

# *Introducing Bayesian Data Analysis Using R*

Mark Andrews

Psychology Department, Nottingham Trent University

✉ mark.andrews@ntu.ac.uk

🐦 @xmjandrews

🔗 [https://github.com/lawsofthought/notts\\_rmeetup-jul2018](https://github.com/lawsofthought/notts_rmeetup-jul2018)

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## *Bayesian data analysis*

- ▶ Bayesian statistics is an alternative school of statistics to the *classical* or *frequentist* or school.
- ▶ Classical statistics is defined by concepts like *sampling distributions*, *(null) hypothesis significance tests*, *confidence intervals*, etc.
- ▶ These concepts per se do not exist in Bayesian approaches to statistics (though there are analogous concepts).
- ▶ Bayesian statistics arguably originated with a single essay by Reverend Thomas Bayes in 1763, though Bayes's main idea was independently discovered and developed much further by Pierre-Simon Laplace at the end of the 18th century.
- ▶ With the origin of frequentist approaches to statistics in the early 20th century, Bayesian method were sidelined.
- ▶ Beginning in the late 20th century, Bayesian methods have regained popularity.

## Bayesian methods: A definition

- ▶ Classical and Bayesian approaches to data analysis both begin by positing a probabilistic *generative model* of the data being analysed.
- ▶ For example, if our data was  $x_1, x_2 \dots x_n$ , we might assume or propose that this data arose from the following process:

$$x_i \sim N(\mu, \sigma^2), \quad \text{for } i \in 1 \dots n,$$

where  $\mu$  and  $\sigma^2$  are the fixed but unknown mean and variance of a Normal distribution.

- ▶ The fundamental difference between classical and Bayesian methods are that Bayesian methods describes our state of uncertainty about  $\mu$  and  $\sigma^2$  by a probability distribution (known as *priors*).
- ▶ In general, all unknown variables in the probabilistic are described by priors.

## Posterior distributions

- In general, given observed data  $D$  and a model  $\Omega$ , the posterior distribution over the parameters  $\theta$  of the model is

$$P(\theta|D, \Omega) = \frac{\overbrace{P(D|\theta)}^{\text{Likelihood}} \overbrace{P(\theta|\Omega)}^{\text{Prior}}}{\underbrace{\int P(D|\theta)P(\theta|\Omega) d\theta}_{\text{Marginal likelihood}}}.$$

where the *marginal likelihood* gives the likelihood of the model given the observed data.

- Given the posterior distribution  $P(\theta|D, \Omega)$ , our aim is often to characterise this distribution in terms of e.g. its mean, variance, etc.
- Likewise, we may aim to calculate *posterior predictive* distributions such as

$$P(x_{\text{new}}|D, \Omega) = \int P(x_{\text{new}}|\theta, \Omega)P(\theta|D, \Omega) d\theta.$$

## *Sampling from posterior distributions*

- ▶ In only rare situations can we determine the characteristics of the posterior distribution, or calculate posterior predictive distributions, in closed form.
- ▶ However, in general, if we can draw samples from  $P(\theta|D, \Omega)$  then we can approximate, e.g., the mean of the distribution by

$$\langle \theta \rangle = \int \theta P(\theta|D, \Omega) \approx \frac{1}{N} \sum_{i=1}^N \tilde{\theta}_i,$$

or the posterior predictive distribution by

$$P(x_{\text{new}}|D, \Omega) = \int P(x_{\text{new}}|\theta, \Omega) P(\theta|D, \Omega) d\theta \approx \frac{1}{N} \sum_{i=1}^N P(x_{\text{new}}|\tilde{\theta}_i, \Omega),$$

where

$$\tilde{\theta}_1, \tilde{\theta}_2 \dots \tilde{\theta}_N$$

are samples from  $P(\theta|D, \Omega)$ .

## *Markov Chain Monte Carlo (MCMC)*

- ▶ Markov Chain Monte Carlo (MCMC) methods provide with general purpose methods for drawing samples from the posterior distributions of Bayesian models.
- ▶ Until recently the two most widely used MCMC methods were
  - ▶ Metropolis Hastings
  - ▶ Gibbs sampling
- ▶ More recently Hamiltonian Monte Carlo (HMC) has become very popular.

## *Probabilistic programming languages*

- ▶ The most general purpose approach to Bayesian data analysis is to use a *probabilistic programming language* like
  - ▶ Bugs
  - ▶ Jags
  - ▶ PyMC
  - ▶ Stan
- ▶ In all these case, your work entails defining your probabilistic model, including priors, and then a MCMC sampling algorithm is compiled.

# Using Stan

- We define a probabilistic model in Stan as follows:

```
...  
transformed parameters {  
  vector[N] mu;  
  mu = a + b * x;  
}  
  
model {  
  a ~ normal(0, 10);  
  b ~ normal(0, 10);  
  sigma ~ cauchy(0, 5);  
  y ~ normal(mu, sigma);  
}
```



## Call Stan from R

```
M_stan <- stan(file="regression.stan",  
              data = model_data,  
              pars = c('a', 'b', 'sigma'),  
              warmup = 5000,  
              iter=10000)
```

- Here, `model_data` is artificial data with  $N = 50$  data points and where the true values of the parameters were:  $a = 0.5$ ,  $b = 2.25$ ,  $\sigma = 1.75$ .

## Summarize

```
S <- rstan::summary(M_stan)
pander::pander(S$summary)
```

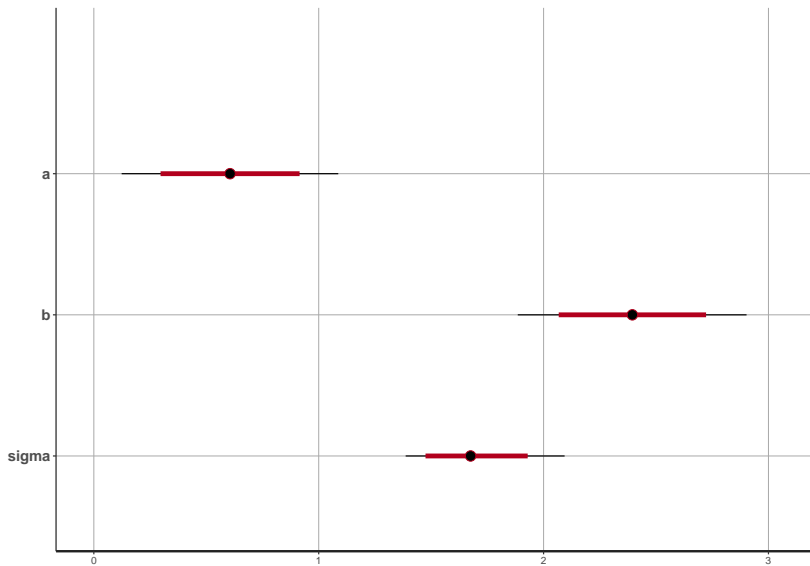
Table 1: Table continues below

	mean	se_mean	sd	2.5%	25%	50%	75%
<b>a</b>	0.6058	0.001801	0.2436	0.1238	0.445	0.6057	0.7656
<b>b</b>	2.395	0.001959	0.259	1.885	2.223	2.395	2.569
<b>sigma</b>	1.692	0.001362	0.1808	1.387	1.563	1.675	1.803
<b>**lp_**</b>	-50.26	0.01322	1.271	-53.55	-50.83	-49.93	-49.33

	97.5%	n_eff	Rhat
<b>a</b>	1.087	18282	0.9999
<b>b</b>	2.903	17481	1
<b>sigma</b>	2.093	17621	0.9999
<b>**lp_**</b>	-48.83	9249	1

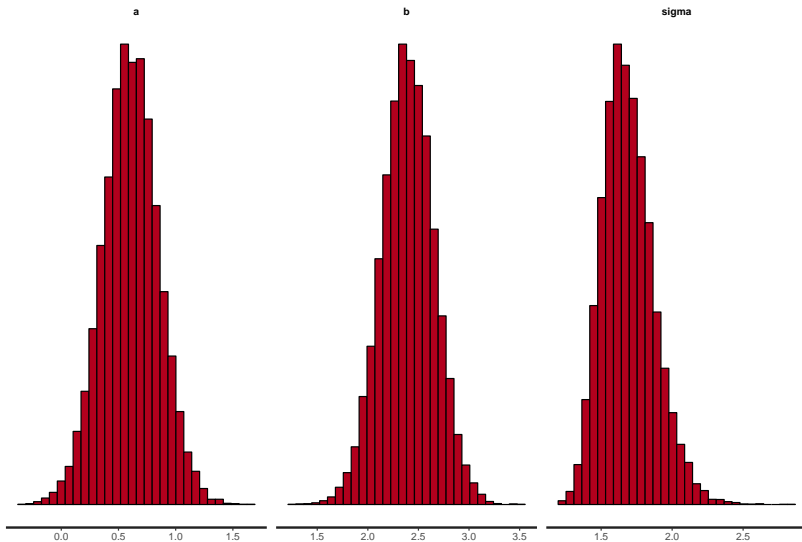
# Visualize

```
rstan::plot(M_stan)
```



# Visualize

```
rstan::stan_hist(M_stan)
```



# *Conclusions*

- ▶ Bayesian methods are vital where you need to build complex probabilistic models.
- ▶ In general, inference is based on MCMC sampling.
- ▶ Probabilistic modelling language like Stan make this easy and efficient.