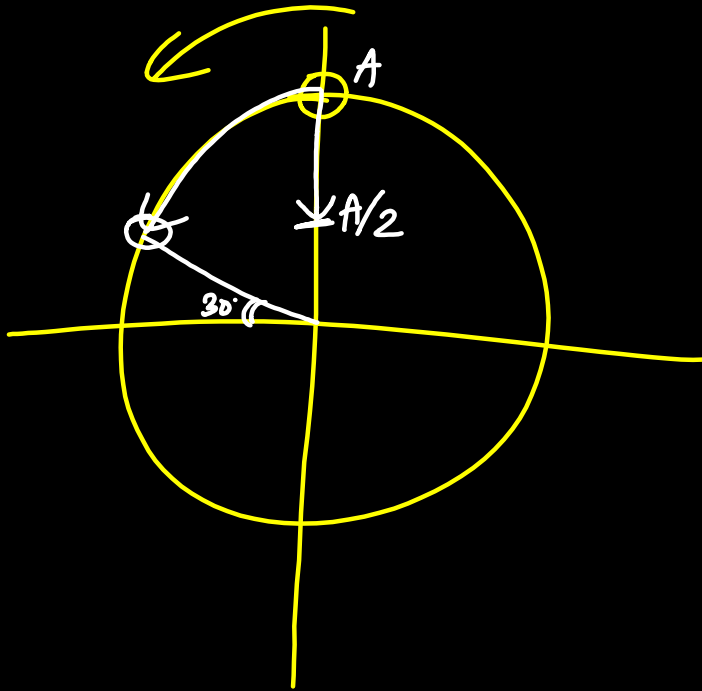


$\frac{\pi}{4} = \frac{2\pi}{T} t$

$t = T/8$

(5) $x=A$ to $x=A/2$





$$\theta_{\text{rot}} = \omega t$$

Go

$$\frac{\pi}{3} = \frac{2\pi}{T} t$$

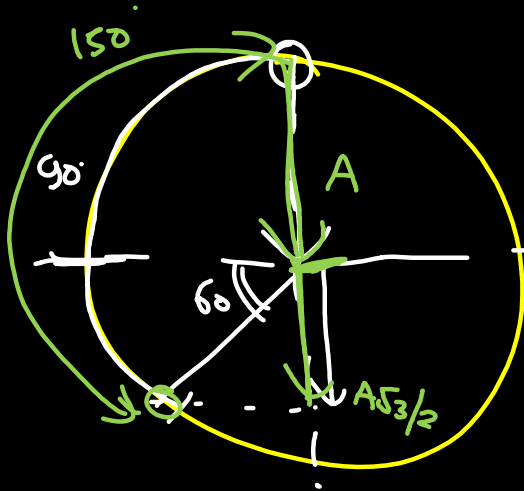
$$t = T/6$$

Q Distance covered by particle executing SHM

(A) (T)

Particle starts from extreme

Find distance travelled in $\frac{5T}{12}$ sec



$$\theta = \omega t$$

$$= \left(\frac{2\pi}{T} \right) \left(\frac{5T}{12} \right)$$

$$= \frac{\pi 10}{12} = 10 \times \frac{180}{72} \times \frac{5}{8}$$

$$= 150^\circ$$

$$Ans = A + \frac{A\sqrt{3}}{2}$$

Break 10min

Resume 9:15pm

After Break

- Spring
- Simple
- Time Calculation
- Superposition / SHM.

Calculation of Time Period

Find mean position \longleftrightarrow

Displace by small amount x

Find F_{net} & acc at this position

Compare with

$$F = -kx$$

$$a = -\omega^2 x$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

\longleftrightarrow

$$x \rightarrow \theta$$

$$F \rightarrow \tau$$

$$m \rightarrow m \text{ or } I$$

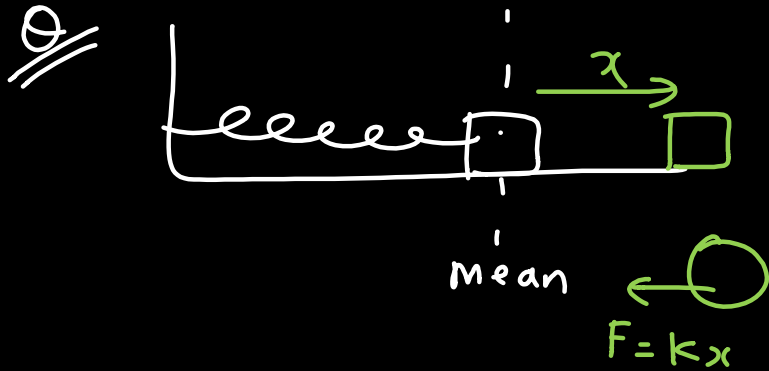
$$a \rightarrow \alpha$$



$$\tau = -k\theta$$

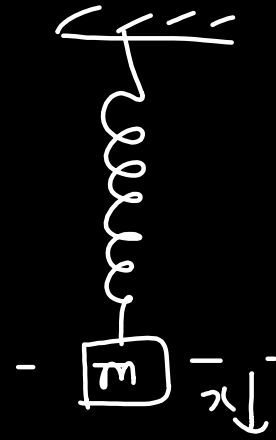
$$T = 2\pi \sqrt{\frac{I}{k}}$$

$$\alpha = -\omega^2 \theta$$



$$F_{\text{spring}} = -kx$$

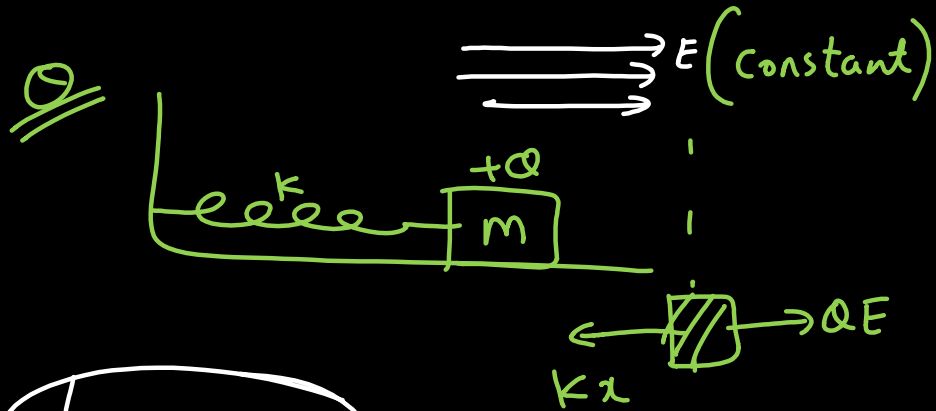
$$T = 2\pi \sqrt{\frac{m}{k}}$$



In spring block system
for calculation of T
we can ignore any
constant forces (like mg)

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$F_{\text{net}} = -kx$$



force = QE

Find ① mean position = ?

② Time period = ?

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$kx = QE$$

$$x = \frac{QE}{k} \Rightarrow \text{mean position.}$$

Combination of Springs

$$T = 2\pi \sqrt{\frac{m}{K_{eq}}}$$

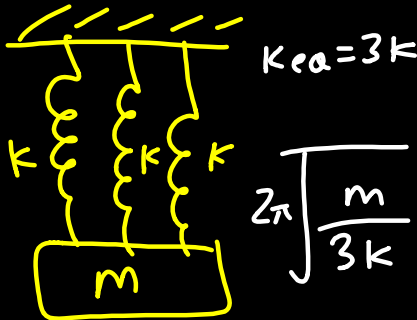
Parallel

$$K_{eq} = k_1 + k_2$$

Series

$$\frac{1}{K_{eq}} = \frac{1}{k_1} + \frac{1}{k_2}$$

Q //



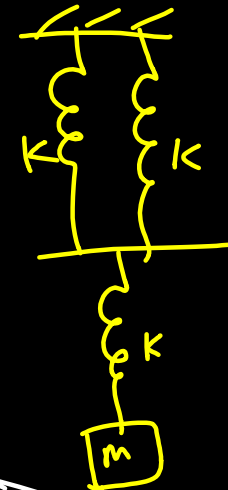
$$2\pi \sqrt{\frac{m}{3k}}$$

Q //



$$K_{eq} = k/3$$

$$T = 2\pi \sqrt{\frac{m}{k/3}} = 2\pi \sqrt{\frac{3m}{k}}$$



$$2k$$

$$k$$

$$\frac{1}{K_{eq}} = \frac{1}{k} + \frac{1}{2k}$$

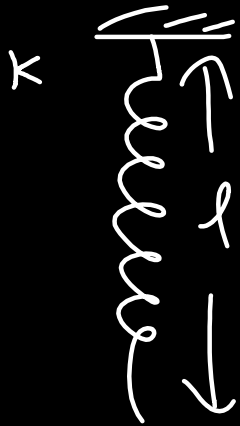
$$\frac{1}{K_{eq}} = \frac{3}{2k}$$

$$K_{eq} = \frac{2k}{3}$$

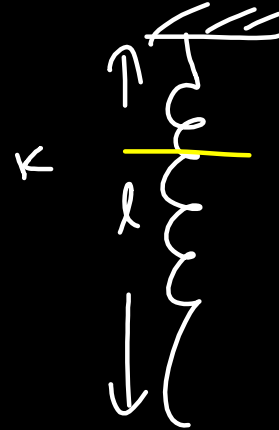
$$T = 2\pi \sqrt{\frac{3m}{2k}}$$

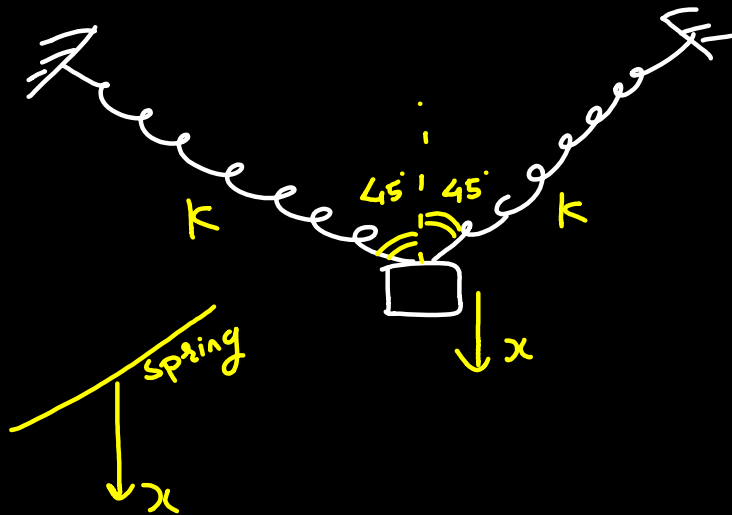
Cutting of Springs

$$K \propto \frac{1}{\text{natural length}}$$

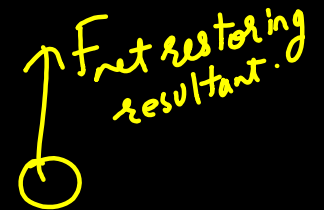
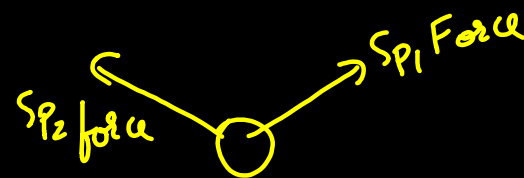


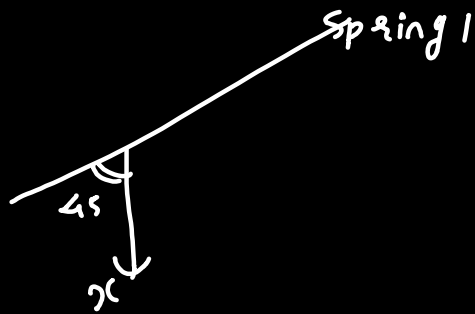
$$Kl = k_1 l_1 = k_2 l_2$$





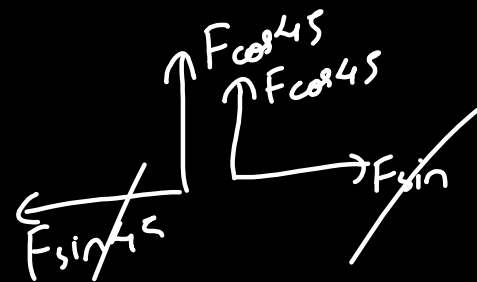
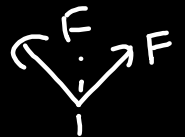
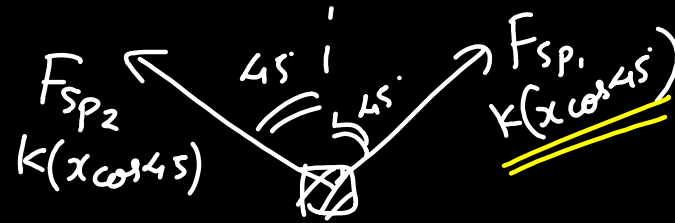
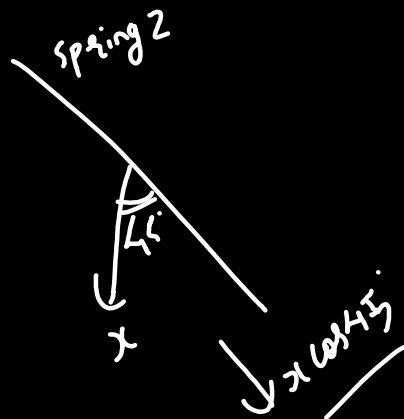
Spring $\frac{1}{2}$ elongation $\equiv x$ component





$x \cos 45^\circ$
elongation

t.me/ajitlulla



$$\uparrow 2 F \cos 45^\circ$$

$$2 (k x \cos 45^\circ) \cos 45^\circ$$

$$2 k x \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \Rightarrow (k x)$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$



$$T = 2\pi \sqrt{\frac{\mu}{k}}$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

reduced mass

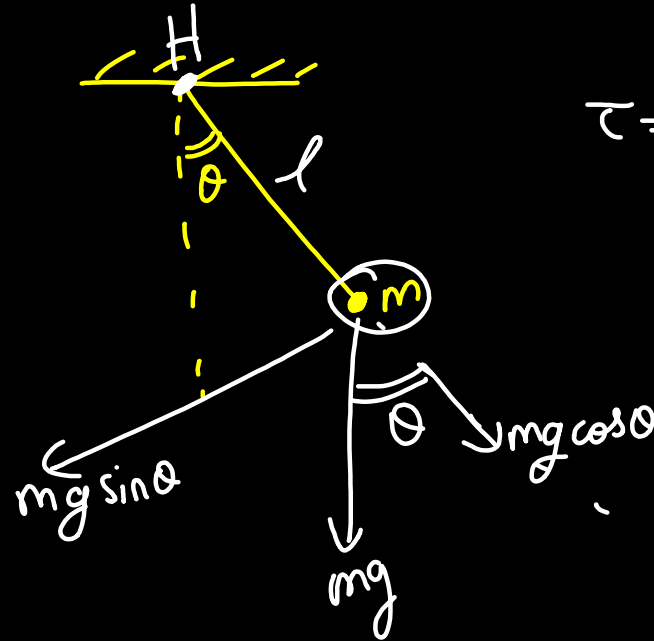
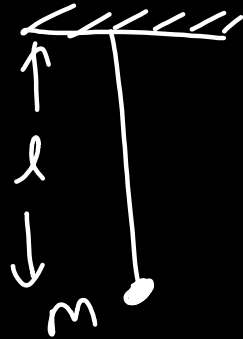
Simple Pendulum

$$F=ma$$

$$\tau$$

$$\tau = I\alpha$$

$$\alpha = -\omega^2 \theta$$



$$\tau = (\text{force})(\perp \text{ dist})$$

$$\tau = -(mg \sin \theta) l$$

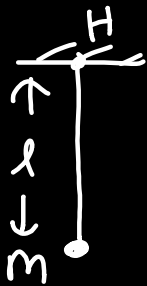
for small angle
 $\sin \theta \approx \theta$

$$\begin{aligned} \tau &= -mg l \theta \\ I\alpha &= -mg l \theta \\ \alpha &= \frac{-mg l \theta}{I} \end{aligned}$$

$$\begin{aligned} \alpha &= -\omega^2 \theta \\ \omega &= \sqrt{\frac{mgl}{I}} \end{aligned}$$

$$\begin{aligned} T &= 2\pi/\omega \\ T &= 2\pi \sqrt{\frac{I}{mgl}} \end{aligned}$$

Point mass $M O I = m l^2$
(I)



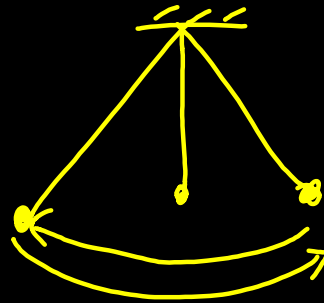
$$T = 2\pi \sqrt{\frac{I}{mgl}}$$

$$= 2\pi \sqrt{\frac{m l^2}{mgl}}$$

$$T = 2\pi \sqrt{\frac{l}{g}}$$

Second's pendulum

$$T = 2 \text{ sec}$$



$$\pi = \sqrt{10}$$

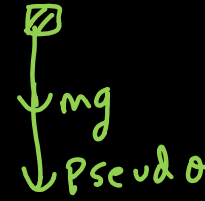
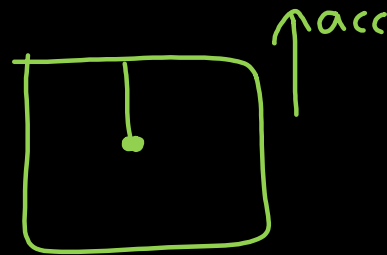
$$T = 2\pi \sqrt{\frac{l}{g}}$$

$$2 = 2\pi \sqrt{\frac{l}{g}}$$

$$\underline{\underline{l \approx 1 \text{ m}}}$$

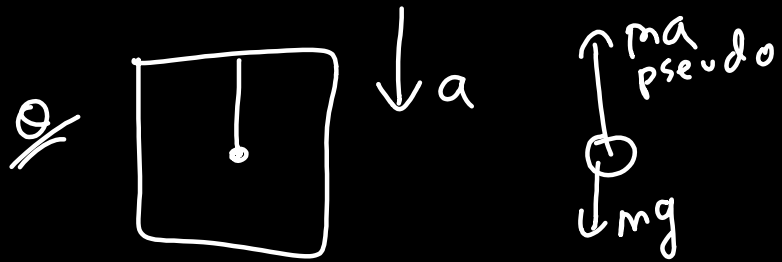
$$T = 2\pi \sqrt{\frac{l}{g_{\text{effective}}}}$$

pseudo
force



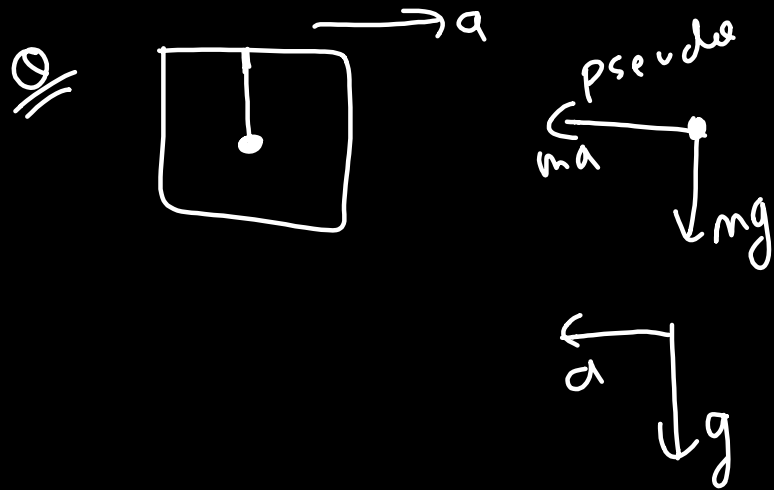
$$g_{\text{eff}} = g + a$$

$$T = 2\pi \sqrt{\frac{l}{g+a}}$$



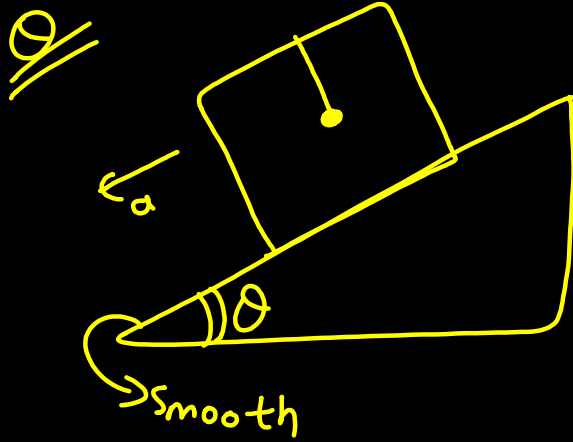
$$g_{\text{eff}} = g - a$$

$$T = 2\pi \sqrt{\frac{l}{g-a}}$$



$$\sqrt{a^2 + g^2} = g_{\text{eff}}$$

$$T = 2\pi \sqrt{\frac{l}{\sqrt{g^2 + a^2}}}$$



$g \sin \theta = \text{acc}$

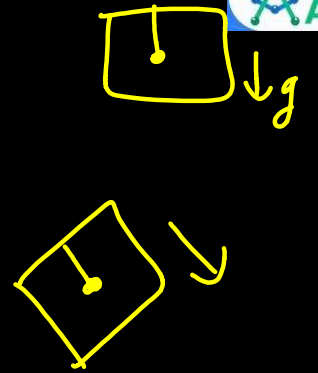
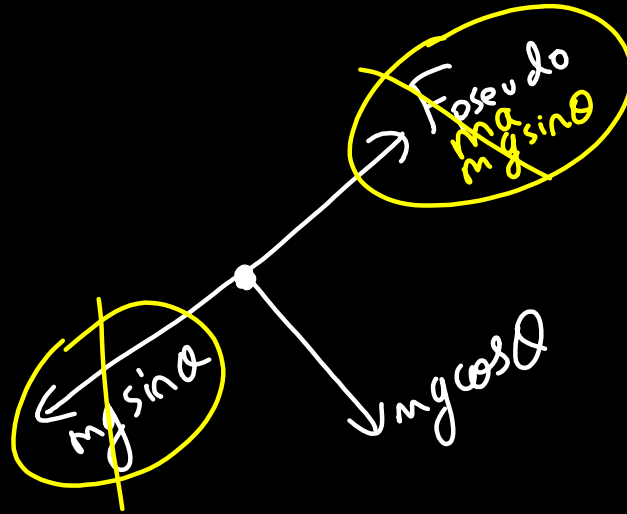
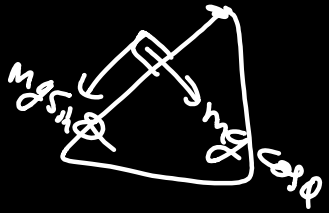
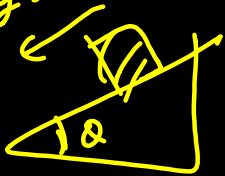
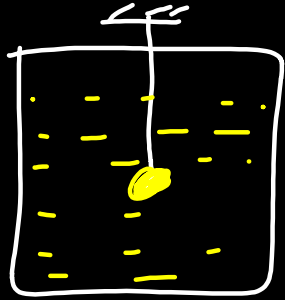


Diagram showing a block on an inclined plane with angle θ . It shows the component of gravity acting down the plane labeled $mg \cos \theta$ and the component acting perpendicular to the plane labeled $g \cos \theta$.

$$T = 2\pi \sqrt{\frac{l}{g \cos \theta}}$$



$$mg \rightarrow mg_{\text{effective}} = mg \left(1 - \frac{\rho_L}{\rho_s} \right)$$

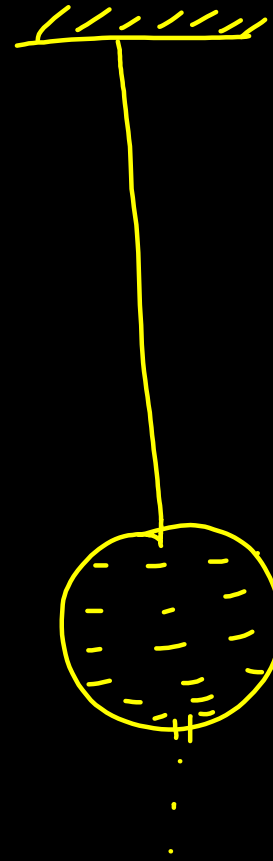
$$T = 2\pi \sqrt{\frac{l}{g \left(1 - \frac{\rho_L}{\rho_s} \right)}}$$

$$\rho_L = \rho_{\text{liquid}}$$

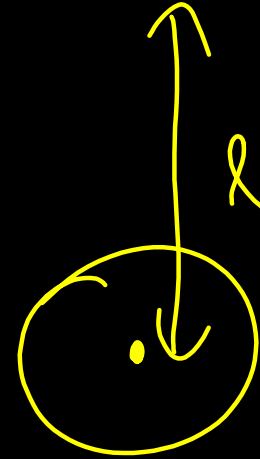
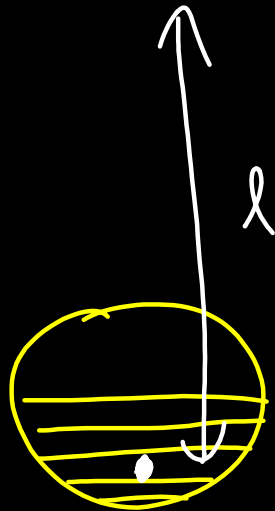
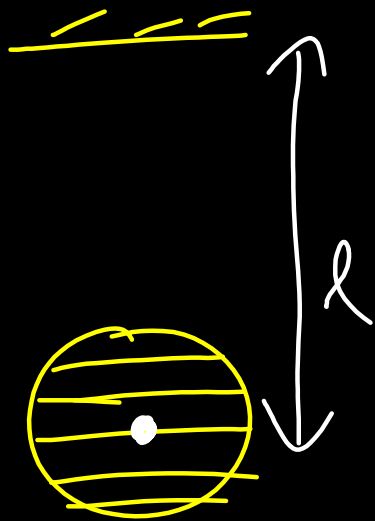
$$\rho_s = \rho_{\text{solid}}$$

$$T = 2\pi \sqrt{\frac{l}{g}}$$

→ distance of COM from hinge



leakage
Time changes?

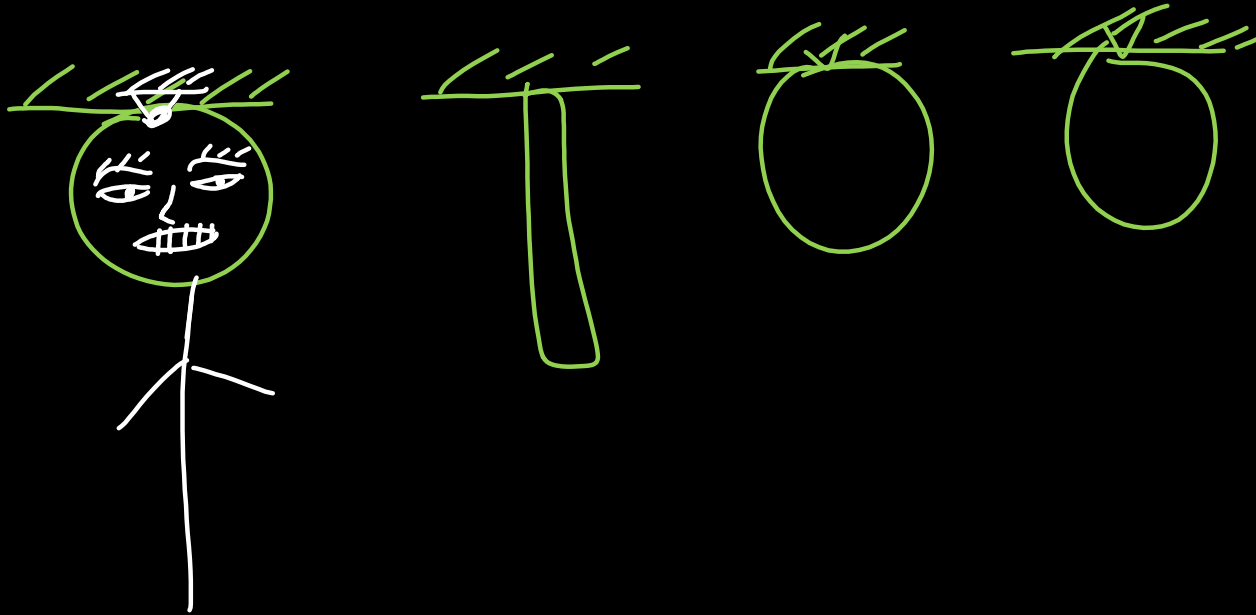


l increase than decrease & init $l = \text{final } l$.

T 1st increases than decrease

$$\underline{\underline{\& T_{ini} = T_{final}}}$$

Physical Pendulum Compound Pendulum

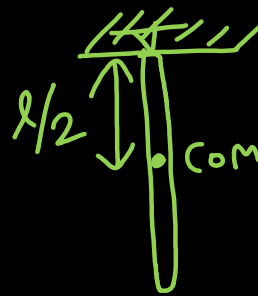


$$T = 2\pi \sqrt{\frac{I}{mgd}}$$

$I \rightarrow$ moment of inertia
of body about hinge

$d \rightarrow$ distance of com from
hinge.

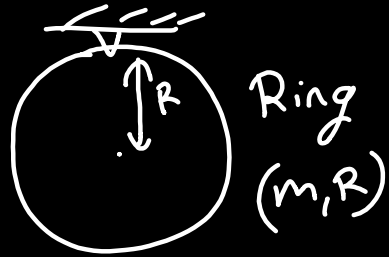
$m \rightarrow$ mass of system.



$$I = \frac{ml^2}{3}$$

$$T = 2\pi \sqrt{\frac{ml^2/3}{mg(l/2)}}$$

$$T = 2\pi \sqrt{\frac{2l}{3g}}$$



$$I_{\text{com}} + md^2$$

$$I = MR^2 + MR^2$$

$$I = 2MR^2$$

$$T = 2\pi \sqrt{\frac{2MR^2}{mgR}} = 2\pi \sqrt{\frac{2R}{g}}$$



$$MOI = \frac{mR^2}{2} + mR^2$$

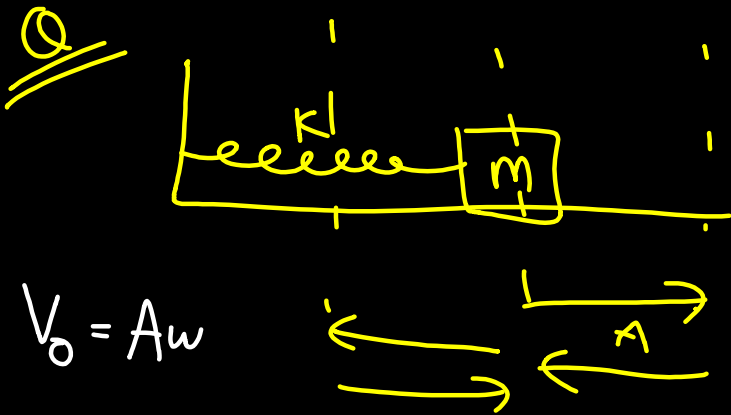
$$= \frac{3}{2}mR^2$$

$$T = 2\pi \sqrt{\frac{\frac{3}{2}mR^2}{mgR}} = 2\pi \sqrt{\frac{3R}{2g}}$$

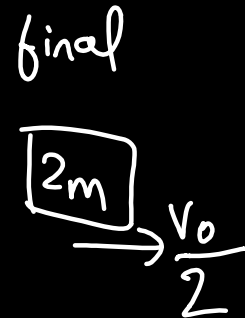
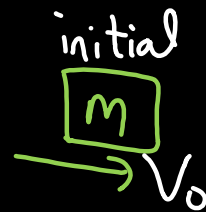
Mechanics Use

$$V = \omega \sqrt{A^2 - x^2}$$

$$V = A\omega$$



when it was crossing mean position, another block of mass m is dropped over it & it sticks to body. Find new Amplitude?



$$\begin{aligned} P_{\text{ini}} &= P_{\text{fin}} \\ mV_0 &= 2mV_f \\ \frac{V_0}{2} &= V_f \end{aligned}$$

initial final

$$V_0$$

$$\frac{V_0}{2}$$

$$A\omega$$

$$A'\omega'$$

$$V_0 = A\omega$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$\omega' = \sqrt{\frac{k}{2m}}$$

$$V_{\text{final}} = \frac{V_0}{2}$$

$$A'\omega' = \frac{A\omega}{2}$$

$$A' \sqrt{\frac{k}{2m}} = \frac{A}{2} \sqrt{\frac{k}{m}}$$

$$A' = \frac{A}{\sqrt{2}}$$

Rotational

τ method

$$\tau = I\alpha$$

$$\alpha = -\omega^2\theta$$

Energy method

$$TE = \text{constant}$$

↓ diff
○

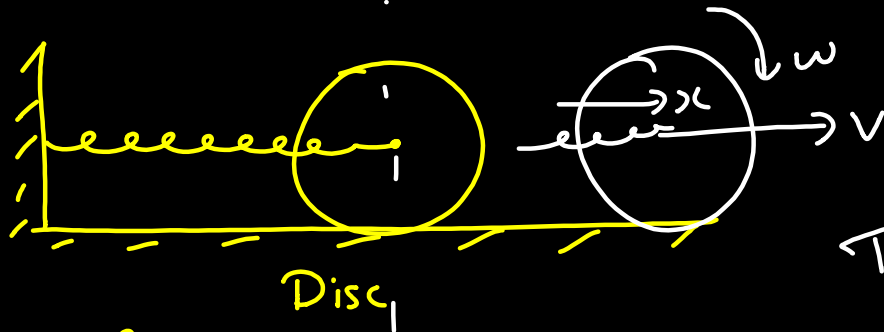
Find mean

Displace by small amount x

Find $TE = KE + PE$

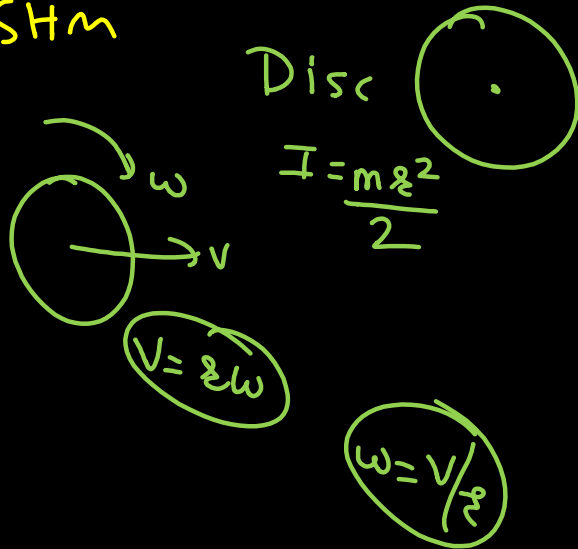
$$\# \frac{d(TE)}{dx} = 0$$

$$\text{or } \frac{d(TE)}{dt} = 0.$$



pure
rolling

SHM



$$TE = \frac{1}{2} kx^2 + \frac{1}{2} mv^2 + \frac{1}{2} I\omega^2$$

$$TE = \frac{1}{2} kx^2 + \frac{1}{2} mv^2 + \frac{1}{2} \left(\frac{mR^2}{2} \right) \left(\frac{v}{R} \right)^2$$

$$\frac{1}{2} kx^2 + \frac{1}{2} mv^2 + \frac{1}{2} \frac{mR^2}{2} \frac{v^2}{R^2}$$

$$\frac{1}{2} kx^2 + \frac{1}{2} mv^2 + \frac{1}{4} mv^2$$

$$TE = \frac{1}{2} kx^2 + \frac{3}{4} mv^2$$

$$TE = \frac{1}{2} kx^2 + \frac{3}{4} mv^2$$

$$\frac{d(TE)}{dx} = \frac{1}{2} k(2x) + \frac{3}{4} m \left(2v \frac{dv}{dx} \right)$$

$$= kx + \frac{3}{2} m v \frac{dv}{dx}$$

$$0 = kx + \frac{3mq}{2}$$

$$a = -\omega^2 x$$

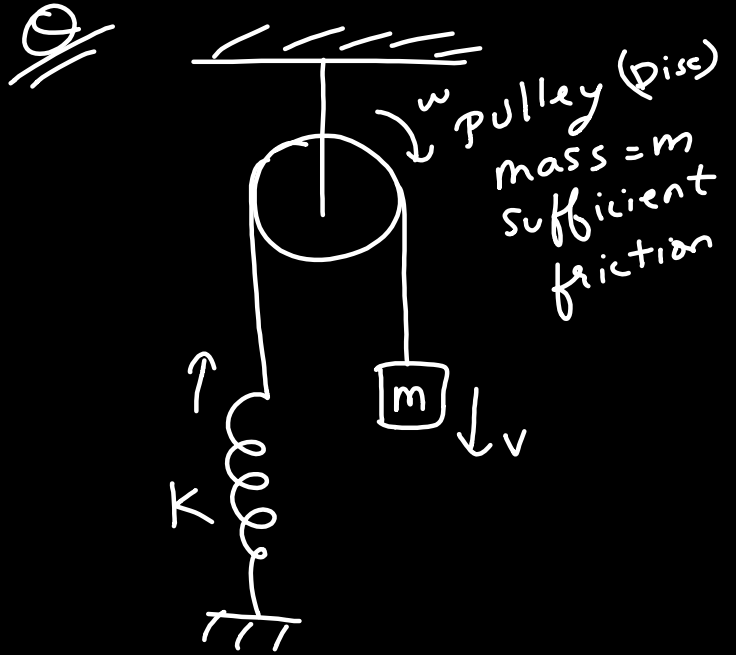
$$a = -\frac{2k}{3m} x$$

$$\omega = \sqrt{\frac{2k}{3m}}$$

$$T = 2\pi \sqrt{\frac{3m}{2k}}$$

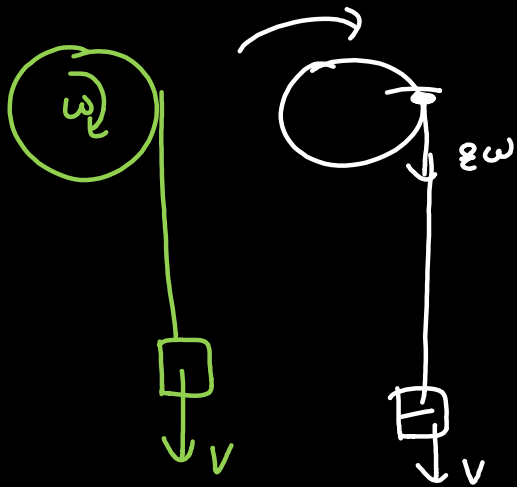
$$v^2 \rightarrow \text{diff}$$

$$2v \frac{dv}{dx}$$



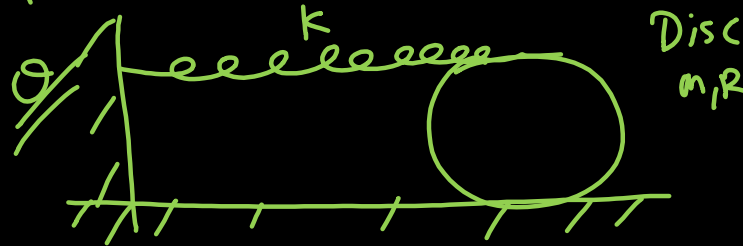
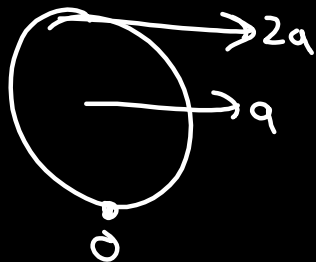
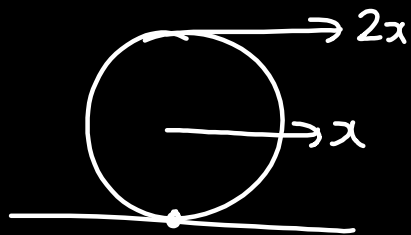
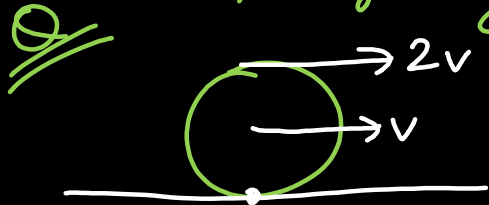
$$TE = \underbrace{\frac{1}{2} K x^2}_{\text{spring}} + \underbrace{\frac{1}{2} m v^2}_{\text{Block}} + \underbrace{\frac{1}{2} I \omega^2}_{\text{pulley}}$$

$$T = 2\pi \sqrt{\frac{3m}{2K}}$$

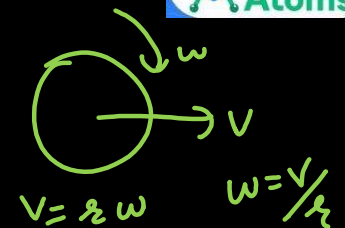


$$v = r\omega$$

Rolling on ground



$$I = \frac{mR^2}{2}$$



$$TE = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 + \frac{1}{2}k(2x)^2$$

$$= \frac{1}{2}mv^2 + \frac{1}{2} \frac{mR^2}{2} \frac{v^2}{R^2} + \frac{1}{2}k4x^2$$

$$\left(\frac{1}{2} + \frac{1}{4} \right) mv^2$$

$$TE = \frac{3}{4}mv^2 + 2kx^2$$

$$TE = \frac{3}{4}mv^2 + 2kx^2$$

$$\frac{d(TE)}{dx} = \frac{3}{4}m \left(2v \frac{dv}{dx} \right) + 2k(2x)$$

$$0 = \frac{3}{2}ma + 4kx$$

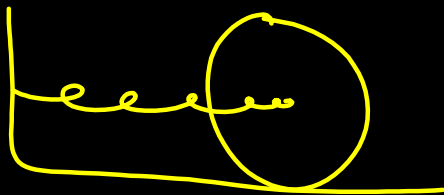
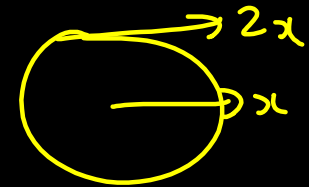
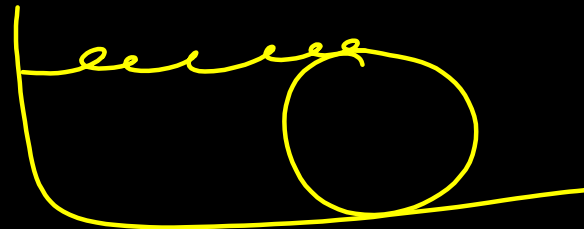
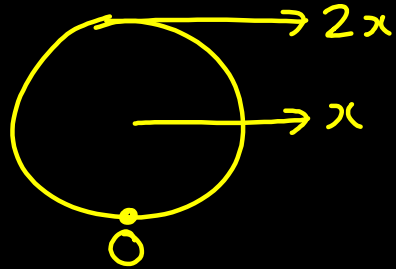
$$a = -\frac{8k}{3m}x = -\omega^2x$$

$$\omega = \checkmark$$

$$T = \frac{2\pi}{\omega}$$

$$T = 2\pi \sqrt{\frac{3m}{8k}}$$

Pure Rolling



$$\frac{1}{2} k x^2$$

Superposition of SHM's along same axis

$$y_1 = A_1 \sin(\omega t)$$

$$y_2 = A_2 \sin(\omega t + \phi)$$

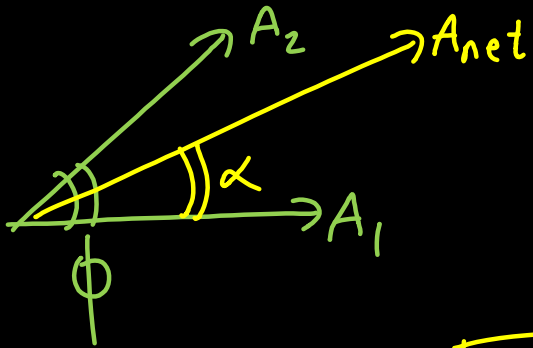
Same freq
Same axis

Result motion \rightarrow SHM of same freq
of A_{new} .

$$y_{\text{net}} = y_1 + y_2$$

$$= A_1 \sin(\omega t) + A_2 \sin(\omega t + \phi)$$

$$y_{\text{net}} = A_{\text{net}} \sin(\omega t + \alpha)$$



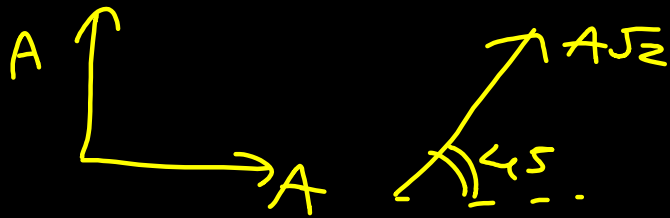
$$A_{net} = \sqrt{A_1^2 + A_2^2 + 2A_1A_2\cos\phi}$$

$$\tan\alpha = \frac{A_2 \sin\phi}{A_1 + A_2 \cos\phi}$$

Q

$$y_1 = A \sin(\omega t)$$

$$y_2 = A \sin(\omega t + 90)$$



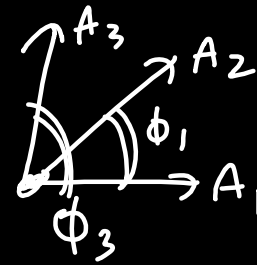
$$\underline{y_{net} = (A\sqrt{2}) \sin(\omega t + \alpha)}$$

$$y_1 = A_1 \sin(\omega t)$$

$$y_2 = A_2 \sin(\omega t + \phi_1)$$

$$y_3 = A_3 \sin(\omega t + \phi_2)$$

$$y_{\text{net}} = A_{\text{net}} \sin(\omega t + \alpha)$$



2022

Two massless springs with spring constants 2 K and 9 K , carry 50 g and 100 g masses at their free ends .These two masses oscillate vertically such that their maximum velocities are equal . Then , the ratio of their respective amplitudes will be :

A. 1:2

☒ B. 3:2

C. 3:1

D. 2:3

$$\omega = \sqrt{\frac{k}{m}}$$

$$\Downarrow \\ A\omega$$

$$A_1 \omega_1 = A_2 \omega_2$$

$$A_1 \sqrt{\frac{2K}{50}} = A_2 \sqrt{\frac{9K}{100g}}$$

$$A_1 = A_2 \sqrt{\frac{9}{4}}$$

$$\frac{A_1}{A_2} = \frac{3}{2}$$

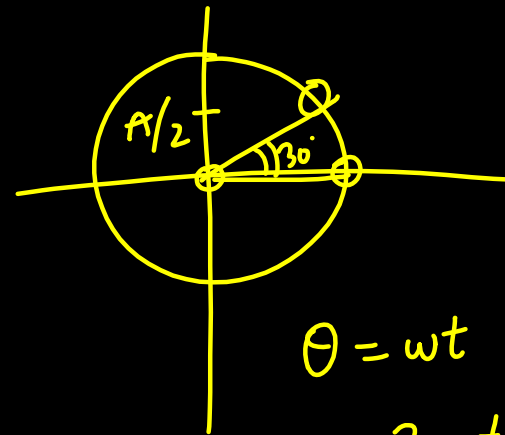
2022

The displacement of simple harmonic oscillator after 3 seconds starting from its Mean position is equal to half of its amplitude. The time period of harmonic motion is :

$$x = 0 \quad \text{to} \quad x = A/2$$

$$t = 3 \text{ sec}$$

$$\frac{T}{12} = 3$$



$$\theta = \omega t$$

$$\frac{\pi}{6} = \frac{2\pi}{T} t$$

$$\frac{T}{12} = t$$

- A. 6 s
- B. 8 s
- C. 12 s
- ~~D. 36 s~~

Time period of a simple pendulum in a stationary lift is 'T'. If the lift accelerates with $\frac{g}{6}$

vertically upwards then the time period will be :

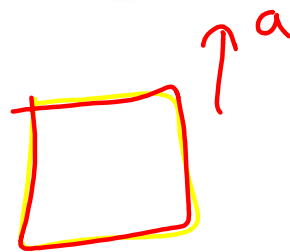
(Where g =acceleration due to gravity)

A $\sqrt{\frac{6}{5}} T$

B $\sqrt{\frac{5}{6}} T$

☒ C $\sqrt{\frac{6}{7}} T$

D $\sqrt{\frac{7}{6}} T$



$$T = 2\pi \sqrt{\frac{l}{g}}$$

$$T' = 2\pi \sqrt{\frac{l}{g + g/6}} = \frac{\sqrt{6}}{\sqrt{7}} 2\pi \sqrt{\frac{l}{g}} = \sqrt{\frac{6}{7}} T$$

The equation of a particle executing simple harmonic motion is given by $x = \sin \pi \left(t + \frac{1}{3} \right) m$. At $t = 1$ s, the speed of particle will be (Given: $\pi = 3.14$) -

A. 0 cm s^{-1}

B. 157 cm s^{-1}

C. 272 cm s^{-1}

D. 314 cm s^{-1}

$$x = \sin \left(\pi t + \frac{\pi}{3} \right)$$

$$v = \cos \left(\pi t + \frac{\pi}{3} \right) \times \pi$$

$$v = \pi \cos \left(\pi t + \frac{\pi}{3} \right)$$

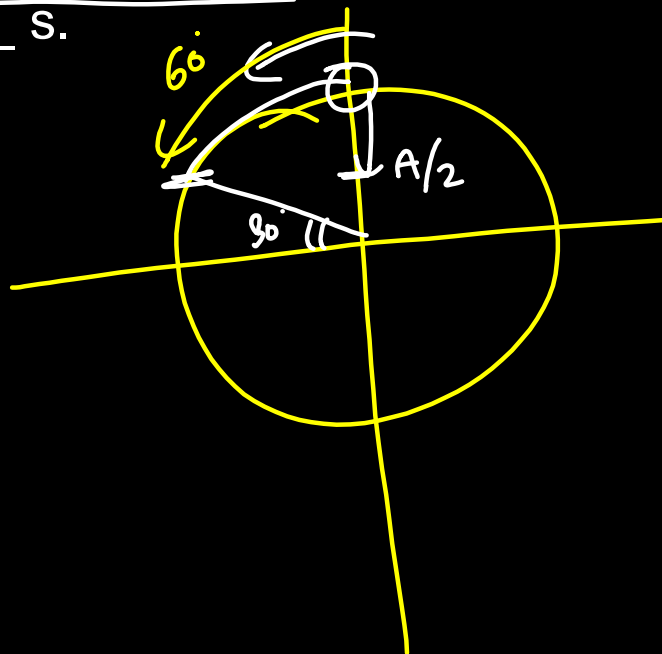
$$\pi \cos \left(\pi + \frac{\pi}{3} \right)$$

$$\cos(180 + 60) = -\pi \cos 60 = -\frac{\pi}{2} = -\frac{3.14}{2} = -1.57 \text{ m/s}$$

2022

A particle executes simple harmonic motion . Its amplitude is 8 cm and time period is 6 s. The time it will take to travel from its position of maximum displacement to the point corresponding to half of its amplitude is _____ s.

1 sec



$$\theta = \omega t$$

$$\frac{\pi}{3} = \frac{2\pi}{T} t$$

$$T/6 = t$$

$$T = 6$$

Motion of a particle in $x - y$ plane is described by a set of following equations

$x = 4 \sin\left(\frac{\pi}{2} - \omega t\right) \text{ m}$ and $y = 4 \sin(\omega t) \text{ m}$. The path of the particle will be :

Handwritten notes: $\cos \theta$ under $\sin(\frac{\pi}{2} - \omega t)$ and $\sin \theta$ under $\sin(\omega t)$

- ☒ A. Circular.
- ☐ B. Helical .
- ☐ C. Parabolic.
- ☐ D. Elliptical.

Superposition of two SHM's along x & y axis



Find locus / relation b/w x & y

$$\sin \theta = x/A$$

① $x = A \sin \omega t$
 $y = A \sin \omega t$

$x = y$
 St. line

② $x = A \sin(\omega t)$
 $y = A \cos(\omega t)$

$$\sin^2 + \cos^2 = 1$$

$$\frac{x^2}{A^2} + \frac{y^2}{A^2} = 1$$

$$x^2 + y^2 = A^2$$

circle

③ $x = A \sin(\omega t + \phi)$
 $y = A \sin(\omega t)$

ellipse

$$x = A_1 \sin(\omega t)$$

$$y = A_2 \cos(\omega t)$$

2022

A body is performing simple harmonic with an amplitude of 10 cm. The velocity of the body was tripled by air Jet when it is at 5 cm from its mean position. The new amplitude of vibration is \sqrt{x} cm. The value of x is

mechanics Use

$$A = 10 \text{ cm}$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$V = \omega \sqrt{A^2 - x^2}$$

$$V = \omega \sqrt{100 - 25}$$

$$V_{\text{init}} = \omega \sqrt{75}$$

$$V_{\text{final}} = \omega \sqrt{A'^2 - x^2}$$

$$3\omega \sqrt{75} = \omega \sqrt{A'^2 - (5)^2}$$

$$9 \times 75 = A'^2 - 25$$

$$\sqrt{700} = A'$$

A damped harmonic oscillator has a frequency of 5 oscillations per second. The amplitude drops to half its value for every 10 oscillations. The time it will take to drop to $\frac{1}{1000}$ of the original

amplitude is close to

(2019 Main)

(a) 20 s

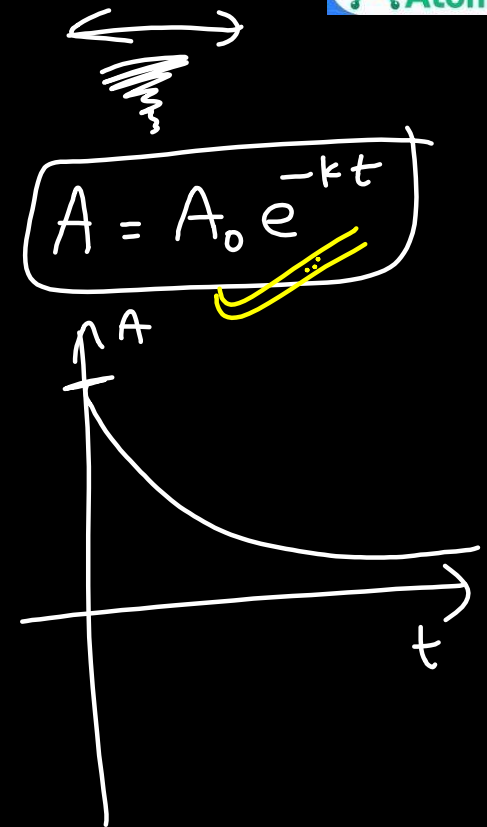
(b) 50 s

(c) 100 s

(d) 10 s

$$A \xrightarrow{10 \text{ oscillation}} \frac{A}{2}$$

$$A \longrightarrow \frac{A}{1000}$$



exponential decrease

Half life $A \xrightarrow{t_{1/2}} \frac{A}{2} \xrightarrow{t_{1/2}} \frac{A}{4} \xrightarrow{t_{1/2}} \frac{A}{8}$

$$A \xrightarrow{t_{1/3}} \frac{A}{3} \xrightarrow{t_{1/3}} \frac{A}{9} \xrightarrow{t_{1/3}} \frac{A}{27}$$

$$f_{\text{req}} = 5$$

$$T = \frac{1}{5}$$

$$1 \text{ oscillation } \frac{1}{5} \text{ sec}$$

$$10 \text{ oscillation } 2 \text{ sec}$$

$$A \rightarrow \frac{A}{2}$$

$$t = 2 \text{ sec}$$

$$A_f = A_0 e^{-kt}$$

$$\frac{A}{2} = A e^{-k \cdot 2}$$

$$\frac{A}{1000} = A e^{-kt}$$

Divide

$$\frac{A/2}{A/1000} = \frac{e^{-k \cdot 2}}{e^{-kt}}$$

$$500 = e^{k(t-2)}$$

$$\underline{\underline{\ln(500) = k(t-2)}}$$

$$\frac{A}{2} = A e^{-k2}$$

$$\frac{1}{2} = e^{-2k}$$

$$(2)^{-1} = e^{-k2}$$

$$\ln 2 = 2k$$

$$\frac{1}{2} \ln(2) = k$$

$$\frac{A}{1000} = A e^{-kt}$$

$$(10)^{-3} = e^{-kt}$$

$$-3 \ln(10) = -kt$$

$$3 \ln(10) = \frac{1}{2} \ln(2) t$$

$$\frac{6 \ln(10)}{\ln(2)} = t$$

$$= 20 \text{ sec}$$