

Already Done in Previous Part of Moving Charges. - - -

- B calculation
- effect of B on moving charge
- " " " " Current carrying wire
- force b/w two current " "

Charge in both \vec{E} & \vec{B}

$$\vec{F} = Q\vec{E}$$

$$\vec{F}_{\text{mag}} = Q(\vec{v} \times \vec{B})$$

$$\vec{F}_{\text{net}} = Q\vec{E} + Q(\vec{v} \times \vec{B})$$

Lorentz
force

Case 1

$\longrightarrow B$
 $\longrightarrow E$

$(+Q)$
rest
released.

initially $\vec{F} = Q\vec{E}$

$Q \longrightarrow \text{vel}$
 $\longrightarrow B$

$\vec{v} \parallel \vec{B}$
 $\vec{F} = Q(\vec{v} \times \vec{B}) = 0$

St-line constant acc. motion

$$acc = \frac{QE}{m}$$

$$S = ut + \frac{1}{2}at^2$$

$$u = 0$$

$$\underline{v = u + at}$$

$$t = t$$

Case 2

$\odot \rightarrow \text{vel}$

\leftarrow
E
 \leftarrow
B

$$\vec{F}_{\text{electric}} = Q\vec{E}$$

\vec{v} anti || to \vec{B}

$$F_{\text{mag}} = Q(\vec{v} \times \vec{B}) = 0$$

\leftarrow
 $Q\vec{E}$

St. line retardation

$$U = U$$

$$a = -\frac{QE}{m}$$

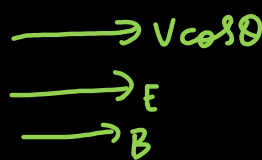
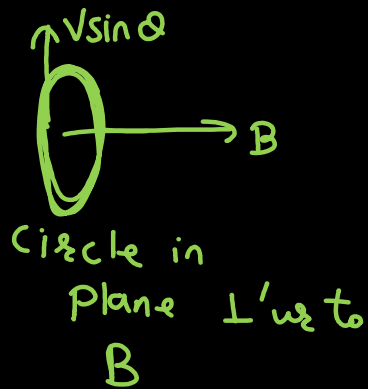
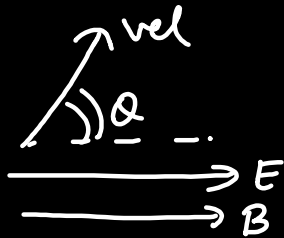
\leftarrow
electric
force

Speed decrease

Stop

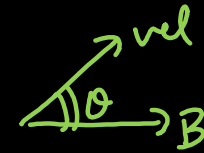
reverse.

Case 3

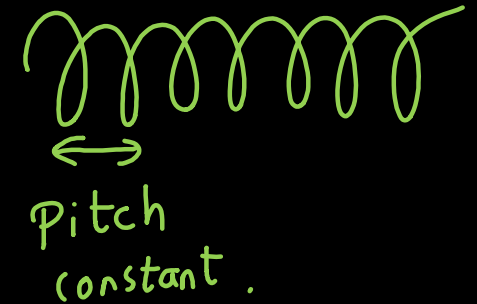


accelerated
 $\left(\frac{QE}{m}\right)$

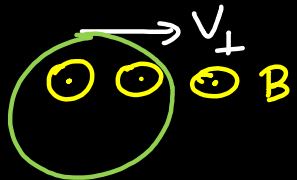
vector addition



helix



Let's try to find coordinates

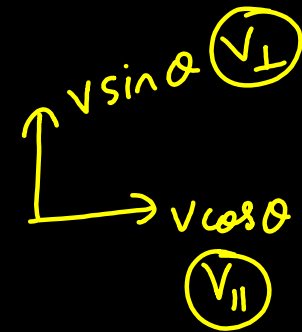
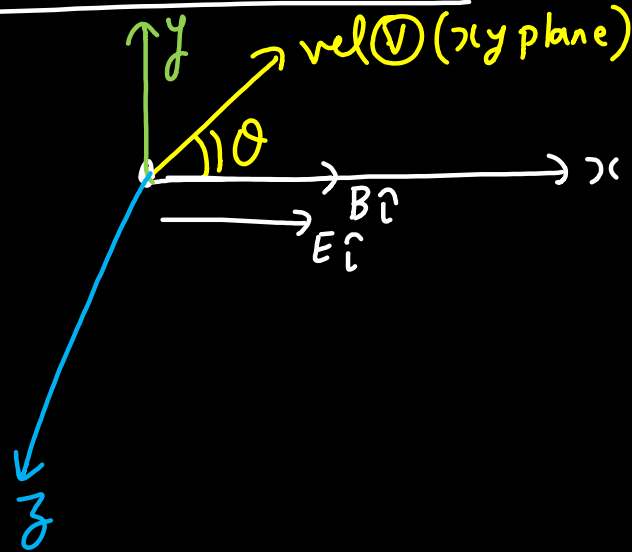


$$r = \frac{m v_{\perp}}{Q B}$$

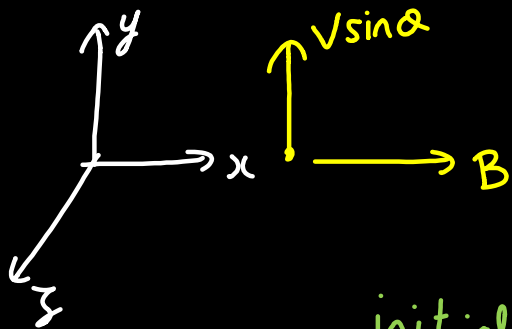
$$T = \frac{2\pi m}{Q B}$$

$$\theta_{\text{rot}} = \omega t$$

$$\omega = \frac{Q B}{m}$$

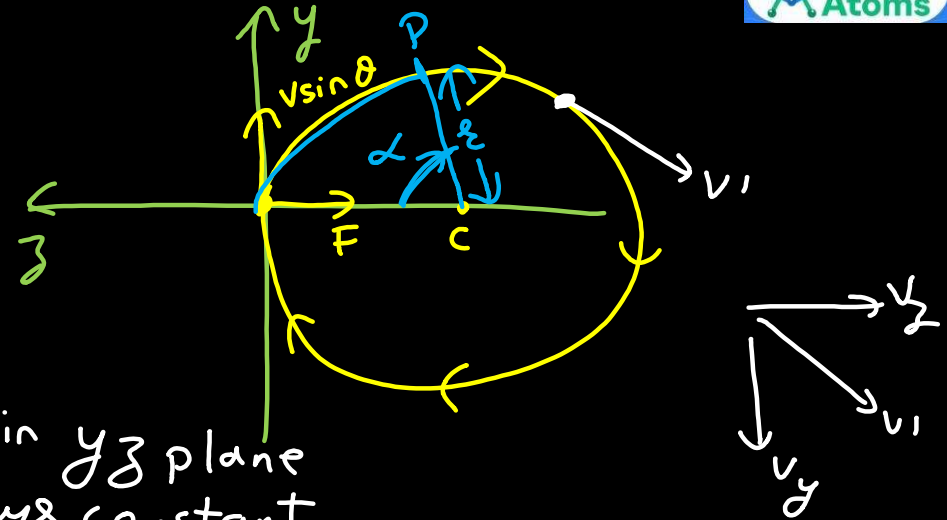


Circular Motion



initial F in $-z$ axis

circle plane yz plane



speed in yz plane always constant

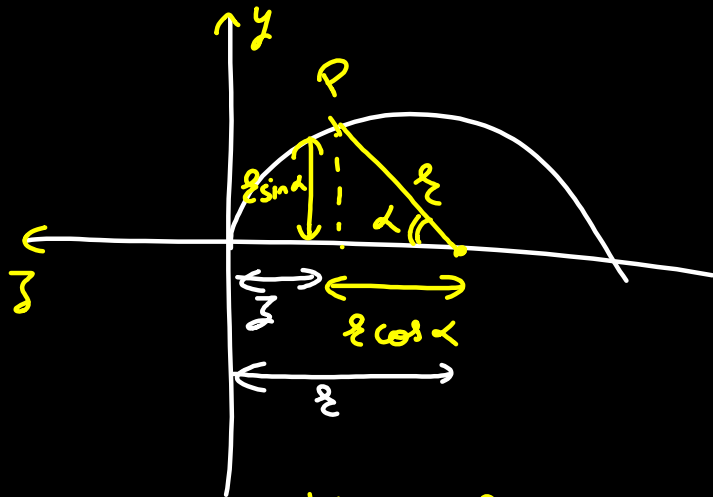
$$L = \frac{m v_{\perp}}{q B}$$

$$\theta_{rotated} = \omega t$$

$$\alpha = \frac{q B}{m} t$$

$$v' = v \sin \theta$$

$$\sqrt{v_y^2 + v_z^2} = v \sin \theta$$



$$y \text{ coordinate} = r \sin \alpha$$

$$z = - (r - r \cos \alpha)$$

Coordinate

$$= \frac{mv_{\perp}}{QB} \sin(\omega t)$$

X axis

$$\begin{aligned} &\longrightarrow v \cos \theta \\ &\longrightarrow QE \end{aligned}$$

$$s = vt + \frac{1}{2} at^2$$

$$x = (v_{||} t) + \frac{1}{2} \left(\frac{QE}{m} \right) t^2$$

$\vec{E} = E_0 \hat{i}$
 $\vec{B} = B_0 \hat{i}$
 initial vel = $v_0 \hat{j}$

Find time when speed of particle becomes $2v_0$.

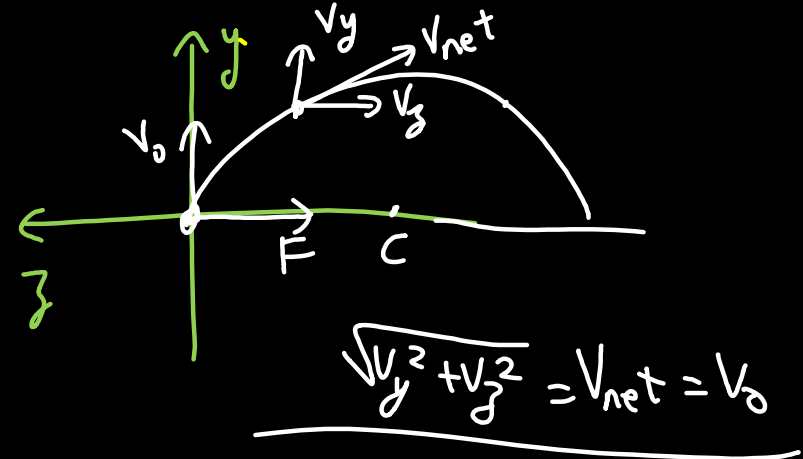
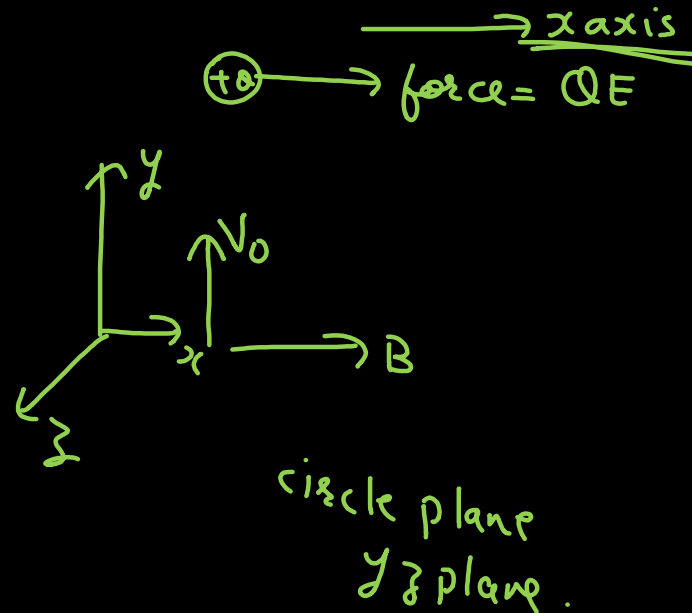
$\textcircled{+Q}$ is projected from origin

a) $\frac{mv_0}{QE}$

b) $\frac{2mv_0}{QE}$

c) $\frac{mv_0}{2QE}$

d) $\frac{\sqrt{3}mv_0}{QE}$



$$V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$$

$$\text{Speed} = \sqrt{V_x^2 + V_y^2 + V_z^2}$$

$$(2V_0)^2 = V_x^2 + \underline{(V_y^2 + V_z^2)}$$

$$4V_0^2 = V_x^2 + V_0^2$$

$$3V_0^2 = V_x^2$$

$$\sqrt{3}V_0 = V_x$$

X axis

$$u = 0$$

$$a = \frac{QE}{m}$$

$$V = \sqrt{3}V_0$$

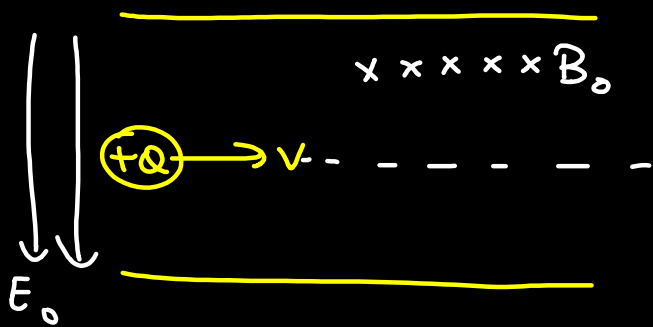
$$V = u + at$$

$$\sqrt{3}V_0 = 0 + \frac{QE}{m}t$$

$$\frac{\sqrt{3}mV_0}{QE} = t$$

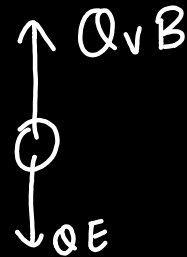
Case: Next

Velocity Selector



Particle No deflection
No change in vel.

$$\vec{F} = Q\vec{E}$$



$$F_{\text{mag}} = Q(\vec{v} \times \vec{B})$$

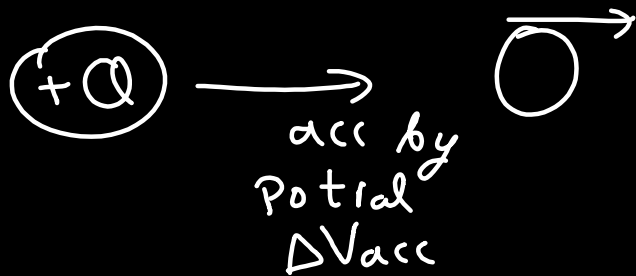
$$\text{net } F = 0$$

$$\cancel{QE} = \cancel{QvB}$$

$$E = vB$$

$$v = \frac{E}{B}$$

J. J. Thomson to find specific charge $\Rightarrow \frac{Q}{m}$



$$WD = Q(\Delta V_{acc}) \rightarrow KE$$

$$\frac{1}{2}mv^2 = Q\Delta V_{acc}$$

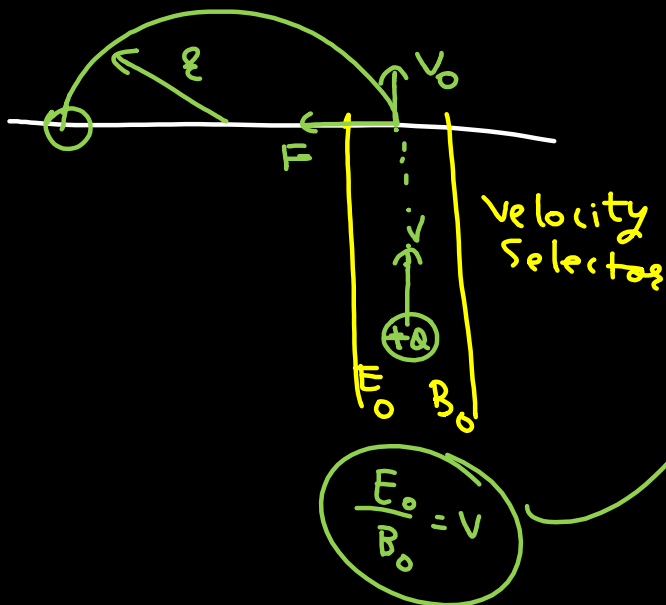
$$v = \sqrt{\frac{2Q\Delta V_{acc}}{m}}$$

$$v = \frac{E}{B}$$

$$\sqrt{\frac{2Q\Delta V_{acc}}{m}} = \frac{E}{B}$$

$$\frac{Q}{m} = \frac{E^2}{2B^2\Delta V_{acc}}$$

Mass Spectrometer



r is measured

$$r = \frac{mv}{QB_1}$$

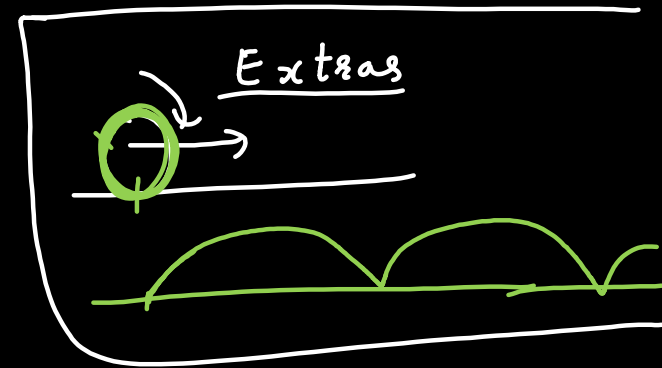
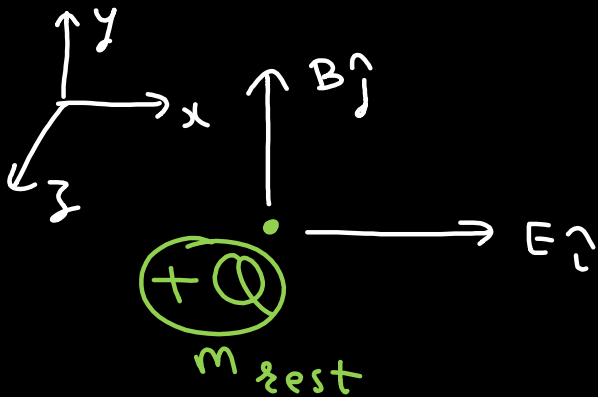
$$m = \frac{QB_1 r}{v}$$

$$m = \frac{QB_1 r B_0}{E_0}$$

Case: Next

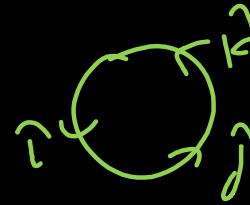
E & B are \perp 've & charge is released from rest

→ final path is cycloid



$$\vec{v}_e = v_x \hat{i} + v_z \hat{k}$$

$$\vec{F} = Q\vec{E} + Q(\vec{v} \times \vec{B})$$



$$= QE_0 \hat{i} + Q(v_x \hat{i} + v_z \hat{k}) \times (B_0 \hat{j})$$

$$= QE_0 \hat{i} + Qv_x B_0 \hat{k} + Qv_z B_0 (-\hat{i})$$

$$\vec{a}_{cc} = \frac{(QE_0 - QB_0 v_z)}{m} \hat{i} + \frac{QB_0 v_x}{m} \hat{k}$$

$$a_x = \left(\frac{qE - qBv_z}{m} \right)$$

↓ diff.

$$a_z = \frac{qB_0 v_x}{m}$$

$$\frac{da_x}{dt} = 0 - \frac{qB}{m} \frac{dv_z}{dt}$$

$$= -\frac{qB}{m^2} a_z$$

$$\frac{d^2 v_x}{dt^2} = -\frac{q^2 B^2}{m^2} v_x$$

SHM Example.

$$\frac{d^2x}{dt^2} = -\omega^2 x$$

V_x is performing SHM

$$\omega = \frac{QB}{m}$$

$$V_x = A \sin(\omega t)$$

V_x
↓ diff
 a_x

$$t=0 \quad a_x = A\omega \cos(\omega t)$$

$$a_x = A\omega \longrightarrow \frac{QE_0}{m}$$

$$A = \frac{E_0}{B_0}$$

$$V_x = \frac{E}{B} \sin(\omega t)$$

$$x = \frac{E}{B\omega} (1 - \cos \omega t)$$

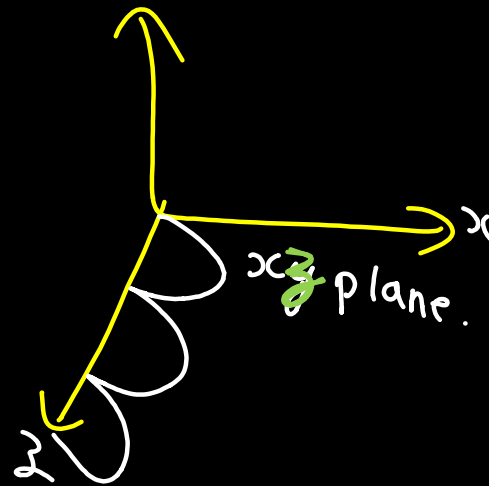
$$x = \frac{E}{B\omega} (1 - \cos \omega t)$$

$$z = \frac{E}{B\omega} (\omega t - \sin(\omega t))$$

z axis

$$V_z = \frac{E}{B} (1 - \cos \omega t)$$

$$z = \frac{E}{B\omega} (\omega t - \sin(\omega t))$$



Q More than Correct

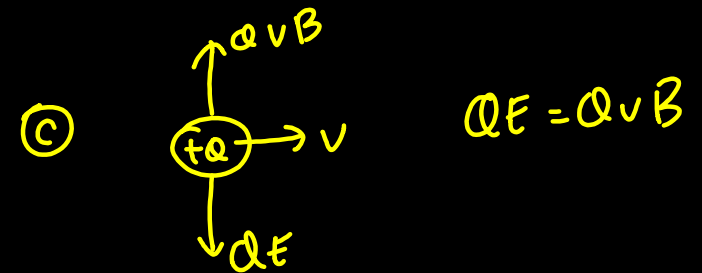
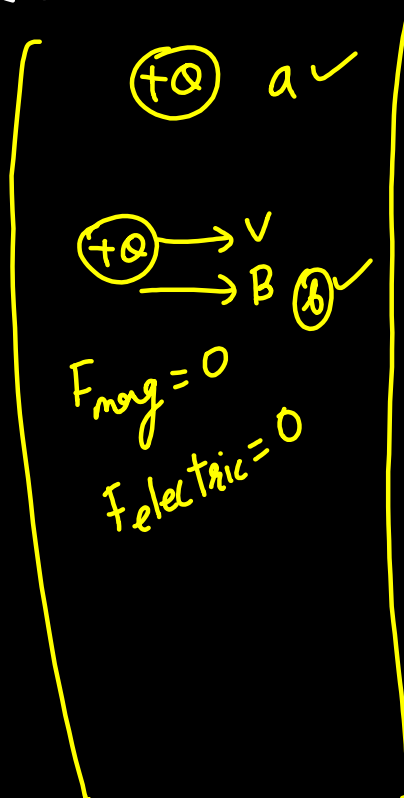
charge particle enters in gravity free space & it comes out without change in vel. \vec{E} or \vec{B} may be present which case it can be possible

~~a)~~ $E = 0$ $B = 0$

~~b)~~ $E = 0$ $B \neq 0$

~~c)~~ $E \neq 0$ $B \neq 0$

~~d)~~ $E \neq 0$ $B = 0$



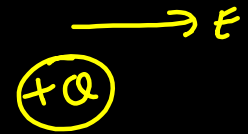
Q// charge at rest experiences Electromagnetic force

a) E must be there

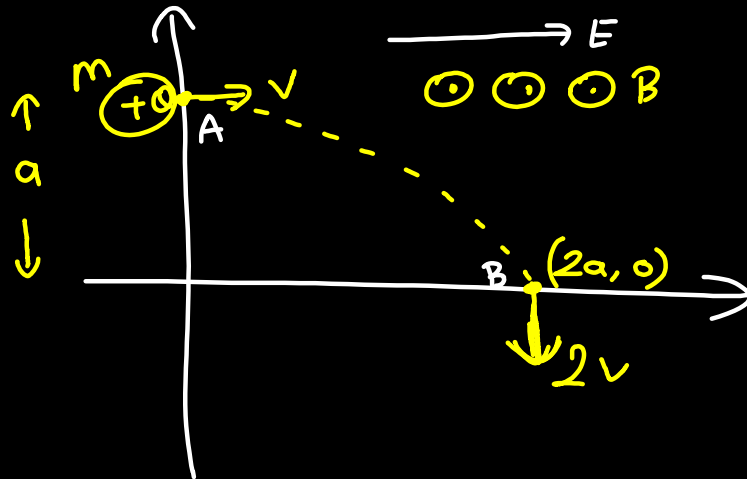
b) B must " "

c) B may or may not be there.

d) E " " " " " "



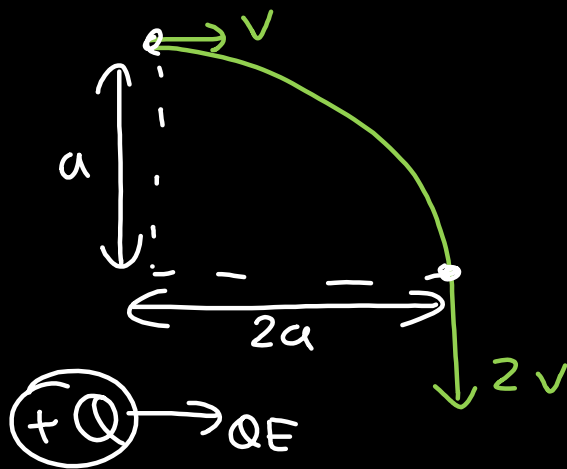
Q
See.
(gravity free)



$$\text{Power} = \vec{F} \cdot \vec{v}$$

Find

- ① E in terms of m, v, a & q
- ② Power of E at A & at B
- ③ Power of B at A & at B
(rate of WD)



$$WD_{mag} = 0$$

$$WD_{Elec} = \Delta KE$$

$$= \frac{1}{2} m (2v)^2 - \frac{1}{2} m (v)^2$$

$$(F)(displ) = \frac{3}{2} mv^2$$

$$(QE)(2a) = \frac{3}{2} mv^2$$

$$E = \frac{3 mv^2}{4 Qa}$$

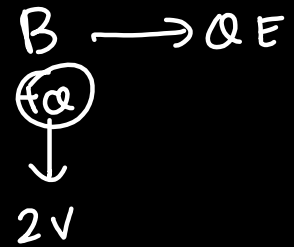
$$WD_{\text{mag}} = 0$$

$$\text{Power} = \frac{d(WD)}{dt}$$

$$\text{Power}_{\text{mag}} = 0$$



$$\text{Power}_{\text{at A}} = QE v$$



$$\text{Power}_{\text{at B}} = 0$$

Force on Current Carrying Wire in \vec{B}

$$\vec{F} = \int I \, d\vec{\ell} \times \vec{B}$$

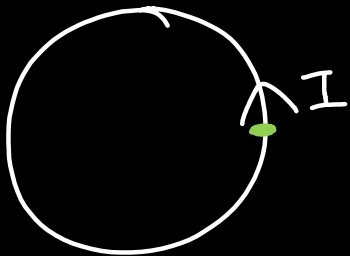
$$\vec{F} = I \vec{\ell} \times \vec{B}$$

↓
displacement
 $I \vec{\ell}$

already done
in previous
lecture.

Closed loop in uniform \vec{B}

$\Rightarrow \vec{B}$



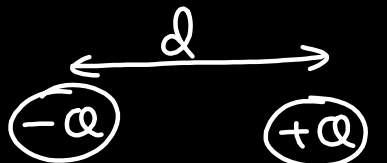
$$F_{\text{net}} = 0$$

$$\vec{\tau} = \vec{M} \times \vec{B}$$

↓

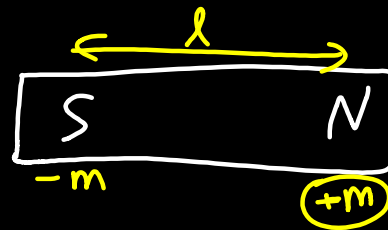
Torque on loop

\vec{M} (magnetic dipole moment)



$$\vec{P} = Q(d)$$

(-ve to +ve)



$$\vec{M} = (+m) l$$

$$m = \text{pole strength}$$

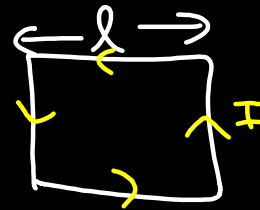
\vec{M} of a Current Carrying Loop

$$\vec{M} = I (\vec{\text{area}})$$

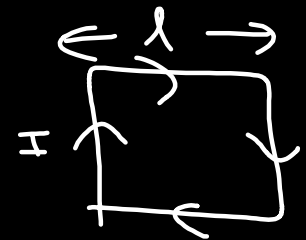
N turns

$$\vec{M} = N I (\vec{\text{area}})$$

$\vec{\text{area}}$ $\begin{cases} \text{magnitude area} \\ \text{direction} \\ \perp \text{ to plane} \\ \text{of loop} \end{cases}$



$$\vec{M} = I l^2 (+\hat{k})$$



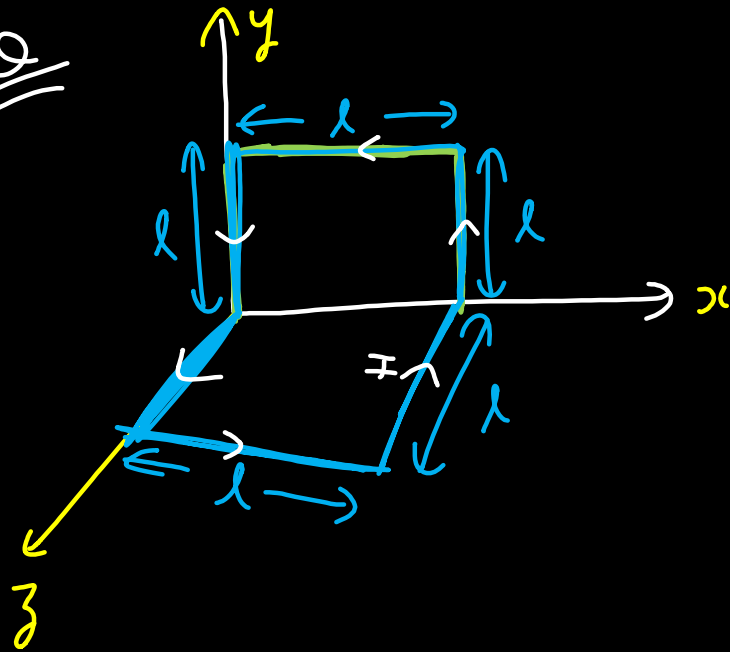
$$\vec{M} = I l^2 (-\hat{k})$$



100 turns

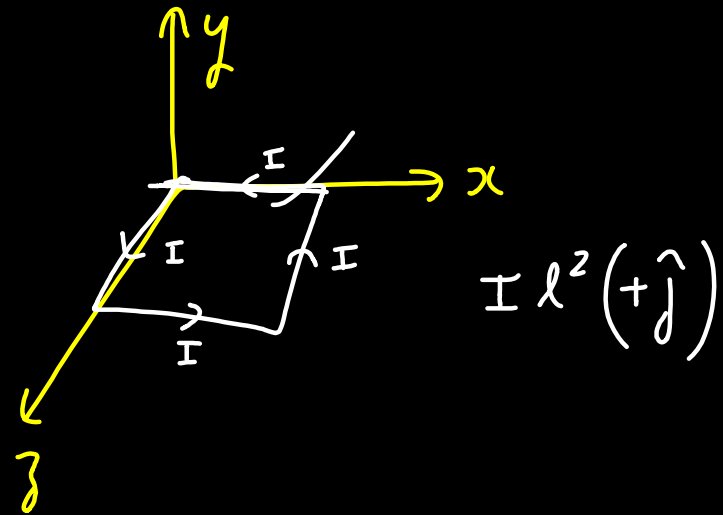
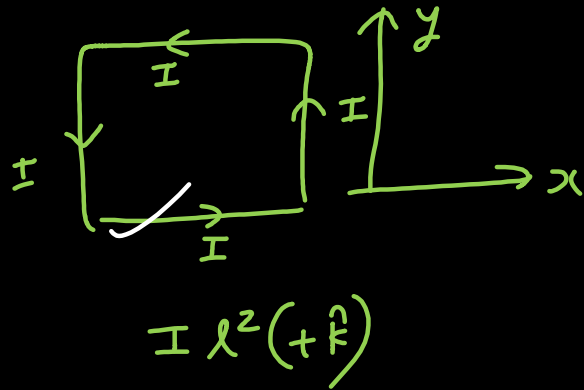
$$\vec{M} = (I \pi r^2) (100) (+\hat{k})$$

Q



$$\vec{M} =$$

\vec{H} assume
 \vec{H}

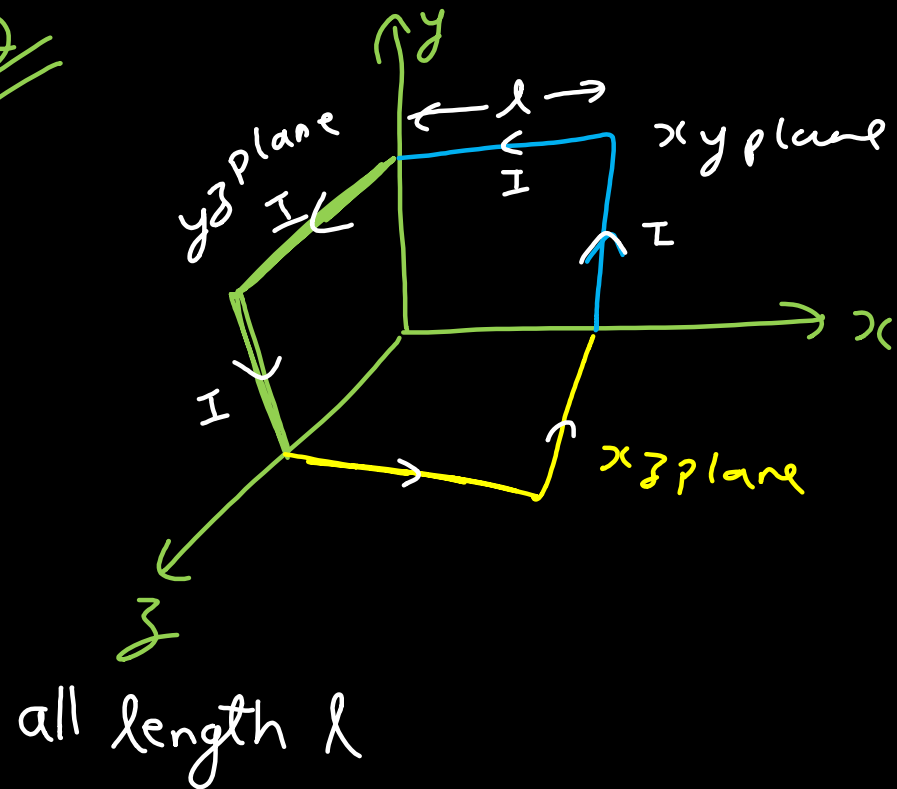


$$\vec{M} = I \ell^2 (+\hat{k} + \hat{j})$$

$$|M| = I \ell^2 \sqrt{1^2 + 1^2}$$

$$= \sqrt{2} I \ell^2$$

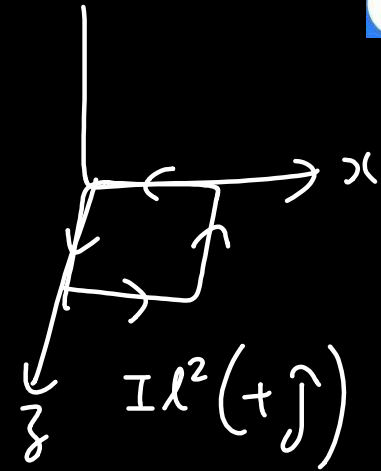
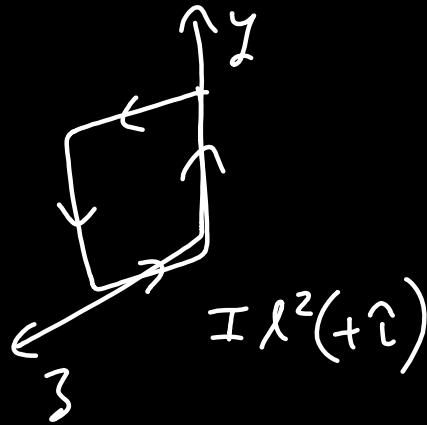
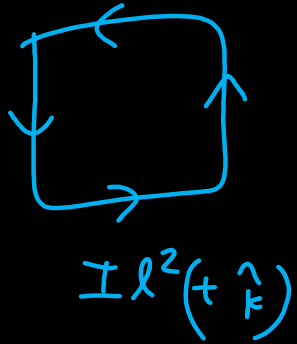
Q //



$$xy \text{ plane } \vec{M} + \hat{k} \text{ or } -\hat{k}$$

$$yz \text{ " } \vec{M} + \hat{i} \text{ or } -\hat{i}$$

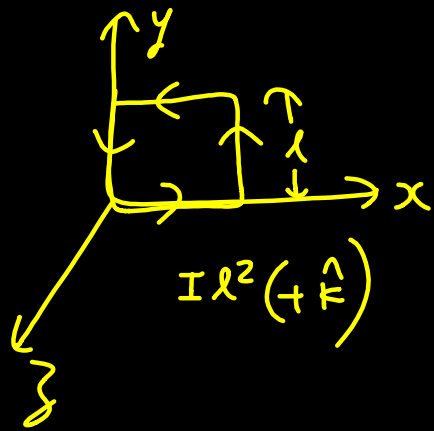
$$xz \text{ " } \vec{M} + \hat{j} \text{ or } -\hat{j}$$



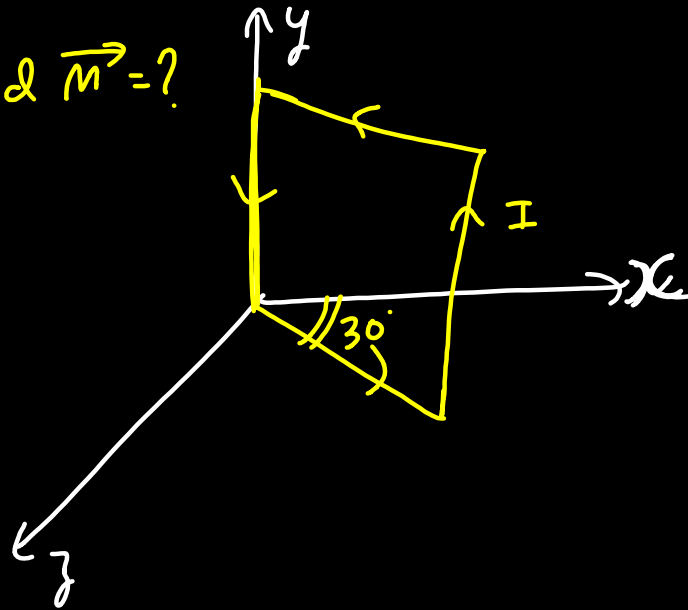
$$\vec{M} = I\lambda^2(\hat{i} + \hat{j} + \hat{k})$$

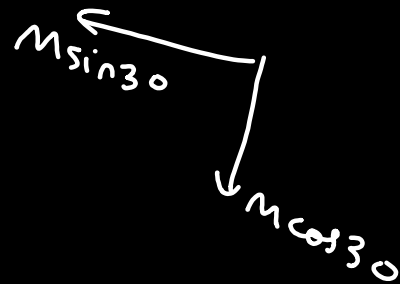
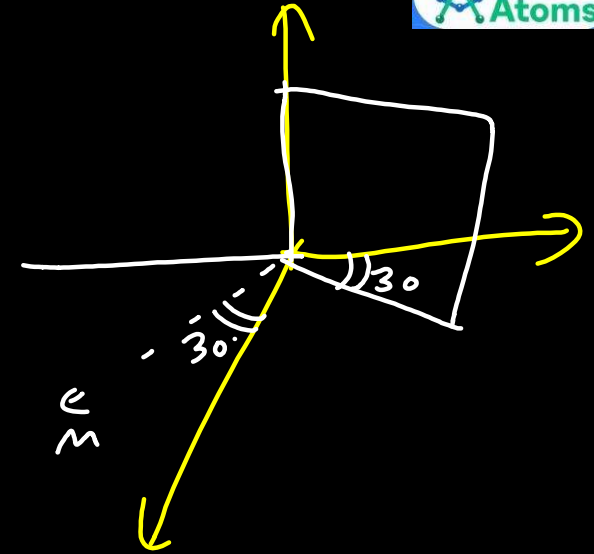
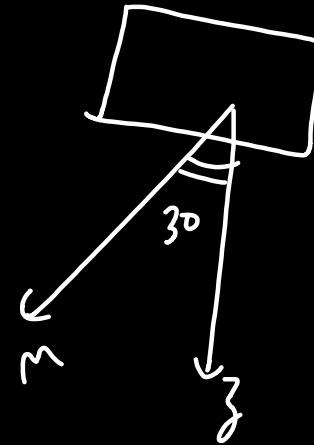
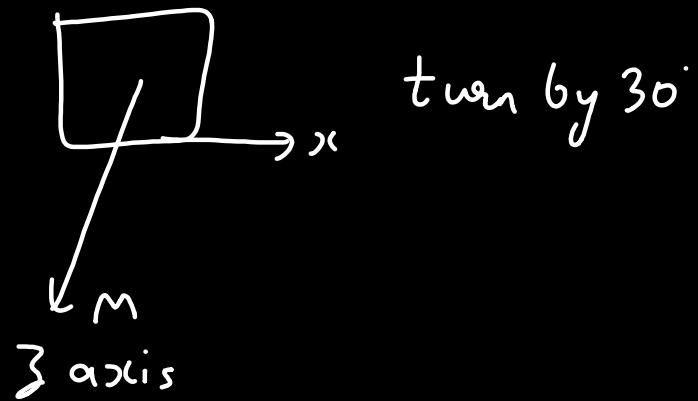
$$|M| = \sqrt{3} I\lambda^2$$

rotating the plane



Find $\vec{M} = ?$





$$I l^2 \cos 30^\circ \hat{k} + I l^2 \sin 30^\circ (-\hat{j})$$

$$\vec{M} = I l^2 \left(-\frac{1}{2} \hat{j} + \frac{\sqrt{3}}{2} \hat{k} \right)$$

Torque on Current Carrying due to $\vec{B}_{\text{external}}$

$$\vec{\tau} = \vec{M} \times \vec{B}$$

Sense of Rotation

\vec{M} wants align along \vec{B}

when $\tau = 0$ rotational equilibrium

0 $\begin{array}{c} \longrightarrow M \\ \longrightarrow B \end{array} \quad \tau = 0$

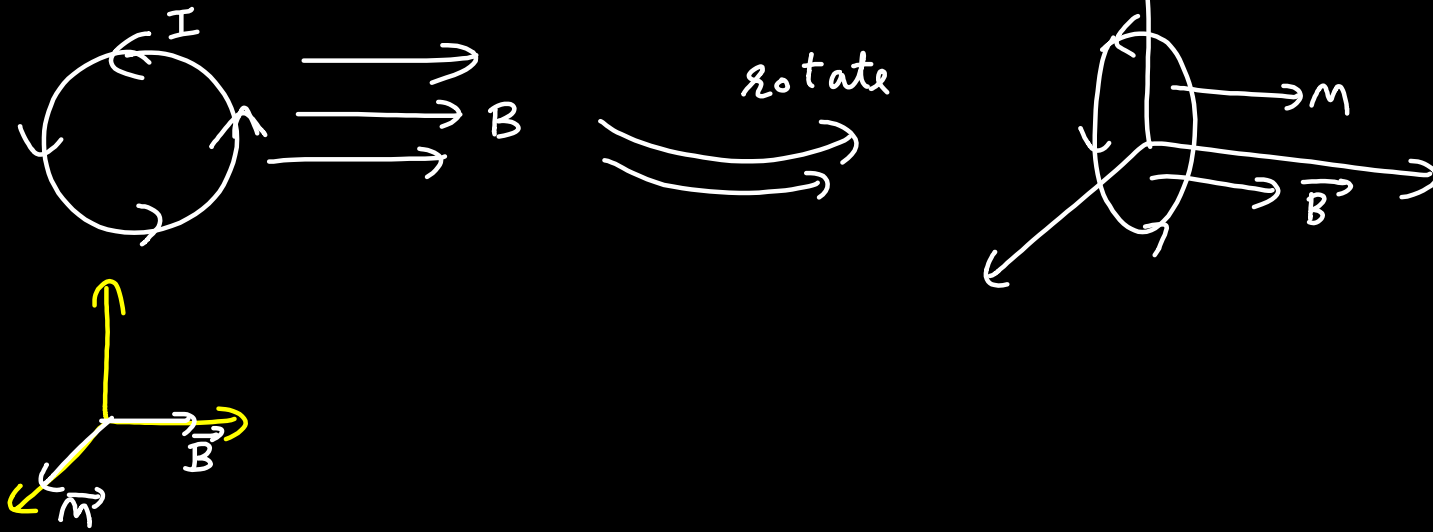
Stable
Equilibrium.

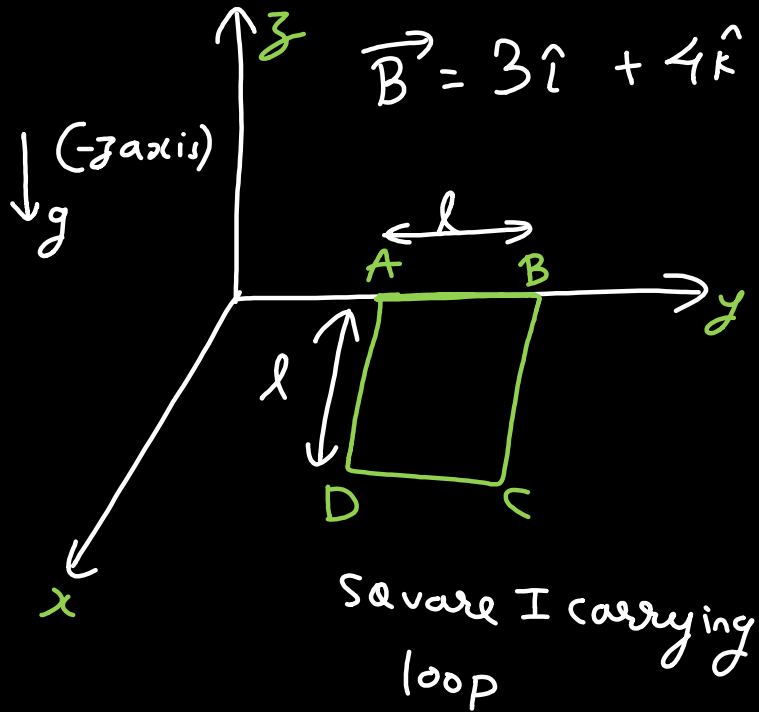
0 $\begin{array}{c} \longrightarrow B \\ \longleftarrow M \end{array} \quad \tau = 0$

Unstable
Equilibrium.

0 $\begin{array}{c} \nearrow M \\ \parallel \theta \longrightarrow B \end{array} \quad \tau = MB \sin \theta$

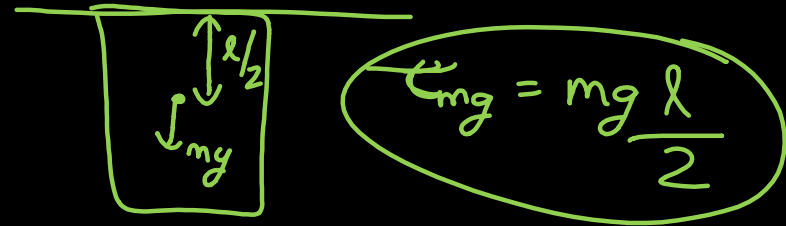
CW torque



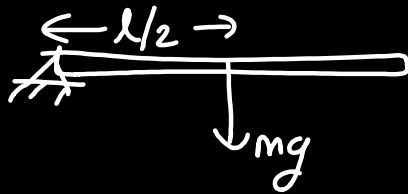


AB is hinged

Find I in loop such that it stays in equilibrium??



Torque = (force) (⊥ distance)



$$\tau = mg \frac{l}{2}$$

$$\vec{\tau} = \vec{M} \times \vec{B}$$

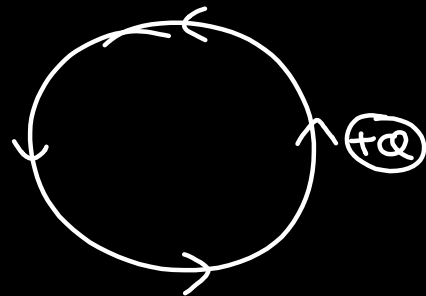
$$= I l^2 (\hat{k}) \times (3\hat{i} + 4\hat{k})$$

$$= \underline{\underline{I l^2 (3) (\hat{j})}}$$

$$mg \frac{l}{2} = I l^2 (3)$$

$$\frac{mg}{6l} = I$$

\vec{M} of charge rotating



U.C.M.
Speed Constant

$$\vec{M} = I \vec{\text{area}}$$

$$I = \frac{Q}{T} = Qf$$

$$I = \frac{Qv}{2\pi r}$$

$$M = I \pi r^2$$

$$= \frac{Qv}{2\pi r} \pi r^2$$

$$M = \frac{Qvr}{2}$$

$$T = \frac{2\pi r}{v} = \frac{2\pi}{\omega}$$

$$f = \frac{1}{T}$$

angular momentum $L = mv_z$

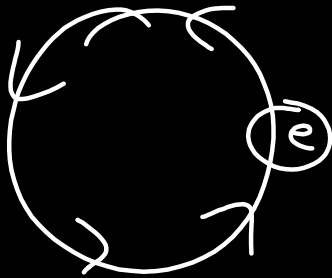
$L = I\omega$ for body



$$\frac{M}{L} = \frac{Qv_z/2}{mv_z}$$

$$\boxed{\frac{M}{L} = \frac{Q}{2m}}$$

also Bohr Model can be included



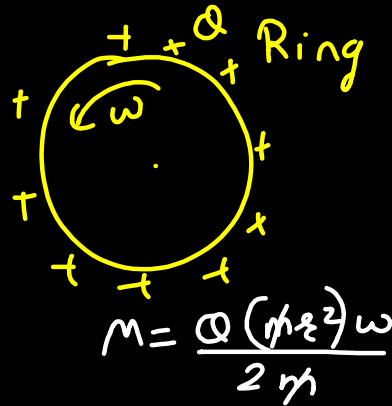
$$\frac{mv^2}{r} = \frac{kq_1q_2}{r^2}$$

$$mvr = \frac{nh}{2\pi}$$

$$\frac{M}{L} = \frac{Q}{2m}$$

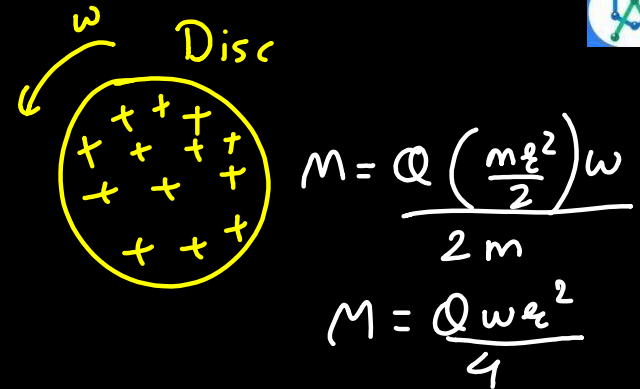
Body
I ω

Ring



$$M = \frac{Q \left(\frac{m r^2}{2} \right) \omega}{2 m}$$

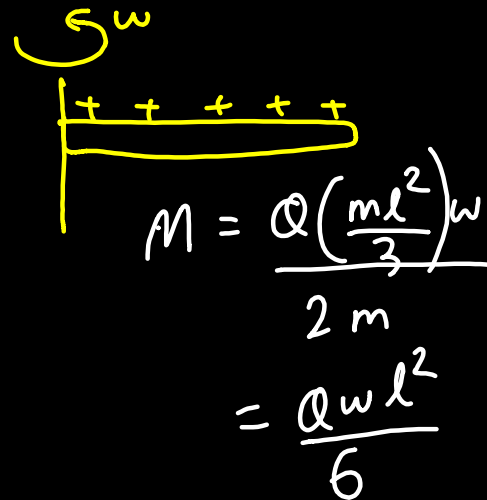
Disc



$$M = \frac{Q \left(\frac{m r^2}{2} \right) \omega}{2 m}$$

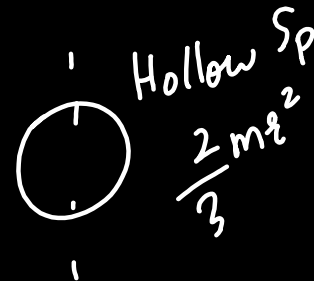
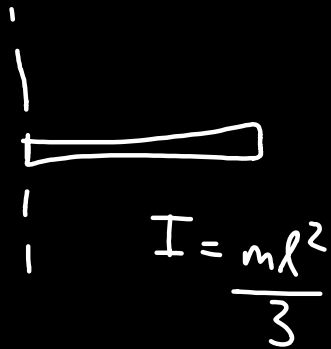
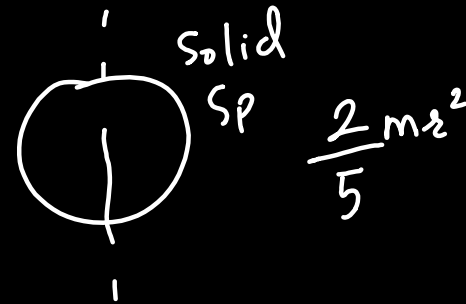
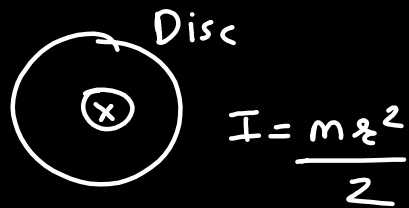
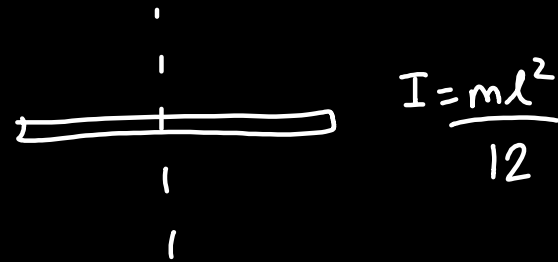
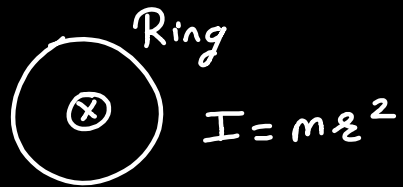
$$M = \frac{Q \omega r^2}{4}$$

Bar



$$M = \frac{Q \left(\frac{m l^2}{3} \right) \omega}{2 m}$$

$$= \frac{Q \omega l^2}{6}$$



Moving Coil Galvanometer

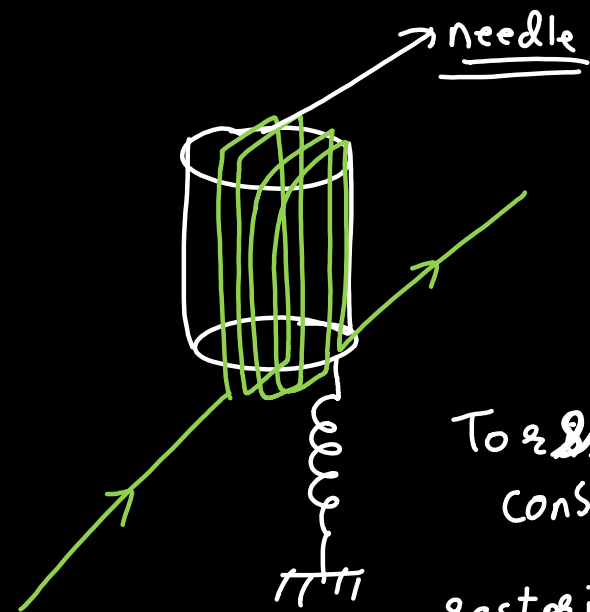


Top view

$$\underline{|M| = N I A}$$

$$\tau = M B \sin \theta$$

M & B are always cross to each other $\theta = 90^\circ$



Torsional
constant = K

$$\text{Restoring Torque} = K \theta$$

Concept \rightarrow magnetic Torque
 $\theta = 90^\circ$

$$\tau = MB$$

$$\tau = N I A B$$

needle equilibrium

$$\tau_{\text{mag}} = \tau_{\text{sp}}$$

$$N I A B = k \theta$$

$$\left(\frac{\text{radian}}{\text{Ampere}} \right) \text{ or } \left(\frac{\text{degree}}{\text{Ampere}} \right)$$

$$\frac{\theta}{I} = \frac{N A B}{k}$$

\rightarrow Current sensitivity

$$\frac{\theta}{I} \quad \begin{array}{l} \Delta V = I R \\ \frac{V}{R} = I \end{array}$$

$$\frac{\theta}{V} R = \frac{N A B}{k}$$

$$\frac{\theta}{\Delta \text{Voltage}} = \frac{N A B}{k R}$$

\rightarrow Voltage

"

$$\# \frac{\theta}{I} = \frac{NAB}{k}$$

N is doubled

current sensitivity double

$$\# \frac{\theta}{\Delta \text{Voltage}} = \frac{NAB}{k \underline{R}}$$

Voltage sensitivity remains same.

$$R = \frac{\rho l}{A}$$

R → resistance.

N double

R double

$$\frac{2}{2} = 1$$

A galvanometer is used in laboratory for detecting the null point in electrical experiments. If, on passing a current of 6 mA it produces a deflection of 2° , its figure of merit is close to :
[Sep. 05, 2020 (II)]

- (a) 333° A/div. (b) $6 \times 10^{-3} \text{ A/div.}$
(c) 666° A/div. (d) $3 \times 10^{-3} \text{ A/div.}$

$$I = 6 \text{ mA} \quad \theta = 2^\circ$$

figure of merit

$$\frac{I}{\theta} = \text{current per division} \Rightarrow \text{figure of merit}$$

$$\frac{6 \text{ mA}}{2^\circ} = 3 \times 10^{-3} \frac{\text{A}}{\text{div.}}$$

A galvanometer coil has 500 turns and each turn has an average area of $3 \times 10^{-4} \text{ m}^2$. If a torque of 1.5 Nm is required to keep this coil parallel to a magnetic field when a current of 0.5 A is flowing through it, the strength of the field (in T) is _____.

[NA Sep. 03, 2020 (II)]

$$N = 500$$

$$A = 3 \times 10^{-4}$$

$$I = 0.5$$

$$\tau = 1.5$$

$$B = ?$$

$$\tau = MB$$

$$\tau = NIA B$$

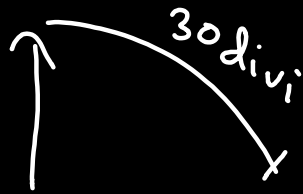
$$B = 20 \text{ T}$$

A galvanometer having a resistance of $20\ \Omega$ and 30 division on both sides has figure of merit 0.005 ampere/division. The resistance that should be connected in series such that it can be used as a voltmeter upto 15 volt, is:

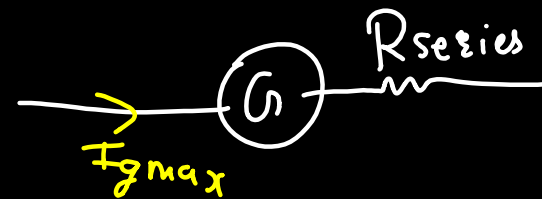
[11 Jan 2019, II]

- (a) $100\ \Omega$ (b) $120\ \Omega$ (c) $80\ \Omega$ (d) $125\ \Omega$

$$R_{gal} = 20\ \Omega$$



$$I_{gmax} = 0.15$$



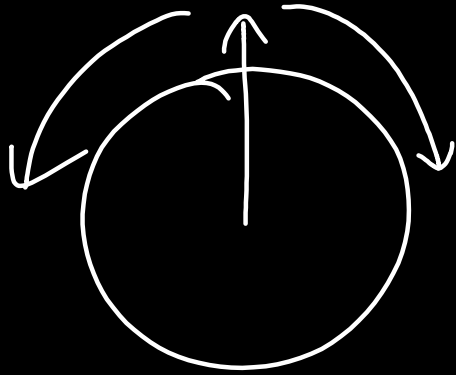
$$I_g (G + R_{series}) = 15$$

$$30 \times \frac{5}{1000}$$

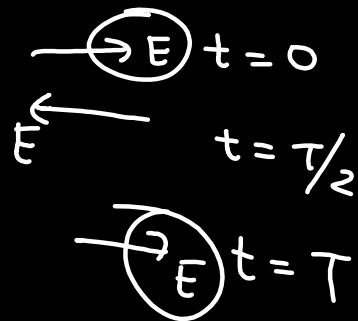
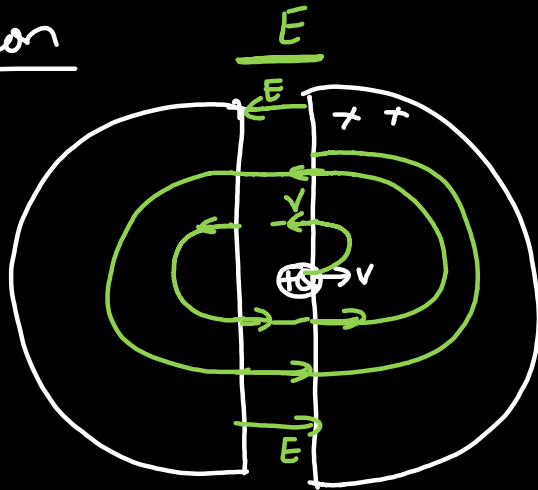
$$0.005\ I\ \text{in}\ 1\ \text{div}$$

$$30(0.005)\ I\ \text{in}\ 30\ \text{div}$$

$$0.15\ A\ \text{in}\ 30\ \text{div}$$



Cyclotron



Particle accelerator

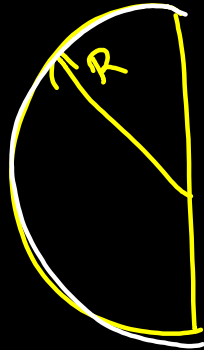
$$\text{Time} = \frac{2\pi m}{QB}$$

$$\text{freq} = \frac{QB}{2\pi m} \quad \left(\frac{1}{T} \right)$$

$$\text{freq of cyclotron} = \text{freq of oscillation of } E = \text{freq of charged particle (circle)}$$

$$f e Q = \frac{Q B}{2 \pi m}$$

max speed / max KE



$$e = \frac{m v}{Q B}$$

$$v = \frac{Q B e}{m}$$

$$\frac{Q B R_{\max}}{m} = v_{\max}$$

$$KE_{\max} = \frac{1}{2} m v^2 = \frac{1}{2} m \frac{Q^2 B^2 R^2}{m^2}$$

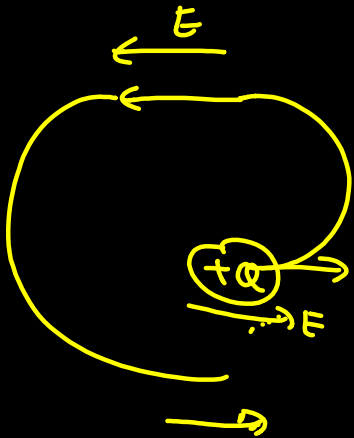
$$KE_{\max} = \frac{Q^2 B^2 R^2}{2 m}$$

Cannot be used for neutron & electron

→ small size
speed up very fast


$$m' = \frac{m_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$T_{\text{time}} = \frac{2\pi m}{Q\mathcal{B}}$$



Revision Electrostatics Dipole

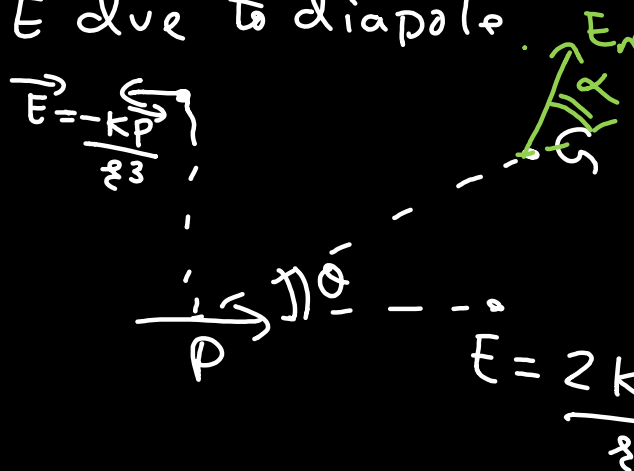
#



$$\vec{P} = Q(2a)$$

-ve to +ve

E due to dipole




$$\vec{E} = -\frac{kP}{r^3}$$

$$\vec{E} = \frac{2kP}{r^3}$$

$$E = \frac{kP}{r^3} \sqrt{1+3\cos^2\theta}$$

$$\tan\alpha = \frac{\tan\theta}{2}$$

τ on dipole in E_{ext}



$$\vec{\tau} = \vec{P} \times \vec{E}$$

$$\tau = PE \sin\theta$$

Small oscillation

$$Time = 2\pi \sqrt{\frac{I}{PE}}$$

Force on dipole in uniform $E = 0$

Pot. Energy of dipole = $-\vec{p} \cdot \vec{E}$

WD on " = ΔU (change in Pot. energy.)

F on dipole in non uniform $E = \vec{p} \cdot \frac{d\vec{E}}{dx}$

analogy

Electric

$$K = \frac{1}{4\pi\epsilon_0}$$

Q charge

\vec{P}

E

Magnetic

$$\frac{\mu_0}{4\pi}$$

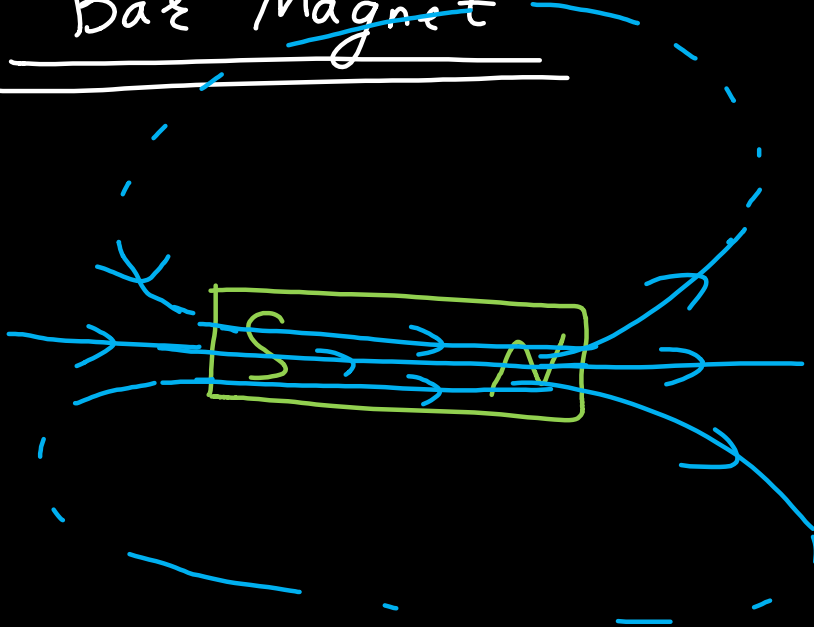
m (pole strength)

\vec{M}

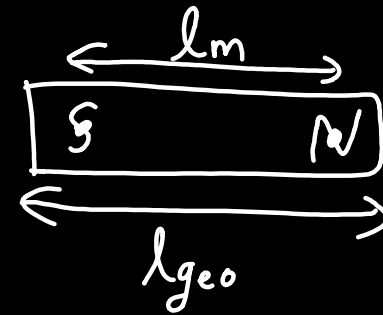
B

$$\epsilon_0 \rightarrow \frac{1}{\mu_0}$$

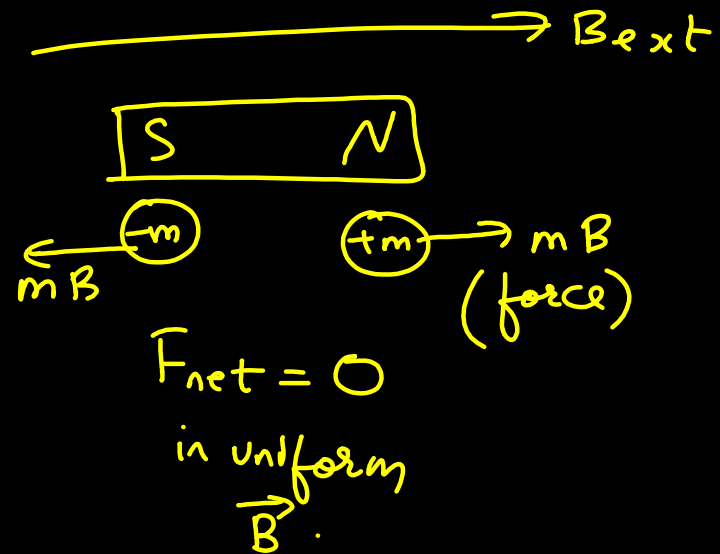
Bar Magnet



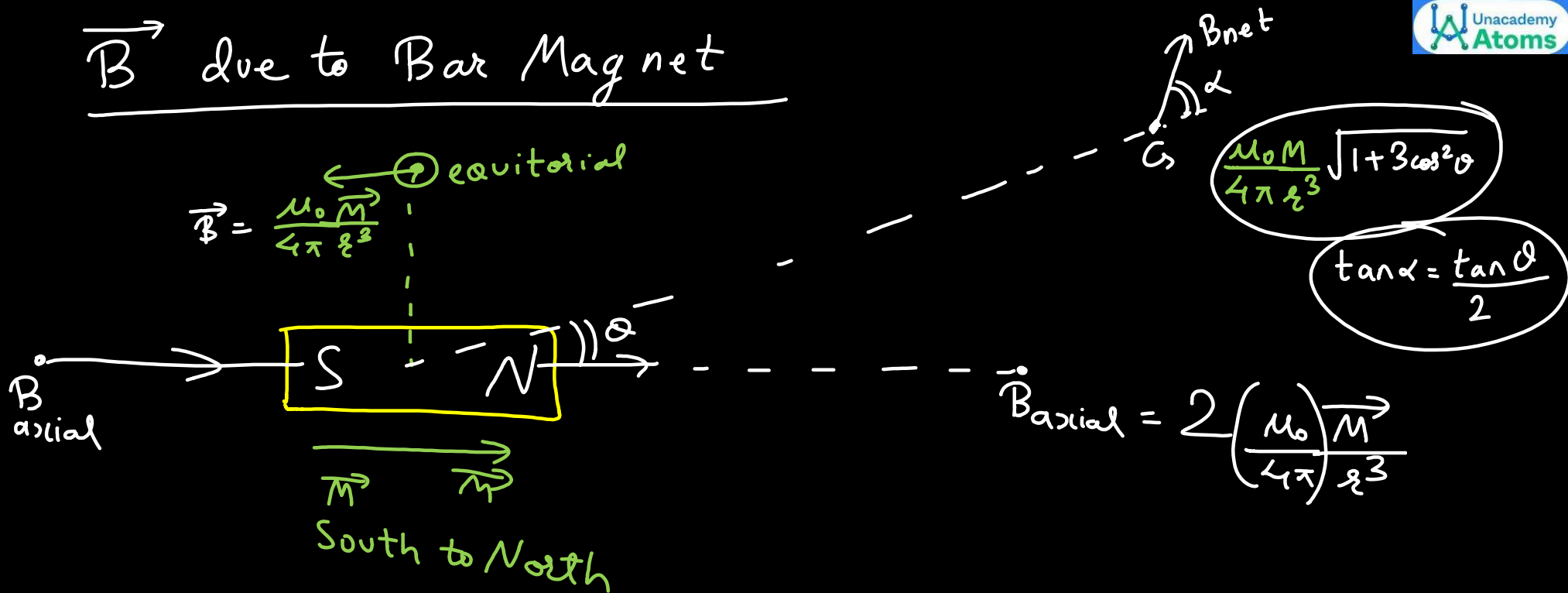
$$\vec{M} = (m) (l_m)$$



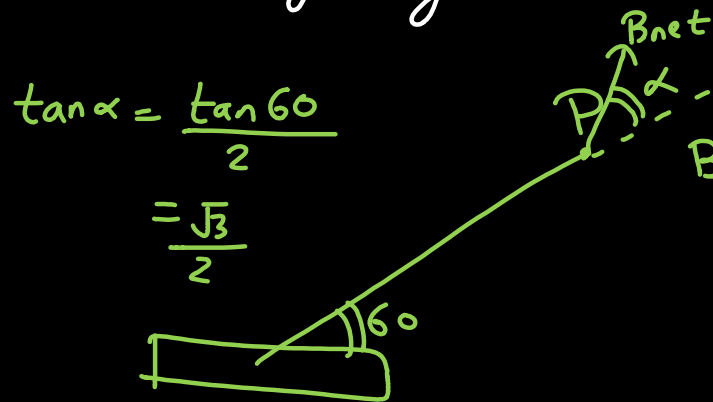
$$\frac{l_m}{l_{geo}} \approx 0.84$$



\vec{B} due to Bar Magnet



Q Find B due to dipole magnetic moment = 1.2 Am^2 at a point 1m away from it in a direction making angle 60° with dipole axis.



$$\tan \alpha = \frac{\tan 60}{2}$$

$$= \frac{\sqrt{3}}{2}$$

$$\alpha = \tan^{-1}\left(\frac{\sqrt{3}}{2}\right)$$

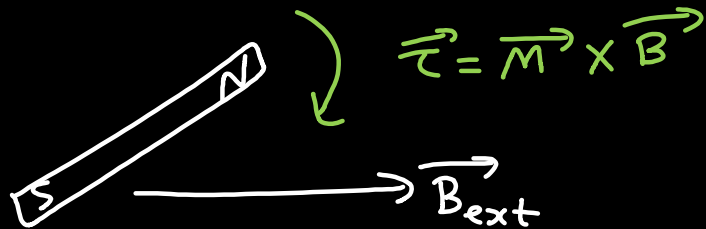
$$B = \frac{\mu_0 M}{4\pi r^3} \sqrt{1 + 3\cos^2\theta}$$

$$= \frac{10^{-7} \times 1.2}{(1)^3} \sqrt{1 + 3\left(\frac{1}{4}\right)}$$

$$= \frac{1.2 \times 10^{-7}}{2} \sqrt{2} = \underline{\underline{\sqrt{2} \times 0.6 \times 10^{-7} \text{ T}}}$$



\vec{M} wants to align along \vec{B}



released from rest
small angle oscillation

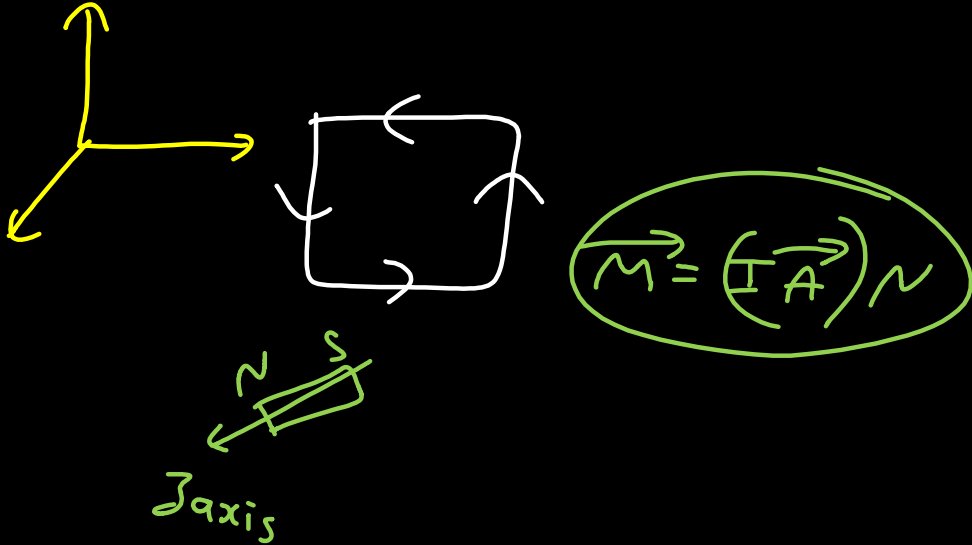
$$T = 2\pi \sqrt{\frac{I}{MB}}$$

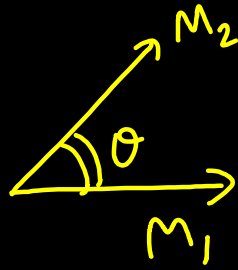
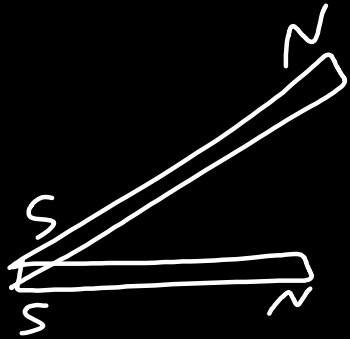
$$U = - \vec{M} \cdot \vec{B}$$

$$W_{\text{ext}} = \Delta U$$

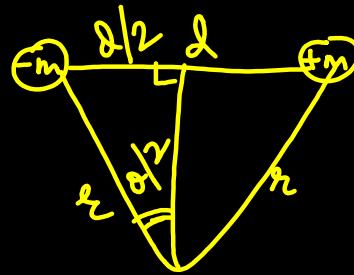
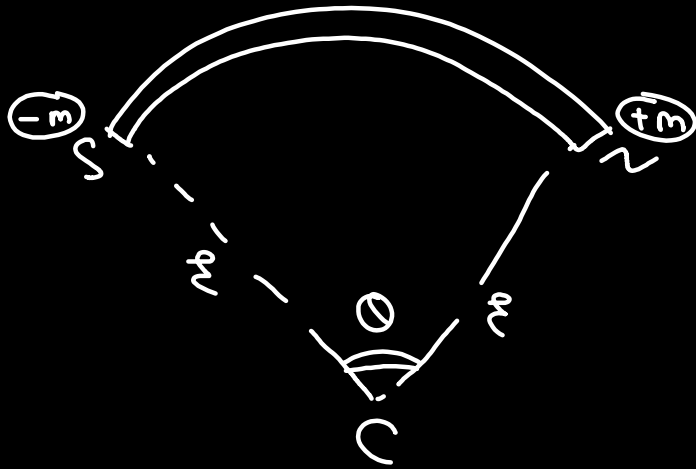
Force on bar magnet in non uniform $B = \vec{M} \cdot \frac{d\vec{B}}{dx}$.

Current Carrying loop can be treated as a bar Magnet



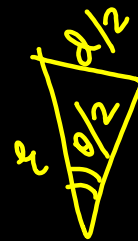


$$M_{\text{net}} = \sqrt{M_1^2 + M_2^2 + 2M_1M_2 \cos \theta}$$



$$M = md$$

$$M = m \left(2r \sin \left(\frac{\theta}{2} \right) \right)$$



$$\sin \frac{\theta}{2} = \frac{d/2}{r}$$

$$2r \sin \frac{\theta}{2} = d$$

Magnetisation



created field

Vacuum

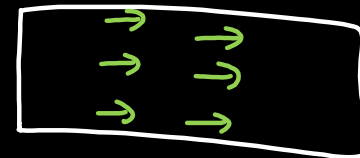
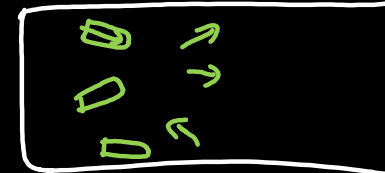
$$\vec{H} = \frac{\vec{B}}{\mu_0}$$

↓
magnetising
field

unit of $H \Rightarrow \text{A/m}$

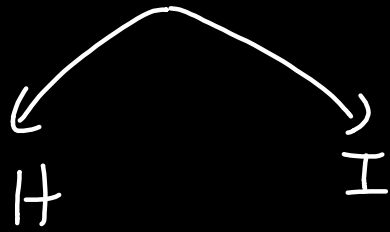
$$\vec{B} = \mu_0 \vec{H}$$

→ B_{ext}



$$B_{\text{net inside}} = B_{\text{ext}} + B_{\text{induced}}$$

Unit A/m



B unit (T)

I (intensity of magnetisation)

$$I = \frac{M}{\text{Volume}}$$

(magnetic moment induced)

unit of $I \rightarrow A/m$

$$B_{\text{induced}} = \mu_0 I$$

ext

$$B_{\text{ext}} = \mu_0 H$$

$$B_{\text{induced}} = \mu_0 I$$

$$B_{\text{net}} = \mu_0 H + \mu_0 I$$

$$B_{\text{net}} = \mu_0 (H + I)$$



$$\mu_0 \xrightarrow{\text{vacuum}} \mu_0 \mu_r \text{ medium}$$

$$B = \mu_0 H \text{ vacuum}$$

$$B_{\text{net}} = \mu_0 \mu_r H \text{ medium}$$

$$B_{\text{net}} = B_{\text{net}}$$

$$\mu_0 \mu_r H = \mu_0 (H + I)$$

$$\mu_r = \left(\frac{H + I}{H} \right)$$

$$\mu_r = 1 + \frac{I}{H}$$

$$\mu_r = 1 + \chi$$

$$\frac{I}{H} = \chi \text{ susceptibility}$$

$$B_{\text{ext}} = \mu_0 H$$

$$B_{\text{induced}} = \mu_0 I$$

$$B_{\text{net inside}} = \mu_0 (H + I)$$

$$B_{\text{net inside}} = \mu_0 \mu_r H$$

$$\mu_r = 1 + \chi$$

$$\chi = \frac{I}{H}$$

→ Magnetic susceptibility

$$\text{magnetisation} \propto \frac{B}{\text{Temp}}$$

$$B_{\text{ext}} = 1$$

$$B_{\text{int}} = 1.2$$

χ less

Paramagnet

$$B_{\text{int}} = \text{very high}$$

χ more

Ferro magnet

$$B_{\text{ext}} = 1$$

$$B_{\text{ind}} = 0.9$$

χ - ve small

Dimagnetic

$$\longrightarrow B_{\text{ext}}$$

$$\longleftarrow B_{\text{ind}}$$

$$B_{\text{net}} = B_{\text{ext}} - B_{\text{induced}}$$

$$B_{\text{ext}} = \mu_0 H$$

↙
magnetic
field

↘ magnetising
A/m field.

①

$$B_{\text{induced}} = \mu_0 I$$

$$B_{\text{net}} = \mu_0 (H + I)$$

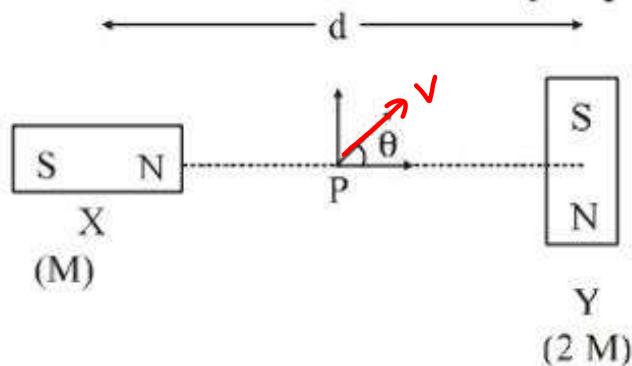
$$B_{\text{net}} = \mu_0 \mu_r H$$

$$\mu_r = 1 + \chi$$

$$\chi = \frac{I}{H}$$

Two magnetic dipoles X and Y are placed at a separation d , with their axes perpendicular to each other. The dipole moment of Y is twice that of X. A particle of charge q is passing through their midpoint P, at angle $\theta = 45^\circ$ with the horizontal line, as shown in figure. What would be the magnitude of force on the particle at that instant? (d is much larger than the dimensions of the dipole)

[8 April 2019 II]



(a) $\left(\frac{\mu_0}{4\pi}\right) \frac{M}{(d/2)^3} \times qv$ (b) 0

(c) $\sqrt{2} \left(\frac{\mu_0}{4\pi}\right) \frac{M}{(d/2)^3} \times qv$ (d) $\left(\frac{\mu_0}{4\pi}\right) \frac{2M}{(d/2)^3} \times qv$

Handwritten notes on a blackboard background:

- A horizontal arrow pointing right, labeled M .
- A vector diagram showing a horizontal vector $\frac{\mu_0 2M}{4\pi r^3}$ and a vertical vector $\frac{\mu_0 (2M)}{4\pi r^3}$ pointing upwards.
- A vertical arrow pointing down, labeled $2M$.
- A vector \vec{v} pointing up and to the right.
- A vector \vec{B}_{net} pointing up and to the right, parallel to \vec{v} .
- The equation $\vec{F} = q \vec{v} \times \vec{B}$ is written, followed by $= 0$.

A magnet of total magnetic moment $10^{-2} \hat{i}$ A-m² is placed in a time varying magnetic field, $B \hat{i} (\cos \omega t)$ where $B = 1$ Tesla and $\omega = 0.125$ rad/s. The work done for reversing the direction of the magnetic moment at $t = 1$ second, is: [10 Jan. 2019 I]

- | | |
|-------------|-------------|
| (a) 0.01 J | (b) 0.007 J |
| (c) 0.028 J | (d) 0.014 J |

$$\vec{M} = 10^{-2} \hat{i}$$

$$B = B \cos(\omega t) \hat{i}$$

H.W.

at $t = 1$

$$U = -\vec{M} \cdot \vec{B}$$

WD

$$U_{\text{ini}} = -MB \cos \alpha$$

$$U_{\text{ini}} = -MB \cos 0 \\ = -MB$$

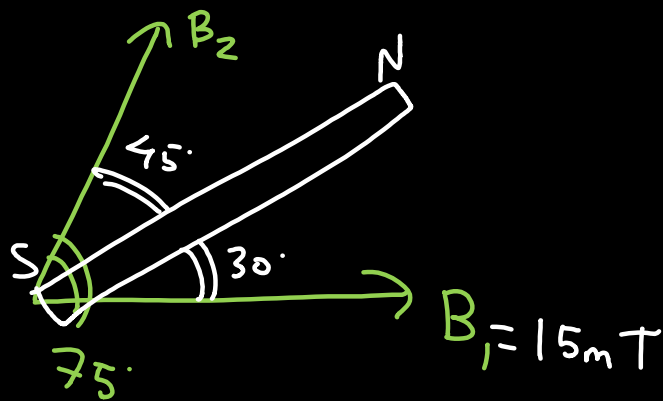
$$U_{\text{final}} = -MB \cos 180^\circ \\ = \underline{\underline{+MB}}$$

$$\Delta U = W_{\text{Dext}}$$

A magnetic dipole is acted upon by two magnetic fields which are inclined to each other at an angle of 75° . One of the fields has a magnitude of 15 mT. The dipole attains stable equilibrium at an angle of 30° with this field. The magnitude of the other field (in mT) is close to :

[Online April 9, 2016]

- (a) 1 (b) 11 (c) 36 (d) 1060



$$\mu B_1 \sin 30 = \mu B_2 \sin 45$$

$$15 \frac{1}{2} = B_2 \frac{1}{\sqrt{2}}$$

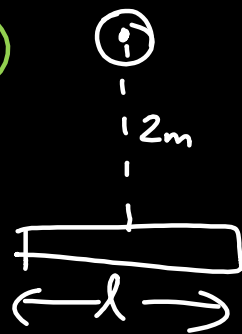
$$\frac{15}{\sqrt{2}} = B_2$$

$$11 \text{ mT} \approx B_2$$

A bar magnet of length 6 cm has a magnetic moment of 4 J T^{-1} . Find the strength of magnetic field at a distance of 200 cm from the centre of the magnet along its equatorial line. **[Online May 7, 2012]**

- (a) 4×10^{-8} tesla (b) 3.5×10^{-8} tesla
(c) 5×10^{-8} tesla (d) 3×10^{-8} tesla

H.W.



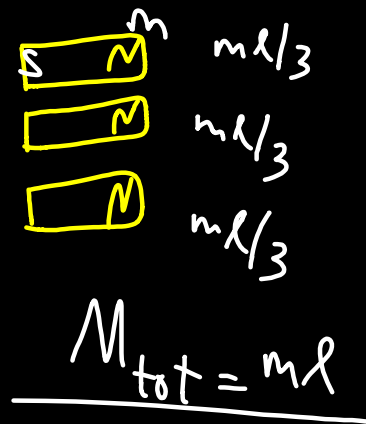
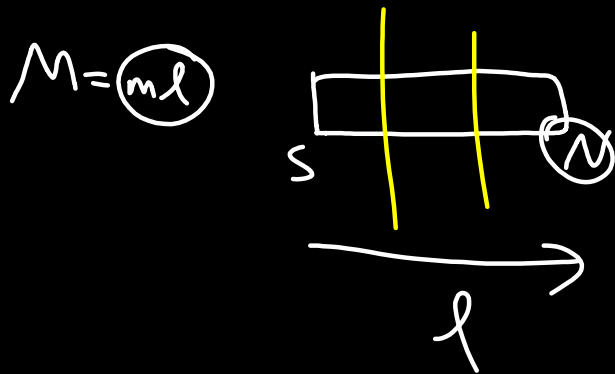
$$B = \left(\frac{\mu_0}{4\pi} \right) \frac{M}{r^3}$$

$$l = 6 \text{ cm}$$

$$M = 4$$

The length of a magnet is large compared to its width and breadth. The time period of its oscillation in a vibration magnetometer is 2s. The magnet is cut along its length into three equal parts and these parts are then placed on each other with their like poles together. The time period of this combination will be [2004]

- (a) $2\sqrt{3}$ s ~~(b) $\frac{2}{3}$ s~~ (c) 2 s (d) $\frac{2}{\sqrt{3}}$ s

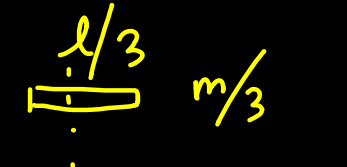


$$T = 2s = 2\pi\sqrt{\frac{I}{MB}}$$

$$T = 2\pi \sqrt{\frac{I}{MB}}$$



$$I = \frac{ml^2}{12}$$



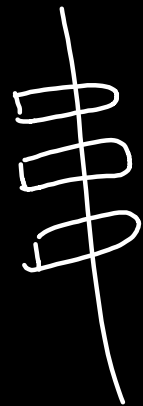
A horizontal rod of length $l/3$ and mass $m/3$ is shown. The length is indicated by a double-headed arrow below the rod, and the mass $m/3$ is written to the right of the rod.

$$I = \frac{(m/3)(l/3)^2}{12}$$

$$= \frac{ml^2}{27 \cdot 12}$$

$$\frac{I \rightarrow 1/9 \text{ times}}{\text{Time} \rightarrow \sqrt{1/9} \text{ time}}$$

$$= \frac{1}{3} \text{ times.}$$



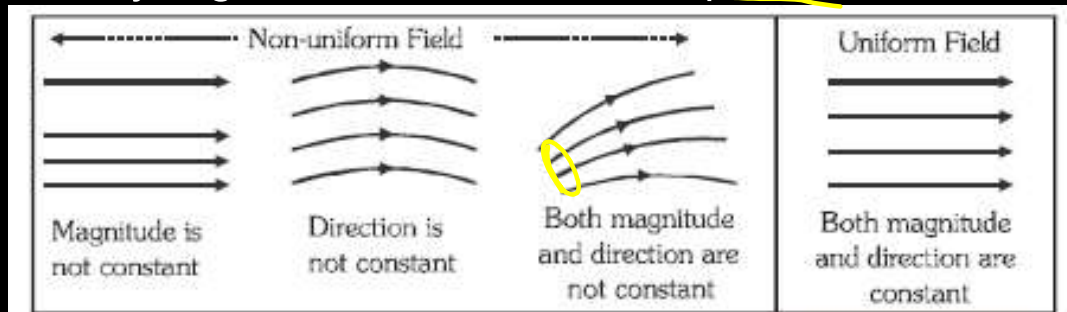
A vertical rod is shown, divided into three equal segments by two horizontal lines. The total length is indicated by a double-headed arrow to the left of the rod.

$$I_{\text{tot}} = \left(\frac{ml^2}{12} \right) \frac{1}{27} \times 3$$

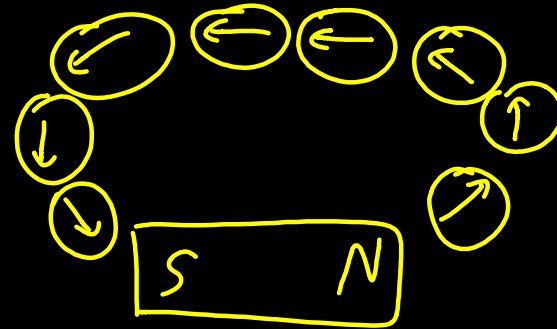
$$= I \frac{1}{9}$$

Magnetic Field lines Properties

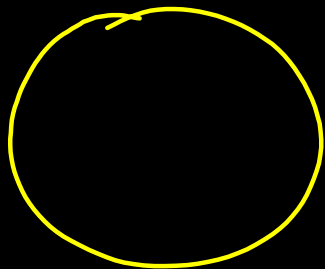
- Magnetic field lines are closed curves.
- Tangent drawn at any point on the field line represents direction of the field at that point.
- Field lines never intersects to each other.
- At any place crowded line represent stronger field while distant lines represents weaker field.
- In any region, if field lines are equidistant and straight the field uniform otherwise not.



- Magnetic field lines emanate from or enter the surface of a magnetic material at any angle.
- Magnetic field lines exist inside every magnetised material.
- Magnetic field lines can be mapped by using iron dust or using a compass needle.



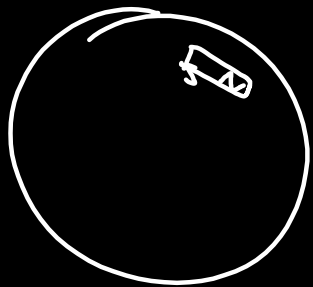
Gauss Law in Magnetism



closed
3D sphere

$$\text{Total flux} = \frac{Q_{\text{enclosed}}}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{A}$$



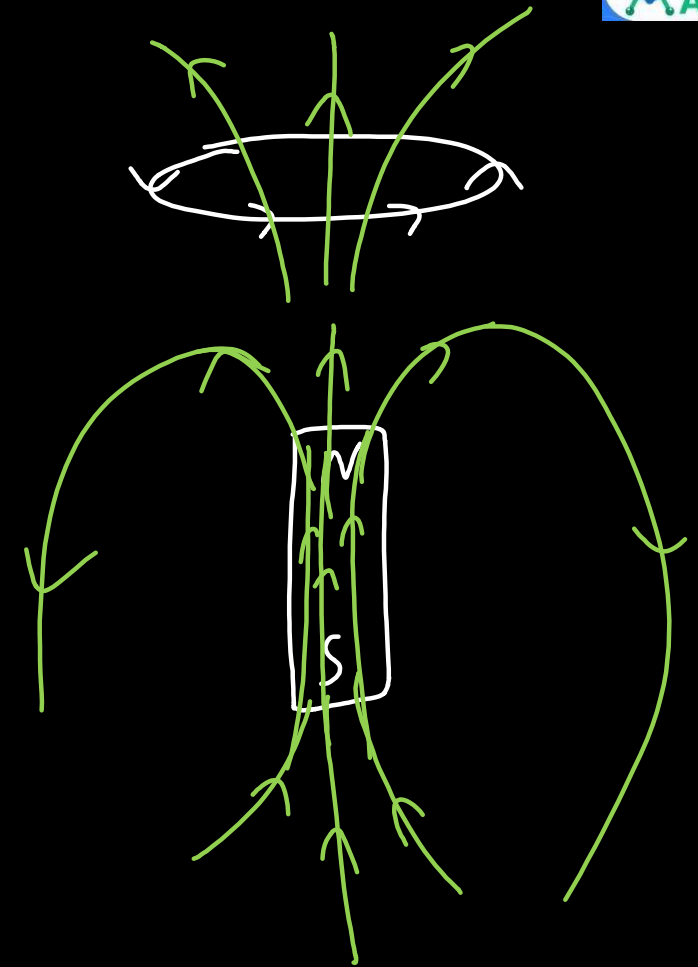
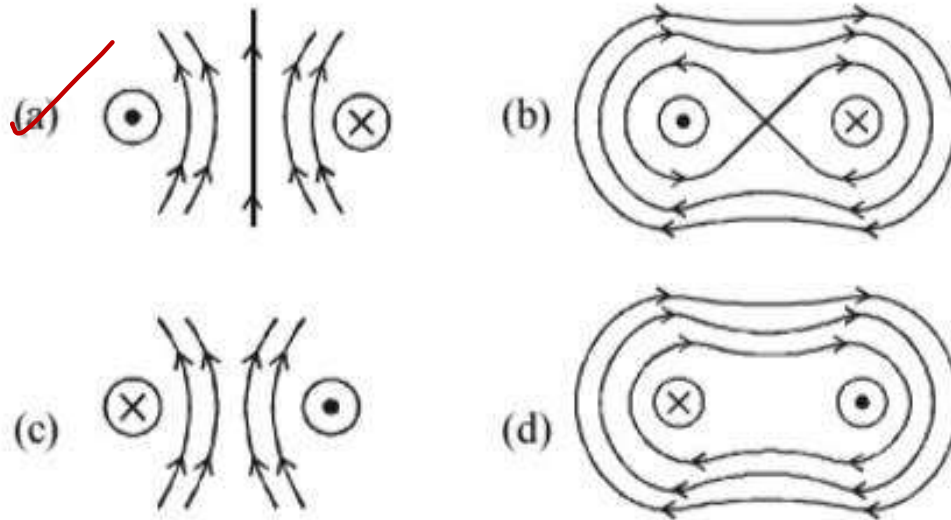
closed
3D
surface

total magnetic flux

$$\oint \vec{B} \cdot d\vec{A}$$

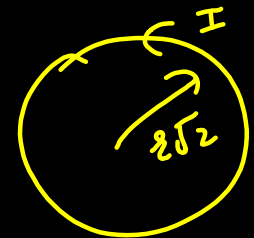
$$= \frac{m_{\text{enclosed}}}{\epsilon_0} = 0$$

Choose the correct sketch of the magnetic field lines of a circular current loop shown by the dot \odot and the cross \otimes .
[Online April 22, 2013]

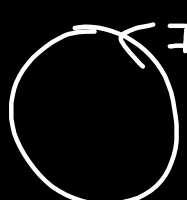


The dipole moment of a circular loop carrying a current I , is m and the magnetic field at the centre of the loop is B_1 . When the dipole moment is doubled by keeping the current constant, the magnetic field at the centre of the loop is B_2 . The ratio $\frac{B_1}{B_2}$ is: [2018]

- (a) 2 (b) $\sqrt{3}$ ☒ (c) $\sqrt{2}$ (d) $\frac{1}{\sqrt{2}}$



$$B_2 = \frac{\mu_0 I}{2(r\sqrt{2})}$$



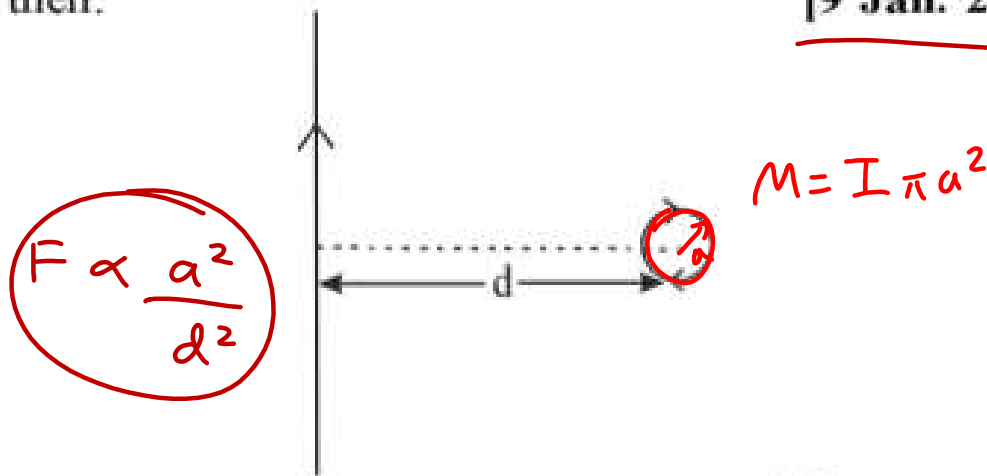
$$B_1 = \frac{\mu_0 I}{2r}$$

$$m = I\pi r^2$$

$$\frac{B_1}{B_2} = \sqrt{2}$$

An infinitely long current carrying wire and a small current carrying loop are in the plane of the paper as shown. The radius of the loop is a and distance of its centre from the wire is d ($d \gg a$). If the loop applies a force F on the wire then:

[9 Jan. 2019 I]



(a) $F = 0$

(b) $F \propto \left(\frac{a}{d}\right)$

(c) $F \propto \left(\frac{a^2}{d^3}\right)$

☒ (d) $F \propto \left(\frac{a}{d}\right)^2$

force = $M \frac{dB}{dx}$

$B = \frac{\mu_0 I}{2\pi x}$

$\frac{dB}{dx} = \frac{\mu_0 I}{2\pi} \left(\frac{-1}{x^2}\right)$

$F = I \pi a^2 \left(\frac{\mu_0 I}{2\pi x^2}\right)$

A 25 cm long solenoid has radius 2 cm and 500 total number of turns. It carries a current of 15 A. If it is equivalent to a magnet of the same size and magnetization \vec{M} (magnetic moment/volume), then $|\vec{M}|$ is : [Online April 10, 2015]

(a) $30000\pi \text{ Am}^{-1}$

(b) $3\pi \text{ Am}^{-1}$

~~(c) 30000 Am^{-1}~~

(d) 300 Am^{-1}

$$l = 25 \text{ cm}$$

$$r = 2 \text{ cm}$$

$$N = 500$$

$$I = 15 \text{ A}$$

$$I = \frac{\text{Magnetization}}{\text{Vol}}$$

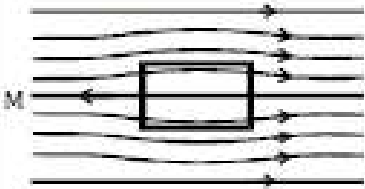
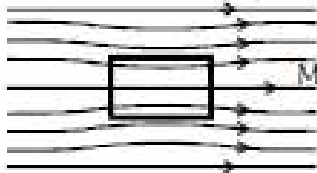
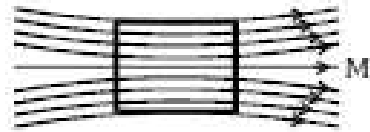


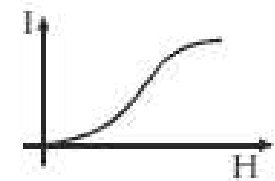
$$= \frac{(I)(\text{area})N}{\text{Vol}}$$

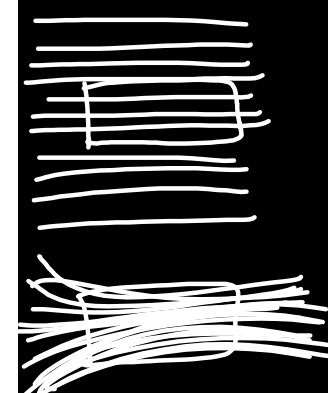
$$= \frac{(I)(A)N}{(A)l}$$

$$= \frac{(I)(N)}{l}$$

Break Time
20min

Resume 9:10pm

PROPERTIES	DIAMAGNETIC	PARAMAGNETIC	FERROMAGNETIC
<u>Cause of magnetism</u>	<u>Orbital motion of electrons</u>	<u>Spin motion of electrons</u>	<u>Formation of domains</u>
Substance placed in uniform magnetic field.	Poor magnetisation in opposite direction. Here $B_m < B_0$ 	Poor magnetisation in same direction. Here $B_m > B_0$ 	Strong magnetisation in same direction. Here $B_m \gg B_0$ 
I - H curve <div style="border: 1px solid red; padding: 2px; display: inline-block;">$\rightarrow M$</div> $I = \frac{M}{\mu_0}$	<u>I \rightarrow Small, negative, varies linearly with field</u> 	<u>I \rightarrow Small, positive, varies linearly with field</u> 	<u>I \rightarrow very large, positive & varies non-linearly with field</u> 

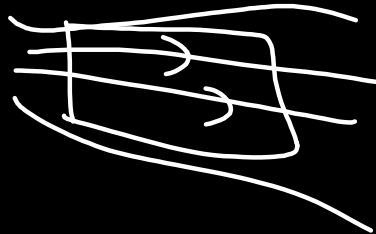
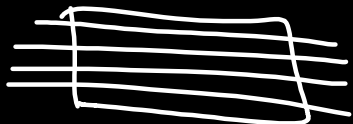


Di



Induced
Small &
opp

χ -ve
& small



Para



Induced
small

χ +ve
small

unpaired e^-



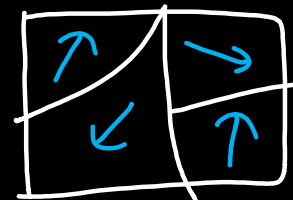
Ferro



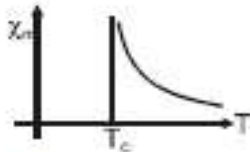


Induced very high

χ +ve high.

Domain



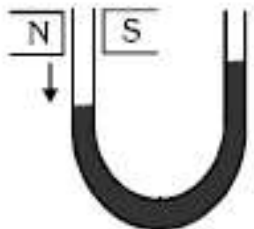







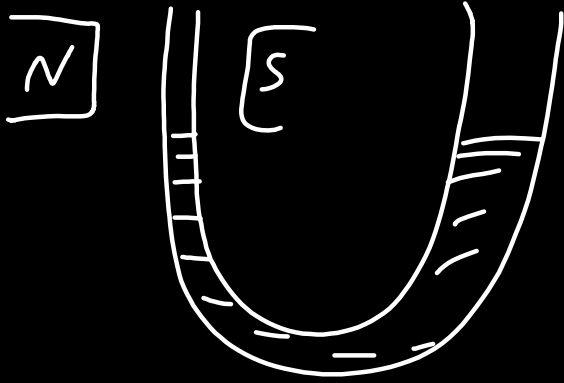
PROPERTIES	DIAMAGNETIC	PARAMAGNETIC	FERROMAGNETIC
$\chi_m - T$ curve	$\chi_m \rightarrow$ <u>small, negative & temperature independent</u> $\chi_m \propto T^0$  $\mu_r = 1 + \chi$	$\chi_m \rightarrow$ small, positive & varies inversely with temp. $\chi_m \propto \frac{1}{T}$ (Curie law) $\chi \propto \frac{1}{\text{Temp}}$ 	$\chi_m \rightarrow$ very large, positive & temp. dependent $\chi_m \propto \frac{1}{T - T_c}$ (Curie Weiss law) (for $T > T_c$) $(T_c = \text{Curie temperature})$  $T_c(\text{Iron}) = 770^\circ\text{C}$ or 1043K
μ_r	$(\mu < \mu_0)$ $1 > \mu_r > 0$	$2 > \mu_r > 1$ ($\mu > \mu_0$)	$\mu_r \gg 1$ ($\mu \gg \mu_0$)
Magnetic moment of single atom	Atoms <u>donot have any permanent magnetic moment</u>	Atoms have permanent magnetic moment which are randomly oriented. (i.e. in absence of external magnetic field the magnetic moment of whole material is zero)	Atoms have permanent magnetic moment which are organised in domains.

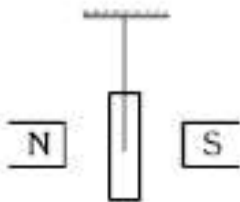
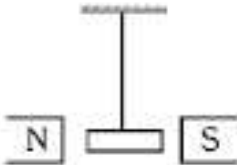
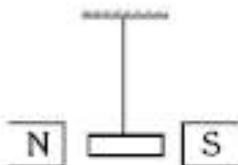
Curie Weisslaw

after Curie T
ferromagnetic
develops
paramagnetic
nature

$$\chi \propto \frac{1}{T - T_c}$$

PROPERTIES	DIAMAGNETIC	PARAMAGNETIC	FERROMAGNETIC
Behaviour of substance in Nonuniform magnetic field	<p>It moves from <u>stronger</u> to <u>weaker</u> magnetic field.</p>  <p>Weak Field</p>  <p>Strong field</p>  <p>Level depressed in that limb</p>	<p>It moves with weak force from <u>weaker</u> magnetic field to <u>stronger</u> magnetic field.</p>  <p>Weak Field</p>  <p>Strong field</p>  <p>Level slightly rises</p>	<p>Strongly attract from <u>weaker</u> magnetic field to <u>stronger</u> magnetic field.</p>  <p>Weak Field</p>  <p>Strong field</p>



PROPERTIES	DIAMAGNETIC	PARAMAGNETIC	FERROMAGNETIC
When rod of material is suspended between poles of magnet.	<p>It becomes perpendicular to the <u>direction of external magnetic field.</u></p> 	<p>If there is strong magnetic field in between the poles then rod becomes parallel to the <u>magnetic field.</u></p> 	<p>Weak magnetic field between magnetic poles can make <u>rod parallel to field direction.</u></p> 
Magnetic moment of substance in presence of external magnetic field	Value \vec{M} is very less and <u>opposite to \vec{H}.</u>	Value \vec{M} is low but in <u>direction of \vec{H}.</u>	\vec{M} is <u>very high</u> and in <u>direction of \vec{H}.</u>
Examples	Bi, <u>Cu</u> , Ag, Pb, H ₂ O, Hg, H ₂ , He, Ne, Au, Zn, Sb, NaCl, Diamond. (May be found in solid, liquid or gas).	Na, K, Mg, Mn, Sn, Pt, Al, O ₂ (May be found in solid, liquid or gas.)	Fe, Co, Ni all their alloys, Fe ₃ O ₄ , Gd, Alnico, etc. (Normally found only in solids) (crystalline solids)

A paramagnetic sample shows a net magnetisation of 6 A/m when it is placed in an external magnetic field of 0.4 T at a temperature of 4 K. When the sample is placed in an external magnetic field of 0.3 T at a temperature of 24 K, then the magnetisation will be : [Sep. 04, 2020 (II)]

- (a) 1 A/m (b) 4 A/m
(c) 2.25 A/m (d) 0.75 A/m

$$\begin{aligned} I &= 6 \text{ A/m} \\ B &= 0.4 \text{ T} \\ T &= 4 \text{ K} \end{aligned}$$

$$\begin{aligned} B' &= 0.3 \text{ T} \\ T' &= 24 \text{ K} \\ I &=? \end{aligned}$$

$$6 \propto \frac{0.4}{4}$$

$$I' \propto \frac{0.3}{24}$$

divide

$$\frac{6}{I'} = \frac{0.4}{4} \times \frac{24}{0.3}$$

$$\frac{3}{4} = \frac{6}{8} = I'$$

0.75

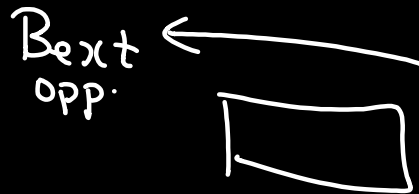


magnet Ban Gaya

when ext B removed

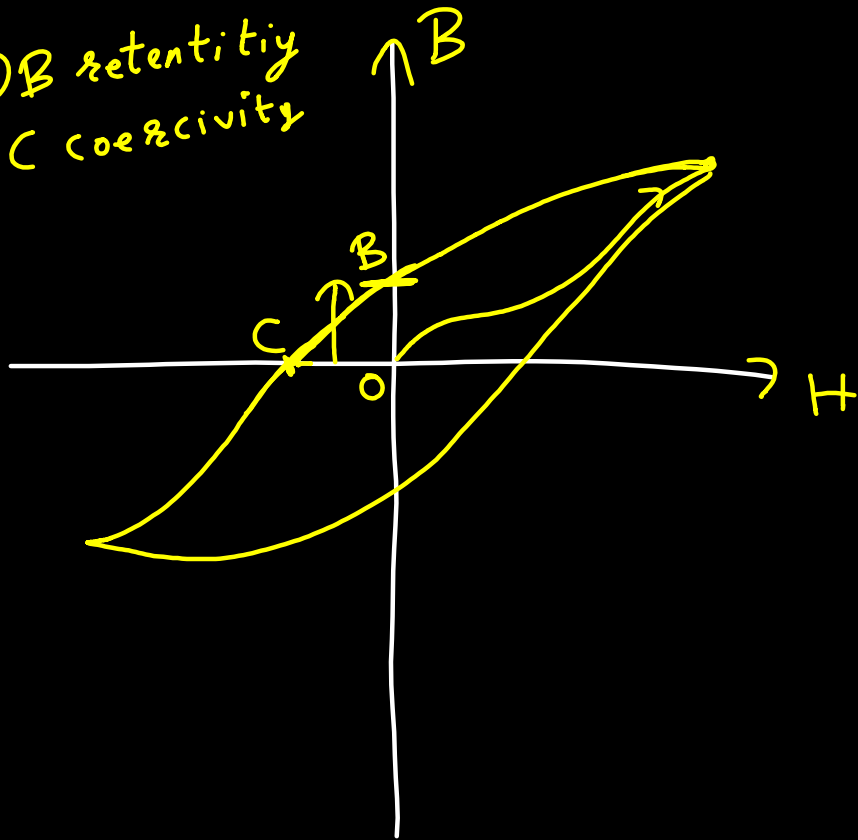
\Rightarrow retentivity induced B Bachhi reh Jati

Now we need to remove it for that

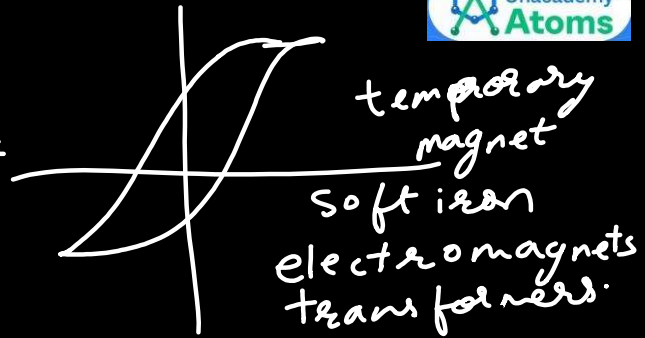


Coercivity

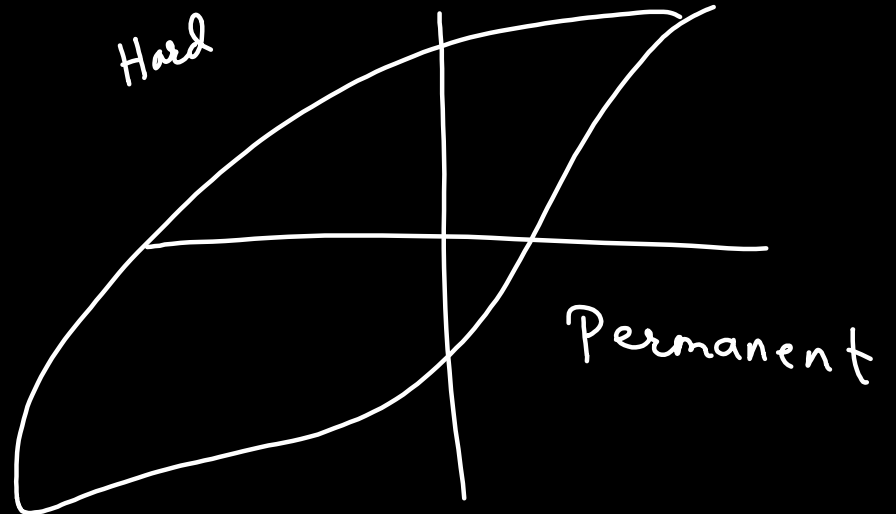
O_B retentivity
 O_C coercivity



Soft
magnetic

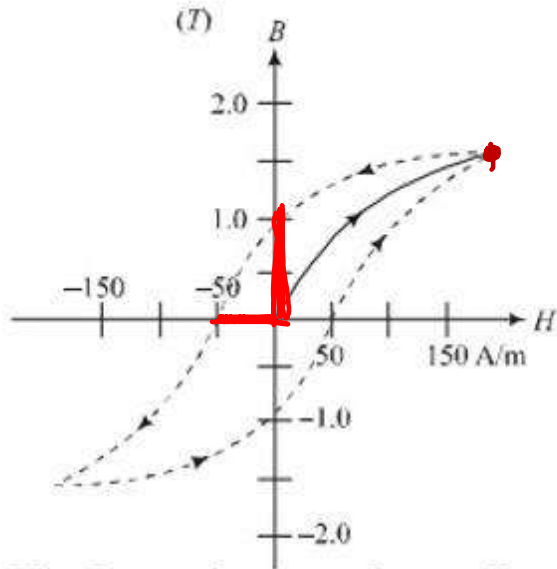


Hard



Magnetic materials used for making permanent magnets (P) and magnets in a transformer (T) have different properties of the following, which property best matches for the type of magnet required? [Sep. 02, 2020 (I)]

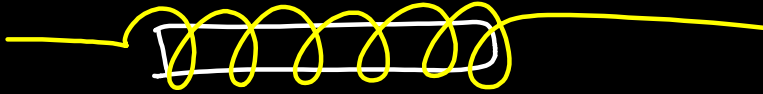
- (a) T : Large retentivity, small coercivity ✗
- (b) P : Small retentivity, large coercivity
- (c) T : Large retentivity, large coercivity ✗
- ~~(d)~~ P : Large retentivity, large coercivity



The figure gives experimentally measured B vs. H variation in a ferromagnetic material. The retentivity, co-ercivity and saturation, respectively, of the material are:

[7 Jan. 2020 II]

- (a) 1.5 T, 50 A/m and 1.0 T
- (b) 1.5 T, 50 A/m and 1.0 T
- (c) 150 A/m, 1.0 T and 1.5 T
- ☒ (d) 1.0 T, 50 A/m and 1.5 T



Earth Magnetism

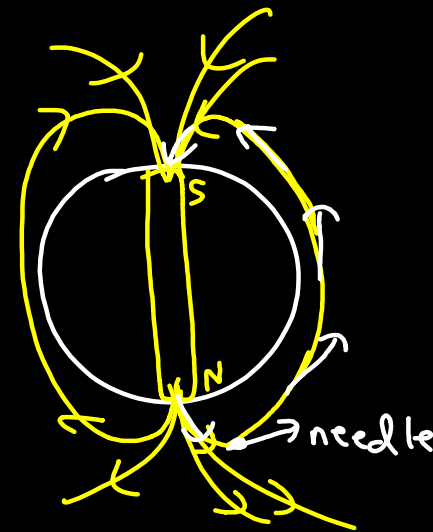
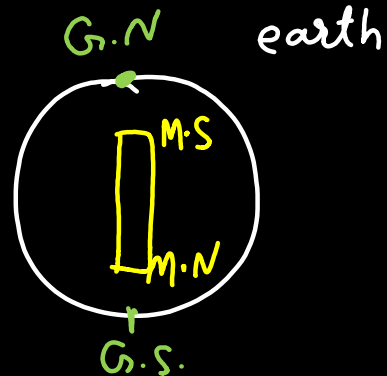
Basics
Clear

G.N \Rightarrow geometry
north

G.S \Rightarrow " "
south

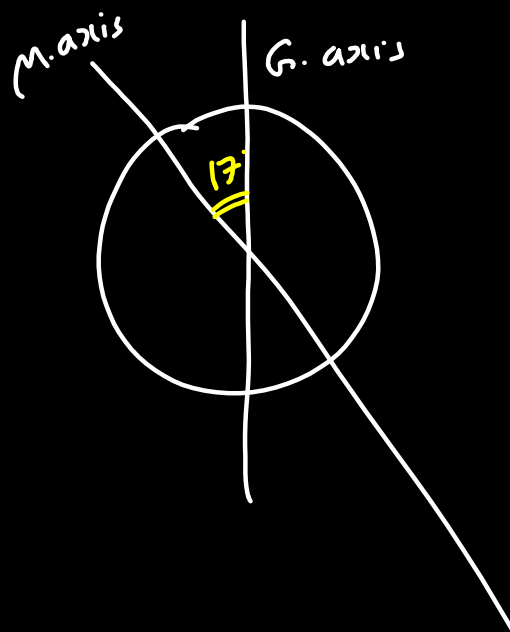
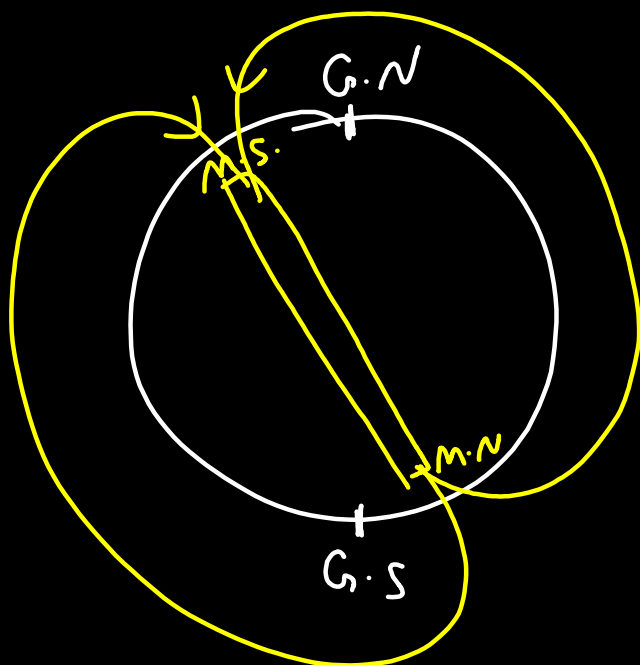
M.S \Rightarrow magnetic
south

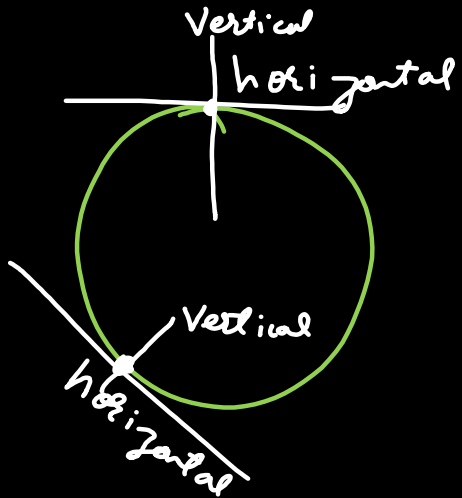
M.N \Rightarrow " "
north



Compass
north needle
point towards
 \Downarrow

Geo north





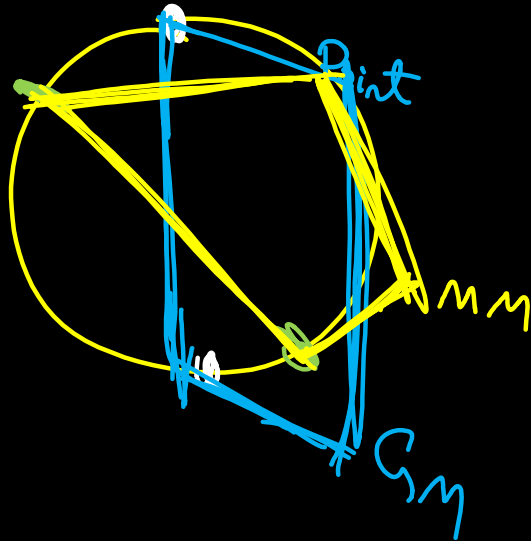
Horizontal \Rightarrow tangent

Vertical \Rightarrow radius

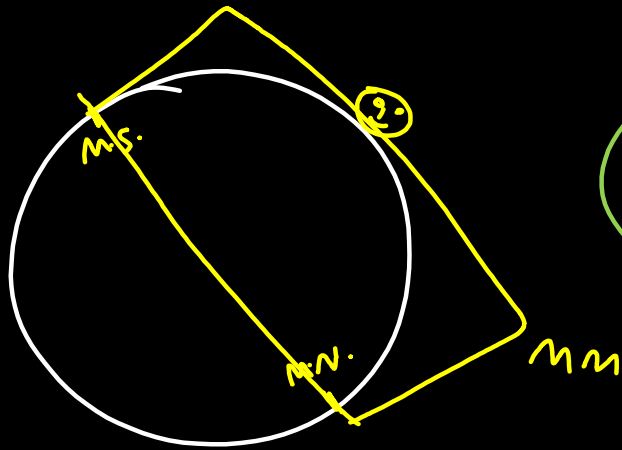
Planes

Geometric Meridian \Rightarrow passing through G. North & G. South

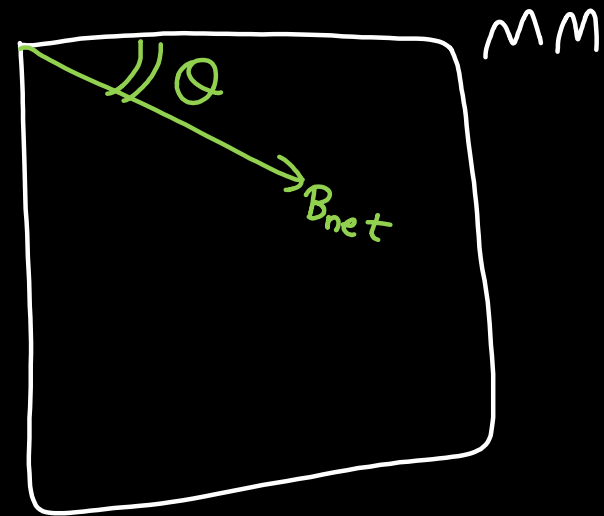
Magnetic Meridian \Rightarrow " " " M. North & M. South

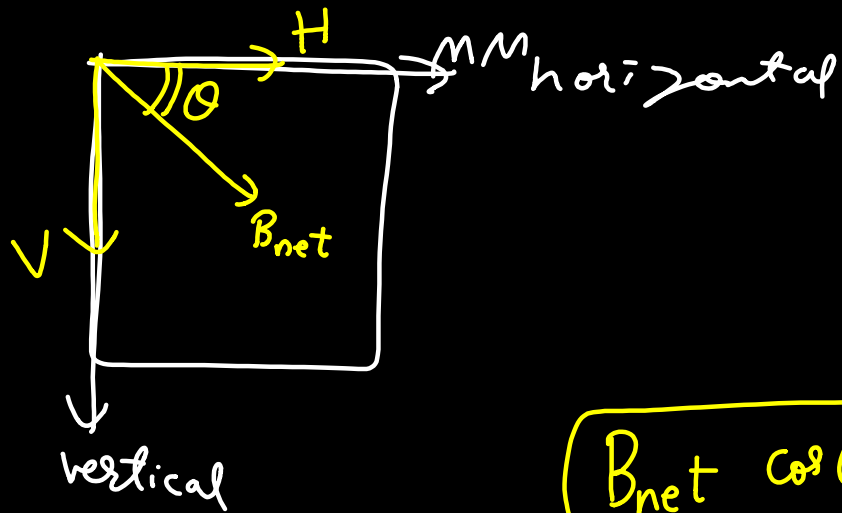


B_{net} of earth always lies in Magnetic Meridian



$\theta \rightarrow$ angle of Dip





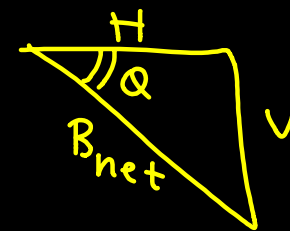
$$B_{net} \cos \theta = H$$

$$B_{net} \sin \theta = V$$

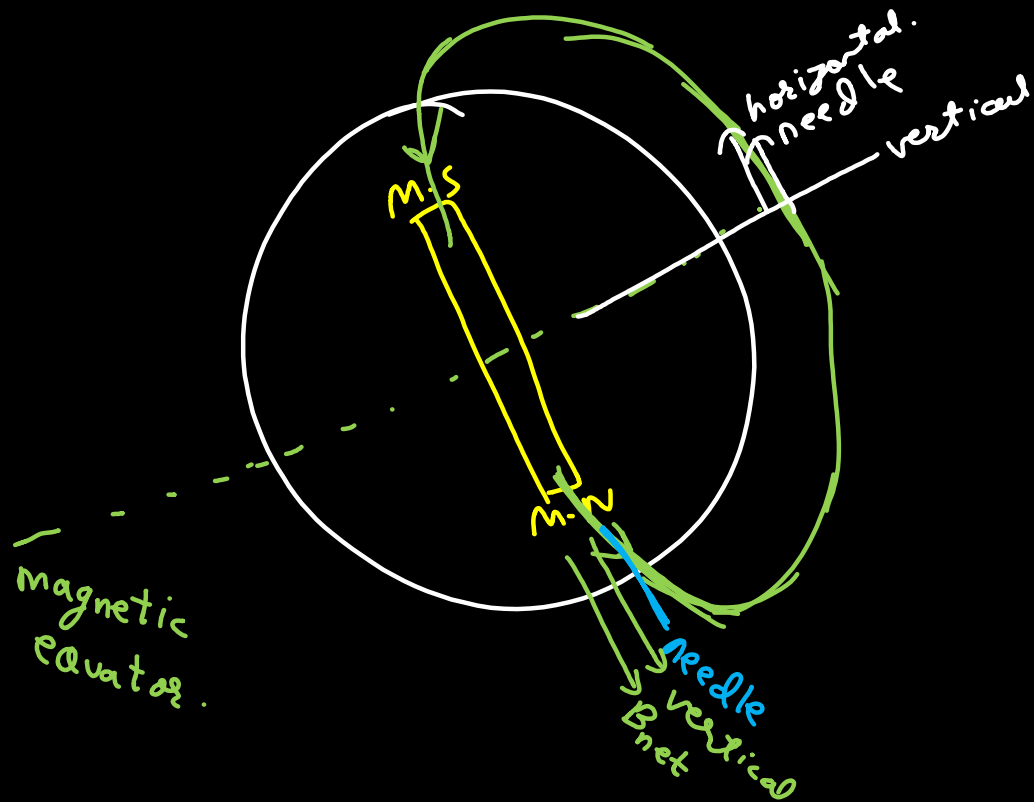
$$B_{net} = \sqrt{H^2 + V^2}$$

$H \rightarrow$ horizontal component of earth's magnetic field

$V \rightarrow$ vertical " " "



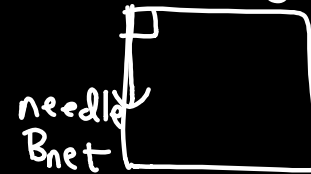
$$\tan \theta_{dip} = \frac{V}{H}$$



needle orientation

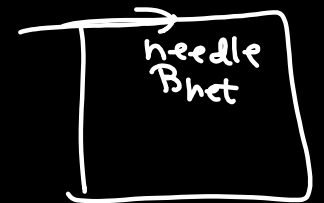
① at poles

② θ dip 90°

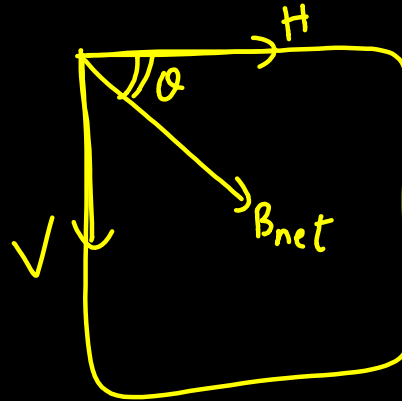
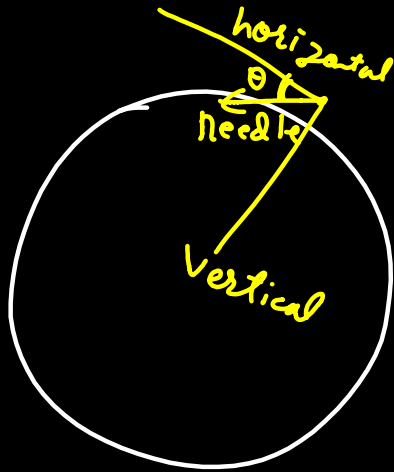


② at equator ^{magnetic}

② θ dip 0°



at any general point



$$B_{net} \sin \theta = V$$

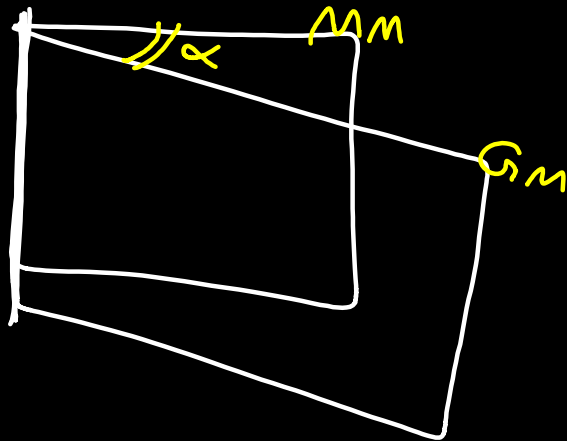
$$B_{net} \cos \theta = H$$

$$\tan \theta = \frac{V}{H}$$

$$\sqrt{V^2 + H^2} = B_{net}$$

Angle of Declination (α_{dec})

angle b/w G-meridian & magnetic meridian.

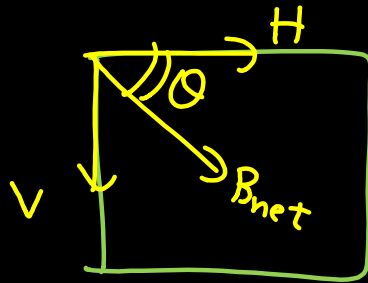


α_{dec}

Vertical direction is Same of Both

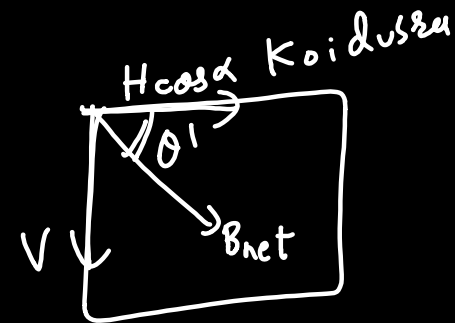
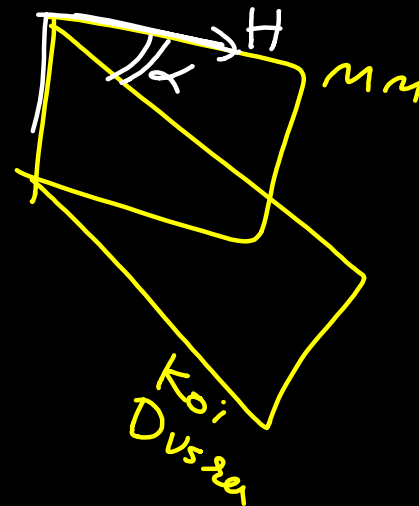
True Angel of Dip & App Angel of Dip

in M. meridian



$$\tan \theta = \frac{V}{H}$$

Koidusse plane



$$\tan \theta' = \frac{V}{H \cos \alpha}$$

$$\tan \theta' = \frac{\tan \theta}{\cos \alpha}$$

$$\tan \theta' = \frac{\tan \theta}{\cos \alpha}$$

$\theta' \Rightarrow$ app dip

$\theta \Rightarrow$ true dip

$\alpha \Rightarrow$ angle b/w MM & koi Dusra plane.

Q. If a magnetic needle is fixed to move in a plane which makes 30° with M. meridian. Dip angle showed by dip circle in above case is 45° . What is true dip angle??

$$\theta = \tan^{-1}\left(\frac{\sqrt{3}}{2}\right) \text{ Ans.}$$

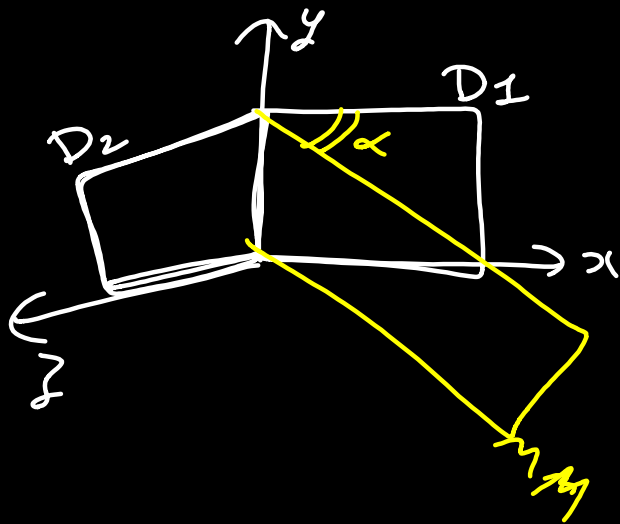
$$\tan \theta' = \frac{\tan \theta}{\cos \alpha}$$

$$\tan 45^\circ = \frac{\tan \theta}{\cos 30^\circ}$$

$$1 \cdot \frac{\sqrt{3}}{2} = \tan \theta$$

Special Case

2 dice plane lin to each other



$$\tan \theta'_{D_1} = \frac{\tan \theta}{\cos \alpha}$$

$$\tan \theta'_{D_2} = \frac{\tan \theta}{\cos(90 - \alpha)} = \frac{\tan \theta}{\sin \alpha}$$

$$\cos^2 \alpha + \sin^2 \alpha = 1$$

$$\frac{\tan^2 \theta}{\tan^2 \theta'_{D_1}} + \frac{\tan^2 \theta}{\tan^2 \theta'_{D_2}} = 1$$

$$\frac{1}{\tan^2 \theta'_{D_1}} + \frac{1}{\tan^2 \theta'_{D_2}} = \frac{1}{\tan^2 \theta}$$

$$\boxed{\cot^2 \theta'_{D_1} + \cot^2 \theta'_{D_2} = \cot^2 \theta}$$

\downarrow \downarrow \downarrow
 $\text{app in } D_1$ $\text{app in } D_2$ true

Vibration Magnetometer

$$T = 2\pi \sqrt{\frac{I}{MB}}$$

$$T = 2\pi \sqrt{\frac{I}{MH}}$$

→ horizontal component of earth's magnetic field.

needle fixed to rotate in
horizontal plane
in presence of
earth's magnetic field.

Comparison of earth Horizontal Component at two diff places

$$T_1 = 2\pi \sqrt{\frac{I}{M H_1}}$$

$$T_2 = 2\pi \sqrt{\frac{I}{M H_2}}$$

$$\frac{T_1}{T_2} = \sqrt{\frac{H_2}{H_1}}$$

Two different needles Compare their M

$$T_1 = 2\pi \sqrt{\frac{I_1}{M_1 H}}$$

$$T_2 = 2\pi \sqrt{\frac{I_2}{M_2 H}}$$

$$\frac{T_1}{T_2} = \sqrt{\frac{I_1 M_2}{M_1 I_2}}$$

if I same of both (same size & same mass)

$$\frac{T_1}{T_2} = \sqrt{\frac{M_2}{M_1}}$$

Calculate M if H is known

$$T = 2\pi \sqrt{\frac{I}{MH}}$$

Comparison of two M by sum & diff method



$$I_{net} = I_1 + I_2$$

#

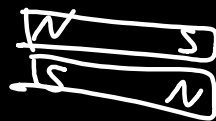


$$M_{net} = M_1 + M_2$$

$$T_1 = 2\pi \sqrt{\frac{I_{net}}{(M_1 + M_2)H}}$$

$$\frac{T_1}{T_2} = \sqrt{\frac{M_1 - M_2}{M_1 + M_2}}$$

#



$$M_{net} = M_1 - M_2$$

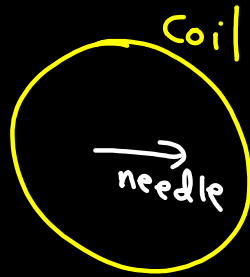
$$T_2 = 2\pi \sqrt{\frac{I_{net}}{(M_1 - M_2)H}}$$

Tangent Galvanometer

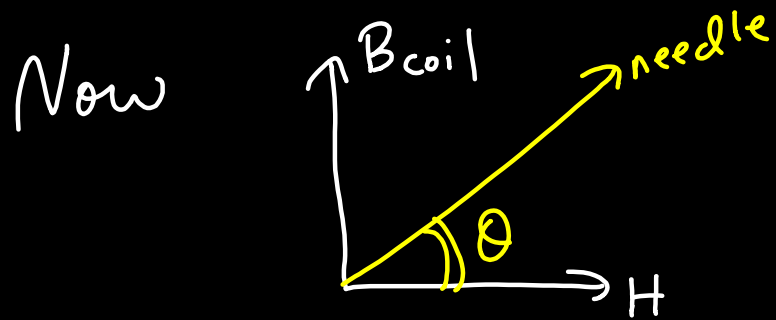
$[I \rightarrow \text{detect}]$

needle free to move in horizontal plane

initially $\begin{matrix} \longrightarrow \text{needle} \\ \longrightarrow H \end{matrix}$



If I passes in coil, B generates on needle



$$\tan \theta = \frac{B_{\text{coil}}}{H}$$

at a place

H, z, r, N, μ_0 fixed

$$B_{\text{coil}} = H \tan \theta$$

$$N \left(\frac{\mu_0 I}{2z} \right) = H \tan \theta$$

$$I = k \tan \theta$$

$$k = \frac{2zH}{\mu_0 N}$$

$\Phi \rightarrow$ we can measure I

more Φ more I

Q when $2A$ I passes deflection is 30° .
Find I which passes when deflection is 45° ?

$$I = k \tan 30^\circ$$

$$2 = k \tan 30^\circ$$

$$I' = k \tan 45^\circ$$

$$\frac{2}{I'} = \frac{\tan 30^\circ}{\tan 45^\circ} = \frac{\frac{1}{\sqrt{3}}}{1} = \frac{1}{\sqrt{3}}$$

$$2\sqrt{3}A = I'$$