

# *Bayesian Inference in Normal Models*

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## *Inference in normal distributions*

- ▶ The univariate normal, or Gaussian, probability distribution with mean  $\mu$  and variance  $\sigma^2$  has the density

$$P(x|\mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}.$$

- ▶ A random variable  $x$  that is normally distributed with mean  $\mu$  and variance  $\sigma^2$  can be written

$$x \sim N(\mu, \sigma^2).$$

## *Inference in normal distributions*

- ▶ A common elementary data analysis problem is when we observe  $n$  iid samples from  $N(\mu, \sigma^2)$ , where  $\mu$  and  $\sigma^2$  are unknown, and we aim to infer  $\mu$ .
- ▶ In other words, we observe

$$D = x_1, x_2 \cdots x_n,$$

where we assume

$$x_i \sim N(\mu, \sigma^2), \quad \text{for } i \in 1, 2 \cdots n,$$

where both  $\mu$  and  $\sigma^2$  are unknown, and we aim to infer the value of  $\mu$ .

- ▶ In other words, we aim to determine the posterior distribution

$$P(\mu|D).$$

## Likelihood of $\mu$ and $\sigma^2$

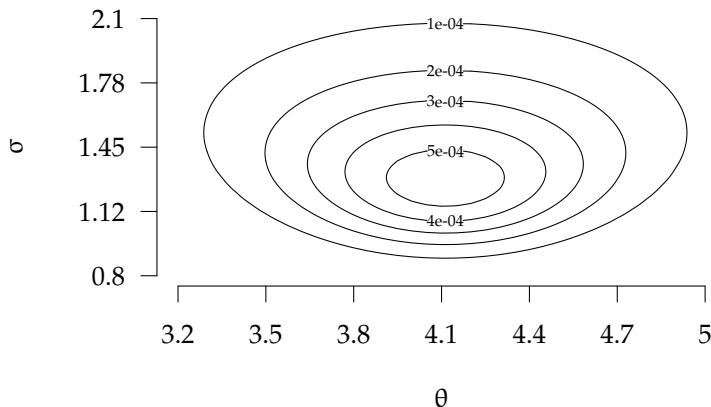
- The likelihood of  $\mu$  and  $\sigma^2$  given D is

$$\begin{aligned} P(x_1, x_2 \cdots x_n | \mu, \sigma^2) &= \prod_{i=1}^n P(x_i | \mu, \sigma^2), \\ &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}, \\ &= \left( \frac{1}{\sqrt{2\pi\sigma^2}} \right)^n e^{\left( -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \right)}, \\ &\propto \sigma^{-n} e^{\left( -\frac{1}{2\sigma^2} [ns^2 + n(\bar{x} - \mu)^2] \right)}, \end{aligned}$$

with

$$\bar{x} \doteq \frac{1}{n} \sum_{i=1}^n x_i, \quad s^2 \doteq \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2.$$

## Likelihood of $\mu$ and $\sigma^2$



The likelihood of  $\mu$  and  $\sigma$  when

$$D = 2.41, 5.37, 5.28, 4.89, 4.40, 4.63, 4.67, 4.52, 1.10, 3.86$$

with  $\bar{x} = 4.11$  and  $s = 1.28$ .

## Conjugate prior for $\mu$ and $\sigma$

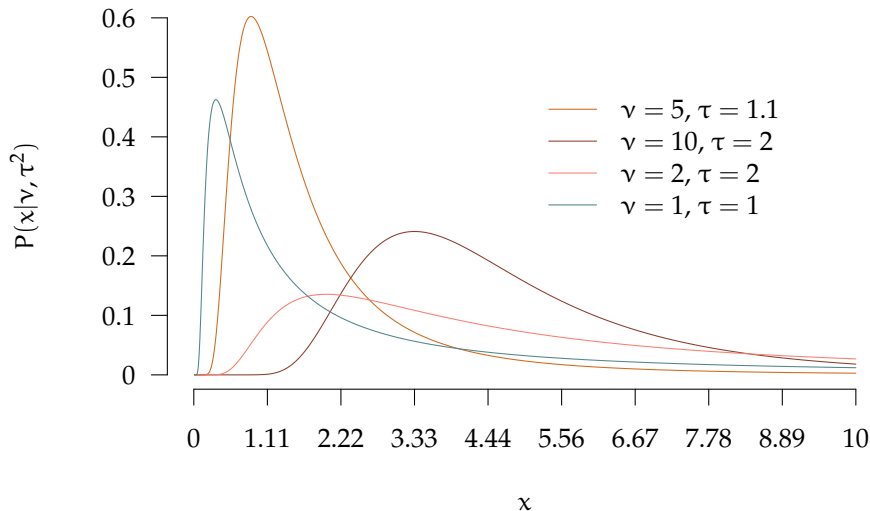
- ▶ A common choice of conjugate prior is the normal/inverse-gamma distribution, also known as the *normal  $\times$  scaled inverse- $\chi^2$*  distribution.
- ▶ Thus, our full model is

$$\begin{aligned}x_i &\sim N(\mu, \sigma^2), \quad \text{for } i \in 1, 2 \dots n, \\ \mu &\sim N(\mu_0, \sigma^2/\kappa_0), \\ \sigma^2 &\sim \text{Inv-}\chi^2(\nu_0, \sigma_0^2).\end{aligned}$$

- ▶ This corresponds to the joint prior density

$$\begin{aligned}P(\mu, \sigma^2) &= N\text{-Inv-}\chi^2(\mu, \sigma^2 | \mu_0, \kappa_0, \nu_0, \sigma_0^2), \\ &= N(\mu | \mu_0, \sigma^2/\kappa_0) \times \text{Inv-}\chi^2(\sigma^2 | \nu_0, \sigma_0^2), \\ &\propto \sigma^{-1} (\sigma^2)^{-(\nu_0/2+1)} e^{\left(-\frac{1}{2\sigma^2} [\nu_0 \sigma_0^2 + \kappa_0 (\mu_0 - \mu)^2]\right)}\end{aligned}$$

## The scaled inverse- $\chi^2$ distribution



The mean is  $\frac{\nu}{\nu-2}\sigma_0^2$ , mode is  $\frac{\nu}{\nu+2}\sigma_0^2$ .

## Joint posterior on $\mu$ and $\sigma$

- ▶ With the normal likelihood and normal/scaled inverse- $\chi^2$  distribution, the joint posterior is:

$$\begin{aligned} P(\mu, \sigma^2 | D) &\propto P(D | \mu, \sigma^2) P(\mu, \sigma^2), \\ &\propto \sigma^{-n} e^{\left(-\frac{1}{2\sigma^2} [ns^2 + n(\bar{x} - \mu)^2]\right)} \\ &\quad \times \sigma^{-1} (\sigma^2)^{-(\nu_0/2 + 1)} e^{\left(-\frac{1}{2\sigma^2} [\nu_0 \sigma_0^2 + \kappa_0 (\mu_0 - \mu)^2]\right)} \\ &= \text{N-Inv-}\chi^2(\mu, \sigma^2 | \mu_n, \kappa_n, \nu_n, \sigma_n^2) \end{aligned}$$

where

$$\begin{aligned} \mu_n &= \frac{\kappa_0 \mu_0 + n \bar{x}}{\kappa_n}, \\ \kappa_n &= \kappa_0 + n, \\ \nu_n &= \nu_0 + n, \\ \sigma_n^2 &= \frac{1}{\nu_n} \left( \nu_0 \sigma_0^2 + ns^2 + \frac{n \kappa_0}{\kappa_0 + n} (\mu_0 - \bar{x})^2 \right). \end{aligned}$$



## *Marginal posterior of $\sigma^2$*

- The marginal posterior of  $\sigma^2$  is obtained by integrating over  $\mu$ :

$$\begin{aligned} P(\sigma^2|D) &= \int P(\sigma^2, \mu|D) \, d\mu, \\ &= \int \text{N-Inv-}\chi^2(\mu, \sigma^2 | \mu_n, \kappa_n, \nu_n, \sigma_n^2) \, d\mu, \\ &\propto (\sigma^2)^{-(\nu_n/2+1)} e^{\left(-\frac{1}{2\sigma^2} [\nu_n \sigma_n^2]\right)}, \\ &= \text{Inv-}\chi^2(\sigma^2 | \nu_n, \sigma_n^2) \end{aligned}$$

## *Marginal posterior of $\mu$*

- The marginal posterior of  $\mu$  is obtained by integrating over  $\sigma^2$ :

$$\begin{aligned} P(\mu|D) &= \int P(\sigma^2, \mu|D) d\sigma^2, \\ &= \int \text{N-Inv-}\chi^2(\mu, \sigma^2 | \mu_n, \kappa_n, \nu_n, \sigma_n^2) d\sigma^2, \\ &\propto \left[ 1 + \frac{\kappa_n}{\nu_n \sigma_n^2} (\mu - \mu_n)^2 \right]^{-(\nu_n+1)/2}, \\ &= t_{\nu_n} \left( \mu | \mu_n, \sigma_n^2 / \kappa_n \right). \end{aligned}$$

which is a (non-standard) t-distribution with  $\nu_n$  degrees of freedom, location  $\mu_n$  and scale  $\sigma_n^2 / \kappa_n$ .

## Marginal posterior density of $\mu$

- To infer the marginal probability of  $\mu$ , we must integrate over the *nuisance* variable  $\sigma^2$ :

$$P(\mu|D) = \int P(\mu, \sigma^2|D) d\sigma^2,$$

which can be done by

$$= \int \overbrace{P(\mu|\sigma^2, D)}^{\text{conditional posterior}} \underbrace{P(\sigma^2|D)}_{\text{marginal posterior}} d\sigma^2.$$

- This demonstrates that the posterior distribution  $P(\mu|D)$  is an infinite mixture of normal distributions.

## Marginal posterior density of $\mu$

- If we fix  $\sigma^2$  at any value and, using the previous prior on  $\mu$ , i.e.  $\mu \sim N(\mu_0, \sigma^2/\kappa_0)$ , then

$$\begin{aligned} P(\mu|D, \sigma^2) &\propto P(D|\mu, \sigma)P(\mu|\mu_0, \sigma^2/\kappa_0), \\ &= N(\mu_n, \sigma^2/\kappa_n), \end{aligned}$$

where

$$\mu_n = \frac{\frac{\kappa_0}{\sigma^2}\mu_0 + \frac{n}{\sigma^2}\bar{x}}{\frac{\kappa_0}{\sigma^2} + \frac{n}{\sigma^2}}, \quad \sigma^2/\kappa_n = \frac{1}{\frac{\kappa_0}{\sigma^2} + \frac{n}{\sigma^2}}.$$

- Integrating over  $\sigma^2$ , when  $\sigma^2$  has a scaled inverse  $\chi^2$  distribution with parameters  $\nu_n, \sigma_n^2$  leads to a non-standard t-distribution leads to  $t_{\nu_n}(\mu|\mu_n, \sigma_n^2/\kappa_n)$  as before.

## Posterior predictive distribution

- Given our  $n$  observed values

$$D = 2.41, 5.37, 5.28, 4.89, 4.40, 4.63, 4.67, 4.52, 1.10, 3.86,$$

and our assumed probabilistic generative model, what is *next* value that we predict?

- In other words, what is

$$P(x_{n+1}|D) = \int \int P(x_{n+1}|\mu, \sigma^2) P(\mu, \sigma^2|D) d\mu d\sigma^2$$

- This is again a t-distribution:

$$t_{\nu_n} \left( \mu | \mu_n, \left( 1 + \frac{1}{\kappa_n} \right) \sigma_n^2 \right)$$

## *Inferences concerning differences of normal means*

- ▶ Let us assume that we have observed two sets of data as follows:

$$x_1, x_2 \cdots x_n \stackrel{\text{iid}}{\sim} N(\mu_x, \sigma^2), \quad y_1, y_2 \cdots y_n \stackrel{\text{iid}}{\sim} N(\mu_y, \sigma^2).$$

- ▶ In other words, both  $x_1, x_2 \cdots x_n$  and  $y_1, y_2 \cdots$  are independently and identically normally distributed, with different means  $\mu_x, \mu_y$  but with a common variance  $\sigma^2$ .
- ▶ In general, we know neither  $\mu_x, \mu_y$  nor  $\sigma^2$ .
- ▶ In such a situation, a common problem we are faced with is to infer the difference

$$\mu_x - \mu_y,$$

given  $D = \{x_1, x_2 \cdots x_n, y_1, y_2 \cdots y_n\}$ , while integrating over the nuisance variable  $\sigma^2$ , i.e.,

$$P(\mu_x - \mu_y | D).$$

## *Posterior inference of differences of means*

- Inference of the differences of means is a special kind of posterior predictive inference:

$$\int P(\mu_x - \mu_y | \mu_x, \mu_y, \sigma^2) P(\mu_x, \mu_y, \sigma^2 | D) d\mu_x d\mu_y d\sigma^2.$$

- We can approach this problem using the methods we have used to deal with inference in the univariate normal distribution.
- We begin by assuming, as before,

$$\mu_x \sim N(\mu_0, \sigma^2/\kappa_0),$$

$$\mu_y \sim N(\mu_0, \sigma^2/\kappa_0),$$

$$\sigma^2 \sim \text{Inv-}\chi^2(\nu_0, \sigma_0^2).$$

## Posterior inference of differences of means

- Given that

$$P(\mu_x, \mu_y, \sigma^2 | D) = P(\mu_x, \mu_y, \sigma^2, D)P(\sigma^2 | D)$$

- From previous results, we see that

$$\begin{aligned} P(\mu_x, \mu_y, \sigma^2, D) &= P(\mu_x | \sigma^2, D)P(\mu_y | \sigma^2, D), \\ &= N(\mu_n^x, \sigma^2 / \kappa_n^x)N(\mu_n^y, \sigma^2 / \kappa_n^y) \end{aligned}$$

where  $\mu_n^x$ ,  $\mu_n^y$ ,  $\kappa_n^x$  and  $\kappa_n^y$  are defined analogously with previous results.



## Posterior inference of differences of means

- As such,

$$\begin{aligned} & \int P(\mu_x - \mu_y | \mu_x, \mu_y, \sigma^2) P(\mu_x, \mu_y | \sigma^2, D) d\mu_x d\mu_y \\ &= N(\mu_n^x - \mu_n^y, \sigma^2 / \kappa_n^x + \sigma^2 / \kappa_n^y). \end{aligned}$$

For simplicity, let's assume  $\kappa_0 \doteq 0$ . In that case,

$$= N(\bar{x} - \bar{y}, \frac{\sigma^2}{n} + \frac{\sigma^2}{m}).$$

- Integrating over  $\sigma^2$  as before leads to

$$\begin{aligned} & \int N(\bar{x} - \bar{y}, \frac{\sigma^2}{n} + \frac{\sigma^2}{m}) P(\sigma^2 | D) \\ &= t_{\nu_n} \left( \bar{x} - \bar{y}, \sigma_n^2 \left( \frac{1}{n} + \frac{1}{m} \right) \right) \end{aligned}$$

## Posterior inference of differences of means

- In the case of the non-informative prior case, i.e.,

$$P(\mu_x, \mu_y, \sigma^2) \propto \frac{1}{\sigma^2},$$

the marginal posterior over  $\mu_x - \mu_y$  is

$$P(\mu_x - \mu_y | D) = t_v \left( \bar{x} - \bar{y}, s^2 \left( \frac{1}{n} + \frac{1}{m} \right) \right)$$

where

$$v = n + m - 2, \quad s^2 = \frac{(n_x - 1)s_x^2 + (n_y - 1)s_y^2}{n_x + n_y - 2}.$$

- This is an identical distribution to the sampling distribution of the difference of the means.