## Gaussian Processes

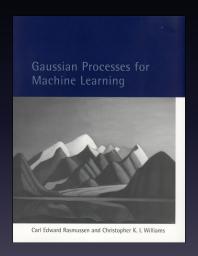
MLAI Lecture 23

Neil D. Lawrence

Department of Computer Science Sheffield University

23rd November 2012

### Book



Rasmussen and Williams (2006)

#### Outline

Distributions over Functions

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

**GP** Limitations

Conclusions

### Outline

#### Distributions over Functions

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

GP Limitations

Conclusion:

### Sampling a Function

#### Multi-variate Gaussians

- We will consider a Gaussian with a particular structure of covariance matrix.
- Generate a single sample from this 25 dimensional Gaussian distribution,  $\mathbf{y} = [y_1, y_2 \dots y_{25}].$
- We will plot these points against their index.

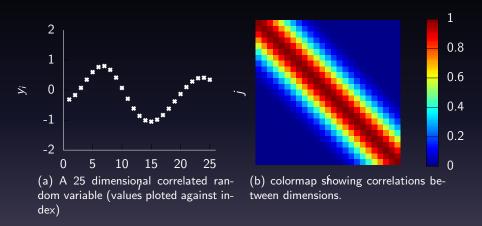


Figure: A sample from a 25 dimensional Gaussian distribution.

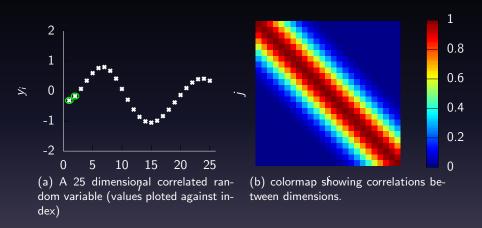


Figure: A sample from a 25 dimensional Gaussian distribution.

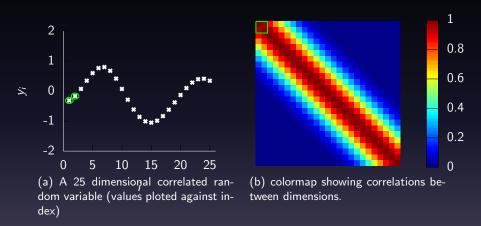


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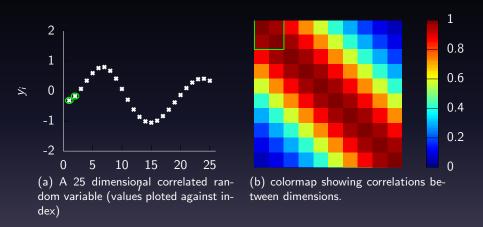


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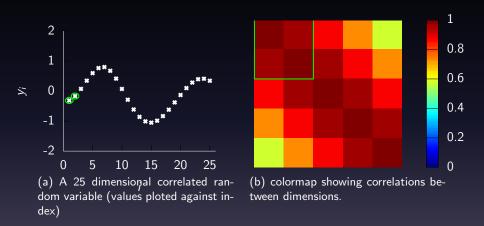


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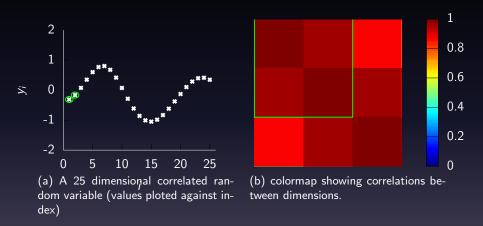


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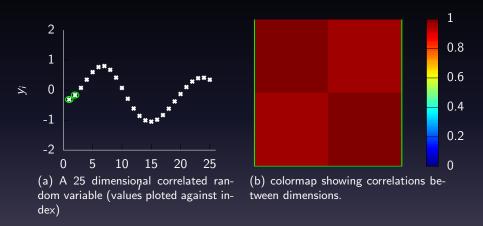


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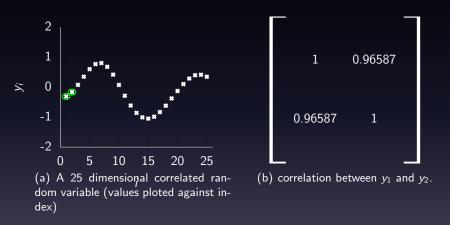
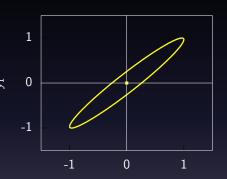


Figure: A sample from a 25 dimensional Gaussian distribution.



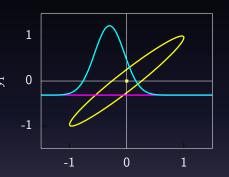


- The single contour of the Gaussian density represents the joint distribution,  $p(y_1, y_2)$ .
- We observe that  $y_1 = -0.313$ .
- Conditional density:  $p(y_2|y_1 = -0.313)$ .



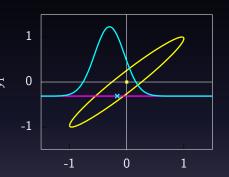


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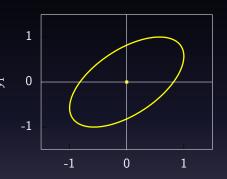
### Prediction with Correlated Gaussians

- Prediction of  $y_2$  from  $y_1$  requires conditional density.
- Conditional density is also Gaussian.

$$p(y_2|y_1) = \mathcal{N}\left(y_2|rac{k_{1,2}}{k_{1,1}}y_1, k_{2,2} - rac{k_{1,2}^2}{k_{1,1}}
ight)$$

where covariance of joint density is given by

$$\mathbf{K} = \begin{bmatrix} k_{1,1} & k_{1,2} \\ k_{2,1} & k_{2,2} \end{bmatrix}$$



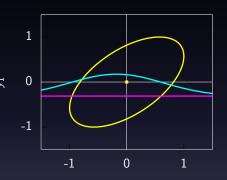


- The single contour of the Gaussian density represents the joint distribution,  $p(y_1, y_5)$ .
- We observe that  $y_1 = -0.313$ .
- Conditional density:  $p(y_5|y_1 = -0.313)$ .



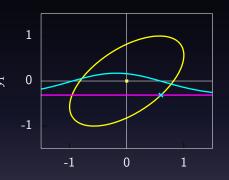


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### Prediction with Correlated Gaussians

- Prediction of y<sub>\*</sub> from y requires multivariate conditional density.
- Multivariate conditional density is also Gaussian.

$$\rho(\mathbf{y}_*|\mathbf{y}) = \mathcal{N}\left(\mathbf{y}_*|\mathbf{K}_{*,\mathbf{y}}\mathbf{K}_{\mathbf{y},\mathbf{y}}^{-1}\mathbf{y},\mathbf{K}_{*,*} - \mathbf{K}_{*,\mathbf{y}}\mathbf{K}_{\mathbf{y},\mathbf{y}}^{-1}\mathbf{K}_{\mathbf{y},*}\right)$$

• Here covariance of joint density is given by

$$\mathbf{K} = egin{bmatrix} \mathbf{K}_{\mathbf{y},\mathbf{y}} & \mathbf{K}_{*,\mathbf{y}} \\ \mathbf{K}_{\mathbf{y},*} & \mathbf{K}_{*,*} \end{bmatrix}$$

### Prediction with Correlated Gaussians

- Prediction of y<sub>\*</sub> from y requires multivariate conditional density.
- Multivariate conditional density is also Gaussian.

$$egin{aligned} 
ho(\mathbf{y}_*|\mathbf{y}) &= \mathcal{N}\left(\mathbf{y}_*|oldsymbol{\mu}, \Sigma
ight) \ oldsymbol{\mu} &= \mathbf{K}_{*,\mathbf{y}}\mathbf{K}_{\mathbf{y},\mathbf{y}}^{-1}\mathbf{y} \ \Sigma &= \mathbf{K}_{*,*} - \mathbf{K}_{*,\mathbf{y}}\mathbf{K}_{\mathbf{y},\mathbf{y}}^{-1}\mathbf{K}_{\mathbf{y},*} \end{aligned}$$

Here covariance of joint density is given by

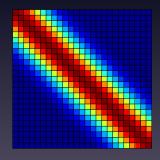
$$\mathbf{K} = egin{bmatrix} \mathbf{K}_{\mathbf{y},\mathbf{y}} & \mathbf{K}_{*,\mathbf{y}} \\ \mathbf{K}_{\mathbf{y},*} & \mathbf{K}_{*,*} \end{bmatrix}$$

Where did this covariance matrix come from?

# Exponentiated Quadratic Kernel Function (RBF, Squared Exponential, Gaussian)

$$k\left(\mathbf{x}, \mathbf{x}'\right) = \alpha \exp\left(-\frac{\left\|\mathbf{x} - \mathbf{x}'\right\|_{2}^{2}}{2\ell^{2}}\right)$$

- Covariance matrix is built using the *inputs* to the function x.
- For the example above it was based on Euclidean distance.
- The covariance function is also know as a kernel.

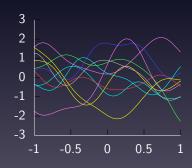


Where did this covariance matrix come from?

## Exponentiated Quadratic Kernel Function (RBF, Squared Exponential, Gaussian)

$$k\left(\mathbf{x}, \mathbf{x}'\right) = \alpha \exp\left(-rac{\|\mathbf{x} - \mathbf{x}'\|_2^2}{2\ell^2}
ight)$$

- Covariance matrix is built using the *inputs* to the function x.
- For the example above it was based on Euclidean distance.
- The covariance function is also know as a kernel.



$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_1 = -3.0, x_1 = -3.0$$

$$k_{1,1} = 1.00 imes \exp\left(-rac{(-3.0 - 3.0)^2}{2 imes 2.00^2}
ight)$$

$$x_1 = -3.0$$
,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k\left(x_{i},x_{j}
ight)=lpha\exp\left(-rac{\left|\left|x_{i}-x_{j}
ight|^{2}}{2\ell^{2}}
ight)}{1.00}$$
 $x_{1}=-3.0,\ x_{1}=-3.0$ 

$$k_{1,1}=1.00 imes\exp\left(-rac{\left(-3.0--3.0
ight)^{2}}{2 imes2.00^{2}}
ight)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_1 = -3.0$$

$$\mathit{k}_{2,1} = 1.00 imes \exp\left(-rac{(1.20 - 1.20)^2}{2 imes 2.00^2}
ight)$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=2.00$  and  $\alpha=1.00$ .

$$k\left(x_{i},x_{j}
ight)=lpha\exp\left(-rac{||x_{i}-x_{j}||^{2}}{2\ell^{2}}
ight)$$
 
$$x_{2}=1.20,\ x_{1}=-3.0$$
 
$$0.110$$
 
$$k_{2,1}=1.00 imes\exp\left(-rac{(1.20-1.20)^{2}}{2 imes2.00^{2}}
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ight)$$
 
$$x_2=1.20,\ x_1=-3.0$$
 
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$$k\left(x_i,x_j
ight)=lpha\exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 
$$x_2=1.20,\ x_2=1.20$$
 
$$0.110$$
 
$$k_{2,2}=1.00 imes\exp\left(-rac{(1.20-1.20)^2}{2 imes2.00^2}
ight)$$

$$x_1 = -3.0$$
,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 $x_2 = 1.20, \ x_2 = 1.20$ 
 $1.00 \quad 0.110$ 
 $1.00$ 
 $1.00$ 
 $1.00$ 

$$x_1=-3.0$$
,  $x_2=1.20$ , and  $x_3=1.40$  with  $\ell=2.00$  and  $\alpha=1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$\begin{bmatrix} 1.00 & 0.110 \end{bmatrix}$$

$$x_3 = 1.40, x_1 = -3.0$$

$$\mathit{k}_{3,1} = 1.00 imes \exp\left(-rac{(1.40 - 1.40)^2}{2 imes 2.00^2}
ight)$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=2.00$  and  $\alpha=1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$k_{3,1} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$k_{3,1} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$
1.00 0.110 0.0889

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,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$\begin{bmatrix}
1.00 & 0.110 & 0.0889
\end{bmatrix}$$

$$k_{3,2} = 1.00 imes \exp\left(-rac{(1.40 - 1.40)^2}{2 imes 2.00^2}
ight)$$

 $x_3 = 1.40, x_2 = 1.20$ 

0.0889

1.00

0.110

 $\emph{x}_1=-3.0$ ,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=2.00$  and  $\alpha=1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

$$0.110 \quad 0.0889$$

$$k_{3,2} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$1.00 \quad 0.110 \quad 0.0889$$

$$0.110 \quad 1.00 \quad 0.995$$

$$k_{3,3} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$1.00 \quad 0.110 \quad 0.0889$$

$$0.110 \quad 1.00 \quad 0.995$$

$$k_{3,3} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995 \quad \boxed{1.00}$$

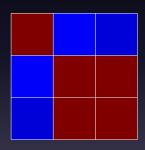
$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$k_{3,3} = 1.00 imes \exp\left(-rac{(1.40 - 1.40)^2}{2 imes 2.00^2}
ight)$$



 $x_1 = -3.0$ ,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 2.00$  and  $\alpha = 1.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_1 = -3$$
,  $x_1 = -3$ 

$$k_{1,1} = 1.0 imes \exp\left(-rac{(-3--3)^2}{2 imes 2.0^2}
ight)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$
 
$$x_1 = -3, \ x_1 = -3$$
 
$$k_{1,1} = 1.0 \times \exp\left(-\frac{(-3 - -3)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

1.0

$$x_2 = 1.2, x_1 = -3$$
  $k_{2,1} = 1.0 imes \exp\left(-rac{(1.2 - 1.2)^2}{2 imes 2.0^2}
ight)$ 

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$
 
$$x_2 = 1.2, x_1 = -3$$
 
$$0.11$$
 
$$k_{2,1} = 1.0 \times \exp\left(-\frac{(1.2 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 
$$x_2 = 1.2, \ x_1 = -3 \qquad \qquad \begin{bmatrix} 1.0 & 0.11 \\ 0.11 \\ k_{2,1} = 1.0 imes \exp\left(-rac{(1.2-1.2)^2}{2 imes 2.0^2}
ight) \end{bmatrix}$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 
$$x_2 = 1.2, \ x_2 = 1.2 \qquad \qquad 0.11$$
 
$$k_{2,2} = 1.0 imes \exp\left(-rac{(1.2-1.2)^2}{2 imes 2.0^2}
ight)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 
$$x_2 = 1.2, \ x_2 = 1.2$$
 
$$0.11 \ 1.0$$
 
$$k_{2,2} = 1.0 imes \exp\left(-rac{(1.2-1.2)^2}{2 imes 2.0^2}
ight)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$
 
$$x_3 = 1.4, \ x_1 = -3 \qquad \qquad \boxed{ egin{array}{c} 1.0 & 0.11 \\ 0.11 & 1.0 \ \end{array} }$$
  $k_{3,1} = 1.0 imes \exp\left(-rac{(1.4-1.4)^2}{2 imes 2.0^2}
ight)$ 

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.4, x_1 = -3$$

$$k_{3,1} = 1.0 \times \exp\left(-\frac{(1.4 - 1.4)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 \\
0.11 & 1.0
\end{bmatrix}$$

0.089

$$\mathit{k}_{3,1} = 1.0 imes \exp\left(-rac{(1.4 - 1.4)^2}{2 imes 2.0^2}
ight)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_{i},x_{j}
ight)=lpha\exp\left(-rac{\left|\left|x_{i}-x_{j}
ight|^{2}}{2\ell^{2}}
ight)}{1.0\ 0.11\ 0.089}$$
  $x_{3}=1.4,\ x_{2}=1.2$   $0.089$   $0.089$ 

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$

$$x_3 = 1.4, \ x_2 = 1.2$$

$$x_3 = 1.0 \times \exp\left(-rac{(1.4-1.4)^2}{2\times 2.0^2}
ight)$$

$$1.0 \quad 0.11 \quad 0.089$$

$$0.11 \quad 1.0$$

$$0.089 \quad 1.0$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

Where did this covariance matrix come from?

$$k\left(x_{i},x_{j}\right)=lpha\exp\left(-rac{||x_{i}-x_{j}||^{2}}{2\ell^{2}}
ight)$$

$$x_{3}=1.4,\ x_{2}=1.2$$

$$0.089 \ 1.0$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

 $k_{3,2} = 1.0 \times \exp\left(-\frac{(1.4-1.4)^2}{2\times 2.0^2}\right)$ 

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_i,x_j
ight) = lpha \exp\left(-rac{||x_i-x_j||^2}{2\ell^2}
ight)$$

$$x_3 = 1.4, \ x_3 = 1.4$$

$$k_{3,3} = 1.0 \times \exp\left(-rac{(1.4-1.4)^2}{2\times 2.0^2}
ight)$$

$$1.0 \quad 0.11 \quad 0.089$$

$$0.11 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0 \quad 1.0$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k\left(x_{i},x_{j}
ight)=lpha\exp\left(-rac{||x_{i}-x_{j}||^{2}}{2\ell^{2}}
ight)$$

$$x_{4}=2.0,\ x_{1}=-3$$

$$0.11\ 1.0\ 1.0$$

$$0.089\ 1.0\ 1.0$$

$$k_{4,1}=1.0 ext{ } \exp\left(-rac{(2.0-2.0)^{2}}{2 ext{ } 2 ext{ } 2.0^{2}}
ight)$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_1 = -3$$

$$k_{4,1} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$0.044$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_1 = -3$$

$$k_{4,1} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044 \quad 0.92$$

$$x_1=-3$$
,  $x_2=1.2$ ,  $x_3=1.4$ , and  $x_4=2.0$  with  $\ell=2.0$  and  $\alpha=1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$0.044 \quad 0.92$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.11 \quad 1.0 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044 \quad 0.92$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.11 \quad 1.0 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044 \quad 0.92 \quad 0.96$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.11 \quad 1.0 \quad 1.0 \quad 0.92$$

0.089 1.0 1.0 0.96

0.044 0.92 0.96

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

 $k_{4,3} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$ 

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.11 \quad 1.0 \quad 1.0 \quad 0.92$$

$$x_4 = 2.0, x_4 = 2.0$$

$$0.11 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0 \quad 0.96$$

$$0.044 \quad 0.92 \quad 0.96$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_4 = 2.0$$

$$k_{4,4} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089 \quad 0.044$$

$$0.11 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0 \quad 0.96$$

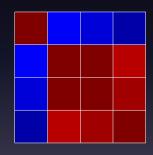
$$0.044 \quad 0.92 \quad 0.96 \quad 1.0$$

$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_4 = 2.0$$

$$k_{4,4} = 1.0 imes \exp\left(-rac{(2.0 - 2.0)^2}{2 imes 2.0^2}
ight)$$



$$x_1 = -3$$
,  $x_2 = 1.2$ ,  $x_3 = 1.4$ , and  $x_4 = 2.0$  with  $\ell = 2.0$  and  $\alpha = 1.0$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_1 = -3.0, x_1 = -3.0$$

$$k_{1,1} = 4.00 imes \exp\left(-rac{(-3.0 - 3.0)^2}{2 imes 5.00^2}
ight)$$

$$x_1 = -3.0$$
,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k\left(x_{i},x_{j}
ight)=lpha\exp\left(-rac{||x_{i}-x_{j}||^{2}}{2\ell^{2}}
ight)$$
 
$$x_{1}=-3.0,\ x_{1}=-3.0$$
 
$$4.00$$
 
$$k_{1,1}=4.00 imes\exp\left(-rac{(-3.0--3.0)^{2}}{2 imes5.00^{2}}
ight)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

4.00

$$x_2 = 1.20, x_1 = -3.0$$

$$k_{2,1} = 4.00 imes \exp\left(-rac{(1.20 - 1.20)^2}{2 imes 5.00^2}
ight)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_1 = -3.0$$

$$k_{2,1} = 4.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 5.00^2}\right)$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_1 = -3.0$$

$$2.81$$

$$k_{2,1} = 4.00 imes \exp\left(-rac{(1.20 - 1.20)^2}{2 imes 5.00^2}
ight)$$

 $\emph{x}_1 = -3.0$ ,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_2 = 1.20$$
 4.00 2.81

$$k_{2,2} = 4.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 5.00^2}\right)$$

 $x_1 = -3.0$ ,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_2 = 1.20$$

$$k_{2,2} = 4.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 5.00^2}\right)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

2.81

4.00

$$x_3 = 1.40, x_1 = -3.0$$
 4.00 
$$k_{3,1} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$x_3 = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

$$2.72$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$k_{3,1} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

$$4.00 \quad 2.81 \quad 2.72$$

$$2.81 \quad 4.00$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$4.00 \quad 2.81$$

$$x_3 = 1.40, x_2 = 1.20$$

$$k_{3,2} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

2.72

$$x_1 = -3.0$$
,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

2.72

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

$$k_{3,2} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$
 $4.00 \quad 2.81 \quad 2.72$ 

$$2.81 \quad 4.00$$

$$\emph{x}_1 = -3.0$$
,  $\emph{x}_2 = 1.20$ , and  $\emph{x}_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

$$k_{3,2} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

$$4.00 \quad 2.81 \quad 2.72$$

$$2.81 \quad 4.00 \quad 4.00$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$k_{3,3} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$

$$4.00 \quad 2.81 \quad 2.72$$

$$2.81 \quad 4.00 \quad 4.00$$

$$x_1 = -3.0$$
,  $x_2 = 1.20$ , and  $x_3 = 1.40$  with  $\ell = 5.00$  and  $\alpha = 4.00$ .

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$k_{3,3} = 4.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 5.00^2}\right)$$
 $4.00 \quad 2.81 \quad 2.72$ 

$$2.81 \quad 4.00 \quad 4.00$$

$$2.72 \quad 4.00 \quad 4.00$$

$$\emph{x}_1=-3.0$$
,  $\emph{x}_2=1.20$ , and  $\emph{x}_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$k_{3,3} = 4.00 imes \exp\left(-rac{(1.40 - 1.40)^2}{2 imes 5.00^2}
ight)$$



 $x_1=-3.0$ ,  $x_2=1.20$ , and  $x_3=1.40$  with  $\ell=5.00$  and  $\alpha=4.00$ .

## Outline

Distributions over Functions

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

Conclusion

### **Basis Function Form**

Radial basis functions commonly have the form

$$\phi_k\left(\mathbf{x}_i\right) = \exp\left(-rac{\left|\mathbf{x}_i - \boldsymbol{\mu}_k
ight|^2}{2\ell^2}
ight).$$

 Basis function maps data into a "feature space" in which a linear sum is a non linear function.

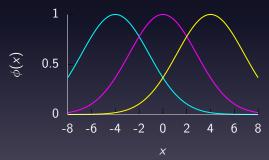


Figure: A set of radial basis functions with width  $\ell = 2$  and location parameters  $\mu = \begin{bmatrix} -4 & 0 & 4 \end{bmatrix}^{\top}$ .

# Basis Function Representations

• Represent a function by a linear sum over a basis,

$$y(\mathbf{x}_{i,:};\mathbf{w}) = \sum_{k=1}^{m} w_k \phi_k(\mathbf{x}_{i,:}), \tag{1}$$

• Here: m basis functions and  $\phi_k(\cdot)$  is kth basis function and

$$\mathbf{w} = [w_1, \dots, w_m]^{\top}$$
.

• For standard linear model:  $\phi_k(\mathbf{x}_{i,:}) = x_{i,k}$ .

#### Random Functions

Functions derived using:

$$y(x) = \sum_{k=1}^{m} w_k \phi_k(x),$$

where W is sampled from a Gaussian density,

$$w_k \sim \mathcal{N}(0, \alpha)$$
.

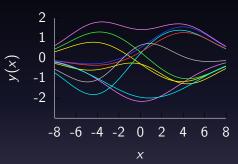


Figure: Functions sampled using the basis set from figure 2. Each line is a separate sample, generated by a weighted sum of the basis set. The weights,  $\mathbf{w}$  are sampled from a Gaussian density with variance  $\alpha=1$ .

• Use matrix notation to write function,

$$y\left(\mathbf{x}_{i};\mathbf{w}\right)=\sum_{k=1}^{m}w_{k}\phi_{k}\left(\mathbf{x}_{i}\right)$$

$$y = \Phi w$$
.

- w and y are only related by a inner product
- ullet is fixed and non-stochastic for a given training set
- y is Gaussian distributed.
- it is straightforward to compute distribution for **y**

• Use matrix notation to write function,

$$y\left(\mathbf{x}_{i};\mathbf{w}\right)=\sum_{k=1}^{m}w_{k}\phi_{k}\left(\mathbf{x}_{i}\right)$$

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• Use matrix notation to write function,

$$y\left(\mathbf{x}_{i};\mathbf{w}\right)=\sum_{k=1}^{m}w_{k}\phi_{k}\left(\mathbf{x}_{i}\right)$$

$$\mathsf{y} = \Phi \mathsf{w}$$
 .

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$$y = \Phi w$$
.

- w and y are only related by a inner product.
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• Use matrix notation to write function,

$$y\left(\mathbf{x}_{i};\mathbf{w}\right)=\sum_{k=1}^{m}w_{k}\phi_{k}\left(\mathbf{x}_{i}\right)$$

$$y = \Phi w$$
.

- w and y are only related by a inner product.
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- y is Gaussian distributed.
- it is straightforward to compute distribution for y

• Use matrix notation to write function,

$$y\left(\mathbf{x}_{i};\mathbf{w}\right)=\sum_{k=1}^{m}w_{k}\phi_{k}\left(\mathbf{x}_{i}\right)$$

$$\mathbf{y} = \mathbf{\Phi} \mathbf{w}$$
.

- w and y are only related by a inner product.
- ullet  $\Phi$  is fixed and non-stochastic for a given training set.
- y is Gaussian distributed.
- it is straightforward to compute distribution for y

- ullet We use  $\langle\cdot
  angle$  to denote expectations under prior distributions.
- We have

$$\langle \mathsf{y}
angle = \phi \, \langle \mathsf{w}
angle$$

Prior mean of w was zero giving

$$\langle \mathsf{y} \rangle = \mathsf{0}.$$

Prior covariance of v is

$$\mathsf{K} = \left\langle \mathsf{y} \mathsf{y}^{ op} 
ight
angle - \left\langle \mathsf{y} 
ight
angle \left\langle \mathsf{y} 
ight
angle^{ op}$$

$$\left\langle \mathsf{y}\mathsf{y}^{ op} \right
angle = \Phi \left\langle \mathsf{w}\mathsf{w}^{ op} \right
angle \Phi^{ op}$$

$$K = \gamma' \Phi \Phi^{\top}$$
.

- We use  $\langle \cdot \rangle$  to denote expectations under prior distributions.
- We have

$$\left\langle \mathsf{y}
ight
angle =\phi\left\langle \mathsf{w}
ight
angle$$
 .

Prior mean of w was zero giving

$$\langle \mathsf{y} 
angle = \mathsf{0}$$
 .

Prior covariance of y is

$$\mathsf{K} = \left\langle \mathsf{y}\mathsf{y}^{ op} \right
angle - \left\langle \mathsf{y} 
ight
angle \left\langle \mathsf{y} 
ight
angle^{ op}$$

$$\left\langle \mathsf{y}\mathsf{y}^{ op} \right
angle = \mathbf{\Phi} \left\langle \mathsf{w}\mathsf{w}^{ op} \right
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angle - \left\langle \mathbf{y} 
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• The prior covariance between two points  $x_i$  and  $x_j$  is

$$k\left(\mathbf{x}_{i},\mathbf{x}_{j}\right)=\gamma'\sum_{\ell}^{m}\phi_{\ell}\left(\mathbf{x}_{i}\right)\phi_{\ell}\left(\mathbf{x}_{j}\right)$$

or in vector form

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$$k(\mathbf{x}_i, \mathbf{x}_j) = \gamma' \sum_{k=1}^{m} \exp\left(-\frac{|\mathbf{x}_i - \boldsymbol{\mu}_k|^2 + |\mathbf{x}_j - \boldsymbol{\mu}_k|^2}{2\ell^2}\right)$$

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# Selecting Number and Location of Basis

- Need to choose
  - location of centers
  - number of basis functions
- Consider uniform spacing over a region:

$$k\left(x_{i}, x_{j}\right) = \gamma \Delta \mu \sum_{k=1}^{\infty} \exp\left(-\frac{1 - i \gamma_{j} - i \beta_{k} + i \gamma_{k} + i \gamma_{k}}{2\ell^{2}}\right)$$

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### **Uniform Basis Functions**

• Set each center location to

$$\mu_k = a + \Delta \mu \cdot (k-1).$$

Specify the bases in terms of their indices,

$$k(x_i, x_j) = \gamma \Delta \mu \sum_{k=1}^{\infty} \exp\left(-\frac{1}{2\ell^2}\right)$$
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- Take  $\mu_0 = a$  and  $\mu_m = b$  so  $b = a + \Delta \mu \cdot (m-1)$
- Take limit as  $\Delta\mu \to 0$  so  $m \to \infty$

$$k(x_i, x_j) = \gamma \int_a^b \exp\left(-\frac{x_i^2 + x_j^2}{2\ell^2} + \frac{2(\mu - \frac{1}{2}(x + x_j))^2 - \frac{1}{2}(x + y_j)^2}{2\ell^2}\right) d\mu$$

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#### Result

• Performing the integration leads to

$$k(x_i, x_j) = \gamma \frac{\sqrt{\pi \ell^2}}{2} \exp\left(-\frac{(x_i - x_j)^2}{4\ell^2}\right)$$

$$\times \left[ \operatorname{erf}\left(\frac{\left(b - \frac{1}{2}(x_i + x_j)\right)}{\ell}\right) - \operatorname{erf}\left(\frac{\left(a - \frac{1}{2}(x_i + x_j)\right)}{\ell}\right) \right],$$

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### Nonparametric Gaussian Processes

- This work takes us from parametric to non-parametric.
- The limit implies infinite dimensional w.
- Gaussian processes are generally non-parametric: combine data with covariance function to get model.
- This representation cannot be summarized by a parameter vector of a fixed size.

- Parametric models have a representation that does not respond to increasing training set size.
- Bayesian posterior distributions over parameters contain the information about the training data.
  - Use Bayes' rule from training data,  $p(\mathbf{w}|\mathbf{t}, \mathbf{X})$ ,
  - Make predictions on test data

$$p\left(t_{*}|\mathbf{X}_{*},\mathbf{t},\mathbf{X}
ight)=\int p\left(t_{*}|\mathbf{w},\mathbf{X}_{*}
ight)p\left(\mathbf{w}|\mathbf{t},\mathbf{X}
ight)d\mathbf{w}
ight).$$

- w becomes a bottleneck for information about the training set to pass to the test set.
- Solution: increase *m* so that the bottleneck is so large that it no longer presents a problem.
- How big is big enough for m? Non-parametrics says  $m \to \infty$ .

- Now no longer possible to manipulate the model through the standard parametric form given in (1).
- However, it is possible to express parametric as GPs

$$k(\mathbf{x}_i, \mathbf{x}_j) = \phi_{:}(\mathbf{x}_i)^{\top} \phi_{:}(\mathbf{x}_j).$$

- These are known as degenerate covariance matrices.
- Their rank is at most m, non-parametric models have full rank covariance matrices.
- Most well known is the "linear kernel",  $k(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}_i^{\top} \mathbf{x}_j$ .

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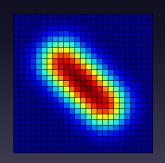
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### **Covariance Functions**

#### **RBF Basis Functions**

$$k(\mathbf{x}, \mathbf{x}') = \alpha \phi(\mathbf{x})^{\top} \phi(\mathbf{x}')$$

$$\phi_i(x) = \exp\left(-rac{\|x-\mu_i\|_2^2}{\ell^2}
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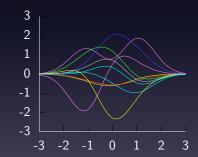


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- Algorithms can be simpler, but probabilistic interpretation is crucial for kernel parameter optimization.

### Outline

Distributions over Functions

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

GP Limitation

Conclusion:

## Constructing Covariance Functions

• Sum of two covariances is also a covariance function.

$$k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}') + k_2(\mathbf{x}, \mathbf{x}')$$

## Constructing Covariance Functions

• Product of two covariances is also a covariance function.

$$k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}')k_2(\mathbf{x}, \mathbf{x}')$$

# Multiply by Deterministic Function

- If y(x) is a Gaussian process.
- $g(\mathbf{x})$  is a deterministic function.
- $h(\mathbf{x}) = y(\mathbf{x})g(\mathbf{x})$
- Then

$$k_h(\mathbf{x}, \mathbf{x}') = g(\mathbf{x})k_f(\mathbf{x}, \mathbf{x}')g(\mathbf{x}')$$

where  $k_h$  is covariance for  $h(\cdot)$  and  $k_f$  is covariance for  $y(\cdot)$ .

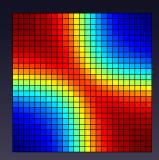
### **Covariance Functions**

#### MLP Covariance Function

$$k\left(\mathbf{x}, \mathbf{x}'\right) = \alpha \mathrm{asin}\left(\frac{w\mathbf{x}^{\top}\mathbf{x}' + b}{\sqrt{w\mathbf{x}^{\top}\mathbf{x} + b + 1}\sqrt{w\mathbf{x}'^{\top}\mathbf{x}' + b + 1}}\right)$$

 Based on infinite neural network model.

$$w = 40$$



#### **Covariance Functions**

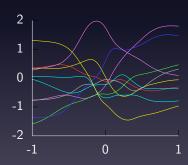
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 Based on infinite neural network model.

$$w = 40$$

$$b=4$$



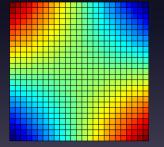
#### Covariance Functions

#### **Linear Covariance Function**

$$k(\mathbf{x}, \mathbf{x}') = \alpha \mathbf{x}^{\mathsf{T}} \mathbf{x}'$$

• Bayesian linear regression.

$$\alpha = 1$$



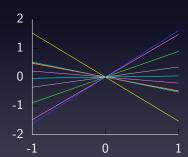
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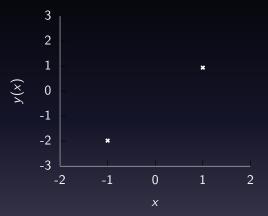
#### **Linear Covariance Function**

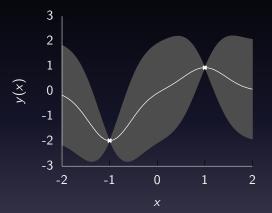
$$k(\mathbf{x}, \mathbf{x}') = \alpha \mathbf{x}^{\mathsf{T}} \mathbf{x}'$$

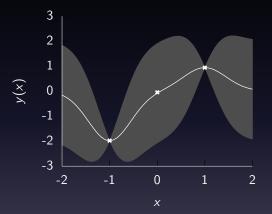
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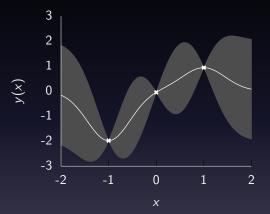
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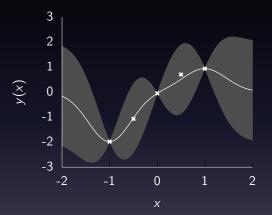


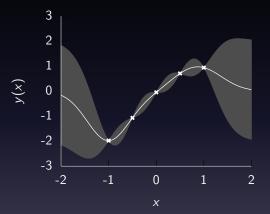


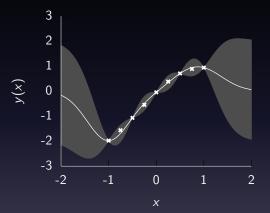


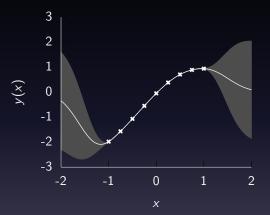












#### Gaussian Noise

• Gaussian noise model,

$$p(t_i|y_i) = \mathcal{N}(t_i|y_i, \sigma^2)$$

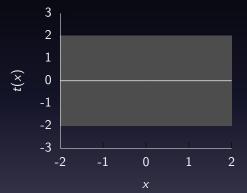
where  $\sigma^2$  is the variance of the noise.

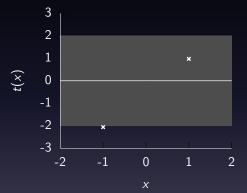
• Equivalent to a covariance function of the form

$$k(\mathbf{x}_i, \mathbf{x}_i) = \delta_{i,i}\sigma^2$$

where  $\delta_{i,i}$  is the Kronecker delta function.

 Additive nature of Gaussians means we can simply add this term to existing covariance matrices.





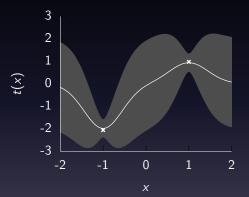
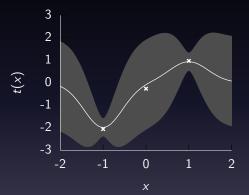
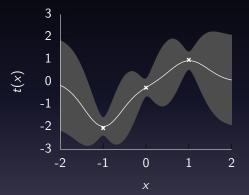
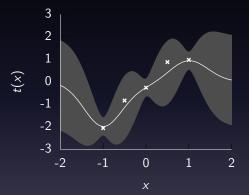
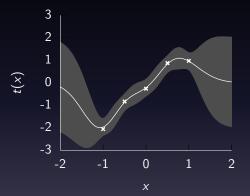


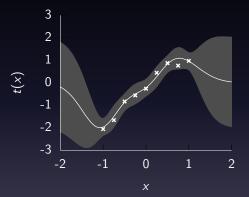
Figure: Examples include WiFi localization, C14 callibration curve.

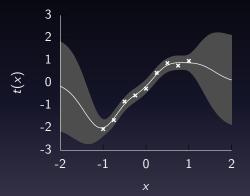












#### Learning Covariance Parameters

Can we determine covariance parameters from the data?

$$\mathcal{N}\left(\mathbf{t}|\mathbf{0},\mathbf{K}
ight) = rac{1}{(2\pi)^{rac{N}{2}}|\mathbf{K}|} \mathrm{exp}\left(-rac{\mathbf{t}^{ op}\mathbf{K}^{-1}\mathbf{t}}{2}
ight)$$

$$k_{i,j} = k(\mathbf{x}_i, \mathbf{x}_j; \boldsymbol{\theta})$$

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#### Learning Covariance Parameters

Can we determine covariance parameters from the data?

$$\log \mathcal{N}\left(\mathbf{t}|\mathbf{0},\mathbf{K}\right) = -\frac{N}{2}\log 2\pi - \frac{1}{2}\log |\mathbf{K}| - \frac{\mathbf{t}^{\top}\mathbf{K}^{-1}\mathbf{t}}{2}$$

$$k_{i,j} = k(\mathbf{x}_i, \mathbf{x}_j; \boldsymbol{\theta})$$

# Learning Covariance Parameters Can we determine covariance parameters from the data?

$$E(\boldsymbol{\theta}) = \frac{1}{2} \log |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$

$$k_{i,j} = k(\mathbf{x}_i, \mathbf{x}_j; \boldsymbol{\theta})$$

#### Eigendecomposition of Covariance

A useful decomposition for understanding the objective function.

$$\mathsf{K} = \mathsf{R} \Lambda^2 \mathsf{R}^{ op}$$



Diagonal of  $\Lambda$  represents distance along axes.

**R** gives a rotation of these axes.

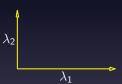
where  $oldsymbol{\Lambda}$  is a  $\emph{diagonal}$  matrix and  $oldsymbol{\mathsf{R}}^{ op}oldsymbol{\mathsf{R}}=oldsymbol{\mathsf{I}}.$ 

Useful representation since  $|\mathbf{K}| = ig| \Lambda^2 ig| = |\Lambda|^2.$ 

$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 \ 0 & \lambda_2 \end{bmatrix}$$



$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 \ \hline 0 & \lambda_2 \end{bmatrix}$$



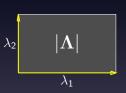
$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 \ 0 & \lambda_2 \end{bmatrix} egin{bmatrix} \lambda_2 \ \lambda_1 \end{bmatrix}$$

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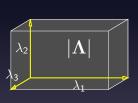
$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 \ 0 & \lambda_2 \end{bmatrix} egin{bmatrix} \lambda_2 & |oldsymbol{\Lambda}| \ \lambda_1 & \lambda_1 \end{bmatrix}$$

$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 & 0 \ 0 & \lambda_2 & 0 \ \hline 0 & 0 & \lambda_3 \end{bmatrix}$$



$$|\mathbf{\Lambda}| = \lambda_1 \lambda_2$$

$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 & 0 \ 0 & \lambda_2 & 0 \ \hline 0 & 0 & \lambda_3 \end{bmatrix}$$



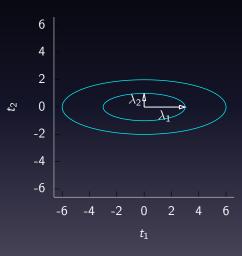
$$|\mathbf{\Lambda}| = \lambda_1 \lambda_2 \lambda_3$$

$$oldsymbol{\Lambda} = egin{bmatrix} \lambda_1 & 0 \ 0 & \lambda_2 \end{bmatrix} egin{bmatrix} \lambda_1 & \lambda_2 \ \lambda_1 \end{bmatrix}$$

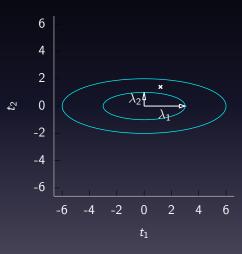
$$\mathsf{R}\Lambda = egin{bmatrix} w_{1,1} & w_{1,2} \ w_{2,1} & w_{2,2} \end{bmatrix} egin{bmatrix} \lambda_1 \ \lambda_2 \end{bmatrix} \lambda_1$$

$$|\mathbf{R}\mathbf{\Lambda}| = \lambda_1\lambda_2$$

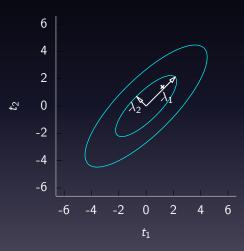
# Data Fit: $\frac{\mathbf{t}^{-1}\mathbf{K}^{-1}\mathbf{t}}{2}$

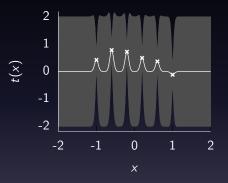


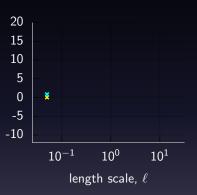
# Data Fit: $\frac{\mathbf{t}^{-1}\mathbf{K}^{-1}\mathbf{t}}{2}$



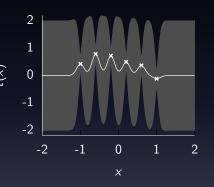
# Data Fit: $\frac{\mathbf{t}^{-1}\mathbf{K}^{-1}\mathbf{t}}{2}$

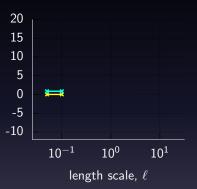




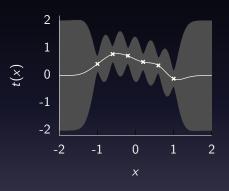


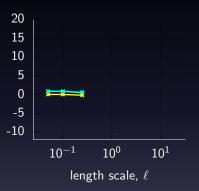
$$E(\theta) = \frac{1}{2} |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$



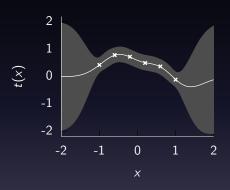


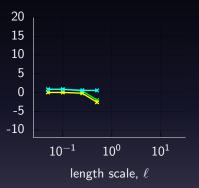
$$E(\theta) = \frac{1}{2} |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$



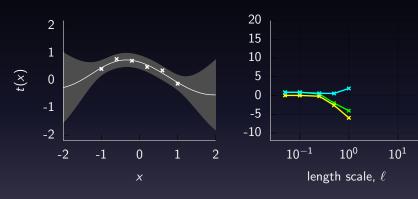


$$E(\theta) = \frac{1}{2} |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$

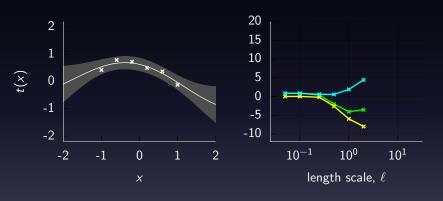




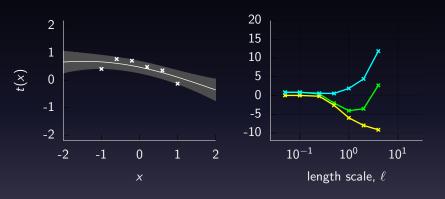
$$E(\theta) = \frac{1}{2} |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$



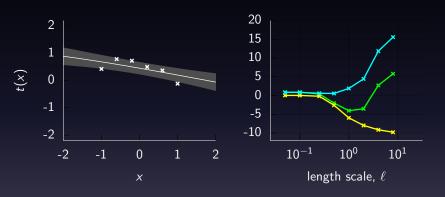
$$E(\theta) = \frac{1}{2} |\mathbf{K}| + \frac{\mathbf{t}^{\top} \mathbf{K}^{-1} \mathbf{t}}{2}$$



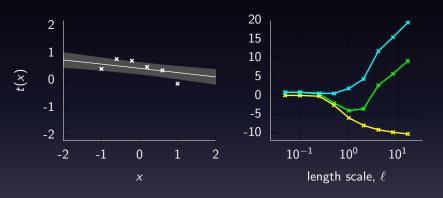
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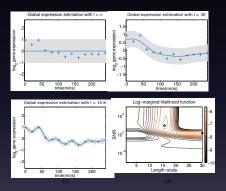


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## Gene Expression Example



Data from Della Gatta et al. (2008). Figure from Kalaitzis and Lawrence (2011).

#### Outline

Distributions over Functions

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

**GP Limitations** 

Conclusion

#### Limitations of Gaussian Processes

- Inference is  $O(N^3)$  due to matrix inverse (in practice use Cholesky).
- Gaussian processes don't deal well with discontinuities (financial crises, phosphorylation, collisions, edges in images).
- Widely used exponentiated quadratic covariance (RBF) can be too smooth in practice (but there are many alternatives!!).

#### Summary

- Broad introduction to Gaussian processes.
  - Started with Gaussian distribution.
  - Motivated Gaussian processes through the multivariate density.
- Emphasized the role of the covariance (not the mean).
- Performs nonlinear regression with error bars.
- Parameters of the covariance function (kernel) are easily optimized with maximum likelihood.

## Reading

- Section 2.3 of Bishop up to top of pg 85 (multivariate Gaussians).
- Section 3.3 of Bishop up to 159 (pg 152-159).

#### References I

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- G. Della Gatta, M. Bansal, A. Ambesi-Impiombato, D. Antonini, C. Missero, and D. di Bernardo. Direct targets of the trp63 transcription factor revealed by a combination of gene expression profiling and reverse engineering. *Genome Research*, 18(6): 939–948, Jun 2008. [URL]. [DOI].
- A. A. Kalaitzis and N. D. Lawrence. A simple approach to ranking differentially expressed gene expression time courses through Gaussian process regression. *BMC Bioinformatics*, 12(180), 2011. [DOI].
- R. M. Neal. *Bayesian Learning for Neural Networks*. Springer, 1996. Lecture Notes in Statistics 118.

#### References II

- J. Oakley and A. O'Hagan. Bayesian inference for the uncertainty distribution of computer model outputs. *Biometrika*, 89(4): 769–784, 2002.
- C. E. Rasmussen and C. K. I. Williams. Gaussian Processes for Machine Learning. MIT Press, Cambridge, MA, 2006. [Google Books].
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